

ZTE ZM8300G Module Hardware User Manual

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Contents

1	OVERVIEW	7
1.1	SCOPE	7
1.2	ACRONYMS	7
1.3	PRODUCT DESCRIPTION	7
2	GENERAL INTRODUCTION	9
2.1	ABOUT THIS CHAPTER	9
2.2	FEATURE INTRODUCTION.....	9
2.3	APPLICATION DIAGRAM	11
2.4	CIRCUIT DIAGRAM	11
2.5	OUTLINE DIMENSIONS DIAGRAM.....	12
2.6	TRANSFERRED BOARD AND DEBUG BOARD	13
3	APPLICATION INTERFACES	14
3.1	ABOUT THIS CHAPTER	14
3.2	DEFINITIONS OF LGA PINS	14
3.2.1	<i>Pin Definitions</i>	14
3.2.2	<i>Pin Distribution</i>	18
3.3	POWER INTERFACES	19
3.3.1	<i>Overview of Power Pins</i>	19
3.3.2	<i>VSYS Primary Power</i>	19
3.3.3	<i>VIO Power</i>	20
3.4	CONTROL SIGNAL INTERFACES	20
3.4.1	<i>Overview of Control Signals</i>	20
3.4.2	<i>POWN_ON Signal</i>	20
3.4.3	<i>RESET_N Signal</i>	22
3.4.4	<i>WAKEUP_IN Signal</i>	23
3.4.5	<i>WAKEUP_OUT Signal</i>	24
3.4.6	<i>PSM_MON Signal</i>	24
3.4.7	<i>STATE Signal</i>	25
3.5	DEBUG_UART INTERFACE.....	25
3.6	BLSP INTERFACES.....	26
3.6.1	<i>Pin Description</i>	26
3.6.2	<i>UART Interfaces</i>	26
3.6.3	<i>SPI Bus Interface</i>	27

3.6.4	I ² C Bus	29
3.7	GPIO INTERFACES	30
3.8	USIM INTERFACE	31
3.8.1	Pin Description	31
3.8.2	Electrical Characteristics and Design Points.....	31
3.8.3	Circuit Recommended for the USIM Card Interface.....	32
3.9	USB INTERFACE	32
3.9.1	Pin Description	32
3.9.2	Design Points and Recommended Circuit.....	33
3.10	AUDIO INTERFACES	34
3.10.1	Pin Description	34
3.10.2	Design Points.....	34
3.11	ADC/MPP INTERFACES.....	35
3.11.1	Pin Description	35
3.11.2	Design Points.....	35
3.12	JTAG INTERFACE	36
3.12.1	Pin Description	36
3.12.2	Design Points.....	37
3.13	ANTENNA INTERFACES.....	37
3.13.1	Pin Description	37
3.13.2	Antenna Design Points	38
4	RF CHARACTERISTICS	39
4.1	ABOUT THIS CHAPTER	39
4.1.1	Power Supply.....	39
4.1.2	Operating Current	39
4.2	REFERENCE DESIGN FOR RF LAYOUT.....	39
4.3	TEST STANDARD FOR CONDUCTED RF	40
4.4	REQUIREMENTS FOR ANTENNA DESIGN.....	40
4.4.1	Key Points for Antenna Design	40
4.4.2	Antenna Efficiency.....	41
4.4.3	VSWR.....	42
4.4.4	S11.....	42
4.4.5	Polarization	42
4.4.6	Radiation Pattern	42
4.4.7	Requirements for IoT Antenna Design.....	43
4.4.8	Precautions for Early Antenna Design	43

5	MECHANICAL CHARACTERISTICS	44
5.1	ABOUT THIS CHAPTER	44
5.2	ASSEMBLY PROCEDURE	44
5.2.1	Overview	44
5.2.2	Steel Mesh	44
5.2.3	Reflow Curve	46
5.3	REPAIR PROCEDURE	47
5.3.1	Repair Procedure	47
5.3.2	Module Dismantling	47
5.3.3	treatment in weld area	47
5.3.4	Module Installation	47
5.3.5	Visual Inspection	47
5.3.6	Feature Validation	47
5.4	EMC AND ESD PROTECTION	48

1 Overview

1.1 Scope

This document is intended for customers who use and develop wireless IoT terminal products. This document provides information and precautions for developing the hardware of IoT terminal products using ZTE ZM8300G IoT wireless module. This document applies only to hardware development that uses the ZM8300G IoT wireless module.

1.2 Acronyms

Table 1-1 Acronyms Used in This Document

Acronym	Full Name
ESD	Electro-Static discharge
USB	Universal Serial Bus
UART	Universal Asynchronous Receiver Transmitter
USIM	Universal Subscriber Identity Module
I/O	Input/Output
BLSP	BAM (bus access module) low-speed peripheral
SPI	Serial Peripheral Interface
I ² C	Inter-Integrated Circuit
PCM	Pulse-coded Modulation
LED	Light Emitting Diode
GPIO	General-purpose input/output
EMC	Electromagnetic Compatibility
NB-IoT	Narrow Band Internet of Things
AP	Application processor

1.3 Product Description

The ZM8300G module is an IoT module that uses the LGA packaging. The ZM8300G module supports the CAT NB/eMTC, multiple band combinations such as Band 5/8 and Band 3/39,

and Support for GNSS (GPS, Beidou, GLONASS, and Galileo), and provides a wide variety of interfaces, such as the USB, UART, SPI, I²C, PCM, and ADC. The ZM8300G module can be used for the development of various kinds of IoT products. This document describes the functions, application interfaces, RF characteristics, electrical characteristics, reliability, and mechanical characteristics of the ZM8300G module and provides precautions for design, with the goal of providing design guidelines and references for the hardware application and development of the ZM8300G module.

The ZM8300G module is small and its dimensions are as follows: 23.0 mm x 28.0 mm x 2.4 mm (excluding the label thickness, which is 0.1 mm). The ZM8300G module meets requirements of M2M applications and can be widely used in IoT-related devices such as data metering devices, data collection devices, security solution devices, wireless POS devices, and mobile computing devices.

Being an LGA module, the ZM8300G IoT module provides 67 pads (consisting of 58 LGA signal pads, seven JTAG test pads, and two PG pads) and can be applied to customers' design.

2 General Introduction

2.1 About This Chapter

This chapter describes the ZM8300G module in general, covering the following aspects:

- Feature introduction
- Application diagram
- Circuit diagram
- Outline dimensions diagram

2.2 Feature Introduction

Table 2-1 provides major technical parameters and features of the ZM8300G module.

Table 2-1 Major Technical Parameters and Features of the ZM8300G Module

Title	Description
Physical features	Dimensions: 23.0 mm x 28.0 mm x 2.4 mm Weight: 3.3 g
Airlink technologies	Supports the NB-IoT: Band 5/8,3/39. Supports the GNSSes: GPS, Beidou, GLONASS, and Galileo.
Operating temperature	-40 to 85°C
Storage temperature	-40 to 85°C
Operating voltage	DC 3.0 V to 4.2 V (with the typical value being 3.6 V)
AT command set	Refer to the <i>ZTE ZM8300G IoT Module AT Command Set</i> .
Power consumption (3.6 V)	leakage current: 4.8 uA
	PSM (power saving mode) sleep current: 7 uA
	Average sleep current: 0.7 mA
	Idle current: 1.47mA , 2.56s DRX Online ◆注 1 idle current: note 1
	Average operating current: NB-IoT: 50 mA (UL)/50 mA (DL) ◆Note 2

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Title	Description
	eMTC: 115 mA (UL)/112 mA (DL) ◆Note 3
Application interfaces (LGA interfaces)	USB 2.0 interface
	USIM card interface (2.85 V and 1.8 V), supporting hot plugging
	UART/JTAG debug interface
	UART/SPI/I2C/GPIO (multiple combinations; for details, see Table 3-6
	PCM/I ² S interface
	ADC/MPP interface
	Startup/Shutdown interface
	Module hardware reset interface
	Status indication interface
	AP waking up interface for module
	Module waking up interface for AP
Antenna interface	Antenna pads (1xeMTC/NB-IoT antenna pad; 1xGPS antenna pad)
◆Note 1: The lab data(sleep and Idle current) provided by Qualcomm 's test data from lab. ◆Note 2: The lab data provided by Qualcomm 's test data from lab. The operating condition is as follows: LTE 10 MHz bandwidth embedded data call@0dBm TX, UL/DL only. Used data packets are as follows: UL 62.5 kbps (15 kHz single tone)/DL 21 kbps (multi tone). ◆Note 3: The lab data provided by Qualcomm 's test data from lab. The operating condition is as follows: LTE 10 MHz bandwidth embedded data call@0dBm TX, UL/DL only. 375 kbps data packets are used in both the uplink and downlink directions.	

2.3 Application Diagram

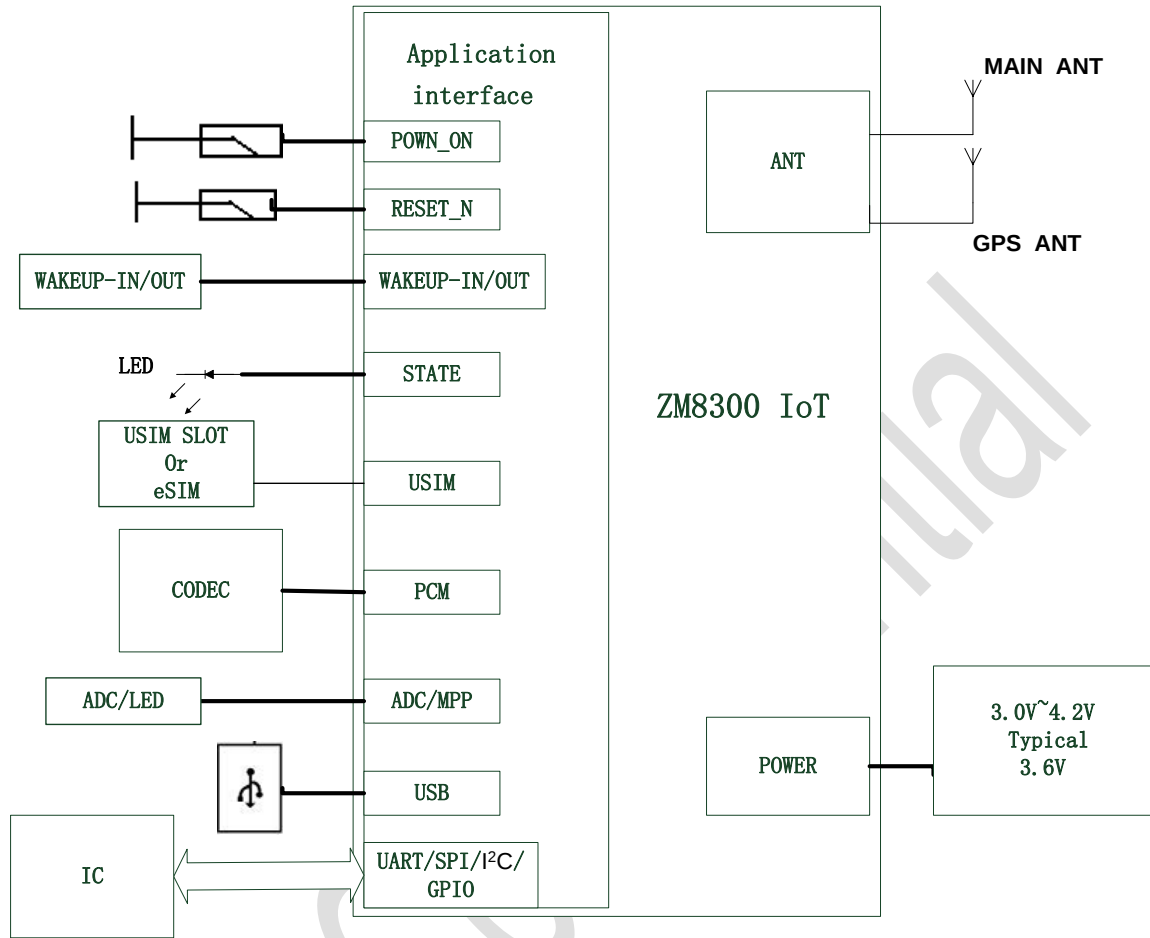


Figure 2-1 Application Diagram of the ZM8300G Module

2.4 Circuit Diagram

Figure 2-2 is the circuit diagram of the ZM8300G module. The ZM8300G module consists of the following main function units:

- Baseband controller/power management unit
- Memory (1 Gbit NAND + 512 bit LPDDR2)
- LGA interface unit
- RF transceiver IC
- RF front-end circuit

