



SAR TEST REPORT

REPORT NO.: SA930908H01

MODEL NO.: USR5422

SERIES MODEL NO.: USRXX5422

(The "X" could be "0~9", "A~Z", or "None", and "XX" is defined for selling in different country or area.)

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1. CERTIFICATION

PRODUCT : U.S. Robotics 802.11g 54Mbps USB Adapter

MODEL NO. : USR5422

SERIES MODEL NO.: USRXX5422

(The "X" could be "0~9", "A~Z", or "None", and "XX" is defined for selling in different country or area.)

BRAND NAME : U.S. Robotics

APPLICANT : U.S. Robotics

TESTED : Aug. 09, 2004

TEST SAMPLE : MASS-PRODUCTION

STANDARDS : FCC Part 2 (Section 2.1093), FCC OET Bulletin 65,
Supplement C (01-01), RSS-102

The above equipment (Model: USR5422) has been tested by **Advance Data Technology Corporation**, and found compliance with the requirement of the above standards. The test record, data evaluation & Equipment Under Test (EUT) configurations represented herein are true and accurate accounts of the measurements of the sample' s EMC characteristics under the conditions specified in this report.

PREPARED BY : Windy Chou, **DATE:** Sep. 21, 2004
(Windy Chou)

TECHNICAL
ACCEPTANCE : Ansen Lei, **DATE:** Sep. 21, 2004
Responsible for RF (Ansen Lei)

APPROVED BY : Cody Chang, **DATE:** Sep. 21, 2004
(Cody Chang,
Deputy Manager)



2. GENERAL INFORMATION

2.1 GENERAL DESCRIPTION OF EUT

PRODUCT	U.S. Robotics 802.11g 54Mbps USB Adapter
MODEL NO.	USR5422
SERIES MODEL NO.	USRXX5422
POWER SUPPLY	5.0 Vdc from host equipment
CLASSIFICATION	Portable device, production unit
MODULATION TYPE	BPSK, QPSK, CCK, 16QAM, 64QAM
RADIO TECHNOLOGY	DSSS, OFDM
TRANSFER RATE	54/48/36/24/18/12/11/9/6/5.5/2/1 Mbps
FREQUENCY RANGE	2412MHz ~ 2462MHz
NUMBER OF CHANNEL	11
MAXIMUN CONDUCTED OUTPUT POWER (FOR CCK)	112.20mW
MAXIMUN CONDUCTED OUTPUT POWER (FOR OFDM)	95.50mW
ANTENNA TYPE	PCB antenna with 1.43dBi gain
AVERAGE SAR(1g) (FOR CCK)	1.400W/kg
AVERAGE SAR(1g) (FOR OFDM)	0.575W/kg
DATA CABLE	NA
I/O PORTS	NA
ASSOCIATED DEVICES	NA

NOTE:

1. The "X" of the Model Name: USRXX5422, could be "0~9", "A~Z", or "None", and "XX" is defined for selling in different country or area.
2. Normal operating condition of the EUT shall be plugged into the laptop PC. Then the property of the EUT shall be complied with the portable device according to the FCC 2.1093.
3. The above EUT information was declared by manufacturer and for more detailed features description, please refer to the manufacturer's specifications or User's Manual.



2.2 GENERAL DESCRIPTION OF APPLIED STANDARDS

According to the specifications of the manufacturer, this product must comply with the requirements of the following standards:

FCC Part 2 (2.1093)
FCC OET Bulletin 65, Supplement C (01- 01)
RSS-102
IEEE 1528-200X

All test items have been performed and recorded as per the above standards.

2.3 GENERAL INFORMATION OF THE SAR SYSTEM

DASY4 (software 4.1d) consists of high precision robot, probe alignment sensor, phantom, robot controller, controlled measurement server and near-field probe. The robot includes six axes that can move to the precision position of the DASY4 software defined. The DASY4 software can define the area that is detected by the probe. The robot is connected to controlled box. Controlled measurement server is connected to the controlled robot box. The DAE includes amplifier, signal multiplexing, AD converter, offset measurement and surface detection. It is connected to the Electro-optical coupler (ECO). The ECO performs the conversion from the optical into digital electric signal of the DAE and transfers data to the PC.

ET3DV6 ISOTROPIC E-FIELD PROBE

Construction	Symmetrical design with triangular core. Built-in optical fiber for surface detection system. Built-in shielding against static charges. PEEK enclosure material (resistant to organic solvents, e.g., glycoether).
Calibration	Basic Broad Band Calibration in air: 10-2500 MHz Conversion Factors (CF) for HSL 900, HSL 1800, HSL2450, MSL 900, MSL 1800 and MSL2450. CF-Calibration for other liquids and frequencies upon request
Frequency	10 MHz to 3 GHz; Linearity: ± 0.2 dB (30 MHz to 3 GHz)
Directivity	± 0.2 dB in HSL (rotation around probe axis) ± 0.4 dB in HSL (rotation normal to probe axis)
Dynamic Range	5 μ W/g to > 100 mW/g; Linearity: ± 0.2 dB
Optical Surface Detection	± 0.2 mm repeatability in air and clear liquids over diffuse reflecting surfaces
Dimensions	Overall length: 330 mm (Tip Length: 16 mm)



Tip diameter: 6.8 mm (Body diameter: 12 mm)
 Distance from probe tip to dipole centers: 2.7 mm

Application

General dosimetric measurements up to 3 GHz
 Compliance tests of mobile phones
 Fast automatic scanning in arbitrary phantoms (ET3DV6)

Sensitivity

X axis : 1.74 μ V ; Y axis : 1.69 μ V ; Z axis : 1.76 μ V

Diode compression point

X axis : 96 mV ; Y axis : 96 mV ; Z axis : 96mV

Conversion Factor	Frequency range (MHz)	X axis	Y axis	Z axis
	800~950 (Head)	6.4	6.4	6.4
	800~950 (Body)	6.2	6.2	6.2
	1700~1910 (Head)	5.1	5.1	5.1
	1700~1910 (Body)	4.8	4.8	4.8
	2400~2500 (Head)	4.7	4.7	4.7
	2400~2500 (Body)	4.4	4.4	4.4

Boundary effect	Frequency range (MHz)	Alpha	Depth
	800~950 (Head)	0.48	2.13
	800~950 (Body)	0.40	2.57
	1700~1910 (Head)	0.49	2.70
	1700~1910 (Body)	0.54	2.76
	2400~2500 (Head)	1.00	1.89
	2400~2500 (Body)	1.21	1.59

NOTE

1. The Probe parameters have been calibrated by the SPEAG. Please reference "APPENDIX D" for the Calibration Certification Report.
2. For frequencies above 800 MHz, calibration in a rectangular wave-guide is used, because wave-guide size is manageable.
3. For frequencies below 800 MHz, temperature transfer calibration is used because the wave-guide size becomes relatively large.



TWIN SAM V4.0

Construction	The shell corresponds to the specifications of the Specific Anthropomorphic Mannequin (SAM) phantom defined in IEEE 1528-200X, CENELEC 50361 and IEC 62209. It enables the dosimetric evaluation of left and right hand phone usage as well as body mounted usage at the flat phantom region. A cover prevents evaporation of the liquid. Reference markings on the phantom allow the complete setup of all predefined phantom positions and measurement grids by manually teaching three points with the robot.
Shell Thickness	2 ± 0.2 mm
Filling Volume	Approx. 25 liters
Dimensions	Height: 810 mm; Length: 1000 mm; Width: 500 mm

SYSTEM VALIDATION KITS: D900V2 – D2450V2

Construction	Symmetrical dipole with 1/4 balun enables measurement of feedpoint impedance with NWA matched for use near flat phantoms filled with brain simulating solutions. Includes distance holder and tripod adaptor
Calibration	Calibrated SAR value for specified position and input power at the flat phantom in brain simulating solutions
Frequency	900, 1800, 1900, 2450 MHz
Return Loss	> 20 dB at specified validation position
Power Capability	> 100 W ($f < 1\text{GHz}$); > 40 W ($f > 1\text{GHz}$)
Options	Dipoles for other frequencies or solutions and other calibration conditions upon request
Dimensions	D900V2: dipole length: 149 mm; overall height: 83.3mm D1800V2: dipole length: 72 mm; overall height: 41.2 mm D1900V2: dipole length: 68 mm; overall height: 39.5 mm D2450V2: dipole length: 51.5 mm; overall height: 30.6 mm



DEVICE HOLDER FOR SAM TWIN PHANTOM

Construction

The device holder for the mobile phone device is designed to cope with different positions given in the standard. It has two scales for the device rotation (with respect to the body axis) and the device inclination (with respect to the line between the ear reference points). The rotation centers for both scales is the ear reference point (ERP). Thus the device needs no repositioning when changing the angles. The holder has been made out of low-loss POM material having the following dielectric parameters: relative permittivity $\epsilon = 3$ and loss tangent $\delta = 0.02$. The amount of dielectric material has been reduced in the closest vicinity of the device, since measurements have suggested that the influence of the clamp on the test results could thus be lowered. The device holder for the portable device makes up of the polyethylene foam. The dielectric parameters of material close to the dielectric parameters of the air.

DATA ACQUISITION ELECTRONICS

Construction

The data acquisition electronics (DAE3) consists of a highly sensitive electrometer grade preamplifier with auto-zeroing, a channel and gain-switching multiplex, a fast 16 bit AD converter and a command decoder and control logic unit. Transmission to the measurement server is accomplished through an optical downlink for data and status information as well as an optical uplink for commands and the clock. The mechanical probe is mounting device includes two different sensor systems for frontal and sideways probe contacts. They are used for mechanical surface detection and probe collision detection. The input impedance of the DAE3 box is 200M Ω ; the inputs are symmetrical and floating. Common mode rejection is above 80 dB.



2.4 GENERAL DESCRIPTION OF THE SPATIAL PEAK SAR EVALUATION

The DASY4 post-processing software (SEMCAD) automatically executes the following procedures to calculate the field units from the micro-volt readings at the probe connector. The parameters used in the evaluation are stored in the configuration modules of the software:

Probe parameters:	- Sensitivity	Norm _i , a _{i0} , a _{i1} , a _{i2}
	- Conversion factor	ConvF _i
	- Diode compression point	dcp _i
Device parameters:	- Frequency	F
	- Crest factor	cf
Media parameters:	- Conductivity	σ
	- Density	ρ

The first step of the evaluation is a linearization of the filtered input signal to account for the compression characteristics of the detector diode. The compensation depends on the input signal, the diode type and the DC-transmission factor from the diode to the evaluation electronics. If the exciting field is pulsed, the crest factor of the signal must be known to correctly compensate for peak power. The formula for each channel can be given as:

$$V_i = U_i + U_i^2 \cdot \frac{cf}{dcp_i}$$

V _i	=compensated signal of channel i	(i = x, y, z)
U _i	=input signal of channel i	(i = x, y, z)
cf	=crest factor of exciting field	(DASY parameter)
dcp _i	=diode compression point	(DASY parameter)

From the compensated input signals the primary field data for each channel can be evaluated:

$$\text{E-field probes :} \quad E_i = \sqrt{\frac{V_i}{\text{Norm}_i \cdot \text{ConvF}}}$$

$$\text{H-field probes :} \quad H_i = \sqrt{V_i} \cdot \frac{a_{i0} + a_{i1}f + a_{i2}f^2}{f}$$

V_i = compensated signal of channel i ($i = x, y, z$)
 Norm_i = sensor sensitivity of channel i $\mu\text{V}/(\text{V/m})^2$ for E-field Probes ($i = x, y, z$)
 ConvF = sensitivity enhancement in solution
 a_{ij} = sensor sensitivity factors for H-field probes
 f = carrier frequency [GHz]
 E_i = electric field strength of channel i in V/m
 H_i = magnetic field strength of channel i in A/m

The RSS value of the field components gives the total field strength (Hermitian magnitude):

$$E_{tot} = \sqrt{E_x^2 + E_y^2 + E_z^2}$$

The primary field data are used to calculate the derived field units.

$$SAR = E_{tot}^2 \cdot \frac{\sigma}{\rho \cdot 1'000}$$

SAR = local specific absorption rate in mW/g
 E_{tot} = total field strength in V/m
 σ = conductivity in [mho/m] or [Siemens/m]
 ρ = equivalent tissue density in g/cm³



Note that the density is set to 1, to account for actual head tissue density rather than the density of the tissue simulating liquid. The entire evaluation of the spatial peak values is performed within the Post-processing engine (SEMCAD). The system always gives the maximum values for the 1 g and 10 g cubes. The algorithm to find the cube with highest averaged SAR is divided into the following stages:

1. The extraction of the measured data (grid and values) from the Zoom Scan
2. The calculation of the SAR value at every measurement point based on all stored data (A/D values and measurement parameters)
3. The generation of a high-resolution mesh within the measured volume
4. The interpolation of all measured values from the measurement grid to the high-resolution grid
5. The extrapolation of the entire 3-D field distribution to the phantom surface over the distance from sensor to surface
6. The calculation of the averaged SAR within masses of 1g and 10g.

The probe is calibrated at the center of the dipole sensors that is located 1 to 2.7mm away from the probe tip. During measurements, the probe stops shortly above the phantom surface, depending on the probe and the surface detecting system. Both distances are included as parameters in the probe configuration file. The software always knows exactly how far away the measured point is from the surface. As the probe cannot directly measure at the surface, the values between the deepest measured point and the surface must be extrapolated. The angle between the probe axis and the surface normal line is less than 30 degree.

In the Area Scan, the gradient of the interpolation function is evaluated to find all the extreme of the SAR distribution. The uncertainty on the locations of the extreme is less than 1/20 of the grid size. Only local maximum within -2 dB of the global maximum are searched and passed for the Cube Scan measurement. In the Cube Scan, the interpolation function is used to extrapolate the Peak SAR from the lowest measurement points to the inner phantom surface (the extrapolation distance). The uncertainty increases with the extrapolation distance. To keep the uncertainty within 1% for the 1 g and 10 g cubes, the extrapolation distance should not be larger than 5mm.



The maximum search is automatically performed after each area scan measurement. It is based on splines in two or three dimensions. The procedure can find the maximum for most SAR distributions even with relatively large grid spacing. After the area scanning measurement, the probe is automatically moved to a position at the interpolated maximum. The following scan can directly use this position for reference, e.g., for a finer resolution grid or the cube evaluations. The 1g and 10g peak evaluations are only available for the predefined cube 7x7x7 scans. The routines are verified and optimized for the grid dimensions used in these cube measurements. The measured volume of 30x30x30mm contains about 30g of tissue. The first procedure is an extrapolation (incl. Boundary correction) to get the points between the lowest measured plane and the surface. The next step uses 3D interpolation to get all points within the measured volume in a 1mm grid (42875 points). In the last step, a 1g cube is placed numerically into the volume and its averaged SAR is calculated. This cube is moved around until the highest averaged SAR is found. If the highest SAR is found at the edge of the measured volume, the system will issue a warning: higher SAR values might be found outside of the measured volume. In that case the cube measurement can be repeated, using the new interpolated maximum as the center.

3. DESCRIPTION OF TEST MODES AND CONFIGURATIONS

CARRIER MODULATION UNDER TEST	CCK, OFDM
CREST FACTOR	1.0
CHANNEL FREQUENCIES UNDER TEST AND ITS CONDUCTED OUTPUT POWER	93.33mW / Ch1: 2412MHz For CCK 112.20mW / Ch6: 2437MHz For CCK 85.11mW / Ch11: 2462MHz For CCK 83.18mW / Ch1: 2412MHz For OFDM 95.50mW / Ch6: 2437MHz For OFDM 70.80mW / Ch11: 2462MHz For OFDM
ANTENNA CONFIGURATION	PCB antenna with 1.43dBi gain
ANTENNA POSITION	Inside the front cover, near the top
EUT POWER SOURCE	From Host Notebook
HOST POWER SOURCE	Fully Charged Battery

The following test configurations have been applied in this test report:

- Mode 1: The EUT is plugged in the USB slot of the notebook (Brand: Compaq, Model: N800C), the bottom of the notebook contact the bottom of the flat phantom with 0mm separation distance. Therefore the bottom of the EUT face to the phantom and the separation distance is 7mm. The area scan size is 5 x 8 points.
(CCK Modulation)
- Mode 2: The EUT is plugged in the USB slot of the notebook (Brand: Compaq, Model: N800C), the keyboard face of the notebook is perpendicular to the bottom of the flat phantom and the EUT is located between notebook and phantom. The separation distance is 0mm between the tip of the EUT and the bottom of the flat phantom. The area scan size is 5 x 6 points. (CCK Modulation)
- Mode 3: The EUT is plugged in the USB slot of the notebook (Brand: Compaq, Model: N800C), the bottom of the notebook contact the bottom of the flat phantom with 0mm separation distance. Therefore the bottom of the EUT face to the phantom and the separation distance is 7mm. The area scan size is 5 x 8 points.
(OFDM Modulation)
- Mode 4: The EUT is plugged in the USB slot of the notebook (Brand: Compaq, Model: N800C), the keyboard face of the notebook is perpendicular to the bottom of the flat phantom and the EUT is located between notebook and phantom. The separation distance is 0mm between the tip of the EUT and the bottom of the flat phantom. The area scan size is 5 x 6 points. (OFDM Modulation)



- Mode 5: The EUT is plugged in the USB slot of the notebook (Brand: IBM, Model: ThinkPad X31), the bottom of the notebook contact the bottom of the flat phantom with 0mm separation distance. Therefore the bottom of the EUT face to the phantom and the separation distance is 7mm. The area scan size is 5 x 8 points.
(CCK Modulation)
- Mode 6: The EUT is plugged in the USB slot of the notebook (Brand: IBM, Model: ThinkPad X31), the keyboard face of the notebook is perpendicular to the bottom of the flat phantom and the EUT is located between notebook and phantom. The separation distance is 0mm between the tip of the EUT and the bottom of the flat phantom. The area scan size is 5 x 6 points. (CCK Modulation)
- Mode 7: The EUT is plugged in the USB slot of the notebook (Brand: IBM, Model: ThinkPad X31), the bottom of the notebook contact the bottom of the flat phantom with 0mm separation distance. Therefore the bottom of the EUT face to the phantom and the separation distance is 7mm. The area scan size is 5 x 8 points.
(OFDM Modulation)
- Mode 8: The EUT is plugged in the USB slot of the notebook (Brand: IBM, Model: ThinkPad X31), the keyboard face of the notebook is perpendicular to the bottom of the flat phantom and the EUT is located between notebook and phantom. The separation distance is 0mm between the tip of the EUT and the bottom of the flat phantom. The area scan size is 5 x 6 points. (OFDM Modulation)
- Mode 9: The EUT is plugged in the USB slot of the notebook (Brand: IBM, Model: ThinkPad X20), the bottom of the notebook contact the bottom of the flat phantom with 0mm separation distance. Therefore the bottom of the EUT face to the phantom and the separation distance is 9mm. The area scan size is 5 x 8 points.
(CCK Modulation)
- Mode 10: The EUT is plugged in the USB slot of the notebook (Brand: IBM, Model: ThinkPad X20), the keyboard face of the notebook is perpendicular to the bottom of the flat phantom and the EUT is located between notebook and phantom. The separation distance is 0mm between the tip of the EUT and the bottom of the flat phantom. The area scan size is 5 x 6 points. (CCK Modulation)
- Mode 11: The EUT is plugged in the USB slot of the notebook (Brand: IBM, Model: ThinkPad X20), the bottom of the notebook contact the bottom of the flat phantom with 0mm separation distance. Therefore the bottom of the EUT face to the phantom and the separation distance is 9mm. The area scan size is 5 x 8 points.
(OFDM Modulation)



Mode 12: The EUT is plugged in the USB slot of the notebook(Brand: IBM, Model: ThinkPad X20), the keyboard face of the notebook is perpendicular to the bottom of the flat phantom and the EUT is located between notebook and phantom. The separation distance is 0mm between the tip of the EUT and the bottom of the flat phantom. The area scan size is 5 x 6 points. (OFDM Modulation)

- NOTE:**
1. Please reference "APPENDIX A" for the photos of test configuration.
 2. All test modes have been complied with the body worn configuration.
 3. The notebook has been installed the controlling software that could control the EUT transmitted channel and power. But that software is just for test software, not for normal user.
 4. Test for both CCK and OFDM modulation.



4. DESCRIPTION OF SUPPORT UNITS

The EUT has been tested as an independent unit together with other necessary accessories or support units. The following support units or accessories were used to form a representative test configuration during the tests.

NO.	PRODUCT	BRAND	MODEL NO.	SERIAL NO.	FCC ID
1	NOTEBOOK	Compaq	N800C	470048-515	FCC DoC Approved
2	NOTEBOOK	IBM	ThinkPad X31	99FMVFP	FCC DoC Approved
3	NOTEBOOK	IBM	ThinkPad X20	FX-11719	FCC DoC Approved

NO.	SIGNAL CABLE DESCRIPTION OF THE ABOVE SUPPORT UNITS
1	NA
2	NA
3	NA



5. TEST RESULTS

5.1 TEST PROCEDURES

The EUT (U.S. Robotics 802.11g 54Mbps USB Adapter) plugged into the notebook. Use the software to control the EUT channel and transmission power. Then record the conducted power before the testing. Place the EUT to the specific test location. After the testing, must writing down the conducted power of the EUT into the report. The SAR value was calculated via the 3D spline interpolation algorithm that has been implemented in the software of DASY4 SAR measurement system manufactured and calibrated by SPEAG. According to the IEEE P1528 draft standards, the recommended procedure for assessing the peak spatial-average SAR value consists of the following steps:

- Power reference measurement
- Area scan
- Zoom scan
- Power reference measurement

The area scan with 15mm x 15mm grid was performed for the highest spatial SAR location. Consist of 5 x 8 points while the scan size is the 60mm x 105mm. The zoon scan with 30mm x 30mm x 30mm volume was performed for SAR value averaged over 1g and 10g spatial volumes.

In the zoon scan, the distance between the measurement point at the probe sensor location (geometric center behind the probe tip) and the phantom surface is 4.0 mm and maintained at a constant distance of ± 1.0 mm during a zoon scan to determine peak SAR locations. The distance is 4mm between the first measurement point and the bottom surface of the phantom. The secondary measurement point to the bottom surface of the phantom is with 9mm separation distance. The cube size is 7 x 7 x 7 points consist of 343 points and the grid space is 5mm.

The measurement time is 0.5 s at each point of the zoon scan. The probe boundary effect compensation shall be applied during the SAR test. Because of the tip of the probe to the Phantom surface separated distances are longer than half a tip probe diameter.

In the area scan, the separation distance is 4mm between the each measurement point and the phantom surface. The scan size shall be included the transmission portion of the EUT. The measurement time is the same as the zoon scan. At last the reference power drift shall be less than $\pm 5\%$.

5.2 MEASURED SAR RESULT

EUT			U.S. Robotics 802.11g 54Mbps USB Adapter			MODEL	USR5422		
ENVIRONMENTAL CONDITION			Air Temperature : 21.0°C, Liquid Temperature : 21.0°C Humidity : 60%RH						
TESTED BY			Johan Kuo						
Chan.	Freq. (MHz)	Modulate type	Conducted Power (dBm)		Power Drift (%)	Device Use Power	Device Test Position Mode	Antenna Position	Measured 1g SAR (W/kg)
			Begin Test	After Test					
1	2412 (Low)	CCK	19.70	19.53	-3.84	Standard Battery from host	1	Internal Fixed	0.945
6	2437 (Mid.)	CCK	20.50	20.40	-2.28	Standard Battery from host	1	Internal Fixed	0.842
11	2462 (High)	CCK	19.30	19.12	-4.06	Standard Battery from host	1	Internal Fixed	0.724
1	2412 (Low)	CCK	19.70	19.53	-3.84	Standard Battery from host	2	Internal Fixed	0.426
6	2437 (Mid.)	CCK	20.50	20.31	-4.28	Standard Battery from host	2	Internal Fixed	0.504
11	2462 (High)	CCK	19.30	19.12	-4.06	Standard Battery from host	2	Internal Fixed	0.356

NOTE:

1. Test configuration of each mode is described in section 3.
2. In this testing, the limit for General Population Spatial Peak averaged over 1g, **1.6 W/kg**, is applied.
3. Please see the Appendix A for the photo of the test configuration and also the data.
4. The variation of the EUT conducted power measured before and after SAR testing should not over 5%.

EUT			U.S. Robotics 802.11g 54Mbps USB Adapter			MODEL	USR5422		
ENVIRONMENTAL CONDITION			Air Temperature : 21.0°C, Liquid Temperature : 21.0°C Humidity : 60%RH						
TESTED BY			Johan Kuo						
Chan.	Freq. (MHz)	Modulate type	Conducted Power (dBm)		Power Drift (%)	Device Use Power	Device Test Position Mode	Antenna Position	Measured 1g SAR (W/kg)
			Begin Test	After Test					
1	2412 (Low)	OFDM	19.20	19.00	-4.50	Standard Battery from host	3	Internal Fixed	0.385
6	2437 (Mid.)	OFDM	19.80	19.61	-4.28	Standard Battery from host	3	Internal Fixed	0.394
11	2462 (High)	OFDM	18.50	18.47	-0.69	Standard Battery from host	3	Internal Fixed	0.292
1	2412 (Low)	OFDM	19.20	19.05	-3.39	Standard Battery from host	4	Internal Fixed	0.192
6	2437 (Mid.)	OFDM	19.80	19.67	-2.95	Standard Battery from host	4	Internal Fixed	0.198
11	2462 (High)	OFDM	18.50	18.37	-2.95	Standard Battery from host	4	Internal Fixed	0.145

NOTE:

1. Test configuration of each mode is described in section 3.
2. In this testing, the limit for General Population Spatial Peak averaged over 1g, **1.6 W/kg**, is applied.
3. Please see the Appendix A for the photo of the test configuration and also the data.
4. The variation of the EUT conducted power measured before and after SAR testing should not over 5%.

EUT			U.S. Robotics 802.11g 54Mbps USB Adapter			MODEL	USR5422		
ENVIRONMENTAL CONDITION			Air Temperature : 21.0°C, Liquid Temperature : 21.0°C Humidity : 60%RH						
TESTED BY			Johan Kuo						
Chan.	Freq. (MHz)	Modulate type	Conducted Power (dBm)		Power Drift (%)	Device Use Power	Device Test Position Mode	Antenna Position	Measured 1g SAR (W/kg)
			Begin Test	After Test					
1	2412 (Low)	CCK	19.70	19.51	-4.28	Standard Battery from host	5	Internal Fixed	0.877
6	2437 (Mid.)	CCK	20.50	20.39	-2.50	Standard Battery from host	5	Internal Fixed	1.040
11	2462 (High)	CCK	19.30	19.12	-4.06	Standard Battery from host	5	Internal Fixed	0.728
1	2412 (Low)	CCK	19.70	19.54	-3.62	Standard Battery from host	6	Internal Fixed	0.438
6	2437 (Mid.)	CCK	20.50	20.33	-3.84	Standard Battery from host	6	Internal Fixed	0.506
11	2462 (High)	CCK	19.30	19.12	-4.06	Standard Battery from host	6	Internal Fixed	0.342

NOTE:

5. Test configuration of each mode is described in section 3.
6. In this testing, the limit for General Population Spatial Peak averaged over 1g, **1.6 W/kg**, is applied.
7. Please see the Appendix A for the photo of the test configuration and also the data.
8. The variation of the EUT conducted power measured before and after SAR testing should not over 5%.

EUT			U.S. Robotics 802.11g 54Mbps USB Adapter			MODEL	USR5422		
ENVIRONMENTAL CONDITION			Air Temperature : 21.0°C, Liquid Temperature : 21.0°C Humidity : 60%RH						
TESTED BY			Johan Kuo						
Chan.	Freq. (MHz)	Modulate type	Conducted Power (dBm)		Power Drift (%)	Device Use Power	Device Test Position Mode	Antenna Position	Measured 1g SAR (W/kg)
			Begin Test	After Test					
1	2412 (Low)	OFDM	19.20	19.05	-3.39	Standard Battery from host	7	Internal Fixed	0.382
6	2437 (Mid.)	OFDM	19.80	19.67	-2.95	Standard Battery from host	7	Internal Fixed	0.395
11	2462 (High)	OFDM	18.50	18.30	-4.50	Standard Battery from host	7	Internal Fixed	0.291
1	2412 (Low)	OFDM	19.20	19.04	-3.62	Standard Battery from host	8	Internal Fixed	0.195
6	2437 (Mid.)	OFDM	19.80	19.65	-3.39	Standard Battery from host	8	Internal Fixed	0.197
11	2462 (High)	OFDM	18.50	18.40	-2.28	Standard Battery from host	8	Internal Fixed	0.144

NOTE:

1. Test configuration of each mode is described in section 3.
2. In this testing, the limit for General Population Spatial Peak averaged over 1g, **1.6 W/kg**, is applied.
3. Please see the Appendix A for the photo of the test configuration and also the data.
4. The variation of the EUT conducted power measured before and after SAR testing should not over 5%.

EUT			U.S. Robotics 802.11g 54Mbps USB Adapter			MODEL	USR5422		
ENVIRONMENTAL CONDITION			Air Temperature : 21.0°C, Liquid Temperature : 21.0°C Humidity : 60%RH						
TESTED BY			Johan Kuo						
Chan.	Freq. (MHz)	Modulate type	Conducted Power (dBm)		Power Drift (%)	Device Use Power	Device Test Position Mode	Antenna Position	Measured 1g SAR (W/kg)
			Begin Test	After Test					
1	2412 (Low)	CCK	19.70	19.60	-2.28	Standard Battery from host	9	Internal Fixed	1.120
6	2437 (Mid.)	CCK	20.50	20.67	3.99	Standard Battery from host	9	Internal Fixed	1.400
11	2462 (High)	CCK	19.30	19.19	-2.50	Standard Battery from host	9	Internal Fixed	1.050
1	2412 (Low)	CCK	19.70	19.53	-3.84	Standard Battery from host	10	Internal Fixed	0.443
6	2437 (Mid.)	CCK	20.50	20.43	-1.60	Standard Battery from host	10	Internal Fixed	0.515
11	2462 (High)	CCK	19.30	19.13	-3.84	Standard Battery from host	10	Internal Fixed	0.380

NOTE:

9. Test configuration of each mode is described in section 3.

10. In this testing, the limit for General Population Spatial Peak averaged over 1g, **1.6 W/kg**, is applied.

11. Please see the Appendix A for the photo of the test configuration and also the data.

12. The variation of the EUT conducted power measured before and after SAR testings should not over 5%.

EUT			U.S. Robotics 802.11g 54Mbps USB Adapter			MODEL	USR5422		
ENVIRONMENTAL CONDITION			Air Temperature : 21.0°C, Liquid Temperature : 21.0°C Humidity : 60%RH						
TESTED BY			Johan Kuo						
Chan.	Freq. (MHz)	Modulate type	Conducted Power (dBm)		Power Drift (%)	Device Use Power	Device Test Position Mode	Antenna Position	Measured 1g SAR (W/kg)
			Begin Test	After Test					
1	2412 (Low)	OFDM	19.20	19.06	-3.17	Standard Battery from host	11	Internal Fixed	0.524
6	2437 (Mid.)	OFDM	19.80	19.65	-3.39	Standard Battery from host	11	Internal Fixed	0.575
11	2462 (High)	OFDM	18.50	18.35	-3.39	Standard Battery from host	11	Internal Fixed	0.455
1	2412 (Low)	OFDM	19.20	19.05	-3.39	Standard Battery from host	12	Internal Fixed	0.200
6	2437 (Mid.)	OFDM	19.80	19.62	-4.06	Standard Battery from host	12	Internal Fixed	0.215
11	2462 (High)	OFDM	18.50	18.49	-0.23	Standard Battery from host	12	Internal Fixed	0.169

NOTE:

1. Test configuration of each mode is described in section 3.
2. In this testing, the limit for General Population Spatial Peak averaged over 1g, **1.6 W/kg**, is applied.
3. Please see the Appendix A for the photo of the test configuration and also the data.
4. The variation of the EUT conducted power measured before and after SAR testing should not over 5%.

5.3 SAR LIMITS

HUMAN EXPOSURE	SAR (W/kg)	
	(General Population / Uncontrolled Exposure Environment)	(Occupational / controlled Exposure Environment)
Spatial Average (whole body)	0.08	0.4
Spatial Peak (averaged over 1 g)	1.6	8.0
Spatial Peak (hands/wrists/feet/ankles averaged over 10 g)	4.0	20.0

NOTE

1. This limits accord to ANSI/IEEE C95.1 1992 – Safety Limit.
2. The EUT property been complied with the partial body exposure limit under the general population environment.

5.4 RECIPES FOR TISSUE SIMULATING LIQUIDS

For the measurement of the field distribution inside the SAM phantom, the phantom must be filled with 25 liters of tissue simulation liquid.

The following ingredients are used :

- Water- Deionized water (pure H₂O), resistivity _ 16 M - as basis for the liquid
- Sugar- Refined sugar in crystals, as available in food shops - to reduce relative permittivity
- Salt- Pure NaCl - to increase conductivity
- Cellulose- Hydroxyethyl-cellulose, medium viscosity (75-125 mPa.s, 2% in water, 20_C), CAS # 54290 - to increase viscosity and to keep sugar in solution
- Preservative- Preventol D-7 Bayer AG, D-51368 Leverkusen, CAS # 55965-84-9 - to prevent the spread of bacteria and molds
- DGMBE- Diethyleneglycol-monobuthyl ether (DGMBE), Fluka Chemie GmbH, CAS # 112-34-5 - to reduce relative permittivity

The Recipes For 2450MHz Simulating Liquid Table

Ingredient	Head Simulating Liquid 2450MHz(HSL-2450)	Muscle Simulating Liquid 2450MHz(MSL-2450)
Water	45%	69.83%
DGMBE	55%	30.17%
Salt	NA	NA
Dielectric Parameters at 22°C	f=2450MHz $\epsilon' = 39.2 \pm 5\%$ $s = 1.80 \pm 5\%$ S/m	f=2450MHz $\epsilon' = 52.7 \pm 5\%$ $s = 1.95 \pm 5\%$ S/m

The liquid nature is tested by Agilent Network Analyzer E8358A and Agilent Dielectric Probe Kit 85070D. Here are the procedure.

1. Turn Network Analyzer on and allow at least 30 min. warm up.
2. Mount dielectric probe kit so that interconnecting cable to Network Analyzer will not be moved during measurements or calibration.
3. Pour de-ionized water and measure water temperature ($\pm 1^\circ$).
4. Set water temperature in Agilent-Software (Calibration Setup).
5. Perform calibration.
6. Validate calibration with dielectric material of known properties (e.g. polished ceramic slab with >8mm thickness $\epsilon' = 10.0$, $\epsilon'' = 0.0$). If measured parameters do not fit within tolerance, repeat calibration (± 0.2 for ϵ' : ± 0.1 for ϵ'').
7. Conductivity can be calculated from ϵ'' by $s = \epsilon_0 \epsilon'' f [\text{GHz}] / 18$.
8. Measure liquid shortly after calibration. Repeat calibration every hour.
9. Stir the liquid to be measured. Take a sample (~50ml) with a syringe from the center of the liquid container.
10. Pour the liquid into a small glass flask. Hold the syringe at the bottom of the flask to avoid air bubbles.
11. Put the dielectric probe in the glass flask. Check that there are no air bubbles in front of the opening in the dielectric probe kit.
12. Perform measurements.
13. Adjust medium parameters in DASY4 for the frequencies necessary for the measurements ('Setup Config', select medium (e.g. Brain 900 MHz) and press 'Option' -button.
14. Select the current medium for the frequency of the validation (e.g. Setup Medium Brain 900 MHz).

Simulating Liquid

Liquid Type		HSL-2450		MSL-2450	
Simulating Liquid Temp.		21		21	
Test Date		2004 / 08 / 09		2004 / 08 / 09	
Tested By		Johan Kuo		Johan Kuo	
Freq. (MHz)	Liquid Parameter	Standard Value	Measurement Value	Standard Value	Measurement Value
2412	Permittivity (ε)	NA	NA	52.7507	50.8147
2437		NA	NA	52.7173	50.7402
2450		NA	NA	52.7000	50.6991
2462		NA	NA	52.6847	50.6638
2412	Conductivity (σ) S/m	NA	NA	1.9137	1.9267
2437		NA	NA	1.9376	1.9596
2450		NA	NA	1.9500	1.9771
2462		NA	NA	1.9670	1.9932
Dielectric Parameters Required at 22°C					

5.5 TEST EQUIPMENT FOR TISSUE PROPERTY

Item	Name	Band	Type	Series No.	Calibrated Until
1	Network Analyzer	Agilent	E8358A	US41480538	Mar. 24, 2005
2	Dielectric Probe	Agilent	85070D	US01440176	NA

NOTE:

- Before starting, all test equipment shall be warmed up for 30min.
- The tolerance ($k=1$) specified by Agilent for general dielectric measurements, deriving from inaccuracies in the calibration data, analyzer drift, and random errors, are usually $\pm 2.5\%$ and $\pm 5\%$ for measured permittivity and conductivity, respectively. However, the tolerances for the conductivity is smaller for material with large loss tangents, i.e., less than $\pm 2.5\%$ ($k=1$). It can be substantially smaller if more accurate methods are applied.



6. SYSTEM VALIDATION

The system validation was performed in the flat phantom with equipment listed in the following table. Since the SAR value is calculated from the measured electric field, dielectric constant and conductivity of the body tissue, and the SAR is proportional to the square of the electric field. So, the SAR value will be also proportional to the RF power input to the system validation dipole under the same test environment. In our system validation test, 250mW RF input power was used.

6.1 TEST EQUIPMENT

Item	Name	Band	Type	Series No.	Calibrated Until
1	SAM Phantom	S & P	QD000 P40 CA	PT-1150	NA
2	Signal Generator	R & S	SMP04	10001	May 05, 2005
3	E-Field Probe	S & P	ET3DV6	1790	Aug. 28, 2004
4	DAE	S & P	DAE3 V1	579	Aug. 14, 2004
5	Robot Positioner	Staubli Unimation	NA	NA	NA
6	Validation Dipole	S & P	D2450V2	737	Aug. 26, 2004

NOTE: Before starting the measurement, all test equipment shall be warmed up for 30min.

6.2 TEST PROCEDURE

Before the system performance check, we need only to tell the system which components (probe, medium, and device) are used for the system performance check; the system will take care of all parameters. The dipole must be placed beneath the flat section of the SAM Twin Phantom with the correct distance holder in place. The distance holder should touch the phantom surface with a light pressure at the reference marking (little cross) and be oriented parallel to the long side of the phantom. Accurate positioning is not necessary, since the system will search for the peak SAR location, except that the dipole arms should be parallel to the surface. The device holder for mobile phones can be left in place but should be rotated away from the dipole.



