

FSC-BT806

Bluetooth Module Datasheet
Version 1.2





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Version	Data	Notes	
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1.1	2019/10/22	1. Add Ordering Informationand modify some incorrect descriptions	Devin Wan
		2. UpdateGeneral Specifications	
1.2	2020/03/25	Update module picture, block diagram	Devin Wan

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1. INTRODUCTION

Overview

FSC-BT806 is a Bluetooth 5.0 dual-mode module. It provides a Bluetooth Low Energy fully compliant system for audio and data communication with Feasycom stack. FSC-BT806 integrates an ultra-low-power DSP and application processor with embedded flash memory, a high-performance stereo codec, a power management subsystem, I²S,LED drivers and ADC I/O in a SOC IC. The dual-core architecture with flash memory enables manufacturers to easily differentiate their products with new features without extending development cycles. By default, FSC-BT806 module is equipped with powerful and easy-to-use Feasycom firmware. It's easy-to-use and completely encapsulated. Feasycom firmware enables users to access Bluetooth functionality with simple ASCII commands delivered to the module over serial interface it's just like a Bluetooth modem.

Therefore, FSC-BT806 provides an ideal solution for developers who want to integrate Bluetooth wireless technology into their design.

- Music Enhancements: SBC,MP3,AAC and AAC+,Faststream codec,atpX,5-band EQ,3D stereo separation and so on.
- Support HSP, HFP, A2DP, AVRCP,PBAP,MAP,SPP,BLE profile
- Multipoint support for HFP connection to 2 handsets for voice
- Multipoint support for A2DP connection to 2 A2DP source for music playback
- 3 Hardware LED controllers(for RGB)
- UART, 1²C, SPI, PIO, AIO, USB control interfaces
- Postage stamp sized form factor
- MFI Support
- Built-in RF combo filter, Built-in PCB antenna to support external antenna
- Fast charging support up to 200mA with no externalcomponents
- RoHS compliant
- Industrial temperature range from -40°C to +85°C

Features

- Bluetooth v5.0/4.0/3.0/2.1/2.0/1.2/1.1, Class 1.5
- 80MHz RISC MCU and 80MIPS Kalimba DSP
- Stereo codec with 2 channels of ADC and up to 4 microphone inputs (includes bias generators anddigital microphone support)
- Support for CSR's latest CVC technology for narrow-band and wideband voice connections including wind noise reduction
- Audio interfaces: I²S/PCM and SPDIF

Application

- Smart watches&Bluetooth bracelets
- Bluetooth headphones
- Smart remote controllers
- Wired or wireless sound bars
- Wired or wireless speakers
- Wearable audio with sensors(health and well-being applications)
- Stereo (AV) Transmitter
- Automotive Hands-Free Kits



Module picture as below showing



Figure 1: FSC-BT806 Picture

Ordering Information

Device	Order Number
CSR8670	FSC-BT806A
CSR8675	FSC-BT806
	.000.000



2. General Specification

Table 1:General Specifications

Categories	Features	Implementation
_	On-board chip	CSR8670/CSR8675
		V5.0 Dual-mode Bluetooth low energy radio
		Software complies with the Bluetooth Core v5.0 Specification
	Bluetooth Low energy	Support for Bluetooth basic rate / EDR and low energyConnections
Wireless		3 Bluetooth low energy connections at the same time asbasic rate
Specification		A2DP
Specification	Frequency	2.402 - 2.480 GHz
	Transmit Power	+10 dBm (Maximum)
	Receive Sensitivity	-88 dBm(Typical)
		Real-time digitised RSSI available to application
	Raw Data Rates (Air)	3 Mbps(Classic BT - BR/EDR)
		TX, RX, CTS, RTS
		General Purpose I/O
	UART Interface	Default 115200,N,8,1
		Baudrate support from 1200 to 921600
		8 data bit character
		23(maximum – configurable) lines
	GPIO	O/P drive strength (4 mA)
	drio	Pull-up resistor (33 KΩ) control
		Read pin-level
	I ² C Interface	1 (hardware I ² C interface). Up to 400 kbps
		Master and slave I ² C interface
	SPI Interface	SPI debug and programming interface with read accessdisable
Host Interface and		locking
Peripherals		Analog input voltage range: 0~ 1.3V
	ADC Interface	Supports single a 10-bit ADC and a 10-bit DAC
		1 channels (configured from GPIO total)
	USB Interface	1 full-speed (12Mbps)
		80MHz RISC MCU and 80MIPS Kalimba DSP
	Digital audio	16-bit audio
	parametersCSR8670	Supported sample rates of 8, 11.025, 16, 22.05, 32, 44.1,48 and
		96kHz (DAC only)
		80 MHz RISC MCU and 120 MHz Kalimba DSP
	Digital audio	Up to 120MIPS DSP for intensive digital signal processing algorithms
	parametersCSR8675	24-bit audio
		Supported sample rates of 8, 11.025, 16, 22.05, 32, 44.1,48,96kHz
		and 192kHz (DAC only)
Profiles	BR/EDR	SPP (Serial Port Profile) - Up to 600 Kbps
		A2DP/AVRCP/HFP/HSP/HID/PBAP/SPP Profiles support



	Bluetooth Low Energy	GATT Client & Peripheral - Any Custom Services	
	Didetootii Low Liieigy	Simultaneous BR/EDR and BLE support	
Maximum	BR/EDR	up to 7 active slaves	
Connections	Bluetooth Low Energy	1 connection as peripheral, up to 5 connections as central	
		Via UART	
FW upgrade		USB	
		SPI	
Supply Voltage	Supply	VDD_IO: 1.7 ~ 3.6V; VBAT_IN: 2.8V~ 4.3V	
		Max Peak Current(TX Power @ +10dBm TX): 85mA	
Power Consumption		Standby Doze (Waitevent) - <1mA (TBD)	
		Deep Sleep - ~300uA(TBD)	
Physical	Dimensions	13mm(W) X 26.9mm(L) X 2.2mm(H); Pad Pitch 1mm	
Environmental	Operating	-40°C to +85°C	
Environmental	Storage	-40°C to +105°C	
Miscellaneous	Lead Free	Lead-free and RoHS compliant	
Miscellaneous	Warranty	One Year	
Humidity		10% ~ 90% non-condensing	
MSL grade:		MSL 3 (With JEDEC J-STD-020)	
		Human Body Model: Class-2	
ESD grade:		Machine Model: Class-200V	
		Charged Device Model: ClassII	



3. HARDWARE SPECIFICATION

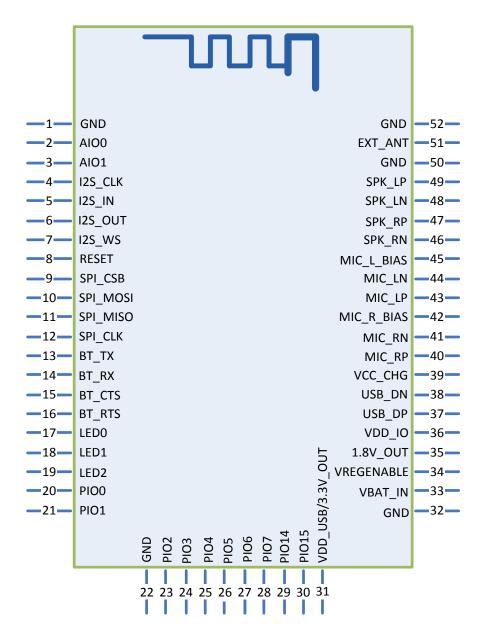


Figure 3: FSC-BT806 PIN Diagram(Top View)

3.2 PIN Definition Descriptions

Table 2:Pindefinition

Pin	Pin Name	Туре	Pin Descriptions	Notes
1	GND Vss Power Ground		Power Ground	
2	AIO0	I/O	Analogue 1 programmable input/output line.	Note 8
3	AIO1	I/O	Analogue 2 programmable input/output line.	Note 8
4	I2S_CLK	I/O	I2S/PCM synchronous data clock.	Note 6
	Alternative Function: Programmable input/output line			
5	I2S_IN	1/0	I2S/PCM synchronous data input.	Note 6



			Alternative Function: Programmable input/output line	
6	I2S_OUT	I/O	I2S/PCM synchronous data output.	Note 6
			Alternative Function: Programmable input/output line	
7	I2S_WS	I/O	I2S/PCM synchronous data sync.	Note 6
			Alternative Function: Programmable input/output line	
8	RESET	1	External reset input: Active LOW, with an inter an internal pull-up.	
			Set this pin low reset to initial state. (>5mS)	
9	SPI_CSB	1/0	Chip select for SPI, active low.(Debug)	
10	SPI_MOSI	1/0	SPI data input. (Debug)	
11	SPI_MISO	1/0	SPI data output. (Debug)	
12	SPI_CLK	1/0	SPI clock. (Debug)	
13	BT_TX	I/O	UART Data output	Note6
			Alternative Function: Programmable input/output line	
14	BT_RX	I/O	UART Data input	Note 6
			Alternative Function: Programmable input/output line	
15	BT_CTS	1/0	UART clear to send, active low.	Note6
			Alternative Function: Programmable input/output line	
16	BT_RTS	I/O	UARTrequest to send, active low.	Note 6
			Alternative Function: Programmable input/output line	
17	LED0	1/0	LED driver. (RED LED)	Note 6
18	LED1	1/0	LED driver. (BLUE LED)	Note 6
19	LED2	I/O	LED driver. (GREEN LED)	
20	PIO0	1/0	Programmable input/output line	
21	PIO1	I/O	Programmable input/output line	
22	GND	Vss	Power Ground	
23	PIO2	I/O	Programmable input/output line	
24	PIO3	1/0	Programmable input/output line	
25	PIO4	I/O	Programmable input/output line	
26	PIO5	1/0	Programmable input/output line	
27	PIO6	I/O	Programmable input/output line	Note 5
			Alternative Function:1 ² C_SCL	
28	PIO7	1/0	Programmable input/output line	Note 5
			Alternative Function:1 ² C_SDA	
29	PIO14	1/0	Programmable input/output line	
30	PIO15	1/0	Programmable input/output line	
31	VDD_USB/3.3V_OUT	Vdd	Positive supply for USB ports/ 3.3V bypass linear regulator output	Note 7
32	GND	Vss	Power Ground	
33	VBAT_IN	Vdd	Power supply voltage 2.8V~ 4.3V(Battery positive terminal)	
34	VREGENABLE	I	Power enable	Note 3
			* The PIN on electricity than VBAT_IN and VDD_IO foot 100 ms	
			delay.	
35	1.8V_OUT	Vdd	1.8V switch-mode power regulator output	Note 1
36	VDD_IO	Vdd	Power supply voltage 1.7V ~ 3.6V (for input/output ports)	Note 2
37	USB_DP	I/O	USB data positive	Note 4



38	USB_DN	1/0	USB data negative	Note 4
39	VCC_CHG	Vdd	Battery charger input (5V)	Note 4
40	MIC_RP	1	Microphone input positive, right	
41	MIC_RN	I	Microphone input negative, right	
42	MIC_R_BIAS	0	Microphone R bias	
43	MIC_LP	I	Microphone input positive, left	
44	MIC_LN	I	Microphone input negative, left	
45	MIC_L_BIAS	0	Microphone L bias	
46	SPK_RN	0	Speaker output negative, right	
47	SPK_RP	0	Speaker output positive, right	
48	SPK_LN	0	Speaker output negative, left	
49	SPK_LP	0	Speaker output positive, left	
50	GND	Vss	Power Ground	
51	EXT_ANT	RF	Bluetooth 50Ω transmitter output /receiver input	Note 9
52	GND	Vss	Power Ground	

Mο	dule	Pin	Not	tec.

