

DFS Test Report

Report No.: RF140107C15L-6

FCC ID: JNF-Z-224X

Test Model: Z-2242

Series Model: Z-2240

Received Date: Dec. 26, 2013

Test Date: Aug. 10 ~ Aug. 12, 2015

Issued Date: Dec. 23, 2015

Applicant: ZEBEX INDUSTRIES INC.

Address: B1F.-1, No. 207, Sec. 3, Beixin Rd, Xindian Dist, New Taipei City 23143, Taiwan

Issued By: Bureau Veritas Consumer Products Services (H.K.) Ltd., Taoyuan Branch

Lab Address: No. 47-2, 14th Ling, Chia Pau Vil., Lin Kou Dist., New Taipei City, Taiwan

Test Location: No. 19, Hwa Ya 2nd Rd., Wen Hwa Vil., Kwei Shan Dist., Taoyuan City 33383, TAIWAN (R.O.C.)



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Table of Contents

Release Control Record	3
1 Certificate of Conformity	4
2 EUT Information	5
2.1 Operating Frequency Bands and Mode of EUT	5
2.2 EUT Hardware, Software and Firmware Version	5
2.3 Description Of Available Antennas to The EUT	5
2.4 EUT Maximum Conducted Power	6
2.5 EUT Maximum E.I.R.P. Power	7
2.6 Transmit Power Control (TPC)	8
2.7 Statement of Manufacturer	8
3. U-NII DFS Rule Requirements	9
3.1 Working Modes and Required Test Items	9
3.2 Test Limits And Radar Signal Parameters	10
4. Test & Support Equipment List	12
4.1 Test Instruments	12
4.2 Description of Support Units	12
5. Test Procedure	13
5.1 ADT DFS Measurement System	13
5.2 Calibration of DFS Detection Threshold Level	14
5.3 Deviation From Test Standard	14
5.4 Radiated Test Setup Configuration	15
5.4.1 Client Without Radar Detection Mode	15
6. Test Results	16
6.1 Summary of Test Results	16
6.2 Test Results	17
6.2.1 Test Mode: Device Operating In Client Without Radar Detection Mode	17
6.2.2 Channel Closing Transmission And Channel Move Time	18
6.2.3 Non-Occupancy Period	20
6.2.4 Non-Associated Test	21
6.2.5 Non-Co-Channel Test	21
7. Information on The Testing Laboratories	22



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Release Control Record

Issue No.	Description	Date Issued
RF140107C15L-6	Original release.	Dec. 23, 2015

1 Certificate of Conformity

Product: Rugged Mobile Handheld Computer

Brand: ZEBEX

Test Model: Z-2242

Series Model: Z-2240

Sample Status: MASS-PRODUCTION

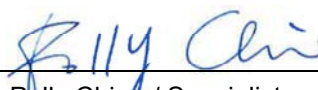
Applicant: ZEBEX INDUSTRIES INC.

Test Date: Aug. 10 ~ Aug. 12, 2015

Standards: FCC Part 15, Subpart E (Section 15.407)

KDB 905462 D03

The above equipment has been tested by **Bureau Veritas Consumer Products Services (H.K.) Ltd., Taoyuan Branch**, and found compliance with the requirement of the above standards. The test record, data evaluation & Equipment Under Test (EUT) configurations represented herein are true and accurate accounts of the measurements of the sample's EMC characteristics under the conditions specified in this report.

Prepared by : , **Date:** Dec. 23, 2015
Polly Chien / Specialist

Approved by : , **Date:** Dec. 23, 2015
Ken Liu / Senior Manager

2 EUT Information

2.1 Operating Frequency Bands and Mode of EUT

TABLE 1: Operating Frequency Bands and Mode of EUT

Operational Mode	Operating Frequency Range	
	5250~5350MHz	5470~5725MHz
Client without radar detection and ad hoc function	✓	✓

*The EUT doesn't operate in 5600 ~ 5650MHz via software controls.

2.2 EUT Hardware, Software and Firmware Version

Table 2: The EUT Hardware/Software/Firmware Version

No.	Product	Model No.	Series Model	Hardware/Software/Firmware Version
1	Rugged Mobile Handheld Computer	Z-2242	Z-2240	Android version: 4.2.2 Kernel version: 3.4.0 askey@askey-System-Product-Name #1 Fri Mar 6 14:52:35 CST 2015 Build number: 20150306.143054 test

NOTE: All brands and models are listed as below. After pretesting, the model of the Z-2242 was worst case and chosen for final test.