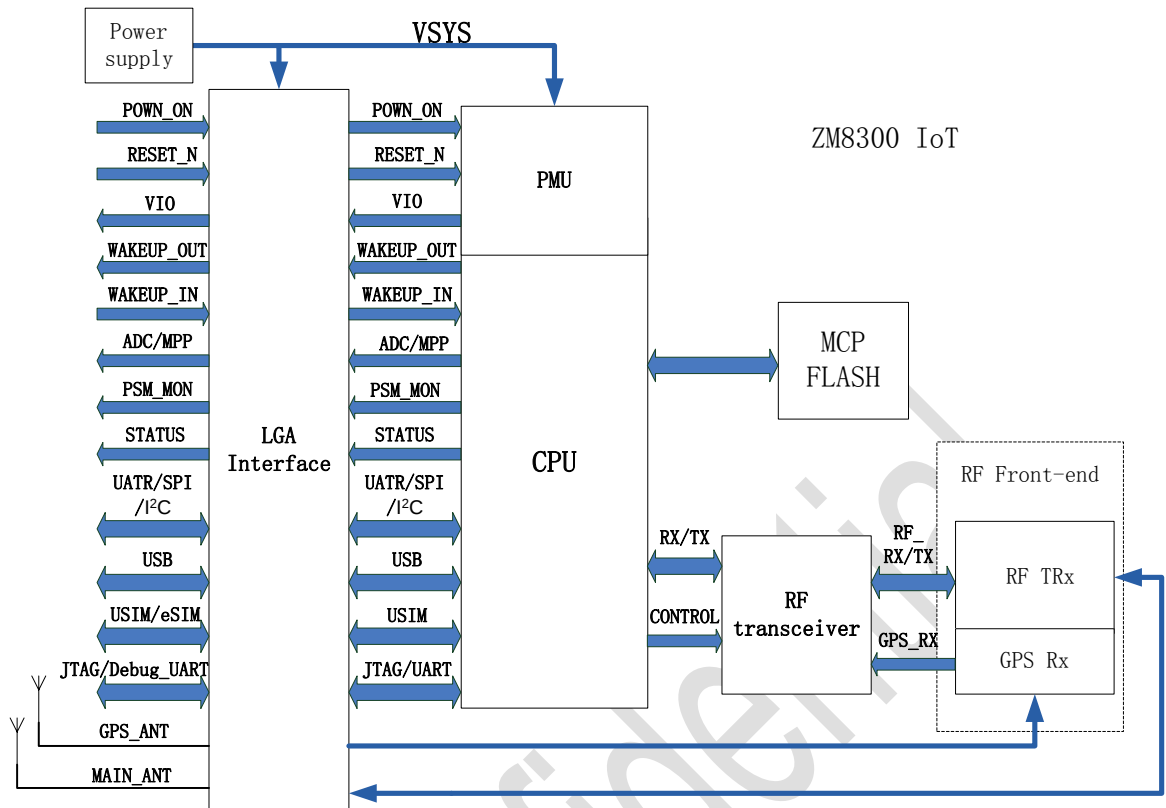


Figure 2-1 Circuit Diagram of the ZM8300G Module

2.5 Outline Dimensions Diagram

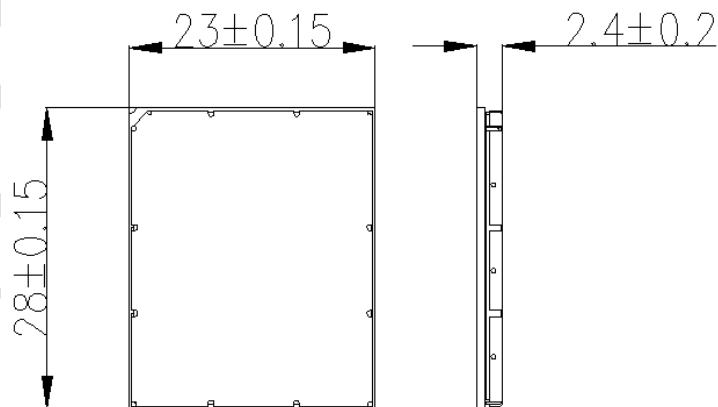


Figure 2-3 Dimensions of the ZM8300G Module (in mm)

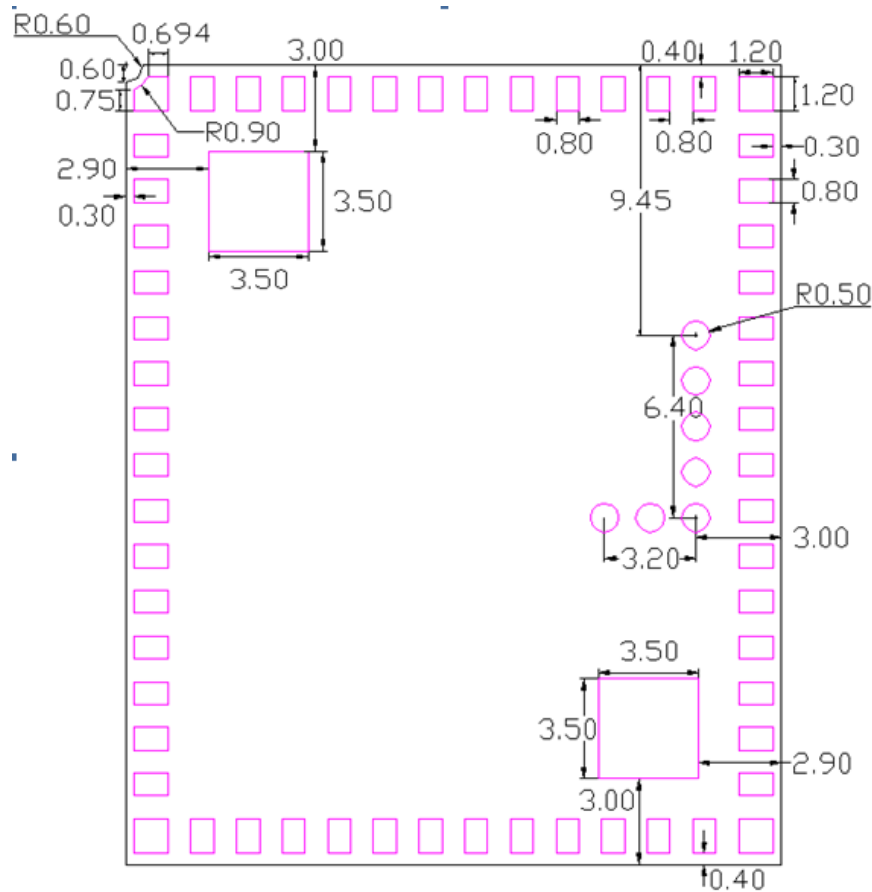


Figure 2-4 Dimensions of the BOT Side of the ZM8300G Module (in mm) ♦Note 4

♦Note 4: Figure 2-4 is the outline pad diagram of the ZM8300G module. If pad design of a system board is required, ZTE can provide a dedicated outline drawing file.

2.6 transferred board and debug board

ZTE provide transferred board, debug board and peripheral such as antenna, power supplier, Serial Interface cable in order to better apply the ZM8300G to design the product for you, detailed referred to <<ZTE debug board use manual for module product>>

3 Application Interfaces

3.1 About This Chapter

This chapter describes the following major interfaces provided by the ZM8300G module:

- Power interfaces
- Control signal interfaces
- DEBUG_UART interface
- BLSP interfaces
- GPIO interfaces
- USIM interface
- USB interface
- Audio interfaces
- ADC/MPP interfaces
- JTAG interface
- Antenna interfaces

3.2 Definitions of LGA Pins

The ZM8300G IoT module uses the LGA package and has 67 pads, namely, 58 signal pads, seven JTAG test pads, and two PG pads. Using the pads, the ZM8300G module is connected to a customer's IoT application platform. The following sections describe interfaces provided by the ZM8300G module.

3.2.1 Pin Definitions

Table 3-1 provides definitions for input/output parameters of pins of the ZM8300G module.

Table 3-1 Definitions for Input/Output Parameters of Pins of the ZM8300G Module ◆ Note 1

Type	Description
DO	Digital output
DI	Digital input
B	Bidirectional digital
PI	Power input
PO	Power output
I	In

O	Out
AI	Analog input
AO	Analog output

◆Note 1: The pin directions in Table 3-1 are based on the body of the ZM8300G module.

Table 3-2 provides definitions for pins of the ZM8300G LGA module.

Table 3-2-1 Definitions for Interfaces Provided by the ZM8300G Module

Pin	Signal	Type	Description	Parameter	Minimum Value (V)	Typical Value (V)	Maximum Value (V)	Remarks
1	GND	GND	Grounding	-	-	-	-	
2	MAIN_ANT	-	Main antenna interface	-	-	-	-	50 Ω
3	GND	GND	Grounding	-	-	-	-	
4	GND	GND	Grounding	-	-	-	-	
5	STATE	DO	Module status indication signal	VOH	1	1.8	1.9	1.8 V Power domain
				VOL	0	-	0.45	
6	WAKEUP_IN	DI	AP waking up module signal	VIH	1	-	2.1	
				VIL	0	-	0.63	
7	WAKEUP_OUT	DO	module waking up AP signal	VOH	1	1.8	1.9	
				VOL	0	-	0.45	
8	PSM_MON	DO	Module deep sleeping indication signal	VOH	1	1.8	1.9	
				VOL	0	-	0.45	
9	GND	GND	Grounding	-	-	-	-	
10	GND	GND	Grounding	-	-	-	-	
11	GPS_ANT	-	GPS antenna interface	-	-	-	-	50 ohms
12	GND	GND	Grounding	-	-	-	-	
13	GND	GND	Grounding	-	-	-	-	
14	GND	GND	Grounding	-	-	-	-	
15	DEBUG_UART_RX	DI	Debug serial port RX signal	VIH	-	-	-	Led out by means of external design
16	DEBUG_UART_TX	DO	Debug serial port TX signal	VOH	-	-	-	
17	BLSPA_0	B	Two groups of four-wire BLSP signals being configured as UART, SPI, I ² C, and GPIO interfaces	VIH	1	-	2.1	1.8 V power domain
18	BLSPA_1			VIL	0	-	0.63	
19	BLSPA_2			VOH	1	1.8	1.9	
20	BLSPA_3							
21	BLSPB_0							
22	BLSPB_1							

Pin	Signal	Type	Description	Parameter	Minimum Value (V)	Typical Value (V)	Maximum Value (V)	Remarks
23	BLSPB_2			VOL	0	-	0.45	
24	BLSPB_3							
25	GND	GND	Grounding	-	-	-	-	
26	PCM_DIN	DI	PCM voice data input signal	-	-	-	-	1.8 V power domain
27	PCM_DOUT	DO	PCM voice data output signal	-	-	-	-	
28	PCM_CLK	DO	PCM voice clock signal	-	-	-	-	
29	PCM_SYNC	DO	PCM voice synchronization signal	-	-	-	-	
30	GND	GND	Grounding	-	-	-	-	
31	RESET_N	DI	Module hardware reset signal	-	-	-	-	
32	POWN_ON	DI	Module startup/shutdown signal	-	-	-	-	
33	GND	GND	Grounding	-	-	-	-	
34	RESERVED	-	Pin reserved for multiplexing	-	-	-	-	For example, to multiplex the GPIO function
35	RESERVED	-	Pin reserved for multiplexing	-	-	-	-	
36	GND	GND	Grounding	-	-	-	-	
37	VIO	PO	1.8 V output power of the module	-	-	1.8	-	20 mA
38	GND	GND	Grounding	-	-	-	-	
39	USB_ID	DI	USB 2.0 ID signal	-	-	-	-	
40	USB_VBUS	AI	USB2.0 PHY detection signal	-	-	-	-	
41	GND	GND	Grounding	-	-	-	-	
42	ADC1/MPP1	AI	ADC/current sinks	-	0		1.8	
43	GND	GND	Grounding	-	-	-	-	
44	ADC0/MPP0	AI	ADC/current sinks	-	0		1.8	
45	GND	GND	Grounding	-	-	-	-	
46	USIM_PWR	PO	USIM signal power	-	-	1.8/2.85	-	Supporting 1.8 V/2.85 V SIM card
47	GND	GND	Grounding	-	-	-	-	
48	VSYS	PI	Power supply for module	-	3	3.6	4.2	
49	VSYS	PI	Power supply for module	-	3	3.6	4.2	

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Pin	Signal	Type	Description	Parameter	Minimum Value (V)	Typical Value (V)	Maximum Value (V)	Remarks
50	GND	GND	Grounding	-	-	-	-	
51	GND	GND	Grounding	-	-	-	-	
52	USB_DP	AI/O	USB2.0 differential signal DP	-	-	-	-	90Ω
53	USB_DM	AI/O	USB2.0 differential signal DM	-	-	-	-	90Ω
54	GND	GND	Grounding	-	-	-	-	
55	USIM_DET	DI	Detection of the SIM card hot plugging function	-	-	-	-	Select the card slot that supports the hot plugging function.
56	USIM_RESET	DO	SIM card reset signal	-	-	-	-	Supporting 1.8 V/2.85 V SIM card
57	USIM_DATA	B	SIM card data signal	-	-	-	-	
58	USIM_CLK	DO	SIM card clock signal	-	-	-	-	
T1	JTAG_PS_HOLD	-	Power setup holding signal	-	-	-	-	Led out using a test point or connector
T2	JTAG_TDI	-	TDI signal of the JTAG interface	-	-	-	-	
T3	JTAG_TMS	-	TMS signal of the JTAG interface	-	-	-	-	
T4	JTAG_TDO	-	TDO signal of the JTAG interface	-	-	-	-	
T5	JTAG_TCK	-	TCK signal of the JTAG interface	-	-	-	-	
T6	JTAG_RESOUT_N	-	JTAG debug reset output	-	-	-	-	
T7	JTAG_TRST_N	-	TRST signal of the JTAG interface	-	-	-	-	
G1	PG1	-	POWER PAD	-	-	-	-	Geothermal pads
G2	PG2	-	POWER PAD	-	-	-	-	

Table 3-2-2 Electrical characteristics of the IO interfaces

Parameter		Description	Minimum Value	Typical Value	Maximum Value	Unit
VIH	High-level input voltage		0.65*Vio	-	Vio+0.3	V
VIL	Low-level input voltage		0	-	0.35*Vio	V
VSHYS	Schmitt hysteresis voltage		15	-	-	mV
IL	Input leakage current	Vio=max, Vin=0V to Vio	0	-	0.2	uA
VOH	High-level output voltage	Iout=Ioh	Vio-0.45	-	Vio	V
VOL	Low-level output voltage	Iout=Iol	0	-	1.45	V

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Parameter		Description	Minimum Value	Typical Value	Maximum Value	Unit
IOH	High-level output current	Vout=Voh	3		-	mA
IOL	Low-level output current	Vout=Vol	-	-	-	mA
IOH_XO	High-level output current	XO digital clock outputs only	6	-	-	mA
IOL_XO	Low-level output current	XO digital clock outputs only	-	-	-	mA
CIN	Input capacitance		-	-	5	pf

3.2.2 Pin Distribution

Figure 3-1 illustrates the distribution of LGA pins of the ZM8300G module (top view).

