

SAR TEST REPORT

Reference No. : WTD24D08202260W005
FCC ID : 2BC9FSP007
Applicant : YIWU HEMAI TECHNOLOGY CO.,LTD
Address : No.39 Suxin Street, Suxi Town, Yiwu City, Zhejiang Province, China
Manufacturer : YIWU HEMAI TECHNOLOGY CO.,LTD
Address : No.39 Suxin Street, Suxi Town, Yiwu City, Zhejiang Province, China
Product : Thermal Printer
Model(s) : POCKET S1, POCKET S2, POCKET S3, POCKET S4, POCKET S5,
POCKET S6, POCKET S7, POCKET S8, POCKET S9, X1, X2,
X3, X4, X5, X6, X7, X8, X9
Standards : FCC 47 CFR Part2(2.1093)
IEEE Std. C95.1-2019
IEC/IEEE 62209-1528:2020
Date of Receipt sample : 2024-08-30
Date of Test : 2024-09-02 to 2024-09-13
Date of Issue : 2024-10-16
Test Result : **Pass**

Remarks:

The results shown in this test report refer only to the sample(s) tested, this test report cannot be reproduced, except in full, without prior written permission of the company. The report would be invalid without specific stamp of test institute and the signatures of compiler and approver.

Prepared By:

Waltek Testing Group Co., Ltd.

Address: No. 77, Houjie Section, Guantai Road, Houjie Town, Dongguan City, Guangdong, China

Tel: +86-769-2267 6998

Fax: +86-769-2267 6828

Compiled by:

Ford Wang

Ford Wang / Project Engineer

Approved by:

Deval



Deval Qin / Designated Reviewer

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3 Revision History

Test Report No.	Date of Receipt Sample	Date of Test	Date of Issue	Purpose	Comment	Approved
WTD24D08202260W005	2024-08-30	2024-09-02 to 2024-09-12	2024-10-16	Original	-	Valid

4 General Information

4.1 General Description of E.U.T.

Product:	Thermal Printer
Model(s):	POCKET S1, POCKET S2, POCKET S3, POCKET S4, POCKET S5, POCKET S6, POCKET S7, POCKET S8, POCKET S9, X1, X2, X3, X4, X5, X6, X7, X8, X9
Model Description:	Only the model names are different. Model POCKET S7 was tested in the report.
Test Sample No.:	1-1/1
Wi-Fi Specification:	2.4G-802.11b/g/n HT20
Bluetooth Version:	V5.0
Hardware Version:	PN82_JL_BWU_V1.0_240322
Software Version:	0.5.1.20240822_BETA

4.2 Details of E.U.T.

Operation Frequency:	2.4G Wi-Fi: 802.11b/g/n HT20: 2412~2462MHz Bluetooth: 2402~2480MHz BLE: 2402~2480MHz
Max. RF output power:	2.4G Wi-Fi: 14.82dBm Bluetooth: 5.88dBm BLE: 4.75dBm
Max.SAR:	0.663W/Kg 1g Body Tissue
Type of Modulation:	2.4G Wi-Fi: CCK, DSSS, OFDM Bluetooth: GFSK, $\pi/4$ QPSK, 8DPSK BLE: GFSK
Antenna installation	2.4G Wi-Fi/Bluetooth/BLE: FPC Antenna
Antenna Gain:	2.4G Wi-Fi/Bluetooth/BLE: 1dBi

Note:

#: The antenna gain is provided by the applicant, and the applicant should be responsible for its authenticity, WALTERK lab has not verified the authenticity of its information.

Ratings:	DC 5V $\overline{\text{---}}$ 3A from adapter DC 7.4V from battery
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4.3 Test Facility

The test facility has a test site registered with the following organizations:

ISED CAB identifier: CN0013. Test Firm Registration No.: 7760A.

Waltek Testing Group Co., Ltd. Has been registered and fully described in a report filed with the Industry Canada. The acceptance letter from the Industry Canada is maintained in our files. Registration number 7760A, October 15, 2016.

FCC Designation No.: CN1201. Test Firm Registration No.: 523476.

Waltek Testing Group Co., Ltd. EMC Laboratory has been registered and fully described in a report filed with the (FCC) Federal Communications Commission. The acceptance letter from the FCC is maintained in our files. Registration number 523476, September 10, 2019.

5 Equipment Used during Test

5.1 Equipment List

Name of Equipment	Manufacturer	Type/Model	Serial Number	Calibration Date	Calibration Due
6 AXIS ROBOT	KUKA	KR6 R900 SIXX	502635	N/A	N/A
SATIMO Test Software	MVG	OPENSAR	OPENSAR V_4_02_27	N/A	N/A
PHANTOM TABLE	MVG	N/A	SAR_1215_01	N/A	N/A
SAM PHANTOM	MVG	SAM118	SN 11/15 SAM118	N/A	N/A
MultiMeter	Keithley	MiltiMeter 2000	4073942	2024-02-25	2025-02-24
S-Parameter Network Analyzer	Agilent	8753E	JP38160684	2023-09-15	2024-09-14
Universal Radio Communication Tester	ROHDE&SCHWARZ	CMU200	114798	2024-07-18	2025-07-17
Wideband Radio Communication Tester	ROHDE&SCHWARZ	CMW500	127818	2024-04-22	2025-04-21
E-Field Probe	MVG	SSE2	2523-EPGO-417	2024-07-29	2025-07-28
DIPOLE 2450	MVG	SID2450	SN 09/15 DIP 2G450-363	2023-08-08	2026-08-07
Limesar Dielectric Probe	MVG	SCLMP	SN 11/15 OCPG 69	2024-02-24	2025-02-23
Power Amplifier	BONN	BLWA 0830 -160/100/40D	128740	2024-07-18	2025-07-17
Signal Generator	R&S	SMB100A	105942	2024-07-18	2025-07-17
Power Meter	R&S	NRP2	102031	2024-07-18	2025-07-17
Power Meter	R&S	NRVD	102284	2024-07-18	2025-07-17
USB Wideband Power Sensor	Malaysia Keysight	U2021XA	MY54340009	2024-07-18	2025-07-17
USB Wideband Power Sensor	Malaysia Keysight	U2021XA	MY54340010	2024-07-18	2025-07-17

6 SAR Introduction

6.1 Introduction

This measurement report shows compliance of the EUT with IEEE Std. C95.1-2019 and FCC 47 CFR Part2 (2.1093). The test procedures, as described in IEC/IEEE 62209-1528:2020 Standard for Measurement procedure for the assessment of specific absorption rate of human exposure to radio frequency fields from hand-held and body-mounted wireless communication devices –Part 1528: Human models, instrumentation, and procedures (Frequency range of 4 MHz to 10 GHz)

6.2 SAR Definition

- SAR : Specific Absorption Rate
- The SAR characterizes the absorption of energy by a quantity of tissue
- This is related to an increase of the temperature of these tissues during a time period.

$$DAS = \frac{d}{dt} \left(\frac{dW}{dm} \right) = \frac{d}{dt} \left(\frac{dW}{\rho dV} \right)$$

$$DAS = \frac{\sigma E^2}{\rho}$$

$$DAS = c_h \left. \frac{dT}{dt} \right|_{t=0}$$

SAR definition

$$SAR = \frac{\sigma E^2}{\rho}$$

- SAR : Specific Absorption Rate

- σ : Liquid conductivity

$$\circ \epsilon_r = \epsilon' - j\epsilon'' \text{ (complex permittivity of liquid)}$$

$$\circ \sigma = \frac{\epsilon'' \omega}{\epsilon_0}$$

- ρ : Liquid density

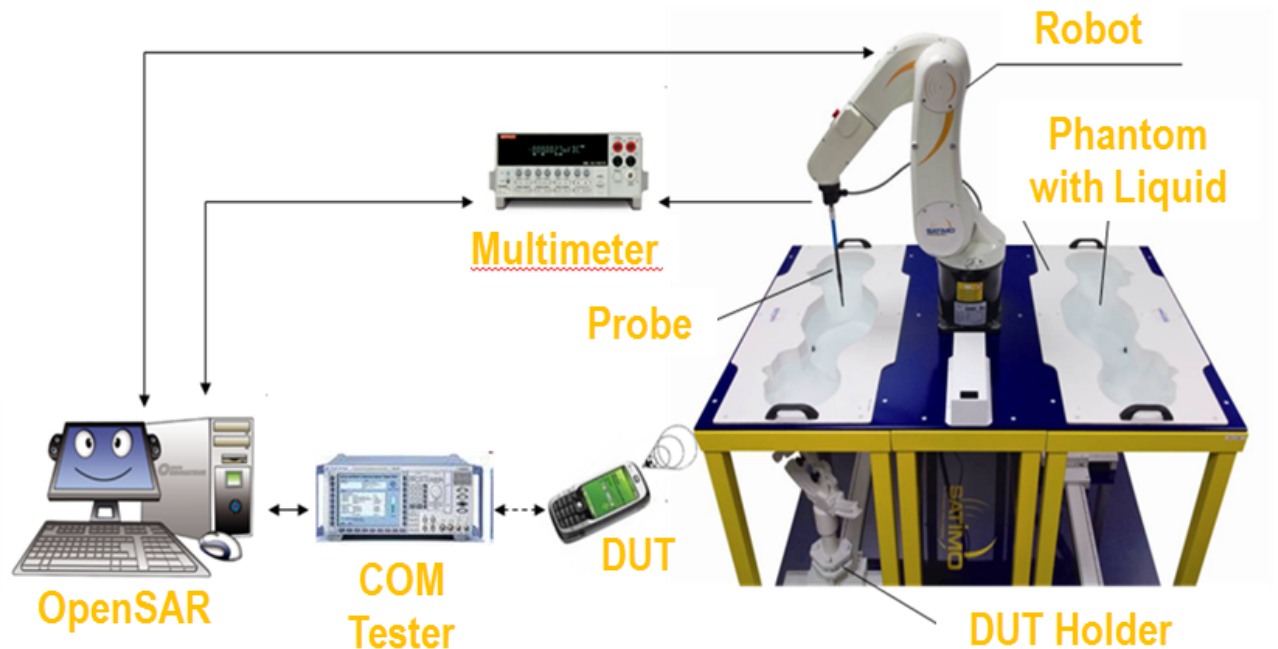
$$\circ \rho = 1000 \text{ g/L} = 1000 \text{ Kg/m}^3$$

where:

σ = conductivity of the tissue (S/m)
 ρ = mass density of the tissue (kg/m³)
 E = rms electric field strength (V/m)

7 SAR Measurement Setup

SAR bench sub-systems



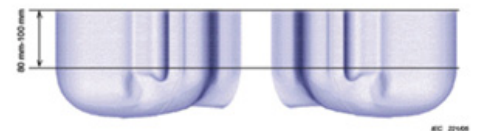
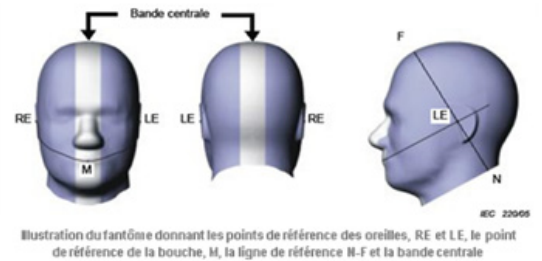
Scanning System (robot)

- ✎ It must be able to scan all the volume of the phantom to evaluate the tridimensional distribution of SAR.
- ✎ Must be able to set the probe orthogonal of the surface of the phantom ($\pm 30^\circ$).
- ✎ Detects stresses on the probe and stop itself if necessary to keep the integrity of the probe.