Brand	Model	Description
ZEBEX	Z-2242	Barcode scanner
	Z-2240	Non-barcode scanner
		For marketing purpose

2.3 Description Of Available Antennas to The EUT

Table 3: Antenna List

ANT No.	Antenna Type	Operation Frequency Range (MHz)	Max. Gain (dBi)
1	PIFA	5250~5350	3.67
1	PIFA	5470~5725	3.67

2.4 EUT Maximum Conducted Power

Table 4: The Measured Conducted Output Power

802.11a

ANT No.	Frequency Band (MHz)	MAX. Power	
		Output Power(dBm)	Output Power(mW)
1	5250~5350	15.43	34.914
1	5470~5725	17.80	60.256

802.11n HT20

ANT No.	Frequency Band (MHz)	MAX. Power	
		Output Power(dBm)	Output Power(mW)
1	5250~5350	15.64	36.644
1	5470~5725	17.56	57.016

802.11n HT40

ANT No.	Frequency Band (MHz)	MAX. Power	
		Output Power(dBm)	Output Power(mW)
1	5250~5350	15.28	33.729
1	5470~5725	18.52	71.121

2.5 EUT Maximum E.I.R.P. Power

Table 5: The EIRP Output Power List

802.11a

ANT No.	Frequency Band (MHz)	MAX. Power	
		Output Power(dBm)	Output Power(mW)
1	5250~5350	19.10	81.283
1	5470~5725	21.47	140.281

802.11n HT20

ANT No.	Frequency Band (MHz)	MAX. Power	
		Output Power(dBm)	Output Power(mW)
1	5250~5350	19.31	85.31
1	5470~5725	21.23	132.739

802.11n HT40

ANT No.	Frequency Band (MHz)	MAX. Power	
		Output Power(dBm)	Output Power(mW)
1	5250~5350	18.95	78.524
1	5470~5725	22.19	165.577

2.6 Transmit Power Control (TPC)

U-NII devices operating in the 5.25-5.35 GHz band and the 5.47-5.725 GHz band shall employ a TPC mechanism. The U-NII device is required to have the capability to operate at least 6 dB below the mean EIRP value of 30 dBm. A TPC mechanism is not required for systems with an e.i.r.p. of less than 500 mW.

Maximum EIRP of this device is 165.577mW which less than 500mW, therefore it's not require TPC function.

2.7 Statement of Manufacturer

Manufacturer statement confirming that information regarding the parameters of the detected Radar Waveforms is not available to the end user. **And the device doesn't have Ad Hoc mode and Master mode on DFS frequency band.**

3. U-NII DFS Rule Requirements

3.1 Working Modes and Required Test Items

The manufacturer shall state whether the UUT is capable of operating as a Master and/or a Client. If the UUT is capable of operating in more than one operating mode then each operating mode shall be tested separately. See tables 6 and 7 for the applicability of DFS requirements for each of the operational modes.

Table 6: Applicability of DFS Requirements Prior To Use a Channel

Requirement	Operational Mode		
	Master	Client without radar detection	Client with radar detection
Non-Occupancy Period	✓	Not required	✓
DFS Detection Threshold	✓	Not required	✓
Channel Availability Check Time	✓	Not required	Not required
U-NII Detection Bandwidth	✓	Not required	✓

Table 7: Applicability of DFS Requirements During Normal Operation.

Requirement	Operational Mode	
	Master or Client with radar detection	Client without radar detection
DFS Detection Threshold	✓	Not required
Channel Closing Transmission Time	✓	✓
Channel Move Time	✓	✓
U-NII Detection Bandwidth	✓	Not required

Additional requirements for devices with multiple bandwidth modes	Master or Client with radar detection	Client without radar detection
U-NII Detection Bandwidth and Statistical Performance Check	All BW modes must be tested	Not required
Channel Move Time and Channel Closing Transmission Time	Test using widest BW mode available	Test using the widest BW mode available for the link
All other tests	Any single BW mode	Not required

Note: Frequencies selected for statistical performance check (Section 7.8.4) should include several frequencies within the radar detection bandwidth and frequencies near the edge of the radar detection bandwidth. For 802.11 devices it is suggested to select frequencies in all 20 MHz channel blocks and a null frequencies between the bonded 20 MHz channel blocks.

3.2 Test Limits And Radar Signal Parameters

Detection Threshold Values

Table 8: DFS Detection Thresholds For Master Devices And Client Devices With Radar Detection

Maximum Transmit Power	Value (See Notes 1, 2, and 3)
EIRP $\geq$ 200 milliwatt	-64 dBm
EIRP < 200 milliwatt and power spectral density < 10 dBm/MHz	-62 dBm
EIRP < 200 milliwatt that do not meet the power spectral density requirement	-64 dBm

Note 1: This is the level at the input of the receiver assuming a 0 dBi receive antenna.

Note 2: Throughout these test procedures an additional 1 dB has been added to the amplitude of the test transmission waveforms to account for variations in measurement equipment. This will ensure that the test signal is at or above the detection threshold level to trigger a DFS response.

Note3: EIRP is based on the highest antenna gain. For MIMO devices refer to KDB Publication 662911 D01.

Table 9: DFS Response Requirement Values

Parameter	Value
Non-occupancy period	Minimum 30 minutes
Channel Availability Check Time	60 seconds
Channel Move Time	10 seconds See Note 1.
Channel Closing Transmission Time	200 milliseconds + an aggregate of 60 milliseconds over remaining 10 second period. See Notes 1 and 2.
U-NII Detection Bandwidth	Minimum 100% of the U-NII 99% transmission power bandwidth. See Note 3

Note 1: Channel Move Time and the Channel Closing Transmission Time should be performed with Radar Type 0. The measurement timing begins at the end of the Radar Type 0 burst.