Note 1	The internal output of 1.8 V power supply provides maximum 30MA current, and the specific use method can see the application circuit diagram
Note 2	Provid voltage reference to I/O, such as: PIO, UART, SPI, I2S, PCM,etc
Note 3	Regulator enable input.Can also be sensed as an input. Regulator enable and multifunction button. A high input (tolerant to VBAT) enables the on-chip regulators, which can then be latched on internally and the button used as a multifunction input. * The PIN on electricity than VBAT_IN and VDD_IO foot 100 ms delay.
Note 4	Using USB function and Lithium battery charging function, the pin should connect 5V voltage
Note 5	I ² C Serial Clock and Data. It is essential to remember that pull-up resistors on both SCL and SDA lines are not provided in the module and MUST be provided external to the module.
Note 6	For customized module, this pin can be work as I/O Interface.
Note 7	1, When you need to use the USB function, this pin needs to be connected to 3.3V (voltage range: 3.1V~3.6V) 2, when the No. 39 PIN (VCC_CHG) with a 5V input pin, this pin outputs 3.2V ~ 3.4V (maximum current: 250mA)
Note 8	Analog input voltage range: 0~ 1.3V
Note 9	By default, this PIN is an empty feet. This PIN can connect to an external antenna to improve the Bluetooth signal coverage. If you need to use an external antenna, by modifying the module on the OR resistance to block out the on-board antenna; Or contact Feasycom for modification.



4. PHYSICAL INTERFACE

4.1 Power Management

4.1.1 Power Supply

The transient response of the regulator is important. If the power rails of the module are supplied from an external voltage source, the transient response of any regulator used should be $20\mu s$ or less. It is essential that the power rail recovers quickly.

4.1.2Battery Charger

4.1.2.1Battery Charger Hardware Operating Modes

The default mode for the FSC-BT806 battery charger is OFF.

The internal charger circuit can provide up to 200mA of charge current.

The battery charger hardware is controlled by the VM, see picture below. The battery charger has 5 modes:

- Disabled
- Trickle charge
- Fast charge
- Standby: fully charged or float charge
- Error: charging input voltage, VCHG, is too low

The battery charger operating mode is determined by the battery voltage and current, see the table below and the picture below.

Table 3: Battery Charger Operating Modes Determined by Battery Voltage and Current

Parameter	Battery Charger Enabled	VBAT_SENSE(internal)		
Off	No	X		
Trickle charge	Yes	>0 and <v<sub>fast</v<sub>		
Fast charge	Yes	>V _{fast} and <v<sub>float</v<sub>		
Standby	Yes	$I_{term}^{(a)}$ and $>(V_{float} - V_{hyst})$		
Error	Yes	>(VCC_CHG - 50mV)		
(a)I _{term} is 10% of I _{fast} for a given I _{fast} setting				

The picture belowshows the mode-to-mode transition voltages. These voltages are fixed and calibrated. The transition between modes can occur at any time.



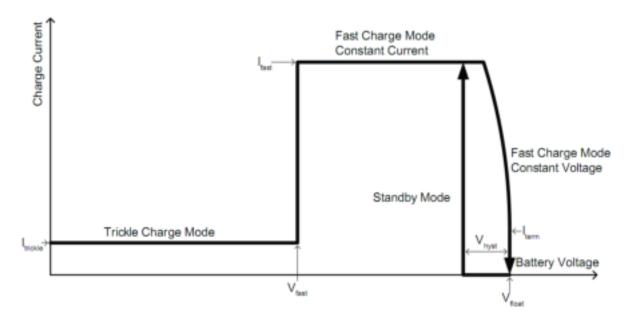


Figure 4:Battery Charger Mode-to-Mode Transition Diagram

Disabled Mode

In the disabled mode the battery charger is fully disabled and draws no active current on any of its terminals.

Trickle Charge Mode

In the trickle charge mode, when the voltage on VBAT_SENSE is lower than the V_{fast} threshold, a current of approximately 10% of the fast charge current, I_{fast} , is sourced from the VBAT_IN pin.

The V_{fast} threshold detection has hysteresis to prevent the charger from oscillating between modes.

Fast Charge Mode

When the voltage on VBAT_SENSE is greater than V_{fast} , the current sourced from the VBAT pin increases to I_{fast} is between 10mA and 200mA set by PS Key or a VM trap. In addition, I_{fast} is calibrated in production test to correct for process variation in the charger circuit.

The current is held constant at I_{fast} until the voltage at VBAT_SENSE reaches V_{float} , then the charger reduces the current sourced to maintain a constant voltage on the VBAT_SENSE pin.

When the current sourced is below the termination current, I_{term} , the charging stops and the charger enters standby mode. I_{term} is typically 10% of the fast charge current.

Standby Mode

When the battery is fully charged, the charger enters standby mode, and battery charging stops. The battery voltageon the VBAT_SENSE pin is monitored, and when it drops below a threshold set at V_{hyst} below the final chargingvoltage, V_{float} , the charger re-enters fast charge mode.



Error Mode

The charger enters the error mode if the voltage on the VCC_CHG pin is too low to operate the charger correctly(VBAT_SENSE is greater than VCC_CHG - 50mV (typical)).

In this mode, charging is stopped. The battery charger does not require a reset to resume normal operation.

4.1.2.2 Battery Charger Trimming and Calibration

The battery charger default trim values are written into internal flash when each IC is characterised. Please contact Feasycom regarding to PS keys.

4.1.2.3 VM Battery Charger Control

The VM charger code has overall supervisory control of the battery charger and is responsible for:

- Responding to charger power connection/disconnection events
- Monitoring the temperature of the battery
- Monitoring the temperature of the die to protect against silicon damage
- Monitoring the time spent in the various charge states
- Enabling/disabling the charger circuitry based on the monitored information
- Driving the user visible charger status LED(s)

4.1.2.4 Battery Charger Firmware and PS Keys

The battery charger firmware sets up the charger hardware based on the PS Key settings and call traps from the VM charger code. It also performs the initial analogue trimming. Settings for the charger current depend on the battery capacity and type, which are set by the user in the PS Keys.

4.2 Reset

FSC-BT806 is reset from several sources:

- RST# pin
- Power-on reset
- USB charger attach reset
- UART break character
- Software configured watchdog timer

The RST# pin is an active low reset and is internally filtered using the internal low frequency clock oscillator. Feasycomrecommends applying RST# for a period >5ms.

At reset the digital I/O pins are set to inputs for bidirectional pins and outputs are set to tristate. Following a reset,FSC-BT806 assumes the maximum XTAL_IN frequency, which ensures that the internal clocks run at a safe(low) frequency until FSC-BT806 is configured for the actual XTAL_IN frequency. If no clock is present atXTAL_IN, the oscillator in FSC-BT806 free runs, again at a safe frequency.



The RESET pin is an active low reset and is internally filtered using the internal low frequency clock oscillator. A reset will be performed between 1.5 and 4.0ms following RESET being active. It is recommended that RESET be applied for a period greater than 5ms.

At reset the digital I/O pins are set to inputs for bi-directional pins and outputs are tri-state. The PIOs have weak pull-ups.

4.2.1Digital Pin States on Reset

This table shows the pin states of FSC-BT806 on reset. PU and PD default to weak values unless specified otherwise.

Table 4: Pin States on Reset

Pin Name/Group	I/O Type	Full Chip Reset
USB_DP	Digitalbidirectional	N/A
USB_DN	Digitalbidirectional	N/A
BT_TX	Digitalbidirectional with PU	Weak PU
BT_RX	Digitalbidirectional with PU	Strong PU
BT_CTS	Digital bidirectional with PD	Weak PD
BT_RTS	Digitalbidirectional with PU	Strong PU
SPI_CSB	Digital input with PU	Strong PU
SPI_CLK	Digital input with PD	Weak PD
SPI_MISO	Digital tristate output with PD	Weak PD
SPI_MOSI	Digital input with PD	Weak PD
RESET	Digital input with PU	Strong PU
I2S_IN	Digital bidirectional with PD	Weak PD
I2S_OUT	Digital bidirectional with PD	Weak PD
I2S_WS	Digital bidirectional with PD	Weak PD
I2S_CLK	Digital bidirectional with PD	Weak PD
RESET	Digital input with PU	Strong PU
PIO0,1,2,3,4,5,6,7,14,15	Digital bidirectional with PD	Weak PD

4.2.2Status After Reset

The status of FSC-BT806 after a reset is:

Warm reset: baud rate and RAM data remain available

Cold reset: baud rate and RAM data not available

4.2.3Automatic Reset Protection

FSC-BT806 includes an automatic reset protection circuit which restarts/resets CSR8670 WLCSP when anunexpected reset occurs, e.g. ESD strike or lowering of RST#. The automatic reset protection circuit enables resetsfrom the VM without the requirement for external circuitry.



Note:

The reset protection is cleared after typically 2s (1.6s min to 2.4s max).

If RST# is held low for >2.4s FSC-BT806 turns off.

A rising edge on VREGENABLE or VCC CHG is required to power on FSC-BT806

4.3 General Purpose Analog IO

FSC-BT806 has 1 general-purpose analogue interface pins, AlO1, for accessing internal circuitry and controlsignals. Auxiliary functions available on the analogue interface include a 10-bit ADC and a 10-bit DAC. Signalsselectable on this interface include the band gap reference voltage. When configured for analogue signals the voltagerange is constrained by the analogue supply voltage. When configured to drive out digital level signals generatedfrom within the analogue part of the device, the output voltage level is determined by VDD AUX(internal).

4.4 General Purpose Digital IO

10 lines of programmable bidirectional I/O are available on the FSC-BT806. Some of the PIOs on the FSC-BT806 have alternative functions:

- 3 digital microphone interfaces for control of up to 3 digital microphones:
 - Clock on any even PIOs as determined by the software
 - ◆ Data on any odd PIOs as determined by the software
- I²C interface on any PIOs as determined by the software
- LED[2:0] directly map to PO[31:29]
- I2S/PCM interface on PIO[20:17]

4.5 RF Interface

For this module, the antenna must be connected to work properly.

The user can connect a 50ohm antenna directly to the RF port.

- 2402–2480 MHz Bluetooth 5.0 Dual Mode (BT and BLE); 1 Mbps to 3 Mbps over the air data rate.
- TX output power of +10dBm(MAX).
- Receiverto achieve maximum sensitivity -88dBm @ 1 Mbps BLE or Classic BT, 2 Mbps, 3 Mbps).

4.6 Serial Interfaces

4.6.1 UART Interface

FSC-BT806provides one channels of Universal Asynchronous Receiver/Transmitters(UART)(Full-duplex asynchronous communications). The UART Controller performs a serial-to-parallel conversion on data received from the peripheral and a parallel-to-serial conversion on data transmitted from the CPU. Each UART Controller channel supports ten types of interrupts.



This is a standard UART interface for communicating with other serial devices. The UART interface provides a simple mechanism for communicating with other serial devices using the RS232 protocol.