1. The "Power Reference Measurement" and "Power Drift Measurement" jobs are located at the beginning and end of the batch process. They measure the field drift at one single point in the liquid over the complete procedure. The indicated drift is mainly the variation of the amplifier output power. If it is too high (above ± 0.1 dB), the system performance check should be repeated; some amplifiers have very high drift during warm-up. A stable amplifier gives drift results in the DASY system below ± 0.02 dB.
2. The "Surface Check" job tests the optical surface detection system of the DASY system by repeatedly detecting the surface with the optical and mechanical surface detector and comparing the results. The output gives the detecting heights of both systems, the difference between the two systems and the standard deviation of the detection repeatability. Air bubbles or refraction in the liquid due to separation of the sugar-water mixture gives poor repeatability (above ± 0.1 mm). In that case it is better to abort the system performance check and stir the liquid. The difference between the optical surface detection and the actual surface depends on the probe and is specified with each probe. (It does not depend on the surface reflectivity or the probe angle to the surface within $\pm 30^\circ$.) However, varying breaking indices of different liquid compositions might also influence the distance. If the indicated difference varies from the actual setting, the probe parameter "optical surface
3. The "Area Scan" job measures the SAR above the dipole on a plane parallel to the surface. It is used to locate the approximate location of the peak SAR. The proposed scan uses large grid spacing for faster measurement; due to the symmetric field, the peak detection is reliable. If a finer graphic is desired, the grid spacing can be reduced. Grid spacing and orientation have no influence on the SAR result.
4. The "Zoom Scan" job measures the field in a volume around the peak SAR value assessed in the previous "Area Scan" job (for more information see the application note on SAR evaluation).



About the validation dipole positioning uncertainty, the constant and low loss dielectric spacer is used to establish the correct distance between the top surface of the dipole and the bottom surface of the phantom, the error component introduced by the uncertainty of the distance between the liquid (i.e., phantom shell) and the validation dipole in the DASY4 system is less than $\pm 0.1\text{mm}$.

$$SAR_{\text{tolerance}} [\%] = 100 \times \left(\frac{(a + d)^2}{a^2} - 1 \right)$$

As the closest distance is 10mm, the resulting tolerance $SAR_{\text{tolerance}} [\%]$ is $< 2\%$.

6.3 VALIDATION RESULT

ENVIRONMENTAL CONDITION	Temperature : 22.0°C, Humidity : 60%RH		
TESTED BY	Johan Kuo		
TEST DATE	2004/08/09		
2450MHz System Validation Test in the Muscle Simulating Liquid			
Required SAR (mW/g)	Measured SAR (mW/g)	Deviation (%)	Separation Distance
13.80 (1g)	14.00	1.45	10mm
6.36 (10g)	6.29	-1.10	10mm

NOTE: Please see Appendix for the photo of system validation test.

6.4 SYSTEM VALIDATION UNCERTAINTIES

In the table below, the system validation uncertainty with respect to the analytically assessed SAR value of a dipole source as given in the P1528 standard is given. This uncertainty is smaller than the expected uncertainty for mobile phone measurements due to the simplified setup and the symmetric field distribution.

Error Description	Tolerance (±%)	Probability Distribution	Divisor	(C _i)		Standard Uncertainty (±%)		(v _i)
				(1g)	(10g)	(1g)	(10g)	
Measurement System								
Probe Calibration	4.8	Normal	1	1	1	4.8	4.8	∞
Axial Isotropy	4.7	Rectangular	√3	1	1	2.7	2.7	∞
Hemispherical Isotropy	0	Rectangular	√3	1	1	0	0	∞
Boundary effect	1.0	Rectangular	√3	1	1	0.6	0.6	∞
Linearity	4.7	Rectangular	√3	1	1	2.7	2.7	∞
System Detection Limit	1.0	Rectangular	√3	1	1	0.6	0.6	∞
Readout Electronics	1.0	Normal	1	1	1	1.0	1.0	∞
Response Time	0	Rectangular	√3	1	1	0	0	∞
Integration Time	0	Rectangular	√3	1	1	0	0	∞
RF Ambient Conditions	3.0	Rectangular	√3	1	1	1.7	1.7	∞
Probe Positioner	0.4	Rectangular	√3	1	1	0.2	0.2	∞
Probe positioning	2.9	Rectangular	√3	1	1	1.7	1.7	∞
Algorithms for Max. SAR Evaluation	1.0	Rectangular	√3	1	1	0.6	0.6	∞
Dipole								
Dipole Axis to Liquid Distance	2.0	Rectangular	√3	1	1	1.2	1.2	∞
Input power and SAR drift measurement	4.7	Rectangular	√3	1	1	2.7	2.7	∞
Phantom and Tissue Parameters								
Phantom Uncertainty	4.0	Rectangular	√3	1	1	2.3	2.3	∞
Liquid Conductivity (target)	5.0	Rectangular	√3	0.64	0.43	1.8	1.2	∞
Liquid Conductivity (measurement)	2.5	Normal	1	0.64	0.43	1.6	1.1	∞
Liquid Permittivity (target)	5.0	Rectangular	√3	0.6	0.49	1.7	1.4	∞
Liquid Permittivity (measurement)	2.5	Normal	1	0.6	0.49	1.5	1.2	∞
Combined Standard Uncertainty						8.4	8.1	∞
Coverage Factor for 95%						kp=2		
Expanded Uncertainty (K=2)						16.8	16.2	

NOTE: About the system validation uncertainty assessment, please reference the section 7.



7. MEASUREMENT SAR PROCEDURE UNCERTAINTIES

The assessment of spatial peak SAR of the hand handheld devices is according to IEEE 1528. All testing situation shall be met below these requirement.

- The system is used by an experienced engineer who follows the manual and the guidelines taught during the training provided by SPEAG.
- The probe has been calibrated within the requested period and the stated uncertainty for the relevant frequency bands does not exceed 4.8% ($k=1$).
- The validation dipole has been calibrated within the requested period and the system performance check has been successful.
- The DAE unit has been calibrated within the within the requested period.
- The minimum distance between the probe sensor and inner phantom shell is selected to be between 4 and 5mm.
- The operational mode of the DUT is CW, CDMA, FDMA or TDMA (GSM, DCS, PCS, IS136 and PDC) and the measurement/integration time per point is >500 ms.
- The dielectric parameters of the liquid have been assessed using Agilent 85070D dielectric probe kit or a more accurate method.
- The dielectric parameters are within 5% of the target values.
- The DUT has been positioned as described in section 3.

7.1 PROBE CALIBRATION UNCERTAINTY

SPEAG conducts the probe calibration in compliance with international and national standards (e.g. IEEE 1528, EN50361, IEC 62209, etc.) under ISO17025. The uncertainties are stated on the calibration certificate. For the most relevant frequency bands, these values do not exceed 4.8% ($k=1$). If evaluations of other bands are performed for which the uncertainty exceeds these values, the uncertainty tables given in the summary have to be revised accordingly.

7.2 ISOTROPY UNCERTAINTY

The axial isotropy tolerance accounts for probe rotation around its axis while the hemispherical isotropy error includes all probe orientations and field polarizations. These parameters are assessed by SPEAG during initial calibration. In 2001, SPEAG further tightened its quality controls and warrants that the maximal deviation from axial isotropy is ± 0.20 dB, while the maximum deviation of hemispherical isotropy is ± 0.40 dB, corresponding to $\pm 4.7\%$ and $\pm 9.6\%$, respectively. A weighting factor of c_p equal to 0.5 can be applied, since the axis of the probe deviates less than 30 degrees from the normal surface orientation.

7.3 BOUNDARY EFFECT UNCERTAINTY

The effect can be estimated according to the following error approximation formula

$$SAR_{tolerance}[\%] = SAR_{be}[\%] \times \frac{(d_{be} + d_{step})^2}{2d_{step}} e^{\frac{d_{be}}{\delta/2}}$$

$$d_{be} + d_{step} < 10mm$$

The parameter d_{be} is the distance in mm between the surface and the closest measurement point used in the averaging process; d_{step} is the separation distance in mm between the first and second measurement points; d is the minimum penetration depth in mm within the head tissue equivalent liquids (i.e., $d = 13.95$ mm at 3GHz); SAR_{be} is the deviation between the measured SAR value at the distance d_{be} from the boundary and the wave-guide analytical value SAR_{ref} . DASY4 applies a boundary effect compensation algorithm according to IEEE 1528, which is possible since the axis of the probe never deviates more than 30 degrees from the normal surface orientation. $SAR_{be}[\%]$ is assessed during the calibration process and SPEAG warrants that the uncertainty at distances larger than 4mm is always less than 1%. In summary, the worst case boundary effect SAR tolerance[%] for scanning distances larger than 4mm is $< \pm 0.8\%$.

7.4 PROBE LINEARITY UNCERTAINTY

Field probe linearity uncertainty includes errors from the assessment and compensation of the diode compression effects for CW and pulsed signals with known duty cycles. This error is assessed using the procedure described in IEEE 1528. For SPEAG field probes, the measured difference between CW and pulsed signals, with pulse frequencies between 10 Hz and 1 kHz and duty cycles between 1 and 100, is $< \pm 0.20$ dB ($< \pm 4.7\%$).

7.5 READOUT ELECTRONICS UNCERTAINTY

All uncertainties related to the probe readout electronics (DAE unit), including the gain and linearity of the instrumentation amplifier, its loading effect on the probe, and accuracy of the signal conversion algorithm, have been assessed accordingly to IEEE 1528. The combination (root-sum-square RSS method) of these components results in an overall maximum error of $\pm 1.0\%$.

7.6 RESPONSE TIME UNCERTAINTY

The time response of the field probes is assessed by exposing the probe to a well-controlled electric field producing SAR larger than 2.0 W/kg at the tissue medium surface. The signal response time is evaluated as the time required by the system to reach 90% of the expected final value after an on/of switch of the power source. Analytically, it can be expressed as:

$$SAR_{tolerance} [\%] = 100 \times \left(\frac{T_m}{T_m + \tau e^{-T_m/\tau}} - 1 \right)$$

where T_m is 500 ms, i.e., the time between measurement samples, and τ the time constant. The response time τ of SPEAG's probes is <5 ms. In the current implementation, DASY4 waits longer than 100 ms after having reached the grid point before starting a measurement, i.e., the response time uncertainty is negligible.

7.7 INTEGRATION TIME UNCERTAINTY

If the device under test does not emit a CW signal, the integration time applied to measure the electric field at a specific point may introduce additional uncertainties due to the discretization and can be assessed as follows

$$SAR_{tolerance} [\%] = 100 \times \sum_{allsub-frames} \frac{t_{frame}}{t_{integration}} \frac{slot_{idle}}{slot_{total}}$$

The tolerances for the different systems are given in Table 7.1, whereby the worst-case $SAR_{tolerance}$ is 2.6%.

System	$SAR_{tolerance} \%$
CW	0
CDMA*	0
WCDMA*	0
FDMA	0
IS-136	2.6
PDC	2.6
GSM/DCS/PCS	1.7
DECT	1.9
Worst-Case	2.6

Table 7.1

7.8 PROBE POSITIONER MECHANICAL TOLERANCE

The mechanical tolerance of the field probe positioner can introduce probe positioning uncertainties. The resulting SAR uncertainty is assessed by comparing the SAR obtained according to the specifications of the probe positioner with respect to the actual position defined by the geometric enter of the probe sensors. The tolerance is determined as:

$$SAR_{tolerance} [\%] = 100 \times \frac{d_{ss}}{\delta/2}$$

The specified repeatability of the RX robot family used in DASY4 systems is $\pm 25 \mu\text{m}$. The absolute accuracy for short distance movements is better than $\pm 0.1\text{mm}$, i.e., the $SAR_{tolerance} [\%]$ is better than 1.5% (rectangular).



7.9 PROBE POSITIONING

The probe positioning procedures affect the tolerance of the separation distance between the probe tip and the phantom surface as:

$$SAR_{tolerance} [\%] = 100 \times \frac{d_{ph}}{\delta/2}$$

where d_{ph} is the maximum deviation of the distance between the probe tip and the phantom surface. The optical surface detection has a precision of better than 0.2 mm, resulting in an $SAR_{tolerance} [\%]$ of <2.9% (rectangular distribution). Since the mechanical detection provides better accuracy, 2.9% is a worst-case figure for DASY4 system.

7.10 PHANTOM UNCERTAINTY

The SAR measurement uncertainty due to SPEAG phantom shell production tolerances has been evaluated using

$$SAR_{tolerance} [\%] \cong 100 \times \frac{2d}{a}, \quad d \ll a$$

For a maximum deviation d of the inner and outer shell of the phantom from that specified in the CAD file of ± 0.2 mm, and a 10mm spacing a between source and tissue liquid, the calculated phantom uncertainty is $\pm 4.0\%$.

7.11 DASY4 UNCERTAINTY BUDGET

Error Description	Tolerance (±%)	Probability Distribution	Divisor	(C _i)		Standard Uncertainty (±%)		(v _i)
				(1g)	(10g)	(1g)	(10g)	
Measurement System								
Probe Calibration	4.8	Normal	1	1	1	4.8	4.8	∞
Axial Isotropy	4.7	Rectangular	√3	1	1	1.9	1.9	∞
Hemispherical Isotropy	9.6	Rectangular	√3	1	1	3.9	3.9	∞
Boundary effect	1.0	Rectangular	√3	1	1	0.6	0.6	∞
Linearity	4.7	Rectangular	√3	1	1	2.7	2.7	∞
System Detection Limit	1.0	Rectangular	√3	1	1	0.6	0.6	∞
Readout Electronics	1.0	Normal	1	1	1	1.0	1.0	∞
Response Time	0.8	Rectangular	√3	1	1	0.5	0.5	∞
Integration Time	2.6	Rectangular	√3	1	1	1.5	1.5	∞
RF Ambient Conditions	3.0	Rectangular	√3	1	1	1.7	1.7	∞
Probe Positioner	0.4	Rectangular	√3	1	1	0.2	0.2	∞
Probe positioning	2.9	Rectangular	√3	1	1	1.7	1.7	∞
Algorithms for Max. SAR Evaluation	1.0	Rectangular	√3	1	1	0.6	0.6	∞
Test EUT Related								
Device Positioning	2.9	Normal	1	1	1	2.9	2.9	875
Device Holder	3.6	Normal	1	1	1	3.6	3.6	5
Power Drift	5	Rectangular	√3	1	1	2.9	2.9	∞
Phantom and Tissue Parameters								
Phantom Uncertainty	4.0	Rectangular	√3	1	1	2.3	2.3	∞
Liquid Conductivity (target)	5.0	Rectangular	√3	0.64	0.43	1.8	1.2	∞
Liquid Conductivity (measurement)	2.5	Normal	1	0.64	0.43	1.6	1.1	∞
Liquid Permittivity (target)	5.0	Rectangular	√3	0.6	0.49	1.7	1.4	∞
Liquid Permittivity (measurement)	2.5	Normal	1	0.6	0.49	1.5	1.2	∞
Combined Standard Uncertainty						10.3	10	331
Coverage Factor for 95%						kp=2		
Expanded Uncertainty (K=2)						20.6	20.1	

Table 7.2

The table 7.2: Worst-Case uncertainty budget for DASY4 assessed according to IEEE P1528. The budget is valid for the frequency range 300MHz ~ 3 GHz and represents a worst-case analysis. For specific tests and configurations, the uncertainty could be considerable smaller.



8. INFORMATION ON THE TESTING LABORATORIES

We, ADT Corp., were founded in 1988 to provide our best service in EMC, Radio, Telecom and Safety consultation. Our laboratories are accredited and approved by the following approval agencies according to ISO/IEC 17025, Guide 25 or EN 45001:

USA	FCC, NVLAP, UL, A2LA
Germany	TUV Rheinland
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Canada	INDUSTRY CANADA , CSA
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Netherlands	Telefication
Singapore	PSB , GOST-ASIA(MOU)
Russia	CERTIS(MOU)

Copies of accreditation certificates of our laboratories obtained from approval agencies can be downloaded from our web site:

www.adt.com.tw/index.5/phtml. If you have any comments, please feel free to contact us at the following:

Linko EMC/RF Lab:

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Fax: 886-3-3185050

Linko RF Lab.

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Web Site: www.adt.com.tw

The address and road map of all our labs can be found in our web site also.

Report Format Version 1.5

APPENDIX A: TEST CONFIGURATIONS AND TEST DATA

A1: TEST CONFIGURATION

Mode 1 Compaq N800C Bottom Position



The bottom of the EUT to the flat phantom distance 7 mm

Mode 2 Compaq N800C Tip Position



The tip of the EUT to the flat phantom distance 0 mm

Mode 3 Compaq N800C Bottom Position



The bottom of the EUT to the flat phantom distance 7 mm

Mode 4 Compaq N800C Tip Position



The tip of the EUT to the flat phantom distance 0 mm

Mode 5 IBM ThinkPad X31 Bottom Position



The bottom of the EUT to the flat phantom distance 7 mm

Mode 6 IBM ThinkPad X31 Tip Position



The tip of the EUT to the flat phantom distance 0 mm

Mode 7 IBM ThinkPad X31 Bottom Position



The bottom of the EUT to the flat phantom distance 7 mm

Mode 8 IBM ThinkPad X31 Tip Position



The tip of the EUT to the flat phantom distance 0 mm

Mode 9 IBM ThinkPad X20 Bottom Position



The bottom of the EUT to the flat phantom distance 6 mm

Mode 10 IBM ThinkPad X20 Tip Position



The tip of the EUT to the flat phantom distance 0 mm

Mode 11 IBM ThinkPad X20 Bottom Position



The bottom of the EUT to the flat phantom distance 6 mm

Mode 12 IBM ThinkPad X20 Tip Position



The tip of the EUT to the flat phantom distance 0 mm

EUT Photo



Liquid Level Photo

MSL 2450MHz D=150mm



A2 : TEST DATA

Date/Time: 08/09/04 09:57:58

Test Laboratory: Advance Data Technology

USR5422 Compaq N800C 11b Bottom Mode 1 Ch 1

DUT: 11G USB Dongle ; Type: WG111T ; Test Channel Frequency: 2412 MHz

Communication System: 802.11b ; Frequency: 2412 MHz ; Duty Cycle: 1:1 ; Modulation type: CCK
Medium: MSL2450 ($\sigma = 1.9267$ mho/m, $\epsilon_r = 50.8147$, $\rho = 1000$ kg/m³) ; Liquid level : 150mm
Phantom section: Flat Section ; Separation distance : 7 mm (The bottom side of the EUT to the Phantom)

Antenna type : Internal Antenna ; Air temp. : 22.0 degrees ; Liquid temp. : 21.0 degrees

DASY4 Configuration:

- Probe: ET3DV6 - SN1790 ; ConvF(4.4, 4.4, 4.4) ; Calibrated: 2003/8/29
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn579 ; Calibrated: 2003/8/15
- Phantom: SAM 12 ; Type: SAM V4.0 ; Serial: TP 1202
- Measurement SW: DASY4, V4.1 Build 47 ; Postprocessing SW: SEMCAD, V1.6 Build 115

Low Channel/Area Scan (5x8x1): Measurement grid: dx=15mm, dy=15mm

Reference Value = 13.6 V/m

Power Drift = -0.2 dB

Maximum value of SAR = 1.01 mW/g

Low Channel/Zoon Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

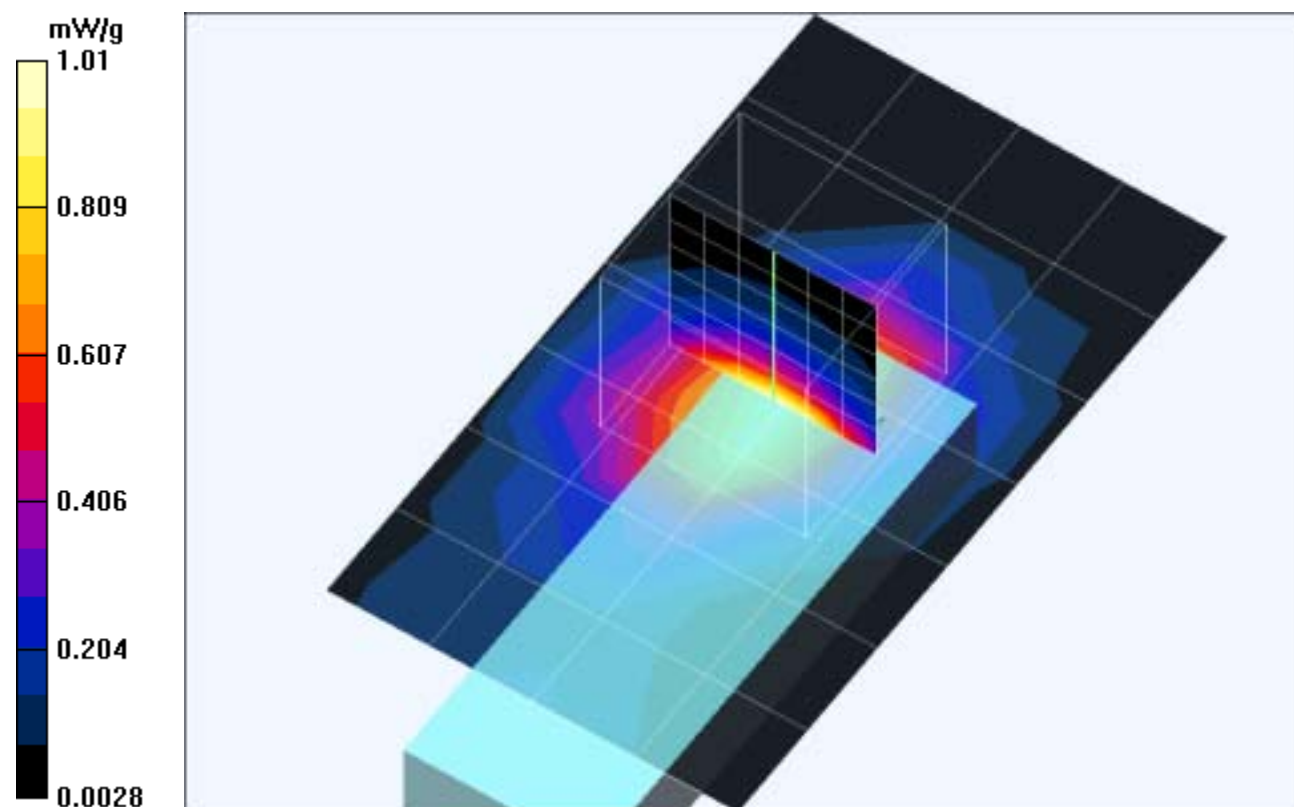
Peak SAR (extrapolated) = 2.39 W/kg

SAR(1 g) = 0.945 mW/g; SAR(10 g) = 0.449 mW/g

Reference Value = 13.6 V/m

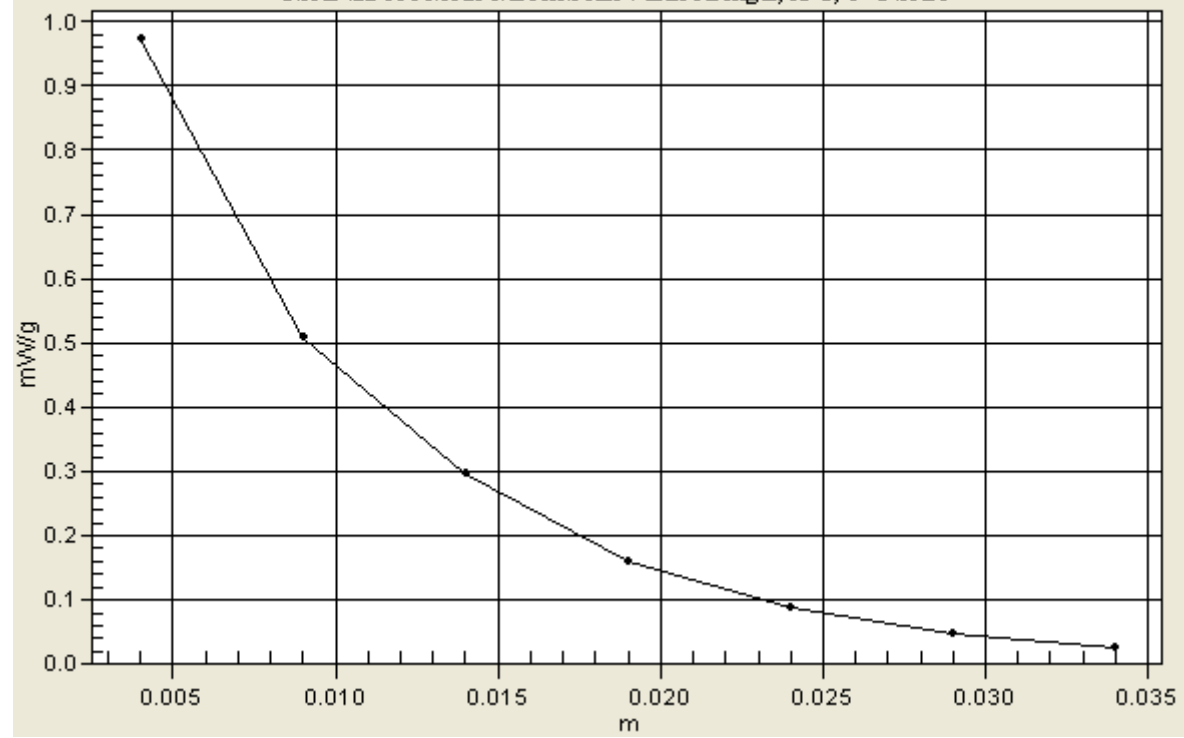
Power Drift = -0.2 dB

Maximum value of SAR = 0.972 mW/g



Averaged SAR

USR5422 11b Mode 1/Zoom Scan/V alue Along Z, X=3, Y=3 SAR



Test Laboratory: Advance Data Technology

USR5422 Compaq N800C 11b Bottom Mode 1 Ch 6

DUT: 11G USB Dongle ; Type: WG111T ; Test Channel Frequency: 2437 MHz

Communication System: 802.11b ; Frequency: 2437 MHz ; Duty Cycle: 1:1 ; Modulation type: CCK
Medium: MSL2450 ($\sigma = 1.9596$ mho/m, $\epsilon_r = 50.7402$, $\rho = 1000$ kg/m³) ; Liquid level : 150mm
Phantom section: Flat Section ; Separation distance : 7 mm (The bottom side of the EUT to the Phantom)

Antenna type : Internal Antenna ; Air temp. : 22.0 degrees ; Liquid temp. : 21.0 degrees

DASY4 Configuration:

- Probe: ET3DV6 - SN1790 ; ConvF(4.4, 4.4, 4.4) ; Calibrated: 2003/8/29
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn579 ; Calibrated: 2003/8/15
- Phantom: SAM 12 ; Type: SAM V4.0 ; Serial: TP 1202
- Measurement SW: DASY4, V4.1 Build 47 ; Postprocessing SW: SEMCAD, V1.6 Build 115

Middle Channel/Area Scan (5x8x1): Measurement grid: dx=15mm, dy=15mm

Reference Value = 13 V/m

Power Drift = -0.1 dB

Maximum value of SAR = 0.925 mW/g

Middle Channel/Zoon Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

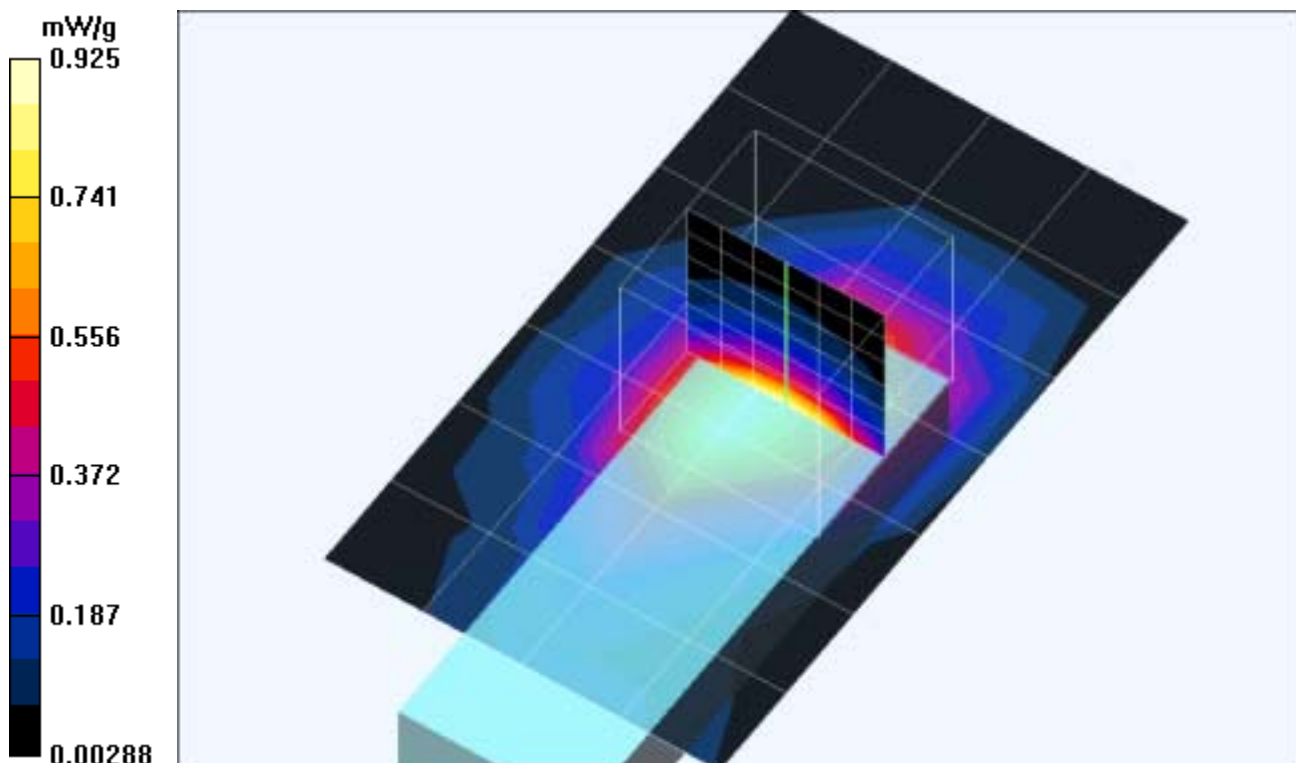
Peak SAR (extrapolated) = 1.78 W/kg

SAR(1 g) = 0.842 mW/g; SAR(10 g) = 0.426 mW/g

Reference Value = 13 V/m

Power Drift = -0.1 dB

Maximum value of SAR = 0.887 mW/g



Test Laboratory: Advance Data Technology

USR5422 Compaq N800C 11b Bottom Mode 1 Ch 11

DUT: 11G USB Dongle ; Type: WG111T ; Test Channel Frequency: 2462 MHz

Communication System: 802.11b ; Frequency: 2462 MHz ; Duty Cycle: 1:1 ; Modulation type: CCK
Medium: MSL2450 ($\sigma = 1.9932 \text{ mho/m}$, $\epsilon_r = 50.6638$, $\rho = 1000 \text{ kg/m}^3$) ; Liquid level : 150mm
Phantom section: Flat Section ; Separation distance : 7 mm (The bottom side of the EUT to the Phantom)

Antenna type : Internal Antenna ; Air temp. : 22.0 degrees ; Liquid temp. : 21.0 degrees

DASY4 Configuration:

- Probe: ET3DV6 - SN1790 ; ConvF(4.4, 4.4, 4.4) ; Calibrated: 2003/8/29
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn579 ; Calibrated: 2003/8/15
- Phantom: SAM 12 ; Type: SAM V4.0 ; Serial: TP 1202
- Measurement SW: DASY4, V4.1 Build 47 ; Postprocessing SW: SEMCAD, V1.6 Build 115

High Channel/Area Scan (5x8x1): Measurement grid: dx=15mm, dy=15mm

Reference Value = 11.6 V/m

Power Drift = -0.2 dB

Maximum value of SAR = 0.82 mW/g

High Channel/Zoon Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

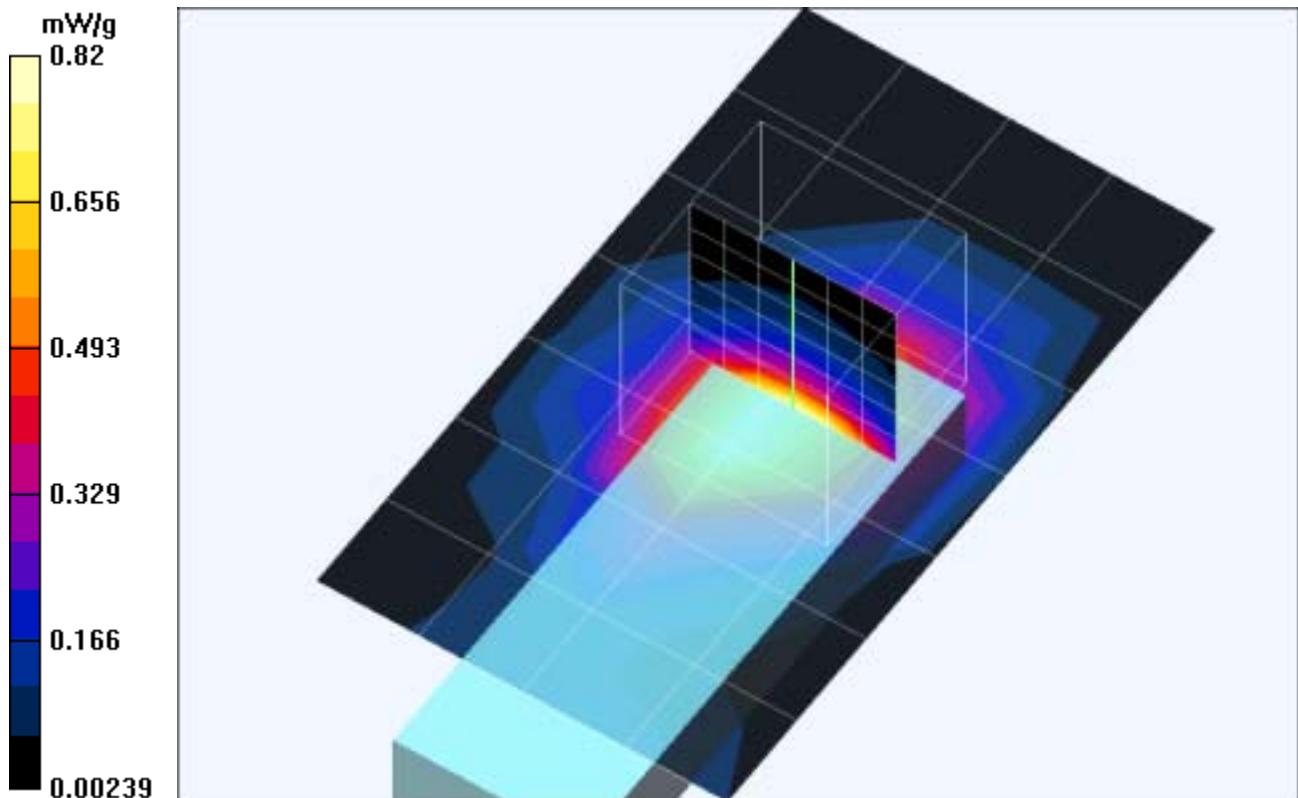
Peak SAR (extrapolated) = 1.51 W/kg

SAR(1 g) = 0.724 mW/g; SAR(10 g) = 0.362 mW/g

Reference Value = 11.6 V/m

Power Drift = -0.2 dB

Maximum value of SAR = 0.771 mW/g



Test Laboratory: Advance Data Technology

USR5422 Compaq N800C 11b Tip Mode 2 Ch 1

DUT: U.S. Robotics 802.11g 54Mbps USB Adapter ; Type: USR5422 ; Test Channel
Frequency: 2412 MHz

Communication System: 802.11b ; Frequency: 2412 MHz; Duty Cycle: 1:1; Modulation type: CCK
 Medium: MSL2450 ($\sigma = 1.9267$ mho/m, $\epsilon_r = 50.8147$, $\rho = 1000$ kg/m³) ; Liquid level : 150 mm

Phantom section: Flat Section ; Separation distance : 0 mm (The tip of the EUT to the Phantom)

Antenna type : Internal Antenna ; Air temp. : 22.0 degrees ; Liquid temp. : 21.0 degrees

DASY4 Configuration:

- Probe: ET3DV6 - SN1790 ; ConvF(4.4, 4.4, 4.4) ; Calibrated: 2003/8/29
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn579; Calibrated: 2003/8/15
- Phantom: SAM 12; Type: SAM V4.0; Serial: TP 1202
- Measurement SW: DASY4, V4.1 Build 47; Postprocessing SW: SEMCAD, V1.6 Build 115

Low Channel/Area Scan (5x6x1): Measurement grid: dx=15mm, dy=15mm

Reference Value = 15.5 V/m

Power Drift = -0.2 dB

Maximum value of SAR = 0.444 mW/g

Low Channel/Zoon Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

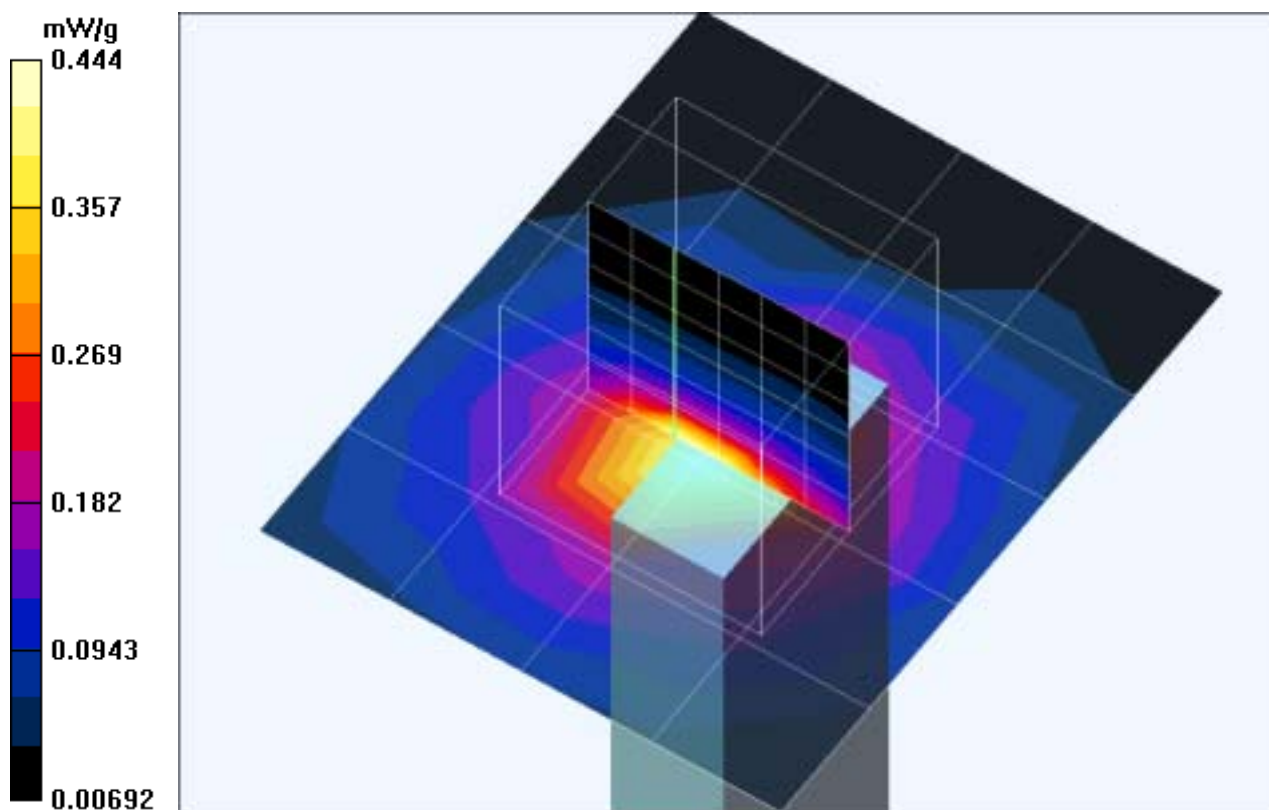
Peak SAR (extrapolated) = 1.18 W/kg

SAR(1 g) = 0.426 mW/g; SAR(10 g) = 0.187 mW/g

Reference Value = 15.5 V/m

Power Drift = -0.2 dB

Maximum value of SAR = 0.466 mW/g



Test Laboratory: Advance Data Technology

USR5422 Compaq N800C 11b Tip Mode 2 Ch 6

**DUT: U.S. Robotics 802.11g 54Mbps USB Adapter ; Type: USR5422 ; Test Channel
Frequency: 2437 MHz**

Communication System: 802.11b ; Frequency: 2437 MHz; Duty Cycle: 1:1; Modulation type: CCK
Medium: MSL2450 ($\sigma = 1.9596$ mho/m, $\epsilon_r = 50.7402$, $\rho = 1000$ kg/m³) ; Liquid level : 150 mm