Note 2: The Channel Closing Transmission Time is comprised of 200 milliseconds starting at the beginning of the Channel Move Time plus any additional intermittent control signals required to facilitate a Channel move (an aggregate of 60 milliseconds) during the remainder of the 10 second period. The aggregate duration of control signals will not count quiet periods in between transmissions.

Note 3: During the U-NII Detection Bandwidth detection test, radar type 0 should be used. For each frequency step the minimum percentage of detection is 90 percent. Measurements are performed with no data traffic.

Parameters of DFS Test Signals

Step intervals of 0.1 microsecond for Pulse Width, 1 microsecond for PRI, 1 MHz for chirp width and 1 for the number of pulses will be utilized for the random determination of specific test waveforms.

Table 10: Short Pulse Radar Test Waveforms

Radar Type	Pulse Width (μsec)	PRI (μsec)	Number of Pulses	Minimum Percentage of Successful Detection	Minimum Number of Trials
0	1	1428	18	See Note 1	See Note 1
1	1	Test A: 15 unique PRI values randomly selected from the list of 23 PRI values in Table 5a	Roundup $\left\{ \frac{1}{360} \right\} \cdot \left\{ \frac{19 \cdot 10^6}{\text{PRI}_{\mu\text{sec}}} \right\}$	60%	30
		Test B: 15 unique PRI values randomly selected within the range of 518-3066 μsec, with a minimum increment of 1 μsec, excluding PRI values selected in Test A			
2	1-5	150-230	23-29	60%	30
3	6-10	200-500	16-18	60%	30
4	11-20	200-500	12-16	60%	30
Aggregate (Radar Types 1-4)				80%	120
Note 1: Short Pulse Radar Type 0 should be used for the detection bandwidth test, channel move time, and channel closing time tests.					

Table 11: Long Pulse Radar Test Waveform

Radar Type	Pulse Width (μsec)	Chirp Width (MHz)	PRI (μsec)	Number Of Pulses Per Burst	Number Of Bursts	Minimum Percentage Of Successful Detection	Minimum Number Of Trials
5	50-100	5-20	1000-2000	1-3	8-20	80%	30

Table 12: Frequency Hopping Radar Test Waveform

Radar Type	Pulse Width (μsec)	PRI (μsec)	Pulses per Hop	Hopping Rate (kHz)	Hopping Sequence Length (msec)	Minimum Percentage Of Successful Detection	Minimum Number Of Trials
6	1	333	9	0.333	300	70%	30

4. Test & Support Equipment List

4.1 Test Instruments

Table 13: Test Instruments List

Description & Manufacturer	Model No.	Brand	Date Of Calibration	Due Date Of Calibration
R&S Spectrum analyzer	ESR	R&S	2015/01/14	2016/01/13
Signal generator	SMJ100A	R&S	2014/11/21	2015/11/20

4.2 Description of Support Units

Table 14: Support Unit Information.

No.	Product	Brand	Model No.	FCC ID	Spec.
1	Router	D-Link	DIR-868L	RRK2012060056-1	5G Ant gain : 3.428dB Maximum EIRP : 27.64dBm

NOTE: This device was functioned as a ☒ Master ☐ Slave device during the DFS test.

Table 15: Software/Firmware Information.

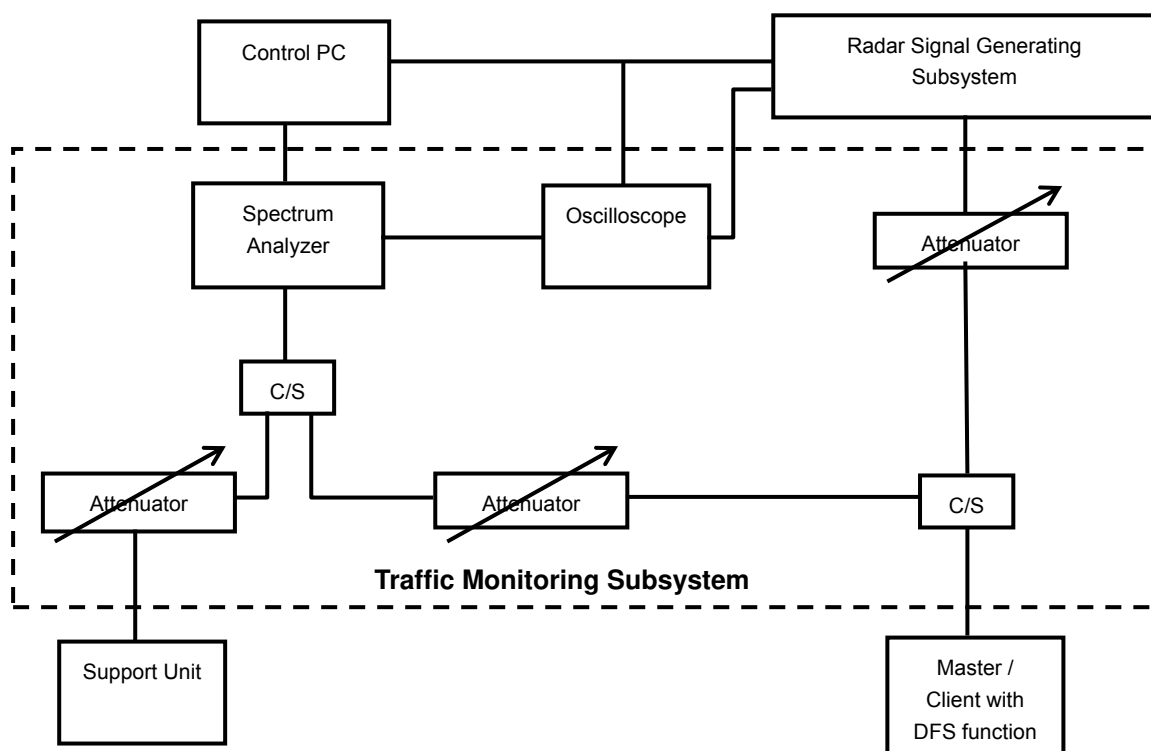
No.	Product	Model No.	Software/Firmware Version
1	Router	DIR-868L	1.00