When the module is connected to another digital device, UART_RX and UART_TX transfer data between the two devices. The remaining two signals, UART_CTS and UART_RTS, can be used to implement RS232 hardware flow control where both are active low indicators.

This module output is at 3.3V CMOS logic levels (tracks VCC). Level conversion must be added to interface with an RS-232 level compliant interface.

Some serial implementations link CTS and RTS to remove the need for handshaking. We do not recommend linking CTS and RTS except for testing and prototyping. If these pins are linked and the host sends data when the FSC-BT806 deasserts its RTS signal, there is significant risk that internal receive buffers will overflow, which could lead to an internal processor crash. This drops the connection and may require a power cycle to reset the module. We recommend that you adhere to the correct CTS/RTS handshaking protocol for proper operation.

Table 5: Possible UART Settings

Parameter	Possible Values	
	Minimum	1200 baud (≤2%Error)
Baudrate	Standard	115200bps(≤1%Error)
	Maximum	4Mbaud(≤1%Error)
Flow control		RTS/CTS, or None
Parity		None, Odd or Even
Number of stop bits		1 /2
Bits per channel		8

When connecting the module to a host, please make sure to follow .

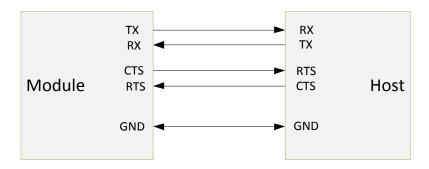


Figure 5: UART Connection

The UART interface resets FSC-BT806 on reception of a break signal. A break is identified by a continuous logic low (0V) on the UART_RX terminal, as belowpicture shows. If t BRK is longer than the value defined by the PSKEY_HOSTIO_UART_RESET_TIMEOUT, a reset occurs. This feature enables a host to initialise the system toa known state. Also, FSC-BT806 can issue a break character for waking the host.



Figure 6: Break Signal



The UART interface is tristate while FSC-BT806 is being held in reset. This enables the user to connect otherdevices onto the physical UART bus. The restriction with this method is that any devices connected to this bus must ristate when FSC-BT806 reset is de-asserted and the firmware begins to run.

4.6.2 I²C Interface

FSC-BT806 includes a configurable I²C interface.

I²C is a two-wire, bi-directional serial bus that provides a simple and efficient method of data exchange between devices. The I²C standard is a true multi-master bus including collision detection and arbitration that prevents data corruption if two or more masters attempt to control the bus simultaneously.

Data is transferred between a Master and a Slave synchronously to SCL on the SDA line on a byte-by-byte basis. Each data byte is 8-bit long. There is one SCL clock pulse for each data bit with the MSB being transmitted first. An acknowledge bit follows each transferred byte. Each bit is sampled during the high period of SCL; therefore, the SDA line may be changed only during the low period of SCL and must be held stable during the high period of SCL. A transition on the SDA line while SCL is high is interpreted as a command (START or STOP). Please refer to the following figure for more details about I²C Bus Timing.

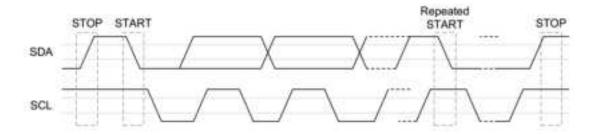


Figure 7: I2C Bus Timing

The device on-chip I^2C logic provides the serial interface that meets the I^2C bus standard modespecification. The I^2C port handles byte transfers autonomously. The I^2C H/W interfaces to the I^2C bus via two pins: SDA and SCL. Pull up resistor is needed for I^2C operation as these are open drain pins. When the I/O pins are used as I^2C port, user must set the pins function to I^2C in advance.

4.6.3USB Interface

FSC-BT806 has a full-speed (12Mbps) USB interface for communicating with other compatible digital devices. The USB interface on FSC-BT806 acts as a USB peripheral, responding to requests from a master host controller.

FSC-BT806 supports the Universal Serial Bus Specification, Revision v2.0 (USB v2.0 Specification) and USB Battery Charging Specification , available from http://www.usb.org. For more information on how to integrate the USB interface on FSC-BT806 see the Bluetooth and USB Design Considerations Application Note.

As well as describing USB basics and architecture, the application note describes:

- Power distribution for high and low bus-powered configurations
- Power distribution for self-powered configuration, which includes USB VBUS monitoring (when VBUS is>3.1)
- USB enumeration
- Electrical design guidelines for the power supply and data lines, as well as PCB tracks and the effects offerrite beads



- USB suspend modes and Bluetooth low-power modes:
 - ◆ Global suspend
 - Selective suspend, includes remote wake
 - ♦ Wake on Bluetooth, includes permitted devices and set-up prior to selective suspend
 - Suspend mode current draw
 - ◆ PIO status in suspend mode
 - ◆ Resume, detach and wake PIOs
- Battery charging from USB, which describes dead battery provision, charge currents, charging in suspend modes and USB VBUS voltage consideration
- USB termination when interface is not in use
- Internal modules, certification and non-specification compliant operation

4.7LED Drivers

FSC-BT806 includes a 3-pad synchronised PWM LED driver for driving RGB LEDs for producing a wide rangeof colours. All LEDs are controlled by firmware.

The terminals are open-drain outputs, so the LED must be connected from a positive supply rail to the pad in series with a current-limiting resistor.

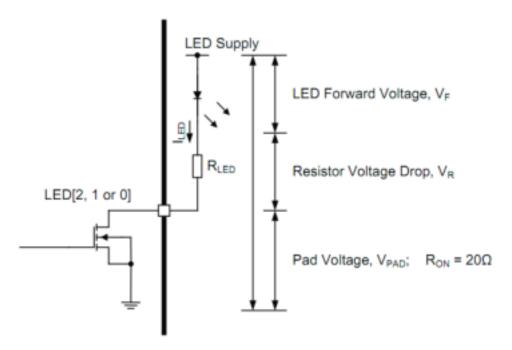


Figure 8: LED Equivalent Circuit

If a known value of current is required throughthe LED to give a specific luminous intensity, then the value of R_{LED} is calculated.

$$I_{LED} = \frac{VDD - V_F}{R_{LED} + R_{ON}}$$

For the LED pads to act as resistance, the external series resistor, R_{LED} , needs to be such that the voltage dropacross it, V_R , keeps V_{PAD} below 0.5V.

$$VDD=V_F+V_R+V_{PAD}$$



Note:

The LED current adds to the overall current. Conservative LED selection extends battery life.

4.8Audio Interfaces

The audio interface circuit consists of:

- Stereo/dual-mono audio codec
- Dual analogue audio inputs
- Dual analogue audio outputs
- 2 digital MEMS microphone inputs
- A configurable PCM, I²S or SPDIF interface

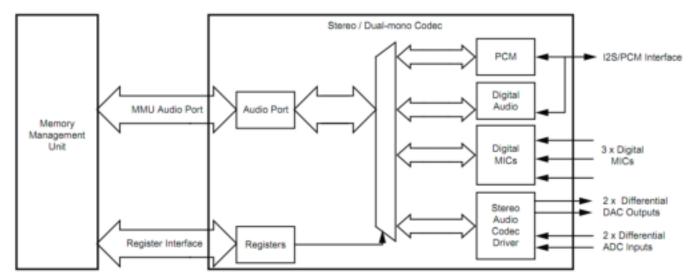


Figure 9: Audio Interface

The interface for the digital audio bus shares the same pins as the PCM codec interface described. which means each of the audio buses are mutually exclusive in their usage.

Table 6: Alternative functions of the digital audio bus interface on the PCM interface

PCM Interface	SPDIF Interface	I2S Interface
PCM_OUT	SPDIF_OUT	I2S_OUT
PCM_IN	SPDIF_IN	I2S_IN
PCM_SYNC		12S_WS
PCM_CLK		I2S_CLK



4.8.1 Audio Input and Output

The audio input circuitry consists of:

- 2 independent 16-bit high-quality ADC channels:
 - Programmable as either microphone or line input
 - Programmable as either stereo or dual-mono inputs
 - ◆ Multiplexed with 2 of the digital microphone inputs
 - Each channel is independently configurable to be either single-ended or fully differential
 - ◆ Each channel has an analogue and digital programmable gain stage for optimisation of differentmicrophones
- 2 digital MEMS microphone channels, of which 4 have independent codec channels and 2 share their codecs with the 2 high-quality audio inputs

The audio output circuitry consists of a dual differential class A-B output stage.

Note:

FSC-BT806 is designed for a differential audio output. If a single-ended audio output is required, use anexternal differential to single-ended converter.

4.8.2 Audio Codec Interface

The main features of the interface are:

- Stereo and mono analogue input for voice band and audio band
- Stereo and mono analogue output for voice band and audio band
- Support for stereo digital audio bus standards such as I²S
- Support for IEC-60958 standard stereo digital audio bus standards, e.g. SPDIF and AES3 (also known as AES/EBU)
- Support for PCM interfaces including PCM master codecs that require an external system clock

Note:

To avoid any confusion regarding stereo operation this data sheet explicitly states which is the left and right channel for audio output. With respect to audio input, software and any registers, channel 0 or channel A represents the left channel and channel 1 or channel B represents the right channel.



Audio Codec Block Diagram

Stereo Audio, Voice Bend and Digital Microphone Input L/R pins on digital microphones pulled up or down on the PCB Digital Circuitry PIO(EVEN) Digital MIC Interface Digital Mic Digital Codes PIOJODD) []-Clock Digital Mic Digital Codec Input E Date PIO(EVEN) []-Digital MIC Interface Digital Mic Digital Codes Input D PIOJODOI C Data Clock Digital Mic Digital Codec Input C MIC_RP righ-quality ADC MIC_RN Digital Codec Input B PIO(EVEN) □-Digital MIC Interface Digital Mic PIO(ODD) [] MIC UP ID High-quality ADC MIC LN I Digital Codes ▶ input A Digital Mic Stereo Audio and Voice Band Output SPKR_LN □ High-quality DAC SPKR LP D SPKR AN De High-quality DAC SPKR RP []4

Figure 10: Audio Codec Input and Output Stages

FSC-BT806 audio codec uses a fully differential architecture in the analogue signal path, which resultsin low noise sensitivity and good power supply rejection while effectively doubling the signal amplitude. It operates from a dual power supply, VDD_AUDIO(internal) for the audio circuits and VDD_AUDIO_DRV (internal) for the audio driver circuits.

