



C.2 Dasy5 E-field Probe System

The SAR measurements were conducted with the dosimetric probe designed in the classical triangular configuration and optimized for dosimetric evaluation. The probe is constructed using the thick film technique; with printed resistive lines on ceramic substrates. The probe is equipped with an optical multifiber line ending at the front of the probe tip. It is connected to the EOC box on the robot arm and provides an automatic detection of the phantom surface. Half of the fibers are connected to a pulsed infrared transmitter, the other half to a synchronized receiver. As the probe approaches the surface, the reflection from the surface produces a coupling from the transmitting to the receiving fibers. This reflection increases first during the approach, reaches maximum and then decreases. If the probe is flatly touching the surface, the coupling is zero. The distance of the coupling maximum to the surface is independent of the surface reflectivity and largely independent of the surface to probe angle. The DASY5 or DASY6 software reads the reflection durning a software approach and looks for the maximum using 2nd ord curve fitting. The approach is stopped at reaching the maximum.

Probe Specifications:

Model: ES3DV3, EX3DV4

Frequency 10MHz — 6.0GHz(EX3DV4) Range: 10MHz — 4GHz(ES3DV3)

Calibration: In head and body simulating tissue at

Frequencies from 835 up to 5800MHz

Linearity: \pm 0.2 dB(30 MHz to 6 GHz) for EX3DV4

± 0.2 dB(30 MHz to 4 GHz) for ES3DV3 DynamicRange: 10 mW/kg — 100W/kg

Probe Length: 330 mm

Probe Tip

Length: 20 mm Body Diameter: 12 mm

Tip Diameter: 2.5 mm (3.9 mm for ES3DV3)
Tip-Center: 1 mm (2.0mm for ES3DV3)

Application: SAR Dosimetry Testing

Compliance tests of mobile phones

Dosimetry in strong gradient fields

Picture C.3E-field Probe

C.3 E-field Probe Calibration

Each E-Probe/Probe Amplifier combination has unique calibration parameters. A TEM cell calibration procedure is conducted to determine the proper amplifier settings to enter in the probe parameters. The amplifier settings are determined for a given frequency by subjecting the probe to a known E-field density (1 mW/cm²) using an RF Signal generator, TEM cell, and RF Power Meter.

The free space E-field from amplified probe outputs is determined in a test chamber. This calibration can be performed in a TEM cell if the frequency is below 1 GHz and inn a waveguide or



Picture C.2Near-field Probe







other methodologies above 1 GHz for free space. For the free space calibration, the probe is placed in the volumetric center of the cavity and at the proper orientation with the field. The probe is then rotated 360 degrees until the three channels show the maximum reading. The power density readings equates to 1 mW/cm².

E-field temperature correlation calibration is performed in a flat phantom filled with the appropriate simulated brain tissue. The E-field in the medium correlates with the temperature rise in the dielectric medium. For temperature correlation calibration a RF transparent thermistor-based temperature probe is used in conjunction with the E-field probe.

$$SAR = C \frac{\Delta T}{\Delta t}$$

Where:

 $\Delta t = \text{Exposure time (30 seconds)},$

C = Heat capacity of tissue (brain or muscle),

 ΔT = Temperature increase due to RF exposure.

$$SAR = \frac{\left|E\right|^2 \cdot \sigma}{\rho}$$

Where:

 σ = Simulated tissue conductivity,

 ρ = Tissue density (kg/m³).

C.4 Other Test Equipment

C.4.1 Data Acquisition Electronics(DAE)

The data acquisition electronics consist of a highly sensitive electrometer-grade preamplifier with auto-zeroing, a channel and gain-switching multiplexer, a fast 16 bit AD-converter and a command decoder with a control logic unit. Transmission to the measurement server is accomplished through an optical downlink for data and status information, as well as an optical uplink for commands and the clock.

The mechanical probe mounting device includes two different sensor systems for frontal and sideways probe contacts. They are used for mechanical surface detection and probe collision detection.

The input impedance of the DAE is 200 MOhm; the inputs are symmetrical and floating. Common mode rejection is above 80 dB.



PictureC.4: DAE





C.4.2 Robot

The SPEAG DASY system uses the high precision robots (DASY5: RX160L) type from Stäubli SA (France). For the 6-axis controller system, the robot controller version from Stäubli is used. The Stäubli robot series have many features that are important for our application:

- ➤ High precision (repeatability 0.02mm)
- > High reliability (industrial design)
- Low maintenance costs (virtually maintenance free due to direct drive gears; no belt drives)
- Jerk-free straight movements (brushless synchron motors; no stepper motors)
- Low ELF interference (motor control fields shielded via the closed metallic construction shields)



Picture C.5 DASY 5

C.4.3 Measurement Server

The Measurement server is based on a PC/104 CPU broad with CPU (DASY5: 400 MHz, Intel Celeron), chipdisk (DASY5: 128MB), RAM DASY5: 128MB). The necessary circuits for communication with the DAE electronic box, as well as the 16 bit AD converter system for optical detection and digital I/O interface are contained on the DASY I/O broad, which is directly connected to the PC/104 bus of the CPU broad.