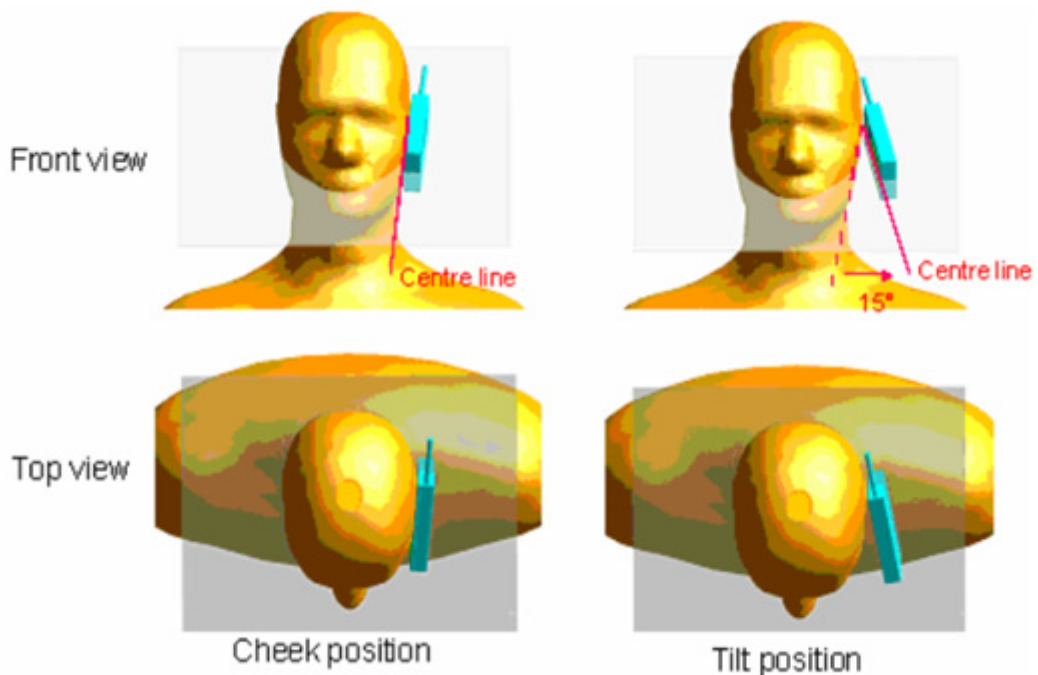


SAM Phantom (Specific Anthropomorphic Mannequin)

- ✎ The probe scanning of the E-Field is done in the 2 half of the normalized head.
- ✎ The normalized shape of the phantom corresponds to the dimensions of 90% of an adult head size.
- ✎ The materials for the phantom should not affect the radiation of the device under test (DUT)
 - Permittivity < 5
- ✎ The head is filled with tissue simulating liquid.
- ✎ The hand holding the DUT does not have to be modeled.



Bi-section sagittale du fantôme avec périmètre étendu (montrée sur le côté comme lors des essais de DAS de l'appareil)



The OPENSAR system for performing compliance tests consist of the following items:

1. A standard high precision 6-axis robot (KUKA) with controller and software.
2. KUKA Control Panel (KCP).
3. A dosimetric probe, i.e., an isotropic E-field probe optimized and calibrated for usage in tissue simulating liquid. The probe is equipped with an optical surface detector system.
4. The functions of the PC plug-in card are to perform the time critical task such as signal filtering, surveillance of the robot operation fast movement interrupts.
5. A computer operating Windows 7.
6. OPENSAR software.
7. Remote control with teaches pendant and additional circuitry for robot safety such as warning lamps, etc.
8. The SAM phantom enabling testing left-hand right-hand and body usage.
9. The Position device for handheld EUT.
10. Tissue simulating liquid mixed according to the given recipes (see Application Note).
11. System validation dipoles to validate the proper functioning of the system.

Data Evaluation

The OPENSAR software automatically executes the following procedure to calculate the field units from the microvolt readings at the probe connector. The parameters used in the valuation are stored in the configuration modules of the software:

Probe Parameters	- Sensitivity	Norm _i
	- Conversion factor	ConvFi
	- Diode compression point Dcpi	
Device Parameter	- Frequency	f
	- Crest factor	cf
Media Parametrs	- Conductivity	σ
	- Density	ρ

These parameters must be set correctly in the software. They can either be found in the component documents or be imported into the software from the configuration files issued for the OPENSAR components.

The first step of the evaluation is a linearization of the filtered input signal to account for the compression characteristics of the detector diode. The compensation depends on the input signal, the diode type and the DC-transmission factor from the diode to the evaluation electronics. If the exciting field is pulsed, the crest factor of the signal must be known to correctly compensate for peak power. The formula for each channel can be given as

$$V_i = U_i + U_i^2 \cdot \frac{cf}{dcp_i}$$

Where V_i = Compensated signal of channel i ($i = x, y, z$)

U_i = Input signal of channel i ($i = x, y, z$)

cf = Crest factor of exciting field (DASY parameter)

dcp_i = Diode compression point (DASY parameter)

From the compensated input signals the primary field data for each channel can be evaluated:

$$\text{E-field probes: } E_i = \sqrt{\frac{V_i}{\text{Norm}_i \cdot \text{ConvF}}}$$

$$\text{H-field probes: } H_i = \sqrt{V_i} \cdot \frac{a_{i0} + a_{i1}f + a_{i2}f^2}{f}$$

Where V_i = Compensated signal of channel i ($i = x, y, z$)

Norm_i = Sensor sensitivity of channel i ($i = x, y, z$)
μV/(V/m)² for E0field Probes

ConvF = Sensitivity enhancement in solution

a_{ij} = Sensor sensitivity factors for H-field probes

$$\begin{aligned}
 f &= \text{Carrier frequency (GHz)} \\
 E_i &= \text{Electric field strength of channel } i \text{ in V/m} \\
 H_i &= \text{Magnetic field strength of channel } i \text{ in A/m}
 \end{aligned}$$

The RSS value of the field components gives the total field strength (Hermitian magnitude):

$$E_{\text{tot}} = \sqrt{E_x^2 + E_y^2 + E_z^2}$$

The primary field data are used to calculate the derived field units.

$$SAR = E_{\text{tot}}^2 \cdot \frac{\sigma}{\rho \cdot 1000}$$

$$\begin{aligned}
 \text{where } SAR &= \text{local specific absorption rate in mW/g} \\
 E_{\text{tot}} &= \text{total field strength in V/m} \\
 \sigma &= \text{conductivity in [mho/m] or [siemens/m]} \\
 \rho &= \text{equivalent tissue density in g/cm}^3
 \end{aligned}$$

Note that the density is normally set to 1 (or 1.06), to account for actual brain density rather than the density of the simulation liquid.

The power flow density is calculated assuming the excitation field as a free space field.

$$P_{\text{pwe}} = \frac{E_{\text{tot}}^2}{3770} \quad \text{or} \quad P_{\text{pwe}} = H_{\text{tot}}^2 \cdot 37.7$$

$$\begin{aligned}
 \text{where } P_{\text{pwe}} &= \text{Equivalent power density of a plane wave in mW/cm}^2 \\
 E_{\text{tot}} &= \text{total electric field strength in V/m} \\
 H_{\text{tot}} &= \text{total magnetic field strength in A/m}
 \end{aligned}$$

SAR Evaluation – Peak Spatial - Average

The procedure for assessing the peak spatial-average SAR value consists of the following steps

- **Power Reference Measurement**

The reference and drift jobs are useful jobs for monitoring the power drift of the device under test in the batch process. Both jobs measure the field at a specified reference position, at a selectable distance from the phantom surface. The reference position can be either the selected section's grid reference point or a user point in this section. The reference job projects the selected point onto the phantom surface, orients the probe perpendicularly to the surface, and approaches the surface using the selected detection method.

- **Area Scan**

The area scan is used as a fast scan in two dimensions to find the area of high field values, before doing a finer measurement around the hot spot. The sophisticated interpolation routines implemented in OPENSAR software can find the maximum locations even in relatively coarse grids. The scan area is defined by an editable grid. This grid is anchored at the grid reference point of the selected section in the phantom.

When the area scan's property sheet is brought-up, grid was at to 15 mm by 15 mm and can be edited by a user.

- **Zoom Scan**

Zoom scans are used to assess the peak spatial SAR values within a cubic averaging volume containing 1 g and 10 g of simulated tissue. The default zoom scan measures 5 x 5 x 7 points within a cube whose base faces are centered around the maximum found in a preceding area scan job within the same procedure. If the preceding Area Scan job indicates more than one maximum, the number of Zoom Scans has to be enlarged accordingly (The default number inserted is 1).

- **Power Drift measurement**

The drift job measures the field at the same location as the most recent reference job within the same procedure, and with the same settings. The drift measurement gives the field difference in dB from the reading conducted within the last reference measurement. Several drift measurements are possible for one reference measurement. This allows a user to monitor the power drift of the device under test within a batch process. In the properties of the Drift job, the user can specify a limit for the drift and have OPENSAR software stop the measurements if this limit is exceeded.

SAR Evaluation – Peak SAR

The procedure for spatial peak SAR evaluation has been implemented according to the IEEE1528 standard. It can be conducted for 1 g and 10 g. The OPENSAR system allows evaluations that combine measured data and robot positions, such as:

- maximum search
- extrapolation
- boundary correction
- peak search for averaged SAR

During a maximum search, global and local maximum searches are automatically performed in 2-D after each Area Scan measurement with at least 6 measurement points. It is based on the evaluation of the local SAR gradient calculated by the Quadratic Shepard's method. The algorithm will find the global maximum and all local maxima within -2 dB of the global maxima for all SAR distributions.