Phantom section: Flat Section ; Separation distance : 0 mm (The tip of the EUT to the Phantom)

Antenna type : Internal Antenna ; Air temp. : 22.0 degrees ; Liquid temp. : 21.0 degrees

DASY4 Configuration:

- Probe: ET3DV6 - SN1790 ; ConvF(4.4, 4.4, 4.4) ; Calibrated: 2003/8/29
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn579; Calibrated: 2003/8/15
- Phantom: SAM 12; Type: SAM V4.0; Serial: TP 1202
- Measurement SW: DASY4, V4.1 Build 47; Postprocessing SW: SEMCAD, V1.6 Build 115

Middle Channel/Area Scan (5x6x1): Measurement grid: dx=15mm, dy=15mm

Reference Value = 16.9 V/m

Power Drift = -0.2 dB

Maximum value of SAR = 0.533 mW/g

Middle Channel/Zoon Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

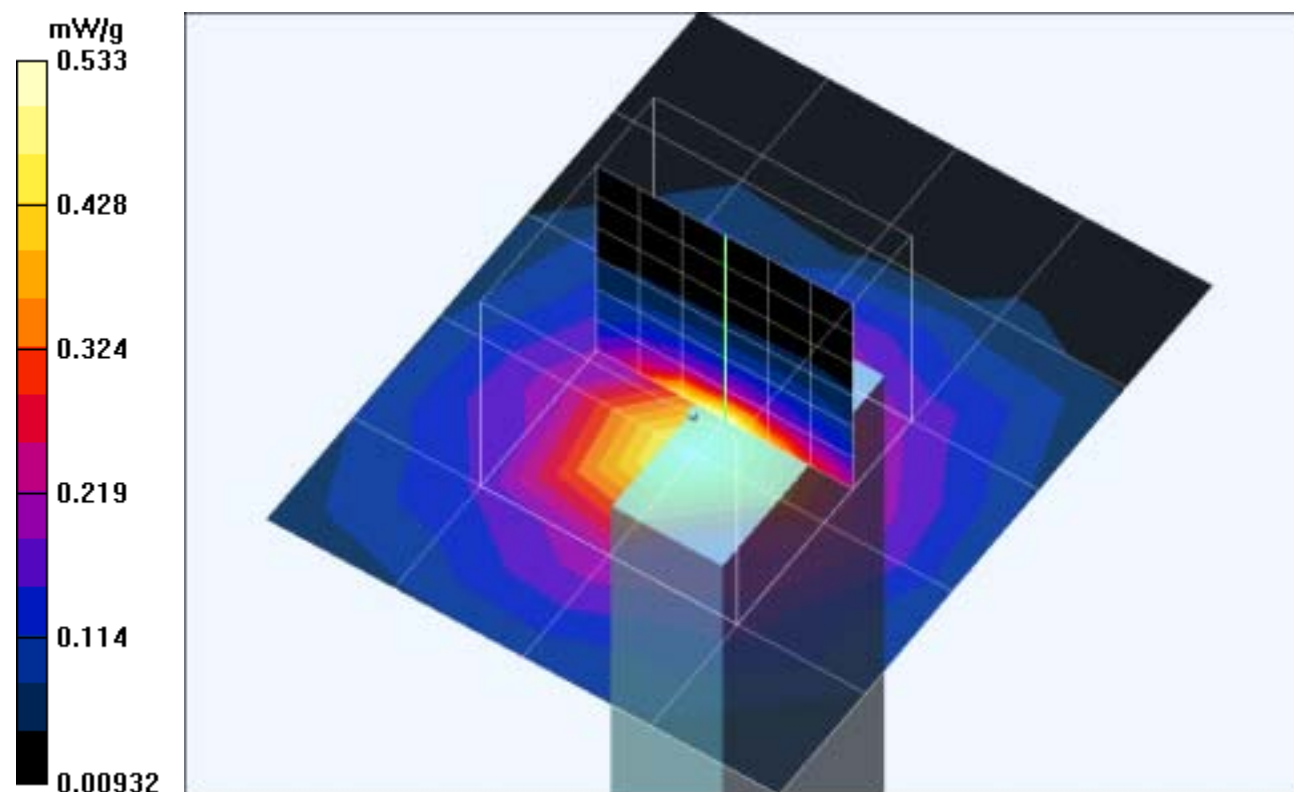
Peak SAR (extrapolated) = 1.41 W/kg

SAR(1 g) = 0.504 mW/g; SAR(10 g) = 0.221 mW/g

Reference Value = 16.9 V/m

Power Drift = -0.2 dB

Maximum value of SAR = 0.559 mW/g



Test Laboratory: Advance Data Technology

USR5422 Compaq N800C 11b Tip Mode 2 Ch 11

DUT: U.S. Robotics 802.11g 54Mbps USB Adapter ; Type: USR5422 ; Test Channel Frequency: 2462 MHz

Communication System: 802.11b ; Frequency: 2462 MHz; Duty Cycle: 1:1; Modulation type: CCK
Medium: MSL2450 ($\sigma = 1.9932$ mho/m, $\epsilon_r = 50.6638$, $\rho = 1000$ kg/m³) ; Liquid level : 150 mm

Phantom section: Flat Section ; Separation distance : 0 mm (The tip of the EUT to the Phantom)

Antenna type : Internal Antenna ; Air temp. : 22.0 degrees ; Liquid temp. : 21.0 degrees

DASY4 Configuration:

- Probe: ET3DV6 - SN1790 ; ConvF(4.4, 4.4, 4.4) ; Calibrated: 2003/8/29
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn579; Calibrated: 2003/8/15
- Phantom: SAM 12; Type: SAM V4.0; Serial: TP 1202
- Measurement SW: DASY4, V4.1 Build 47; Postprocessing SW: SEMCAD, V1.6 Build 115

High Channel/Area Scan (5x6x1): Measurement grid: dx=15mm, dy=15mm

Reference Value = 13.9 V/m

Power Drift = -0.2 dB

Maximum value of SAR = 0.37 mW/g

High Channel/Zoon Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

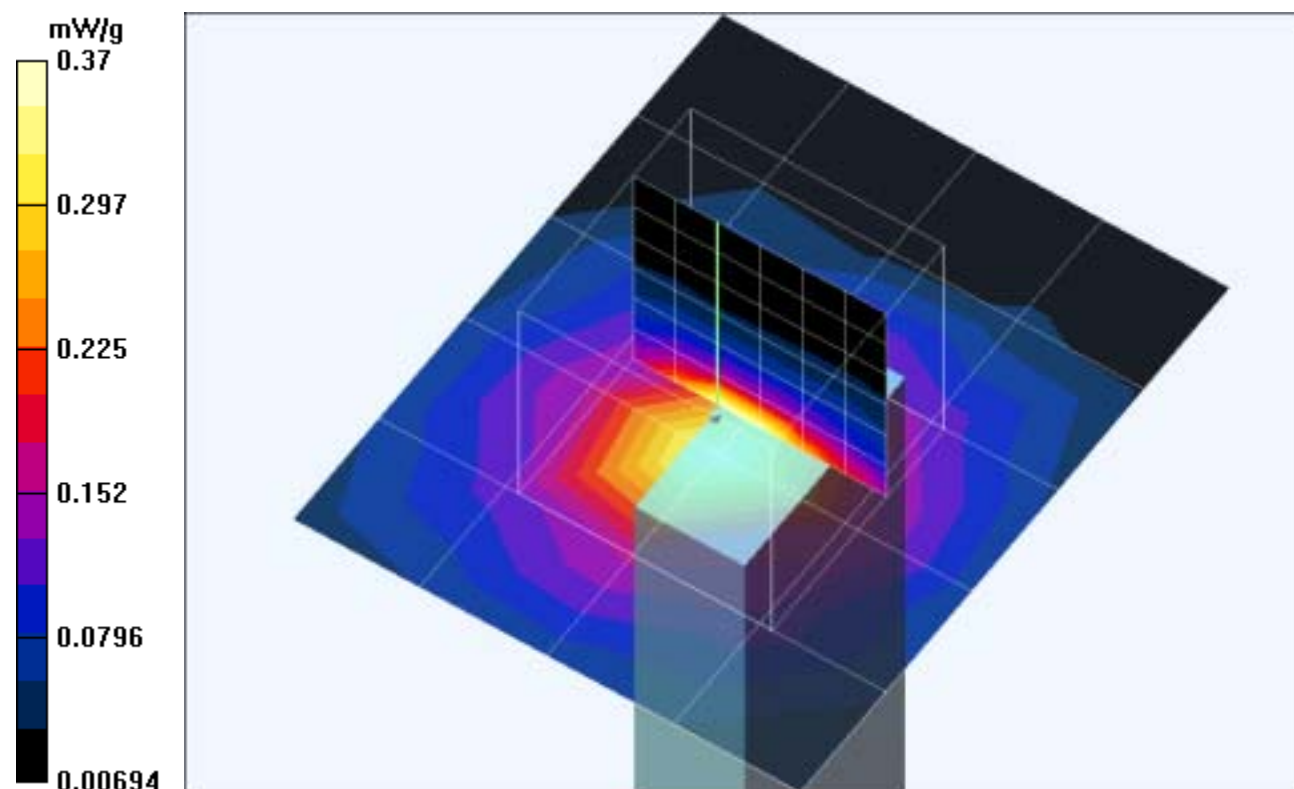
Peak SAR (extrapolated) = 1.01 W/kg

SAR(1 g) = 0.356 mW/g; SAR(10 g) = 0.157 mW/g

Reference Value = 13.9 V/m

Power Drift = -0.2 dB

Maximum value of SAR = 0.37 mW/g



Test Laboratory: Advance Data Technology

USR5422 Compaq N800C 11g Bottom Mode 3 Ch 1

DUT: U.S. Robotics 802.11g 54Mbps USB Adapter ; Type: USR5422 ; Test Channel Frequency: 2412 MHz

Communication System: 802.11g ; Frequency: 2412 MHz ; Duty Cycle: 1:1 ; Modulation type: OFDM

Medium: MSL2450 ($\sigma = 1.9267$ mho/m, $\epsilon_r = 50.8147$, $\rho = 1000$ kg/m³) ; Liquid level : 150mm

Phantom section: Flat Section ; Separation distance : 7 mm (The bottom side of the EUT to the Phantom)

Antenna type : Internal Antenna ; Air temp. : 22.0 degrees ; Liquid temp. : 21.0 degrees

DASY4 Configuration:

- Probe: ET3DV6 - SN1790 ; ConvF(4.4, 4.4, 4.4) ; Calibrated: 2003/8/29
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn579 ; Calibrated: 2003/8/15
- Phantom: SAM 12 ; Type: SAM V4.0 ; Serial: TP 1202
- Measurement SW: DASY4, V4.1 Build 47 ; Postprocessing SW: SEMCAD, V1.6 Build 115

Low Channel/Area Scan (5x8x1): Measurement grid: dx=15mm, dy=15mm

Reference Value = 7.19 V/m

Power Drift = -0.2 dB

Maximum value of SAR = 0.417 mW/g

Low Channel/Zoon Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

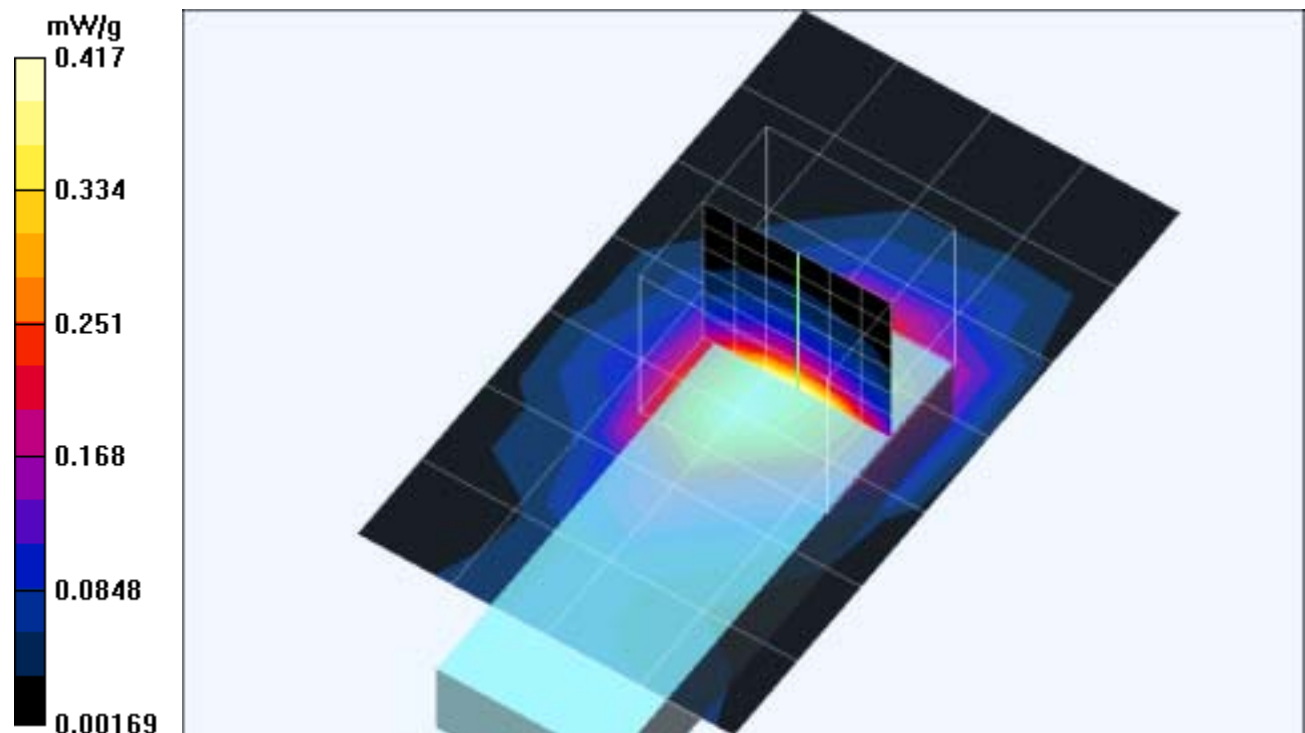
Peak SAR (extrapolated) = 0.802 W/kg

SAR(1 g) = 0.385 mW/g; SAR(10 g) = 0.194 mW/g

Reference Value = 7.19 V/m

Power Drift = -0.2 dB

Maximum value of SAR = 0.407 mW/g



Test Laboratory: Advance Data Technology

USR5422 Compaq N800C 11g Bottom Mode 3 Ch 6

DUT: U.S. Robotics 802.11g 54Mbps USB Adapter ; Type: USR5422 ; Test Channel Frequency: 2437 MHz

Communication System: 802.11g ; Frequency: 2437 MHz ; Duty Cycle: 1:1 ; Modulation type: OFDM

Medium: MSL2450 ($\sigma = 1.9596$ mho/m, $\epsilon_r = 50.7402$, $\rho = 1000$ kg/m³) ; Liquid level : 150mm

Phantom section: Flat Section ; Separation distance : 7 mm (The bottom side of the EUT to the Phantom)

Antenna type : Internal Antenna ; Air temp. : 22.0 degrees ; Liquid temp. : 21.0 degrees

DASY4 Configuration:

- Probe: ET3DV6 - SN1790 ; ConvF(4.4, 4.4, 4.4) ; Calibrated: 2003/8/29
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn579 ; Calibrated: 2003/8/15
- Phantom: SAM 12 ; Type: SAM V4.0 ; Serial: TP 1202
- Measurement SW: DASY4, V4.1 Build 47 ; Postprocessing SW: SEMCAD, V1.6 Build 115

Middle Channel/Area Scan (5x8x1): Measurement grid: dx=15mm, dy=15mm

Reference Value = 7.62 V/m

Power Drift = -0.2 dB

Maximum value of SAR = 0.403 mW/g

Middle Channel/Zoon Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

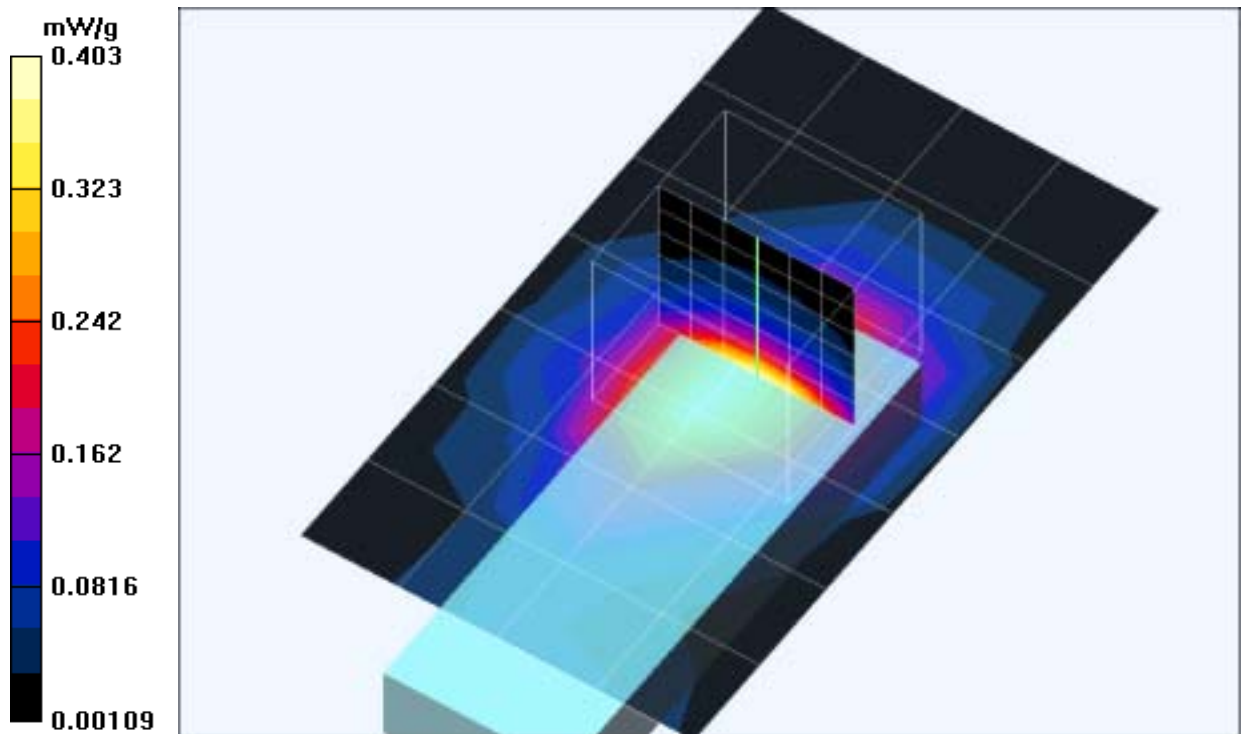
Peak SAR (extrapolated) = 0.815 W/kg

SAR(1 g) = 0.394 mW/g; SAR(10 g) = 0.199 mW/g

Reference Value = 7.62 V/m

Power Drift = -0.2 dB

Maximum value of SAR = 0.416 mW/g



Test Laboratory: Advance Data Technology

USR5422 Compaq N800C 11g Bottom Mode 3 Ch 11

DUT: U.S. Robotics 802.11g 54Mbps USB Adapter ; Type: USR5422 ; Test Channel Frequency: 2462 MHz

Communication System: 802.11g ; Frequency: 2462 MHz ; Duty Cycle: 1:1 ; Modulation type: OFDM

Medium: MSL2450 ($\sigma = 1.9932$ mho/m, $\epsilon_r = 50.6638$, $\rho = 1000$ kg/m³) ; Liquid level : 150mm

Phantom section: Flat Section ; Separation distance : 7 mm (The bottom side of the EUT to the Phantom)

Antenna type : Internal Antenna ; Air temp. : 22.0 degrees ; Liquid temp. : 21.0 degrees

DASY4 Configuration:

- Probe: ET3DV6 - SN1790 ; ConvF(4.4, 4.4, 4.4) ; Calibrated: 2003/8/29
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn579 ; Calibrated: 2003/8/15
- Phantom: SAM 12 ; Type: SAM V4.0 ; Serial: TP 1202
- Measurement SW: DASY4, V4.1 Build 47 ; Postprocessing SW: SEMCAD, V1.6 Build 115

High Channel/Area Scan (5x8x1): Measurement grid: dx=15mm, dy=15mm

Reference Value = 6.33 V/m

Power Drift = -0.03 dB

Maximum value of SAR = 0.283 mW/g

High Channel/Zoon Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

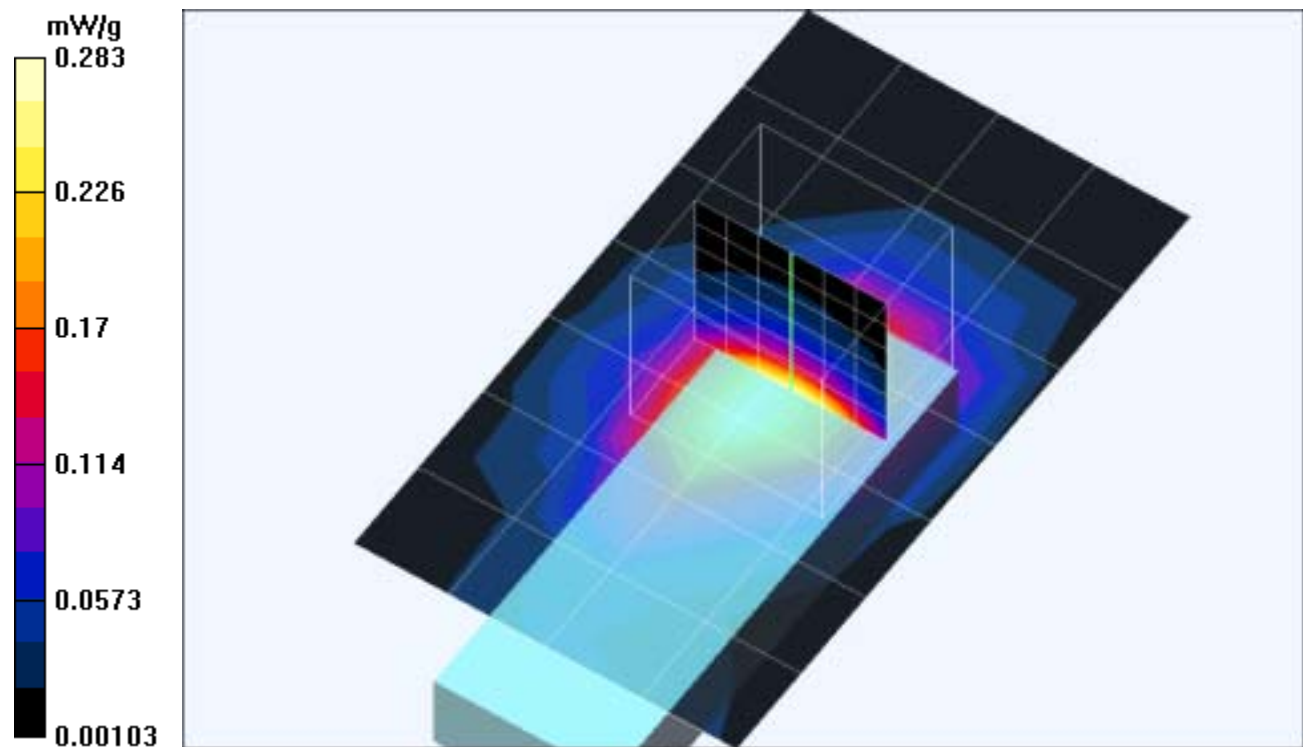
Peak SAR (extrapolated) = 0.616 W/kg

SAR(1 g) = 0.292 mW/g; SAR(10 g) = 0.146 mW/g

Reference Value = 6.33 V/m

Power Drift = -0.03 dB

Maximum value of SAR = 0.308 mW/g



Test Laboratory: Advance Data Technology

USR5422 Compaq N800C 11g Tip Mode 4 Ch 1

DUT: U.S. Robotics 802.11g 54Mbps USB Adapter ; Type: USR5422 ; Test Channel Frequency: 2412 MHz

Communication System: 802.11g ; Frequency: 2412 MHz; Duty Cycle: 1:1; Modulation type: OFDM

Medium: MSL2450 ($\sigma = 1.9267$ mho/m, $\epsilon_r = 50.8147$, $\rho = 1000$ kg/m³) ; Liquid level : 150 mm

Phantom section: Flat Section ; Separation distance : 0 mm (The tip of the EUT to the Phantom)

Antenna type : Internal Antenna ; Air temp. : 22.0 degrees ; Liquid temp. : 21.0 degrees

DASY4 Configuration:

- Probe: ET3DV6 - SN1790 ; ConvF(4.4, 4.4, 4.4) ; Calibrated: 2003/8/29
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn579; Calibrated: 2003/8/15
- Phantom: SAM 12; Type: SAM V4.0; Serial: TP 1202
- Measurement SW: DASY4, V4.1 Build 47; Postprocessing SW: SEMCAD, V1.6 Build 115

Low Channel/Area Scan (5x6x1): Measurement grid: dx=15mm, dy=15mm

Reference Value = 10.9 V/m

Power Drift = -0.2 dB

Maximum value of SAR = 0.214 mW/g

Low Channel/Zoon Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

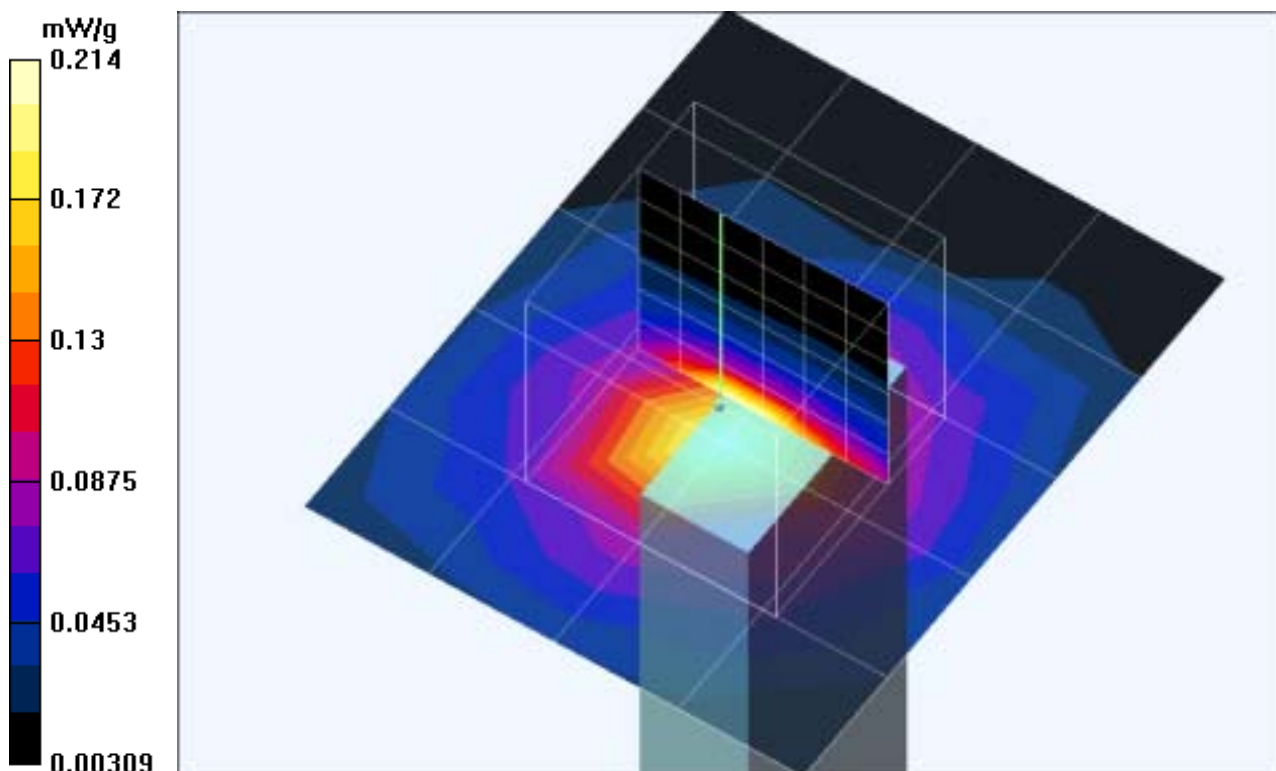
Peak SAR (extrapolated) = 0.52 W/kg

SAR(1 g) = 0.192 mW/g; SAR(10 g) = 0.0851 mW/g

Reference Value = 10.9 V/m

Power Drift = -0.2 dB

Maximum value of SAR = 0.203 mW/g



Test Laboratory: Advance Data Technology

USR5422 Compaq N800C 11g Tip Mode 4 Ch 6

DUT: U.S. Robotics 802.11g 54Mbps USB Adapter ; Type: USR5422 ; Test Channel Frequency: 2437 MHz

Communication System: 802.11g ; Frequency: 2437 MHz; Duty Cycle: 1:1; Modulation type: OFDM

Medium: MSL2450 ($\sigma = 1.9596$ mho/m, $\epsilon_r = 50.7402$, $\rho = 1000$ kg/m³) ; Liquid level : 150 mm

Phantom section: Flat Section ; Separation distance : 0 mm (The tip of the EUT to the Phantom)

Antenna type : Internal Antenna ; Air temp. : 22.0 degrees ; Liquid temp. : 21.0 degrees

DASY4 Configuration:

- Probe: ET3DV6 - SN1790 ; ConvF(4.4, 4.4, 4.4) ; Calibrated: 2003/8/29
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn579; Calibrated: 2003/8/15
- Phantom: SAM 12; Type: SAM V4.0; Serial: TP 1202
- Measurement SW: DASY4, V4.1 Build 47; Postprocessing SW: SEMCAD, V1.6 Build 115

Middle Channel/Area Scan (5x6x1): Measurement grid: dx=15mm, dy=15mm

Reference Value = 10.5 V/m

Power Drift = -0.1 dB

Maximum value of SAR = 0.21 mW/g

Middle Channel/Zoon Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

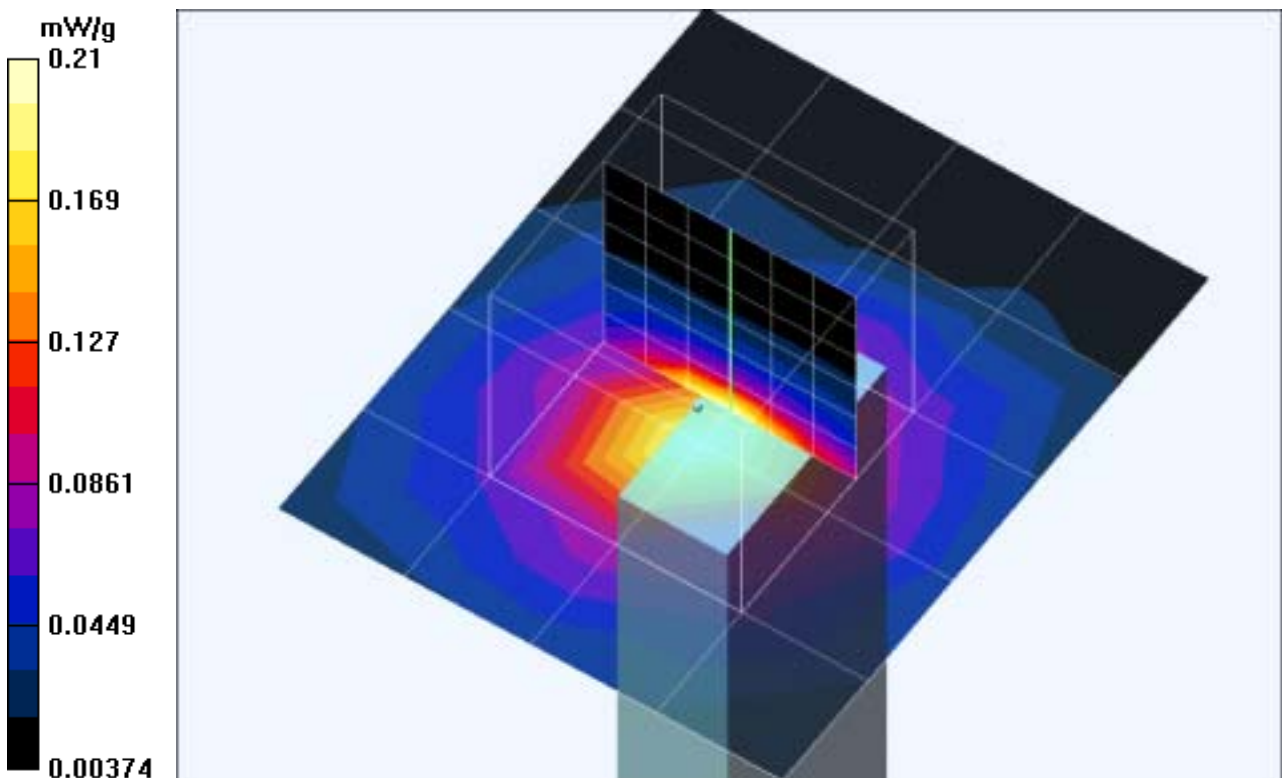
Peak SAR (extrapolated) = 0.534 W/kg

SAR(1 g) = 0.198 mW/g; SAR(10 g) = 0.0873 mW/g

Reference Value = 10.5 V/m

Power Drift = -0.1 dB

Maximum value of SAR = 0.214 mW/g



Test Laboratory: Advance Data Technology

USR5422 Compaq N800C 11g Tip Mode 4 Ch 11

DUT: U.S. Robotics 802.11g 54Mbps USB Adapter ; Type: USR5422 ; Test Channel Frequency: 2462 MHz

Communication System: 802.11g ; Frequency: 2462 MHz; Duty Cycle: 1:1; Modulation type: OFDM

Medium: MSL2450 ($\sigma = 1.9932$ mho/m, $\epsilon_r = 50.6638$, $\rho = 1000$ kg/m³) ; Liquid level : 150 mm

Phantom section: Flat Section ; Separation distance : 0 mm (The tip of the EUT to the Phantom)

Antenna type : Internal Antenna ; Air temp. : 22.0 degrees ; Liquid temp. : 21.0 degrees

DASY4 Configuration:

- Probe: ET3DV6 - SN1790 ; ConvF(4.4, 4.4, 4.4) ; Calibrated: 2003/8/29
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn579; Calibrated: 2003/8/15
- Phantom: SAM 12; Type: SAM V4.0; Serial: TP 1202
- Measurement SW: DASY4, V4.1 Build 47; Postprocessing SW: SEMCAD, V1.6 Build 115

High Channel/Area Scan (5x6x1): Measurement grid: dx=15mm, dy=15mm

Reference Value = 8.99 V/m

Power Drift = -0.1 dB

Maximum value of SAR = 0.155 mW/g

High Channel/Zoon Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

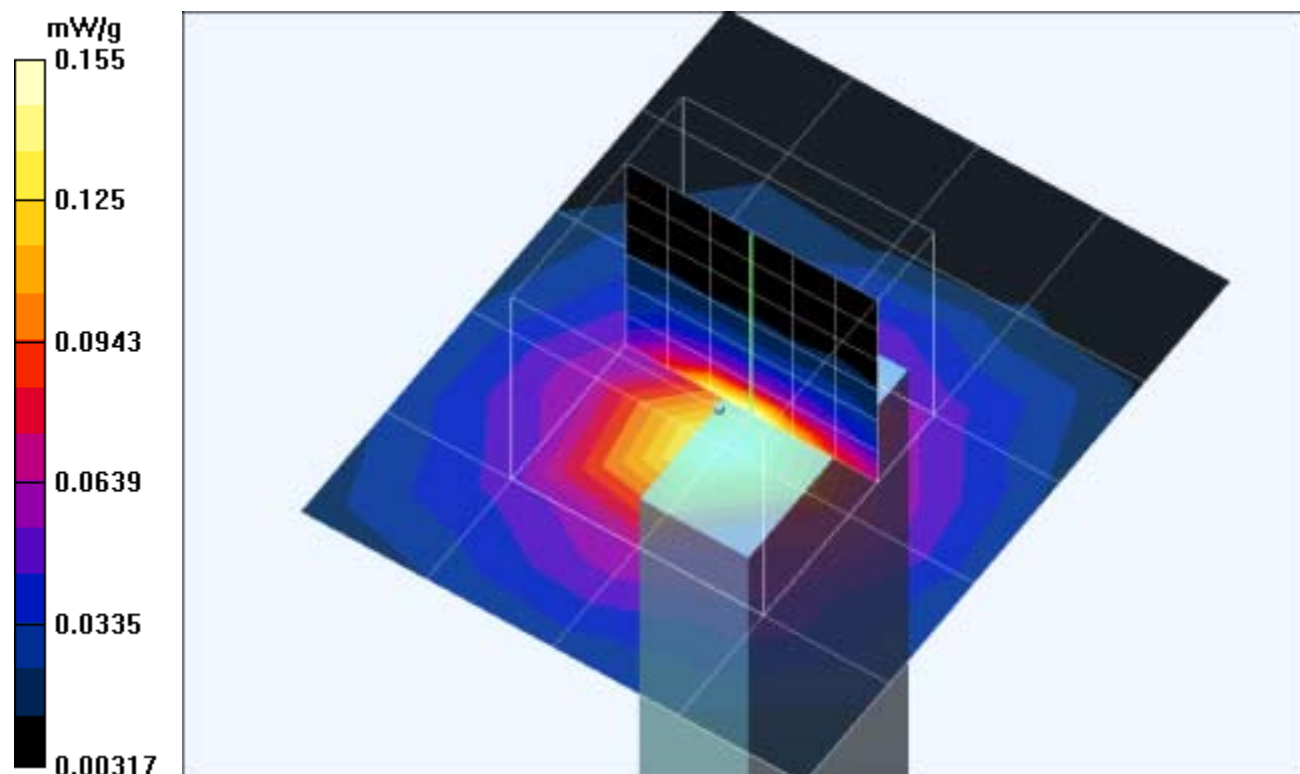
Peak SAR (extrapolated) = 0.405 W/kg

SAR(1 g) = 0.145 mW/g; SAR(10 g) = 0.0642 mW/g

Reference Value = 8.99 V/m

Power Drift = -0.1 dB

Maximum value of SAR = 0.156 mW/g



Test Laboratory: Advance Data Technology

USR5422 IBM ThinkPad X31 11b Bottom Mode 5 Ch 1

DUT: 11G USB Dongle ; Type: WG111T ; Test Channel Frequency: 2412 MHz

Communication System: 802.11b ; Frequency: 2412 MHz ; Duty Cycle: 1:1 ; Modulation type: CCK
Medium: MSL2450 ($\sigma = 1.9267$ mho/m, $\epsilon_r = 50.8147$, $\rho = 1000$ kg/m³) ; Liquid level : 150mm
Phantom section: Flat Section ; Separation distance : 7 mm (The bottom side of the EUT to the Phantom)