The measurement server performs all real-time data evaluation of field measurements and surface detection, controls robot movements and handles safety operation. The PC operating system cannot interfere with these time critical processes. All connections are supervised by a watchdog, and disconnection of any of the cables to the measurement server will automatically disarm the robot and disable all program-controlled robot movements. Furthermore, the measurement server is equipped with an expansion port which is reserved for future applications. Please note that this expansion port does not have a standardized pinout, and therefore only devices provided by SPEAG can be connected. Devices from any other supplier could seriously damage the measurement server.



Picture C.6 Server for DASY 5





C.4.4 Device Holder for Phantom

The SAR in the phantom is approximately inversely proportional to the square of the distance between the source and the liquid surface. For a source at 5mm distance, a positioning uncertainty of ± 0.5 mm would produce a SAR uncertainty of $\pm 20\%$. Accurate device positioning is therefore crucial for accurate and repeatable measurements. The positions in which the devices must be measured are defined by the standards.

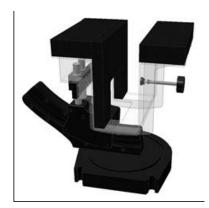
The DASY device holder is designed to cope with the different positions given in the standard. It has two scales for device rotation (with respect to the body axis) and device inclination (with respect to the line between the ear reference points). The rotation centers for both scales are the ear reference point (ERP). Thus the device needs no repositioning when changing the angles. The DASY device holder is constructed of low-loss POM material having the following dielectric parameters: relative permittivity $\ell=3$ and loss tangent $\delta=0.02$. The amount of dielectric material has been reduced in the closest vicinity of the device, since measurements have suggested that the influence of the clamp on the test results could thus be lowered.

<Laptop Extension Kit>

The extension is lightweight and made of POM, acrylic glass and foam. It fits easily on the upper part of the Mounting Device in place of the phone positioner. The extension is fully compatible with the Twin-SAM and ELI phantoms.







Picture C.7-2: Laptop Extension Kit

C.4.5 Phantom

The SAM Twin Phantom V4.0 is constructed of a fiberglass shell integrated in a table. The shape of the shell is based on data from an anatomical study designed to

Represent the 90th percentile of the population. The phantom enables the dissymmetric evaluation of SAR for both left and right handed handset usage, as well as body-worn usage using the flat phantom region. Reference markings on the Phantom allow the complete setup of all predefined phantom positions and measurement grids by manually teaching three points in the robot. The shell phantom has a 2mm shell thickness (except the ear region where shell thickness increases to 6 mm).

Shell Thickness: 2±0. 2 mm

Filling Volume: Approx. 25 liters

Dimensions: 810 x 1000 x 500 mm (H x L x W)

Available: Special





Picture C.8: SAM Twin Phantom

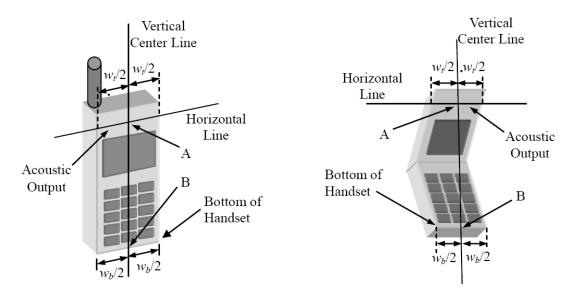




ANNEX D Position of the wireless device in relation to the phantom

D.1 General considerations

This standard specifies two handset test positions against the head phantom – the "cheek" position and the "tilt" position.