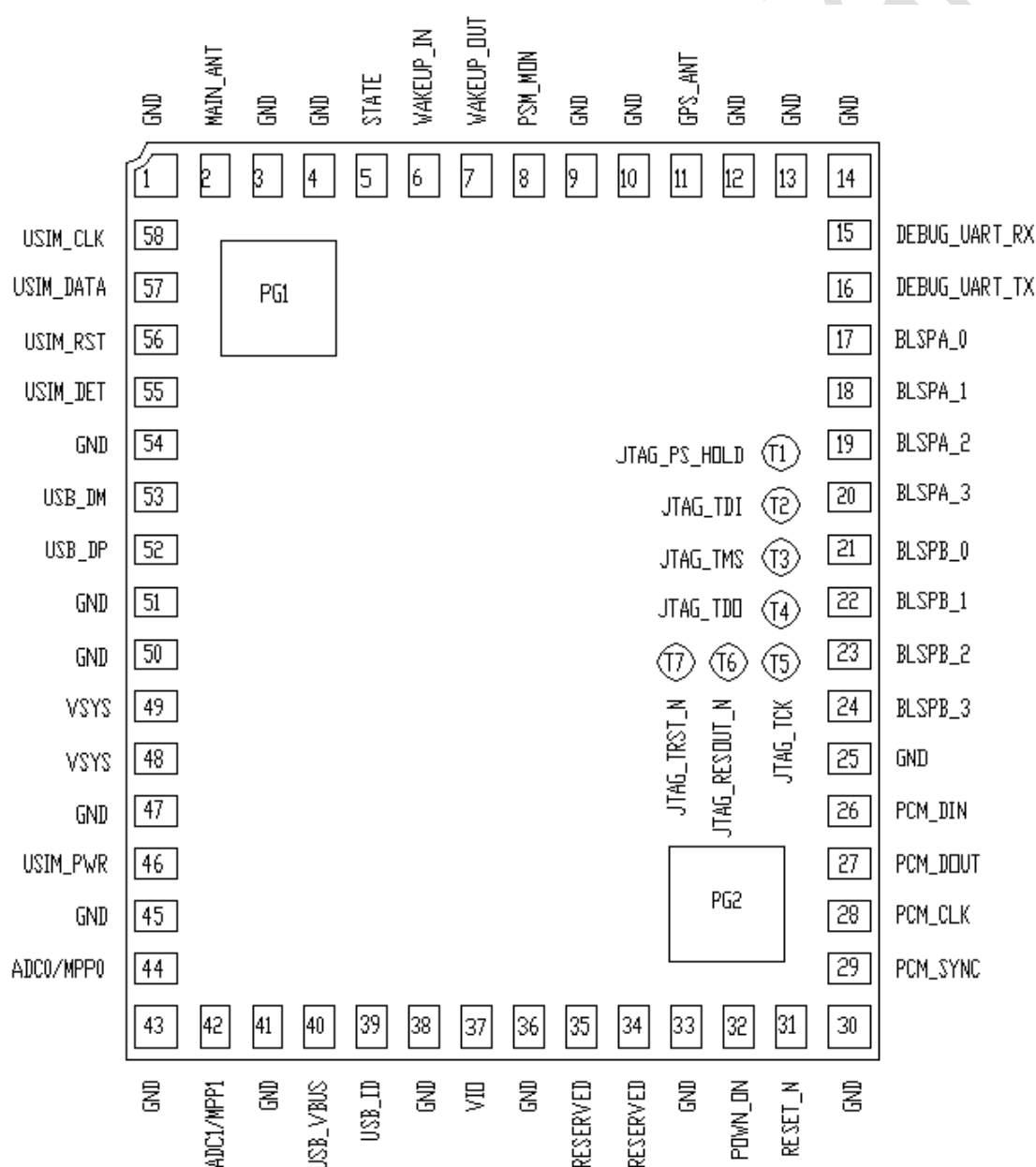


Figure 3-1 Distribution of LGA Pins of the ZM8300G Module (Top View)

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3.3 Power Interfaces

3.3.1 Overview of Power Pins

The LGA interface unit of the ZM8300G module provides the following power pins:

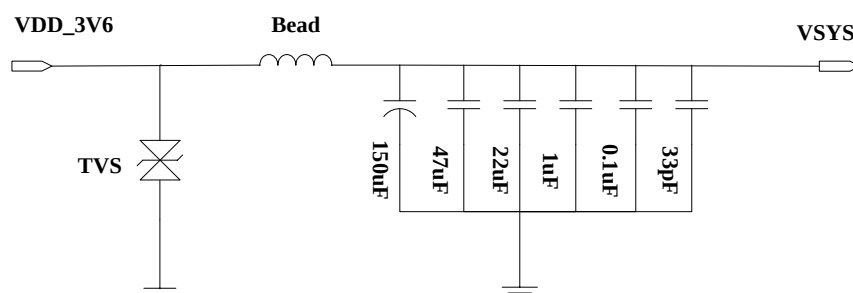
- VSYS: Power supply for module
- VIO: power output pin of the module

3.3.2 VSYS Primary Power

The ZM8300G module uses the VSYS pins (PIN 48 and PIN 49 is the interface for LGA), which are Power supply for module, to receive power provided by an external power supply. The input voltage should be within the range of 3.0 V to 4.2 V (with the typical value being 3.6 V), and the input current should not be less than 1 A.

Considering all external applications of the ZM8300G module, focus on the specifications of the external power supply. As the network environments differ from each other dramatically, when the ZM8300G module sends signals at the maximum transmit power, the peak operating current for module is more than 600mA, which continued for 10ms. In this case, ensure that the voltage drop of the external power supply is not lower than the operating voltage of the ZM8300G module (3.0 V). Otherwise, abnormal case such as a ZM8300G module reset may occur.

For external power supplies, ensure that they provide adequate and steady input capabilities. Buck or Boost/LDOs/Battery with the output capability not less than 1 A are required. In addition, ensure that the power circuit on the external system board is as short as possible and is wide enough and that a good backflow is formed on the ground plane. Connect energy storage capacitors of at least one hundred uF in parallel at power interfaces of the module, with the goal of reducing instantaneous power fluctuations. Moreover, it is recommended that customers add a ferrite-bead (or a same-package zero-ohm resistor) to the VSYS power circuit in order to reduce EMI. Ensure that the rated current of the selected ferrite-bead meets the requirement. In addition, carry out ESD measures for the power interfaces. Figure 3-2 illustrates the recommended power supply circuit.



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Figure 3-2 Recommended Power Supply Circuit

3.3.3 VIO Power

The ZM8300G module uses the VIO pin (PIN 37 on the LGA interface unit) to output 1.8 V power, whose output capacity is 20mA. The 1.8 V power can be used for level conversion or pull-up. It is recommended that the 1.8 V power could not be used as a consumable power supply. If the VIO pin is not used, leave it unconnected.

3.4 Control Signal Interfaces

3.4.1 Overview of Control Signals

The ZM8300G module provides the following LGA interface control signals: startup/shutdown signal, hardware reset signal, wake-up signal, and status indication signal. For details, see Table 3-3.

Table 3-3 Control Signals of the ZM8300G Module

Pin	Signal	I/O	Description	Remarks
32	POWN_ON	I	Startup/shutdown signal	
31	RESET_N	I	Hardware reset signal	
6	WAKEUP_IN	I	Signal used by a host to wake the module	Being developed
7	WAKEUP_OUT	O	Signal used by the module to wake a host	
8	PSM_MON	O	Module deep sleep signal	
5	STATE	O	Module status indication signal	

3.4.2 POWN_ON Signal

The POWN_ON pin is used for module power on/off function, low level trigger, 1.8V pull-up internal for module. After the power supply is normal for module, the module power on when POWN_ON is driven low which must stay at least 500ms; after power on, if the POWN_ON

is driven low which stay at least 1200ms. The power off sequence is accomplished. note that if the user want the module to power off after power supply is off, the POWN_ON should be driven low for 1200ms and idle state should be at least 200ms. Power on/off sequence timing diagram showed as FIG.3-3

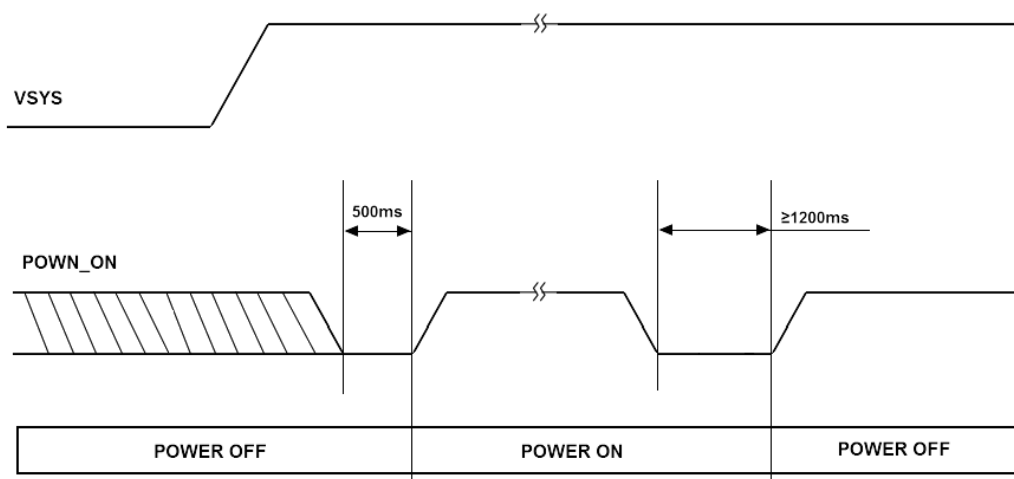


Figure 3-3 Sequence timing of power on/off

For the design of the POWN_ON pin, the following schemes are available:

Scheme 1: If a customer wants to control the startup/shutdown of the module, connect the POWN_ON signal pin to an AP and enable the AP to control the POWN_ON signal pin.

Scheme 2: If a customer wants to control the startup/shutdown of the module using a button, design a button circuit on the system board. When using this scheme, pay attention to ESD protection.

Scheme 3: If a customer requires that the module starts up immediately after being powered on, ground the POWN_ON pin.

Figure 3-4 illustrates the three schemes.

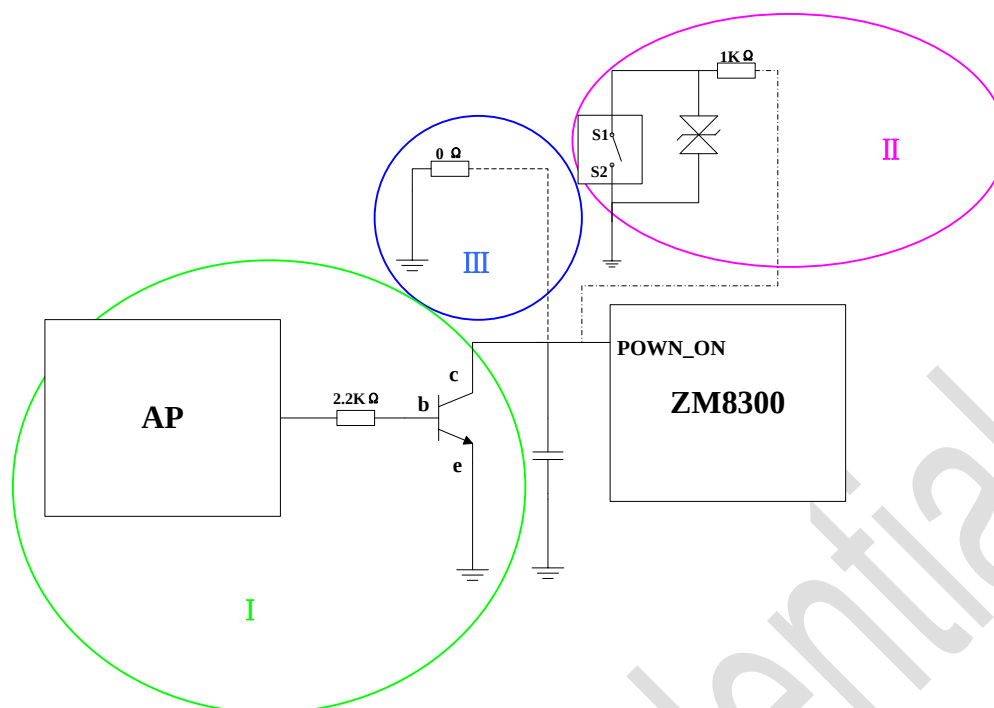


Figure 3-4 Schemes for Controlling the Startup/Shutdown of the ZM8300G Module

Note that if scheme 3 is used, the module cannot enter the PSM sleep state. If a customer's products prefer low power consumption, scheme 1 is recommended.

