Allen-Bradley

PowerFlex® Communications

DPI Wireless Interface Module

20-WIM-N1
20-WIM-N4S
PowerFlex 70 NEMA 4/12 WIM

FRN 1.xxx

FINAL DRAFT (as of 1-21-2005)

User Manual

Rockwell Automation

Important User Information

Solid state equipment has operational characteristics differing from those of electromechanical equipment. *Safety Guidelines for the Application, Installation and Maintenance of Solid State Controls* (Publication SGI-1.1 available from your local Rockwell Automation sales office or online at **http://www.rockwellautomation.com/literature**) describes some important differences between solid state equipment and hard-wired electromechanical devices. Because of this difference, and also because of the wide variety of uses for solid state equipment, all persons responsible for applying this equipment must satisfy themselves that each intended application of this equipment is acceptable.

In no event will Rockwell Automation, Inc. be responsible or liable for indirect or consequential damages resulting from the use or application of this equipment.

The examples and diagrams in this manual are included solely for illustrative purposes. Because of the many variables and requirements associated with any particular installation, Rockwell Automation, Inc. cannot assume responsibility or liability for actual use based on the examples and diagrams.

No patent liability is assumed by Rockwell Automation, Inc. with respect to use of information, circuits, equipment, or software described in this manual.

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Throughout this manual, when necessary we use notes to make you aware of safety considerations.

WARNING: Identifies information about practices or circumstances that can cause an explosion in a hazardous environment, which may lead to personal injury or death, property damage, or economic loss.

Important: Identifies information that is critical for successful application and understanding of the product.

ATTENTION: Identifies information about practices or circumstances that can lead to personal injury or death, property damage, or economic loss. Attentions help you:

- identify a hazard
- avoid the hazard
- recognize the consequences

Shock Hazard labels may be located on or inside the equipment (e.g., drive or motor) to alert people that dangerous voltage may be present.

Burn Hazard labels may be located on or inside the equipment (e.g., drive or motor) to alert people that surfaces may be at dangerous temperatures.

Summary of Changes

This is the first release of the 20-WIM-N* Wireless Interface Module FRN 1.xxx.

Table of Contents

About This Manual

Related Documentation

For:	Refer to:	Publication
Pocket DriveExplorer™ for Pocket PC	http://www.ab.com/drives/driveexplorer, and Pocket DriveExplorer for Pocket PC online help (installed with the software)	—
DriveExplorer™	http://www.ab.com/drives/driveexplorer, and DriveExplorer online help (installed with the software)	—
DriveTools™ SP (includes DriveExecutive™)	http://www.ab.com/drives/drivetools, and DriveExecutive online help (installed with the software)	—
HIM	*HIM Quick Reference*	20HIM-QR001…
PowerFlex® 70/70EC Drive	*PowerFlex 70 User Manual* *PowerFlex 70/700 Reference Manual*	20A-UM001… PFLEX-RM001…
PowerFlex® 700/700VC Drive PowerFlex® 700 Series B Drive	*PowerFlex 700 User Manual* *PowerFlex 700 Series B User Manual* *PowerFlex 70/700 Reference Manual*	20B-UM001… 20B-UM002… PFLEX-RM001…
PowerFlex® 700H Drive	*PowerFlex 700H Installation Instructions* *PowerFlex 700H Programming Manual*	PFLEX-IN006… 20C-PM001…
PowerFlex® 700S Drive (Frames 1 through 6)	*PowerFlex 700S with Phase I Control User Manual* *PowerFlex 700S with Phase II Control User Manual* *PowerFlex 700S Reference Manual*	20D-UM001… 20D-UM006… PFLEX-RM002…
PowerFlex® 700S Drive (Frames 9 through 11)	*PowerFlex 700S Installation Instructions* *PowerFlex 700S with Phase I Control User Manual* *PowerFlex 700S with Phase II Control User Manual* *PowerFlex 700S Reference Manual*	PFLEX-IN006… 20D-UM001… 20D-UM006… PFLEX-RM002…
RSLinx™ or RSLinx Lite	*Getting Results with RSLinx Guide* Online help (installed with the software)	LINX-GR001…
Bluetooth® wireless technology	http://www.Bluetooth.org or http://www.Bluetooth.com	—

Documentation can be obtained online at **http://www.rockwellautomation.com/literature**.