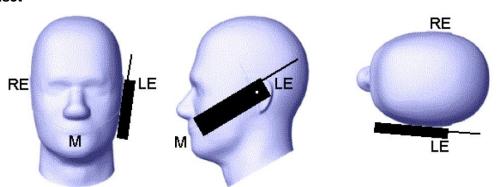
 W_t Width of the handset at the level of the acoustic

 W_b Width of the bottom of the handset

A Midpoint of the width W_t of the handset at the level of the acoustic output

B Midpoint of the width W_b of the bottom of the handset

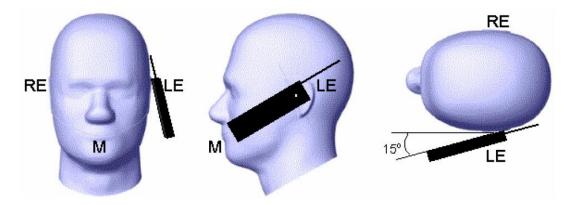
Picture D.1-a Typical "fixed" case handset
Picture D.1-b Typical "clam-shell" case handset



Picture D.2 Cheek position of the wireless device on the left side of SAM



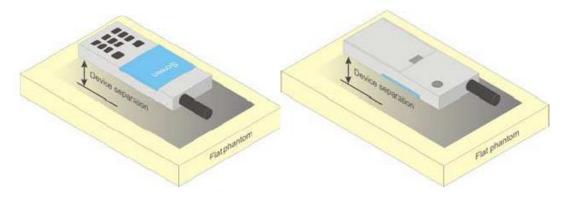




Picture D.3 Tilt position of the wireless device on the left side of SAM

D.2 Body-worn device

A typical example of a body-worn device is a mobile phone, wireless enabled PDA or other battery operated wireless device with the ability to transmit while mounted on a person's body using a carry accessory approved by the wireless device manufacturer.



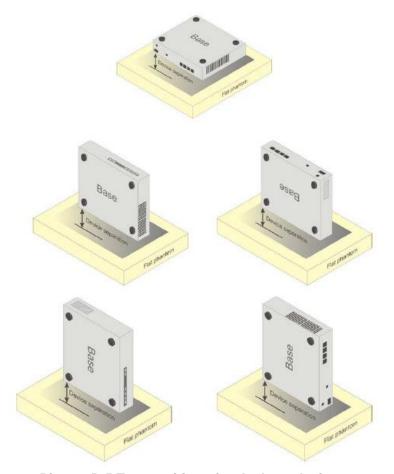
Picture D.4Test positions for body-worn devices

D.3 Desktop device

A typical example of a desktop device is a wireless enabled desktop computer placed on a table or desk when used.

The DUT shall be positioned at the distance and in the orientation to the phantom that corresponds to the intended use as specified by the manufacturer in the user instructions. For devices that employ an external antenna with variable positions, tests shall be performed for all antenna positions specified. Picture 8.5 show positions for desktop device SAR tests. If the intended use is not specified, the device shall be tested directly against the flat phantom.





Picture D.5 Test positions for desktop devices

D.4 DUT Setup Photos



Picture D.6





ANNEX E Equivalent Media Recipes

The liquid used for the frequency range of 800-3000 MHz consisted of water, sugar, salt, preventol, glycol monobutyl and Cellulose. The liquid has been previously proven to be suited for worst-case. The Table E.1 shows the detail solution. It's satisfying the latest tissue dielectric parameters requirements proposed by the IEEE 1528 and IEC 62209.

TableE.1: Composition of the Tissue Equivalent Matter

Frequency	835Head	925Dady	1900	1900	2450	2450	5800	5800
(MHz)	ossneau	835Body	Head	Body	Head	Body	Head	Body
Ingredients (% by	/ weight)							
Water	41.45	52.5	55.242	69.91	58.79	72.60	65.53	65.53
Sugar	56.0	45.0	\	\	\	\	\	\
Salt	1.45	1.4	0.306	0.13	0.06	0.18	\	\
Preventol	0.1	0.1	\	\	\	\	\	\
Cellulose	1.0	1.0	\	\	\	\	\	\
Glycol	\	١	44.452	29.96	41.15	27.22	\	\
Monobutyl	\	\	44.432	29.90	41.15	21.22	\	\
Diethylenglycol	\	,	\	,	\	,	47.04	47.04
monohexylether	\	\	\	\	\	\	17.24	17.24
Triton X-100	\	\	\	\	\	\	17.24	17.24
Dielectric	c=11 F	c=55.0	ε=40.0	c=52.2	ε=39.2	c=50.7	c=25.2	ε=48.2
Parameters	ε=41.5	ε=55.2		ε=53.3		ε=52.7	ε=35.3	
Target Value	σ=0.90	σ=0.97	σ=1.40	σ=1.52	σ=1.80	σ=1.95	σ=5.27	σ=6.00

Note: There are a little adjustment respectively for 750, 1750, 2600, 5200, 5300 and 5600 based on the recipe of closest frequency in table E.1.





ANNEX F System Validation

The SAR system must be validated against its performance specifications before it is deployed. When SAR probes, system components or software are changed, upgraded or recalibrated, these must be validated with the SAR system(s) that operates with such components.