PIN 35 of the ZM8300G module can also provide the startup function. Specifically, after an external logic high level is connected to the ZM8300G module, pull up PIN 35 to the high-level state for 16 ms or more (1.25 V to 2.10 V, with the typical value being 1.5 V). Then, the module starts up. Note that PIN 35 cannot provide the module shutdown function. PIN 35 is a multiplexing pin. Therefore, to use PIN 35, communicate with ZTE FAE team in advance.

3.4.3 RESET_N Signal

RESET_N is used for module hard reset function, low level trigger, 1.8V pull-up internal for module. After the module power on, RESET_N is driven low which must stay at least 500ms, note that the period for low level is no more than 8s or the module will power off. Hard reset sequence timing diagram showed as FIG.3-5

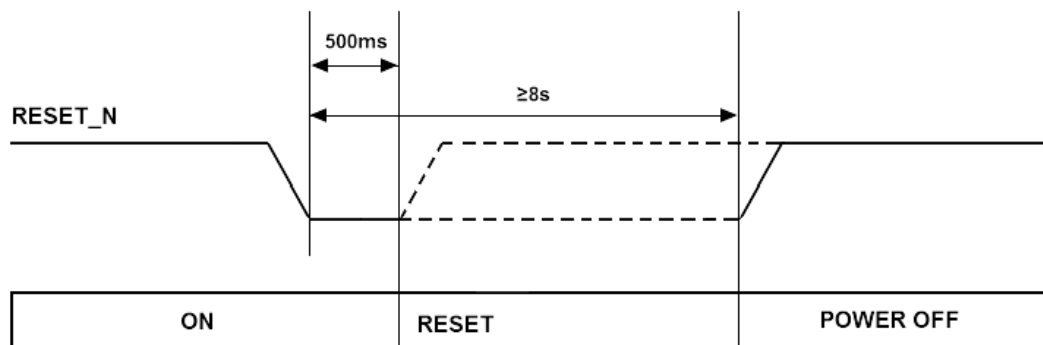


Figure 3-5 Sequence timing of Hard reset

For the design of the RESET_N pin, two schemes are available, namely, being controlled by an AP on the system board or being enabled by a button. Figure 3-6 illustrates the two schemes.

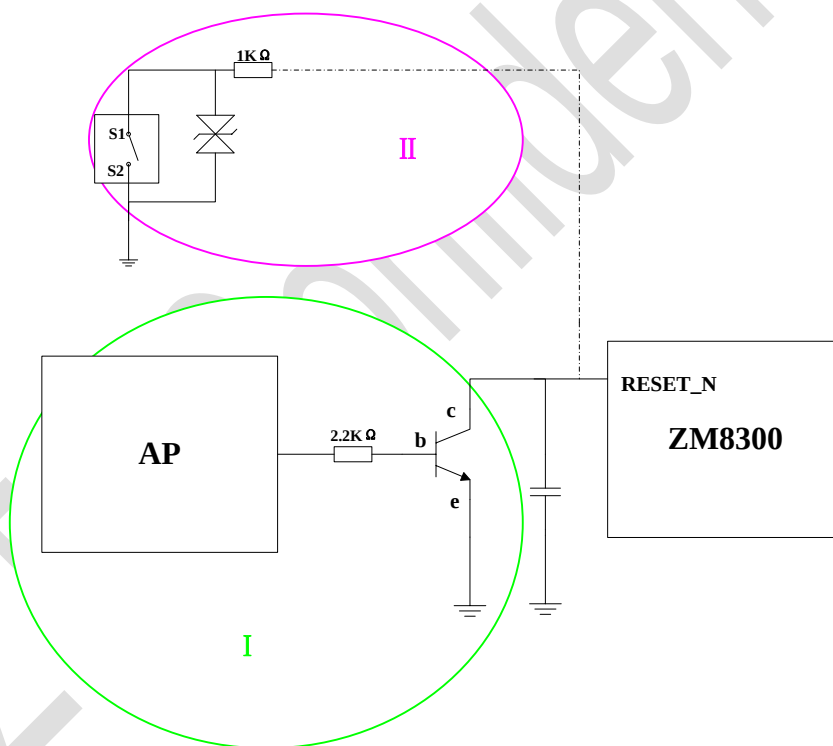


Figure 3-6 Schemes for Controlling the Hardware Reset of the ZM8300G Module

3.4.4 WAKEUP_IN Signal

WAKEUP_IN is used to wake up module, default state is low level. when the pin is driven from low to high, which wake up the module. note that when AP control module to wake up, the high level should be at least 100ms. the anti-dithering for signal should be considered, parallel capacitor is suggested to add near the pin.

Figure 3-7 illustrates the external drive circuit recommended for the WAKEUP_IN pin. Alternatively, the 1.8 V IO of an external AP can be used to directly communicate with the WAKEUP_IN pin.

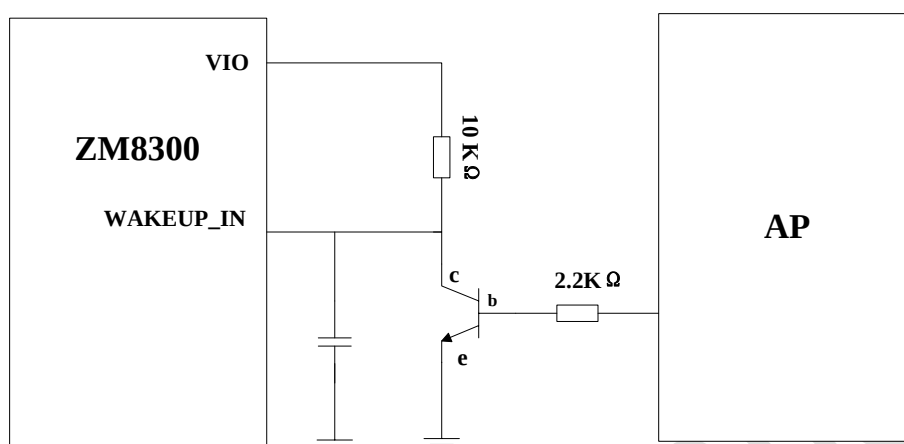


Figure 3-7 Drive Circuit Recommended for the WAKEUP_IN Pin

Note that the WAKEUP_IN signal cannot wake the ZM8300G module that is in the PSM deep sleep state.

3.4.5 WAKEUP_OUT Signal

WAKEUP_OUT for ZM8300G module is used to wake up AP, default state is low level. when the signal should be 100ms high level, which wake up AP.

3.4.6 PSM_MON Signal

PSM mode is UE Power Saving Mode. The fake power off state is applied in 3GPP REL12. The module is on the register state but signalling can not be achieved. The attach or PDN connection is not needed. The purpose is to save the power. Terminal calling is not needed to answer immediately, when the terminal could get terminal calling service or data transmission for activated state. The function should be supported for network.

For the waking up from PSM, ZM8300G could positively be waked up, besides the module could be automatically waked up according to TAU TIME protocol. The module in PSM state could be waked up for triggering the POWN_ON or PIN35 RESERVED no matter that the timer of TAU is full or not.

The specific trigger mode is same as power on sequence. The user could wake up the module from external AP but should note that the RESERVED is multiplex pin. If the user would like to use the function, please contact the ZTE FAE team in advance.

The PSM_MON is the indication signal for PSM mode. when the module is on the PSM mode, the output of PSM_MON is low; when the module is on activated mode, the output of

PSM_MON is high.

Note: Please connect PSM_MON to the MCU I/O that supports wakeup function.

3.4.7 STATE Signal

The STATE is the indication for module operating state. The state could be designed to be state indicator interface. The output pulse signal of the interface is used to control the single color LED indicator. Defined LED state for ZM8300G showed in TABLE3-4

Table 3-4 Status Explanation for the LED Indicator

Indicator Status	Meaning
solid light	connected to the network
flash	data transmission
solid off	sleep/PSM/not connected/power off

In actual applications, the STATE pin cannot directly drive the LED indicator and needs to work with a transistor. Select a current limiting resistor for the LED indicator based on the actual voltage drop and rated current of the LED indicator. When designing an LED indicator, take ESD measures. Figure 3-8 illustrated the reference circuit.

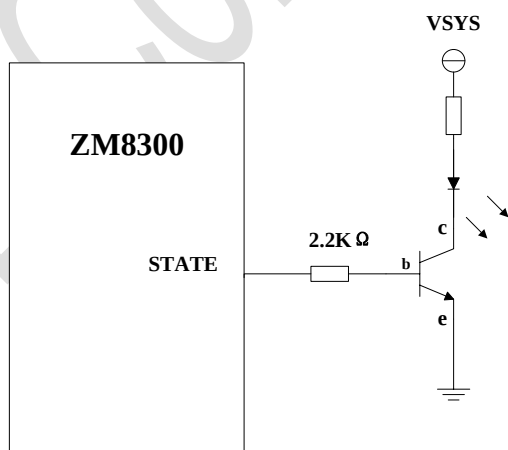


Figure 3-8 STATE Status Indicator Circuit

3.5 DEBUG_UART Interface

The ZM8300G module provides a two-wire DEBUG_UART serial port for module debugging. Tests points or JTAG&UART debugging connectors (see section 3.12.2) should be designed for the two signals. Table 3-5 provides information about pins of the debug

interface. Note that the serial port is used only for module debugging and must not be used for AT command interaction.

Table 3-5 Description of the DEBUG_UART Interface

Pin	Signal	I/O	Description	Remarks
15	DEBUG_UART_RX	I	To receive data	1.8 V power domain
16	DEBUG_UART_TX	O	To transmit data	1.8 V power domain

3.6 BLSP Interfaces

3.6.1 Pin Description

The design of ZM8300G interface include two groups 4-line BLSP (BAM (Bus access manager) Low-speed Peripheral) interface. the interface is configured through UART、SPI、I2C and GPIO by software. the default configuration of 2-line AT UART serial interface is BLSPB_0/1. Description of interface configuration for BLSP showed table3-6.

Table 3-6 Configuration of BLSP Resources

Con figu ration	BLSPA	BLSPA_0 (PIN17)	BLSPA_1 (PIN18)	BLSPA_2 (PIN19)	BLSPA_3 (PIN20)
	BLSPB	BLSPB_0 (PIN21)	BLSPB_1 (PIN22)	BLSPB_2 (PIN23)	BLSPB_3 (PIN24)
1	4-pin UART	UART_TX DO	UART_RX DI	UART_CTS DI	UART_RTS DO
2	2-pin UART + 2-pin I2C	UART_TX DO	UART_RX DI	I ² C_SDA B	I ² C_SCL B
3	4-pin SPI	SPI_MOSI B	SPI_MISO B	SPI_CS_N B	SPI_CLK B
4	2-pin GPIO + 2-pin I ² C	GPIO_XX B	GPIO_XX B	I ² C_SDA B	I ² C_SCL B
5	4 GPIOs	GPIO_XX B	GPIO_XX B	GPIO_XX B	GPIO_XX B
6	2-pin UART +2-pin GPIO	UART_TX DO	UART_RX DI	GPIO_XX B	GPIO_XX B

3.6.2 UART Interfaces

The BLSP pins of the ZM8300G module can be configured as two-pin and four-pin serial bus UART interfaces. The ZM8300G module can perform serial data transmission and AT communication with external devices using the UART interfaces. In addition to traditional UART characteristics, the UART interfaces provided by the ZM8300G module have the

following characteristics:

- 1) The UART_DM interface supports high-speed UART running, with the maximum rate reaching 4 Mbit/s.
- 2) Strengths of the UART_DM block: The RX and TX rate control data movers have separate CRCI channels. An SRAM can achieve a large RX and TX FIFOX and obtain a fast system bus (AHB interface). When the data movers are unavailable, the traditional interrupt is directly saved to the microprocessor.
- 3) The TX and RX channels of a UART_DM interface primarily differ from those of a basic UART interface in the following aspects:
 - a) FIFO is implemented in the SRAM.
 - b) FIFO control and IRQ generation are implemented in the DM control block.
- 4) The UART interfaces can be used as diagnostic interfaces.

Note that the UART level of ZM8300G is 1.8V. If external AP interface is 3.3V, the level shifting circuit is applied(level shifting IC:TXB0104RUTR) when ZM8300G carry out AT communication. The reference design circuit for UART is showed as FIG3-9

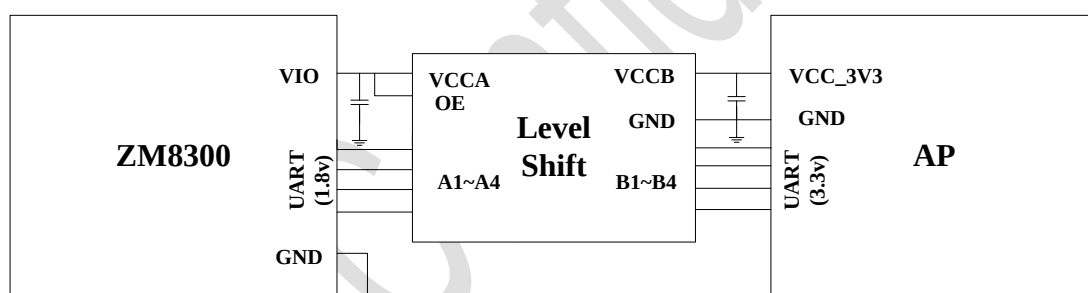


Figure 3-9 UART Reference Circuit

3.6.3 SPI Bus Interface

The SPI is a four-wire (MISO, MOSI, CS, and CLK) synchronous serial data link. The SPI bus interface has the following characteristics:

- 1) When the SPI bus interface works as the master device, the clock frequency of BLSPA can reach 50 MHz and that of BLSPB can reach 38 MHz.
- 2) When the SPI bus interface initiates data transmission as the master device, multiple slave devices can be supported by means of the chip select (CS) signal.
- 3) Explicit communication framing, error checking, and defined data word lengths are absent. Therefore, data transmission must strictly observe the raw bit level.
- 4) When working as the SPI master device, the SPI bus interface supports the following

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system configurations (restricted by the SPI protocol). Figure 3-10 illustrates the system configurations.