Antenna type : Internal Antenna ; Air temp. : 22.0 degrees ; Liquid temp. : 21.0 degrees

DASY4 Configuration:

- Probe: ET3DV6 - SN1790 ; ConvF(4.4, 4.4, 4.4) ; Calibrated: 2003/8/29
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn579 ; Calibrated: 2003/8/15
- Phantom: SAM 12 ; Type: SAM V4.0 ; Serial: TP 1202
- Measurement SW: DASY4, V4.1 Build 47 ; Postprocessing SW: SEMCAD, V1.6 Build 115

Low Channel/Area Scan (5x8x1): Measurement grid: dx=15mm, dy=15mm

Reference Value = 11.8 V/m

Power Drift = -0.2 dB

Maximum value of SAR = 0.997 mW/g

Low Channel/Zoon Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

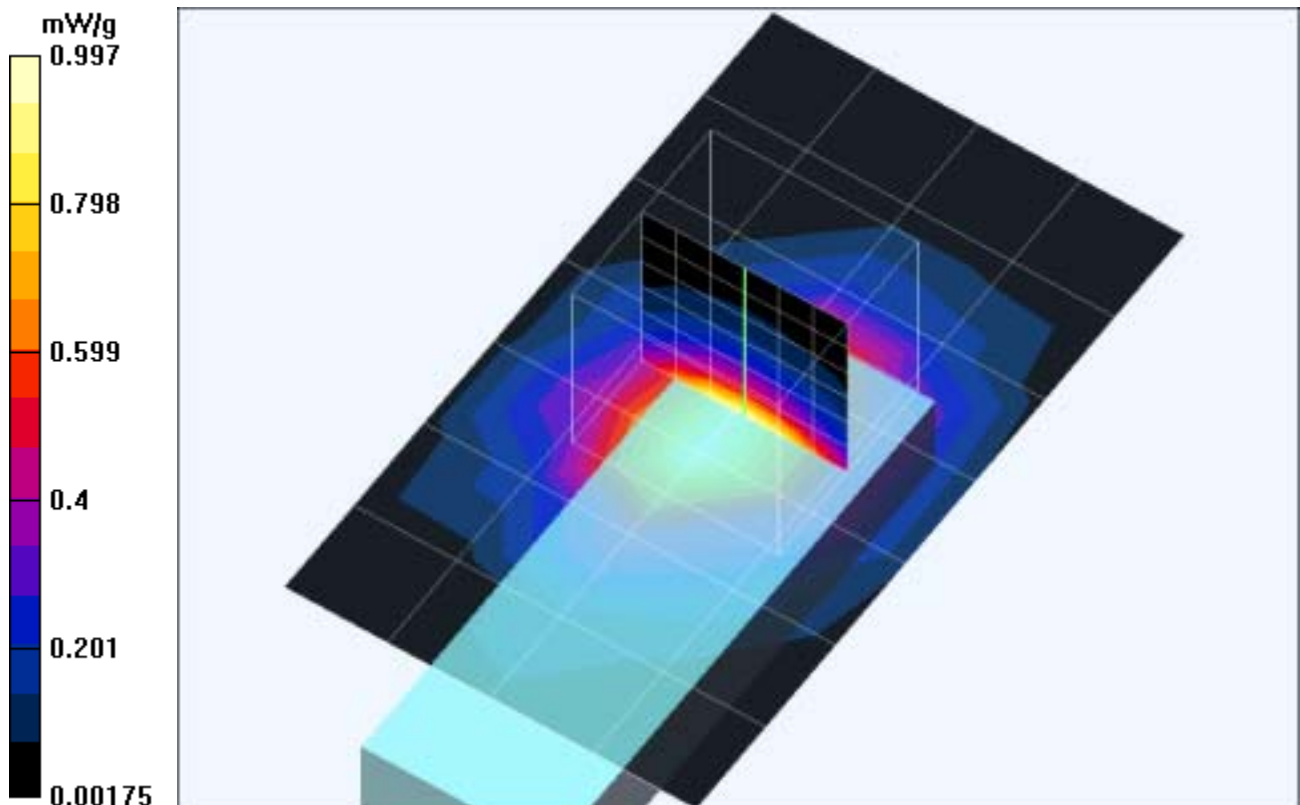
Peak SAR (extrapolated) = 1.83 W/kg

SAR(1 g) = 0.877 mW/g; SAR(10 g) = 0.442 mW/g

Reference Value = 11.8 V/m

Power Drift = -0.2 dB

Maximum value of SAR = 0.92 mW/g



Test Laboratory: Advance Data Technology

USR5422 IBM ThinkPad X31 11b Bottom Mode 5 Ch 6

DUT: 11G USB Dongle ; Type: WG111T ; Test Channel Frequency: 2437 MHz

Communication System: 802.11b ; Frequency: 2437 MHz ; Duty Cycle: 1:1 ; Modulation type: CCK
Medium: MSL2450 ($\sigma = 1.9596$ mho/m, $\epsilon_r = 50.7402$, $\rho = 1000$ kg/m³) ; Liquid level : 150mm
Phantom section: Flat Section ; Separation distance : 7 mm (The bottom side of the EUT to the Phantom)

Antenna type : Internal Antenna ; Air temp. : 22.0 degrees ; Liquid temp. : 21.0 degrees

DASY4 Configuration:

- Probe: ET3DV6 - SN1790 ; ConvF(4.4, 4.4, 4.4) ; Calibrated: 2003/8/29
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn579 ; Calibrated: 2003/8/15
- Phantom: SAM 12 ; Type: SAM V4.0 ; Serial: TP 1202
- Measurement SW: DASY4, V4.1 Build 47 ; Postprocessing SW: SEMCAD, V1.6 Build 115

Middle Channel/Area Scan (5x8x1): Measurement grid: dx=15mm, dy=15mm

Reference Value = 11.5 V/m

Power Drift = -0.1 dB

Maximum value of SAR = 1.07 mW/g

Middle Channel/Zoon Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

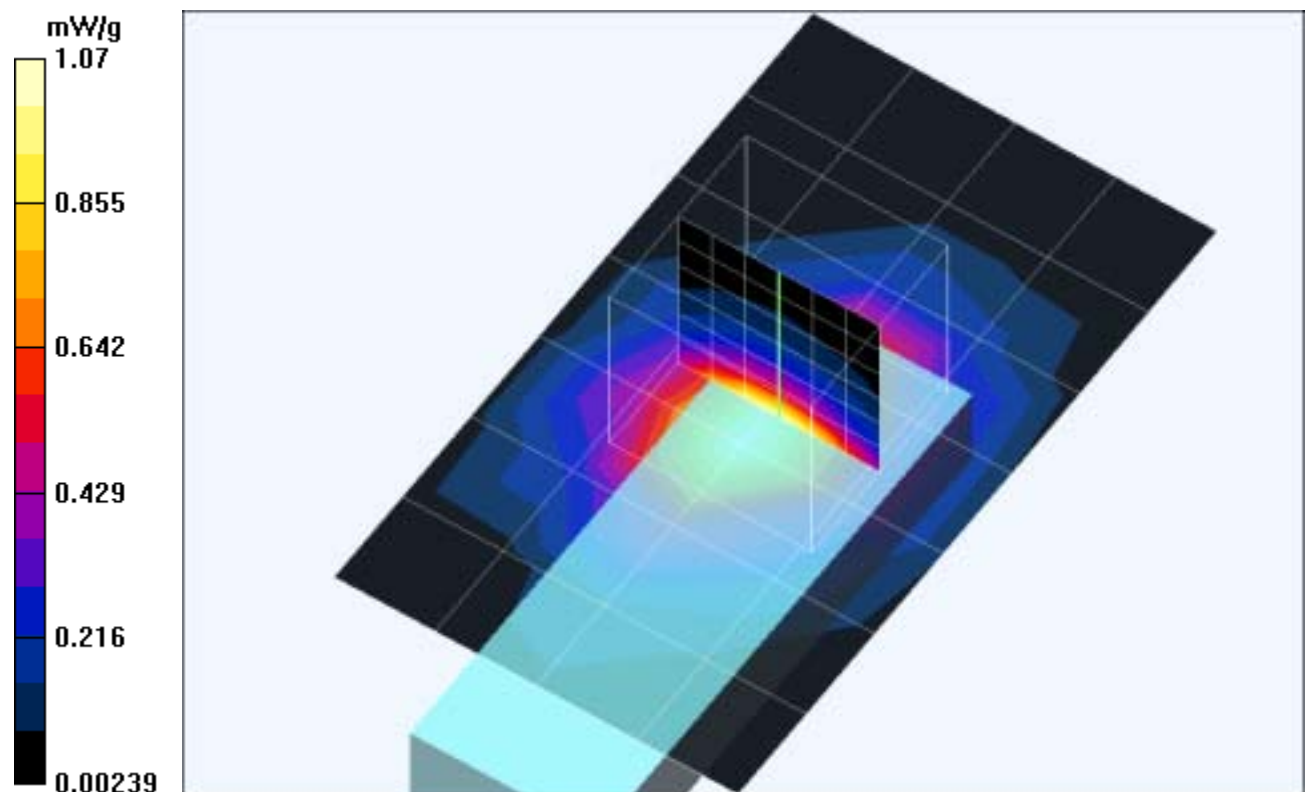
Peak SAR (extrapolated) = 2.24 W/kg

SAR(1 g) = 1.04 mW/g; SAR(10 g) = 0.517 mW/g

Reference Value = 11.5 V/m

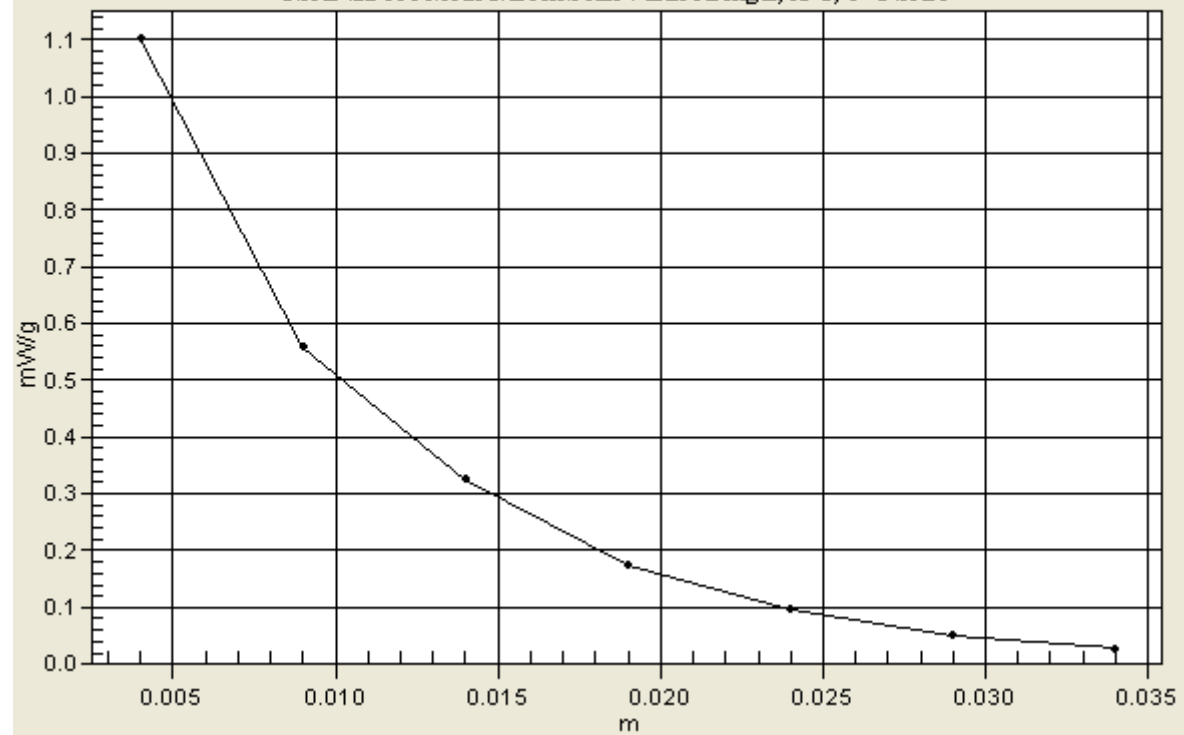
Power Drift = -0.1 dB

Maximum value of SAR = 1.1 mW/g



Averaged SAR

USR5422 11b Mode 5/Zoom Scan/V alue Along Z, X=3, Y=3 SAR



Test Laboratory: Advance Data Technology

USR5422 IBM ThinkPad X31 11b Bottom Mode 5 Ch 11**DUT: 11G USB Dongle ; Type: WG111T ; Test Channel Frequency: 2462 MHz**

Communication System: 802.11b ; Frequency: 2462 MHz ; Duty Cycle: 1:1 ; Modulation type: CCK
 Medium: MSL2450 ($\sigma = 1.9932 \text{ mho/m}$, $\epsilon_r = 50.6638$, $\rho = 1000 \text{ kg/m}^3$) ; Liquid level : 150mm
 Phantom section: Flat Section ; Separation distance : 7 mm (The bottom side of the EUT to the Phantom)

Antenna type : Internal Antenna ; Air temp. : 22.0 degrees ; Liquid temp. : 21.0 degrees

DASY4 Configuration:

- Probe: ET3DV6 - SN1790 ; ConvF(4.4, 4.4, 4.4) ; Calibrated: 2003/8/29
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn579 ; Calibrated: 2003/8/15
- Phantom: SAM 12 ; Type: SAM V4.0 ; Serial: TP 1202
- Measurement SW: DASY4, V4.1 Build 47 ; Postprocessing SW: SEMCAD, V1.6 Build 115

High Channel/Area Scan (5x8x1): Measurement grid: dx=15mm, dy=15mm

Reference Value = 9.63 V/m

Power Drift = -0.2 dB

Maximum value of SAR = 0.771 mW/g

High Channel/Zoon Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

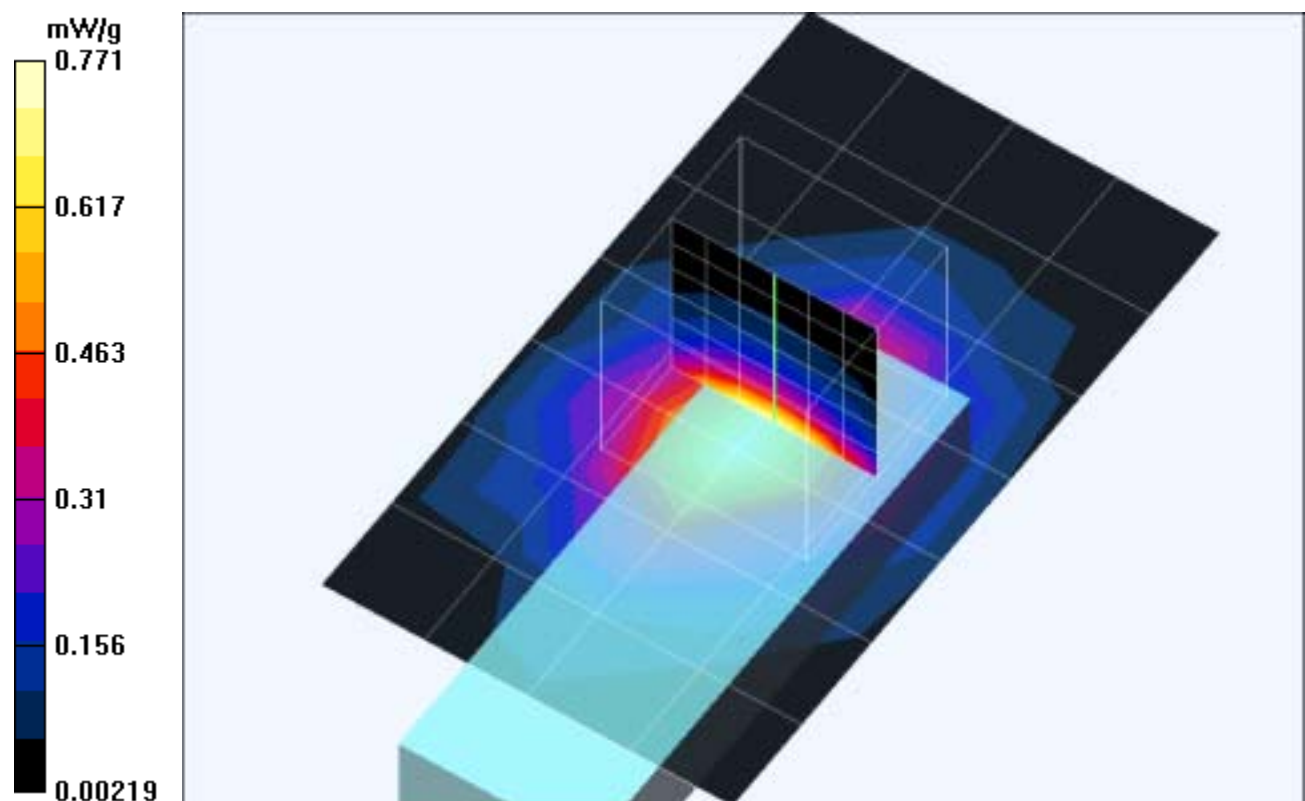
Peak SAR (extrapolated) = 1.55 W/kg

SAR(1 g) = 0.728 mW/g; SAR(10 g) = 0.366 mW/g

Reference Value = 9.63 V/m

Power Drift = -0.2 dB

Maximum value of SAR = 0.761 mW/g



Test Laboratory: Advance Data Technology

USR5422 IBM ThinkPad X31 11b Tip Mode 6 Ch 1

**DUT: U.S. Robotics 802.11g 54Mbps USB Adapter ; Type: USR5422 ; Test Channel
Frequency: 2412 MHz**

Communication System: 802.11b ; Frequency: 2412 MHz; Duty Cycle: 1:1; Modulation type: CCK
Medium: MSL2450 ($\sigma = 1.9267$ mho/m, $\epsilon_r = 50.8147$, $\rho = 1000$ kg/m³) ; Liquid level : 150 mm

Phantom section: Flat Section ; Separation distance : 0 mm (The tip of the EUT to the Phantom)

Antenna type : Internal Antenna ; Air temp. : 22.0 degrees ; Liquid temp. : 21.0 degrees

DASY4 Configuration:

- Probe: ET3DV6 - SN1790 ; ConvF(4.4, 4.4, 4.4) ; Calibrated: 2003/8/29
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn579; Calibrated: 2003/8/15
- Phantom: SAM 12; Type: SAM V4.0; Serial: TP 1202
- Measurement SW: DASY4, V4.1 Build 47; Postprocessing SW: SEMCAD, V1.6 Build 115

Low Channel/Area Scan (5x6x1): Measurement grid: dx=15mm, dy=15mm

Reference Value = 16 V/m

Power Drift = -0.2 dB

Maximum value of SAR = 0.466 mW/g

Low Channel/Zoon Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

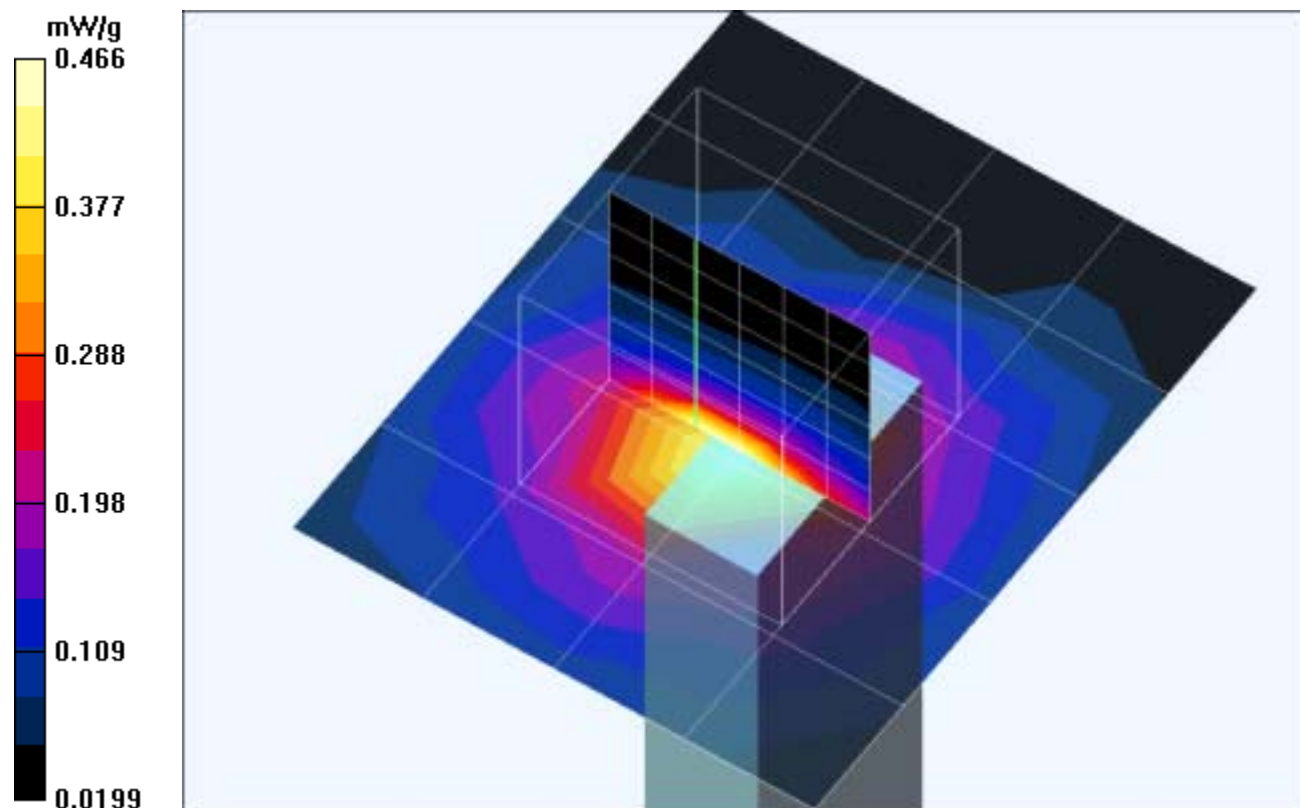
Peak SAR (extrapolated) = 1.21 W/kg

SAR(1 g) = 0.438 mW/g; SAR(10 g) = 0.192 mW/g

Reference Value = 16 V/m

Power Drift = -0.2 dB

Maximum value of SAR = 0.468 mW/g



Test Laboratory: Advance Data Technology

USR5422 IBM ThinkPad X31 11b Tip Mode 6 Ch 6

DUT: U.S. Robotics 802.11g 54Mbps USB Adapter ; Type: USR5422 ; Test Channel Frequency: 2437 MHz

Communication System: 802.11b ; Frequency: 2437 MHz; Duty Cycle: 1:1; Modulation type: CCK
Medium: MSL2450 ($\sigma = 1.9596$ mho/m, $\epsilon_r = 50.7402$, $\rho = 1000$ kg/m³) ; Liquid level : 150 mm

Phantom section: Flat Section ; Separation distance : 0 mm (The tip of the EUT to the Phantom)

Antenna type : Internal Antenna ; Air temp. : 22.0 degrees ; Liquid temp. : 21.0 degrees

DASY4 Configuration:

- Probe: ET3DV6 - SN1790 ; ConvF(4.4, 4.4, 4.4) ; Calibrated: 2003/8/29
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn579; Calibrated: 2003/8/15
- Phantom: SAM 12; Type: SAM V4.0; Serial: TP 1202
- Measurement SW: DASY4, V4.1 Build 47; Postprocessing SW: SEMCAD, V1.6 Build 115

Middle Channel/Area Scan (5x6x1): Measurement grid: dx=15mm, dy=15mm

Reference Value = 17 V/m

Power Drift = -0.2 dB

Maximum value of SAR = 0.55 mW/g

Middle Channel/Zoon Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

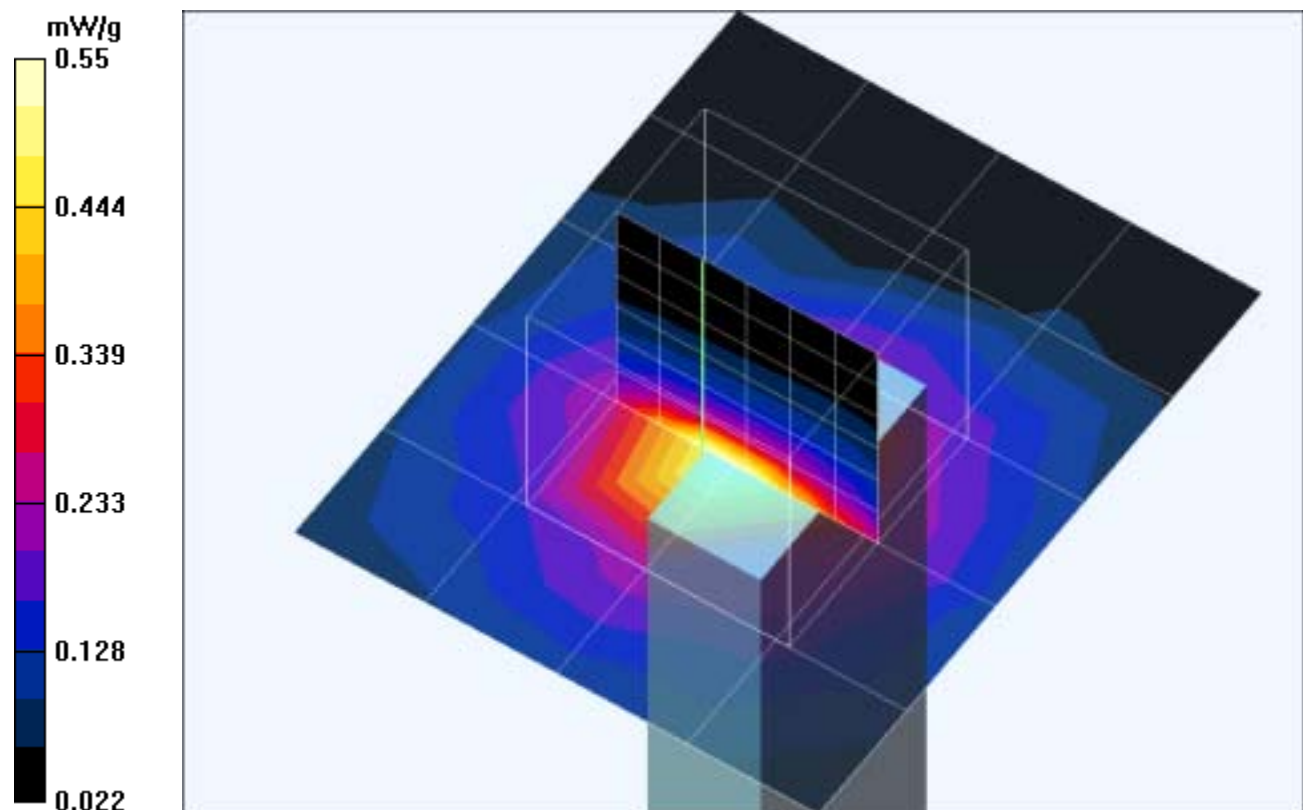
Peak SAR (extrapolated) = 1.4 W/kg

SAR(1 g) = 0.506 mW/g; SAR(10 g) = 0.223 mW/g

Reference Value = 17 V/m

Power Drift = -0.2 dB

Maximum value of SAR = 0.529 mW/g



Test Laboratory: Advance Data Technology

USR5422 IBM ThinkPad X31 11b Tip Mode 6 Ch 11

DUT: U.S. Robotics 802.11g 54Mbps USB Adapter ; Type: USR5422 ; Test Channel Frequency: 2462 MHz

Communication System: 802.11b ; Frequency: 2462 MHz; Duty Cycle: 1:1; Modulation type: CCK
Medium: MSL2450 ($\sigma = 1.9932 \text{ mho/m}$, $\epsilon_r = 50.6638$, $\rho = 1000 \text{ kg/m}^3$) ; Liquid level : 150 mm

Phantom section: Flat Section ; Separation distance : 0 mm (The tip of the EUT to the Phantom)

Antenna type : Internal Antenna ; Air temp. : 22.0 degrees ; Liquid temp. : 21.0 degrees

DASY4 Configuration:

- Probe: ET3DV6 - SN1790 ; ConvF(4.4, 4.4, 4.4) ; Calibrated: 2003/8/29
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn579; Calibrated: 2003/8/15
- Phantom: SAM 12; Type: SAM V4.0; Serial: TP 1202
- Measurement SW: DASY4, V4.1 Build 47; Postprocessing SW: SEMCAD, V1.6 Build 115

High Channel/Area Scan (5x6x1): Measurement grid: dx=15mm, dy=15mm

Reference Value = 13.7 V/m

Power Drift = -0.2 dB

Maximum value of SAR = 0.379 mW/g

High Channel/Zoon Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

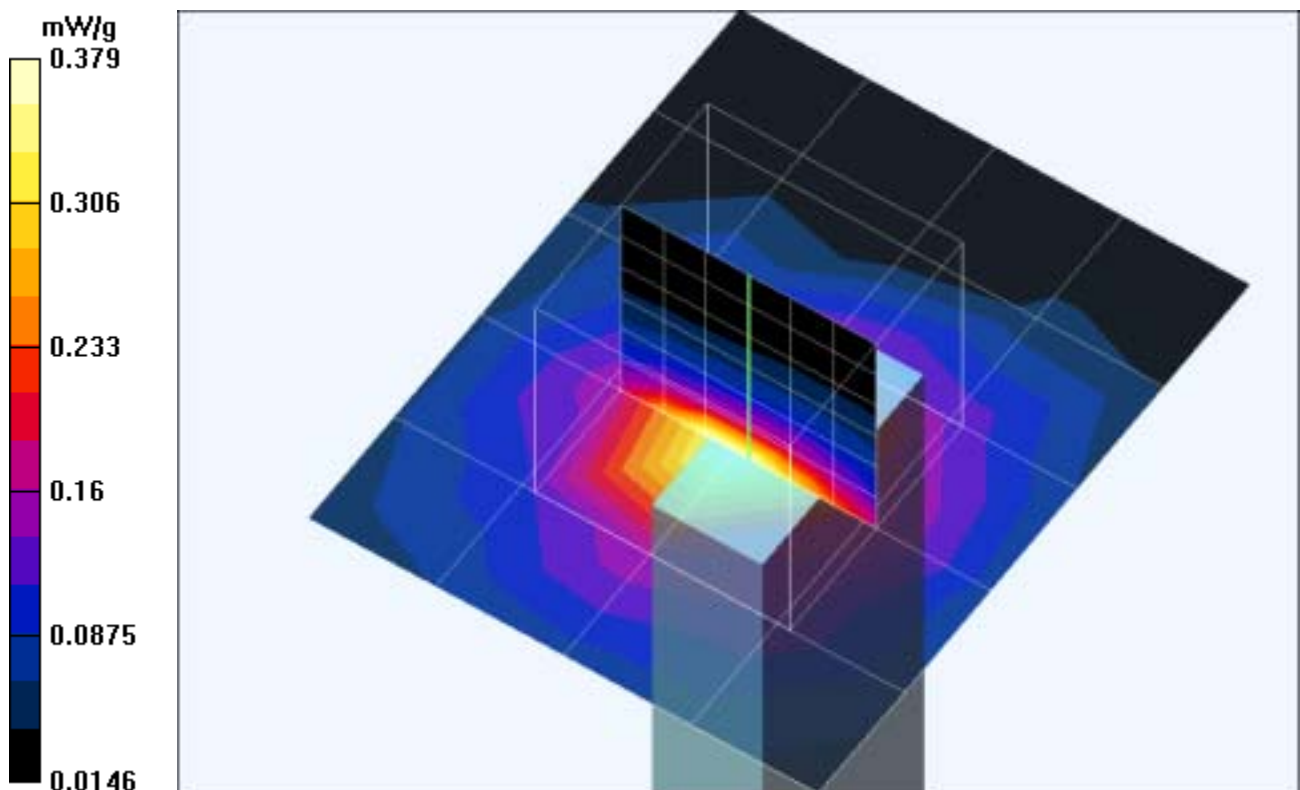
Peak SAR (extrapolated) = 0.933 W/kg

SAR(1 g) = 0.342 mW/g; SAR(10 g) = 0.151 mW/g

Reference Value = 13.7 V/m

Power Drift = -0.2 dB

Maximum value of SAR = 0.353 mW/g



Test Laboratory: Advance Data Technology

USR5422 IBM ThinkPad X31 11g Bottom Mode 7 Ch 1

DUT: U.S. Robotics 802.11g 54Mbps USB Adapter ; Type: USR5422 ; Test Channel Frequency: 2412 MHz

Communication System: 802.11g ; Frequency: 2412 MHz ; Duty Cycle: 1:1 ; Modulation type: OFDM

Medium: MSL2450 ($\sigma = 1.9267$ mho/m, $\epsilon_r = 50.8147$, $\rho = 1000$ kg/m³) ; Liquid level : 150mm

Phantom section: Flat Section ; Separation distance : 7 mm (The bottom side of the EUT to the Phantom)

Antenna type : Internal Antenna ; Air temp. : 22.0 degrees ; Liquid temp. : 21.0 degrees

DASY4 Configuration:

- Probe: ET3DV6 - SN1790 ; ConvF(4.4, 4.4, 4.4) ; Calibrated: 2003/8/29
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn579 ; Calibrated: 2003/8/15
- Phantom: SAM 12 ; Type: SAM V4.0 ; Serial: TP 1202
- Measurement SW: DASY4, V4.1 Build 47 ; Postprocessing SW: SEMCAD, V1.6 Build 115

Low Channel/Area Scan (5x8x1): Measurement grid: dx=15mm, dy=15mm

Reference Value = 7.42 V/m

Power Drift = -0.2 dB

Maximum value of SAR = 0.402 mW/g

Low Channel/Zoon Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

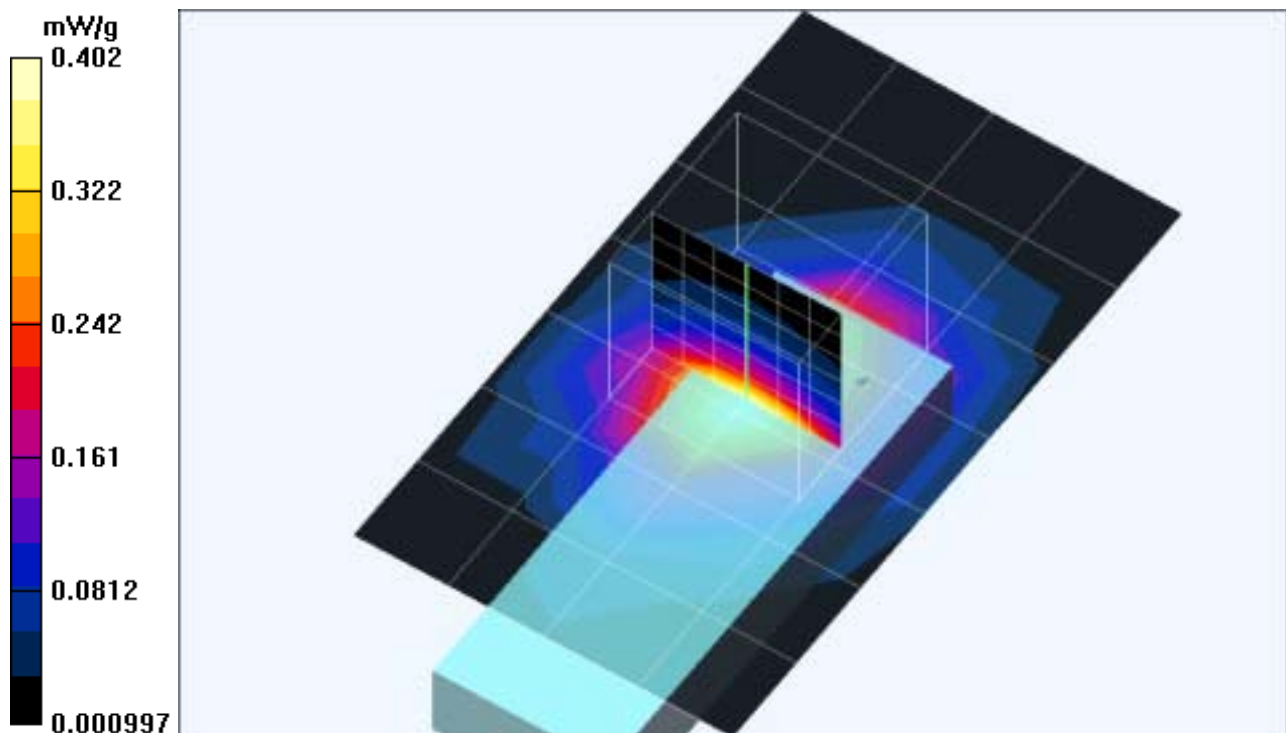
Peak SAR (extrapolated) = 0.798 W/kg

SAR(1 g) = 0.382 mW/g; SAR(10 g) = 0.191 mW/g

Reference Value = 7.42 V/m

Power Drift = -0.2 dB

Maximum value of SAR = 0.398 mW/g



Test Laboratory: Advance Data Technology

USR5422 IBM ThinkPad X31 11g Bottom Mode 7 Ch 6

DUT: U.S. Robotics 802.11g 54Mbps USB Adapter ; Type: USR5422 ; Test Channel Frequency: 2437 MHz