5. Test Procedure

5.1 ADT DFS Measurement System

A complete ADT DFS Measurement System consists of two subsystems: (1) the Radar Signal Generating Subsystem and (2) the Traffic Monitoring Subsystem. The control PC is necessary for generating the Radar waveforms in Table 10, 11 and 12. The traffic monitoring subsystem is specified to the type of unit under test (UUT).

Conducted Setup Configuration of ADT DFS Measurement System



System testing will be performed with channel-loading using means appropriate to the data types that are used by the unlicensed device. The following requirements apply:

	a) The data file must be of a type that is typical for the device (i.e., MPEG-2, MPEG-4, WAV, MP3, MP4, AVI, etc.) and must generally be transmitting in a streaming mode.
	b) Software to ping the client is permitted to simulate data transfer but must have random ping intervals.
V	c) Timing plots are required with calculations demonstrating a minimum channel loading of approximately 17% or greater.
	d) Unicast or Multicast protocols are preferable but other protocols may be used. The appropriate protocol used must be described in the test procedures.

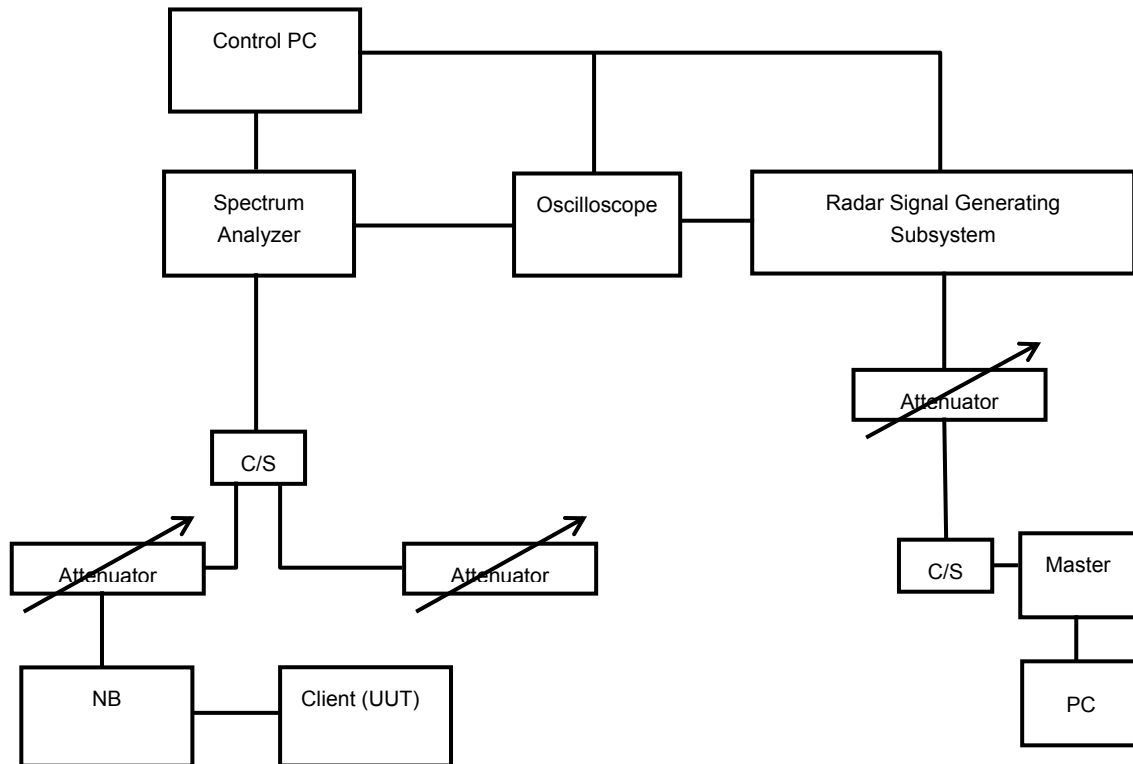
The measured channel is 5500MHz and 5510MHz. The radar signal was the same as transmitted channels, and injected into the antenna of AP (master) or Client Device with Radar Detection, measured the channel closing transmission time and channel move time. The calibrated conducted detection threshold level is set to -64dBm. The tested level is lower than required level hence it provides margin to the limit.