Extrapolation

Extrapolation routines are used to obtain SAR values between the lowest measurement points and the inner phantom surface. The extrapolation distance is determined by the surface detection distance and the probe sensor offset. Several measurements at different distances are necessary for the extrapolation. They are used in the Cube Scan to obtain SAR values between the lowest measurement points and the inner phantom surface. The routine uses the fourth order least square polynomial method for extrapolation. For a grid using 5x5x7 measurement points with 5mm resolution amounting to 343 measurement points, the uncertainty of the extrapolation routines is less than 1% for 1 g and 10 g cubes.

Definition of Reference Points

Ear Reference Point

Figure 6.2 shows the front, back and side views of the SAM Phantom. The point “M” is the reference point for the center of the mouth, “LE” is the left ear reference point (ERP), and “RE” is the right ERP. The ERPs are 15mm posterior to the entrance to the ear canal (EEC) along the B-M line (Back-Mouth), as shown in Figure 6.1. The plane passing through the two ear canals and M is defined as the Reference Plane. The line N-F (Neck-Front) is perpendicular to the reference plane and passing through the RE (or LE) is called the Reference Pivoting Line (see Figure 6.1). Line B-M is perpendicular to the N-F line. Both N-F and B-M lines are marked on the external phantom shell to facilitate handset positioning [5].

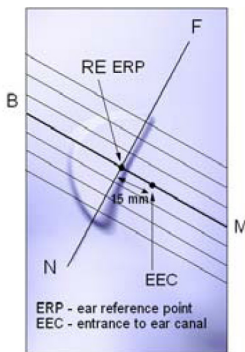


Figure 6.1 Close-up side view of ERP's



Figure 6.2 Front, back and side view of SAM

Device Reference Points

Two imaginary lines on the device need to be established: the vertical centerline and the horizontal line. The test device is placed in a normal operating position with the “test device reference point” located along the “vertical centerline” on the front of the device aligned to the “ear reference point” (See Fig. 6.3). The “test device reference point” is then located at the same level as the center of the ear reference point. The test device is positioned so that the “vertical centerline” is bisecting the front surface of the device at it's top and bottom edges, positioning the “ear reference point” on the outer surface of both the left and right head phantoms on the ear reference point [5].

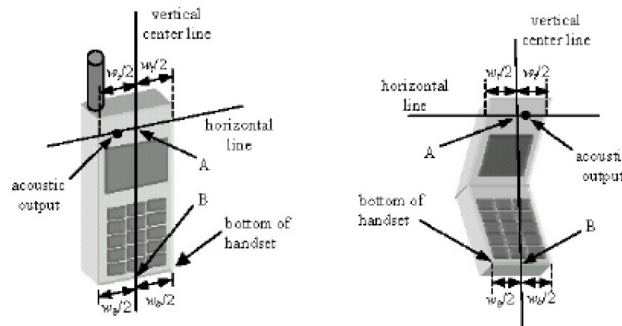


Figure 6.3 Handset Vertical Center & Horizontal Line Reference Points

Test Configuration – Positioning for Cheek / Touch

1. Position the device close to the surface of the phantom such that point A is on the (virtual) extension of the line passing through points RE and LE on the phantom (see Figure below), such that the plane defined by the vertical center line and the horizontal line of the device is approximately parallel to the sagittal plane of the phantom

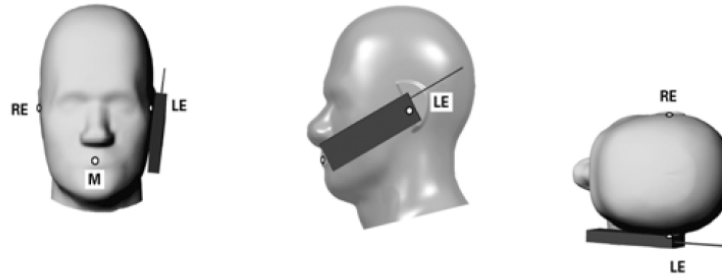


Figure 7.1 Front, Side and Top View of Cheek/Touch Position

2. Translate the device towards the phantom along the line passing through RE and LE until the device touches the ear.
3. While maintaining the device in this plane, rotate it around the LE-RE line until the vertical centerline is in the plane normal to MB-NF including the line MB (called the reference plane).
4. Rotate the device around the vertical centerline until the device (horizontal line) is symmetrical with respect to the line NF.
5. While maintaining the vertical centerline in the reference plane, keeping point A on the line passing through RE and LE and maintaining the device contact with the ear, rotate the device about the line NF until any point on the device is in contact with a phantom point below the ear (cheek). See Figure below.

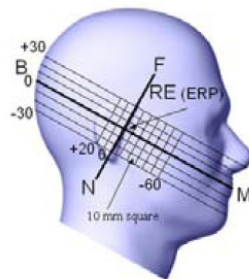


Figure 7.2 Side view w/ relevant markings

Test Configuration – Positioning for Ear / 15° Tilt

With the test device aligned in the Cheek/Touch Position”:

1. While maintaining the orientation of the device, retract the device parallel to the reference plane far enough to enable a rotation of the device by 15 degrees.
2. Rotate the device around the horizontal line by 15 degrees.
3. While maintaining the orientation of the device, move the device parallel to the reference plane until any part of the device touches the head. (In this position, point A is located on the line RE-LE). The tilted position is obtained when the contact is on the pinna. If the contact is at any location other than the pinna, the angle of the device shall be reduced. The tilted position is obtained when any part of the device is in contact with the ear as well as a second part of the device is in contact with the head (see Figure below).

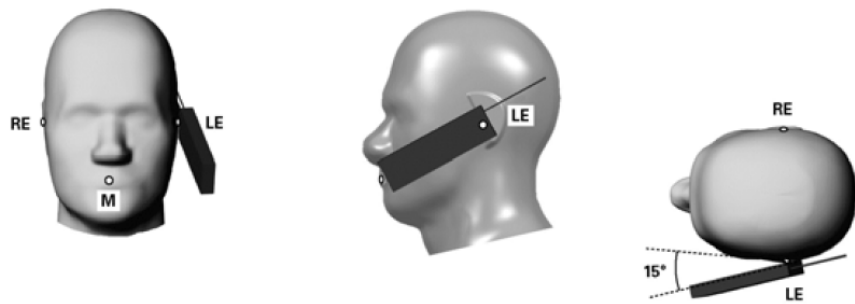
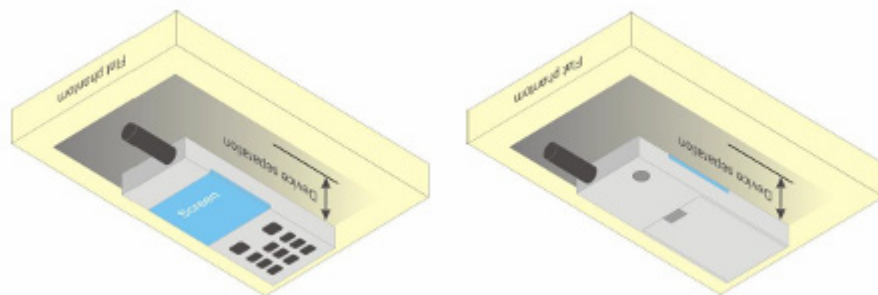


Figure 7.3 Front, Side and Top View of Ear/15° Tilt Position

Test Position – Body Configurations

Body Worn Position

- (a) To position the device parallel to the phantom surface with either keypad up or down.
- (b) To adjust the device parallel to the flat phantom.
- (c) To adjust the distance between the device surface and the flat phantom to 1.0 cm or holster surface and the flat phantom to 0 cm.



8 Exposure limit

In order for users to be aware of the body-worn operating requirements for meeting RF exposure compliance, operating instructions and cautions statements are included in the user's manual.

Uncontrolled Environment

Uncontrolled Environments are defined as locations where there is the exposure of individuals who have no knowledge or control of their exposure. The general population/uncontrolled exposure limits are applicable to situations in which the general public may be exposed or in which persons who are exposed as a consequence of their employment may not be made fully aware of the potential for exposure or cannot exercise control over their exposure. Members of the general public would come under this category when exposure is not employment-related; for example, in the case of a wireless transmitter that exposes persons in its vicinity.

Controlled Environment

Controlled Environments are defined as locations where there is exposure that may be incurred by persons who are aware of the potential for exposure, (i.e. as a result of employment or occupation). In general, occupational/controlled exposure limits are applicable to situations in which persons are exposed as a consequence of their employment, who have been made fully aware of the potential for exposure and can exercise control over their exposure. This exposure category is also applicable when the exposure is of a transient nature due to incidental passage through a location where the exposure levels may be higher than the general population/uncontrolled limits, but the exposed person is fully aware of the potential for exposure and can exercise control over his or her exposure by leaving the area or by some other appropriate means.

Table 8.1 Human Exposure Limits

	UNCONTROLLED ENVIRONMENT General Population (W/kg) or (mW/g)	CONTROLLED ENVIRONMENT Professional Population (W/kg) or (mW/g)
SPATIAL PEAK SAR ¹ Brain	1.60	8.00
SPATIAL AVERAGE SAR ² Whole Body	0.08	0.40
SPATIAL PEAK SAR ³ Hands, Feet, Ankles, Wrists	4.00	20.00

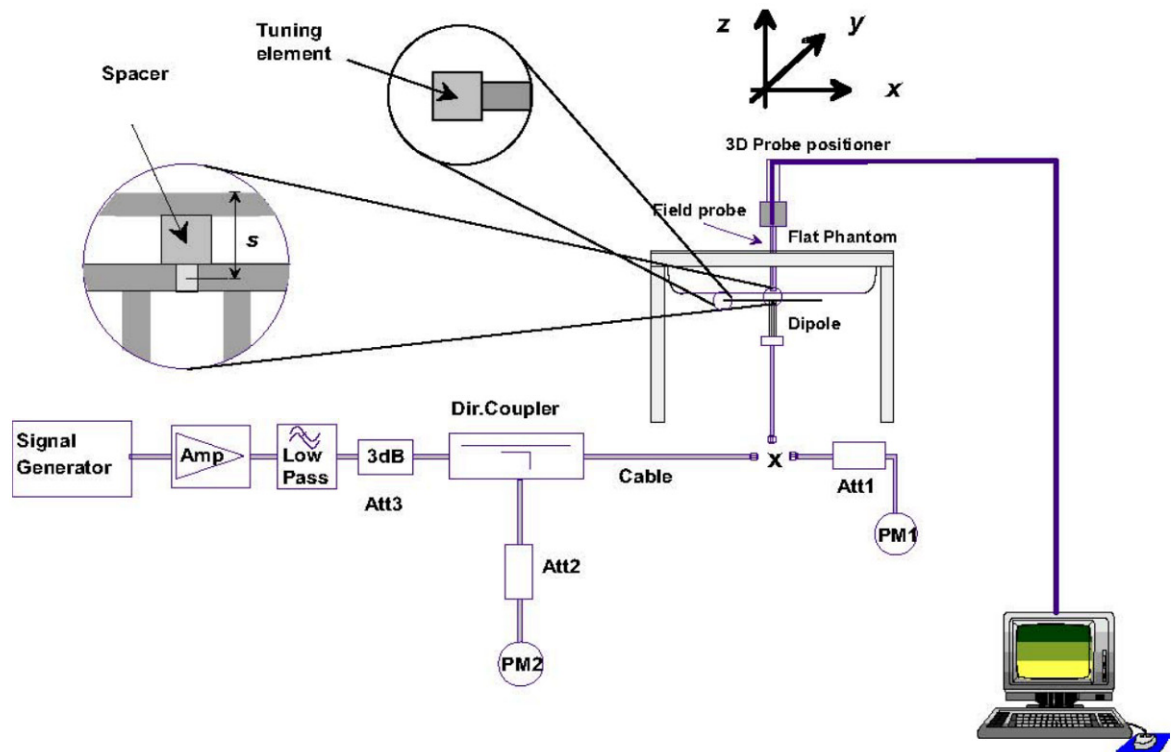
¹ The Spatial Peak value of the SAR averaged over any 1 gram of tissue (defined as a tissue volume in the shape of a cube) and over the appropriate averaging time.