Communication System: 802.11g ; Frequency: 2437 MHz ; Duty Cycle: 1:1 ; Modulation type: OFDM

Medium: MSL2450 ($\sigma = 1.9596$ mho/m, $\epsilon_r = 50.7402$, $\rho = 1000$ kg/m³) ; Liquid level : 150mm

Phantom section: Flat Section ; Separation distance : 7 mm (The bottom side of the EUT to the Phantom)

Antenna type : Internal Antenna ; Air temp. : 22.0 degrees ; Liquid temp. : 21.0 degrees

DASY4 Configuration:

- Probe: ET3DV6 - SN1790 ; ConvF(4.4, 4.4, 4.4) ; Calibrated: 2003/8/29
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn579 ; Calibrated: 2003/8/15
- Phantom: SAM 12 ; Type: SAM V4.0 ; Serial: TP 1202
- Measurement SW: DASY4, V4.1 Build 47 ; Postprocessing SW: SEMCAD, V1.6 Build 115

Middle Channel/Area Scan (5x8x1): Measurement grid: dx=15mm, dy=15mm

Reference Value = 7.12 V/m

Power Drift = -0.1 dB

Maximum value of SAR = 0.405 mW/g

Middle Channel/Zoon Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

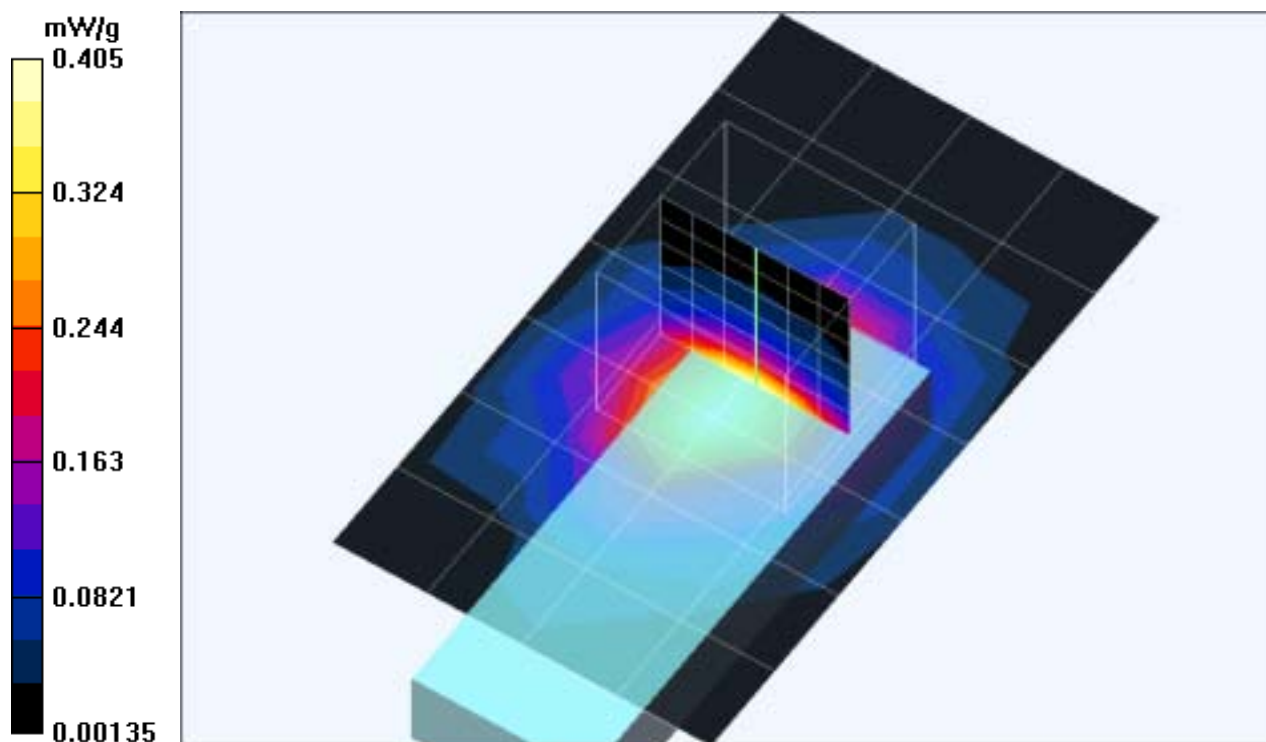
Peak SAR (extrapolated) = 0.845 W/kg

SAR(1 g) = 0.395 mW/g; SAR(10 g) = 0.198 mW/g

Reference Value = 7.12 V/m

Power Drift = -0.1 dB

Maximum value of SAR = 0.414 mW/g



Test Laboratory: Advance Data Technology

USR5422 IBM ThinkPad X31 11g Bottom Mode 7 Ch 11

DUT: U.S. Robotics 802.11g 54Mbps USB Adapter ; Type: USR5422 ; Test Channel Frequency: 2462 MHz

Communication System: 802.11g ; Frequency: 2462 MHz; Duty Cycle: 1:1; Modulation type: OFDM

Medium: MSL2450 ($\sigma = 1.9932$ mho/m, $\epsilon_r = 50.6638$, $\rho = 1000$ kg/m³) ; Liquid level : 150 mm

Phantom section: Flat Section ; Separation distance : 7 mm (The bottom of the EUT to the Phantom)

Antenna type : Internal Antenna ; Air temp. : 22.0 degrees ; Liquid temp. : 21.0 degrees

DASY4 Configuration:

- Probe: ET3DV6 - SN1790 ; ConvF(4.4, 4.4, 4.4) ; Calibrated: 2003/8/29
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn579; Calibrated: 2003/8/15
- Phantom: SAM 12; Type: SAM V4.0; Serial: TP 1202
- Measurement SW: DASY4, V4.1 Build 47; Postprocessing SW: SEMCAD, V1.6 Build 115

High Channel/Area Scan (5x8x1): Measurement grid: dx=15mm, dy=15mm

Reference Value = 6.12 V/m

Power Drift = -0.2 dB

Maximum value of SAR = 0.311 mW/g

High Channel/Zoon Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

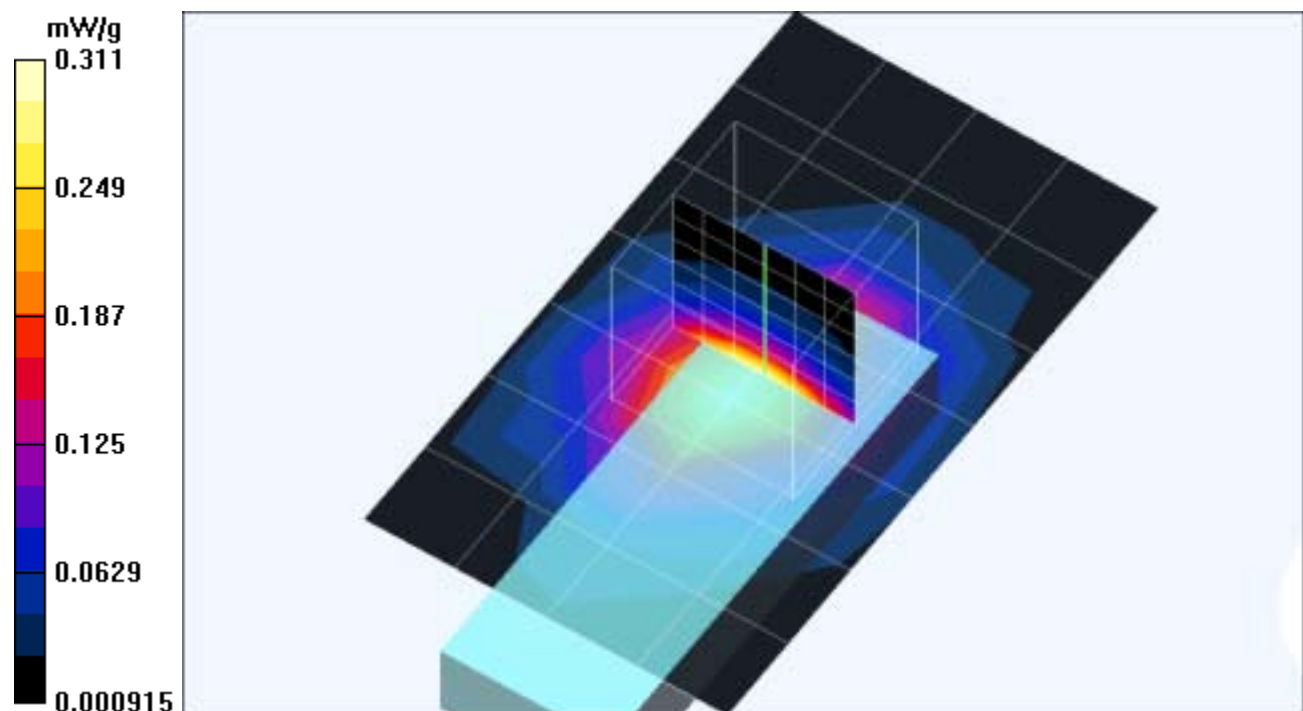
Peak SAR (extrapolated) = 0.615 W/kg

SAR(1 g) = 0.291 mW/g; SAR(10 g) = 0.146 mW/g

Reference Value = 6.12 V/m

Power Drift = -0.2 dB

Maximum value of SAR = 0.303 mW/g



Test Laboratory: Advance Data Technology

USR5422 IBM ThinkPad X31 11g Tip Mode 8 Ch 1

DUT: U.S. Robotics 802.11g 54Mbps USB Adapter ; Type: USR5422 ; Test Channel Frequency: 2412 MHz

Communication System: 802.11g ; Frequency: 2412 MHz; Duty Cycle: 1:1; Modulation type: OFDM

Medium: MSL2450 ($\sigma = 1.9267$ mho/m, $\epsilon_r = 50.8147$, $\rho = 1000$ kg/m³) ; Liquid level : 150 mm

Phantom section: Flat Section ; Separation distance : 0 mm (The tip of the EUT to the Phantom)

Antenna type : Internal Antenna ; Air temp. : 22.0 degrees ; Liquid temp. : 21.0 degrees

DASY4 Configuration:

- Probe: ET3DV6 - SN1790 ; ConvF(4.4, 4.4, 4.4) ; Calibrated: 2003/8/29
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn579; Calibrated: 2003/8/15
- Phantom: SAM 12; Type: SAM V4.0; Serial: TP 1202
- Measurement SW: DASY4, V4.1 Build 47; Postprocessing SW: SEMCAD, V1.6 Build 115

Low Channel/Area Scan (5x6x1): Measurement grid: dx=15mm, dy=15mm

Reference Value = 10.8 V/m

Power Drift = -0.2 dB

Maximum value of SAR = 0.217 mW/g

Low Channel/Zoon Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

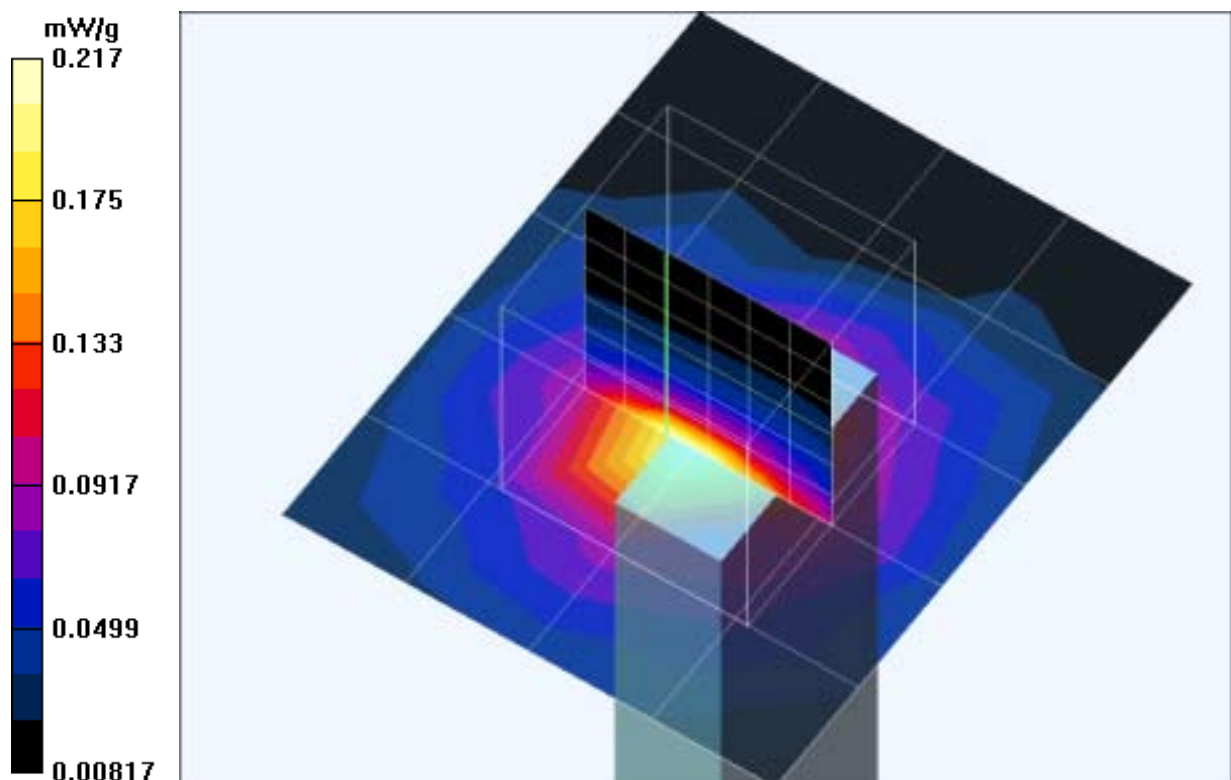
Peak SAR (extrapolated) = 0.539 W/kg

SAR(1 g) = 0.195 mW/g; SAR(10 g) = 0.0849 mW/g

Reference Value = 10.8 V/m

Power Drift = -0.2 dB

Maximum value of SAR = 0.202 mW/g



Test Laboratory: Advance Data Technology

USR5422 IBM ThinkPad X31 11g Tip Mode 8 Ch 6

DUT: U.S. Robotics 802.11g 54Mbps USB Adapter ; Type: USR5422 ; Test Channel Frequency: 2437 MHz

Communication System: 802.11g ; Frequency: 2437 MHz; Duty Cycle: 1:1; Modulation type: OFDM

Medium: MSL2450 ($\sigma = 1.9596$ mho/m, $\epsilon_r = 50.7402$, $\rho = 1000$ kg/m³) ; Liquid level : 150 mm

Phantom section: Flat Section ; Separation distance : 0 mm (The tip of the EUT to the Phantom)

Antenna type : Internal Antenna ; Air temp. : 22.0 degrees ; Liquid temp. : 21.0 degrees

DASY4 Configuration:

- Probe: ET3DV6 - SN1790 ; ConvF(4.4, 4.4, 4.4) ; Calibrated: 2003/8/29
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn579; Calibrated: 2003/8/15
- Phantom: SAM 12; Type: SAM V4.0; Serial: TP 1202
- Measurement SW: DASY4, V4.1 Build 47; Postprocessing SW: SEMCAD, V1.6 Build 115

Middle Channel/Area Scan (5x6x1): Measurement grid: dx=15mm, dy=15mm

Reference Value = 10.4 V/m

Power Drift = -0.1 dB

Maximum value of SAR = 0.212 mW/g

Middle Channel/Zoon Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

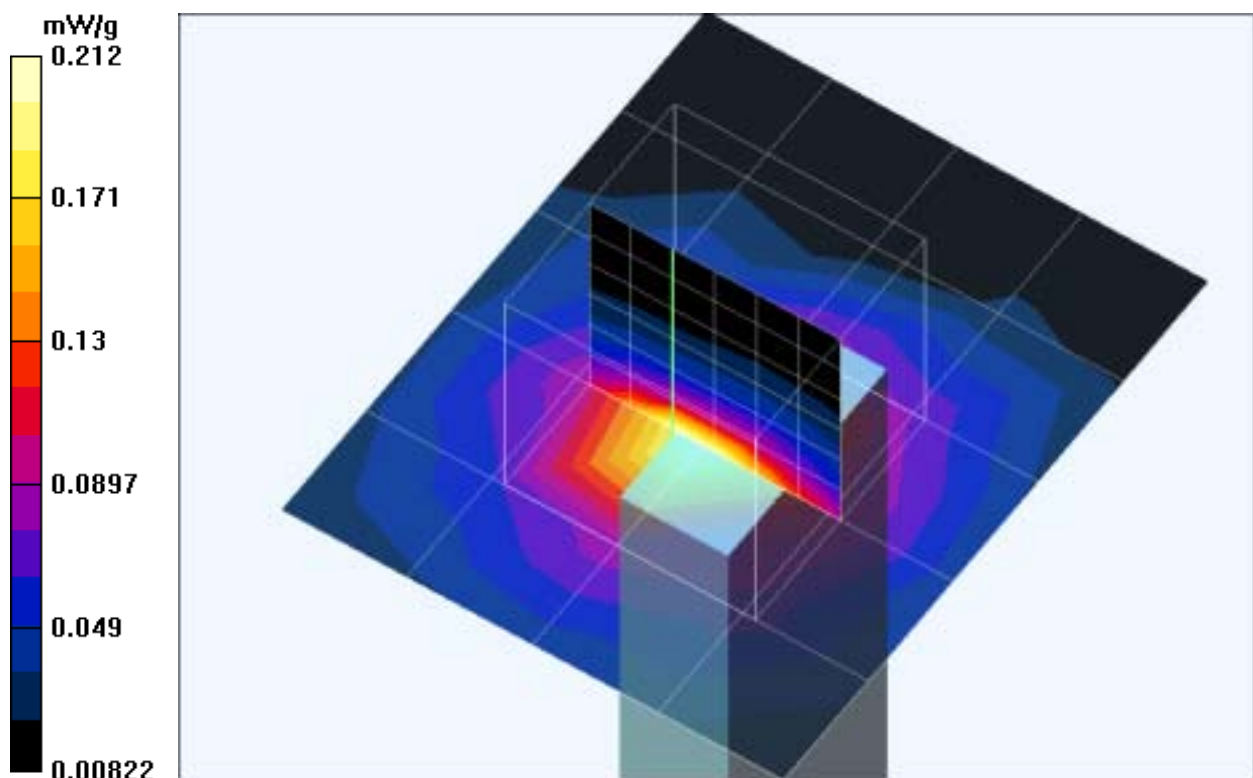
Peak SAR (extrapolated) = 0.553 W/kg

SAR(1 g) = 0.197 mW/g; SAR(10 g) = 0.0861 mW/g

Reference Value = 10.4 V/m

Power Drift = -0.1 dB

Maximum value of SAR = 0.208 mW/g



Test Laboratory: Advance Data Technology

USR5422 IBM ThinkPad X31 11g Tip Mode 8 Ch 11

DUT: U.S. Robotics 802.11g 54Mbps USB Adapter ; Type: USR5422 ; Test Channel Frequency: 2462 MHz

Communication System: 802.11g ; Frequency: 2462 MHz; Duty Cycle: 1:1; Modulation type: OFDM

Medium: MSL2450 ($\sigma = 1.9932$ mho/m, $\epsilon_r = 50.6638$, $\rho = 1000$ kg/m³) ; Liquid level : 150 mm

Phantom section: Flat Section ; Separation distance : 0 mm (The tip of the EUT to the Phantom)

Antenna type : Internal Antenna ; Air temp. : 22.0 degrees ; Liquid temp. : 21.0 degrees

DASY4 Configuration:

- Probe: ET3DV6 - SN1790 ; ConvF(4.4, 4.4, 4.4) ; Calibrated: 2003/8/29
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn579; Calibrated: 2003/8/15
- Phantom: SAM 12; Type: SAM V4.0; Serial: TP 1202
- Measurement SW: DASY4, V4.1 Build 47; Postprocessing SW: SEMCAD, V1.6 Build 115

High Channel/Area Scan (5x6x1): Measurement grid: dx=15mm, dy=15mm

Reference Value = 8.77 V/m

Power Drift = -0.2 dB

Maximum value of SAR = 0.156 mW/g

High Channel/Zoon Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

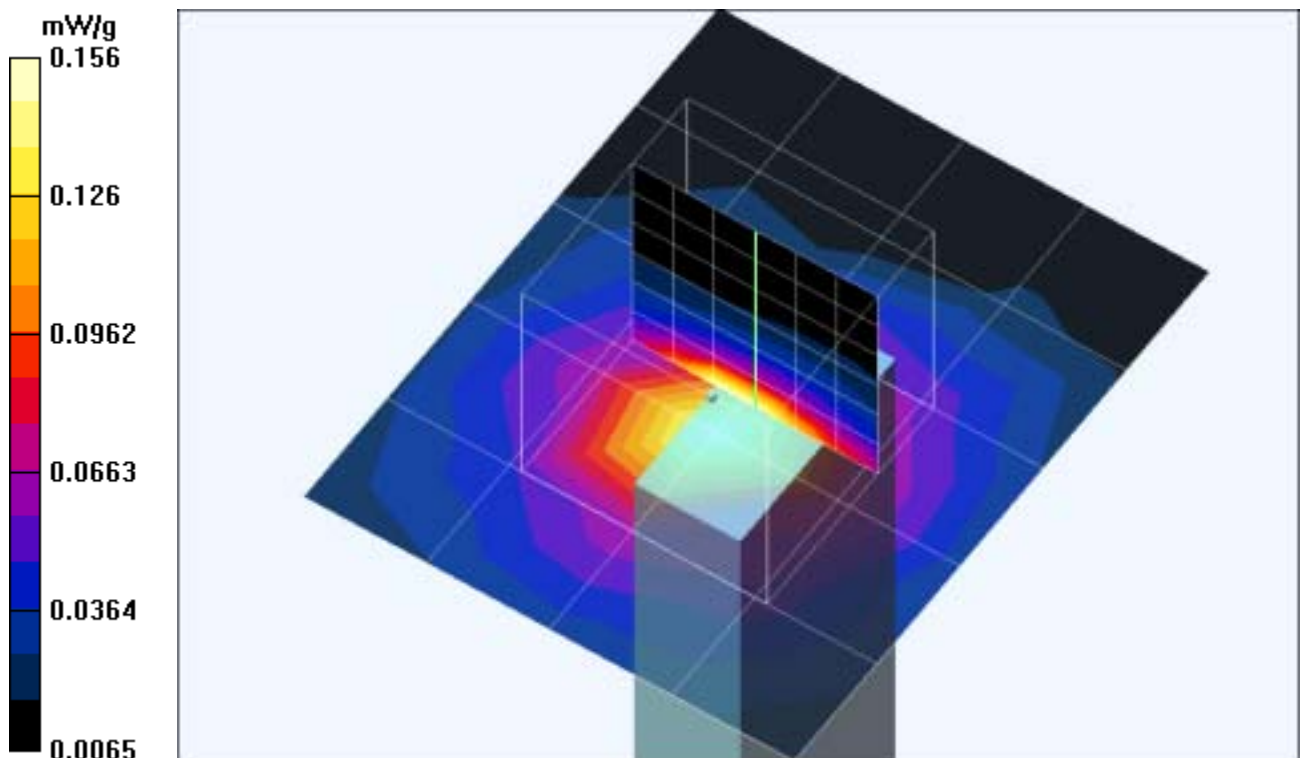
Peak SAR (extrapolated) = 0.404 W/kg

SAR(1 g) = 0.144 mW/g; SAR(10 g) = 0.0625 mW/g

Reference Value = 8.77 V/m

Power Drift = -0.2 dB

Maximum value of SAR = 0.146 mW/g



Test Laboratory: Advance Data Technology

USR5422 IBM ThinkPad X20 11b Bottom Mode 9 Ch 1

DUT: 11G USB Dongle ; Type: WG111T ; Test Channel Frequency: 2412 MHz

Communication System: 802.11b ; Frequency: 2412 MHz ; Duty Cycle: 1:1 ; Modulation type: CCK
Medium: MSL2450 ($\sigma = 1.9267$ mho/m, $\epsilon_r = 50.8147$, $\rho = 1000$ kg/m³) ; Liquid level : 150mm
Phantom section: Flat Section ; Separation distance : 6 mm (The bottom side of the EUT to the Phantom)

Antenna type : Internal Antenna ; Air temp. : 22.0 degrees ; Liquid temp. : 21.0 degrees

DASY4 Configuration:

- Probe: ET3DV6 - SN1790 ; ConvF(4.4, 4.4, 4.4) ; Calibrated: 2003/8/29
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn579 ; Calibrated: 2003/8/15
- Phantom: SAM 12 ; Type: SAM V4.0 ; Serial: TP 1202
- Measurement SW: DASY4, V4.1 Build 47 ; Postprocessing SW: SEMCAD, V1.6 Build 115

Low Channel/Area Scan (5x8x1): Measurement grid: dx=15mm, dy=15mm

Reference Value = 12.6 V/m

Power Drift = -0.1 dB

Maximum value of SAR = 1.09 mW/g

Low Channel/Zoon Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

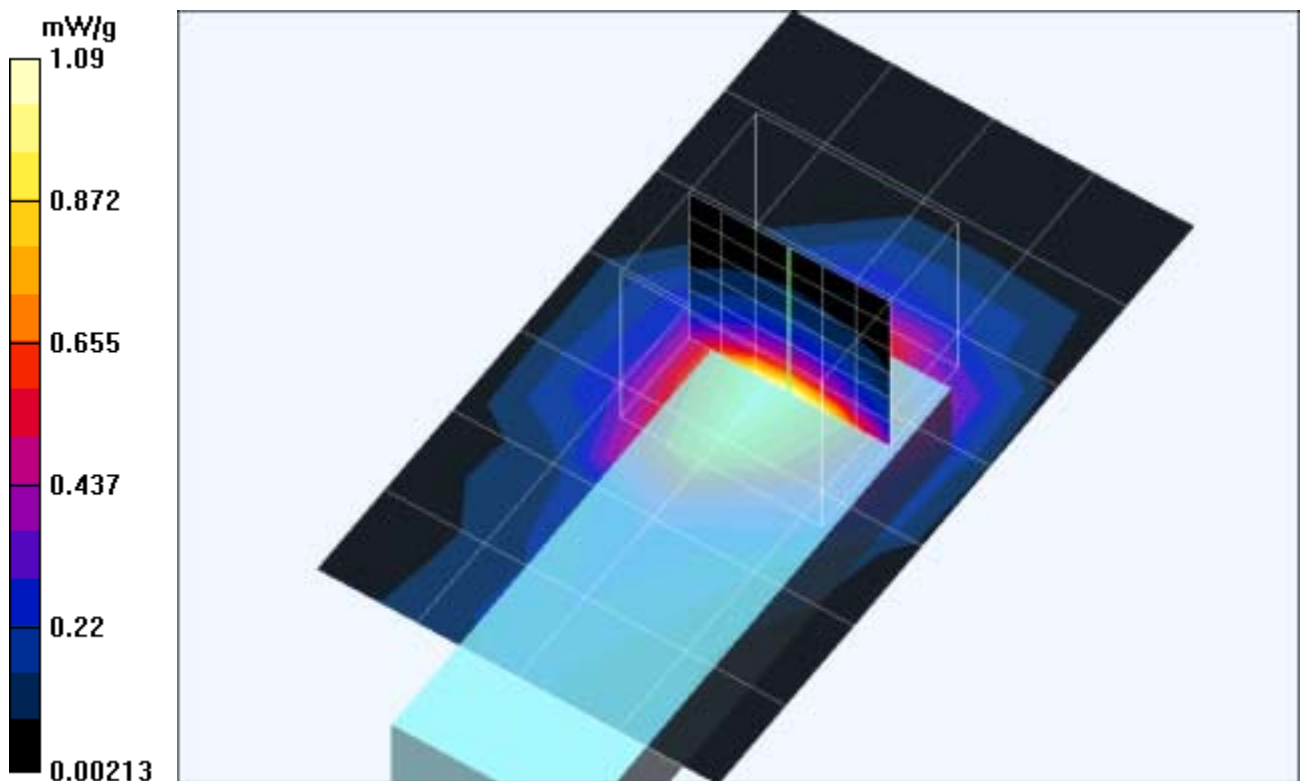
Peak SAR (extrapolated) = 2.44 W/kg

SAR(1 g) = 1.12 mW/g; SAR(10 g) = 0.543 mW/g

Reference Value = 12.6 V/m

Power Drift = -0.1 dB

Maximum value of SAR = 1.21 mW/g



Test Laboratory: Advance Data Technology

USR5422 IBM ThinkPad X20 11b Bottom Mode 9 Ch 6

DUT: 11G USB Dongle ; Type: WG111T ; Test Channel Frequency: 2437 MHz

Communication System: 802.11b ; Frequency: 2437 MHz ; Duty Cycle: 1:1 ; Modulation type: CCK
 Medium: MSL2450 ($\sigma = 1.9596$ mho/m, $\epsilon_r = 50.7402$, $\rho = 1000$ kg/m³) ; Liquid level : 150mm
 Phantom section: Flat Section ; Separation distance : 6 mm (The bottom side of the EUT to the Phantom)

Antenna type : Internal Antenna ; Air temp. : 22.0 degrees ; Liquid temp. : 21.0 degrees

DASY4 Configuration:

- Probe: ET3DV6 - SN1790 ; ConvF(4.4, 4.4, 4.4) ; Calibrated: 2003/8/29
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn579 ; Calibrated: 2003/8/15
- Phantom: SAM 12 ; Type: SAM V4.0 ; Serial: TP 1202
- Measurement SW: DASY4, V4.1 Build 47 ; Postprocessing SW: SEMCAD, V1.6 Build 115

Middle Channel/Area Scan (5x8x1): Measurement grid: dx=15mm, dy=15mm

Reference Value = 13.1 V/m

Power Drift = 0.2 dB

Maximum value of SAR = 1.3 mW/g

Middle Channel/Zoon Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

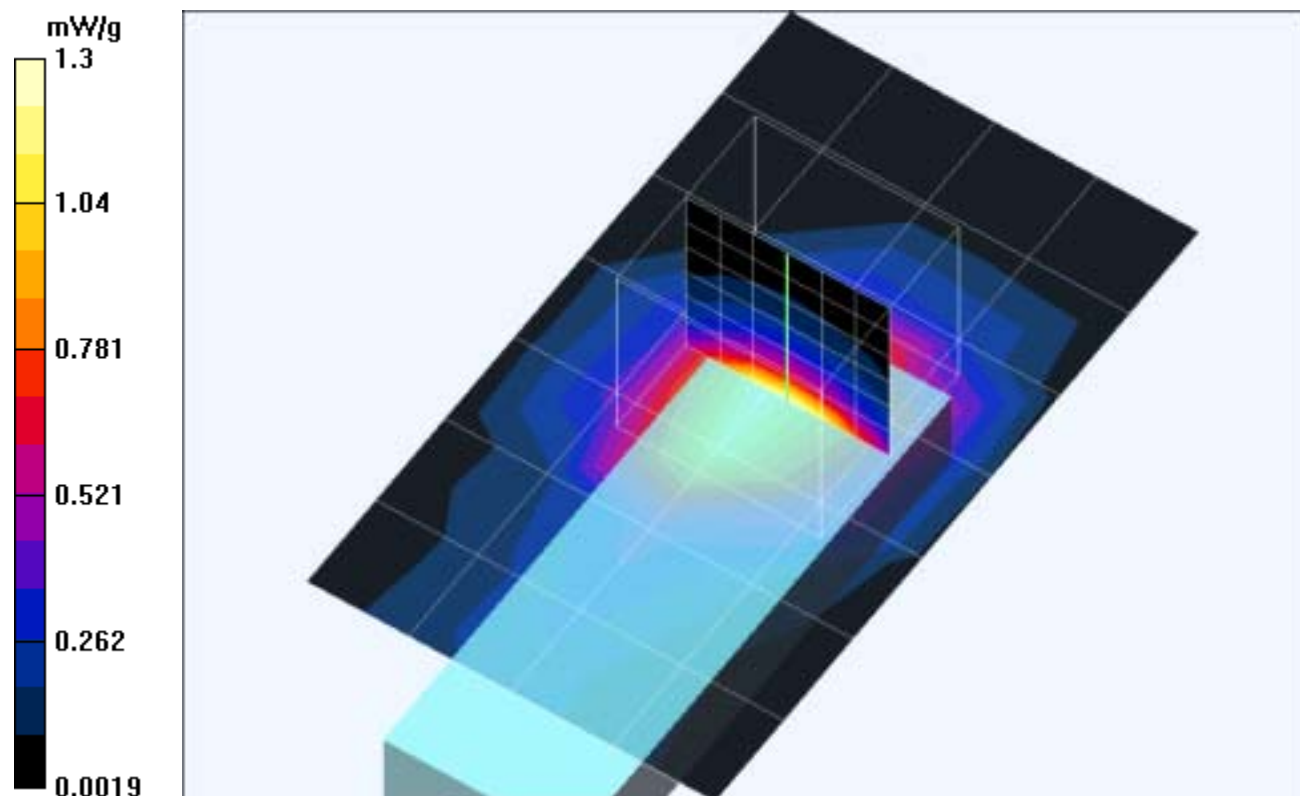
Peak SAR (extrapolated) = 3.03 W/kg

SAR(1 g) = 1.4 mW/g; SAR(10 g) = 0.678 mW/g

Reference Value = 13.1 V/m

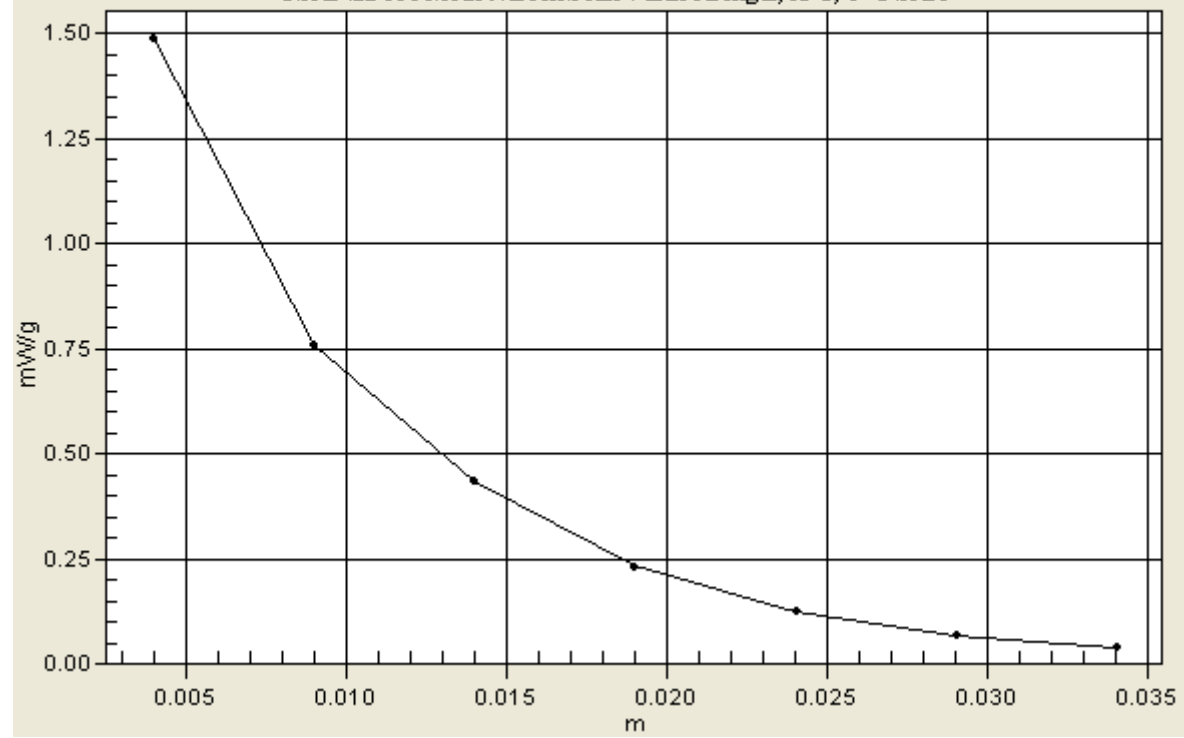
Power Drift = 0.2 dB

Maximum value of SAR = 1.49 mW/g



Averaged SAR

USR5422 11b Mode 9/Zoom Scan/V alue Along Z, X=3, Y=3 SAR



Test Laboratory: Advance Data Technology

USR5422 IBM ThinkPad X20 11b Bottom Mode 9 Ch 11

DUT: 11G USB Dongle ; Type: WG111T ; Test Channel Frequency: 2462 MHz

Communication System: 802.11b ; Frequency: 2462 MHz ; Duty Cycle: 1:1 ; Modulation type: CCK
Medium: MSL2450 ($\sigma = 1.9932 \text{ mho/m}$, $\epsilon_r = 50.6638$, $\rho = 1000 \text{ kg/m}^3$) ; Liquid level : 150mm
Phantom section: Flat Section ; Separation distance : 6 mm (The bottom side of the EUT to the Phantom)

Antenna type : Internal Antenna ; Air temp. : 22.0 degrees ; Liquid temp. : 21.0 degrees

DASY4 Configuration:

- Probe: ET3DV6 - SN1790 ; ConvF(4.4, 4.4, 4.4) ; Calibrated: 2003/8/29
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn579 ; Calibrated: 2003/8/15
- Phantom: SAM 12 ; Type: SAM V4.0 ; Serial: TP 1202
- Measurement SW: DASY4, V4.1 Build 47 ; Postprocessing SW: SEMCAD, V1.6 Build 115