ADC

The picture aboveshows the FSC-BT806 consists of 2 high-quality ADCs

- Each ADC has a second-order Sigma-Delta converter.
- Each ADC is a separate channel with identical functionality.
- There are 2 gain stages for each channel, 1 of which is an analogue gain stage and the other is a digitalgain stage



ADC Sample Rate Selection

Each ADC supports the following pre-defined sample rates, although other rates are programmable, e.g. 40kHz:

- 8kHz
- 11.025kHz
- 16kHz
- 22.050kHz
- 24kHz
- 32kHz
- 44.1kHz
- 48kHz

ADC Audio Input Gain

The picture below shows that the FSC-BT806 audio input gain consists of:

- An analogue gain stage based on a pre-amplifier and an analogue gain amplifier
- A digital gain stage

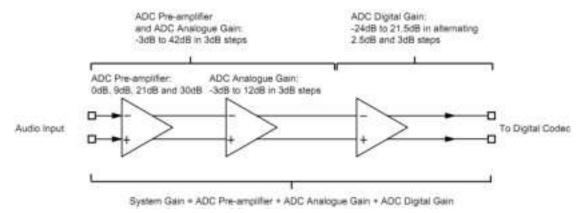


Figure 11: Audio Input Gain

ADC Pre-amplifier and ADC Analogue Gain

FSC-BT806 has an analogue gain stage based on an ADC pre-amplifier and ADC analogue amplifier:

- The ADC pre-amplifier has 4 gain settings: 0dB, 9dB, 21dB and 30dB
- The ADC analogue amplifier gain is -3dB to 12dB in 3dB steps
- The overall analogue gain for the pre-amplifier and analogue amplifier is -3dB to 42dB in 3dB steps
- At mid to high gain levels it acts as a microphone pre-amplifier
- At low gain levels it acts as an audio line level amplifier

ADC Digital Gain

A digital gain stage inside the ADC varies from -24dB to 21.5dB, see following table. There is also a fine gain interface with a 9-bit gain setting allowing gain changes in 1/32 steps, for more infomation contact Feasycom.

The firmware controls the audio input gain.



Table 7: ADC Audio Input Gain Rate

Digital Gain Selection Value	ADC Digital Gain Setting(dB)	Digital Gain Selection Value	ADC Digital Gain Setting(dB)
0	0	8	-24
1	3.5	9	-20.5
2	6	10	-18
3	9.5	11	-14.5
4	12	12	-12
5	15.5	13	-8.5
6	18	14	-6
7	21.5	15	-2.5

ADC Digital IIR Filter

The ADC contains 2 integrated anti-aliasing filters:

- A long IIR filter suitable for music (>44.1kHz)
- G.722 filter is a digital IIR filter that improves the stop-band attenuation required for G.722 compliance(which is the best selection for 8kHz / 16kHz / voice)

For more information contact Feasycom.

DAC

The DAC consists of:

- 2 fourth-order Sigma-Delta converters enabling 2 separate channels that are identical in functionality
- 2 gain stages for each channel, 1 of which is an analogue gain stage and the other is a digital gain stage.

DAC Sample Rate Selection

Each DAC supports the following sample rates:

- 8kHz
- 11.025kHz
- 16kHz
- 22.050kHz
- 32kHz
- 40kHz
- 44.1kHz
- 48kHz
- 96kHz



DAC Digital Gain

A digital gain stage inside the DAC varies from -24dB to 21.5dB, see following table. There is also a fine gain interface with a 9-bit gain setting enabling gain changes in 1/32 steps, for more information contact CSR.

The overall gain control of the DAC is controlled by the firmware. Its setting is a combined function of the digital and analogue amplifier settings.

Table 8: DAC Digital Gain Rate Selection

Digital Gain Selection Value	DAC Digital Gain Setting(dB)	Digital Gain Selection Value	DAC Digital Gain Setting(dB)
0	0	8	-24
1	3.5	9	-20.5
2	6	10	-18
3	9.5	11	-14.5
4	12	12	-12
5	15.5	13	-8.5
6	18	14	-6
7	21.5	15	-2.5

DAC Analogue Gain

The following table shows that the DAC analogue gain stage consists of 8 gain selection values that represent seven 3dBsteps.

The firmware controls the overall gain control of the DAC. Its setting is a combined function of the digital and analogue amplifier settings.

Table 9: DAC Analogue Gain Rate Selection

Analogue Gain Selection Value	DAC Analogue Gain Setting(dB)	Analogue Gain Selection Value	DAC Analogue Gain Setting(dB)
7	0	3	-12
6	-3	2	-15
5	-6	1	-18
4	-9	0	-21

DAC Digital FIR Filter

The DAC contains an integrated digital FIR filter with the following modes:

- A default long FIR filter for best performance at >= 44.1kHz.
- A short FIR to reduce latency.
- A narrow FIR (a very sharp roll-off at Nyquist) for G.722 compliance. Best for 8kHz / 16kHz.



IEC 60958 Interface

The IEC 60958 interface is a digital audio interface that uses bi-phase coding to minimise the DC content of the transmitted signal and enables the receiver to decode the clock information from the transmitted signal. The IEC 60958 specification is based on the 2 industry standards:

- AES3 (also known as AES/EBU)
- Sony and Philips interface specification SPDIF

The interface is compatible with IEC 60958-1, IEC 60958-3 and IEC 60958-4.

The SPDIF interface signals are SPDIF_IN and SPDIF_OUT and are shared on the PCM interface pins. The input and output stages of the SPDIF pins interface to:

- A 75Ω coaxial cable with an RCA connector
- An optical link that uses Toslink optical components

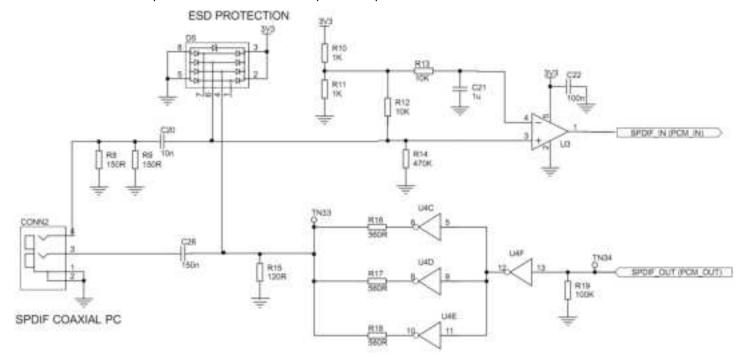


Figure 12: Example Circuit for SPDIF Interface(Co-axial)

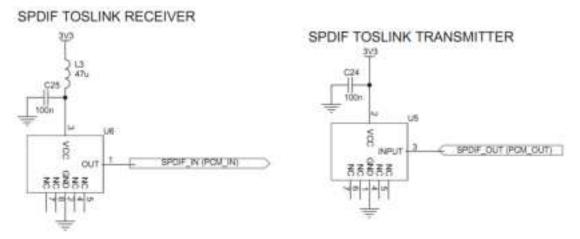


Figure 13: Example Circuit for SPDIF Interface(Optical)



Microphone Input

FSC-BT806 contains an independent low-noise microphone bias generator. The microphone bias generator is recommended for biasing electret condensor microphones. Figure 9.6 shows a biasing circuit for microphoneswith a sensitivity between about -40 to -60dB (0dB = 1V/Pa).

Where:

- The microphone bias generator derives its power from VBAT or 3V3_USB and requires no capacitor on its output.
- The microphone bias generator maintains regulation within the limits 70uA to 2.8mA, supporting a 2mAsource typically required by 2 electret condensor microphones. If the microphone sits below these limits, then the microphone output must be pre-loaded with a large value resistor to ground.
- Biasing resistors R1 and R2 equal 2.2kΩ.
- When the input pre-amplifier is enabled, the input impedance at MIC_LN, MIC_LP, MIC_RN and MIC_RPvaries between $6k\Omega$ (pre-amplifier gain >0dB) and $12k\Omega$ (pre-amplifier gain = 0dB).
- C1, C2, C3 and C4 are 100/150nF if bass roll-off is required to limit wind noise on the microphone.
- \blacksquare R1 and R2 set the microphone load impedance and are normally around 2.2k Ω .

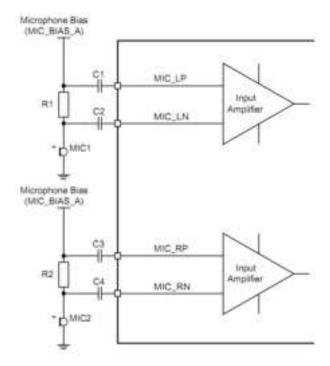


Figure 14: Microphone Biasing

The microphone bias characteristics include:

Power supply:

FSC-BT806 microphone supply is VBAT or 3V3_USB(inernal)

Minimum input voltage = Output voltage + drop-out voltage

Maximum input voltage is 4.3V

Drop-out voltage:

300mV maximum

Output voltage:



1.8V or 2.6V

Tolerance 90% to 110%

Output current:

70uA to 2.8mA

No load capacitor required

Digital Microphone Inputs

FSC-BT806 interfaces to 2 digital MEMS microphones. shows that 4 of the inputs have dedicated codec channels and 2 are multiplexed with the high-quality ADC channels.

Clock lines shared between 2 microphone outputs, linked to any even-numbered PIO pin as determined by the firmware.

Note:

Multiple digital microphones can share the same clock if they are configured for the same frequency, e.g. 1 clock for 6 digital microphones.

Data lines shared between 2 microphone inputs, linked to any odd-numbered PIO as determined by thefirmware.

Note:

For the digital microphone interface to work in this configuration ensure the microphone uses a tristatebetween edges.

The left and right selection for the digital microphones are appropriately pulled up or down for selection on the PCB.

Line Input

The picture belowshow 2 circuits for line input operation and show connections for either differential or single-ended inputs.

In line input mode, the input impedance of the pins to ground varies from $6k\Omega to 34k\Omega depending on input gainsetting.$

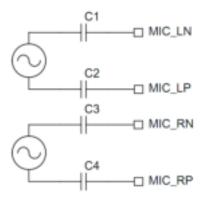


Figure 15: Differential Input



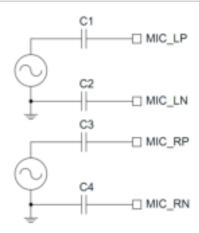


Figure 16: Single-ended Input

4.8.3 Output Stage

The output stage digital circuitry converts the signal from 16-bit per sample, linear PCM of variable sampling frequency to bit stream, which is fed into the analogue output circuitry.

The analogue output circuit comprises a DAC, a buffer with gain-setting, a low-pass filter and a class AB outputstage amplifier. The picture below shows that the output is available as a differential signal between SPKR_LN and SPKR_LPfor the left channel, and between SPKR_RN and SPKR_RP for the right channel.

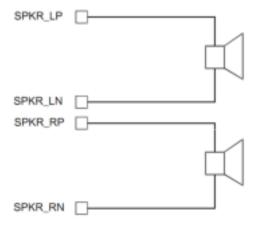


Figure 17: Speaker Output

4.8.4 PCM Controller

The audio PCM interface on the FSC-BT806 supports:

- On-chip routing to Kalimba DSP
- Continuous transmission and reception of PCM encoded audio data over Bluetooth.
- Processor overhead reduction through hardware support for continual transmission and reception of PCM data
- A bidirectional digital audio interface that routes directly into the baseband layer of the firmware. It does not pass through the HCI protocol layer.
- Hardware on the CSR8670 WLCSP for sending data to and from a SCO connection.
- Up to 3 SCO connections on the PCM interface at any one time.



- PCM interface master, generating PCM_SYNC and PCM_CLK.
- PCM interface slave, accepting externally generated PCM_SYNC and PCM_CLK.
- Various clock formats including:
- Long Frame Sync
- Short Frame Sync
- GCI timing environments
- **13**-bit or 16-bit linear, 8-bit μ-law or A-law companded sample formats.
- Receives and transmits on any selection of 3 of the first 4 slots following PCM_SYNC.