Table F.1: System Validation for 7673

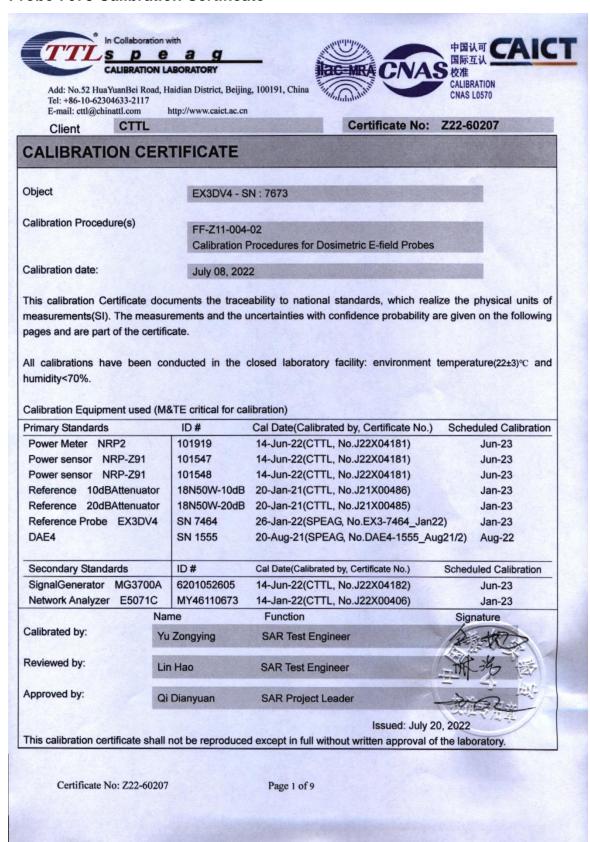
Probe SN.	Liquid name	Validation date	Frequency point	Status (OK or Not)
	Head 750MHz		750 MHz	OK
7673		July.22,2022		
7673	Head 900MHz	July.22,2022	900 MHz	OK
7673	Head 1750MHz	July.22,2022	1750 MHz	OK
7673	Head 1900MHz	July.22,2022	1900 MHz	OK
7673	Head 2000MHz	July.22,2022	2000 MHz	OK
7673	Head 2300MHz	July.22,2022	2300 MHz	OK
7673	Head 2450MHz	July.22,2022	2450 MHz	OK
7673	Head 2600MHz	July.22,2022	2600 MHz	OK
7673	Head 3300MHz	July.23,2022	3300 MHz	OK
7673	Head 3500MHz	July.23,2022	3500 MHz	OK
7673	Head 3700MHz	July.23,2022	3700 MHz	OK
7673	Head 3900MHz	July.23,2022	3900 MHz	OK
7673	Head 4100MHz	July.23,2022	4100 MHz	OK
7673	Head 4200MHz	July.23,2022	4200 MHz	OK
7673	Head 4400MHz	July.24,2022	4400 MHz	OK
7673	Head 4600MHz	July.24,2022	4600 MHz	OK
7673	Head 4800MHz	July.24,2022	4800 MHz	OK
7673	Head 4950MHz	July.24,2022	4950 MHz	OK
7673	Head 5250MHz	July.25,2022	5250 MHz	OK
7673	Head 5600MHz	July.25,2022	5600 MHz	OK
7673	Head 5750MHz	July.25,2022	5750 MHz	OK





ANNEX G Probe Calibration Certificate

Probe 7673 Calibration Certificate











Glossary:

TSL tissue simulating liquid
NORMx,y,z sensitivity in free space
ConvF sensitivity in TSL / NORMx,y,z
DCP diode compression point

CF crest factor (1/duty_cycle) of the RF signal A,B,C,D modulation dependent linearization parameters

Polarization θ θ rotation around an axis that is in the plane normal to probe axis (at measurement center), i

 θ =0 is normal to probe axis

Connector Angle information used in DASY system to align probe sensor X to the robot coordinate system Calibration is Performed According to the Following Standards:

a) IEEE Std 1528-2013, "IEEE Recommended Practice for Determining the Peak Spatial-Averaged Specific Absorption Rate (SAR) in the Human Head from Wireless Communications Devices: Measurement Techniques", June 2013

b) IEC 62209-1, "Measurement procedure for the assessment of Specific Absorption Rate (SAR) from hand-held and body-mounted devices used next to the ear (frequency range of 300 MHz to 6 GHz)", July 2016

c) IEĆ 62209-2, "Procedure to determine the Specific Absorption Rate (SAR) for wireless communication devices used in close proximity to the human body (frequency range of 30 MHz to 6 GHz)", March 2010

d) KDB 865664, "SAR Measurement Requirements for 100 MHz to 6 GHz"

Methods Applied and Interpretation of Parameters:

- NORMx,y,z: Assessed for E-field polarization θ=0 (f≤900MHz in TEM-cell; f>1800MHz: waveguide).
 NORMx,y,z are only intermediate values, i.e., the uncertainties of NORMx,y,z does not effect the E²-field uncertainty inside TSL (see below ConvF).
- NORM(f)x,y,z = NORMx,y,z* frequency_response (see Frequency Response Chart). This
 linearization is implemented in DASY4 software versions later than 4.2. The uncertainty of the
 frequency response is included in the stated uncertainty of ConvF.
- DCPx,y,z: DCP are numerical linearization parameters assessed based on the data of power sweep (no uncertainty required). DCP does not depend on frequency nor media.
- PAR: PAR is the Peak to Average Ratio that is not calibrated but determined based on the signal characteristics.
- Ax,y,z; Bx,y,z; Cx,y,z; VRx,y,z:A,B,C are numerical linearization parameters assessed based on the
 data of power sweep for specific modulation signal. The parameters do not depend on frequency nor
 media. VR is the maximum calibration range expressed in RMS voltage across the diode.
- ConvF and Boundary Effect Parameters: Assessed in flat phantom using E-field (or Temperature Transfer Standard for f≤800MHz) and inside waveguide using analytical field distributions based on power measurements for f >800MHz. The same setups are used for assessment of the parameters applied for boundary compensation (alpha, depth) of which typical uncertainty valued are given. These parameters are used in DASY4 software to improve probe accuracy close to the boundary. The sensitivity in TSL corresponds to NORMx,y,z* ConvF whereby the uncertainty corresponds to that given for ConvF. A frequency dependent ConvF is used in DASY version 4.4 and higher which allows extending the validity from±50MHz to±100MHz.
- Spherical isotropy (3D deviation from isotropy): in a field of low gradients realized using a flat phantom exposed by a patch antenna.
- Sensor Offset: The sensor offset corresponds to the offset of virtual measurement center from the probe tip (on probe axis). No tolerance required.
- Connector Angle: The angle is assessed using the information gained by determining the NORMx (no uncertainty required).

Certificate No:Z22-60207

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Add: No.52 HuaYuanBei Road, Haidian District, Beijing, 100191, China Tel: +86-10-62304633-2117

E-mail: cttl@chinattl.com http://www.caict.ac.cn

DASY/EASY - Parameters of Probe: EX3DV4 - SN:7673

Basic Calibration Parameters

	Sensor X	Sensor Y	Sensor Z	Unc (k=2)
$Norm(\mu V/(V/m)^2)^A$	0.62	0.63	0.61	±10.0%
DCP(mV) ^B	110.3	111.1	110.2	

Modulation Calibration Parameters

UID	Communication System Name		A dB	B dBõV	С	D dB	VR mV	Unc ^E (<i>k</i> =2)
0 CW	X	0.0	0.0	1.0	0.00	198.1	±2.1%	
		Υ	0.0	0.0	1.0		199.1	
		Z	0.0	0.0	1.0		193.0	

The reported uncertainty of measurement is stated as the standard uncertainty of Measurement multiplied by the coverage factor k=2, which for a normal distribution Corresponds to a coverage probability of approximately 95%.

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A The uncertainties of Norm X, Y, Z do not affect the E2-field uncertainty inside TSL (see Page 4).

^B Numerical linearization parameter: uncertainty not required.

^E Uncertainly is determined using the max. deviation from linear response applying rectangular distribution and is expressed for the square of the field value.









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DASY/EASY – Parameters of Probe: EX3DV4 – SN:7673