² The Spatial Average value of the SAR averaged over the whole body.

³ The Spatial Peak value of the SAR averaged over any 10 grams of tissue (defined as a tissue volume in the shape of a cube) and over the appropriate averaging time.

9 System and liquid validation

9.1 System validation



Verification Setup Block Diagram



Dipole Antenna Setup Photo

The system performance check verifies that the system operates within its specifications. System and operator errors can be detected and corrected. It is recommended that the system performance check be performed prior to any usage of the system in order to guarantee reproducible results. The system performance check uses normal SAR measurements in a simplified setup with a well characterized source. This setup was selected to give a high sensitivity to all parameters that might fail or vary over time. The system check does not intend to replace the calibration of the components, but indicates situations where the system uncertainty is exceeded due to drift or failure.

In the simplified setup for system evaluation, the DUT is replaced by a calibrated dipole and the power source is replaced by a continuous wave that comes from a signal generator. The calibrated dipole must be placed beneath the flat phantom section of the SAM twin phantom with the correct distance holder. The distance holder should touch the phantom surface with a light pressure at the reference marking and be oriented parallel to the long side of the phantom. The equipment setup is shown below:

1. Signal Generator
2. Amplifier
3. Directional Coupler
4. Power Meter
5. Calibrated Dipole

The output power on dipole port must be calibrated to 30 dBm (1000 mW) before dipole is connected.

Numerical reference SAR values (W/kg) for reference dipole and flat phantom

Frequency (MHz)	1g SAR	10g SAR	Local SAR at surface(above feed-point)	Local SAR at surface(y = 2 cm offset from feedpoint)
300	3.02	2.04	4.40	2.10
450	4.92	3.28	7.20	3.20
750	8.49	5.55	12.6	4.59
835	9.56	6.22	14.1	4.90
900	10.9	6.99	16.4	5.40
1450	29.0	16.0	50.2	6.50
1800	38.4	20.1	69.5	6.80
1900	39.7	20.5	72.1	6.60
2000	41.1	21.1	74.6	6.50
2450	52.4	24.0	104	7.70
2600	55.3	24.6	113	8.29
3000	63.8	25.7	140	9.50

Table 1: system validation (1g)

Measurement Date	Frequency (MHz)	Liquid Type (head/body)	1W Target SAR1g (W/kg)	Measured SAR1g (W/kg)	1W Normalized SAR1g (W/kg)	Desired Tolerance (%)	Actual Tolerance (%)
2024-09-13	2450	head	54.33	5.242	52.42	±10	-3.52

Remark: 1. system check input power: 100mW.
 2. Referring to IEEE 1528:2013, Section 8.2, The system check shall be performed at a test frequency that is within ±10% or ±100 MHz of the compliance test mid-band frequency, so the 1750 MHz system verification is made of 1800MHz Dipole.

9.2 liquid validation

The dielectric parameters were checked prior to assessment using the HP85070C dielectric probe kit. The dielectric parameters measured are reported in each correspondent section.

KDB 865664 recommended Tissue Dielectric Parameters

The head and body tissue parameters given in this below table should be used to measure the SAR of transmitters operating in 100 MHz to 6 GHz frequency range. The tissue dielectric parameters of the tissue medium at the test frequency should be within the tolerance required in this document. The dielectric parameters should be linearly interpolated between the closest pair of target frequencies to determine the applicable dielectric parameters corresponding to the device test frequency.

The head tissue dielectric parameters recommended by IEEE Std 1528-2013 have been incorporated in the following table. These head parameters are derived from planar layer models simulating the highest expected SAR for the dielectric properties and tissue thickness variations in a human head. Other head and body tissue parameters that have not been specified in 1528 are derived from tissue dielectric parameters computed from the 4-Cole-Cole equations described above and extrapolated according to the head parameters specified in 1528.

Target Frequency	Head Tissue		Body Tissue	
MHz	ϵ_r	σ (S/m)	ϵ_r	σ (S/m)
150	52.3	0.76	61.9	0.80
300	45.3	0.87	58.2	0.92
450	43.5	0.87	56.7	0.94
750	41.9	0.89	55.5	0.96
835	41.5	0.90	55.2	0.97
900	41.5	0.97	55.0	1.05
915	41.5	0.98	55.0	1.06
1450	40.5	1.20	54.0	1.30
1610	40.3	1.29	53.8	1.40
1800-2000	40.0	1.40	53.3	1.52
2450	39.2	1.80	52.7	1.95
2600	39.0	1.96	52.5	2.16
3000	38.5	2.40	52.0	2.73
5800	35.3	5.27	48.2	6.00

Tissue Dielectric Parameters for Head and Body Phantoms

The head tissue dielectric parameters recommended by the IEEE SCC-34/SC-2 in P1528 have been incorporated in the following table. These head parameters are derived from planar layer models simulating the highest expected SAR for the dielectric properties and tissue thickness Power drifts in a human head. Other head and body tissue parameters that have not been specified in P1528 are derived from the tissue dielectric parameters computed from the 4-Cole-Cole equations described in Reference [12] and extrapolated according to the head parameters specified in P1528.

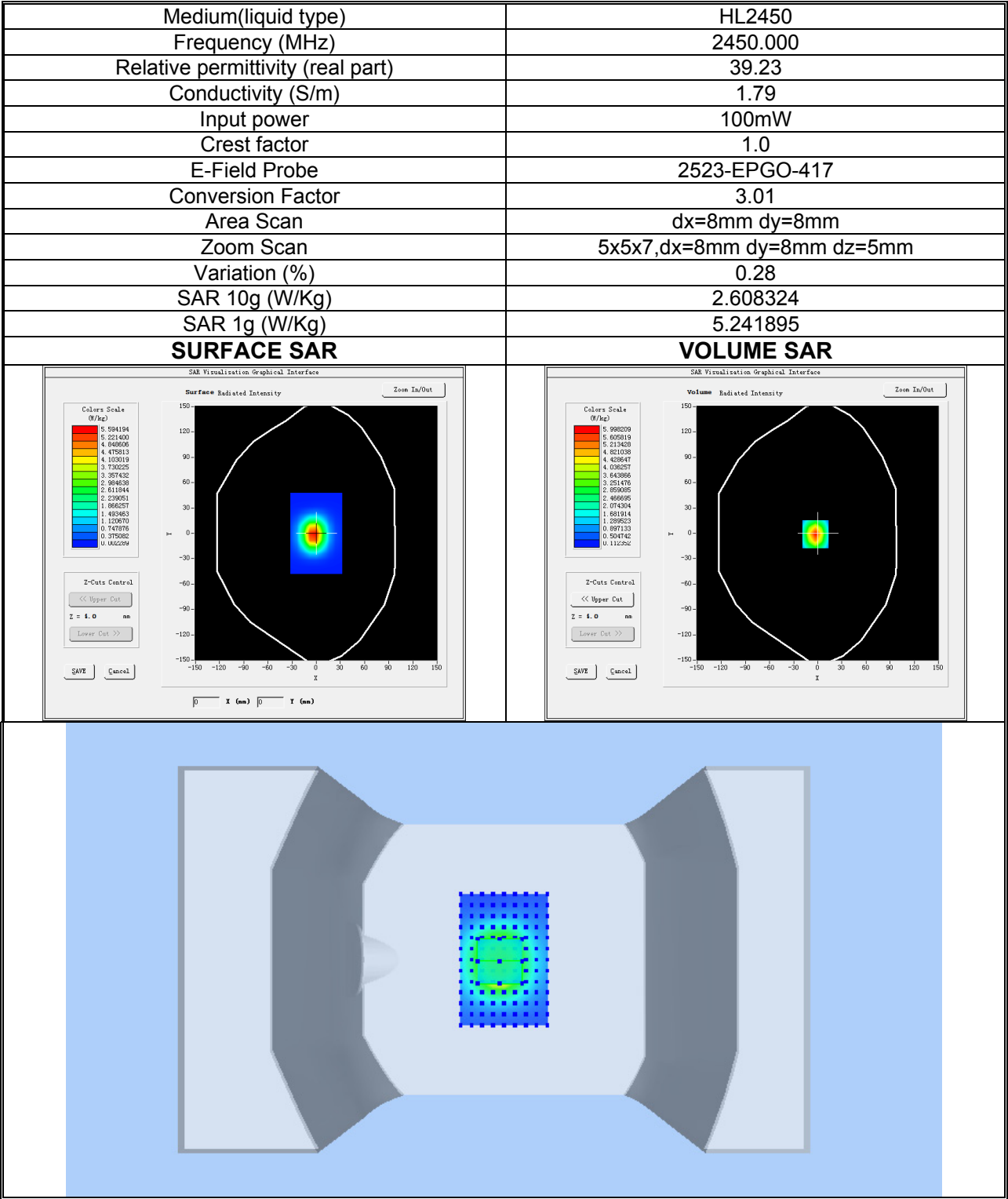
Table 2: Recommended Dielectric Performance of Tissue

Recommended Dielectric Performance of Tissue						
Head/Body						
Ingredients (% by weight)	Frequency (MHz)					
	750	835	1800	1900	2450	2600
Water	40.52	41.45	55.2	54.9	62.7	54.8
Salt (NaCl)	1.61	1.45	0.3	0.18	0.5	0.1
Sugar	57.67	56.0	0.0	0.0	0.0	0.0
HEC	0.1	1.0	0.0	0.0	0.0	0.0
Bactericide	0.1	0.1	0.0	0.0	0.0	0.0
Triton x-100	0.0	0.0	0.0	0.0	36.8	0.0
DGBE	0.0	0.0	44.5	44.92	0.0	45.1
Dielectric	40.93	42.54	40.0	39.9	39.8	39.0
Conductivity	0.87	0.91	1.40	1.42	1.88	1.96