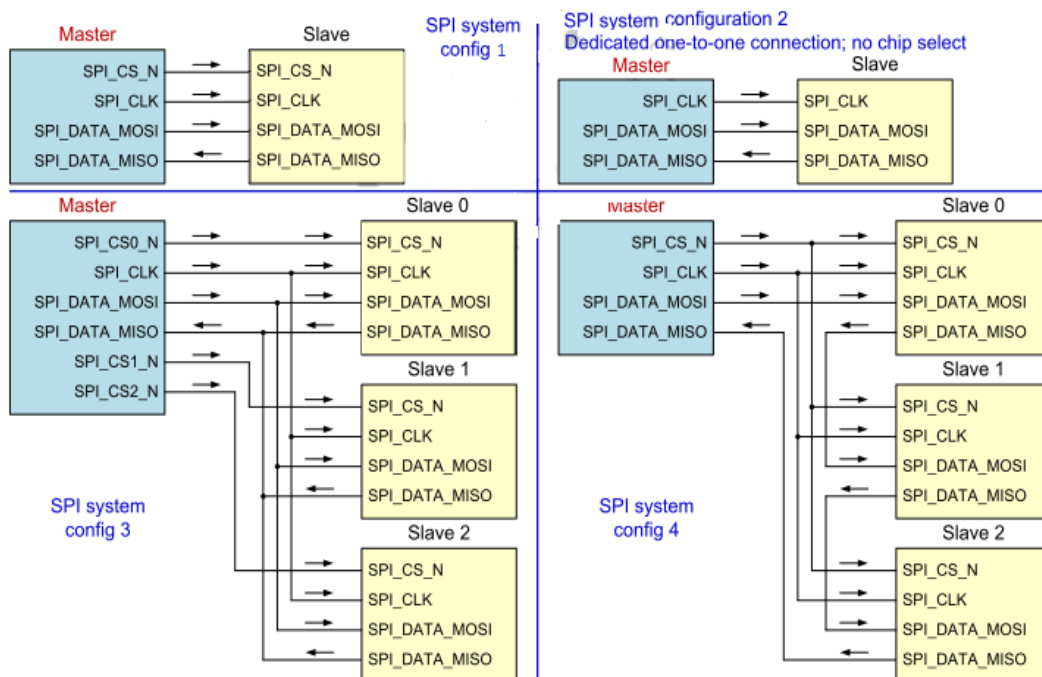


Figure 3-10 SPI System Configurations

Pay attention to the following points during design:

- 1) If the SPI bus reaches the highest frequency during running, its priority must be higher than the priorities of other BLSP bus interfaces.
- 2) If one group of SPI buses is shared by multiple devices, ensure that these devices are close to each other, with the goal of avoiding signal integrity problems caused by long bus branches.
- 3) The SPI interface provided by the ZM8300G module is a 1.8 V IO interface. If the ZM8300G module needs to work with a peripheral that uses a different level, add a level conversion circuit. Figure 3-11 illustrates the recommended level conversion circuit. The level conversion chip (TI: TXB0104RUTR) is recommended.

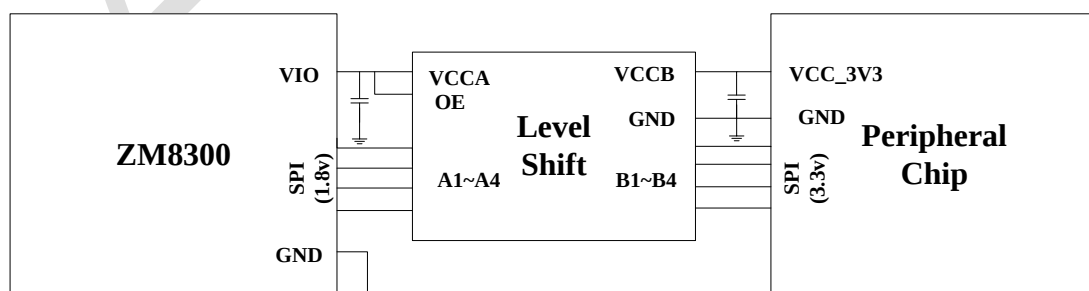


Figure 3-11 SPI Level Conversion Circuit

3.6.4 I²C Bus

I²C is a two-wire bus used for communication between ICs and supports all IC processes (NMOS, CMOS, and bipolar). The two signal lines, namely, the serial data (SDA) line and the serial clock (SCL) line, transfer information between connected devices. Each device (a microcontroller, memory, LCD driver, audio DAC, or keyboard interface) is identified by a unique address and used as a transmitter or a receiver, depending on the provided functions.

The I²C interface has the following characteristics:

- 1) The two-wire bus is used for communication between chips.
- 2) Supports all ICs on the I²C bus. Each device has a unique address and can be used as a transmitter or a receiver.
- 3) Supports external functions, including cameras, microcontrollers, FM radio chips, LCD drivers, audio DACs, and keyboard interfaces.
- 4) An I²C controller provides an interface between advanced high-performance buses (AHBs) and an industry-standard I²C serial bus to handle the I²C protocol and release chip processors and interfaces, so that the chip processors and interfaces can handle other services.
- 5) The I²C interface works in standard mode (100 kbit/s) or high-speed mode (400 kbit/s). The operating frequency of the ZM8300G I²C interface reaches 400 kHz. When the ZM8300G I²C interface works only in master mode, the operating frequency may reach 1 MHz.
- 6) When using the I²C bus, configure the corresponding BLSP pin as an open drain output GPIO. In this case, an external device needs to use VIO to provide pull-up. The group of I²C buses provided by the ZM8300G module (BLSPA_2 and BLSPA_3) already has pull-up. To configure other I²C buses, a customer needs to add an external pull-up. Figure 3-12 illustrates an I²C reference circuit.

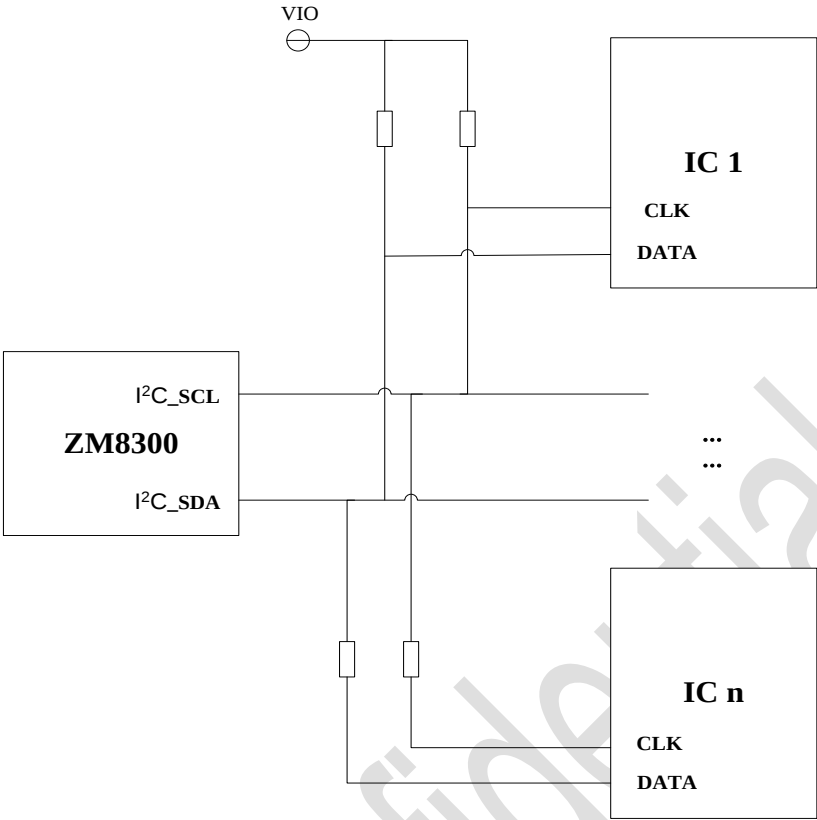


Figure 3-12 I²C Reference Circuit

3.7 GPIO Interfaces

In addition to BLSP pins, which can be configured as general-purpose input/output (GPIO) interfaces, reserved pins and some dedicated pins of the ZM8300G module can also be multiplexed as GPIO interfaces. For details, see Table 3-7. Customers can use these IO interfaces for control functions. By default, all IO interfaces of the ZM8300G module are PD. The multiplexing functions of the reserved pins are being developed.

Table 3-7 ZM8300G GPIO Resources

Multiplexed as GPIO Interfaces				
Pin	Signal	I/O	Description	Remarks
34	RESERVED	B	GPIO	VIO (1.8 V) power domain
35	RESERVED			
26 to 29	PCM audio interface			
5 to 8	Control signal interface			

3.8 USIM Interface

3.8.1 Pin Description

The baseband processor of the ZM8300G module integrates 2.85 V and 1.8 V USIM interfaces that support automatic detection and meet requirements specified by the ETSI and requirements specified for IMT-200 SIM cards. Figure 3-8 describes the USIM interface signals.

Table 3-8 Description of USIM Signals

Pin	Signal	I/O	Description	Remarks
58	USIM_CLK	O	USIM clock signal	
57	USIM_DATA	B	USIM data signal	The 10K resistor inside the module is pulled up to the USIM_PWR.
56	USIM_RESET	O	USIM reset signal	
46	USIM_PWR	PO	USIM power	The module adapts to 1.8 V/2.85 V USIM cards.
55	USIM_DET	I	Detection of the USIM card hot plugging function	If the hot plugging function is unavailable, leave this pin not connected.

3.8.2 Electrical Characteristics and Design Points

Instead of reserving a slot for a USIM card, the ZM8300G module connect USIM signals using an LGA pad. During design, note that ESD circuit protection is added for all USIM signals (do not add ESD protection circuit if eSIM is designed), and ensure that the protection device is close to the card slot. To meet requirements of the 3GPP TS 51.010-1 protocol and EMC certification, locate the USIM card slot near the USIM signal interface of the ZM8300G module, to prevent signal integrity from being affected due to severely distorted waveforms that result from a long distance between the USIM card slot and the USIM signal interface. In addition, ground the USIM_CLK and USIM_DATA signal lines. Connect a 0.1 uF capacitor and a 33 pF capacitor in parallel between USIM_PWR and GND, and connect capacitors in parallel between USIM_CLK/USIM_RESET/USIM_DATA

and GND, with the goal of filtering out interference from RF signals. Then, connect a zero-ohm resistor in series to the USIM_DATA, USIM_CLK, and USIM_RESET signal lines as a measure reserved for ESD protection and EMI design. If the hot plug for SIM is applied, contact ZTE FAE team.

3.8.3 Circuit Recommended for the USIM Card Interface

Figure 3-13 illustrates the peripheral circuit recommended for the USIM card interface.

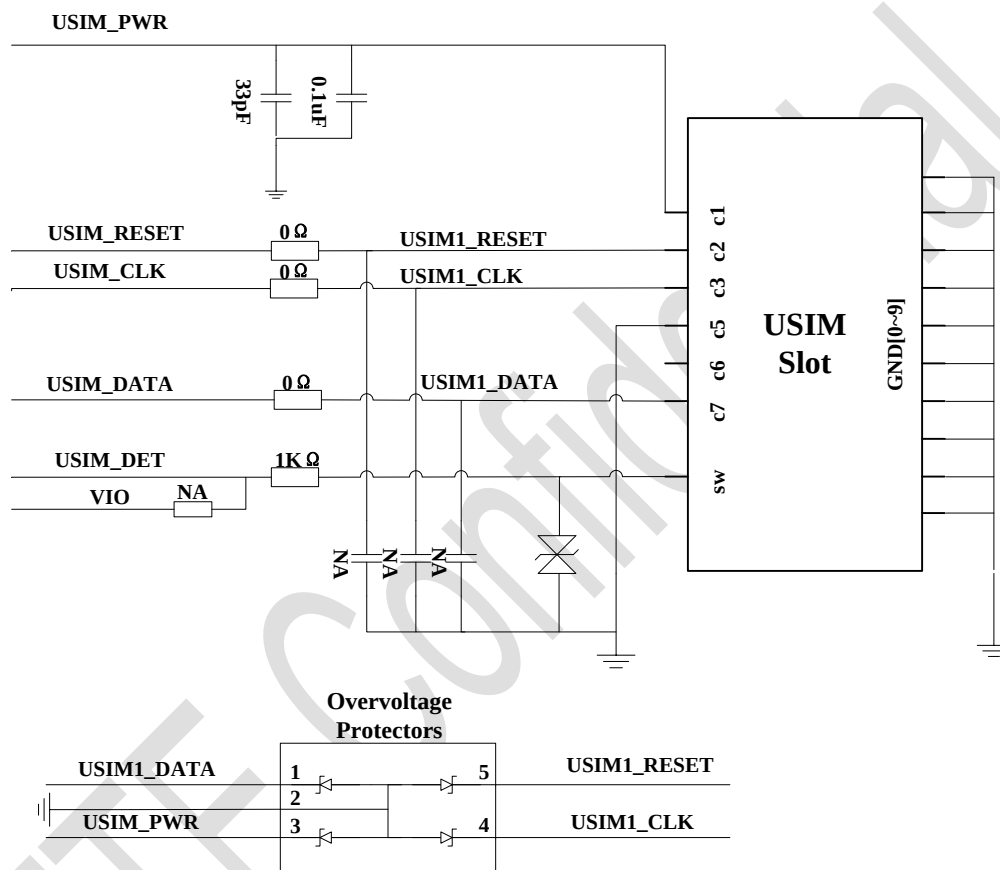


Figure 3-13 Peripheral Circuit Recommended for the USIM Card Interface

In addition to the method of designing a USIM card slot on the system board, customers can design an eSIM chip. The ST or Gemalto scheme is recommended.