Calibration Parameter Determined in Head Tissue Simulating Media

f [MHz] ^C	Relative Permittivity ^F	Conductivity (S/m) F	ConvF X	ConvF Y	ConvF Z	Alpha ^G	Depth ^G (mm)	Unct. (k=2)
750	41.9	0.89	10.34	10.34	10.34	0.14	1.40	±12.1%
900	41.5	0.97	9.95	9.95	9.95	0.17	1.30	±12.1%
1750	40.1	1.37	8.49	8.49	8.49	0.26	0.98	±12.1%
1900	40.0	1.40	8.07	8.07	8.07	0.24	1.07	±12.1%
2000	40.0	1.40	8.08	8.08	8.08	0.20	1.31	±12.1%
2300	39.5	1.67	7.86	7.86	7.86	0.62	0.66	±12.1%
2450	39.2	1.80	7.57	7.57	7.57	0.60	0.68	±12.1%
2600	39.0	1.96	7.31	7.31	7.31	0.65	0.65	±12.1%
3300	38.2	2.71	6.93	6.93	6.93	0.36	0.99	±13.3%
3500	37.9	2.91	6.73	6.73	6.73	0.40	0.94	±13.3%
3700	37.7	3.12	6.50	6.50	6.50	0.30	1.20	±13.3%
3900	37.5	3.32	6.44	6.44	6.44	0.30	1.50	±13.3%
4100	37.2	3.53	6.46	6.46	6.46	0.30	1.40	±13.3%
4200	37.1	3.63	6.35	6.35	6.35	0.35	1.35	±13.3%
4400	36.9	3.84	6.26	6.26	6.26	0.30	1.50	±13.3%
4600	36.7	4.04	6.10	6.10	6.10	0.35	1.50	±13.3%
4800	36.4	4.25	5.99	5.99	5.99	0.35	1.60	±13.3%
4950	36.3	4.40	5.65	5.65	5.65	0.35	1.65	±13.3%
5250	35.9	4.71	5.21	5.21	5.21	0.40	1.42	±13.3%
5600	35.5	5.07	4.71	4.71	4.71	0.40	1.50	±13.3%
5750	35.4	5.22	4.70	4.70	4.70	0.40	1.50	±13.3%

^c Frequency validity above 300 MHz of ±100MHz only applies for DASY v4.4 and higher (Page 2), else it is restricted to ±50MHz. The uncertainty is the RSS of ConvF uncertainty at calibration frequency and the uncertainty for the indicated frequency band. Frequency validity below 300 MHz is ± 10, 25, 40, 50 and 70 MHz for ConvF assessments at 30, 64, 128, 150 and 220 MHz respectively. Above 5 GHz frequency validity can be extended to ± 110 MHz.

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F At frequency below 3 GHz, the validity of tissue parameters (ϵ and σ) can be relaxed to ±10% if liquid compensation formula is applied to measured SAR values. At frequencies above 3 GHz, the validity of tissue parameters (ϵ and σ) is restricted to ±5%. The uncertainty is the RSS of the ConvF uncertainty for indicated target tissue parameters.

^G Alpha/Depth are determined during calibration. SPEAG warrants that the remaining deviation due to the boundary effect after compensation is always less than ± 1% for frequencies below 3 GHz and below ± 2% for the frequencies between 3-6 GHz at any distance larger than half the probe tip diameter from the boundary.

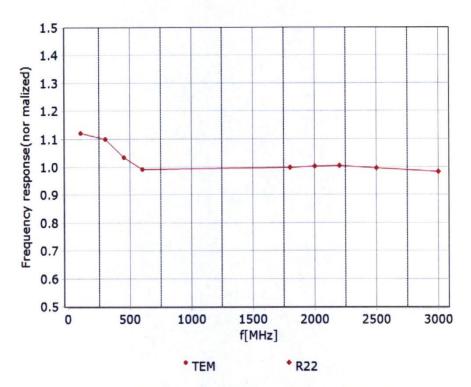








Frequency Response of E-Field (TEM-Cell: ifi110 EXX, Waveguide: R22)



Uncertainty of Frequency Response of E-field: ±7.4% (k=2)

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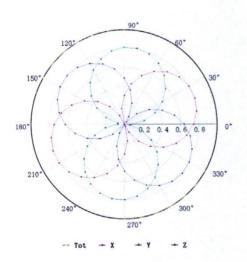
Add: No.52 HuaYuanBei Road, Haidian District, Beijing, 100191, China Tel: +86-10-62304633-2117

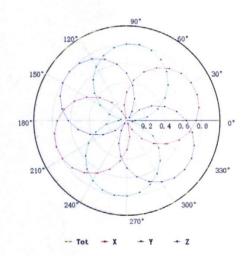
E-mail: cttl@chinattl.com http://www.caict.ac.cn

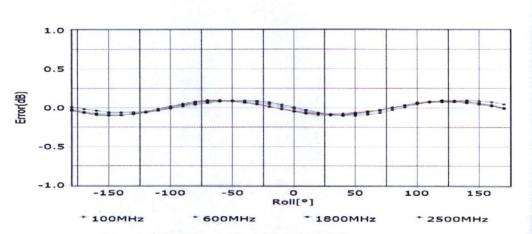
Receiving Pattern (Φ), θ=0°

f=600 MHz, TEM

f=1800 MHz, R22







Uncertainty of Axial Isotropy Assessment: ±1.2% (k=2)