Table 3: Dielectric Performance of Head Tissue Simulating Liquid

Temperature: 24.5°C , Relative humidity: 51%				
Frequency(MHz)	Measured Date	Description	Dielectric Parameters	
			ϵ_r	$\sigma(s/m)$
2450	2023-05-25	Target Value $\pm 5\%$ window	39.2 37.24— 41.16	1.80 1.71 — 1.89
		Measurement Value	39.23	1.79

System Verification Plots
Product Description: Dipole
Model: SID2450
Test Date: 2024-09-13



10 Type a Measurement Uncertainty

The component of uncertainty may generally be categorized according to the methods used to evaluate them. The evaluation of uncertainty by the statistical analysis of a series of observations is termed a Type A evaluation of uncertainty. The evaluation of uncertainty by means other than the statistical analysis of a series of observation is termed a Type B evaluation of uncertainty. Each component of uncertainty, however evaluated, is represented by an estimated standard deviation, termed standard uncertainty, which is determined by the positive square root of the estimated variance

A Type A evaluation of standard uncertainty may be based on any valid statistical method for treating data. This includes calculating the standard deviation of the mean of a series of independent observations; using the method of least squares to fit a curve to the data in order to estimate the parameter of the curve and their standard deviations; or carrying out an analysis of variance in order to identify and quantify random effects in certain kinds of measurement.

A type B evaluation of standard uncertainty is typically based on scientific judgment using all of the relevant information available. These may include previous measurement data, experience and specification, data provided in calibration reports and uncertainties assigned to reference data taken from handbooks. Broadly speaking, the uncertainty is either obtained from an outdoor source or obtained from an assumed distribution, such as the normal distribution, rectangular or triangular distributions indicated in Table below :

Uncertainty Distribution	Normal	Rectangle	Triangular	U Shape
Multi-plying Factor(a)	$1/k(b)$	$1 / \sqrt{3}$	$1 / \sqrt{6}$	$1 / \sqrt{2}$

(a) standard uncertainty is determined as the product of the multiplying factor and the estimated range of variations in the measured quantity

(b) k is the coverage factor

Standard Uncertainty for Assumed Distribution

The combined standard uncertainty of the measurement result represents the estimated standard deviation of the result. It is obtained by combining the individual standard uncertainties of both Type A and Type -sum- by taking the positive square root of the estimated variances.

Expanded uncertainty is a measure of uncertainty that defines an interval about the measurement result within which the measured value is confidently believed to lie. It is obtained by multiplying the combined standard uncertainty by a coverage factor. Typically, the coverage factor ranges from 2 to 3. Using a coverage factor allows the true value of a measured quantity to be specified with a defined probability within the specified uncertainty range. For purpose of this document, a coverage factor two is used, which corresponds to confidence interval of about 95 %.

The COMOSAR Uncertainty Budget is show in below table:

UNCERTAINTY FOR SYSTEM PERFORMANCE CHECK								
a	c	d	e= f(d,k)	f	g	h= c*f/e	i= c*g/e	k
Uncertainty Component	Tol (+-%)	Prob. Dist.	Div.	Ci (1g)	Ci (10g)	1g Ui (+-%)	10g Ui (+-%)	Vi
Measurement System								
Probe calibration	5.8	N	1	1	1	5.80	5.80	∞
Axial Isotropy	3.5	R	$\sqrt{3}$	$(1_{Cp})^{1/2}$	$(1_{Cp})^{1/2}$	1.43	1.43	∞
Hemispherical Isotropy	5.9	R	$\sqrt{3}$	$(Cp)^{1/2}$	$(Cp)^{1/2}$	2.41	2.41	∞
Boundary effect	1.0	R	$\sqrt{3}$	1	1	0.58	0.58	∞
Linearity	4.7	R	$\sqrt{3}$	1	1	2.71	2.71	∞
System detection limits	1.0	R	$\sqrt{3}$	1	1	0.58	0.58	∞
Modulation response	0.00	N	1	1	1	0.00	0.00	∞
Readout Electronics	0.50	N	1	1	1	0.50	0.50	∞
Reponse Time	0.0	R	$\sqrt{3}$	1	1	0.00	0.00	∞
Integration Time	1.4	R	$\sqrt{3}$	1	1	0.81	0.81	∞
RF ambient Conditions - Noise	3.0	R	$\sqrt{3}$	1	1	1.73	1.73	∞
RF ambient Conditions - Reflections	3.0	R	$\sqrt{3}$	1	1	1.73	1.73	∞
Probe positioner Mechanical Tolerance	1.4	R	$\sqrt{3}$	1	1	0.81	0.81	∞
Probe positioning with respect to Phantom Shell	1.40	R	$\sqrt{3}$	1	1	0.81	0.81	∞
Extrapolation, interpolation and integration Algorithms for Max. SAR Evaluation	2.3	R	$\sqrt{3}$	1	1	1.33	1.33	∞
Dipole								
Deviation of experimental source from numerical source	4.00	N	1	1	1	4.00	4.00	∞
Input power and SAR drift measurement	5.00	R	$\sqrt{3}$	1	1	2.89	2.89	∞
Dipole axis to liquid Distance	2.00	R	$\sqrt{3}$	1	1	1.15	1.15	∞
Phantom and Tissue Parameters								
Phantom Uncertainty (Shape and thickness tolerances)	4.00	R	$\sqrt{3}$	1	1	2.31	2.31	∞
Uncertainty in SAR correction for deviation (in permittivity and conductivity)	2.00	N	1	1	1	2.00	1.68	∞
Liquid conductivity (temperature uncertainty)	2.50	N	1	0.78	0.71	1.95	1.77	∞
Liquid conductivity - measurement uncertainty	4.00	N	1	0.23	0.26	0.92	1.04	M
Liquid permittivity (temperature uncertainty)	2.50	N	1	0.78	0.71	1.95	1.77	∞
Liquid permittivity - measurement uncertainty	5.00	N	1	0.23	0.26	1.15	1.30	M
Combined Standard Uncertainty		RSS				10.21	10.12	
Expanded Uncertainty (95% Confidence interval)		k				19.91	19.73	

UNCERTAINTY EVALUATION FOR HANDSET SAR TEST								
a	c	d	e= f(d,k)	f	g	h= c*f/e	i= c*g/e	k
Uncertainty Component	Tol (+-%)	Prob. Dist.	Div.	Ci (1g)	Ci (10g)	1g Ui (+-%)	10g Ui (+-%)	Vi
Measurement System								
Probe calibration	5.8	N	1	1	1	5.80	5.80	∞
Axial Isotropy	3.5	R	$\sqrt{3}$	$(1_{Cp})^{\wedge}_{1/2}$	$(1_{Cp})^{\wedge 1/2}_2$	1.43	1.43	∞
Hemispherical Isotropy	5.9	R	$\sqrt{3}$	$(Cp)^{\wedge}_{1/2}$	$(Cp)^{\wedge}_{1/2}$	2.41	2.41	∞
Boundary effect	1.0	R	$\sqrt{3}$	1	1	0.58	0.58	∞
Linearity	4.7	R	$\sqrt{3}$	1	1	2.71	2.71	∞
System detection limits	1.0	R	$\sqrt{3}$	1	1	0.58	0.58	∞
Modulation response	3.00	N	1	1	1	3.00	3.00	∞
Readout Electronics	0.50	N	1	1	1	0.50	0.50	∞
Reponse Time	0.0	R	$\sqrt{3}$	1	1	0.00	0.00	∞
Integration Time	1.4	R	$\sqrt{3}$	1	1	0.81	0.81	∞
RF ambient Conditions - Noise	3.0	R	$\sqrt{3}$	1	1	1.73	1.73	∞
RF ambient Conditions - Reflections	3.0	R	$\sqrt{3}$	1	1	1.73	1.73	∞
Probe positioner Mechanical Tolerance	1.4	R	$\sqrt{3}$	1	1	0.81	0.81	∞
Probe positioning with respect to Phantom Shell	1.40	R	$\sqrt{3}$	1	1	0.81	0.81	∞
Extrapolation, interpolation and integration Algoritms for Max. SAR Evaluation	2.3	R	$\sqrt{3}$	1	1	1.33	1.33	∞
Test sample Related								
Test sample positioning	2.60	N	1	1	1	2.60	2.60	N-1
Device Holder Uncertainty	3.00	N	1	1	1	3.00	3.00	N-1
Output power Variation - SAR drift measurement	5.00	R	$\sqrt{3}$	1	1	2.89	2.89	∞
SAR scaling	2.00	R	$\sqrt{3}$	1	1	1.15	1.15	∞
Phantom and Tissue Parameters								
Phantom Uncertainty (Shape and thickness tolerances)	4.00	R	$\sqrt{3}$	1	1	2.31	2.31	∞
Uncertainty in SAR correction for deviation (in permittivity and conductivity)	2.00	N	1	1	1	2.00	1.68	∞
Liquid conductivity (temperature uncertainty)	2.50	N	1	0.78	0.71	1.95	1.77	∞
Liquid conductivity - measurement uncertainty	4.00	N	1	0.23	0.26	0.92	1.04	M
Liquid permittivity (temperature uncertainty)	2.50	N	1	0.78	0.71	1.95	1.77	∞
Liquid permittivity - measurement uncertainty	5.00	N	1	0.23	0.26	1.15	1.30	M
Combined Standard Uncertainty		RSS				10.63	10.54	
Expanded Uncertainty (95% Confidence interval)		k				20.73	20.56	

11 Output Power Verification

11.1 Test Condition

1. Conducted Measurement
EUT was set for low, mid, high channel with modulated mode and highest RF output power.
The base station simulator was connected to the antenna terminal.
2. Conducted Emissions Measurement Uncertainty
All test measurements carried out are traceable to national standards. The uncertainty of the measurement at a confidence level of approximately 95% (in the case where distributions are normal), with a coverage factor of 2, in the range 30MHz – 40GHz is $\pm 1.5\text{dB}$.
3. Environmental Conditions

Temperature	25.5°C
Relative Humidity	56%
Atmospheric Pressure	1011mbar

11.2 Test Result

Bluetooth Measurement Result

Mode	Frequency (MHz)	Average Output Power(dBm)	Tune up limited(dBm)
GFSK	2402	4.50	5.0 $\pm$ 1
	2441	4.36	5.0 $\pm$ 1
	2480	4.38	5.0 $\pm$ 1
$\pi/4$ DQPSK	2402	5.49	5.0 $\pm$ 1
	2441	5.38	5.0 $\pm$ 1
	2480	5.21	5.0 $\pm$ 1
8DPSK	2402	5.88	5.0 $\pm$ 1
	2441	5.75	5.0 $\pm$ 1
	2480	5.55	5.0 $\pm$ 1