3.9 USB Interface

3.9.1 Pin Description

The ZM8300G module provides an integrated USB transceiver, which complies with USB2.0 and supports the high speed mode (480 Mbit/s), full speed mode (12 Mbit/s), and low speed mode (1.5 Mbit/s). The USB interface primarily applies to AT commands, data

transmission, software commissioning, and software upgrade. Table 3-9 describes USB signals.

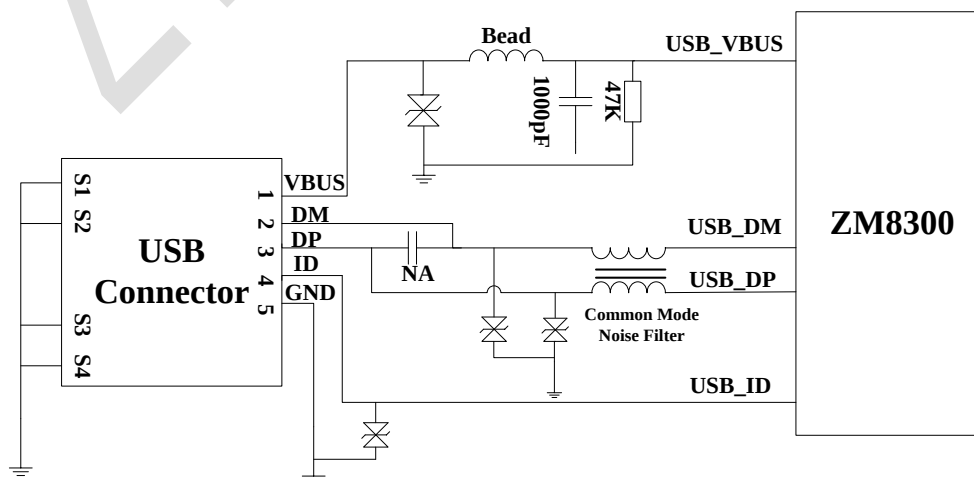
Table 3-9 Description of USB Signals

Pin	Signal	I/O	Description	Remarks
40	USB_VBUS	I	USB PHY power detection	Only used for USB PHY detection and not used as a power supply
52	USB_DP	A/I/O	USB differential data bus (positive)	90 ohm differential impedance
53	USB_DM	A/I/O	USB differential data bus (negative)	90 ohm differential impedance
39	USB_ID	I	USB_ID detection signal	OTG function; No connection when working as a device.
51	GND		GND	

3.9.2 Design Points and Recommended Circuit

For detailed information about USB 2.0 specifications, access <http://www.usb.org/home>.

Figure 3-12 illustrates a circuit recommended for the USB interface. To ensure that subsequent commissioning and upgrading operations can be smoothly performed, customers need to design a USB 2.0 connector on an external system board. ZTE recommends the following model: MOLEX: 1051330001 and LS: GU073-5P-SE-E2000. The bead in Figure 3-14 can be replaced with a resistor. If no high-speed data services are involved and the USB differential signals are properly protected, the common mode inductor can be removed.



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Figure 3-14 Circuit Recommended for the USB Interface

To ensure that the designed USB interface complies with USB 2.0 specifications, observe the following guidelines:

- 1) Ensure that USB differential signal lines have a complete reference ground and the impedance of PCB differential signal lines is 90 ohms.
- 2) Note the impact of the junction capacitor of the ESD protection device on the high-speed USB data line. Generally, select a junction capacitor with the capacitance less than 2 pf, and locate the ESD protection device near the USB interface.
- 3) Ensure that USB differential signal lines are far away from crystal lines, oscillator lines, and RF signal lines and have a complete reference ground plane both above and below. In addition, ensure that USB differential signal lines in the same layer are protected by ground cables.

3.10 Audio Interfaces

3.10.1 Pin Description

The ZM8300G module provides PCM and I²S digital audio interfaces, which share the same physical interface. That is, the ZM8300G module supports only the PCM interface or the I²S interface at a time. The audio interface can be connected to a voice CODEC chip, for example, WCD9330 from Qualcomm. Table 3-10 describe the two types of audio interfaces.

Table 3-10 Description of Digital Audio Interfaces

Pin	PCM	Description	I2S	Description
26	PCM_DIN	PCM audio data RX signal	I2S_D0	I ² S audio data D0 signal
27	PCM_DOUT	PCM audio data TX signal	I2S_D1	I ² S audio data D1 signal
28	PCM_CLK	PCM audio clock signal	I2S_SCLK	I ² S audio clock signal
29	PCM_SYNC	PCM audio synchronization signal	I2S_WS	I ² S audio chip select signal

3.10.2 Design Points

Both the PCM and I²S interfaces use digital, square wave signals. After adding a level conversion circuit, pay attention to signal integrity. To ensure signal integrity, connect a resistor in series and a capacitor in parallel to signal lines as impedance matching and filtering means. When designing a PCB, note the continuity of the signal line impedance. Figure 3-15 illustrates the recommended voice circuit. If the CODEC voice signal interface

uses the 3.3 V level, level conversion is required (TI: TXB0104RUTR). If a customer requires I²S voice, PIN 34 of the ZM8300G module can provide the I²S_MCLK signal. Note that PIN 34 is a multiplexing pin. Therefore, to use PIN 34, communicate with ZTE FAE team in advance.

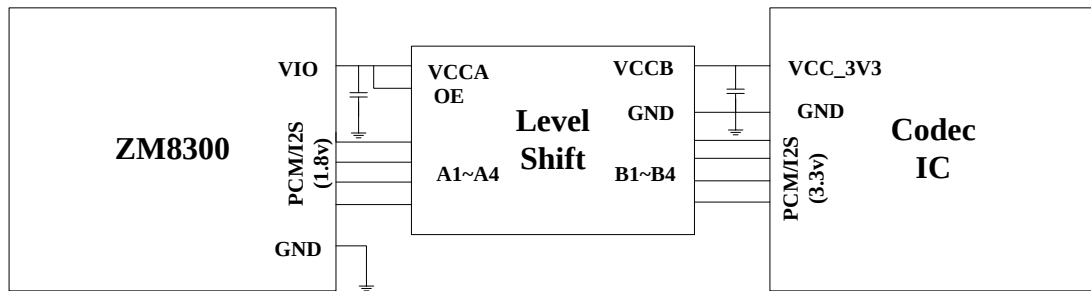


Figure 3-15 Recommended Audio Circuit

3.11 ADC/MPP Interfaces

3.11.1 Pin Description

The ZM8300G module provides two ADC/MPP interfaces (PIN 42 and PIN 44), which can be multiplexed as analog multiplexer inputs and current sinks.

- 1) When working as an ADC analog input interface, the analog multiplexer inputs interface samples external voltages and temperatures. The input voltage should be within the range of 0 V to 1.8 V.
- 2) When working as an input current source, the current sinks interface drives an LED indicator and controls its brightness at 5 mA intervals, with the input current within the range of 5 mA to 40 mA. When the MPP pin is used to light an indicator, the power consumption of the ZM8300G module increases.

3.11.2 Design Points

The following figures illustrate the two functions multiplexed on the MPP interface.

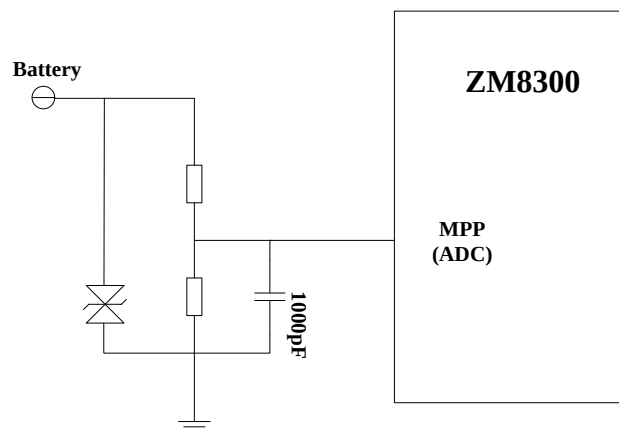


Figure 3-16 ADC Interface Circuit

When the two pins are used to sample ADC analogs (for example, to sample the battery voltage), ensure that the input voltage is within the allowed range. It is recommended that a bleeder circuit be designed and a bleeder resistor of hundreds of kilo-ohms be used, with the goal of reducing the leakage current. In addition, provide the designed circuit with ESD protection. To improve the sampling accuracy, ensure a good reference ground for the ADC PCB circuit.

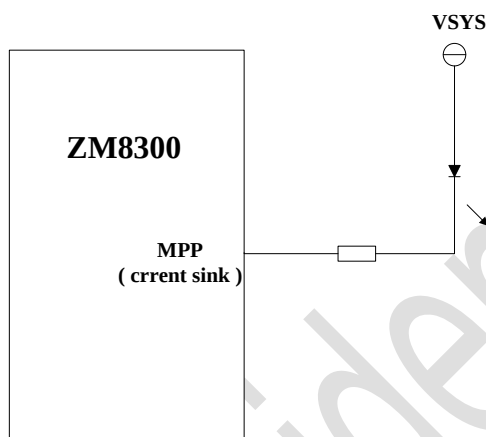


Figure 3-17 MPP Indicator Lighting

Provide ESD protection when using the interface to drive an LED indicator.

3.12 JTAG Interface

3.12.1 Pin Description

The joint test action group (JTAG) interface of the ZM8300G module complies with ANSI/IEEE Std.1149.1-1990. Table 3-11 describes JTAG signals.

Table 3-11 Description of the JTAG Signals

Pin	Signal	I/O	Description
T1	JTAG_PS_HOLD	-	Power setup holding signal
T2	JTAG_TDI	DI-PU	JTAG debug data input signal
T3	JTAG_TMS	DI-PU	JTAG debug mode selection signal
T4	JTAG_TDO	Z	JTAG debug data output signal
T5	JTAG_TCK	DI-PU	JTAG debug clock signal
T6	JTAG_RESOUT_N	DO	JTAG reset output signal

Pin	Signal	I/O	Description
T7	JTAG_TRST_N	DI-PD	JTAG debug reset signal

3.12.2 Design Points

The ZM8300G module provides a test point pad for the JTAG interface. it is recommended that customers design a connector (recommended material: PANASONIC: AXE216044D), with the goal of resolving difficult problems. Figure 3-18 illustrates the recommended connector circuit, which includes JTAG and DEBUG_URAT debug interfaces. If failing to design a connector due to limited dimensions, design JTAG and DEBUG_URAT test points on the system board.

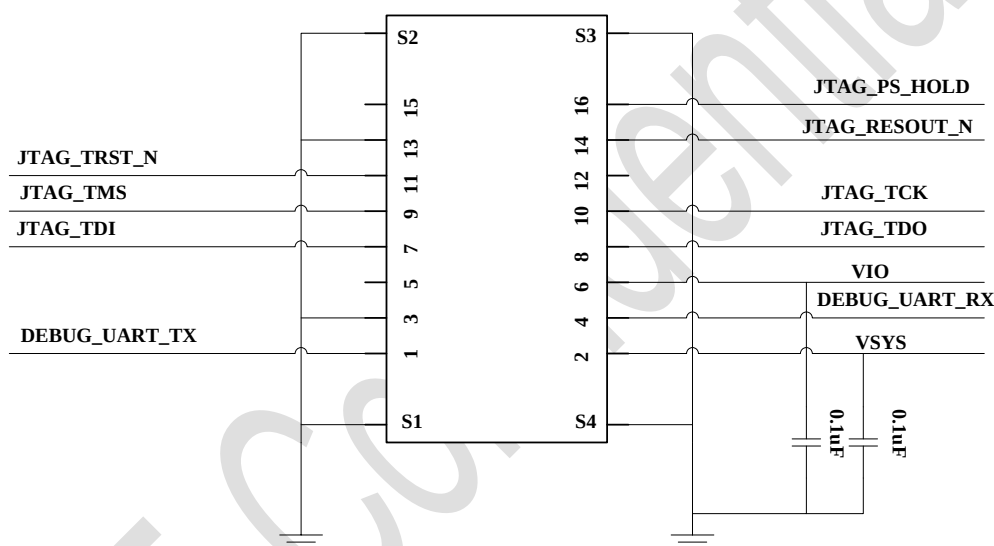


Figure 3-18 Circuit for a JTAG/UART Debug Connector

3.13 Antenna Interfaces

3.13.1 Pin Description

The ZM8300G module provides two antenna pads. Table 3-12 describes the two antenna pads (including the ground points next to the pads).