PCM Interface Master/Slave

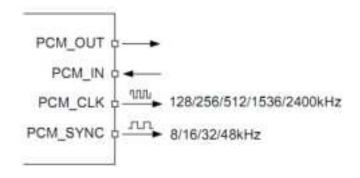


Figure 18:PCM Interface Master

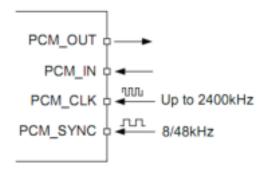


Figure 19:PCM Interface Slave

Long Frame Sync

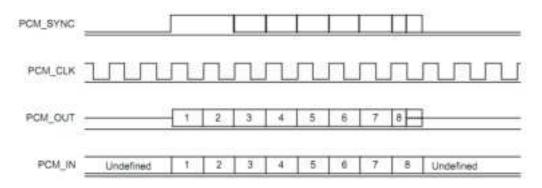


Figure 20:Long Frame Sync (shown with 8-bit Companded Sample)



Short Frame Sync

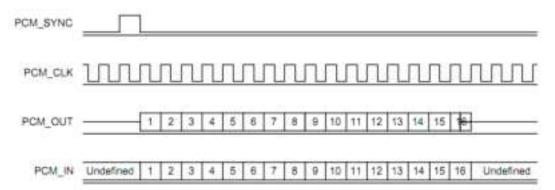


Figure 21: Short Frame Sync (shown with 16-bitSample)

Multi-slot Operation

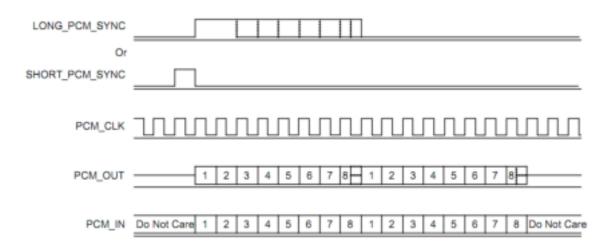


Figure 22:Multi Slot Operation with 2 Slots and 8-bit Companded Samples

GCI Interface

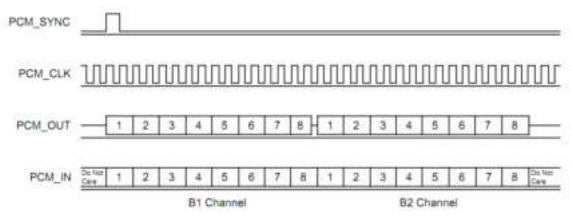


Figure 23:GCI Interface



Slots and Sample Formats

FSC-BT806 receives and transmits on any selection of the first 4 slots following each sync pulse. Slot durations are either 8 or 16 clock cycles:

- 8 clock cycles for 8-bit sample formats.
- 16 clocks cycles for 8-bit, 13-bit or 16-bit sample formats.

FSC-BT806 supports:

- 13-bit linear, 16-bit linear and 8-bit μ-law or A-law sample formats.
- A sample rate of 8ksamples/s, 16ksamples/s or 32ksamples/s.
- Little or big endian bit order.
- For 16-bit slots, the 3 or 8 unused bits in each slot are filled with sign extension, padded with zeros or aprogrammable 3-bit audio attenuation compatible with some codecs.

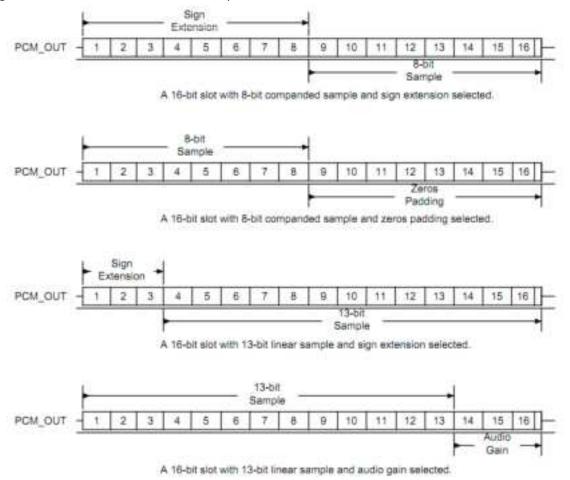


Figure 24:16-bit Slot Length and Sample Formats

Additional Features

FSC-BT806 has a mute facility that forces PCM_OUT to be 0. In master mode, FSC-BT806 is compatible with some codecs which control power down by forcing PCM SYNC to 0 while keeping PCM CLK running.



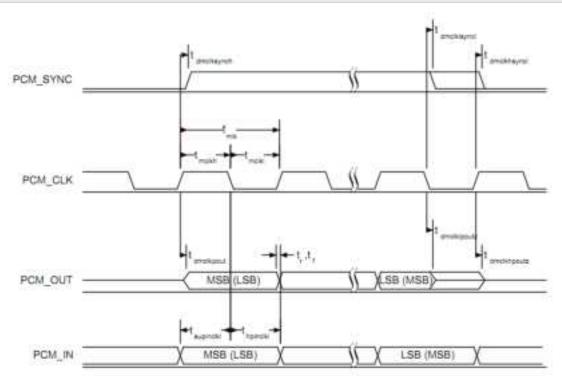


Figure 25:PCM Master Timing Long Frame Sync

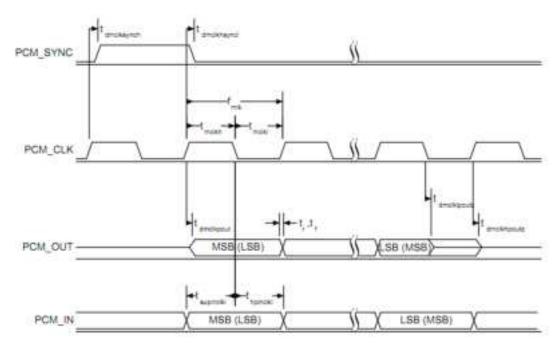


Figure 26: PCM Master Timing Short Frame Sync



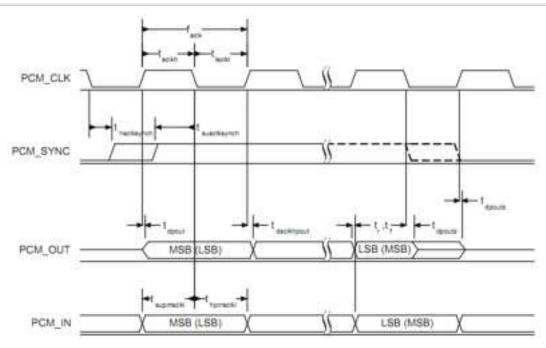


Figure 27: PCM Slave Timing Long Frame Sync

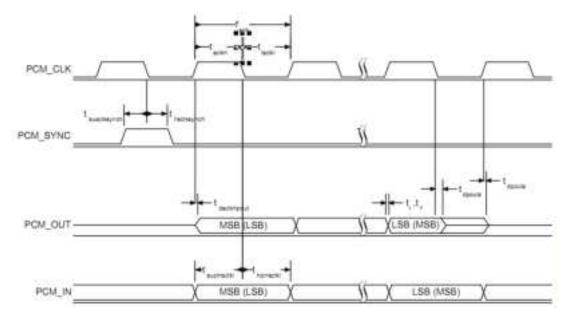


Figure 28: PCM Slave Timing Short Frame Sync

4.8.5 I²S Controller

The digital audio interface supports the industry standard formats for I^2 S, left-justified or right-justified. The interface shares the same pins as the PCM interface, which means each audio bus is mutually exclusive in its usage. This Table lists these alternative functions.



Table 10: Alternative functions of the digital audio bus interface on the PCM interface

PCM Interface	I2S Interface	
PCM_OUT	I2S_OUT	
PCM_IN	I2S_IN	
PCM_SYNC	12S_WS	
PCM_CLK	I2S_CLK	

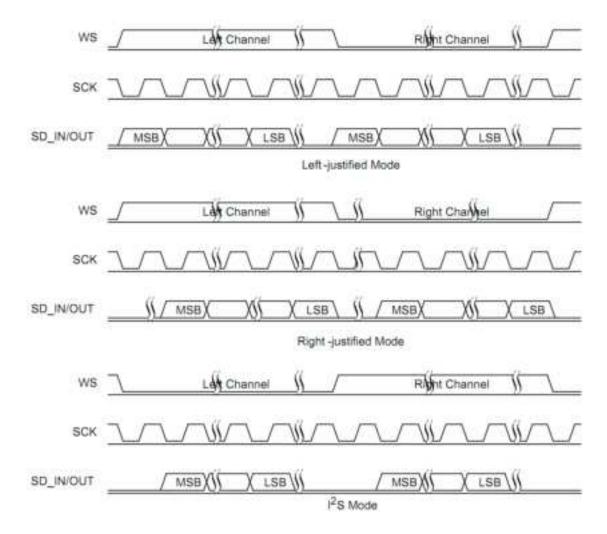


Figure 29: Digital Audio Interface Modes



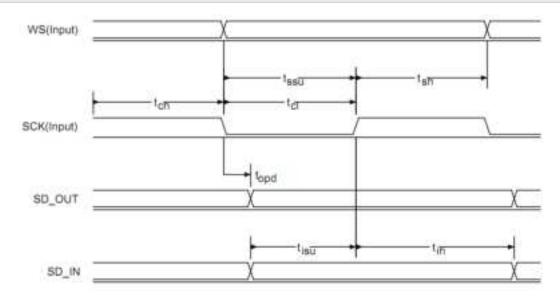


Figure 30: Digital Audio Interface Slave Timing

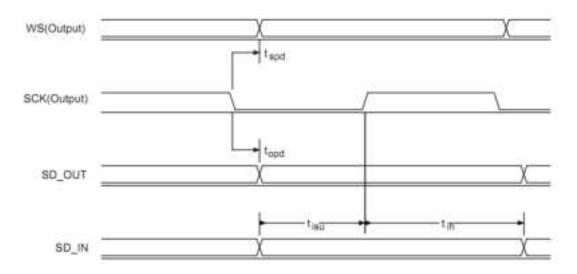


Figure 31: Digital Audio Interface Master Timing

4.9Programming and Debug Interface

Important Note:

The SPI is for programming, configuring (PS Keys) and debugging the FSC-BT806. It is required in production. Ensure the 4 SPI signals are brought out to either test points or a header.

Feasycom provides development and production tools to communicate over the SPI from a PC, although a leveltranslator circuit is often required.

FSC-BT806 uses a 16-bit data and 16-bit address programming and debug interface. Transactions occur when the internal processor is running or is stopped.

Data is written or read one word at a time, or the auto-increment feature is available for block access.



5. ELECTRICAL CHARACTERISTICS

5.1 Absolute Maximum Ratings

Absolute maximum ratings for supply voltage and voltages on digital and analogue pins of the module are listedbelow. Exceeding these values causes permanent damage.

The average PIO pin output current is defined as the average current value flowing through any one of the corresponding pins for a 100mS period. The total average PIO pin output current is defined as the average current value flowing through all of the corresponding pins for a 100mS period. The maximum output current is defined as the value of the peak current flowing through any one of the corresponding pins.