High Channel/Area Scan (5x8x1): Measurement grid: dx=15mm, dy=15mm

Reference Value = 11.8 V/m

Power Drift = -0.1 dB

Maximum value of SAR = 1 mW/g

High Channel/Zoon Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

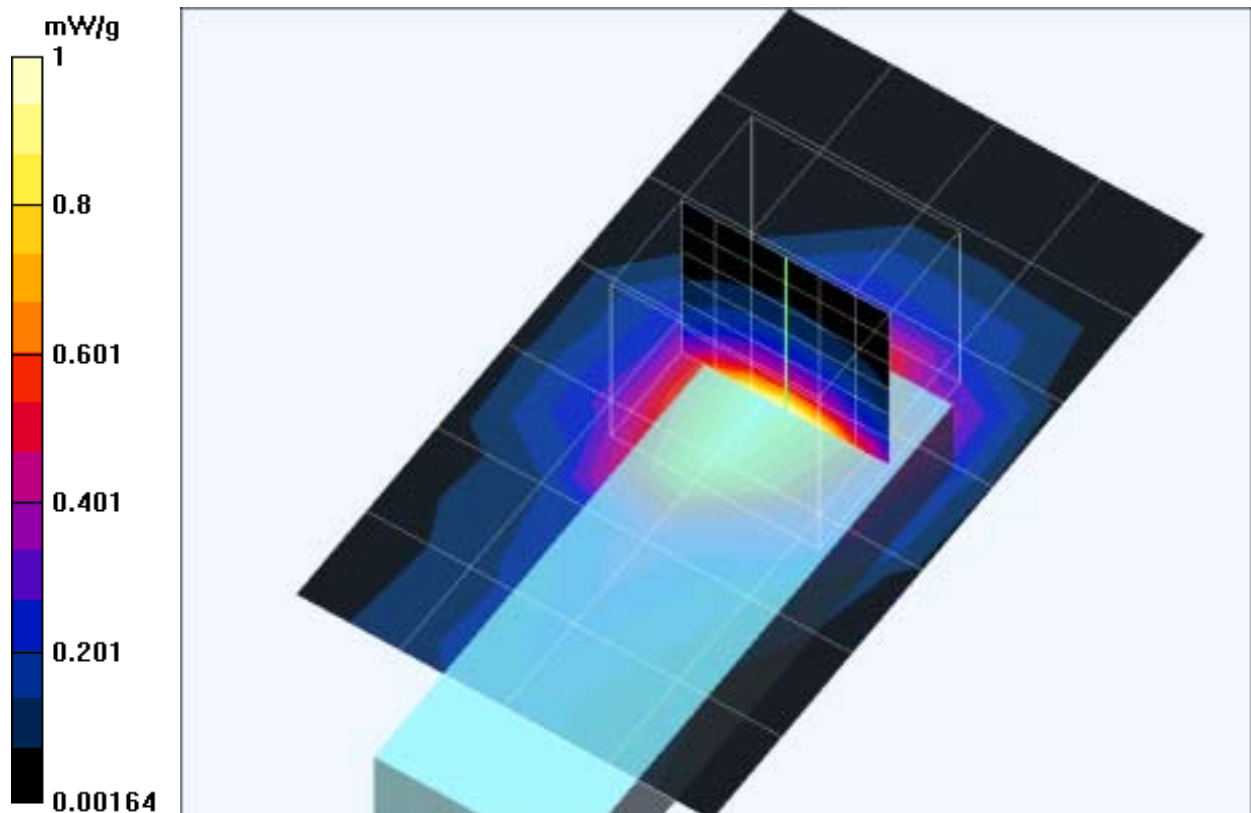
Peak SAR (extrapolated) = 2.28 W/kg

SAR(1 g) = 1.05 mW/g; SAR(10 g) = 0.507 mW/g

Reference Value = 11.8 V/m

Power Drift = -0.1 dB

Maximum value of SAR = 1.12 mW/g



Test Laboratory: Advance Data Technology

USR5422 IBM ThinkPad X20 11b Tip Mode 10 Ch 1

**DUT: U.S. Robotics 802.11g 54Mbps USB Adapter ; Type: USR5422 ; Test Channel
Frequency: 2412 MHz**

Communication System: 802.11b ; Frequency: 2412 MHz; Duty Cycle: 1:1; Modulation type: CCK
Medium: MSL2450 ($\sigma = 1.9267$ mho/m, $\epsilon_r = 50.8147$, $\rho = 1000$ kg/m³) ; Liquid level : 150 mm

Phantom section: Flat Section ; Separation distance : 0 mm (The tip of the EUT to the Phantom)

Antenna type : Internal Antenna ; Air temp. : 22.0 degrees ; Liquid temp. : 21.0 degrees

DASY4 Configuration:

- Probe: ET3DV6 - SN1790 ; ConvF(4.4, 4.4, 4.4) ; Calibrated: 2003/8/29
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn579; Calibrated: 2003/8/15
- Phantom: SAM 12; Type: SAM V4.0; Serial: TP 1202
- Measurement SW: DASY4, V4.1 Build 47; Postprocessing SW: SEMCAD, V1.6 Build 115

Low Channel/Area Scan (5x6x1): Measurement grid: dx=15mm, dy=15mm

Reference Value = 15.3 V/m

Power Drift = -0.2 dB

Maximum value of SAR = 0.472 mW/g

Low Channel/Zoon Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

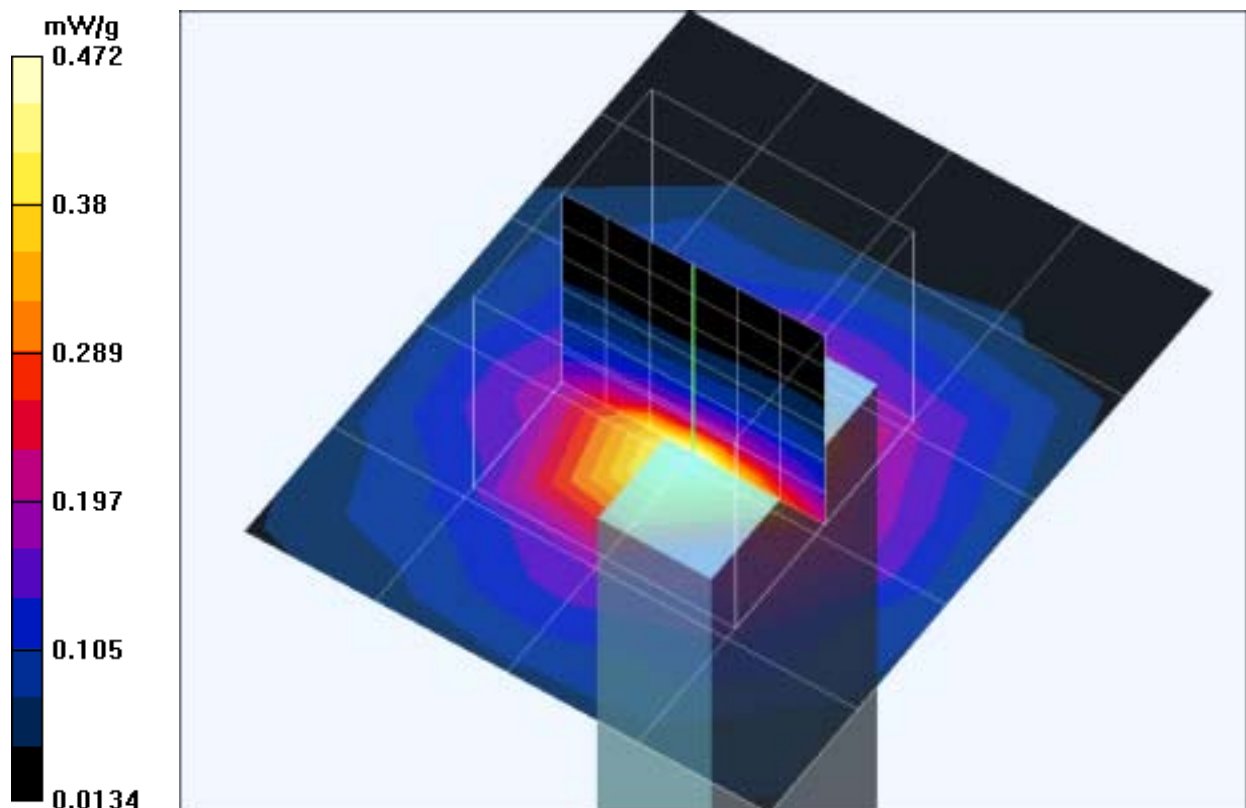
Peak SAR (extrapolated) = 1.21 W/kg

SAR(1 g) = 0.443 mW/g; SAR(10 g) = 0.197 mW/g

Reference Value = 15.3 V/m

Power Drift = -0.2 dB

Maximum value of SAR = 0.499 mW/g



Test Laboratory: Advance Data Technology

USR5422 IBM ThinkPad X20 11b Tip Mode 10 Ch 6

**DUT: U.S. Robotics 802.11g 54Mbps USB Adapter ; Type: USR5422 ; Test Channel
Frequency: 2437 MHz**

Communication System: 802.11b ; Frequency: 2437 MHz; Duty Cycle: 1:1; Modulation type: CCK
Medium: MSL2450 ($\sigma = 1.9596$ mho/m, $\epsilon_r = 50.7402$, $\rho = 1000$ kg/m³) ; Liquid level : 150 mm

Phantom section: Flat Section ; Separation distance : 0 mm (The tip of the EUT to the Phantom)

Antenna type : Internal Antenna ; Air temp. : 22.0 degrees ; Liquid temp. : 21.0 degrees

DASY4 Configuration:

- Probe: ET3DV6 - SN1790 ; ConvF(4.4, 4.4, 4.4) ; Calibrated: 2003/8/29
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn579; Calibrated: 2003/8/15
- Phantom: SAM 12; Type: SAM V4.0; Serial: TP 1202
- Measurement SW: DASY4, V4.1 Build 47; Postprocessing SW: SEMCAD, V1.6 Build 115

Middle Channel/Area Scan (5x6x1): Measurement grid: dx=15mm, dy=15mm

Reference Value = 16.4 V/m

Power Drift = -0.07 dB

Maximum value of SAR = 0.561 mW/g

Middle Channel/Zoon Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

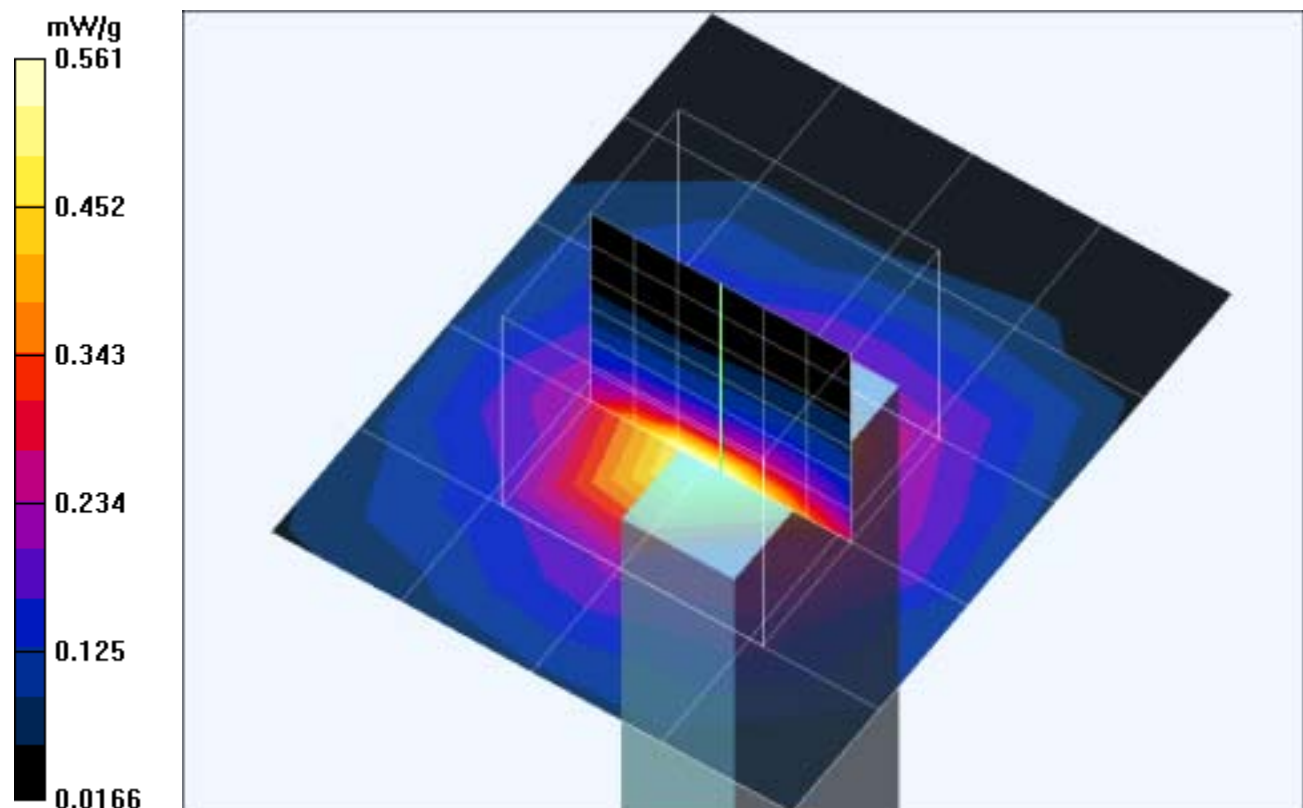
Peak SAR (extrapolated) = 1.42 W/kg

SAR(1 g) = 0.515 mW/g; SAR(10 g) = 0.231 mW/g

Reference Value = 16.4 V/m

Power Drift = -0.07 dB

Maximum value of SAR = 0.533 mW/g



Test Laboratory: Advance Data Technology

USR5422 IBM ThinkPad X20 11b Tip Mode 10 Ch 11

**DUT: U.S. Robotics 802.11g 54Mbps USB Adapter ; Type: USR5422 ; Test Channel
Frequency: 2462 MHz**

Communication System: 802.11b ; Frequency: 2462 MHz; Duty Cycle: 1:1; Modulation type: CCK
Medium: MSL2450 ($\sigma = 1.9932 \text{ mho/m}$, $\epsilon_r = 50.6638$, $\rho = 1000 \text{ kg/m}^3$) ; Liquid level : 150 mm

Phantom section: Flat Section ; Separation distance : 0 mm (The tip of the EUT to the Phantom)

Antenna type : Internal Antenna ; Air temp. : 22.0 degrees ; Liquid temp. : 21.0 degrees

DASY4 Configuration:

- Probe: ET3DV6 - SN1790 ; ConvF(4.4, 4.4, 4.4) ; Calibrated: 2003/8/29
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn579; Calibrated: 2003/8/15
- Phantom: SAM 12; Type: SAM V4.0; Serial: TP 1202
- Measurement SW: DASY4, V4.1 Build 47; Postprocessing SW: SEMCAD, V1.6 Build 115

High Channel/Area Scan (5x6x1): Measurement grid: dx=15mm, dy=15mm

Reference Value = 14 V/m

Power Drift = -0.2 dB

Maximum value of SAR = 0.421 mW/g

High Channel/Zoon Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

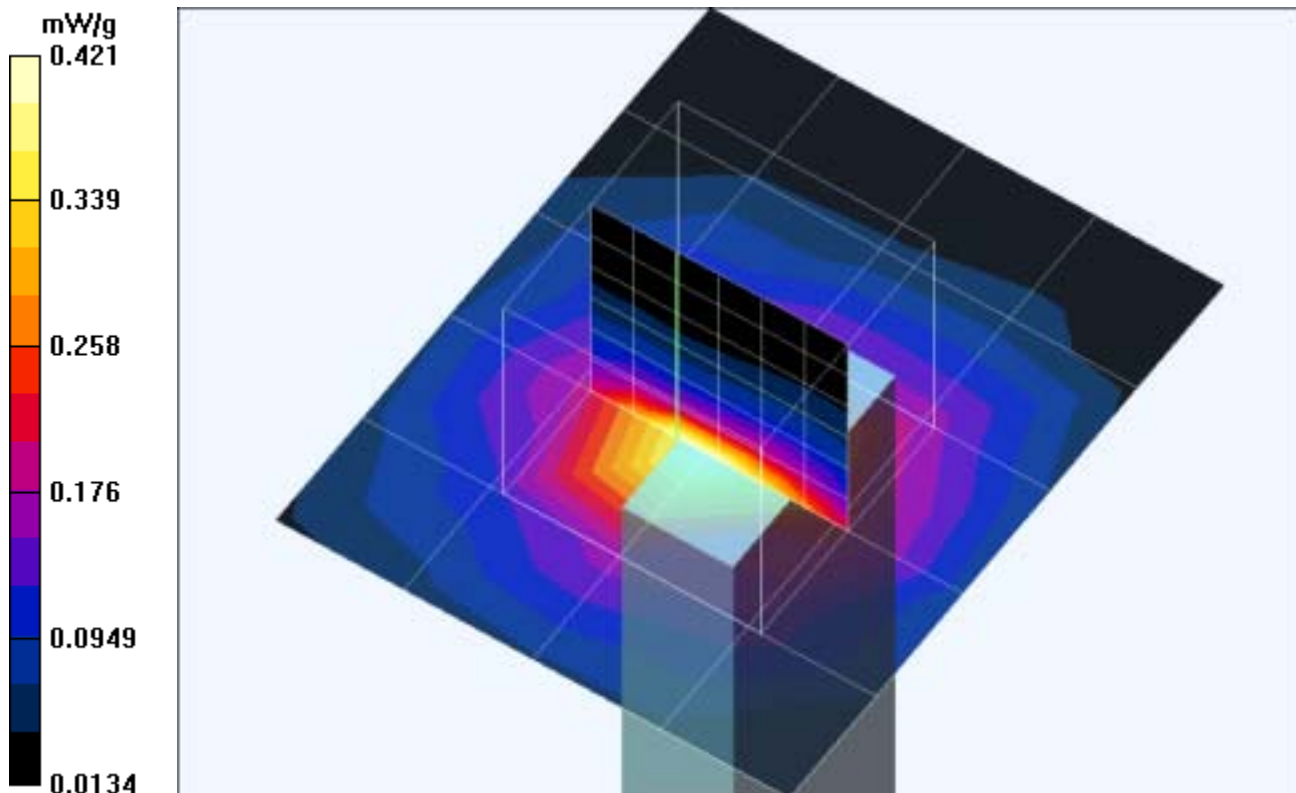
Peak SAR (extrapolated) = 1.06 W/kg

SAR(1 g) = 0.38 mW/g; SAR(10 g) = 0.171 mW/g

Reference Value = 14 V/m

Power Drift = -0.2 dB

Maximum value of SAR = 0.401 mW/g



Test Laboratory: Advance Data Technology

USR5422 IBM ThinkPad X20 11g Bottom Mode 11 Ch 1

DUT: U.S. Robotics 802.11g 54Mbps USB Adapter ; Type: USR5422 ; Test Channel Frequency: 2412 MHz

Communication System: 802.11g ; Frequency: 2412 MHz ; Duty Cycle: 1:1 ; Modulation type: OFDM

Medium: MSL2450 ($\sigma = 1.9267$ mho/m, $\epsilon_r = 50.8147$, $\rho = 1000$ kg/m³) ; Liquid level : 150mm

Phantom section: Flat Section ; Separation distance : 6 mm (The bottom side of the EUT to the Phantom)

Antenna type : Internal Antenna ; Air temp. : 22.0 degrees ; Liquid temp. : 21.0 degrees

DASY4 Configuration:

- Probe: ET3DV6 - SN1790 ; ConvF(4.4, 4.4, 4.4) ; Calibrated: 2003/8/29
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn579 ; Calibrated: 2003/8/15
- Phantom: SAM 12 ; Type: SAM V4.0 ; Serial: TP 1202
- Measurement SW: DASY4, V4.1 Build 47 ; Postprocessing SW: SEMCAD, V1.6 Build 115

Low Channel/Area Scan (5x8x1): Measurement grid: dx=15mm, dy=15mm

Reference Value = 8.85 V/m

Power Drift = -0.1 dB

Maximum value of SAR = 0.522 mW/g

Low Channel/Zoon Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

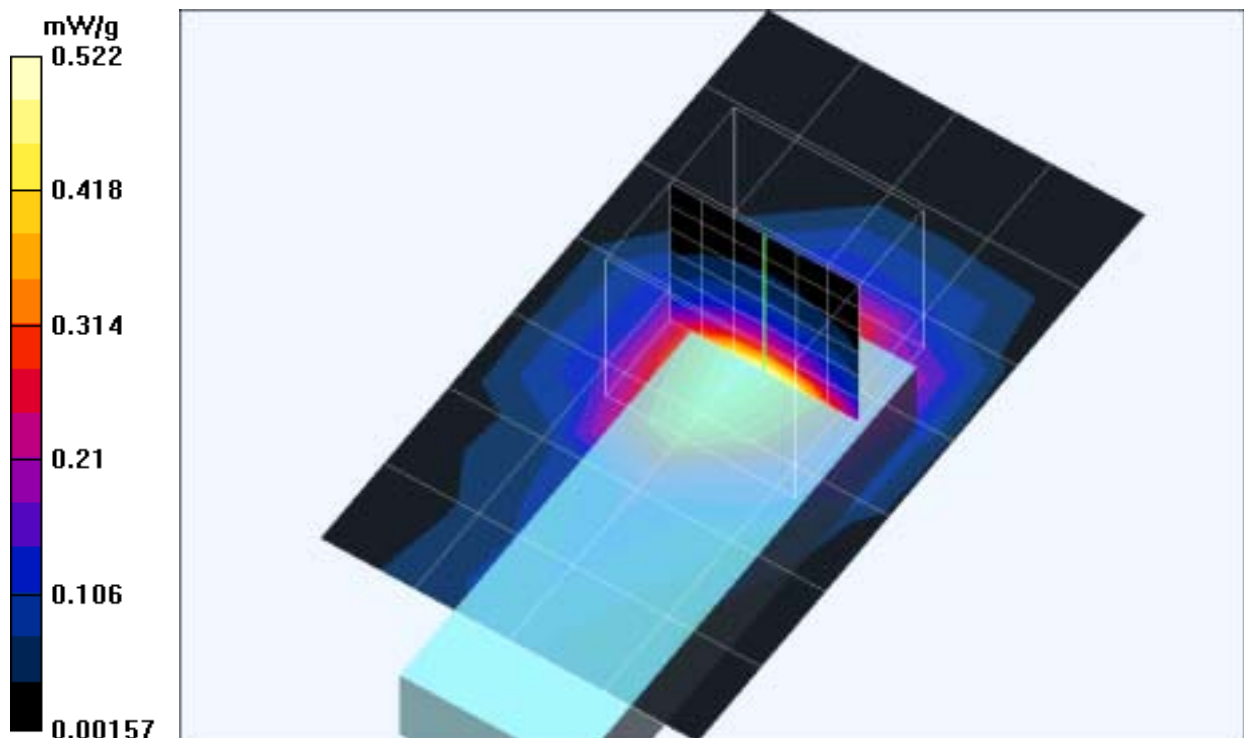
Peak SAR (extrapolated) = 1.12 W/kg

SAR(1 g) = 0.524 mW/g; SAR(10 g) = 0.255 mW/g

Reference Value = 8.85 V/m

Power Drift = -0.1 dB

Maximum value of SAR = 0.561 mW/g



Test Laboratory: Advance Data Technology

USR5422 IBM ThinkPad X20 11g Bottom Mode 11 Ch 6

DUT: U.S. Robotics 802.11g 54Mbps USB Adapter ; Type: USR5422 ; Test Channel Frequency: 2437 MHz

Communication System: 802.11g ; Frequency: 2437 MHz ; Duty Cycle: 1:1 ; Modulation type: OFDM

Medium: MSL2450 ($\sigma = 1.9596$ mho/m, $\epsilon_r = 50.7402$, $\rho = 1000$ kg/m³) ; Liquid level : 150mm

Phantom section: Flat Section ; Separation distance : 6 mm (The bottom side of the EUT to the Phantom)

Antenna type : Internal Antenna ; Air temp. : 22.0 degrees ; Liquid temp. : 21.0 degrees

DASY4 Configuration:

- Probe: ET3DV6 - SN1790 ; ConvF(4.4, 4.4, 4.4) ; Calibrated: 2003/8/29
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn579 ; Calibrated: 2003/8/15
- Phantom: SAM 12 ; Type: SAM V4.0 ; Serial: TP 1202
- Measurement SW: DASY4, V4.1 Build 47 ; Postprocessing SW: SEMCAD, V1.6 Build 115

Middle Channel/Area Scan (5x8x1): Measurement grid: dx=15mm, dy=15mm

Reference Value = 8.86 V/m

Power Drift = -0.2 dB

Maximum value of SAR = 0.55 mW/g

Middle Channel/Zoon Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

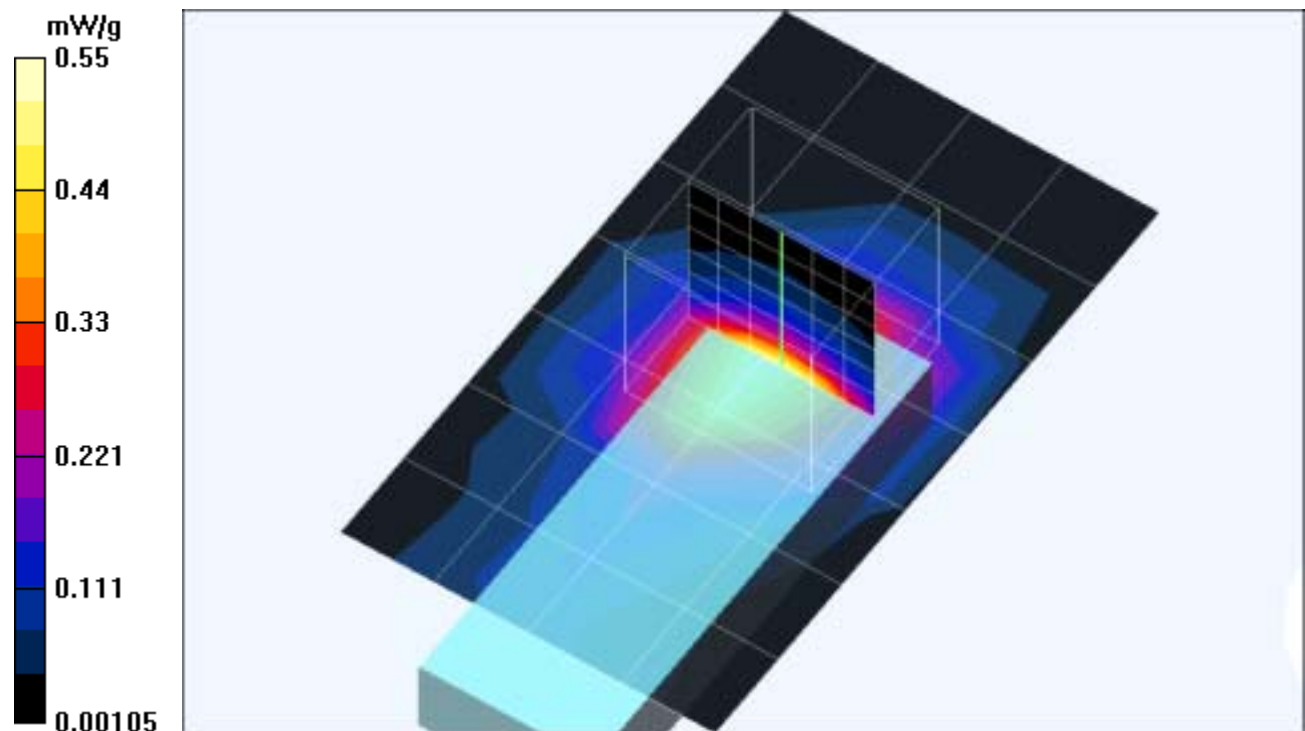
Peak SAR (extrapolated) = 1.24 W/kg

SAR(1 g) = 0.575 mW/g; SAR(10 g) = 0.279 mW/g

Reference Value = 8.86 V/m

Power Drift = -0.2 dB

Maximum value of SAR = 0.61 mW/g



Test Laboratory: Advance Data Technology

USR5422 IBM ThinkPad X20 11g Bottom Mode 11 Ch 11

DUT: U.S. Robotics 802.11g 54Mbps USB Adapter ; Type: USR5422 ; Test Channel Frequency: 2462 MHz

Communication System: 802.11g ; Frequency: 2462 MHz ; Duty Cycle: 1:1 ; Modulation type: OFDM

Medium: MSL2450 ($\sigma = 1.9932$ mho/m, $\epsilon_r = 50.6638$, $\rho = 1000$ kg/m³) ; Liquid level : 150mm

Phantom section: Flat Section ; Separation distance : 6 mm (The bottom side of the EUT to the Phantom)

Antenna type : Internal Antenna ; Air temp. : 22.0 degrees ; Liquid temp. : 21.0 degrees

DASY4 Configuration:

- Probe: ET3DV6 - SN1790 ; ConvF(4.4, 4.4, 4.4) ; Calibrated: 2003/8/29
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn579 ; Calibrated: 2003/8/15
- Phantom: SAM 12 ; Type: SAM V4.0 ; Serial: TP 1202
- Measurement SW: DASY4, V4.1 Build 47 ; Postprocessing SW: SEMCAD, V1.6 Build 115

High Channel/Area Scan (5x8x1): Measurement grid: dx=15mm, dy=15mm

Reference Value = 7.77 V/m

Power Drift = -0.1 dB

Maximum value of SAR = 0.441 mW/g

High Channel/Zoon Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

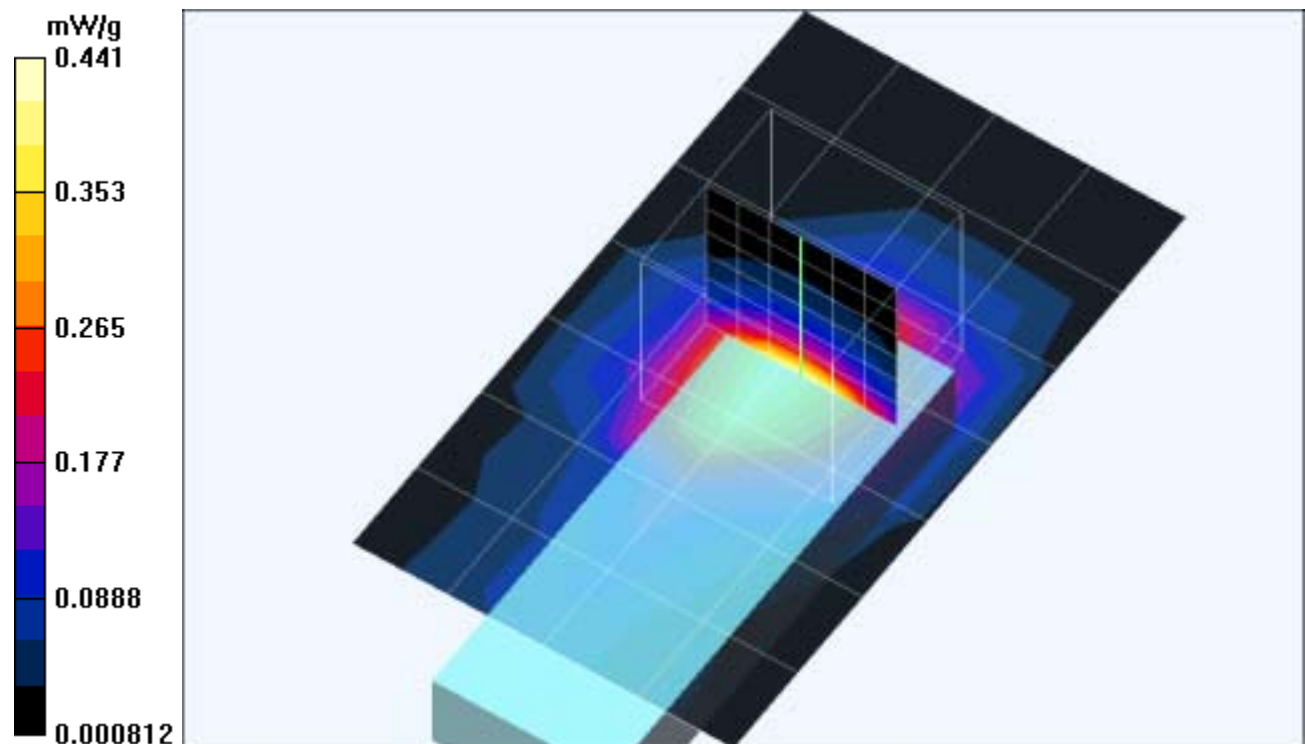
Peak SAR (extrapolated) = 0.991 W/kg

SAR(1 g) = 0.455 mW/g; SAR(10 g) = 0.22 mW/g

Reference Value = 7.77 V/m

Power Drift = -0.1 dB

Maximum value of SAR = 0.485 mW/g



Test Laboratory: Advance Data Technology

USR5422 IBM ThinkPad X20 11g Tip Mode 12 Ch 1

DUT: U.S. Robotics 802.11g 54Mbps USB Adapter ; Type: USR5422 ; Test Channel Frequency: 2412 MHz

Communication System: 802.11g ; Frequency: 2412 MHz; Duty Cycle: 1:1; Modulation type: OFDM

Medium: MSL2450 ($\sigma = 1.9267$ mho/m, $\epsilon_r = 50.8147$, $\rho = 1000$ kg/m³) ; Liquid level : 150 mm

Phantom section: Flat Section ; Separation distance : 0 mm (The tip of the EUT to the Phantom)

Antenna type : Internal Antenna ; Air temp. : 22.0 degrees ; Liquid temp. : 21.0 degrees

DASY4 Configuration:

- Probe: ET3DV6 - SN1790 ; ConvF(4.4, 4.4, 4.4) ; Calibrated: 2003/8/29
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn579; Calibrated: 2003/8/15
- Phantom: SAM 12; Type: SAM V4.0; Serial: TP 1202
- Measurement SW: DASY4, V4.1 Build 47; Postprocessing SW: SEMCAD, V1.6 Build 115

Low Channel/Area Scan (5x6x1): Measurement grid: dx=15mm, dy=15mm

Reference Value = 10.8 V/m

Power Drift = -0.2 dB

Maximum value of SAR = 0.228 mW/g

Low Channel/Zoon Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

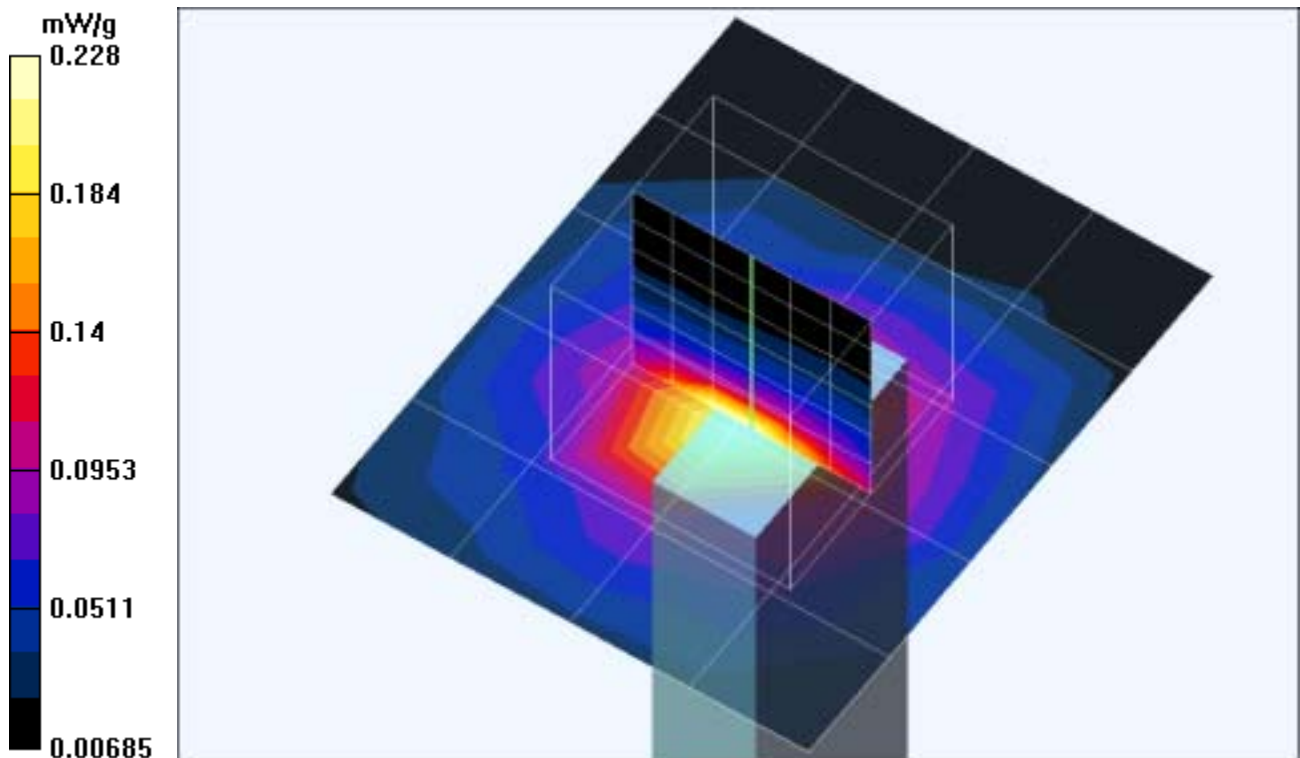
Peak SAR (extrapolated) = 0.542 W/kg

SAR(1 g) = 0.2 mW/g; SAR(10 g) = 0.0888 mW/g

Reference Value = 10.8 V/m

Power Drift = -0.2 dB

Maximum value of SAR = 0.214 mW/g



Test Laboratory: Advance Data Technology

USR5422 IBM ThinkPad X20 11g Tip Mode 12 Ch 6

DUT: U.S. Robotics 802.11g 54Mbps USB Adapter ; Type: USR5422 ; Test Channel Frequency: 2437 MHz

Communication System: 802.11g ; Frequency: 2437 MHz; Duty Cycle: 1:1; Modulation type: OFDM

Medium: MSL2450 ($\sigma = 1.9596$ mho/m, $\epsilon_r = 50.7402$, $\rho = 1000$ kg/m³) ; Liquid level : 150 mm

Phantom section: Flat Section ; Separation distance : 0 mm (The tip of the EUT to the Phantom)

Antenna type : Internal Antenna ; Air temp. : 22.0 degrees ; Liquid temp. : 21.0 degrees

DASY4 Configuration:

- Probe: ET3DV6 - SN1790 ; ConvF(4.4, 4.4, 4.4) ; Calibrated: 2003/8/29
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn579; Calibrated: 2003/8/15
- Phantom: SAM 12; Type: SAM V4.0; Serial: TP 1202
- Measurement SW: DASY4, V4.1 Build 47; Postprocessing SW: SEMCAD, V1.6 Build 115