Table 3-12 Antenna Interfaces

Signal	Pin	Description	Remarks
GND	1	Grounding	
MAIN_ANT	2	RF main antenna interface	50 Ω
GND	3	Grounding	

Signal	Pin	Description	Remarks
GND	10	Grounding	
GPS_ANT	11	GPS antenna interface	50 Ω
GND	12	Grounding	

3.13.2 Antenna Design Points

Antennas are easily affected by external environments, for example, antenna locations, antenna occupied room, and surrounding devices. The ZM8300G module provides two antenna pads for antenna design, with a ground point available to each side of each pad, to ensure good grounding. Figure 3-17 illustrates a reference circuit for antenna design. The dual-L matching network helps improve the RF performance. During the design, place the component near the module, and place the antennas near the matching network, so as to reduce path loss. Figure 3-19 illustrates the recommended antenna circuit, which includes resistors, capacitors, and inductors.

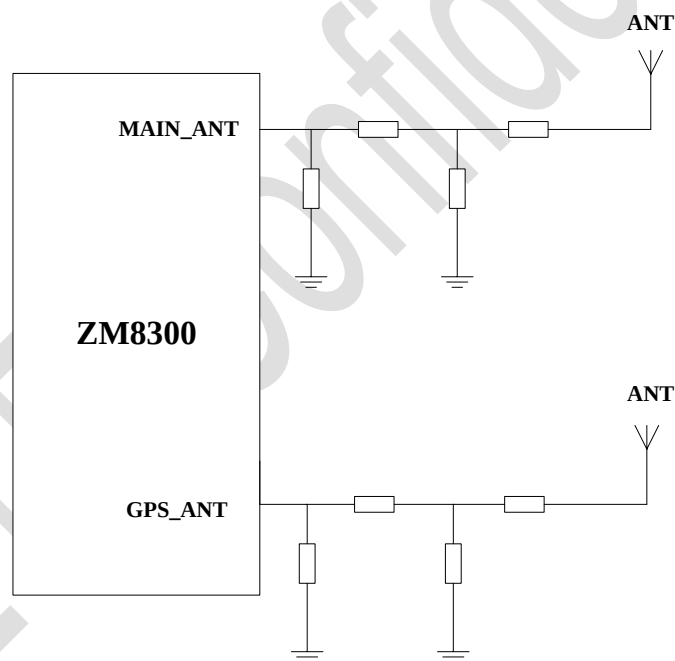


Figure 3-19 Reference Circuit for the Antenna Interfaces

For detailed requirements for antenna design, see section 4.6.

4 RF Characteristics

4.1 About This Chapter

4.1.1 Power Supply

The voltage input to the ZM8300G module should be within the range of DC 3.0 V to 4.2 V, with the typical value being 3.6 V. For details, see Table 4-1.

Table 4-1 Required Input Voltage Range

Parameter	Minimum Value (V)	Typical Value (V)	Maximum Value (V)
Input voltage	3.0	3.6	4.2

4.1.2 Operating Current

Table 4-2 provides part of operating current data of the ZM8300G module.

Table 4-2 Operating Current

Mode	Status	Average Current	Remarks
CAT M	Sleep current	0.7 mA	
	IDLE	1.07mA	2.56Sdrx Online
	Average operating current (UL)	115 mA	LTE 10MHz bandwidth embedded data call@0dBm TX,UL only,375 kbps;
	Average operating current (DL)	112 mA	LTE 10MHz bandwidth embedded data call@0dBm TX,DL only,375 kbps;
CAT NB	Sleep current	0.7 mA	
	IDLE	1.47mA	2.56Sdrx Online
	Average operating current (UL)	50 mA	LTE 10MHz bandwidth embedded data call@0dBm TX,UL only,62.5 kbps(15KHz single tone);
	Average operating current (DL)	50 mA	LTE 10MHz bandwidth embedded data call@0dBm TX,UL only,21kbps(multi tone);

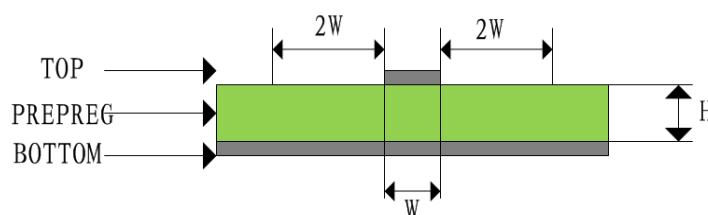
◆Note: The lab data provided by Qualcomm is used.

4.2 Reference Design for RF Layout

For the RF part of a PCB, ensure that the characteristic impedance of the RF line is 50 ohms. The impedance of an RF line is generally determined by the line width (W), dielectric constant of the material, distance away from the reference signal layer (H), and gap between the RF

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line and the ground (S). The microstrip and stripline are generally used to control the characteristic impedance of an RF line.



Microstrip Line Design on a 2-Layer PCB

To ensure RF performance and reliability, refer to the following rules specified for PCB layout:

- Use an impedance simulation tool to ensure that the characteristic impedance of an RF line is 50 ohms.
- Connect the entire ground pin that is adjacent to an RF pin to the main ground. Do not connect it to a thermal pad.
- Minimize the distance between an RF pin and an RF connector.
- Ensure an adequate forbidden area for the pad or solder joint of an antenna connector.
- Ensure a complete reference ground plane for an RF line. In addition, add a row of ground holes between the RF line and the surrounding area to effectively improve RF performance. Ensure that the distance between the ground and the RF line is equal to or greater than twice the line width ($2 \times W$).

4.3 Test Standard for Conducted RF

The ZM8300G module meets RF requirements specified in 3GPP TS 36.521-1.

4.4 Requirements for Antenna Design

4.4.1 Key Points for Antenna Design

Antennas are very important for wireless communication products, because antenna performance directly affects the communication quality of the products. Before designing antennas, select antenna types based on available space and application scenarios. Table 4-6 provides detailed information about how to select NB-IOT antennas.

Table 4-6 Detailed Information About How to Select NB-IOT Antennas

Product Type	Characteristics of Application Scenarios	Antenna Type Selection
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Smart meter reading products such as water meters, electricity meters, and gas meters	Meters are installed at remote locations, surrounding environments are complex, the signal attenuation is large, and the signal quality is poor.	1. Internal antenna 2. High-gain antenna 3. Omni-directional antenna 4. Low cost
Car detector	Car detectors are buried in the ground, and the signal quality is poor.	
Smart city products such as smart streetlights and smart garbage cans	Smart city products are installed outdoors, so they must be easy to install and require good waterproofing measures.	1. External antenna 2. Waterproof and corrosion resistant 3. Low cost
Mobile products	Mobile products provide the positioning function. When mobile products move, signals change and are unstable.	1. GPS antenna with excellent performance 2. Omni-directional antenna pattern, if possible 3. Low cost
Tracker products	Tracker products are carried by people or animals, feature small sizes, and have high requirements for the positioning function.	1. GPS antenna with excellent performance 2. Considering the impact of people or animals on the antenna efficiency 3. Small sizes 4. Low cost

Passive parameters used to measure the performance of an antenna include the antenna efficiency, VSWR, return loss (S11), polarization, and radiation pattern, which are described as follows.

4.4.2 Antenna Efficiency

The efficiency of an antenna refers to the ratio of the power radiated by the antenna to the effective input power. The power radiated by an antenna is generally less than the input power due to antenna loss and cable loss. The antenna loss is primarily reflected by the antenna efficiency. Specifically, high antenna efficiency indicates low antenna loss. The antenna efficiency is affected by the VSWR/S11 and antenna clearance area. An antenna

clearance area is an area without metal. A large clearance area indicates high antenna efficiency. If an RF output port is connected to the input port of an antenna using a cable, the loss caused by the cable needs to be considered. Generally, the loss caused by a cable is proportional to the cable length and frequency. Therefore, use short cables if possible. To enable a ZM8300G module to obtain better RF radiation performance, it is recommended that the antenna efficiency be greater than 45% (within all frequency bands).

4.4.3 VSWR

When a feeder does not match an antenna, an incident wave and a reflected wave co-exist in the feeder. For the in-phase position of the two waves, the amplitude has maximum value, and an antinode is formed. For the reverse-phase position of the two waves, the amplitude has minimum value, and a wave node is formed. The amplitudes at other points are between the antinode and the wave node. Such a combined wave is called a standing wave. The ratio of the voltage at an antinode of a standing wave to the voltage at a node of the standing wave is called the voltage standing wave ratio (VSWR). A small VSWR indicates better antenna performance. The VSWR of an antenna can be measured using a vector network analyzer. For the ZM8300G module, it is recommended that the VSWR be less than 3.0.

4.4.4 S11

The S11 indicates the transmit efficiency of an antenna. A large S11 indicates more returned power and poor antenna efficiency. The S11 can be measured using a vector network analyzer. For the ZM8300G module, it is recommended that the S11 be less than -8 dB.

4.4.5 Polarization

The antenna polarization is a parameter used to describe the spatial orientation of the antenna-radiated electromagnetic field vector. As the electric field has a constant relationship with the magnetic field, the spatial orientation of the electric field vector is generally used as the polarization direction of antenna-radiated electromagnetic waves. Generally, linear polarization, circular polarization, and elliptical polarization are available. For the ZM8300G module, linear polarization is recommended for its antennas.

4.4.6 Radiation Pattern

The radiation pattern describes the distribution of antenna radiation in space, especially the distribution in the far field region, and indicates the characteristics of a field, for example, the product of the size/field strength and the distance, radiant intensity, directivity, absolute gain, and relative gain of a specified component of the electromagnetic field.

Since the incident wave of a base station is horizontal, a wireless terminal has optimal reception performance when the radiation pattern of its receive antenna is omni-directional in the horizontal plane. For the ZM8300G module, omni-directional radiation pattern is recommended for its antennas.

4.4.7 Requirements for IoT Antenna Design

Table 4-7 lists requirements for basic parameters for designing an IoT antenna.

Table 4-7 Requirements for Antenna Design

Parameter	Requirement
VSWR	<2
Gain (dBi)	>1
Maximum input power (dBm)	25.7
Input impedance (ohm)	50
Polarization	Linear polarization

4.4.8 Precautions for Early Antenna Design

When determining a location for an antenna, observe the following guidelines: Ensure that the location and the base station served by the antenna are in the horizontal direction, with the goal of enabling the antenna to produce the highest efficiency; ensure that the location is far away from components or chips that may generate electromagnetic interference such as a switch-mode power supply, data line, and chip; ensure that the location is unreachable by hand, with the goal of preventing hands from causing antenna attenuation. In addition, consider radiation reduction and structure feasibility. Therefore, at the beginning of antenna design, invite structure engineers, ID engineers, circuit engineers, and antenna engineers to assess the layout. If a system board needs to process signals from multiple antennas, consider co-channel interference.

ZTE has certified multiple antenna vendors. If required, ZTE can recommend several antenna vendors for antenna design.

5 Mechanical Characteristics

5.1 About This Chapter

This chapter describes the mechanical structure of the ZM8300G module, covering the following aspects:

- Assembly procedure
- Repair procedure
- EMC and ESD protection

5.2 Assembly Procedure

5.2.1 Overview

The ZM8300G module is mounted on a five-layer antistatic tray with anti-shock foam, vacuumized, and placed in a carton, with the goal of preventing the module from collision or oxidization.

5.2.2 Steel Mesh

It is recommended that a 0.1 mm thick steel mesh be designed for the ZM8300G module. For the design of a steel mesh, refer to Figure 5-1 and Figure 5-2 (in mm).