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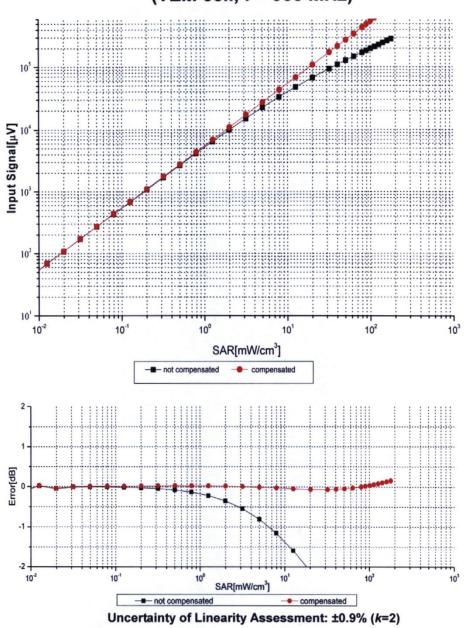
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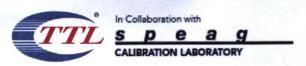
Dynamic Range f(SAR_{head}) (TEM cell, f = 900 MHz)



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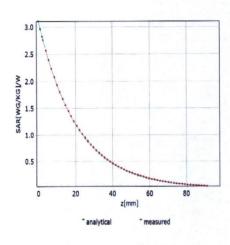


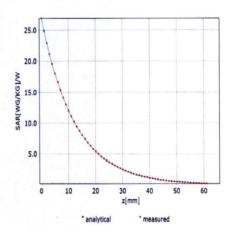


Conversion Factor Assessment

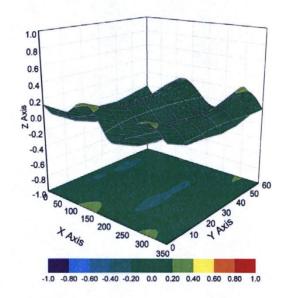
f=750 MHz,WGLS R9(H_convF)

f=1750 MHz,WGLS R22(H_convF)





Deviation from Isotropy in Liquid



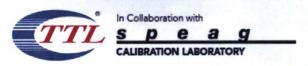
Uncertainty of Spherical Isotropy Assessment: ±3.2% (k=2)

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DASY/EASY - Parameters of Probe: EX3DV4 - SN:7673

Other Probe Parameters

Sensor Arrangement	Triangular
Connector Angle (°)	145.7
Mechanical Surface Detection Mode	enabled
Optical Surface Detection Mode	disable
Probe Overall Length	337mm
Probe Body Diameter	10mm
Tip Length	9mm
Tip Diameter	2.5mm
Probe Tip to Sensor X Calibration Point	1mm
Probe Tip to Sensor Y Calibration Point	1mm
Probe Tip to Sensor Z Calibration Point	1mm
Recommended Measurement Distance from Surface	1.4mm

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ANNEX H Dipole Calibration Certificate

750 MHz Dipole Calibration Certificate

Calibration Laboratory of Schmid & Partner **Engineering AG** Zeughausstrasse 43, 8004 Zurich, Switzerland





Schweizerischer Kalibrierdienst Service suisse d'étalonnage Servizio svizzero di taratura **Swiss Calibration Service**

Accredited by the Swiss Accreditation Service (SAS) The Swiss Accreditation Service is one of the signatories to the EA Multilateral Agreement for the recognition of calibration certificates Accreditation No.: SCS 0108

CTTL (Auden)

Certificate No: D750V3-1017_Jul22 CALIBRATION CERTIFICATE Object D750V3 - SN:1017 Calibration procedure(s) QA CAL-05.v11 Calibration Procedure for SAR Validation Sources between 0.7-3 GHz July 20, 2022 Calibration date: This calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI). The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate. All calibrations have been conducted in the closed laboratory facility: environment temperature (22 ± 3)°C and humidity < 70% Calibration Equipment used (M&TE critical for calibration) Primary Standards ID# Cal Date (Certificate No.) Scheduled Calibration 04-Apr-22 (No. 217-03525/03524) SN: 104778 Power meter NRP Apr-23 Power sensor NRP-Z91 SN: 103244 04-Apr-22 (No. 217-03524) Apr-23 SN: 103245 04-Apr-22 (No. 217-03525) Power sensor NRP-Z91 Apr-23 SN: BH9394 (20k) 04-Apr-22 (No. 217-03527) Apr-23 Reference 20 dB Attenuator SN: 310982 / 06327 04-Apr-22 (No. 217-03528) Type-N mismatch combination Apr-23 Reference Probe EX3DV4 SN: 7349 31-Dec-21 (No. EX3-7349_Dec21) Dec-22 DAE4 SN: 601 02-May-22 (No. DAE4-601_May22) May-23 Secondary Standards ID# Check Date (in house) Scheduled Check Power meter E4419B SN: GB39512475 30-Oct-14 (in house check Oct-20) In house check: Oct-22 Power sensor HP 8481A SN: US37292783 07-Oct-15 (in house check Oct-20) In house check: Oct-22 Power sensor HP 8481A SN: MY41093315 07-Oct-15 (in house check Oct-20) In house check: Oct-22 RF generator R&S SMT-06 SN: 100972 15-Jun-15 (in house check Oct-20) In house check: Oct-22 Network Analyzer Agilent E8358A SN: US41080477 31-Mar-14 (in house check Oct-20) In house check: Oct-22 Name Function Signature Calibrated by: Aidonia Georgiadou Laboratory Technician Approved by: Sven Kühn Technical Manager Issued: July 22, 2022 This calibration certificate shall not be reproduced except in full without written approval of the laboratory