Middle Channel/Area Scan (5x6x1): Measurement grid: dx=15mm, dy=15mm

Reference Value = 10.5 V/m

Power Drift = -0.2 dB

Maximum value of SAR = 0.235 mW/g

Middle Channel/Zoon Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

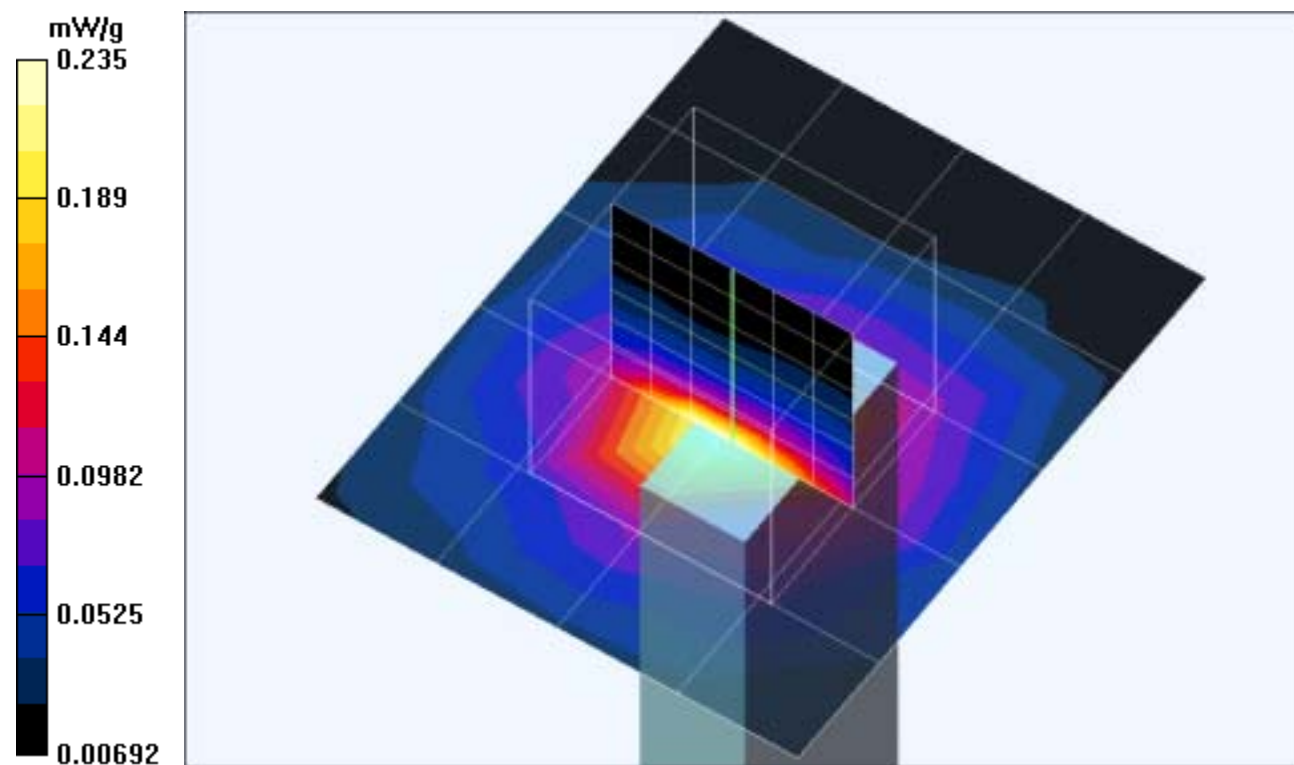
Peak SAR (extrapolated) = 0.588 W/kg

SAR(1 g) = 0.215 mW/g; SAR(10 g) = 0.0955 mW/g

Reference Value = 10.5 V/m

Power Drift = -0.2 dB

Maximum value of SAR = 0.224 mW/g



Test Laboratory: Advance Data Technology

USR5422 IBM ThinkPad X20 11g Tip Mode 12 Ch 11

DUT: U.S. Robotics 802.11g 54Mbps USB Adapter ; Type: USR5422 ; Test Channel Frequency: 2462 MHz

Communication System: 802.11g ; Frequency: 2462 MHz; Duty Cycle: 1:1; Modulation type: OFDM

Medium: MSL2450 ($\sigma = 1.9932$ mho/m, $\epsilon_r = 50.6638$, $\rho = 1000$ kg/m³) ; Liquid level : 150 mm

Phantom section: Flat Section ; Separation distance : 0 mm (The tip of the EUT to the Phantom)

Antenna type : Internal Antenna ; Air temp. : 22.0 degrees ; Liquid temp. : 21.0 degrees

DASY4 Configuration:

- Probe: ET3DV6 - SN1790 ; ConvF(4.4, 4.4, 4.4) ; Calibrated: 2003/8/29
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn579; Calibrated: 2003/8/15
- Phantom: SAM 12; Type: SAM V4.0; Serial: TP 1202
- Measurement SW: DASY4, V4.1 Build 47; Postprocessing SW: SEMCAD, V1.6 Build 115

High Channel/Area Scan (5x6x1): Measurement grid: dx=15mm, dy=15mm

Reference Value = 9.12 V/m

Power Drift = -0.01 dB

Maximum value of SAR = 0.178 mW/g

High Channel/Zoon Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

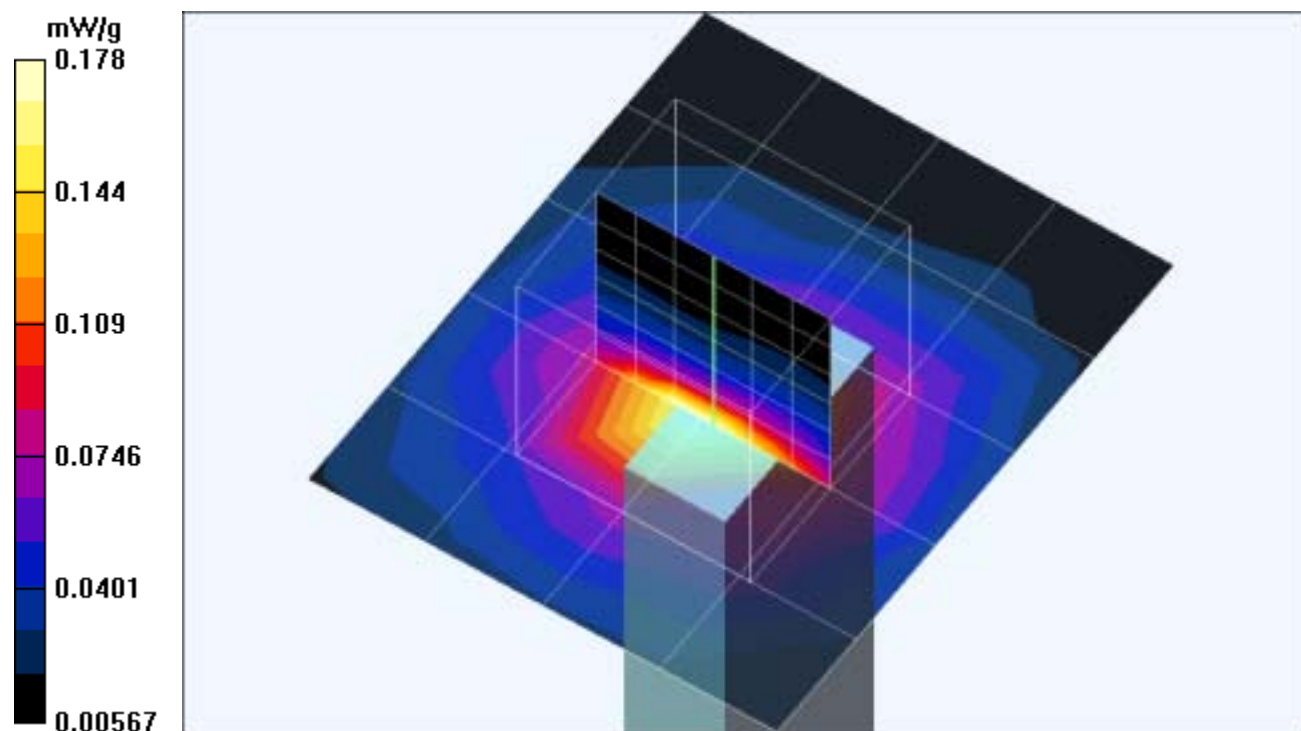
Peak SAR (extrapolated) = 0.481 W/kg

SAR(1 g) = 0.169 mW/g; SAR(10 g) = 0.0751 mW/g

Reference Value = 9.12 V/m

Power Drift = -0.01 dB

Maximum value of SAR = 0.176 mW/g



A3 : SYSTEM VALIDATION

Date/Time: 08/09/04 09:19:24

Test Laboratory: Advance Data Technology

System Validation Check-MSL 2450MHz

DUT: Dipole 2450 MHz ; Type: D2450V2 ; Test Channel Frequency: 2450 MHz

Communication System: CW ; Frequency: 2450 MHz; Duty Cycle: 1:1; Modulation type: CW
Medium: MSL2450 ($\sigma = 1.9771$ mho/m, $\epsilon_r = 50.6991$, $\rho = 1000$ kg/m³) ; Liquid level : 150mm
Phantom section: Flat Section ; Separation distance : 10 mm (The feetpoint of the dipole to the Phantom) Air temp. : 22.0 degrees ; Liquid temp. : 21.0 degrees

DASY4 Configuration:

- Probe: ET3DV6 - SN1790 ; ConvF(4.4, 4.4, 4.4) ; Calibrated: 2003/8/29
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn579; Calibrated: 2003/8/15
- Phantom: SAM 12; Type: SAM V4.0; Serial: TP 1202
- Measurement SW: DASY4, V4.1 Build 47; Postprocessing SW: SEMCAD, V1.6 Build 115

d=10mm, Pin=250mW/Area Scan (6x6x1): Measurement grid: dx=15mm, dy=15mm

Reference Value = 93.7 V/m

Power Drift = -0.2 dB

Maximum value of SAR = 9.96 mW/g

d=10mm, Pin=250mW/Zoom Scan (7x7x7) (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

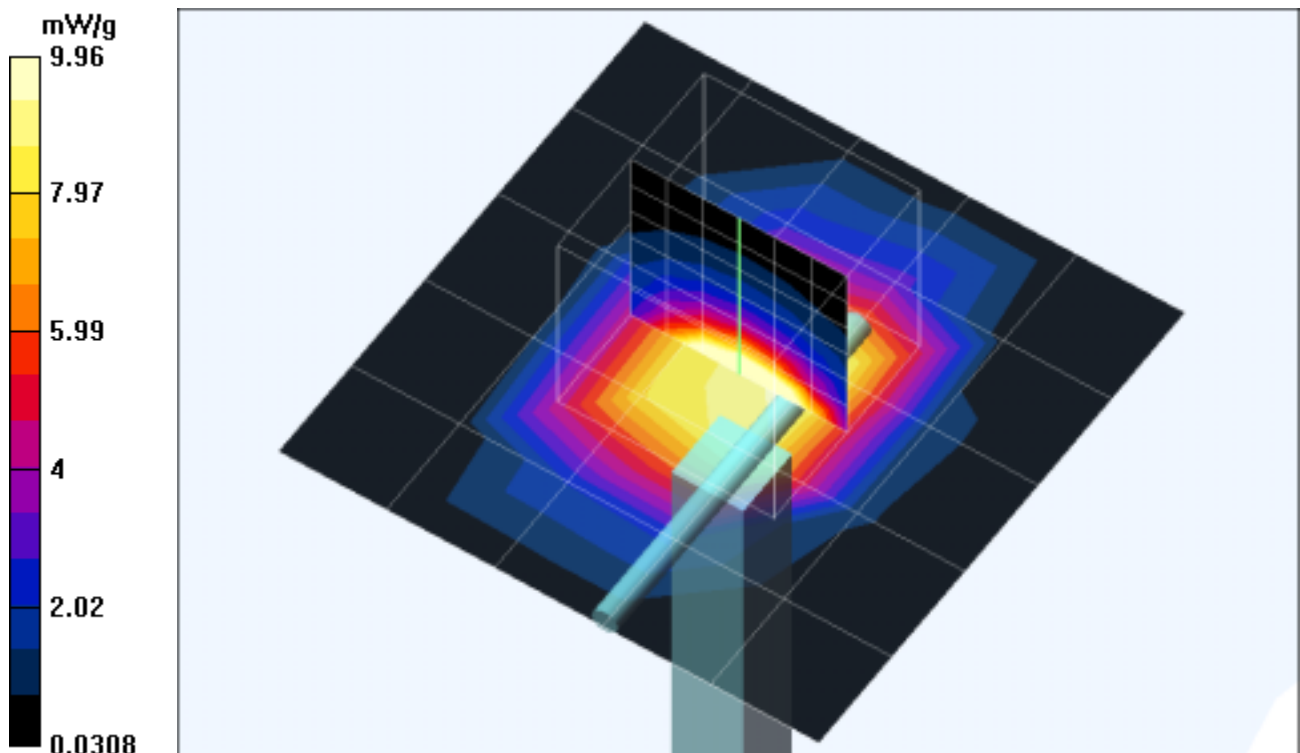
Peak SAR (extrapolated) = 31 W/kg

SAR(1 g) = 14 mW/g; SAR(10 g) = 6.29 mW/g

Reference Value = 93.7 V/m

Power Drift = -0.2 dB

Maximum value of SAR = 15.2 mW/g



APPENDIX B : ADT SAR MEASUREMENT SYSTEM



APPENDIX C: PHOTOGRAPHS OF SYSTEM VALIDATION





APPENDIX D: SYSTEM CERTIFICATE & CALIBRATION

D1: SAM PHANTOM

Schmid & Partner Engineering AG

Zeughausstrasse 43, 8004 Zurich, Switzerland, Phone +41 1 245 97 00, Fax +41 1 245 97 79

Certificate of conformity / First Article Inspection

Item	SAM Twin Phantom V4.0
Type No	QD 000 P40 CA
Series No	TP-1150 and higher
Manufacturer / Origin	Untersee Composites Hauptstr. 69 CH-8559 Fruthwilen Switzerland

Tests

The series production process used allows the limitation to test of first articles. Complete tests were made on the pre-series Type No. QD 000 P40 AA, Serial No. TP-1001 and on the series first article Type No. QD 000 P40 BA, Serial No. TP-1006. Certain parameters have been retested using further series units (called samples).

Test	Requirement	Details	Units tested
Shape	Compliance with the geometry according to the CAD model.	IT'IS CAD File (*)	First article, Samples
Material thickness	Compliant with the requirements according to the standards	2mm +/- 0.2mm in specific areas	First article, Samples
Material parameters	Dielectric parameters for required frequencies	200 MHz – 3 GHz Relative permittivity < 5 Loss tangent < 0.05.	Material sample TP 104-5
Material resistivity	The material has been tested to be compatible with the liquids defined in the standards	Liquid type HSL 1800 and others according to the standard.	Pre-series, First article

Standards

- [1] CENELEC EN 50361
- [2] IEEE P1528-200x draft 6.5
- [3] IEC PT 62209 draft 0.9

(*) The IT'IS CAD file is derived from [2] and is also within the tolerance requirements of the shapes of [1] and [3].

Conformity

Based on the sample tests above, we certify that this item is in compliance with the uncertainty requirements of SAR measurements specified in standard [1] and draft standards [2] and [3].

Date

28.02.2002

Signature / Stamp

F. Bombault

**Schmid & Partner
Engineering AG**

Zeughausstrasse 43, CH-8004 Zurich
Tel. +41 1 245 97 00, Fax +41 1 245 97 79

Johann Kappeler



D2: DOSIMETRIC E-FIELD PROBE

IMPORTANT NOTICE

USAGE OF PROBES IN ORGANIC SOLVENTS

Diethylene Glycol Monobutyl Ether (the basis for liquids above 1 GHz), as many other organic solvents, is a very effective softener for synthetic materials. These solvents can cause irreparable damage to certain SPEAG products, except those which are explicitly declared as compliant with organic solvents.

Compatible Probes:

- ET3DV6
- ET3DV6R
- ES3DV2
- ER3DV6
- H3DV6

Important Note for ET3DV6 Probes:

The ET3DV6 probes shall not be exposed to solvents longer than necessary for the measurements and shall be cleaned daily after use with warm water and stored dry.

Client **Auden > Chunghwa Telecom**

CALIBRATION CERTIFICATE

Object(s) **ET3DV6 - SN: 1790**

Calibration procedure(s) **QA CAL-01.v2
Calibration procedure for dosimetric E-field probes**

Calibration date: **August 29, 2003**

Condition of the calibrated item **In Tolerance (according to the specific calibration document)**

This calibration statement documents traceability of M&TE used in the calibration procedures and conformity of the procedures with the ISO/IEC 17025 international standard.

All calibrations have been conducted in the closed laboratory facility: environment temperature 22 +/- 2 degrees Celsius and humidity < 75%.

Calibration Equipment used (M&TE critical for calibration)

Model Type	ID #	Cal Date (Calibrated by, Certificate No.)	Scheduled Calibration
RF generator HP 8684C	US3642U01700	4-Aug-99 (SPEAG, in house check Aug-02)	In house check: Aug-05
Power sensor E4412A	MY41495277	2-Apr-03 (METAS, No 252-0250)	Apr-04
Power sensor HP 8481A	MY41092180	18-Sep-02 (Agilent, No. 20020918)	Sep-03
Power meter EPM E4419B	GB41293874	2-Apr-03 (METAS, No 252-0250)	Apr-04
Network Analyzer HP 8753E	US37390585	18-Oct-01 (Agilent, No. 24BR1033101)	In house check: Oct 03
Fuke Process Calibrator Type 702	SN: 6295803	3-Sep-01 (ELCAL, No.2360)	Sep-03

Calibrated by:

Name	Function	Signature
Nico Vetterli	Technician	

Approved by:

Katja Pokovic	Laboratory Director
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Date issued: August 28, 2003

This calibration certificate is issued as an intermediate solution until the accreditation process (based on ISO/IEC 17025 International Standard) for Calibration Laboratory of Schmid & Partner Engineering AG is completed.

Probe ET3DV6

SN:1790

Manufactured:	May 28, 2003
Last calibration:	August 29, 2003

Calibrated for DASY Systems

(Note: non-compatible with DASY2 system!)

DASY - Parameters of Probe: ET3DV6 SN:1790**Sensitivity in Free Space****Diode Compression**

NormX	1.74 $\mu\text{V}/(\text{V}/\text{m})^2$	DCP X	96	mV
NormY	1.69 $\mu\text{V}/(\text{V}/\text{m})^2$	DCP Y	96	mV
NormZ	1.76 $\mu\text{V}/(\text{V}/\text{m})^2$	DCP Z	96	mV

Sensitivity in Tissue Simulating Liquid

Head 900 MHz $\epsilon_r = 41.5 \pm 5\%$ $\sigma = 0.97 \pm 5\%$ mho/m

Valid for f=800-1000 MHz with Head Tissue Simulating Liquid according to EN 50361, P1528-200X

ConvF X	6.4 $\pm 9.5\%$ (k=2)	Boundary effect:	
ConvF Y	6.4 $\pm 9.5\%$ (k=2)	Alpha	0.48
ConvF Z	6.4 $\pm 9.5\%$ (k=2)	Depth	2.13

Head 1800 MHz $\epsilon_r = 40.0 \pm 5\%$ $\sigma = 1.40 \pm 5\%$ mho/m

Valid for f=1710-1910 MHz with Head Tissue Simulating Liquid according to EN 50361, P1528-200X

ConvF X	5.1 $\pm 9.5\%$ (k=2)	Boundary effect:	
ConvF Y	5.1 $\pm 9.5\%$ (k=2)	Alpha	0.49
ConvF Z	5.1 $\pm 9.5\%$ (k=2)	Depth	2.70

Boundary Effect

Head 900 MHz Typical SAR gradient: 5 % per mm

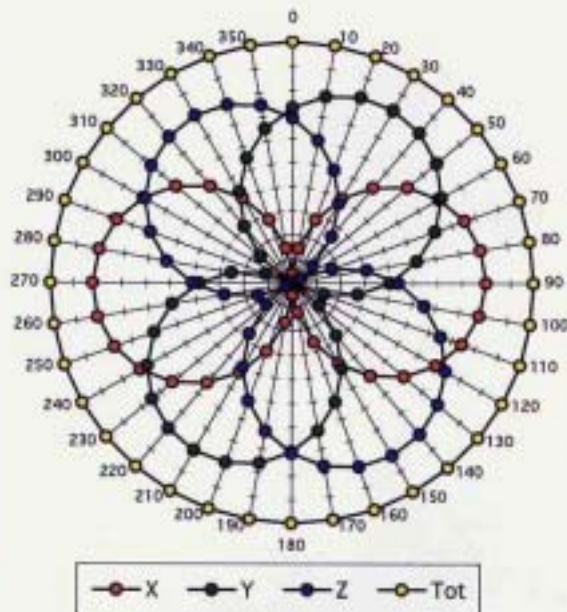
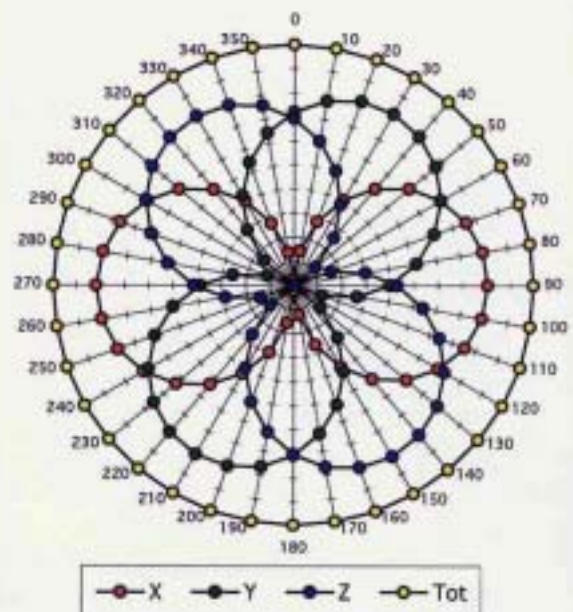
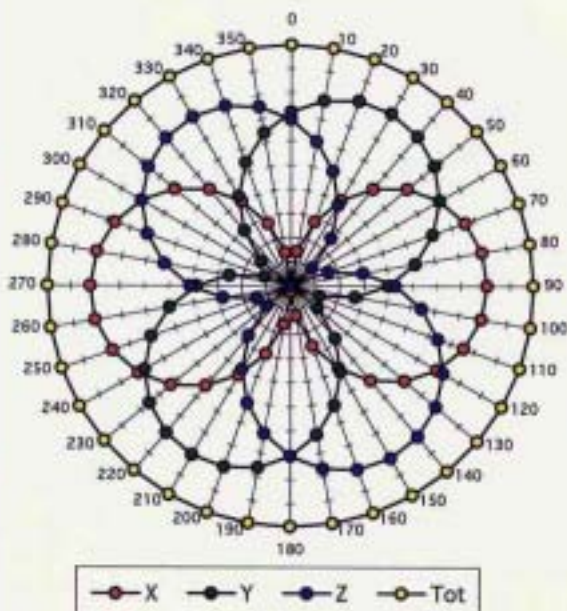
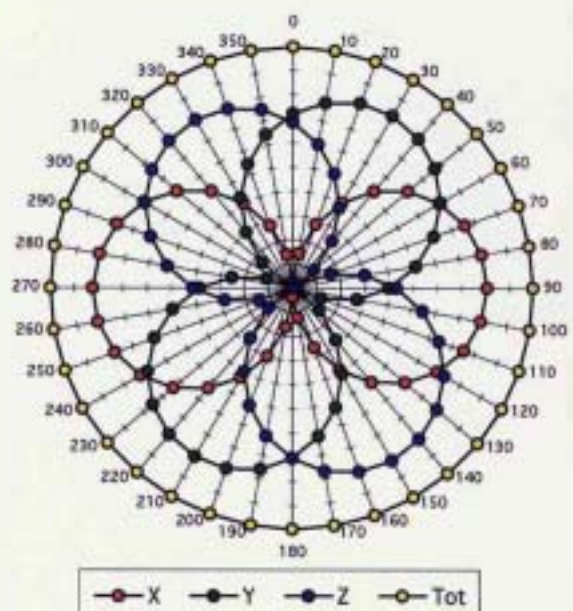
Probe Tip to Boundary		1 mm	2 mm
SAR _{be} [%]	Without Correction Algorithm	9.4	5.2
SAR _{be} [%]	With Correction Algorithm	0.2	0.4

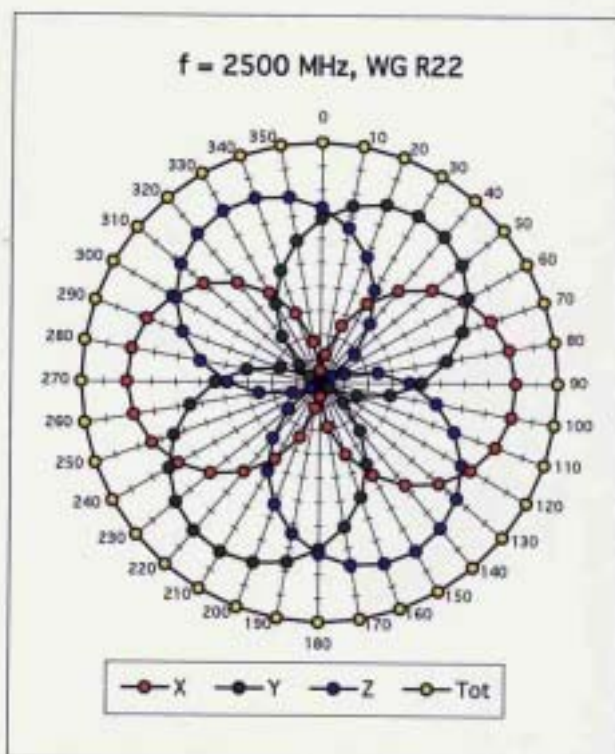
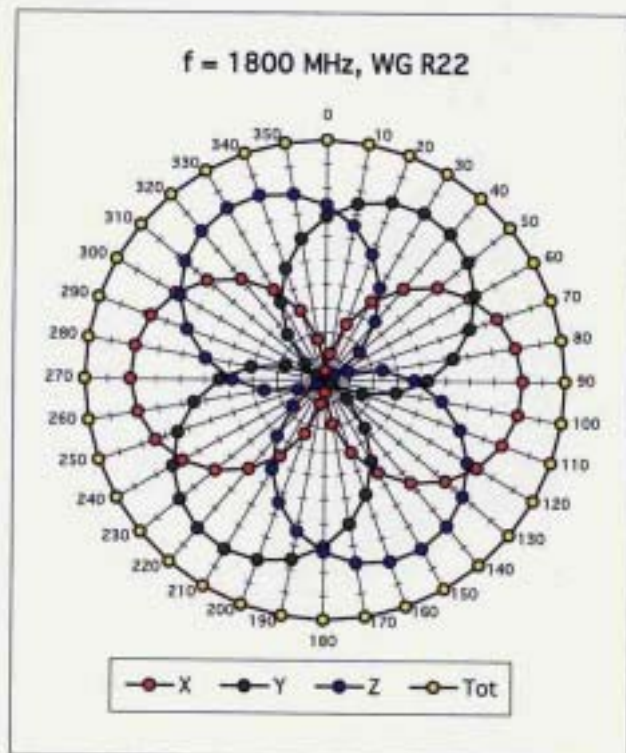
Head 1800 MHz Typical SAR gradient: 10 % per mm

Probe Tip to Boundary		1 mm	2 mm
SAR _{be} [%]	Without Correction Algorithm	13.9	9.5
SAR _{be} [%]	With Correction Algorithm	0.2	0.1

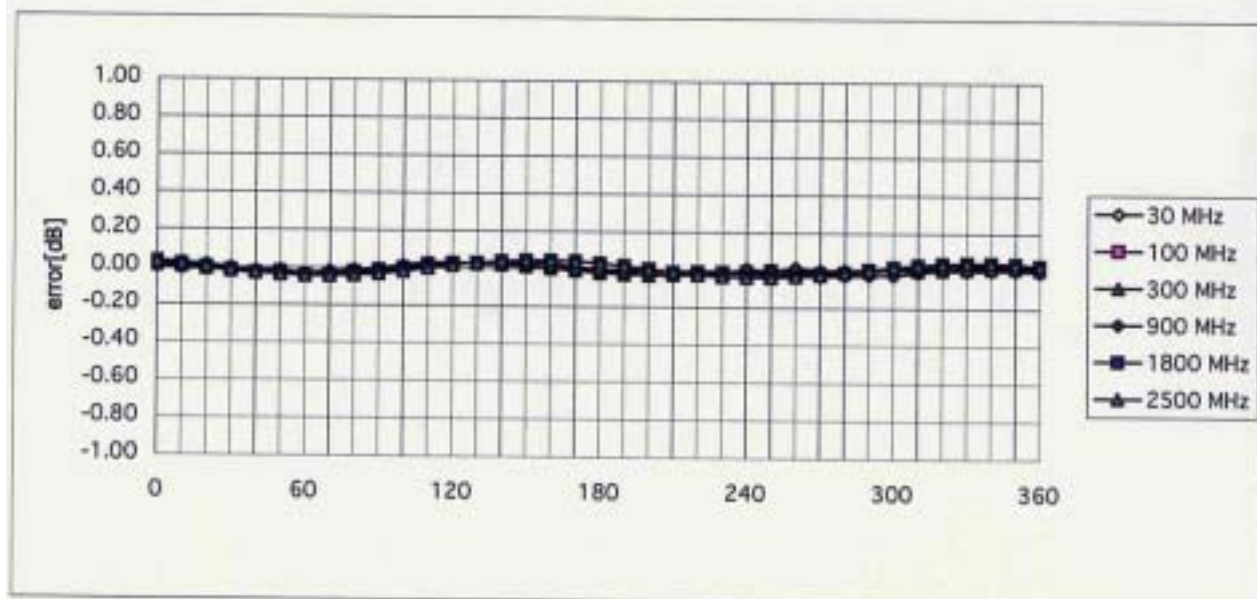
Sensor Offset

Probe Tip to Sensor Center	2.7	mm
Optical Surface Detection	1.6 $\pm$ 0.2	mm

Receiving Pattern (ϕ), $\theta = 0^\circ$ $f = 30 \text{ MHz}$, TEM cell if110 $f = 100 \text{ MHz}$, TEM cell if110 $f = 300 \text{ MHz}$, TEM cell if110 $f = 900 \text{ MHz}$, TEM cell if110

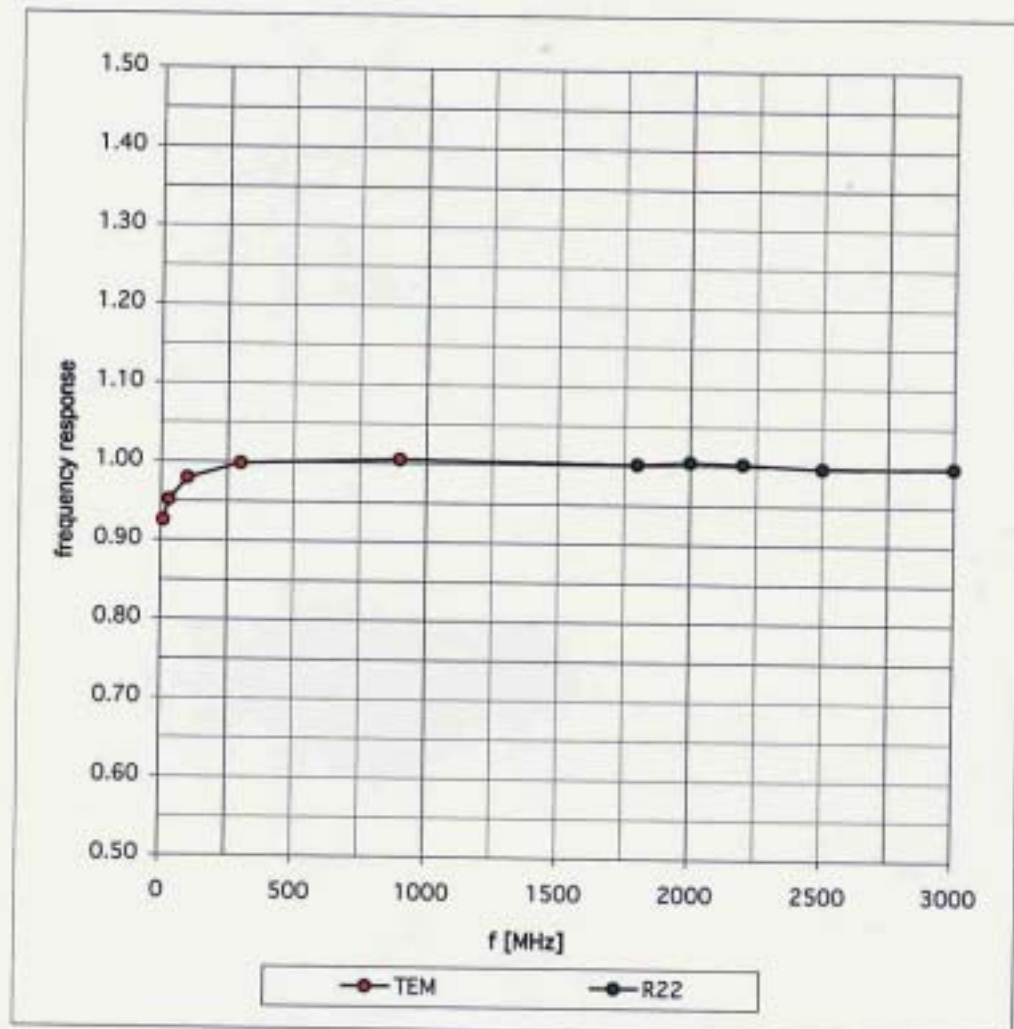


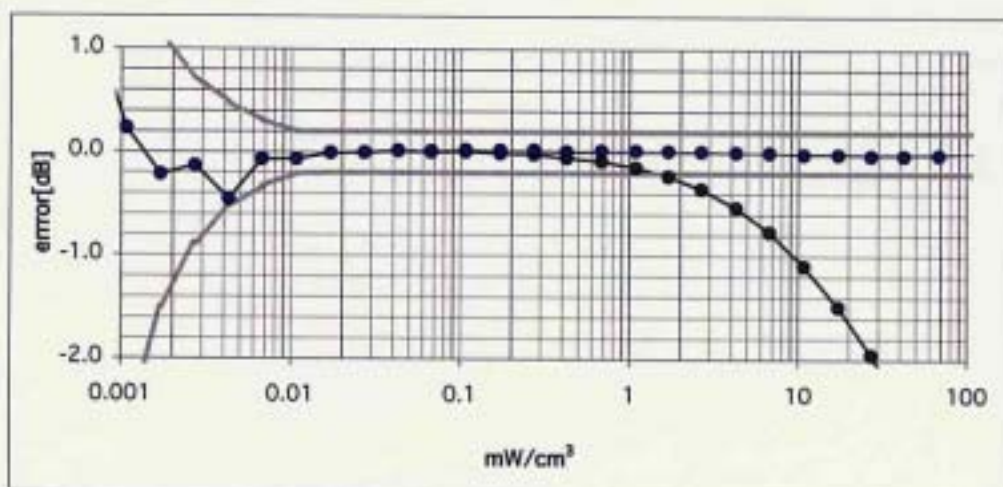
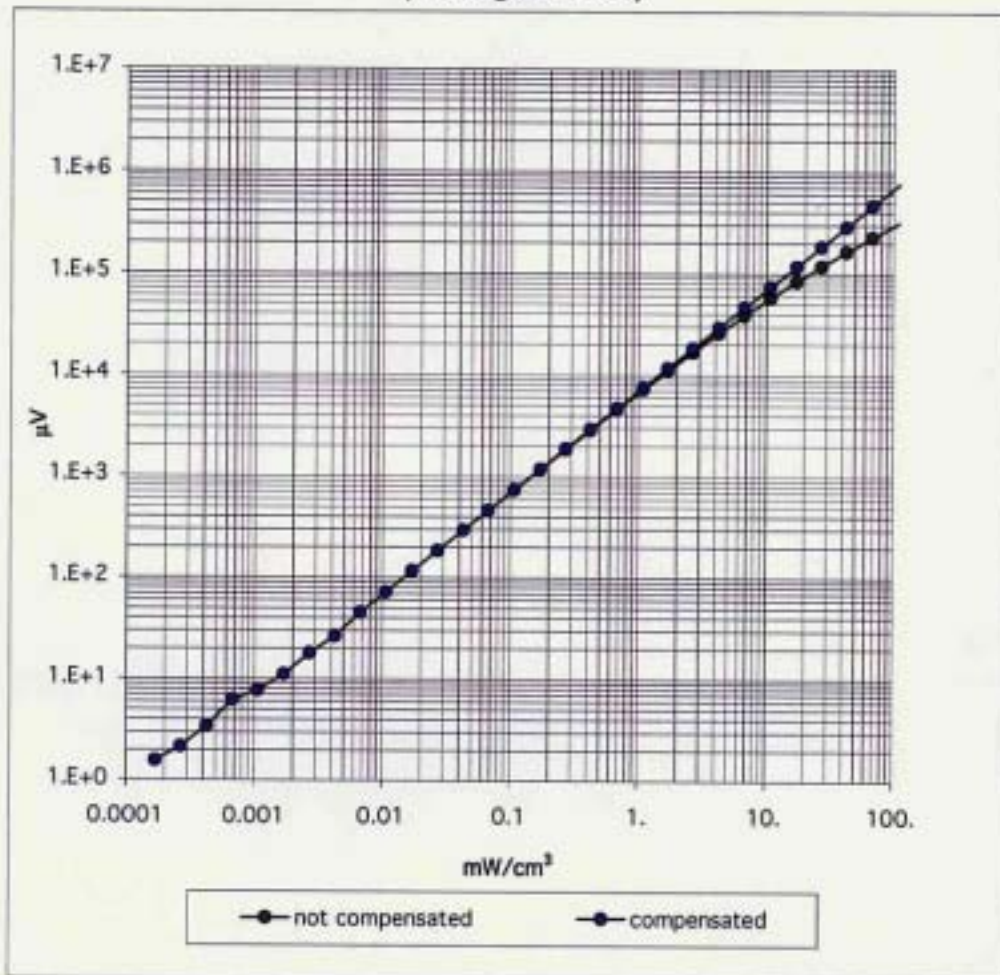
Isotropy Error (ϕ), $\theta = 0^\circ$