Table 11: Absolute Maximum Rating

Parameter	Min	Max	Unit
5V(VCC_CHG)	-0.4	+5.75 / 6.50 ^(a)	V
BATTERY(LED 0,1,2)	-0.4	+4.4	V
BATTERY(VBAT_IN)	2.7	+5.75	V
BATTERY(VREGENABLE)	-0.4	+4.4	V
VDD_IO	-0.4	+3.6	V
Other terminal voltages	VSS-0.4	VDD+0.4	V
T _A - Operating Temperature	-40	+85	°C
T _{ST} - Storage Temperature	-40	+105	°C

⁽a) Standard maximum input voltage is 5.75V, a 6.50V maximum depends on firmware version and implementation of over-temperature protection software, for more information contact Feasycom.

5.2 Recommended Operating Conditions

Table 12: Recommended Operating Conditions

Parameter	Min	Туре	Max	Unit
5V(VCC_CHG)	4.75 / 3.10 (a)	5	5.75 / 6.50 (b)	V
BATTERY(LED 0,1,2)	1.10	3.70	4.30	V
BATTERY(VBAT_IN)	2.8	3.3	4.30	V
BATTERY(VREGENABLE)	0	3.3	4.30	V
VDD_IO	1.7	3.3	3.6	V
T _A - Operating Temperature	-40	25	+85	°C
T _{ST} - Storage Temperature	-40	25	+85	°C

⁽a) Minimum input voltage of 4.75V is required for full specification, regulator operates at reduced load current from 3.1V

⁽b) Standard maximum input voltage is 5.75V, a 6.50V maximum depends on firmware version and implementation of over-temperature protection software, for more information contact Feasycom.



5.3 Input/output Terminal Characteristics

5.3.1 Digital

Table 13: DC Characteristics ($V_{DD} - V_{SS} = 3 \sim 3.6 \text{ V}$, $T_A = 25 ^{\circ}\text{C}$)

Parameter	Min	Type	Max	Unit
Input Voltage				
V _{IL} - Standard IO Low levelinput voltage	-0.4	-	0.4	V
V _{IH} - Standard IO Low levelinput voltage	0.7XVDD_IO	-	VDD_IO+0.4	V
Tr/Tf	-	-	25	nS
Output Voltage				
V _{OL} - Low Level Output Voltage, I _{OL} =4mA	-	-	0.4	V
V _{OH} - High Level Output Voltage, I _{OH} =-4mA	0.7XVDD_IO	-	-	V
Tr/Tf	-	-	5	nS
Input and Tristate Currents				
Strong pull-up	-150	-40	-10	uA
Strong pull-down	10	40	150	uA
Weak pull-up	-5	-1.0	-0.33	uA
Weak pull-down	0.33	1.0	5.0	uA
C Input Capacitance	1.0	-	5.0	pF

5.3.2Battery Charger

Table 14:Battery Charger

Parameter	Min	Туре	Max	Unit
Battery Charger				
Input voltage, VCHG	4.75 / 3.10(a)	5.00	5.75 /6.50(b)	V

⁽a) Reduced specification from 3.1V to 4.75V. Full specification >4.75V.

(b) Standard maximum input voltage is 5.75V, a 6.50V maximum depends on firmware version and implementation of over-temperature protection software, for more information contact Feasycom.

Trickle Charge Mode					
Charge current I _{trickle} , as percen	tage of fast charge current	8	10	12	%
V _{fast} rising threshold		-	2.9	-	V
V _{fast} rising threshold trim step size		-	0.1	-	V
V _{fast} falling threshold		-	2.8	-	V
Fast Charge Mode					
Charge current during	Max, headroom >0.55V	194	200	206	mA
constantcurrent mode, I _{fast}	Min, headroom >0.55V	-	10	-	mA

FSC-BT806 Datasheet



Reduced headroom charge	Mid, headroom =0.15V	50	-	100	%
current, as a percentage of I _{fast}					
Charge current step size		-	10	-	mA
V _{float} threshold, calibrated		4.16	4.20	4.24	V
Charge termination current I _{term}	, as percentage of I _{fast}	7	10	20	%
Standby Mode					
Voltage hysteresis on VBAT_IN, V	V_{hyst}	100	-	150	mV
Error Charge Mode					
Headroom(a) error falling thresh	nold	-	50	-	mV
(a) Headroom = VCC_CHG - VBA	AT_IN				

5.3.3USB

Table 15:USB

Parameter	Min	Type	Max	Unit
3V3_USB for correct USB operation(internal)	3.10	3.30	3.60	V
Input Threshold				
V _{IL} - input logic level low	-	=	0.3X3V3_USB	V
V _{IH} - input logic level high	0.7X3V3_USB -		-	V
Output Voltage Levels to Correctly Terminated USB Cable				
V _{OL} - output logic level low	0	-	0.2	V
V _{OH} - output logic level high	2.8	-	3V3_USB	V

5.3.4LED Driver Pads

Table 16:LED Driver Pads

Parameter	Min	Type	Max	Unit
Current, I _{PAD} - High impedance state	-	=	5	uA
Current, I _{PAD} -Current sink state	-	-	10	mA
LED pad voltage, $V_{PAD}I_{PAD} = 10mA$	-	-	0.55	V
LED pad resistanceV _{PAD} < 0.5V	-	=	40	Ω



5.4 Stereo Codec

5.4.1 Analogue to Digital Converter

Table 17: Analogue to Digital Converter

Parameter	Ccnditions		Min	Type	Max	Unit
Resolution	-		-	-	16	Bits
Input Sample Rate,	-		8	-	48	KHz
F _{sample}						
SNR	f _{in} = 1kHz	F sample				
	$B/W = 20Hz -> F_{sample}/2$	8kHz	-	93	-	dB
	(20kHz max)	16kHz	-	92	-	dB
	A-Weighted	32kHz	-	92	-	dB
	THD+N < 0.1%	44.1kHz	-	92	-	dB
	1.6V _{pk-pk} input	48kHz	-	92	-	dB
THD+N	f _{in} = 1kHz	F sample				
	B/W = 20 Hz->F _{sample} /2 (20 kHz max)	8kHz	-	0.004	-	%
	1.6V _{pk-pk} input	48kHz	-	0.008	-	%
Digital gain	Digital gain resolution = 1/32		-24	-	21.5	dB
Analogue gain	Pre-amplifier setting = 0dB, 9dB,	21dB or30dB	-3	-	42	dB
	Analogue setting = -3dB to 12dB	in 3dBsteps				
Stereo separation (cro	osstalk)		_	-89	_	dB

5.4.1 Digital to Analogue Converter

 Table 18:Digital to Analogue Converter

Parameter	Ccndi	tions		Min	Туре	Max	Unit
Resolution	-			-	-	16	Bits
Output Sample Rate,	-			8	-	96	KHz
F sample							
SNR	f _{in} = 1kHz	F sample	Load				
	B/W = 20Hz -> 20KHz	48kHz	100ΚΩ	-	96	-	dB
	A-Weighted	48kHz	32Ω	-	96	-	dB
	THD+N < 0.1%	48kHz	16Ω	-	96	-	dB
	OdBFS input						
THD+N	f _{in} = 1kHz	F _{sample}	Load	-			
	B/W = 20Hz->20kHz 0dBFS input	8kHz	100ΚΩ	-	0.002	-	%
	·	8kHz	32Ω	-	0.002	-	%
		8kHz	16Ω	-	0.003	-	%
		48kHz	100ΚΩ	-	0.003	-	%



		48kHz	32Ω	-	0.003	-	%
	_	48kHz	16Ω	-	0.004	-	%
Digital gain	Digital gain resolution = 1/3	2		-24	-	21.5	dB
Analogue gain	Analogue Gain Resolution =	Analogue Gain Resolution = 3dB			-	0	dB
Output voltage	Full-scale swing (differential)		-	-	778	mV
							rms
Stereo separation (Stereo separation (crosstalk)			-	-88	-	dB

5.5Auxiliary ADC

Table 19: Auxiliary ADC

Parameter		Min	Туре	Max	Unit
Resolution		-	-	10	Bits
Input voltage range (a)		0	-	1.8	V
Accuracy	INL	-1	-	1	LSB
(Guaranteed monotonic)	DHL	0	-	1	LSB
Offset		-1	-	1	LSB
Gain error		-0.8	-	0.8	%
Input bandwidth		-	100	-	KHz
Conversion time		1.38	1.69	2.75	uS
Sample rate (b)		-	-	700	Samples/s

⁽a) LSB size = 1.8V/1023

5.6Auxiliary DAC

Table 20:Auxiliary DAC

Parameter	Min	Туре	Max	Unit		
Resolution	-	-	10	Bits		
Supply voltage, VDD_AUX	1.30	1.35	1.40	V		
Output voltage range	0	-	VDD_AUX	V		
Full-scale output voltage	-1	1.35	1.40	V		
LSB size	1.30	1.32	2.64	mV		
Offset	0	0	1.32	mV		
Integral non-linearity	-1.32	0	1	LSB		
Settling time (a)	-1	-	250	nS		
(a) The settling time does not include any capacitive load						

⁽b) The auxiliary ADC is accessed through a VM function. The sample rate given is achieved as part of this function.



5.71²C Dynamic Characteristics

Table 21: I²C Dynamic Characteristics

Dovometer	Standard N	Standard Mode[1][2]		Fast Mode[1][2]	
Parameter	Min	Max	Min	Max	Unit
t _{LOW} - SCL low period	4.7	=	1.2	=	uS
T _{HIGH} - SCL high period	4	-	0.6	=	uS
t _{SU; STA} - Repeated START condition setup	4.7	-	1.2	=	uS
time					
t _{HD; STA} - START condition hold time	4	-	0.6	-	uS
t _{SU; STO} - STOP condition setup time	4	-	0.6	-	uS
t _{BUF} - Bus free time	4.7[3]	-	1.2[3]	-	uS
t _{SU;DAT} - Data setup time	250	-	100	-	uS
t _{HD;DAT} - Data hold time	0[4]	3.45[5]	0[4]	0.8[5]	uS
t _r - SCL/SDA rise time	-	1000	20+0.1CB	300	uS
t _f - SCL/SDA fall time	-	300	-	300	uS
C _b - Capacitive load for each bus line	=	400	-	400	pF

Note:

- 1. Guaranteed by design, not tested in production.
- 2. HCLK must be higher than 2 MHz to achieve the maximum standard mode I²C frequency. It must be higher than 8 MHz to achieve the maximum fast mode I2C frequency.
- 3. I2C controller must be retriggered immediately at slave mode after receiving STOP condition.
- 4. The device must internally provide a hold time of at least 300 ns for the SDA signal in order to bridge the undefined region of the falling edge of SCL.
- 5. The maximum hold time of the Start condition has only to be met if the interface does not stretch the low period of SCL signal.