The diagram illustrates the test setup for the radar signal generating subsystem. A Control PC is connected to three main components: a Spectrum Analyzer, an Oscilloscope, and the Radar Signal Generating Subsystem. The Spectrum Analyzer is also connected to the Oscilloscope. The Radar Signal Generating Subsystem is connected to an Attenuator, which is in turn connected to a C/S (Cable Switch) block. This C/S block is connected to another Attenuator, which is connected to a 50Ω Load (Terminator). Additionally, there is a 50Ω Load (Terminator) connected to the Spectrum Analyzer. The diagram shows the flow of signals from the Control PC through the various components to the terminators.

No deviation.

5.4 Radiated Test Setup Configuration

5.4.1 Client Without Radar Detection Mode



6. Test Results

6.1 Summary of Test Results

Clause	Test Parameter	Remarks	Pass/Fail
15.407	DFS Detection Threshold	Not Applicable	NA
15.407	Channel Availability Check Time	Not Applicable	NA
15.407	Channel Move Time	Applicable	Pass
15.407	Channel Closing Transmission Time	Applicable	Pass
15.407	Non- Occupancy Period	Applicable	Pass
15.407	Uniform Spreading	Not Applicable	NA
15.407	U-NII Detection Bandwidth	Not Applicable	NA
15.407	Non-associated test	Applicable	Pass
15.407	Non-Co-Channel test	Applicable	Pass

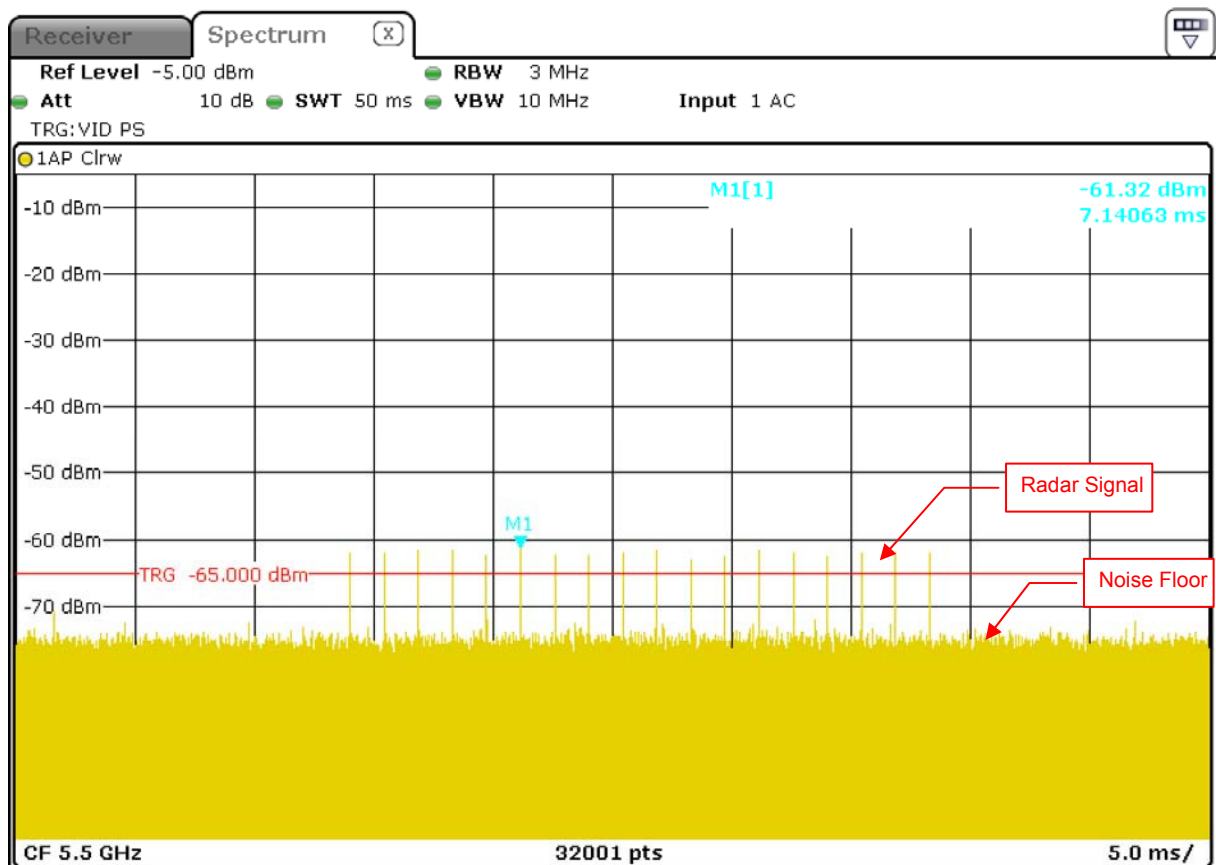
6.2 Test Results

6.2.1 Test Mode: Device Operating In Client Without Radar Detection Mode.

Client with injection at the Master. (The radar test signals are injected into the Master Device)

DFS Detection Threshold

For detection threshold level of -64dBm, the required Radar Signal at antenna port was set to -64dBm + Ant Gain (3.428 dBi) = -60.572dBm. The tested level is lower than required level for 1dB, hence it provides margin to the limit.