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Calibration Laboratory of Schmid & Partner

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Glossary:

TSL tissue simulating liquid

ConvF sensitivity in TSL / NORM x,y,z N/A not applicable or not measured

Calibration is Performed According to the Following Standards:

- a) IEC/IEEE 62209-1528, "Measurement Procedure For The Assessment Of Specific Absorption Rate Of Human Exposure To Radio Frequency Fields From Hand-Held And Body-Worn Wireless Communication Devices - Part 1528: Human Models, Instrumentation And Procedures (Frequency Range of 4 MHz to 10 GHz)", October 2020.
- b) KDB 865664, "SAR Measurement Requirements for 100 MHz to 6 GHz"

Additional Documentation:

c) DASY System Handbook

Methods Applied and Interpretation of Parameters:

- Measurement Conditions: Further details are available from the Validation Report at the end
 of the certificate. All figures stated in the certificate are valid at the frequency indicated.
- Antenna Parameters with TSL: The source is mounted in a touch configuration below the center marking of the flat phantom.
- Return Loss: This parameter is measured with the source positioned under the liquid filled phantom (as described in the measurement condition clause). The Return Loss ensures low reflected power. No uncertainty required.
- SAR measured: SAR measured at the stated antenna input power.
- SAR normalized: SAR as measured, normalized to an input power of 1 W at the antenna connector.
- SAR for nominal TSL parameters: The measured TSL parameters are used to calculate the nominal SAR result.

The reported uncertainty of measurement is stated as the standard uncertainty of measurement multiplied by the coverage factor k=2, which for a normal distribution corresponds to a coverage probability of approximately 95%.

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Measurement Conditions

DASY system configuration, as far as not given on page 1.

DASY Version	DASY52	V52.10.4
Extrapolation	Advanced Extrapolation	
Phantom	Modular Flat Phantom	
Distance Dipole Center - TSL	15 mm	with Spacer
Zoom Scan Resolution	dx, dy, dz = 5 mm	
Frequency	750 MHz ± 1 MHz	

Head TSL parameters
The following parameters and calculations were applied.

	Temperature	Permittivity	Conductivity
Nominal Head TSL parameters	22.0 °C	41.9	0.89 mho/m
Measured Head TSL parameters	(22.0 ± 0.2) °C	40.5 ± 6 %	0.90 mho/m ± 6 %
Head TSL temperature change during test	< 0.5 °C		

SAR result with Head TSL

SAR averaged over 1 cm ³ (1 g) of Head TSL	Condition	
SAR measured	250 mW input power	2.19 W/kg
SAR for nominal Head TSL parameters	normalized to 1W	8.63 W/kg ± 17.0 % (k=2)

SAR averaged over 10 cm³ (10 g) of Head TSL	condition	
SAR measured	250 mW input power	1.43 W/kg
SAR for nominal Head TSL parameters	normalized to 1W	5.64 W/kg ± 16.5 % (k=2)

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Appendix (Additional assessments outside the scope of SCS 0108)

Antenna Parameters with Head TSL

Impedance, transformed to feed point	53.7 Ω - 0.5 jΩ
Return Loss	- 29.0 dB

General Antenna Parameters and Design

Electrical Delay (one direction)	1.034 ns
Liectifical Delay (Offe direction)	1.004 115

After long term use with 100W radiated power, only a slight warming of the dipole near the feedpoint can be measured.

The dipole is made of standard semirigid coaxial cable. The center conductor of the feeding line is directly connected to the second arm of the dipole. The antenna is therefore short-circuited for DC-signals. On some of the dipoles, small end caps are added to the dipole arms in order to improve matching when loaded according to the position as explained in the "Measurement Conditions" paragraph. The SAR data are not affected by this change. The overall dipole length is still according to the Standard.

No excessive force must be applied to the dipole arms, because they might bend or the soldered connections near the feedpoint may be damaged.

Additional EUT Data

Manufactured by	SPEAG

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