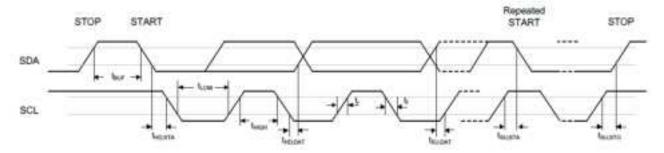


Figure 32: I²C Timing Diagram



5.8PCM Dynamic Characteristics

Table 22:PCM Dynamic Characteristics

Parameter	Min	Тур	Max	Unit
PCM Master Timing	•			
f _{mclk} - PCM_CLK frequency	-	128	-	KHz
4MHz DDS generation. Selection of frequency is programmable.		256		
		512		
f _{mclk} - PCM_CLK frequency	2.9	-	-	KHz
48MHz DDSgeneration. Selectionof frequency isprogrammable.				
PCM_SYNC frequency for SCO connection	-	8	-	KHz
t mclkh (a) - PCM_CLK high4MHz DDS generation	980	-	-	nS
t _{mclkl} (a)- PCM_CLK low 4MHz DDS generation	730	-	-	nS
PCM_CLK jitter48MHz DDS generation	-	-	21	ns pk-p
t dmclksynch - Delay time from PCM_CLK high to PCM_SYNChigh	-	-	20	nS
t dmclkpout - Delay time from PCM_CLK high to valid PCM_OUT	-	-	20	nS
t dmclklsyncl - Delay time from PCM_CLK low to PCM_SYNClow (Long	-	-	20	nS
Frame Sync only)				
t dmclkhsyncl - Delay time from PCM_CLK high to PCM_SYNClow	-	-	20	nS
t _{dmclklpoutz} - Delay time from PCM_CLK low to PCM_OUT high impedance	-	-	20	nS
t dmclkhpoutz - Delay time from PCM_CLK high to PCM_OUT high impedance	-	-	20	nS
t _{supinclkl} - Set-up time for PCM_IN valid to PCM_CLK low	20	-	-	nS
hpinclkl - Hold time for PCM_CLK low to PCM_IN invalid	0	-	-	nS

PCM	SI	ave Timing
f	_	PCM clock

· · · · · · · · · · · · · · · · · · ·				
f sclk - PCM clock frequency (Slave mode: input)	64	-	2048	kHz
f sclk - PCM clock frequency (GCI mode)	128	-	4096	kHz
t sclkl - PCM_CLK low time	200	-	-	nS
t sclkh - PCM_CLK high time	200	-	-	nS
t hsclksynch - Hold time from PCM_CLK low to PCM_SYNC high	2	-	-	nS
t susclksynch - Set-up time for PCM_SYNC high to PCM_CLK low	20	-	-	nS
t dpout - Delay time from PCM_SYNC or PCM_CLK, whichever is later, to	-	-	20	nS
valid PCM_OUT data (Long Frame Sync only)				
t dsclkhpout - Delay time from CLK high to PCM_OUT valid data	-	-	15	nS
t dpoutz - Delay time from PCM_SYNC or PCM_CLK low, whichever is	-	-	15	nS
later, to PCM_OUT data line high impedance				
t supinsclkl - Set-up time for PCM_IN valid to CLK low	20	-	-	nS
t hpinsclki - Hold time for PCM_CLK low to PCM_IN invalid	2	-	-	nS



5.91²S Dynamic Characteristics

Table 23: I²S Dynamic Characteristics

Parameter	Min	Тур	Max	Unit
Digital Audio Interface Slave Timing				
SCK Frequency	-	-	6.2	MHz
WS Frequency	-	-	9.6	KHz
t _{ch} - SCK high time	80	-	-	nS
t _{cl} - SCK low time	80	-	-	nS
I2S Slave Mode Timing				
t _{ssu} - WS valid to SCK high set-uptime	20	-	-	nS
t _{sh} - SCK high to WS invalid holdtime	2.5	-	-	nS
t _{opd} - SCK low to SD_OUT valid delay time	-	-	20	nS
t _{isu} - SD_IN valid to SCK high set-uptime	20	-	-	nS
t _{in} - SCK high to SD_IN invalid hold time	2.5	-	-	nS
Digital Audio Interface Master Timing				
SCK Frequency	-	-	6.2	MHz
WS Frequency	-	-	9.6	KHz
I2S Master Mode Timing Parameters,WS and SCK as Outputs				
t _{spd} - SCK low to WS valid delay time	-	=	39.27	nS
t _{opd} - SCK low to SD_OUT valid delay time	-	-	18.44	nS
t _{isu} - SD_IN valid to SCK high set-uptime	18.44	-	-	nS
t _{ih} - SCK high to SD_IN invalid holdtime	0	-	-	nS

5.10 Power consumptions

Table 24: Power consumptions

Table 24: Power Consumptions			
Parameter	Test Conditions	Туре	Unit
Bluetooth 2.1 Operation Mode	Current Consumption, Power supply 3.0V		
Idle	Power on, discoverable and connectable.	~3.8	mA
Searching	Searching devices	~6.8	mA
Connected Standby	Connected, no data traffic	~3.7	mA
(e)SCO traffic	Handsfree calling	~16	mA
RX/TX active	UART data traffic	~8	mA
Bluetooth 4.0 Operation Mode	Current Consumption, Power supply 3.0V		
Advertising	Advertising	~3.8	mA
Connected Standby	Connected, no data traffic	~4.3	mA
RX/TX active	UART data traffic	~3.6	mA



Bluetooth 2.1 Operation Mode	Current Consumption, Power supply 3.3V		
Idle	Power on, discoverable and connectable.	~3.6	mA
Searching	Searching devices	~6.3	mA
Connected Standby	Connected, no data traffic	~3.4	mA
(e)SCO traffic	Handsfree calling	~15	mA
RX/TX active	UART data traffic	~7	mA
Bluetooth 4.0/5.0Operation Mode	Current Consumption, Power supply 3.3V		
Advertising	Advertising	~3.8	mA
Connected Standby	Connected, no data traffic	~4.0	mA
RX/TX active	UART data traffic	~4.1	mA

6. MSL &ESDProtection

Table 25:MSL and ESD

Parameter	Class	Max Rating	
MSL grade(with JEDEC J-STD-020)		MSL 3	
Human Body Model Contact Discharge per	2	2kV	
ANSI/ESDA/JEDEC JS-001			
Machine Model Contact Discharge per	200V	200V (all pins)	
JEDEC/EIA JESD22-A115			
Charged Device Model Contact Discharge per	II	200V (all pins)	
JEDEC/EIA JESD22-C101			

6.1USB Electrostatic Discharge Immunity

FSC-BT806 has integrated ESD protection on the USB_DP and USB_DN pins as detailed in IEC 61000-4-2.

 Table 26:USB Electrostatic Discharge Protection Level

IEC 61000-4-2 Level	ESD Test Voltage (Positive and Negative)	IEC 61000-4-2 Classification	Comments
1	2kV contact / 2kV air	Class 1	Normal performance within specificationlimits
2	4kV contact / 4kV air	Class 1	Normal performance within specificationlimits
3	6kV contact / 8kV air	Class 2 or class 3	Temporary degradation or operatorintervention required
4	8kV contact / 15kV air	Class 2 or class 3	Temporary degradation or operatorintervention required



7. RECOMMENDED TEMPERATURE REFLOW PROFILE

Prior to any reflow, it is important to ensure the modules were packaged to prevent moisture absorption. New packages contain desiccate (to absorb moisture) and a humidity indicator card to display the level maintained during storage and shipment. If directed to bake units on the card, please check the below **Table 27** and follow instructions specified by IPC/JEDEC J-STD-033.

Note: The shipping tray cannot be heated above 65°C. If baking is required at the higher temperatures displayed in the below **Table 27**, the modules must be removed from the shipping tray.

Any modules not manufactured before exceeding their floor life should be re-packaged with fresh desiccate and a new humidity indicator card. Floor life for MSL (Moisture Sensitivity Level) 3 devices is 168 hours in ambient environment 30°C/60%RH.

Table 27:Recommended baking times and temperatures

	125°C Bal	king Temp.	90°C/≤ 5%RH	Baking Temp.	40°C/ ≤ 5%RF	l Baking Temp.
MSL	Saturated @	Floor Life Limit	Saturated @	Floor Life Limit	Saturated@	Floor Life Limit
IVISL	30°C/85%	+ 72 hours @	30°C/85%	+ 72 hours @	30°C/85%	+ 72 hours @
		30°C/60%		30°C/60%		30°C/60%
3	9 hours	7 hours	33 hours	23 hours	13 days	9 days

Feasycom surface mount modules are designed to be easily manufactured, including reflow soldering to a PCB. Ultimately it is the responsibility of the customer to choose the appropriate solder paste and to ensure oven temperatures during reflow meet the requirements of the solder paste. Feasycom surface mount modules conform to J-STD-020D1 standards for reflow temperatures.

The soldering profile depends on various parameters necessitating a set up for each application. The data here is given only for guidance on solder reflow.

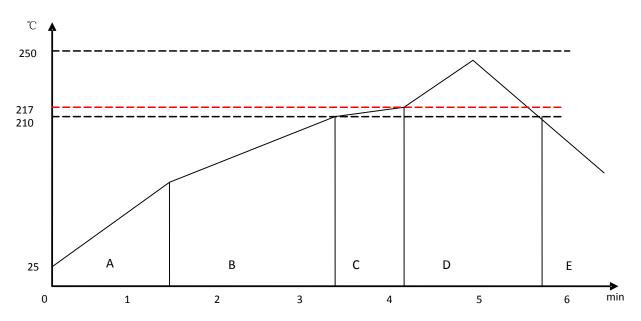


Figure 33: Typical Lead-free Re-flow

Pre-heat zone (A) — This zone raises the temperature at a controlled rate, **typically 0.5 – 2 °C/s**. The purpose of this zone is to preheat the PCB board and components to $120 \sim 150$ °C. This stage is required to distribute the heat uniformly to the PCB board and completely remove solvent to reduce the heat shock to components.

Equilibrium Zone 1 (B) — In this stage the flux becomes soft and uniformly encapsulates solder particles and spread over PCB board, preventing them from being re-oxidized. Also with elevation of temperature and liquefaction of flux,



each activator and rosin get activated and start eliminating oxide film formed on the surface of each solder particle and PCB board. The temperature is recommended to be 150° to 210° for 60 to 120 second for this zone.

Equilibrium Zone 2 (C) (optional) — In order to resolve the upright component issue, it is recommended to keep the temperature in 210 - 217 ° for about 20 to 30 second.

Reflow Zone (D) — The profile in the figure is designed for Sn/Ag3.0/Cu0.5. It can be a reference for other lead-free solder. The peak temperature should be high enough to achieve good wetting but not so high as to cause component discoloration or damage. Excessive soldering time can lead to intermetallic growth which can result in a brittle joint. The recommended peak temperature (Tp) is 230 $^{\sim}$ 250 $^{\circ}$ C. The soldering time should be 30 to 90 second when the temperature is above 217 $^{\circ}$ C.

Cooling Zone (E) — The cooling ate should be fast, to keep the solder grains small which will give a longer-lasting joint. **Typical cooling rate should be 4** °C.

8. MECHANICAL DETAILS

8.1 Mechanical Details

■ Dimension: 13mm(W) x 26.9mm(L) x 2.2mm(H) Tolerance: ±0.1mm

Module size: 13mm X 26.9mm Tolerance: ±0.2mm
 Pad size: 1.6mmX0.6mm Tolerance: ±0.2mm

■ Pad pitch: 1.0mm Tolerance: ±0.1mm

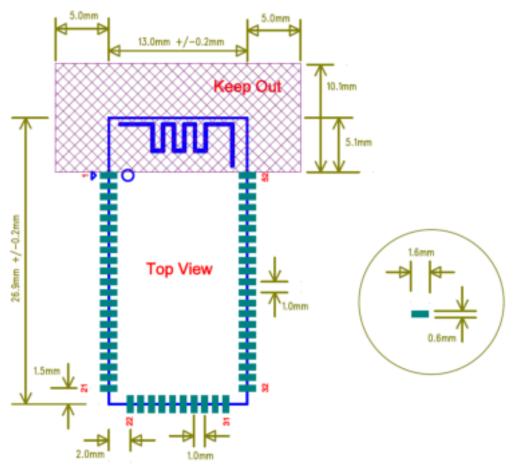


Figure 34: FSC-BT806footprint



9. HARDWARE INTEGRATION SUGGESTIONS

9.1 Soldering Recommendations

FSC-BT806 is compatible with industrial standard reflow profile for Pb-free solders. The reflow profile used is dependent on the thermal mass of the entire populated PCB, heat transfer efficiency of the oven and particular type of solder paste used. Consult the datasheet of particular solder paste for profile configurations.