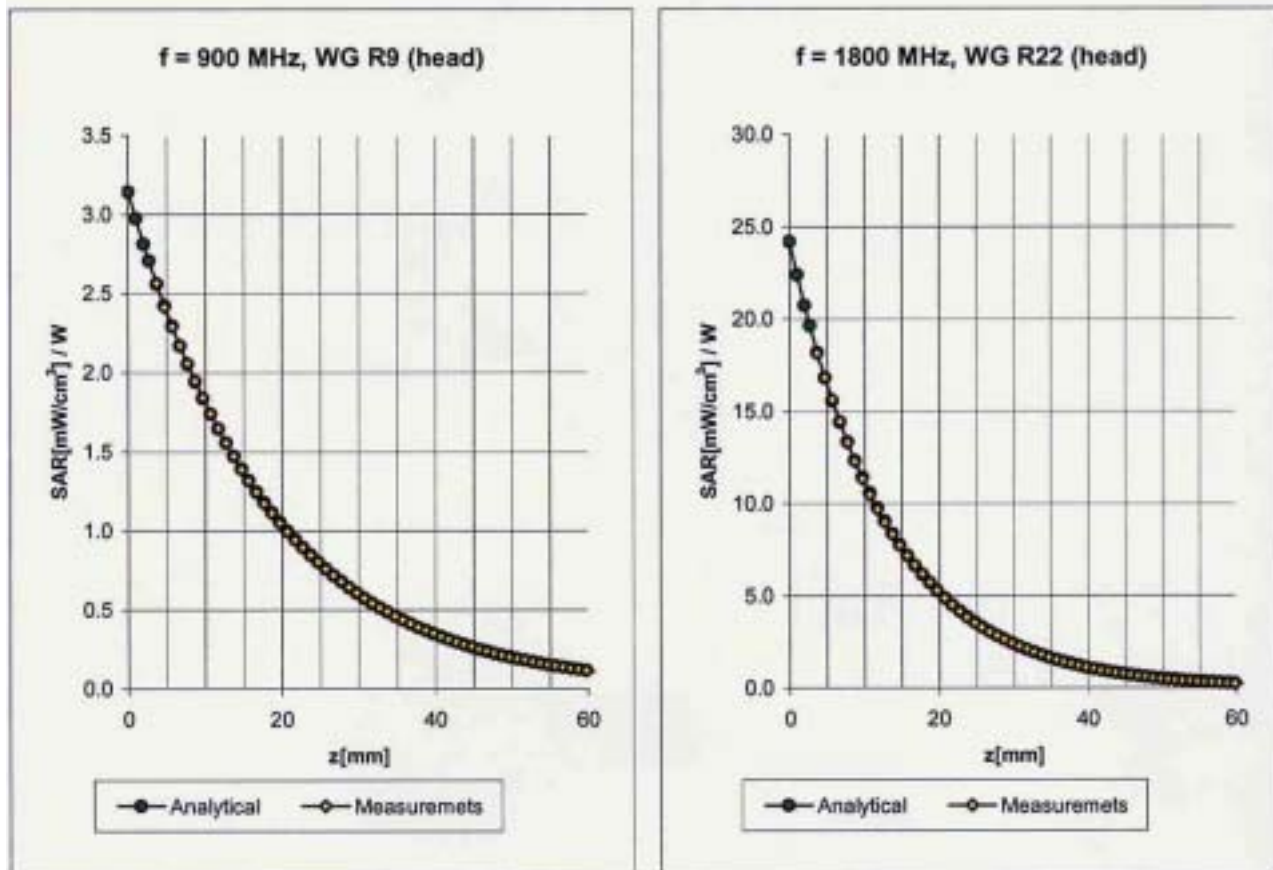
Frequency Response of E-Field

(TEM-Cell:ifi110, Waveguide R22)



Dynamic Range f(SAR_{brain})**(Waveguide R22)**

Conversion Factor Assessment



Head 900 MHz $\epsilon_r = 41.5 \pm 5\%$ $\sigma = 0.97 \pm 5\%$ mho/m

Valid for f=800-1000 MHz with Head Tissue Simulating Liquid according to EN 50361, P1528-200X

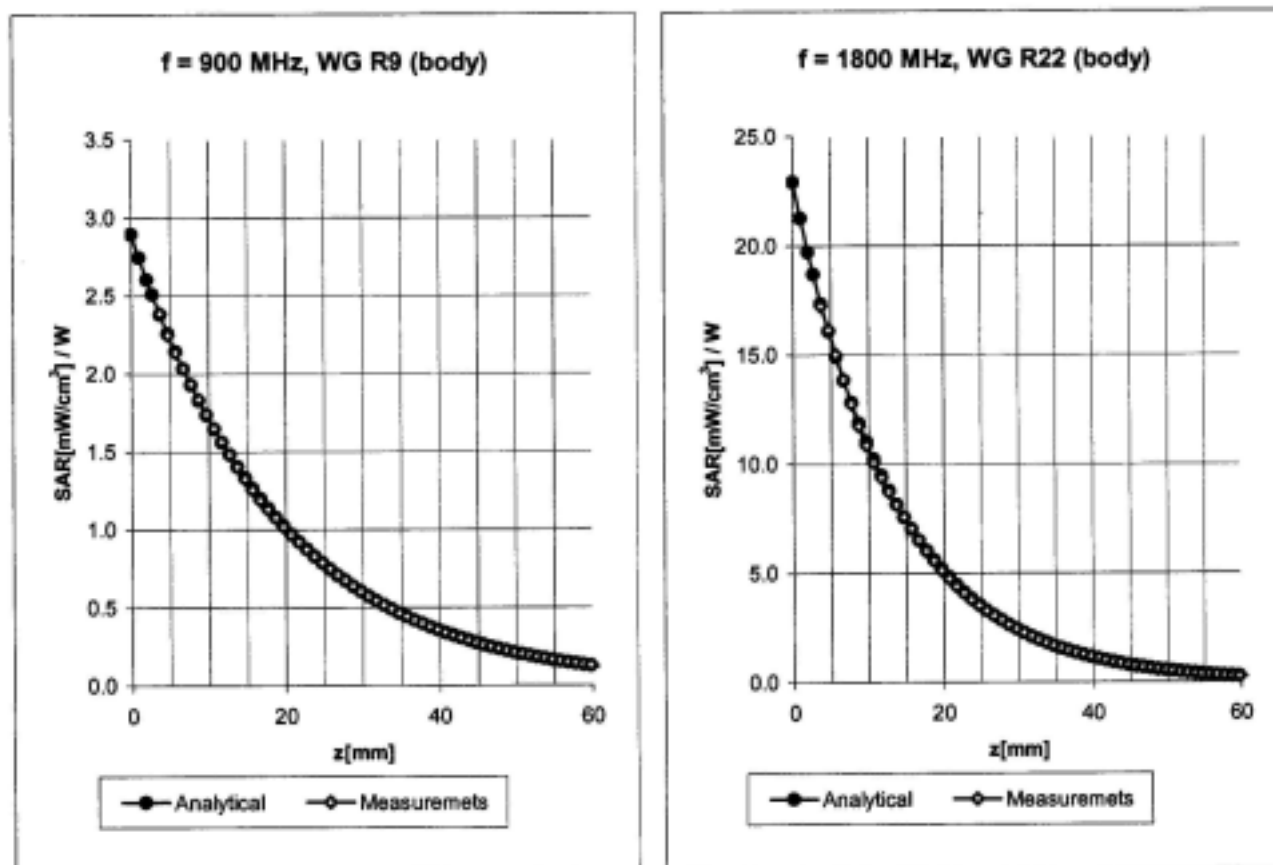
ConvF X	$6.4 \pm 9.5\%$ (k=2)	Boundary effect:	
ConvF Y	$6.4 \pm 9.5\%$ (k=2)	Alpha	0.48
ConvF Z	$6.4 \pm 9.5\%$ (k=2)	Depth	2.13

Head 1800 MHz $\epsilon_r = 40.0 \pm 5\%$ $\sigma = 1.40 \pm 5\%$ mho/m

Valid for f=1710-1910 MHz with Head Tissue Simulating Liquid according to EN 50361, P1528-200X

ConvF X	$5.1 \pm 9.5\%$ (k=2)	Boundary effect:	
ConvF Y	$5.1 \pm 9.5\%$ (k=2)	Alpha	0.49
ConvF Z	$5.1 \pm 9.5\%$ (k=2)	Depth	2.70

Conversion Factor Assessment



Body 900 MHz $\epsilon_r = 55.0 \pm 5\%$ $\sigma = 1.05 \pm 5\%$ mho/m

Valid for f=800-1000 MHz with Body Tissue Simulating Liquid according to OET 65 Suppl. C

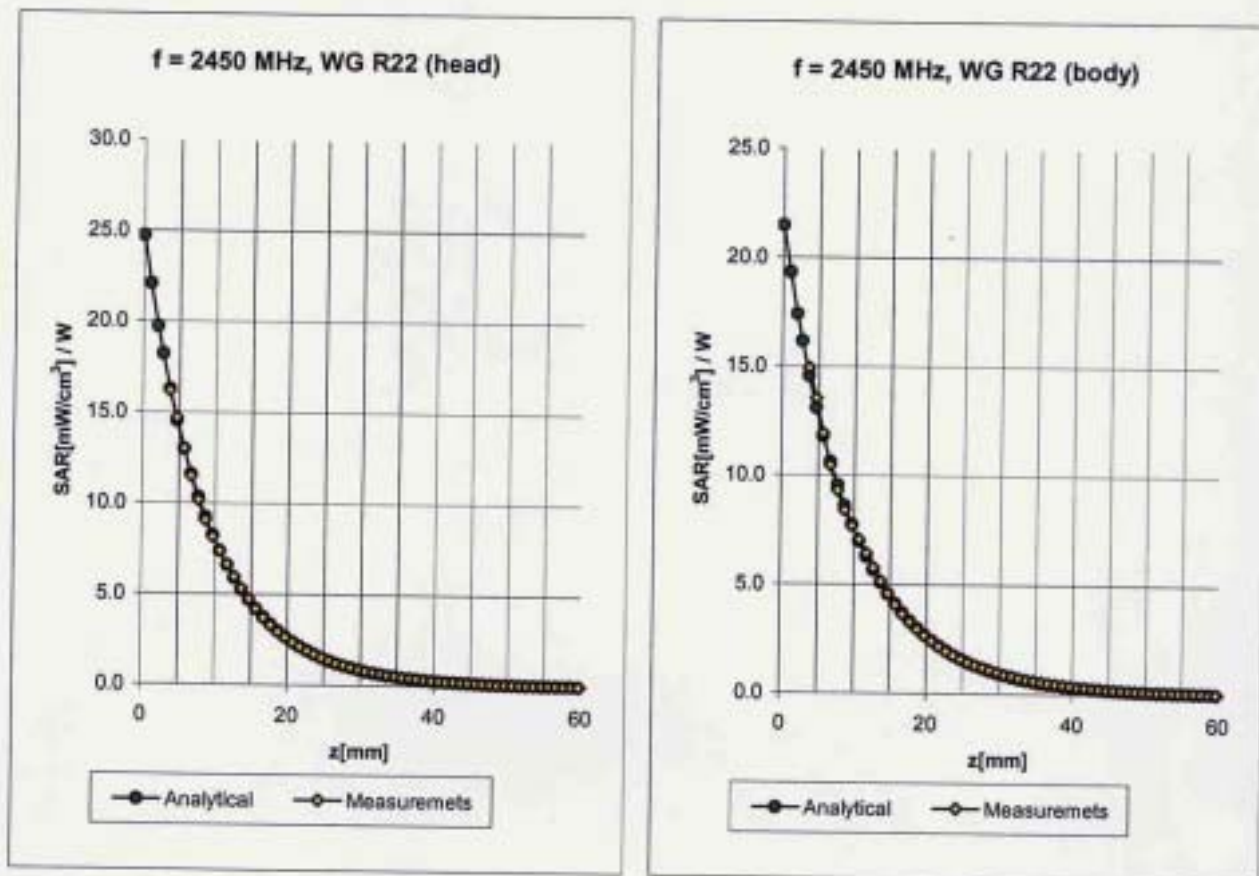
ConvF X	6.2 $\pm$ 9.5% (k=2)	Boundary effect:	
ConvF Y	6.2 $\pm$ 9.5% (k=2)	Alpha	0.40
ConvF Z	6.2 $\pm$ 9.5% (k=2)	Depth	2.57

Body 1800 MHz $\epsilon_r = 53.3 \pm 5\%$ $\sigma = 1.52 \pm 5\%$ mho/m

Valid for f=1710-1910 MHz with Body Tissue Simulating Liquid according to OET 65 Suppl. C

ConvF X	4.8 $\pm$ 9.5% (k=2)	Boundary effect:	
ConvF Y	4.8 $\pm$ 9.5% (k=2)	Alpha	0.54
ConvF Z	4.8 $\pm$ 9.5% (k=2)	Depth	2.76

Conversion Factor Assessment



Head 2450 MHz $\epsilon_r = 39.2 \pm 5\%$ $\sigma = 1.80 \pm 5\%$ mho/m

Valid for f=2400-2500 MHz with Head Tissue Simulating Liquid according to EN 50361, P1528-200X

ConvF X	$4.7 \pm 8.9\%$ (k=2)	Boundary effect:	
ConvF Y	$4.7 \pm 8.9\%$ (k=2)	Alpha	1.00
ConvF Z	$4.7 \pm 8.9\%$ (k=2)	Depth	1.89

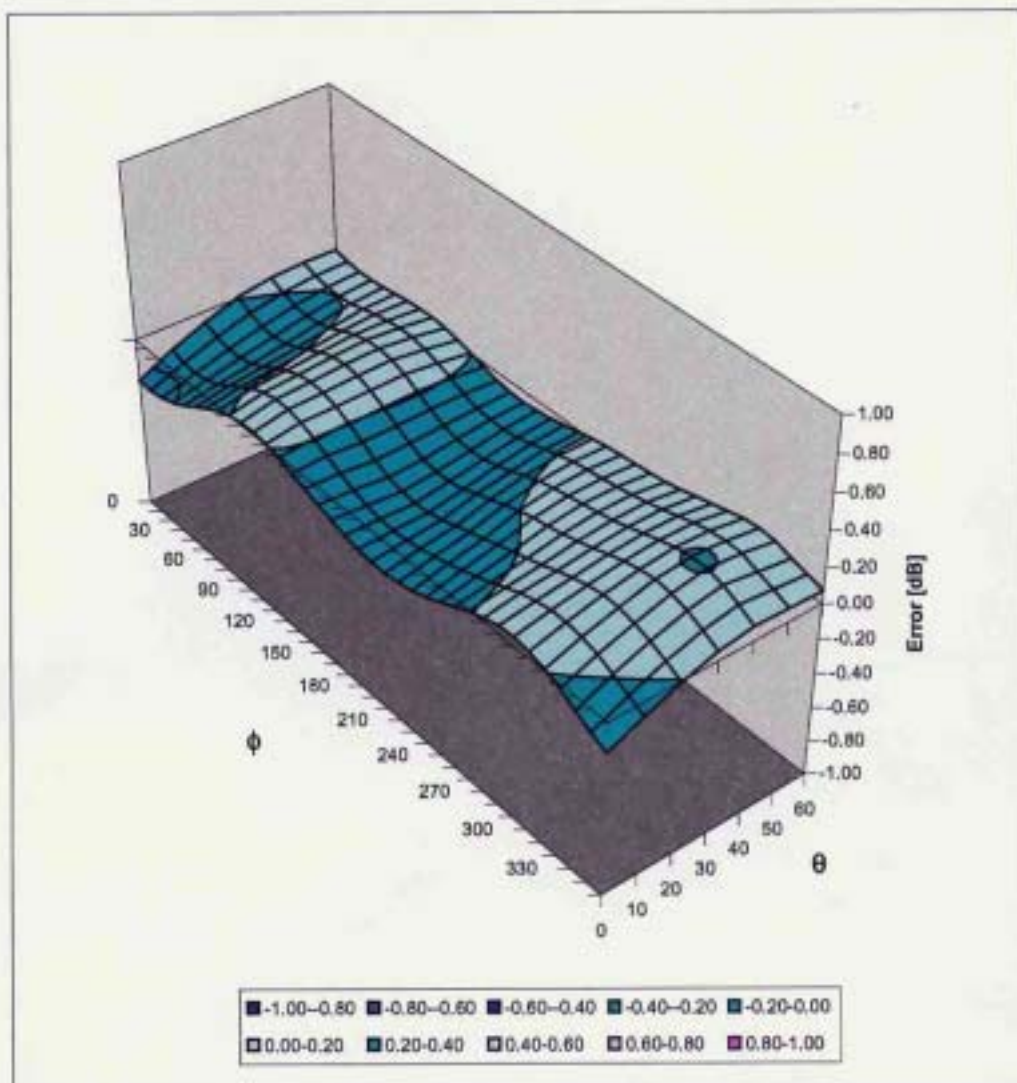
Body 2450 MHz $\epsilon_r = 52.7 \pm 5\%$ $\sigma = 1.95 \pm 5\%$ mho/m

Valid for f=2400-2500 MHz with Body Tissue Simulating Liquid according to OET 65 Suppl. C

ConvF X	$4.4 \pm 8.9\%$ (k=2)	Boundary effect:	
ConvF Y	$4.4 \pm 8.9\%$ (k=2)	Alpha	1.21
ConvF Z	$4.4 \pm 8.9\%$ (k=2)	Depth	1.59

Deviation from Isotropy in HSL

Error (θ, ϕ), $f = 900$ MHz



D3: DAE

Client

CALIBRATION CERTIFICATE

Object(s) DAE3 - SN:579

Calibration procedure(s) QA CAL-06.v3
Calibration procedure for the data acquisition unit (DAE)

Calibration date: August 15, 2003

Condition of the calibrated item In Tolerance (according to the specific calibration document)

This calibration statement documents traceability of M&TE used in the calibration procedures and conformity of the procedures with the ISO/IEC 17025 international standard.

All calibrations have been conducted in the closed laboratory facility: environment temperature 22 ± 2 degrees Celsius and humidity $< 75\%$

Calibration Equipment used (M&TE critical for calibration)

Model Type	ID #	Cal Date	Scheduled Calibration
Fluke Process Calibrator Type 702	SN: 6295803	3-Sep-01	Sep-03

	Name	Function	Signature
Calibrated by:	Philip Storchenegger	Technician	
Approved by:	Fin Bernholt	R&D Director	

Date issued: August 15, 2003

This calibration certificate is issued as an intermediate solution until the accreditation process (based on ISO/IEC 17025 International Standard) for Calibration Laboratory of Schmid & Partner Engineering AG is completed.

3. Common mode sensitivity

DASY measurement parameters:

Auto Zero Time: 3 sec,

Measuring time: 3 sec

High/Low Range

in μV	Common mode Input Voltage	High Range Reading	Low Range Reading
Channel X	200mV	5.15	5.17
	- 200mV	-4.35	-4.88
Channel Y	200mV	9.00	8.70
	- 200mV	-10.57	-10.21
Channel Z	200mV	8.93	8.00
	- 200mV	-10.74	-10.51

4. Channel separation

DASY measurement parameters:

Auto Zero Time: 3 sec,

Measuring time: 3 sec

High Range

in μV	Input Voltage	Channel X	Channel Y	Channel Z
Channel X	200mV	-	0.87	-0.39
Channel Y	200mV	0.80	-	2.29
Channel Z	200mV	-2.73	-0.30	-

5. AD-Converter Values with inputs shorted

in LSB	Low Range	High Range
Channel X	16102	16311
Channel Y	16055	16139
Channel Z	15811	15833

6. Input Offset Measurement

DASY measurement parameters:

Auto Zero Time: 3 sec,

Measuring time: 3 sec

Number of measurements:

100, Low Range

Input 10M Ω

in μV	Average	min. Offset	max. Offset	Std. Deviation
Channel X	0.25	-1.75	1.20	0.43
Channel Y	-1.47	-2.17	0.46	0.35
Channel Z	-1.64	-2.78	0.28	0.45

6. Input Offset Measurement (cont'd)

Input shorted

in μV	Average	min. Offset	max. Offset	Std. Deviation
Channel X	-0.02	-0.85	0.97	0.27
Channel Y	-0.69	-2.12	0.97	0.35
Channel Z	-0.96	-2.39	0.43	0.35

7. Input Offset Current

Nominal Input circuitry offset current on all channels: <25fA

8. Input Resistance

In MOhm	Calibrating	Measuring
Channel X	0.2001	199.9
Channel Y	0.1999	203.3
Channel Z	0.2000	200.4

9. Low Battery Alarm Voltage

in V	Alarm Level
Supply (+ Vcc)	7.72
Supply (- Vcc)	7.55

10. Power Consumption

in mA	Switched off	Stand by	Transmitting
Supply (+ Vcc)	0.00	8.71	14.4
Supply (- Vcc)	-0.01	-8.03	-9.20



D4: 2450MHZ SYSTEM VALIDATION DIPOLE

Client Auden > Chunghwa Telecom

CALIBRATION CERTIFICATE

Object(s) D2450V2 - SN:737

Calibration procedure(s) QA CAL-05.v2
Calibration procedure for dipole validation kits

Calibration date: August 27, 2003

Condition of the calibrated item In Tolerance (according to the specific calibration document)

This calibration statement documents traceability of M&TE used in the calibration procedures and conformity of the procedures with the ISO/IEC 17025 international standard.

All calibrations have been conducted in the closed laboratory facility: environment temperature 22 ± 2 degrees Celsius and humidity < 75%.

Calibration Equipment used (M&TE critical for calibration)

Model Type	ID #	Cal Date (Calibrated by, Certificate No.)	Scheduled Calibration
RF generator R&S SML-03	100698	27-Mar-2002 (R&S, No. 20-92389)	In house check; Mar-05
Power sensor HP 8481A	MY41032317	18-Oct-02 (Agilent, No. 20021018)	Oct-04
Power sensor HP 8481A	US37292783	30-Oct-02 (METAS, No. 252-0236)	Oct-03
Power meter EPME442	GB37430704	30-Oct-02 (METAS, No. 252-0236)	Oct-03
Network Analyzer HP 8713E	US37390585	18-Oct-01 (Agilent, No. 24BR1033101)	In house check: Oct 03

	Name	Function	Signature
Calibrated by:	Judith Mueller	Technician	
Approved by:	Katja Pokovic	Laboratory Director	

Date issued: August 28, 2003

This calibration certificate is issued as an intermediate solution until the accreditation process (based on ISO/IEC 17025 International Standard) for Calibration Laboratory of Schmid & Partner Engineering AG is completed.

DASY

Dipole Validation Kit

Type: D2450V2

Serial: 737

Manufactured: August 26, 2003

Calibrated: August 27, 2003

1. Measurement Conditions

The measurements were performed in the flat section of the SAM twin phantom filled with **head simulating solution** of the following electrical parameters at 2450 MHz:

Relative Dielectricity	38.2	$\pm 5\%$
Conductivity	1.89 mho/m	$\pm 5\%$

The DASY4 System with a dosimetric E-field probe ES3DV2 (SN:3013, Conversion factor 4.8 at 2450 MHz) was used for the measurements.

The dipole was mounted on the small tripod so that the dipole feedpoint was positioned below the center marking of the flat phantom section and the dipole was oriented parallel to the body axis (the long side of the phantom). The standard measuring distance was 10mm from dipole center to the solution surface. Lossless spacer was used during measurements for accurate distance positioning.

The coarse grid with a grid spacing of 15mm was aligned with the dipole. The 7x7x7 fine cube was chosen for cube integration.

The dipole input power (forward power) was 250mW $\pm 3\%$. The results are normalized to 1W input power.

2. SAR Measurement with DASY4 System

Standard SAR-measurements were performed according to the measurement conditions described in section 1. The results (see figure supplied) have been normalized to a dipole input power of 1W (forward power). The resulting averaged SAR-values measured with the dosimetric probe ES3DV2 SN:3013 and applying the advanced extrapolation are:

averaged over 1 cm ³ (1 g) of tissue:	55.2 mW/g $\pm 16.3\%$ (k=2) ¹
averaged over 10 cm ³ (10 g) of tissue:	24.8 mW/g $\pm 16.2\%$ (k=2) ¹

¹ validation uncertainty

3. Dipole Impedance and Return Loss

The impedance was measured at the SMA-connector with a network analyzer and numerically transformed to the dipole feedpoint. The transformation parameters from the SMA-connector to the dipole feedpoint are:

Electrical delay	1.162 ns	(one direction)
Transmission factor:	0.983	(voltage transmission, one direction)

The dipole was positioned at the flat phantom sections according to section 1 and the distance spacer was in place during impedance measurements.

Feedpoint impedance at 2450 MHz:	$\text{Re}\{Z\} = 52.5 \Omega$
	$\text{Im}\{Z\} = 5.4 \Omega$
Return Loss at 2450 MHz	-24.8 dB

4. Measurement Conditions

The measurements were performed in the flat section of the SAM twin phantom filled with **body simulating solution** of the following electrical parameters at 2450 MHz:

Relative Dielectricity	50.8	$\pm 5\%$
Conductivity	2.03 mho/m	$\pm 5\%$

The DASY4 System with a dosimetric E-field probe ES3DV2 (SN:3013, Conversion factor 4.2 at 2450 MHz) was used for the measurements.

The dipole was mounted on the small tripod so that the dipole feedpoint was positioned below the center marking of the flat phantom section and the dipole was oriented parallel to the body axis (the long side of the phantom). The standard measuring distance was 10mm from dipole center to the solution surface. Lossless spacer was used during measurements for accurate distance positioning.

The coarse grid with a grid spacing of 15mm was aligned with the dipole. The 7x7x7 fine cube was chosen for cube integration.

The dipole input power (forward power) was 250mW $\pm 3\%$ The results are normalized to 1W input power.

5. SAR Measurement with DASY4 System

Standard SAR-measurements were performed according to the measurement conditions described in section 4. The results (see figure supplied) have been normalized to a dipole input power of 1W (forward power). The resulting averaged SAR-values measured with the dosimetric probe ES3DV2 SN:3013 and applying the advanced extrapolation are:

averaged over 1 cm³ (1 g) of tissue: **55.2 mW/g ± 16.8 % (k=2)²**

averaged over 10 cm³ (10 g) of tissue: **25.4 mW/g ± 16.2 % (k=2)²**

6. Dipole Impedance and Return Loss

The dipole was positioned at the flat phantom sections according to section 4 and the distance spacer was in place during impedance measurements.

Feedpoint impedance at 2450 MHz: **Re{Z} = 48.5 Ω**

Im {Z} = 6.1 Ω

Return Loss at 2450 MHz **-23.9 dB**

7. Handling

Do not apply excessive force to the dipole arms, because they might bend. Bending of the dipole arms stresses the soldered connections near the feedpoint leading to a damage of the dipole.

8. Design

The dipole is made of standard semirigid coaxial cable. The center conductor of the feeding line is directly connected to the second arm of the dipole. The antenna is therefore short-circuited for DC-signals.

Small end caps have been added to the dipole arms in order to improve matching when loaded according to the position as explained in Sections 1 and 4. The SAR data are not affected by this change. The overall dipole length is still according to the Standard.

9. Power Test

After long term use with 40W radiated power, only a slight warming of the dipole near the feedpoint can be measured.

² validation uncertainty

Test Laboratory: SPEAG, Zurich, Switzerland

File Name: SN737_SN3013_HSL2450_270803.daf

DUT: Dipole 2450 MHz; Type: D2450V2; Serial: D2450V2 - SN737

Program: Dipole Calibration

Communication System: CW-2450; Frequency: 2450 MHz; Duty Cycle: 1:1

Medium: HSL 2450 MHz ($\sigma = 1.89$ mho/m, $\epsilon_r = 38.19$, $\rho = 1000$ kg/m³)

Phantom section: Flat Section

Measurement Standard: DASY4 (High Precision Assessment)

DASY4 Configuration:

- Probe: ES3DV2 - SN3013; ConvF(4.8, 4.8, 4.8); Calibrated: 1/19/2003
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 - SN411; Calibrated: 1/16/2003
- Phantom: SAM with CRP - TP1006; Type: SAM 4.0; Serial: TP1006
- Measurement SW: DASY4, V4.1 Build 47; Postprocessing SW: SEMCAD, V1.6 Build 115

Pin = 250 mW; d = 10 mm/Area Scan (81x81x1): Measurement grid: dx=15mm, dy=15mm

Reference Value = 90.7 V/m

Power Drift = -0.07 dB

Maximum value of SAR = 15.2 mW/g

Pin = 250 mW; d = 10 mm/Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

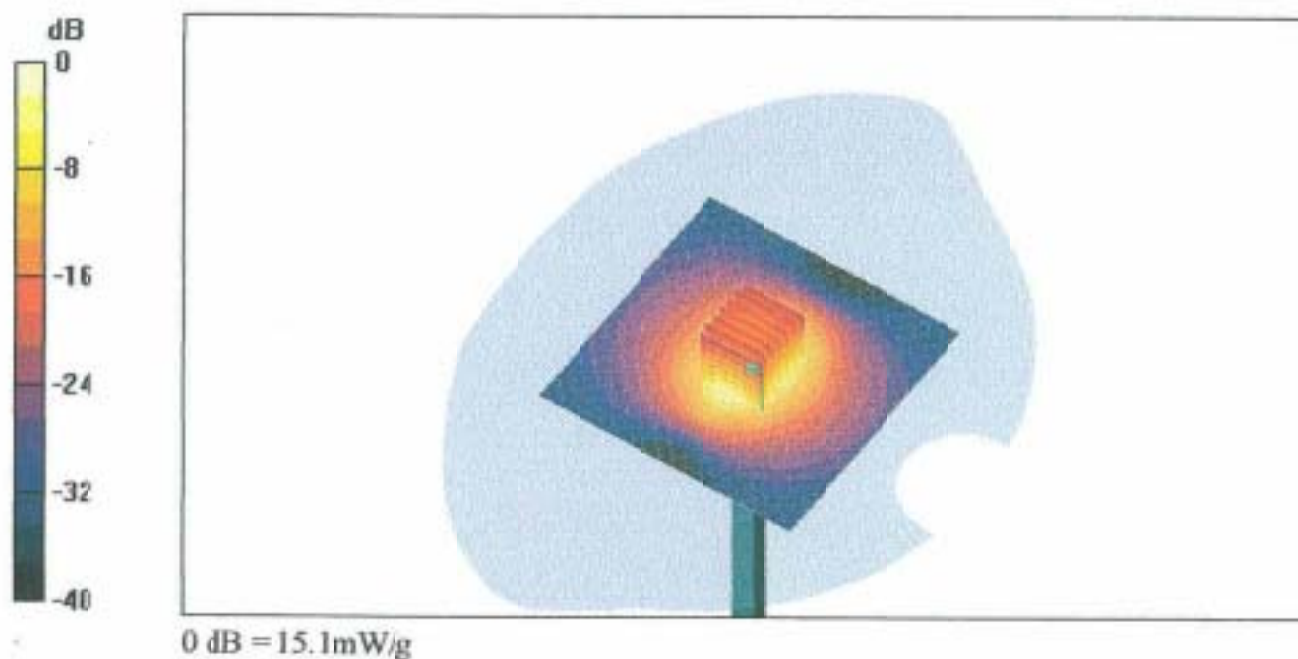
Peak SAR (extrapolated) = 29.6 W/kg

SAR(1 g) = 13.8 mW/g; SAR(10 g) = 6.2 mW/g

Reference Value = 90.7 V/m

Power Drift = -0.07 dB

Maximum value of SAR = 15.1 mW/g



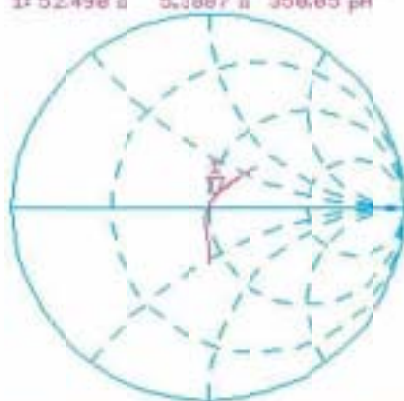
27 Aug 2003 09:59:05
 CH2 S11 1 U 75 1: 52.490 d 5.1887 d 350.85 pH 2 450.000 000 MHz

Del

Cor

Avs
36

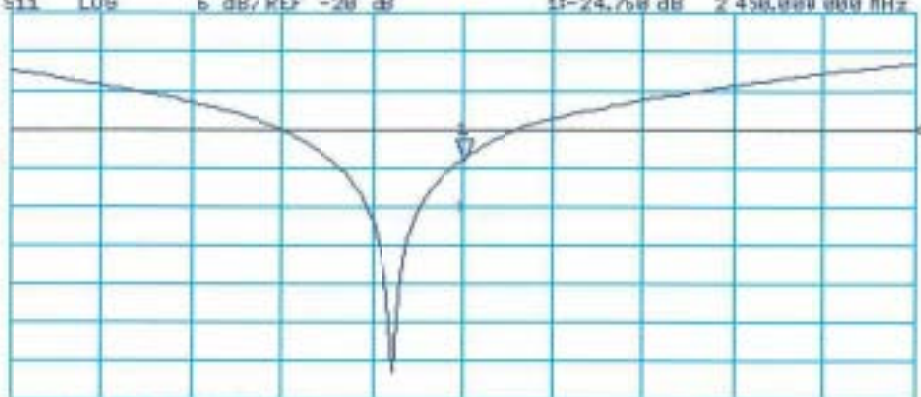
f



CH2 S11 LOG 6 dB/ REF -20 dB 1: -24.750 dB 2 450.000 000 MHz

Cor

f



CENTER 2 450.000 000 MHz

SPAN 400.000 000 MHz

Test Laboratory: SPEAG, Zurich, Switzerland
 File Name: SN737_SN3013_M2450_270803.da4

DUT: Dipole 2450 MHz; Type: D2450V2; Serial: D2450V2 - SN737
Program: Dipole Calibration

Communication System: CW-2450; Frequency: 2450 MHz; Duty Cycle: 1:1

Medium: Muscle 2450 MHz ($\sigma = 2.03$ mho/m, $\epsilon_r = 50.75$, $\rho = 1000$ kg/m³)

Phantom: section: Flat Section

Measurement Standard: DASY4 (High Precision Assessment)

DASY4 Configuration

- Probe: ES3DV2 - SN3013; ConvF(4.2, 4.2, 4.2); Calibrated: 1/19/2003
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 - SN411; Calibrated: 1/16/2003
- Phantom: SAM with CRP - TP1006; Type: SAM 4.0; Serial: TP.1006
- Measurement SW: DASY4, V4.1 Build 47; Postprocessing SW: SEMCAD, V1.6 Build 115

Pin = 250 mW; d = 10 mm/Area Scan (81x81x1): Measurement grid: dx=15mm, dy=15mm

Reference Value = 90.4 V/m

Power Drift = -0.03 dB

Maximum value of SAR = 15.7 mW/g

Pin = 250 mW; d = 10 mm/Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

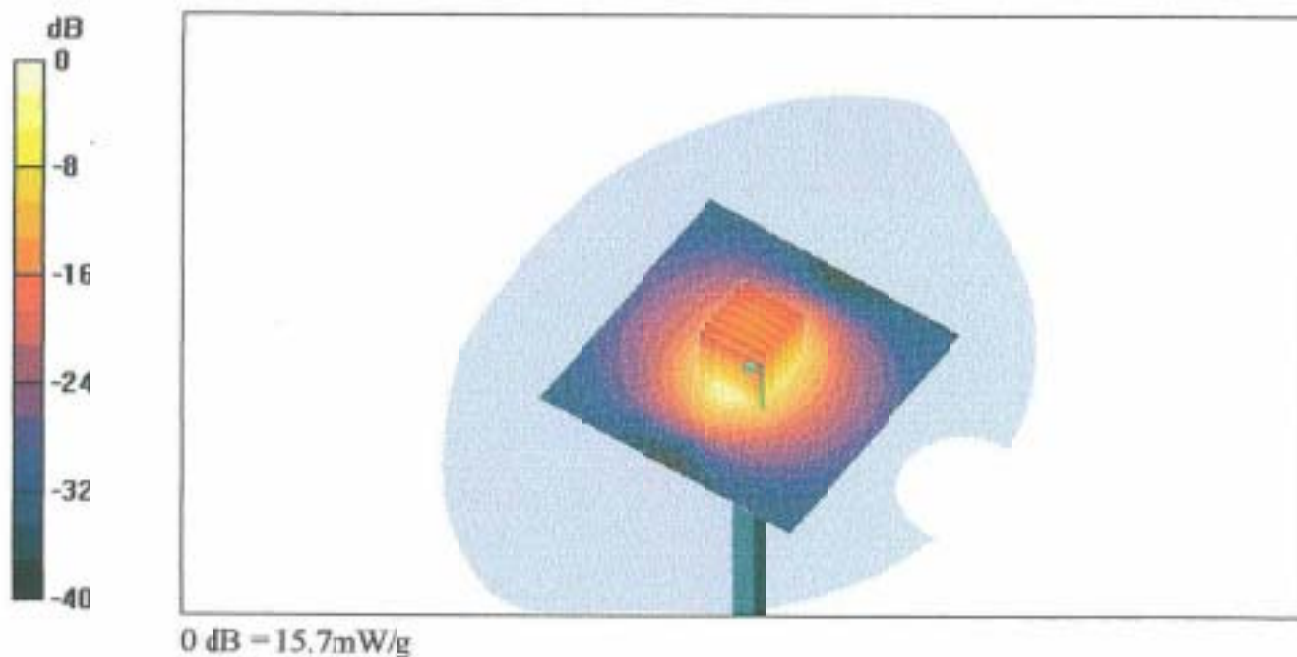
Peak SAR (extrapolated) = 27.3 W/kg

SAR(1 g) = 13.8 mW/g; SAR(10 g) = 6.36 mW/g

Reference Value = 90.4 V/m

Power Drift = -0.03 dB

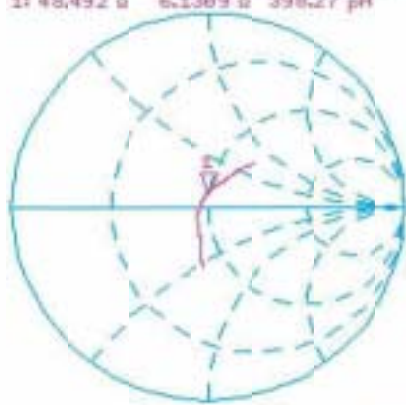
Maximum value of SAR = 15.7 mW/g



737
Body

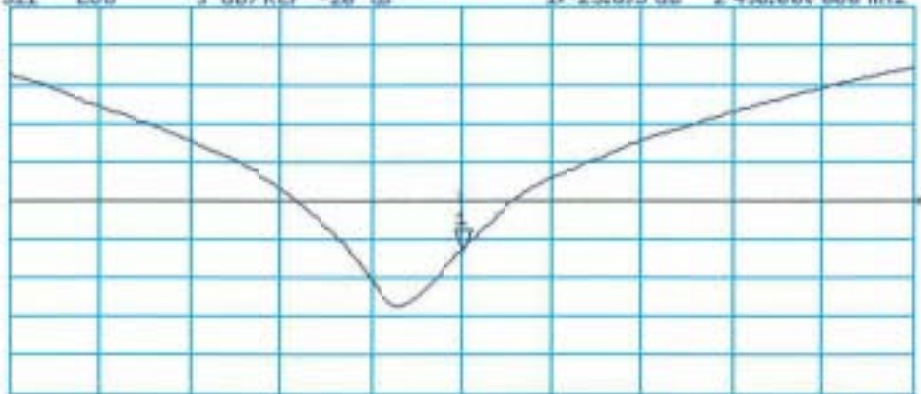
27 Aug 2003 13:31:47
CH1 S11 1 U FS 1: 48.492 ω 6.1389 ω 398.27 μ H 2 450.000 000 MHz

Del
Cor
Avg
15
f



[F2] S11 LOG 3 dB/REF -20 dB 1:-23.855 dB 2 450.000 000 MHz

Cor
f



CENTER 2 450.000 000 MHz SPAN 400.000 000 MHz