BLE Measurement Result

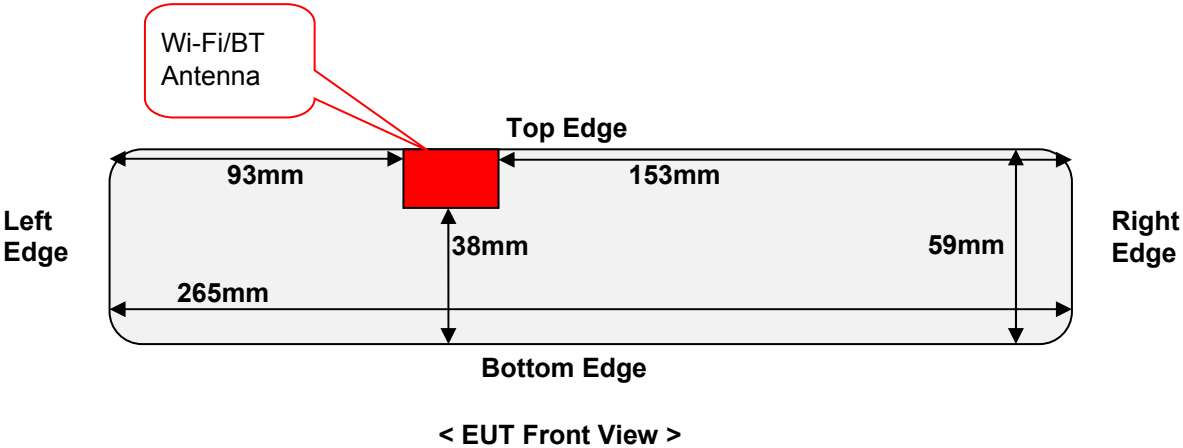
Mode	Channel number	Frequency (MHz)	Average Output Power(dBm)	Tune up limited(dBm)
GFSK(1M)	0	2402	4.51	4.0 $\pm$ 1
	19	2440	4.27	4.0 $\pm$ 1
	39	2480	4.13	4.0 $\pm$ 1
GFSK(1M)	0	2402	4.75	4.0 $\pm$ 1
	19	2440	4.64	4.0 $\pm$ 1
	39	2480	4.61	4.0 $\pm$ 1

2.4G Wi-Fi Measurement Result

Channel number	Frequency (MHz)	Average Output Power(dBm)	Tune up limited(dBm)
TX 11b	2412	14.73	14.0±1
	2437	14.73	14.0±1
	2462	14.82	14.0±1
TX 11g	2412	12.85	12.0±1
	2437	12.90	12.0±1
	2462	12.94	12.0±1
TX 11n HT20	2412	13.06	13.0±1
	2437	12.95	13.0±1
	2462	13.10	13.0±1

12 Exposure Conditions Consideration

12.1 EUT antenna location



12.2 Test position consideration

Distance of EUT antenna-to-edge/surface(mm)						
Antennas	Back side	Front side	Left Edge	Right Edge	Top Edge	Bottom Edge
WLAN	<25	<25	93	153	<25	38
Test distance:0mm						
Antennas	Back side	Front side	Left Edge	Right Edge	Top Edge	Bottom Edge
WLAN	YES	YES	NO	NO	YES	NO

- Note:
1. Body SAR mode assessments are required.
 2. Per KDB 447498 D01v06, for handsets the test separation distance is determined by the smallest distance between the outer surface of the device and the user, which is 0 mm for body SAR.

12.3 RF Exposure

Standard Requirement:

According to §15.247 (i) and §1.1307(b)(1), systems operating under the provisions of this section shall be operated in a manner that ensures that the public is not exposed to radio frequency energy level in excess of the Commission's guidelines.

The 1-g and 10-g SAR test exclusion thresholds for 100 MHz to 6 GHz at *test separation distances* ≤ 50 mm are determined by:

$[(\text{max. power of channel, including tune-up tolerance, mW}) / (\text{min. test separation distance, mm})] \cdot [\sqrt{f_{\text{(GHz)}}}] \leq 3.0$ for 1-g SAR and ≤ 7.5 for 10-g extremity SAR,¹⁶ where

- $f_{\text{(GHz)}}$ is the RF channel transmit frequency in GHz
- Power and distance are rounded to the nearest mW and mm before calculation¹⁷
- The result is rounded to one decimal place for comparison

The test exclusions are applicable only when the minimum *test separation distance* is ≤ 50 mm and for transmission frequencies between 100 MHz and 6 GHz. When the minimum *test separation distance* is < 5 mm, a distance of 5 mm is applied to determine SAR test exclusion.

Routine SAR evaluation refers to that specifically required by § 2.1093, using measurements or computer simulation. When routine SAR evaluation is not required, portable transmitters with output power greater than the applicable low threshold require SAR evaluation to qualify for TCB approval.

Exclusion Thresholds = $P\sqrt{F} / D$

P= Maximum turn-up power in mW

F= Channel frequency in GHz

D= Minimum test separation distance in mm

Test Distance (5mm)

Mode	MAX Power (dBm)	Tune Up Power (dBm)	Max Tune Up Power (dBm)	Max Tune Up Power (mW)	Exclusion Thresholds	Limit
Bluetooth	5.88	5.0±1	6	3.98	1.244	3
BLE	4.75	4.0±1	5	3.16	0.988	3
2.4G Wi-Fi	14.82	14.0±1	15	31.62	9.873	3

13 SAR Test Results

13.1 Test Condition

1. SAR Measurement
The distance between the EUT and the antenna of the emulator is more than 50 cm and the output power radiated from the emulator antenna is at least 30 dB less than the output power of EUT.
2. Environmental Conditions

Temperature	24.5°C
Relative Humidity	51%
Atmospheric Pressure	1013mbar

13.2 Generally Test Procedures

1. Establish communication link between EUT and base station emulation by air link.
2. Place the EUT in the selected test position. (Cheek, tilt or flat)
3. Perform SAR testing at middle or highest output power channel under the selected test mode. If the measured 1-g SAR is ≤ 0.8 W/kg, then testing for the other channel will not be performed.
4. When SAR is < 0.8 W/kg, no repeated SAR measurement is required

13.3 SAR Summary Test Result

Table 4: SAR Values of 2.4G Wi-Fi

Test Positions		Channel		Test Mode	Power(dBm)		SAR 1g(W/Kg), Limit(1.6W/kg)			Plot No.
		CH.	MHz		Maximum Turn-up Power (dBm)	Measured output power (dBm)	Scaling Factor	Measured SAR 1g(W/kg)	Scaled SAR 1g(W/kg)	
Body (0mm Separation)	Front Side	11	2462	802.11b	15	14.82	1.042	0.255	0.266	1
	Back Side	11	2462	802.11b	15	14.82	1.042	0.349	0.364	2
	Top Edge	11	2462	802.11b	15	14.82	1.042	0.636	0.663	3

Measurement variability consideration

According to KDB 865664 D01v01r04 section 2.8.1, repeated measurements are required following the procedures as below:

Repeated measurement is not required when the original highest measured SAR is $< 0.80 \text{ W/kg}$; steps 2) through 4) do not apply.

When the original highest measured SAR is $\geq 0.80 \text{ W/kg}$, repeat that measurement once.

Perform a second repeated measurement only if the ratio of largest to smallest SAR for the original and first repeated measurements is > 1.20 or when the original or repeated measurement is $\geq 1.45 \text{ W/kg}$ (~ 10% from the 1-g SAR limit).

Perform a third repeated measurement only if the original, first or second repeated measurement is $\geq 1.5 \text{ W/kg}$ and the ratio of largest to smallest SAR for the original, first and second repeated measurements is > 1.20 .

No Repeated SAR.**Simultaneous Transmission SAR Analysis.**

Note: No Simultaneous Transmission SAR.