Feasycom will give following recommendations for soldering the module to ensure reliable solder joint and operation of the module after soldering. Since the profile used is process and layout dependent, the optimum profile should be studied case by case. Thus following recommendation should be taken as a starting point guide.

9.2 Layout Guidelines(Internal Antenna)

It is strongly recommended to use good layout practices to ensure proper operation of the module. Placing copper or any metal near antenna deteriorates its operation by having effect on the matching properties. Metal shield around the antenna will prevent the radiation and thus metal case should not be used with the module. Use grounding vias separated max 3 mm apart at the edge of grounding areas to prevent RF penetrating inside the PCB and causing an unintentional resonator. Use GND vias all around the PCB edges.

The mother board should have no bare conductors or vias in this restricted area, because it is not covered by stop mask print. Also no copper (planes, traces or vias) are allowed in this area, because of mismatching the on-board antenna.

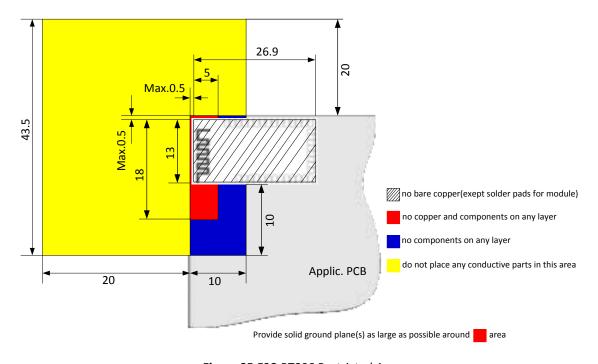


Figure 35:FSC-BT806 Restricted Area

Following recommendations helps to avoid EMC problems arising in the design. Note that each design is unique and the following list do not consider all basic design rules such as avoiding capacitive coupling between signal lines. Following list is aimed to avoid EMC problems caused by RF part of the module. Use good consideration to avoid problems arising from digital signals in the design.

Ensure that signal lines have return paths as short as possible. For example if a signal goes to an inner layer through a via, always use ground vias around it. Locate them tightly and symmetrically around the signal vias. Routing of any sensitive signals should be done in the inner layers of the PCB. Sensitive traces should have a ground area above and under the line. If this is not possible, make sure that the return path is short by other means (for example using a ground line next to the signal line).



9.3 Layout Guidelines(External Antenna)

Placement and PCB layout are critical to optimize the performances of a module without on-board antenna designs. The trace from the antenna port of the module to an external antenna should be 50Ω and must be as short as possible to avoid any interference into the transceiver of the module. The location of the external antenna and RF-IN port of the module should be kept away from any noise sources and digital traces. A matching network might be needed in between the external antenna and RF-IN port to better match the impedance to minimize the return loss.

As indicated in **Figure** below, RF critical circuits of the module should be clearly separated from any digital circuits on the system board. All RF circuits in the module are close to the antenna port. The module, then, should be placed in this way that module digital part towards your digital section of the system PCB.

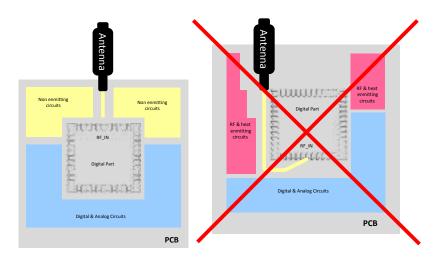


Figure 36: Placement the Module on a System Board

9.3.1 Antenna Connection and Grounding Plane Design

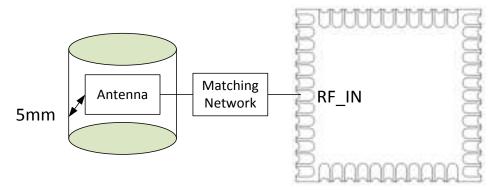


Figure 37: Leave 5mm Clearance Space from the Antenna

General design recommendations are:

- The length of the trace or connection line should be kept as short as possible.
- Distance between connection and ground area on the top layer should at least be as large as the dielectric thickness.
- Routing the RF close to digital sections of the system board should be avoided.



To reduce signal reflections, sharp angles in the routing of the micro strip line should be avoided. Chamfers or fillets are preferred for rectangular routing; 45-degree routing is preferred over Manhattan style 90-degree routing.

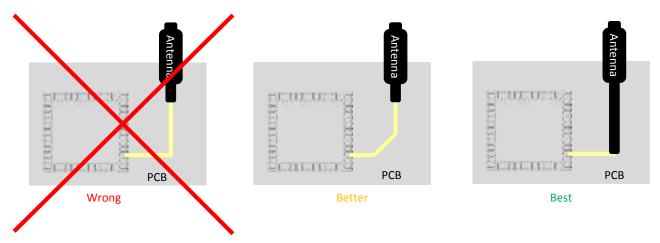


Figure 38: Recommended Trace Connects Antenna and the Module

- Routing of the RF-connection underneath the module should be avoided. The distance of the micro strip line to the ground plane on the bottom side of the receiver is very small and has huge tolerances. Therefore, the impedance of this part of the trace cannot be controlled.
- Use as many vias as possible to connect the ground planes.

10. PRODUCT PACKAGING INFORMATION

10.1 DefaultPacking

a, Tray vacuum

b, Tray Dimension: 180mm * 195mm

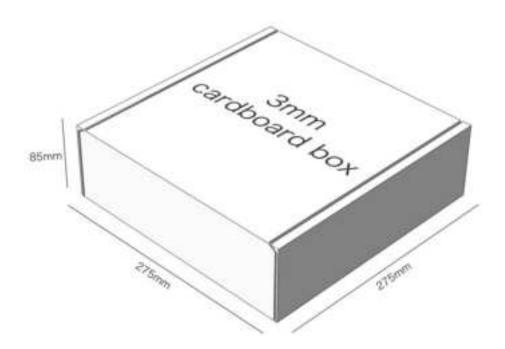






Figure 39: Tray vacuum

10.2 Packing box(Optional)



- * If require any other packing, must be confirmed with customer
- * Package: 2000PCS Per Carton (Min Carton Package)

Figure 40: Packing Box



11. APPLICATION SCHEMATIC

11.1Application circuit diagram(Default)



11.2Application circuit diagram(Earphone)

FCC/IC Statements

(OEM) Integrator has to assure compliance of the entire end-product incl. the integrated RF Module. For 15 B (§15.107 and if applicable §15.109) compliance, the host manufacturer is required to show compliance with 15 while the module is installed and operating.

Furthermore the module should be transmitting and the evaluation should confirm that the module'sintentional emissions (15C) are compliant (fundamental / out-of-band). Finally the integrator has to apply the appropriate equipment authorization (e.g. Verification) for the new host device per definition in §15.101.

Integrator is reminded to assure that these installation instructions will not be made available to the end-user of the final host device.

The final host device, into which this RF Module isintegrated" hasto be labeled with an auxiliary label stating the FCC IDofthe RF Module, such as "Contains FCC ID: 2AMWOFSC-BT806"

"This device complies with part 15 of the FCC rules. Operation is subject to the following two conditions:

- (1)this device may not cause harmful interference, and
- (2)this device must accept any interference received, including interference that may cause undesired operation."

"Changes or modifications to this unit not expressly approved by the party responsible for compliance could void the user's authority to operate the equipment."

the Integrator will be responsible to satisfy SAR/ RF Exposure requirements, when the module integrated into the host device.

RF Exposure Warning Statements:

This equipment complies with FCC radiation exposure limits set forth for an uncontrolled environment.

This equipment shall be installed and operated with minimum distance 20cm between the radiator & body.

The final host device, into which this RF Module is integrated" has to be labeledwith an auxiliary label stating the IC ofthe RF Module, such as "Contains transmitter module IC: 23872-FSCBT806

Le périphériquehôte final, dans lequelce module RF est intégré "doitêtre étiqueté avec une étiquette auxiliaire indiquant le CI du module RF, tel que "Contient le module émetteur IC: 23872-FSCBT806"

This device complies with Industry Canada licence-exempt RSS standard(s). Operation is subject to the



following two conditions: (1)this device may not cause interference, and(2) this device must accept any interference, including interference that may cause undesired operation of the device.

Le présentappareilestconforme aux CNR d'Industrie Canada applicablesauxappareils radio exempts de licence. L'exploitationestautorisée aux deux conditions suivantes :(1) l'appareil ne doit pas produire de brouillage, et(2) l'utilisateur de l'appareildoit accepter tout brouillageradioélectriquesubi, mêmesi le brouillageest susceptible d'encompromettrelefonctionnement.

Radio Frequency Exposure Statement for IC

The device has been evaluated to meet general RF exposure requirements. The device can be used in mobile exposure conditions. The min separation distance is 20cm.

Déclaration d'exposition aux radiofréquences pour IC

L'appareil a été évalué pour répondre aux exigences générales en matière d'exposition aux RF. L'appareil peut être utilisé dans des conditions d'exposition mobiles. La distance de séparation minimale est de 20 cm.

Module statement

The single-modular transmitter is a self-contained, physically delineated, component for which compliance can be demonstrated independent of the host operating conditions, and which complies with all eight requirements of § 15.212(a)(1) as summarized below.

- 1) The radio elements have the radio frequency circuitry shielded.
- 2) The module has buffered modulation/data inputs to ensure that the device will complywith Part 15 requirements with any type of input signal.
- 3) The module contains power supply regulation on the module.
- 4) The module contains a permanently attached antenna.
- 5) The module demonstrates compliance in a stand-alone configuration.
- 6) The module is labeled with its permanently affixed FCC ID label.
- 7) The module complies with all specific rules applicable to the transmitter, including all the conditions provided in the integration instructions by the grantee.
- 8) The module complies with RF exposure requirements.

NOTE: This equipment has been tested and found to comply with the limits for a Class B digital device, pursuant to part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference in a residential installation. This equipment generates uses and can radiate radio frequency energy and, if not installed and used in accordance with the instructions, may cause harmful interference to radio communications. However, there is no guarantee that interference will not occur in a particular installation. If this equipment does cause harmful interference to radio or television reception, which can be determined by turning the equipment off and on, the user is encouraged to try to correct the interference by one or more of the following measures:

- Reorient or relocate the receiving antenna.

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- Increase the separation between the equipment and receiver.
- -Connect the equipment into an outlet on a circuit different from that to which the receiver is connected.
- -Consult the dealer or an experienced radio/TV technician for help

Co-location Warning:

This equipment could not be co-located or operating in conjunction with any other antenna or transmitter except in accordance with the FCC multi-transmitter product procedures.