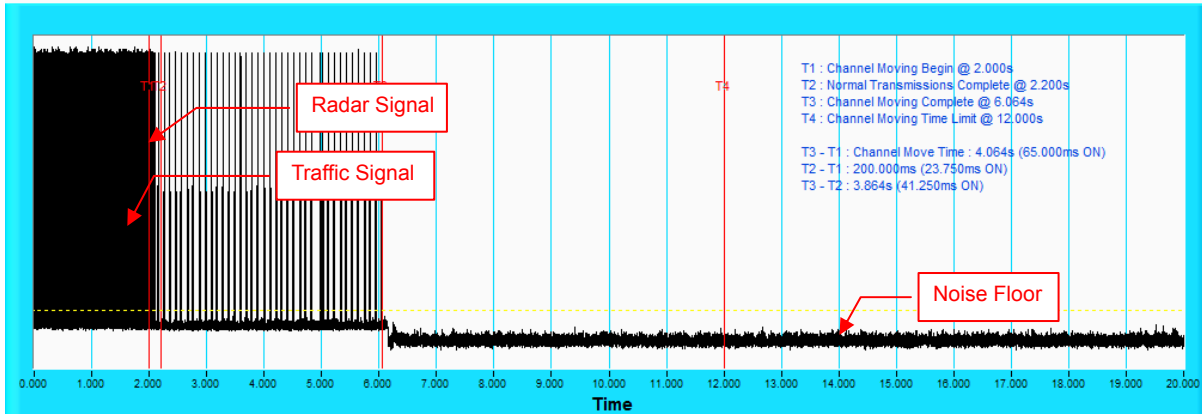
Radar Signal 0

6.2.2 Channel Closing Transmission And Channel Move Time

Radar Signal 0

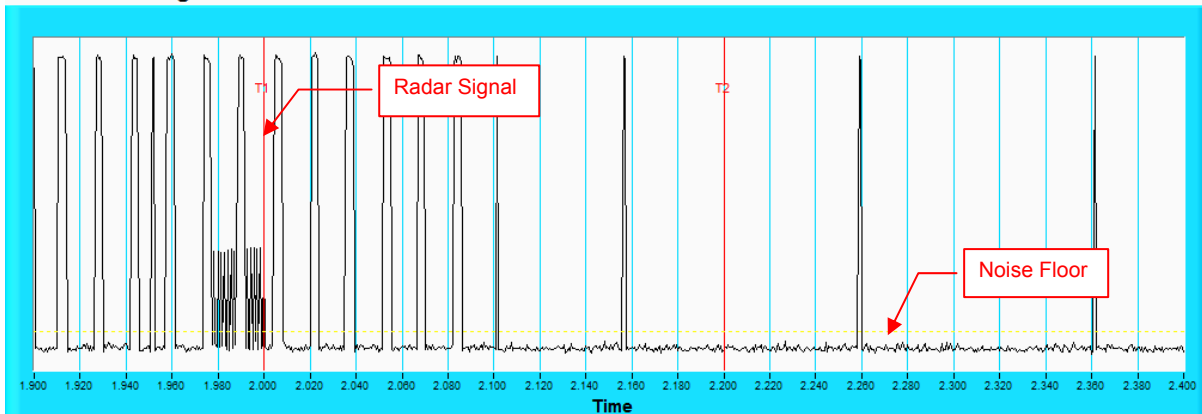
802.11n HT20

Channel Closing Transmission Time & Channel Move Time



NOTE: T1 denotes the start of Channel Move Time upon the end of the last Radar burst. T2 denotes the data transmission time of 200ms from T1. T3 denotes the end of Channel Move Time. T4 denotes the 10 second from T1 to observe the aggregate duration of transmissions.

Channel Closing Transmission Time & Channel Move Time

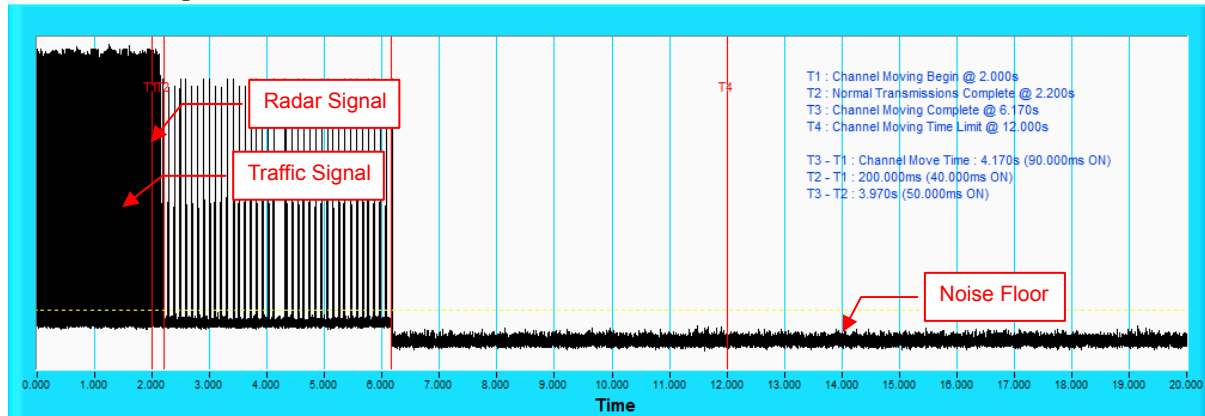


NOTE: An expanded plot for the device vacates the channel in the required 500ms.