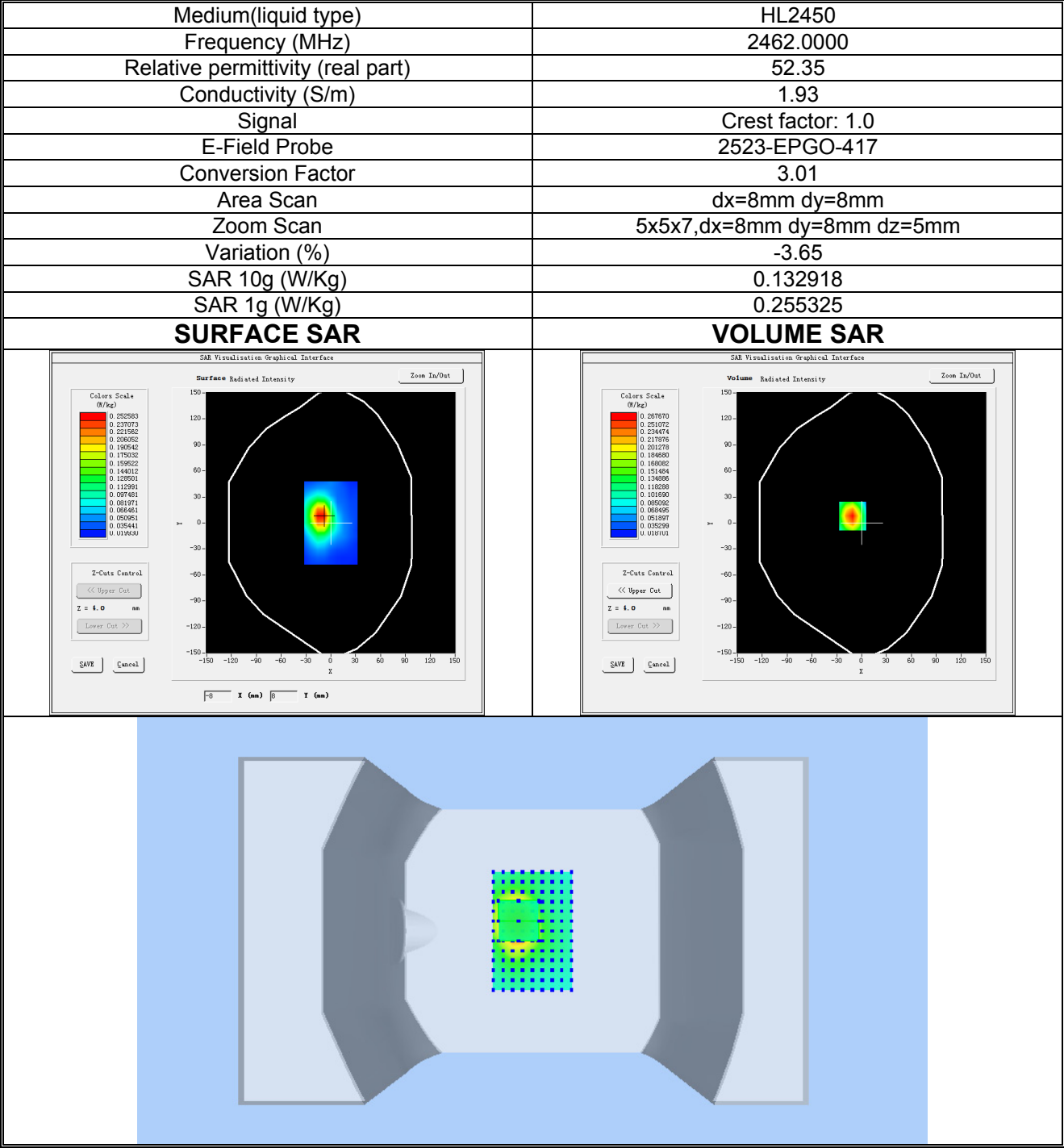
14 SAR Measurement Reference

14.1 References

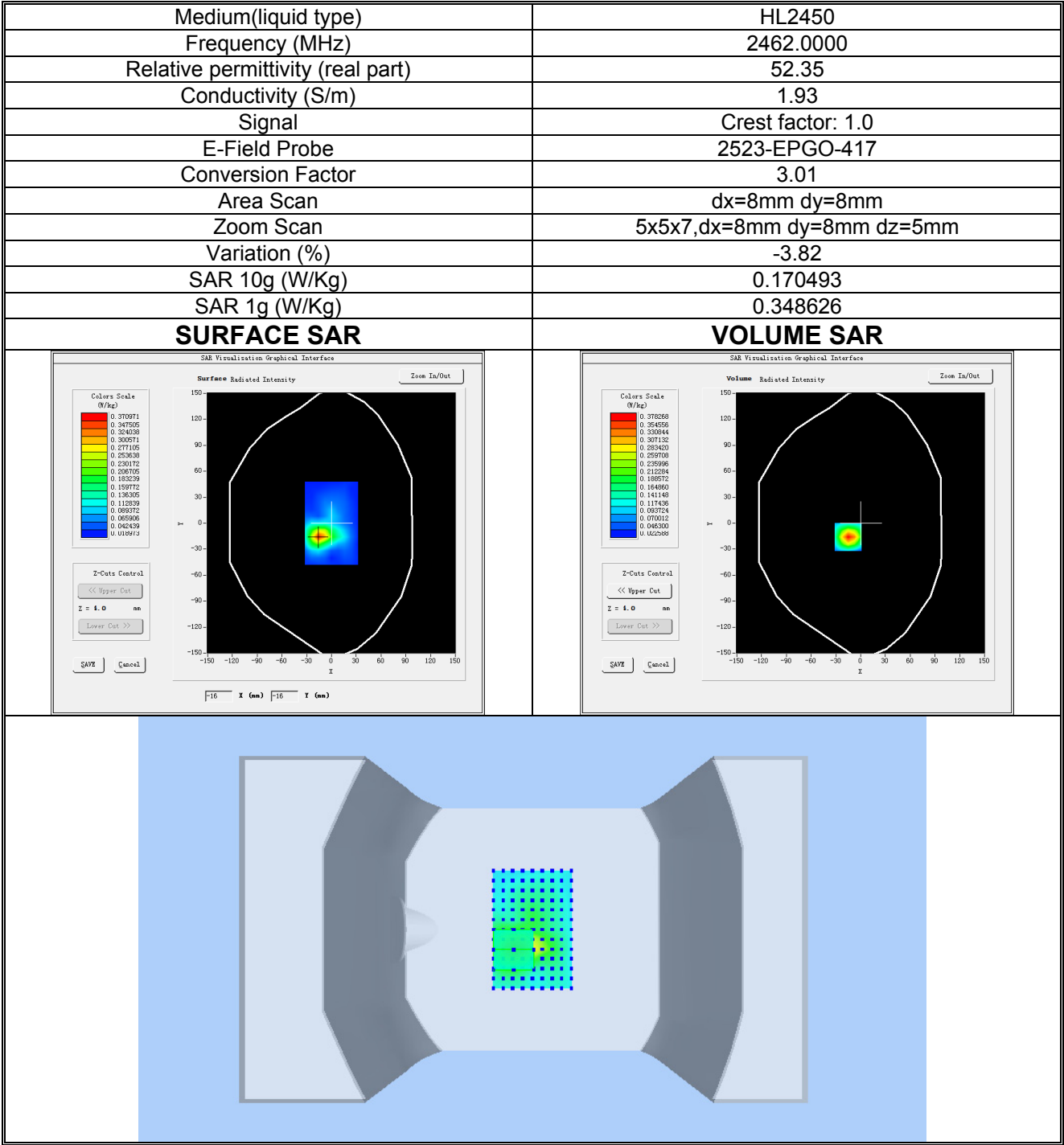
- 1. FCC 47 CFR Part 2 “Frequency Allocations and Radio Treaty Matters; General Rules and Regulations”**
- 2. IEEE Std. C95.1-2019, “IEEE Standards for Safety Levels with Respect to Human Exposure to Electric, Magnetic, and Electromagnetic Fields, 0 Hz to 300 GHz”**
- 3. IEC/IEEE 62209-1528:2020, Measurement procedure for the assessment of specific absorption rate of human exposure to radio frequency fields from hand-held and body-mounted wireless communication devices Part 1528: Human models, instrumentation, and procedures (Frequency range 4 MHz to 10 GHz)**
- 4. FCC KDB447498 D01v06, “RF exposure requirements for mobile and portable device equipment authorizations”**
- 5. FCC KDB865664 D01 v01r04, “SAR measurement procedures for devices operating between 100 MHz to 6 GHz”**
- 6. FCC KDB865664 D02 v01r02, “RF Exposure Compliance Reporting and Documentation Considerations ”**
- 7. FCC KDB248227 D01 v02r02, “SAR measurements for devices incorporating IEEE 802.11 wireless transmitters”**

14.2Maximum SAR measurement Plots

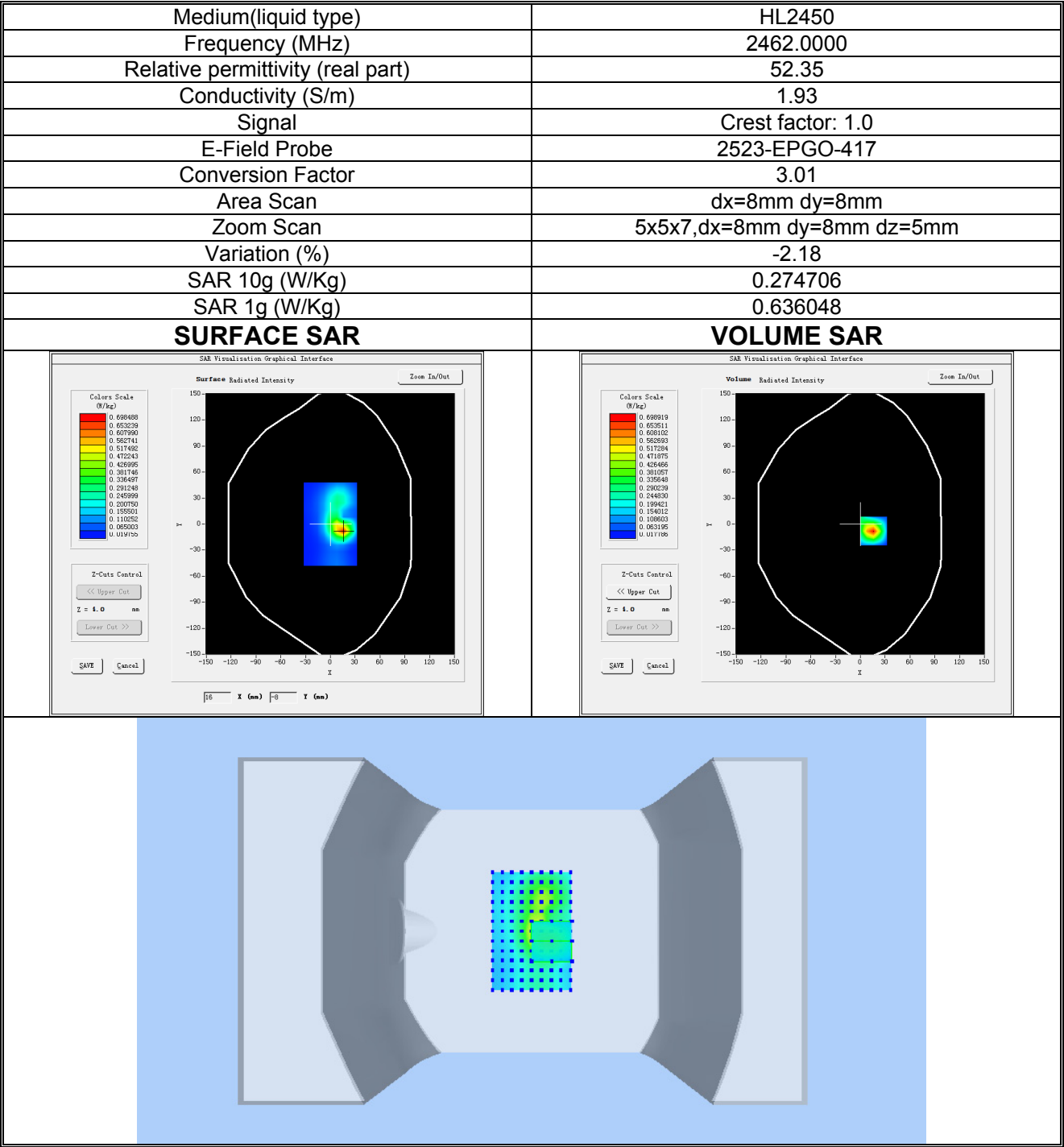
Plot 1: 2.4G Wi-Fi, High channel (Body SAR, Front Side)
Product Description: Thermal Printer
Test Date: 2024-09-13



Plot 2: 2.4G Wi-Fi, High channel (Body SAR, Back Side)
Product Description: Thermal Printer
Test Date: 2024-09-13



Plot 3: 2.4G Wi-Fi, High channel (Body SAR, Top Edge)
Product Description: Thermal Printer
Test Date: 2024-09-13



15 Calibration Reports-Probe and Dipole



COMOSAR E-Field Probe Calibration Report

Ref : ACR.208.13.24.BES.A

WALTEK TESTING GROUP CO., LTD
NO,77, HOUJIE SECTION, GUANTAI ROAD, HOUJIE TOWN
DONGGUAN GUANGDONG 518105, CHINA
MVG COMOSAR DOSIMETRIC E-FIELD PROBE
SERIAL NO.: 2523-EPGO-417

Calibrated at MVG

Z.I. de la pointe du diable

Technopôle Brest Iroise – 295 avenue Alexis de Rochon

29280 PLOUZANE - FRANCE

Calibration date: 07/29/2024



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Scope available on www.cofrac.fr

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Summary:

This document presents the method and results from an accredited COMOSAR Dosimetric E-Field Probe calibration performed at MVG, using the CALIPROBE test bench, for use with a MVG COMOSAR system only. The test results covered by accreditation are traceable to the International System of Units (SI).