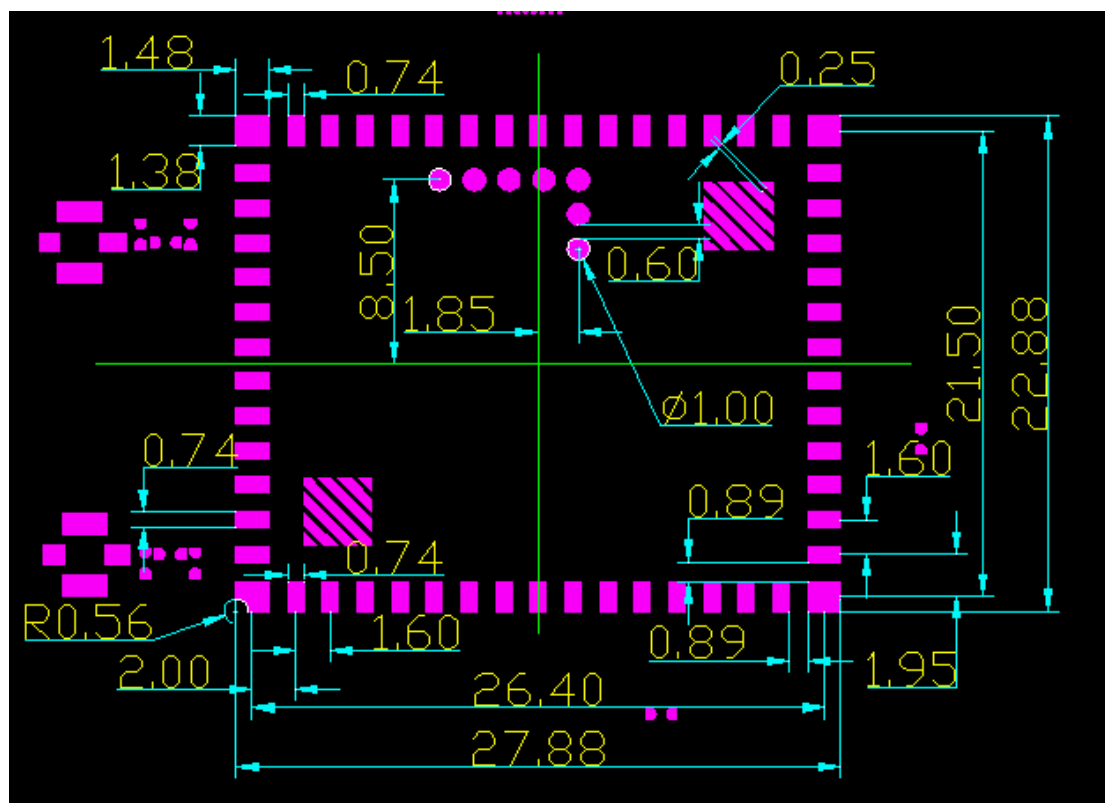
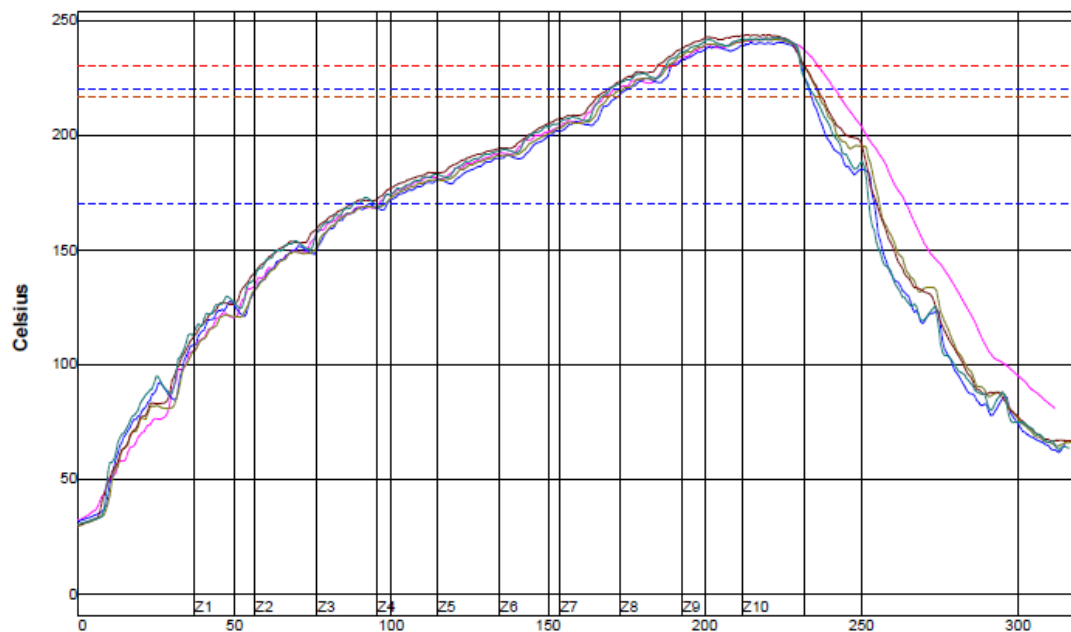


Figure 5-1 Reference Design for a Steel Mesh

5.2.3 Reflow Curve



Seconds												
PWI= 81%	Max Rising Slope		Max Falling Slope		Soak Time 170-220C		Reflow Time /230C		Peak Temp		Tot Time /217C	
D1	1.83	22%	-2.23	-23%	76.03	38%	46.78	79%	242.09	42%	75.08	40%
X9	1.88	26%	-2.62	-62%	76.82	41%	41.82	45%	240.51	10%	61.56	-14%
X13	1.91	28%	-2.51	-51%	75.85	37%	43.78	59%	241.73	35%	66.82	7%
SC6	1.98	32%	-2.54	-54%	81.53	62%	47.14	81%	243.73	75%	71.44	26%
SC8	1.99	33%	-2.55	-55%	79.78	55%	43.17	54%	242.51	50%	67.52	10%
Delta	0.16		0.39		5.68		5.32		3.22		13.52	

Figure 5-2 Reference Reflow Curve

Table 5-1 Reflow Parameter Window

Parameter	Value
Temperature ramp	1°C to 3°C per second
Cooling slope	-3°C to -1°C per second
Duration within which the temperature is between 170°C and 220°C	45 seconds to 90 seconds
Duration within which the temperature is higher than 230°C	20 seconds to 50 seconds
Highest temperature	235°C to 245°C
Duration within which	40 seconds to 90

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Parameter	Value
the temperature is higher than 217℃	seconds

5.3 Repair Procedure

5.3.1 Repair Procedure

Module dismantling – treatment in weld area – module installation – visual inspection – feature validation

5.3.2 Module Dismantling

Apply the flux around the module to be dismantled evenly, fully melt the flux and the solder paste in the weld area using a heating device, and dismantle the module using a dedicated pick-up jig.

5.3.3 treatment in weld area

- Remove existing solder using a soldering iron and a suction line to keep the weld area flat.
- Clean the pads and remove residues.
- Fill the pads with a certain amount of solder paste using a rework steel mesh.

5.3.4 Module Installation

Mount the module accurately on the pads using a dedicated jig, and heat the main board according to the preset temperature curve. After the main board is cooled, use X-RAY to ensure that the module is reliably welded.

5.3.5 Visual Inspection

Ensure that the module is flat without deformation, no residues exist on the surfaces and surrounding areas, and surrounding devices are not damaged.

5.3.6 Feature Validation

Test the repaired module and ensure that the module is operating properly.

5.4 EMC and ESD Protection

Suggestions for EMC and ESD protection are as follows:

- Provide TVS protection for external interfaces of the ZM8300G module, for example, the USB interface, USIM card slot, and key switch. Adopt the V-shape line, instead of the T-shape line, for PCB wiring of protection components.
- Observe the 3W principle when routing power lines and signal lines for peripheral circuits of the ZM8300G module, with the goal of effectively reducing the coupling between signals and providing signals with clean return paths.
- To ensure signal integrity when designing peripheral power circuits, locate decoupling capacitors near the power pins of the ZM8300G module, place high-frequency and high-speed circuits and sensitive circuits far away from PCB edges, isolate the layouts from each other to minimize mutual interference, protect sensitive signals, and perform shielding design for circuits or components that may be near an interference module on the system board side.
- Ensure a complete ground plane around the ZM8300G module, and do not split the ground plane.
- Ensure that surrounding environments and operators involved in the production, assembly, and testing of the ZM8300G module meet ESD requirements.

Requirements for ESD protection are as follows:

- The ground must be laid with an antistatic floor, with the system resistance in the range of 1×10^4 ohms to 1×10^9 ohms.
- Both electrical protection grounds and independently-laid antistatic grounds can be used as antistatic grounds, with the ground resistance less than 1 ohm. When both an electrical protection ground and an independently-laid antistatic ground are used as an antistatic ground, the resistance between the two ground cables should be less than 25 ohms.
- Antistatic workbenches and chairs should be properly grounded. The system resistance of an antistatic workbench should be within the range of 1×10^5 ohms to 1×10^9 ohms. The ground resistance of a ground cable shared by an antistatic workbench and a pipeline should be less than 1 ohm. The system resistance of an antistatic chair should be within the range of 1×10^5 ohms to 1×10^9 ohms.
- All instruments and power tools should be properly grounded, with the ground resistance less than 1 ohm (the resistance between a device ground point and the common ground point should be less than 1 ohm, and the ground resistance can be less than 10

ohms if being measured from the metal shell of the device). The ground resistance of a soldering iron tip should be less than 20 ohms.

- A factory building should be equipped with antistatic ground cables, and antistatic common ground points should be set up on each floor. The ground resistance of a factory building should be less than 1 ohm. The resistance between a ground cable shared by devices and an antistatic common ground point should be less than 1 ohm.
- In an electrostatic discharge protected area (EPA), antistatic dual-circuit wrist straps should be available, all wrist straps should be inserted into dedicated wrist strap jacks, and tools, devices, and ground cables that are fixed, except antistatic wrist straps and mobile device tools, must not be grounded using alligator clips.
- Ensure that tools' and devices' antistatic ground points are connected to antistatic ground cables in parallel. Antistatic common ground bars are preferred, and series connections are prohibited.
- Ensure that SMT devices, board-assembled devices, devices used to assemble and commission modules and systems, and devices/tools with antistatic ground points (for example, a soldering iron) are grounded using separate antistatic ground cables. That is, separate ground cables are connected from metal ground parts of the devices/tools to antistatic ground cables, to ensure that the devices/tools are reliably grounded.
- Set up EPAs according to ANSI/ESD S20.20 and IEC 61340-5-1 (international standard systems for ESD protection), and ensure that the electrostatic sensitivity (HBM) is less than 100 V. That is, devices with the electrostatic sensitivity equal to or greater than 100 V can be effectively protected in EPAs.
- Take antistatic measures for static-electricity-generating articles that are required in an EPA (for example, plastic parts, devices, and monitors used in the assembly procedure), for example, using an ionizing air blower, applying antistatic liquid, and using a static shielding bag/net. Ensure that electrostatic sensitive devices, boards, and components are 30 cm or more away from non-eliminable static-electricity-generating sources. Within the range 30 cm away from electrostatic sensitive devices, boards, and components, ensure that the friction voltage is less than 100 V.
- Use tools made of antistatic materials to turn over electrostatic sensitive devices, boards, and components, for example, antistatic foam, antistatic boxes, antistatic vacuum-formed plastic boxes, antistatic tote carts, and antistatic shielding bags. Do not place electrostatic sensitive devices, boards, and components directly in containers without ESD protection, for example, ordinary EPE trays, ordinary vacuum-formed plastic boxes, ordinary plastic bags, ordinary plastic boxes, ordinary hollow boxes, and tote carts without ESD protection.
- Before transporting electrostatic sensitive devices, boards, and components in non-EPA areas, for example, trans-plant transportation, perform antistatic closed packaging for the

devices, boards, and components.

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The ZM8300G module is designed to comply with the FCC statements. **FCC ID:** SRQ-ZM8300G.

The Host system using ZM8300G should have label “contains FCC ID: SRQ-ZM8300G

FCC Statement

According to the definition of mobile and fixed device is described in Part 2.1091(b), this device is a mobile device.

And the following conditions must be met:

1. This Modular Approval is limited to OEM installation for mobile and fixed applications only.

The antenna installation and operating configurations of this transmitter, including any applicable source-based time- averaging duty factor, antenna gain and cable loss must satisfy MPE categorical Exclusion Requirements of 2.1091.

2. The EUT is a mobile device; maintain at least a 20 cm separation between the EUT and the user's body and must not transmit simultaneously with any other antenna or transmitter.

3. A label with the following statements must be attached to the host end product: This device contains FCC ID: SRQ-ZM8300G.

4. This module must not transmit simultaneously with any other antenna or transmitter.

5. The host end product must include a user manual that clearly defines operating requirements and conditions that must be observed to ensure compliance with current FCC RF exposure guidelines.

For portable devices, in addition to the conditions 3 through 6 described above, a separate approval is required to satisfy the SAR requirements of FCC Part 2.1093.

If the device is used for other equipment that separate approval is required for all other operating configurations, including portable configurations with respect to 2.1093 and different antenna configurations.

For this device, OEM integrators must be provided with labeling instructions of finished products. Please refer to KDB784748 D01 v07, section 8.

A certified modular has the option to use a permanently affixed label, or an electronic label. For a permanently affixed label, the module must be labeled with an FCC ID - Section 2.926. The OEM manual must provide clear instructions explaining to the OEM the labeling requirements, options and OEM user manual instructions that are required.

For a host using a certified modular with a standard fixed label, if (1) the module's FCC ID is not visible when installed in the host, or (2) if the host is marketed so that end users do not have straight forward commonly used methods for access to remove the module so that the FCC ID of the module is visible; then an additional permanent label referring to the enclosed module: "Contains Transmitter Module FCC ID:SRQ-ZM8300G" or "Contains FCC ID: SRQ-ZM8300G" must be used. The host OEM user manual must also contain clear instructions on how end users can find and/or access the module and the FCC ID.

The final host / module combination may also need to be evaluated against the FCC Part 15B criteria for unintentional radiators in order to be properly authorized for operation as a Part 15 digital device.

The user's manual or instruction manual for an intentional or unintentional radiator shall caution the user that changes or modifications not expressly approved by the party responsible for compliance could void the user's authority to operate the equipment. In cases where the manual is provided only in a form other than paper, such as on a computer disk or over the Internet, the information required by this section may be included in the manual in that alternative form, provided the user can reasonably be expected to have the capability to access information in that form.

This device complies with part 15 of the FCC Rules. Operation is subject to the following two conditions:

(1) This device may not cause harmful interference, and (2) this device must accept any interference received, including interference that may cause undesired operation. Changes or modifications not expressly approved by the manufacturer could void the user's authority to operate the equipment.

To ensure compliance with all non-transmitter functions the host manufacturer is responsible for ensuring compliance with the module(s) installed and fully operational. For example, if a host was previously authorized as an unintentional radiator under the Declaration of Conformity procedure without a transmitter certified module and a module is added, the host manufacturer is responsible for ensuring that after the module is installed and operational the host continues to be compliant with the Part 15B unintentional radiator requirements.