Radar Signal 0

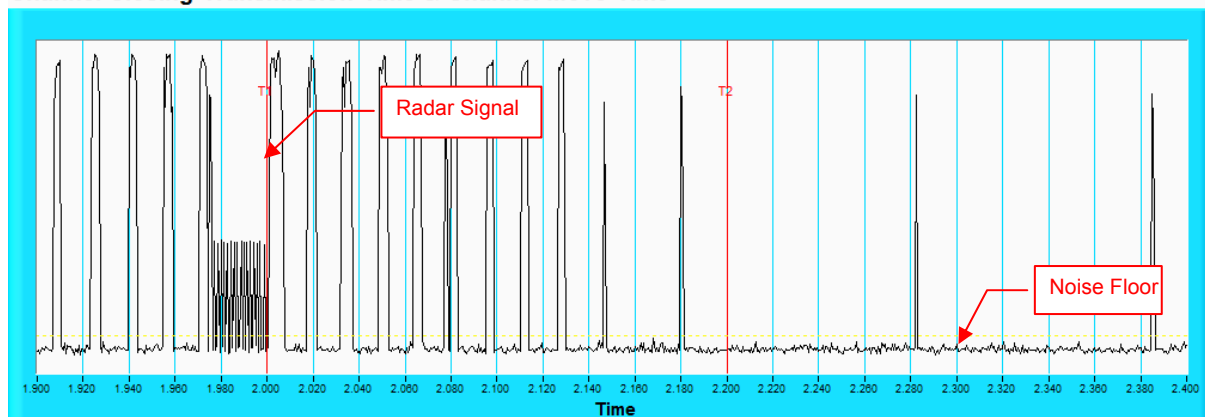
802.11n HT40

Channel Closing Transmission Time & Channel Move Time



NOTE: T1 denotes the start of Channel Move Time upon the end of the last Radar burst. T2 denotes the data transmission time of 200ms from T1. T3 denotes the end of Channel Move Time. T4 denotes the 10 second from T1 to observe the aggregate duration of transmissions.

Channel Closing Transmission Time & Channel Move Time



NOTE: An expanded plot for the device vacates the channel in the required 500ms.

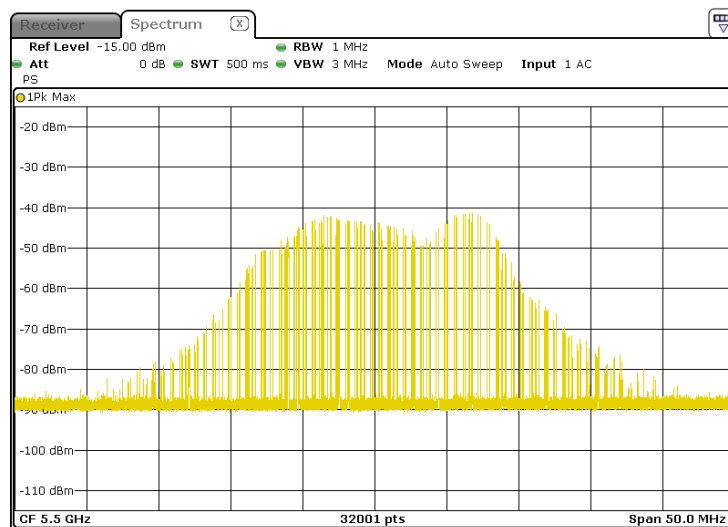
6.2.3 Non-Occupancy Period

Associate test:

During the 30 minutes observation time, UUT did not make any transmissions on a channel after a radar signal was detected on that channel by either the Channel Availability Check or the In-Service Monitoring.

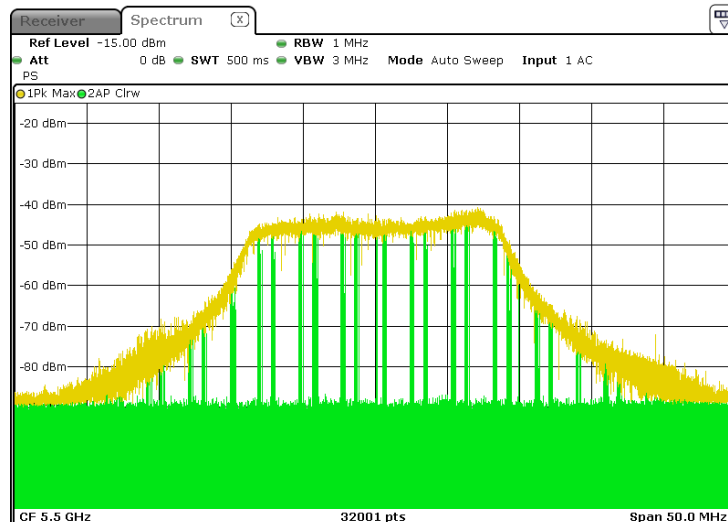
- 1) EUT (Client) links with master on 5500MHz.