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COMOSAR E-FIELD PROBE CALIBRATION REPORT

Ref: ACR.208.13.24.BES.A

	Name	Function	Date	Signature
Prepared by :	Cyrille ONNEE	Measurement Responsible	7/29/2024	
Checked & approved by:	Jérôme Luc	Technical Manager	7/29/2024	
Authorized by:	Yann Toutain	Laboratory Director	7/29/2024	

Yann
Toutain ID

Signature
numérique de
Yann Toutain ID
Date : 2024.07.29
10:49:25 +01'00'

	Customer Name
Distribution :	WALTEK TESTING GROUP CO., LTD

Issue	Name	Date	Modifications
A	Cyrille ONNEE	7/29/2024	Initial release



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COMOSAR E-FIELD PROBE CALIBRATION REPORT

Ref: ACR.208.13.24.BES.A

1 DEVICE UNDER TEST

Device Under Test	
Device Type	COMOSAR DOSIMETRIC E FIELD PROBE
Manufacturer	MVG
Model	SSE2
Serial Number	2523-EPGO-417
Product Condition (new / used)	New
Frequency Range of Probe	0.15 GHz-7.5GHz
Resistance of Three Dipoles at Connector	Dipole 1: R1=0.231 MΩ Dipole 2: R2=0.220 MΩ Dipole 3: R3=0.206 MΩ

2 PRODUCT DESCRIPTION**2.1 GENERAL INFORMATION**

MVG's COMOSAR E field Probes are built in accordance to the IEC/IEEE 62209-1528 and FCC KDB865664 D01 standards.



Figure 1 – MVG COMOSAR Dosimetric E field Probe

Probe Length	330 mm
Length of Individual Dipoles	24.5 mm
Maximum external diameter	8 mm
Probe Tip External Diameter	2.55 mm
Distance between dipoles / probe extremity	12.7 mm

3 MEASUREMENT METHOD

The IEC/IEEE 62209-1528 and FCC KDB865664 D01 standards provide recommended practices for the probe calibrations, including the performance characteristics of interest and methods by which to assess their effect. All calibrations / measurements performed meet the fore-mentioned standards.

3.1 SENSITIVITY

The sensitivity factors of the three dipoles were determined using a two step calibration method (air and tissue simulating liquid) using waveguides as outlined in the standards for frequency range 600-7500MHz and using the calorimeter cell method (transfer method) as outlined in the standards for frequency 150-450 MHz.

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COMOSAR E-FIELD PROBE CALIBRATION REPORT

Ref: ACR.208.13.24.BES.A

3.2 LINEARITY

The evaluation of the linearity was done in free space using the waveguide, performing a power sweep to cover the SAR range 0.01W/kg to 100W/kg.

3.3 ISOTROPY

The axial isotropy was evaluated by exposing the probe to a reference wave from a standard dipole with the dipole mounted under the flat phantom in the test configuration suggested for system validations and checks. The probe was rotated along its main axis from 0 to 360 degrees in 15-degree steps. The hemispherical isotropy is determined by inserting the probe in a thin plastic box filled with tissue-equivalent liquid, with the plastic box illuminated with the fields from a half wave dipole. The dipole is rotated about its axis (0°–180°) in 15° increments. At each step the probe is rotated about its axis (0°–360°).

3.4 BOUNDARY EFFECT

The boundary effect is defined as the deviation between the SAR measured data and the expected exponential decay in the liquid when the probe is oriented normal to the interface. To evaluate this effect, the liquid filled flat phantom is exposed to fields from either a reference dipole or waveguide. With the probe normal to the phantom surface, the peak spatial average SAR is measured and compared to the analytical value at the surface.

The boundary effect uncertainty can be estimated according to the following uncertainty approximation formula based on linear and exponential extrapolations between the surface and $d_{be} + d_{step}$ along lines that are approximately normal to the surface:

$$SAR_{uncertainty} [\%] = \Delta SAR_{be} \frac{(d_{be} + d_{step})^2}{2d_{step}} \frac{(e^{-d_{be}/(\delta/2)})}{\delta/2} \text{ for } (d_{be} + d_{step}) < 10 \text{ mm}$$

where

$SAR_{uncertainty}$	is the uncertainty in percent of the probe boundary effect
d_{be}	is the distance between the surface and the closest <i>zoom-scan</i> measurement point, in millimetre
Δ_{step}	is the separation distance between the first and second measurement points that are closest to the phantom surface, in millimetre, assuming the boundary effect at the second location is negligible
δ	is the minimum penetration depth in millimetres of the head tissue-equivalent liquids defined in this standard, i.e., $\delta \approx 14 \text{ mm}$ at 3 GHz;
ΔSAR_{be}	in percent of SAR is the deviation between the measured SAR value, at the distance d_{be} from the boundary, and the analytical SAR value.

The measured worst case boundary effect SARuncertainty[%] for scanning distances larger than 4mm is 1.0% Limit ,2%).

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4 MEASUREMENT UNCERTAINTY

The guidelines outlined in the IEC/IEEE 62209-1528 and FCC KDB865664 D01 standards were followed to generate the measurement uncertainty associated with a SAR probe calibration using the waveguide or calorimetric cell technique depending on the frequency.

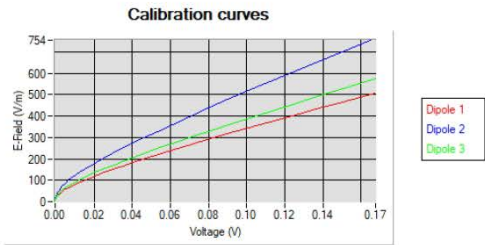
The estimated expanded uncertainty (k=2) in calibration for SAR (W/kg) is +/-11% for the frequency range 150-450MHz.
The estimated expanded uncertainty (k=2) in calibration for SAR (W/kg) is +/-14% for the frequency range 600-7500MHz.

5 CALIBRATION RESULTS

Ambient condition	
Liquid Temperature	20 +/- 1 °C
Lab Temperature	20 +/- 1 °C
Lab Humidity	30-70 %

5.1 CALIBRATION IN AIR

The following curve represents the measurement in waveguide of the voltage picked up by the probe toward the E-field generated inside the waveguide.



From this curve, the sensitivity in air is calculated using the below formula.

$$E^2 = \sum_{i=1}^3 \frac{V_i (1 + V_i / DCP_i)}{Norm_i}$$

where
Vi=voltage readings on the 3 channels of the probe
DCPi=diode compression point given below for the 3 channels of the probe
Normi=dipole sensitivity given below for the 3 channels of the probe



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Normx dipole 1 ($\mu\text{V}/(\text{V}/\text{m})^2$)	Normy dipole 2 ($\mu\text{V}/(\text{V}/\text{m})^2$)	Normz dipole 3 ($\mu\text{V}/(\text{V}/\text{m})^2$)
1.64	0.73	1.30

DCP dipole 1 (mV)	DCP dipole 2 (mV)	DCP dipole 3 (mV)
110	110	106

5.2 CALIBRATION IN LIQUID

The calorimeter cell or the waveguide is used to determine the calibration in liquid using the formula below.

$$\text{ConvF} = \frac{E_{\text{liquid}}^2}{E_{\text{air}}^2}$$

The E-field in the liquid is determined from the SAR measurement according to the below formula.

$$E_{\text{liquid}}^2 = \frac{\rho \text{ SAR}}{\sigma}$$

where

σ =the conductivity of the liquid

ρ =the volumetric density of the liquid

SAR=the SAR measured from the formula that depends on the setup used. The SAR formulas are given below

For the calorimeter cell (150-450 MHz), the formula is:

$$\text{SAR} = c \frac{dT}{dt}$$

where

c =the specific heat for the liquid

dT/dt =the temperature rises over the time

For the waveguide setup (600-75000 MHz), the formula is:

$$\text{SAR} = \frac{4P_W}{ab\delta} e^{-\frac{2z}{\delta}}$$

where

a =the larger cross-sectional of the waveguide

b =the smaller cross-sectional of the waveguide

δ =the skin depth for the liquid in the waveguide

P_W =the power delivered to the liquid

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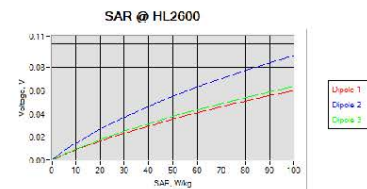
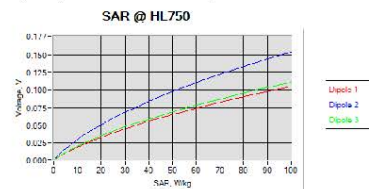
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The below table summarize the ConvF for the calibrated liquid. The curves give examples for the measured SAR depending on the voltage in some liquid.

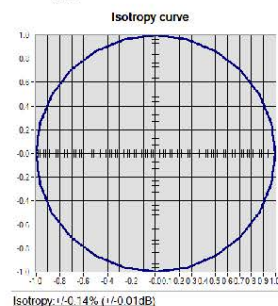
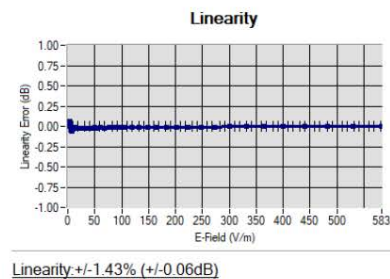
Liquid	Frequency (MHz*)	ConvF
HL750	750	2.58
HL850	835	2.46
HL900	900	2.64
HL1800	1800	2.62
HL1900	1900	2.84
HL2000	2000	2.98
HL2300	2300	2.90
HL2450	2450	3.01
HL2600	2600	2.75

(*) Frequency validity is ± 50 MHz below 600 MHz, ± 100 MHz from 600 MHz to 6 GHz and ± 700 MHz above 6 GHz



6 VERIFICATION RESULTS

The figures below represent the measured linearity and axial isotropy for this probe. The probe specification is ± 0.2 dB for linearity and ± 0.15 dB for axial isotropy.



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