Waveform of EUT links up with Master



- 2) Client plays specified files via master.

Waveform of transmission



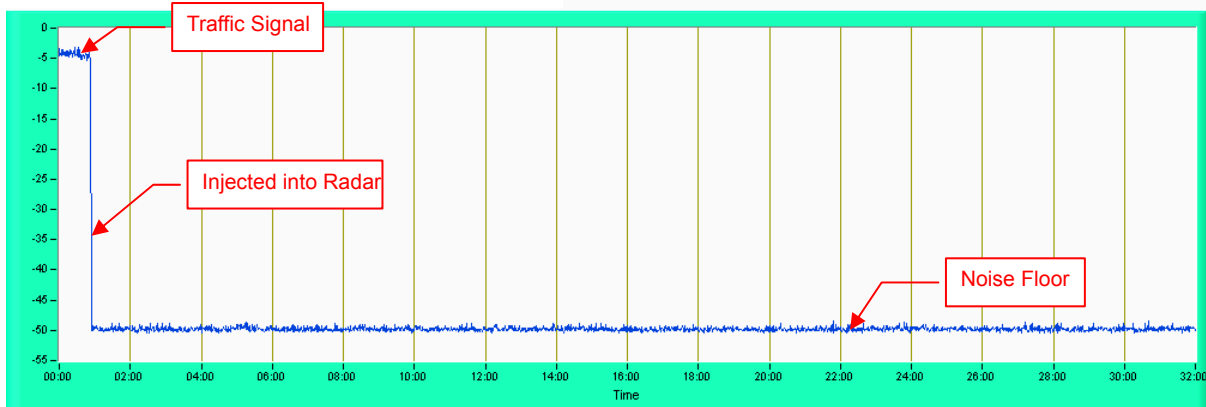
3) Radar signal 0 is applied to the Master device and WiFi traffic signal stop immediately.

Radar signal applied to the master and traffic stopped as described in section 6.2.2.

4) 5500MHz has been monitored in 30 minutes period. In this period, no any transmission occurs.

Plot of 30minutes period

802.11n HT20

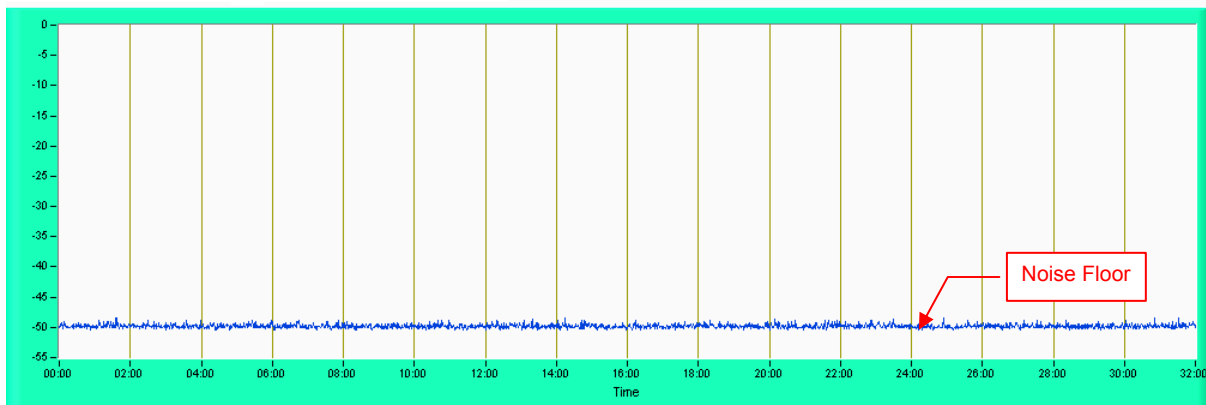


NOTE: Test setup are shown on Test set up photo.pdf

6.2.4 Non-Associated Test

Master was off.

During the 30 minutes observation time, The UUT did not make any transmissions in the DFS band after UUT power up.



6.2.5 Non-Co-Channel Test

The UUT was investigated after radar was detected and confirmed that no co-channel operation with radars.

7. Information on The Testing Laboratories

We, Bureau Veritas Consumer Products Services (H.K.) Ltd., Taoyuan Branch, were founded in 1988 to provide our best service in EMC, Radio, Telecom and Safety consultation. Our laboratories are accredited and approved according to ISO/IEC 17025.

If you have any comments, please feel free to contact us at the following:

Linko EMC/RF Lab:

Tel: 886-2-26052180

Fax: 886-2-26051924

Hsin Chu EMC/RF/Telecom Lab:

Tel: 886-3-6668565

Fax: 886-3-6668323

Hwa Ya EMC/RF/Safety Lab:

Tel: 886-3-3183232

Fax: 886-3-3270892

Email: service.adt@tw.bureauveritas.com

Web Site: www.bureauveritas-adt.com

The address and road map of all our labs can be found in our web site also.

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