Conventions Used in This Manual

The following conventions are used throughout this manual:

- Parameter names are shown in the format **Parameter xx - [*]**. The xx represents the parameter number. The * represents the parameter name. For example **Parameter 01 - [DPI Port]**.
- Menu commands are shown in bold type face and follow the format **Menu > Command**. For example, if you read “Select **File > Open**,” you should click the **File** menu and then click the **Open** command.
- The firmware release is displayed as FRN X.xxx. The “FRN” signifies Firmware Release Number. The “X” is the major release number. The “xxx” is the minor update number.
- Pocket DriveExplorer for Pocket PC (version 1.01), My Bluetooth Places software (version 1.4.2), DriveExplorer Lite (version 4.04), and DriveExecutive (version 3.01) were used for the screen pictures in this manual. Different versions of the software may differ in appearance and procedures.
- This manual provides information about the 20-WIM-N* Wireless Interface Module (WIM) and using it with PowerFlex 7-Class drives. The module can be used with other products that support DPI or SCANport.

Rockwell Automation Support

Rockwell Automation, Inc. offers support services worldwide, with over 75 sales/support offices, over 500 authorized distributors, and over 250 authorized systems integrators located through the United States alone. In addition, Rockwell Automation, Inc. representatives are in every major country in the world.

Local Product Support

Contact your local Rockwell Automation, Inc. representative for:

- Sales and order support
- Product technical training
- Warranty support
- Support service agreements

Technical Product Assistance

If you need to contact Rockwell Automation, Inc. for technical assistance, please review the information in Chapter 4, Troubleshooting, first. If you still have problems, call your local Rockwell Automation, Inc. representative.

U.S. Allen-Bradley Drives Technical Support:
E-mail: support@drives.ra.rockwell.com
Tel: (1) 262.512.8176
Fax (1) 262.512.2222
Online: www.ab.com/support/abdrives

UK Customer Support Center:
E-mail: esupport2@ra.rockwell.com
Tel: +44 (0) 870 2411802
Fax: +44 (0) 1908 838804

Germany Customer Service Center:
E-mail: ragermany-csc@ra.rockwell.com
Tel: +49 (0) 2104 960-630
Fax: +49 (0) 2104 960-501

Notes:

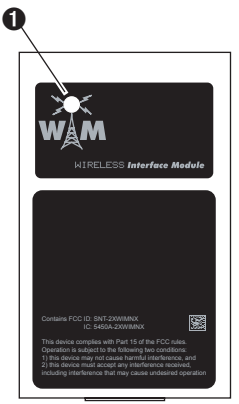
Getting Started

The 20-WIM-N* Wireless Interface Module (WIM) provides a wireless communications interface between a Pocket PC, laptop computer or desktop computer equipped with *Bluetooth* wireless technology and any Allen-Bradley product supporting DPI. The WIM uses the full-duplex DF1 protocol.

Important: The WIM also supports legacy Allen-Bradley AC drives that use the SCANport protocol.

Components

Figure 1.1 Components of the WIM



(NEMA 1 WIM shown)

Item	Part	Description
1	Status Indicator	LED that indicates WIM operation, when data is being received from the *Bluetooth* wireless technology enabled Pocket PC or computer, and when data is being sent to the Pocket PC or computer. Refer to Modes of Operation in this chapter, and Chapter 4, Troubleshooting for more information.

Features

Features of the WIM include the following:

- A status indicator (LED) that reports the operating status of the module.
- Connectivity to products implementing DPI, such as PowerFlex 7-Class drives and peripherals, and products implementing SCANport, such as legacy Allen-Bradley drives. When used with a product, the WIM will autobaud to the DPI or SCANport data rate that is used by the product.
- The WIM receives power from the drive. An outside power source is not needed.
- The following tools can be used to configure the WIM:
  - Pocket DriveExplorer for Pocket PC (version 1.01 or higher)
  - DriveExplorer (version 4.04 or higher)
  - DriveExecutive (version 3.01 or higher)
  - PowerFlex 7-Class HIM

DPI Compatible Products

DPI is a second generation peripheral communication interface. The WIM can be used with Allen-Bradley PowerFlex 7-Class drives and other products that support DPI. At the time of publication, compatible products include all the following types of:

- PowerFlex 70 drives
- PowerFlex 700 drives
- PowerFlex 700H drives
- PowerFlex 700S drives
- PowerFlex 7000 drives
- SMC-Flex

SCANport Compatible Products

The WIM is also compatible with drives and other products that support SCANport. At the time of publication, compatible products include:

- 1305 drives
- 1336 PLUS drives
- 1336 PLUS II drives
- 1336 IMPACT drives
- 1336 FORCE drives
- 1336 REGEN drives
- 1336 SPIDER drives
- 1394 Servo drives
- 1397 drives
- 1557 drives
- 2364F RGU
- SMC Dialog Plus
- SMP-3

Required Equipment

Equipment Shipped with the WIM

When you unpack the WIM, verify that the package includes:

- ❑ One Wireless Interface Module
- ❑ This manual

User-Supplied Equipment

To configure the WIM, you must use one of the following:

- ❑ Pocket DriveExplorer for Pocket PC software (version 1.01 or higher) running on a Pocket PC equipped with *Bluetooth* wireless technology
- ❑ DriveExplorer software (version 4.04 or higher) running on a laptop or desktop computer equipped with *Bluetooth* wireless technology
- ❑ DriveExecutive stand-alone software (version 3.01 or higher) or bundled with the DriveTools SP suite (version 1.01 or higher) running on a laptop or desktop computer equipped with *Bluetooth* wireless technology
- ❑ PowerFlex 7-Class HIM (20-HIM-*)

Safety Precautions

Please read the following safety precautions carefully.

ATTENTION: Risk of injury or death exists from machine motion when using wireless communications and software to Start/Stop/Jog, configure or otherwise communicate with a drive.

Using the control bar feature in Pocket DriveExplorer for Pocket PC, DriveExplorer or DriveExecutive with wireless communications may present safety hazards due to potential loss of the wireless connection. For example, if the wireless connection is interrupted after a start or jog command is initiated from the control bar, the drive cannot be stopped using the control bar until the wireless connection is restored. For this reason, it is required to always use an additional hard-wired stop circuit to disable the drive.

ATTENTION: Risk of injury or equipment damage exists. Only personnel familiar with drive and power products and the associated machinery should plan or implement the installation, start-up, configuration, and subsequent maintenance of the product using a WIM. Failure to comply may result in injury and/or equipment damage.

ATTENTION: Risk of injury or equipment damage exists. **Parameter 02 - [Comm Flt Action]** lets you determine the action of the WIM and connected drive if wireless communications are disrupted. By default, this parameter faults the drive. You can set this parameter so that the drive continues to run. Precautions should be taken to ensure that the setting of this parameter does not create a risk of injury or equipment damage. When commissioning the drive, verify that your system responds correctly to various situations (for example, a communication disruption or a faulted controller).

Quick Start

This section is designed to help experienced users quickly start using the WIM. If you are unsure how to complete a step, refer to the referenced chapter.

Step	Action	Refer to . . .
1	**Review the safety precautions for the WIM.**	Throughout this manual
2	**Install the WIM.** For the NEMA 1 WIM (20-WIM-N1), remove the HIM from the drive cradle and replace it with the WIM. To install the WIM in a remote-mounted HIM bezel (20-HIM-B1), first install the bezel (see Publication 20HIM-IN001...). Make sure the HIM bezel is connected to the drive port using the supplied 1203-C30 cable, and then place the WIM in the bezel cradle. For the NEMA 4 WIM (20-WIM-N4S), see Chapter 2, Installing the NEMA 4 WIM (20-WIM-N4S) for installation instructions.	Chapter 2, Installing the WIM
3	**Configure the WIM parameters.** The WIM is provided ready for use. It is only necessary to configure the WIM if you want to change the default setting (0 = Fault) for Parameter 02 - [Comm Flt Action], or enable the WIM security mode using Parameter 03 - [Security Mode] and Parameter 04 - [Security PIN].	Chapter 3, Configuring the WIM

Figure 1.2 NEMA 1 WIM (20-WIM-N1) Installed in a Drive

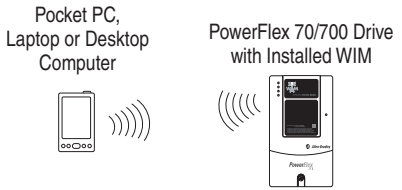
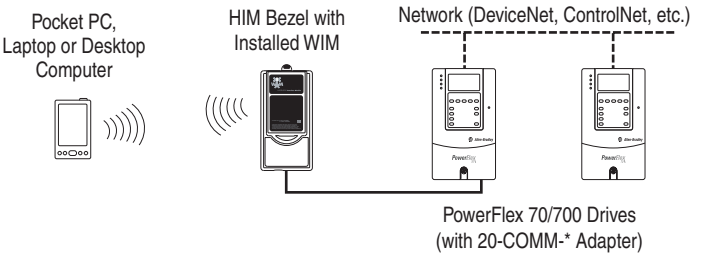


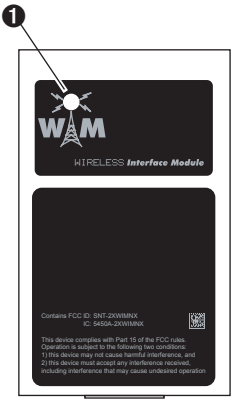
Figure 1.3 NEMA 1 WIM (20-WIM-N1) Installed in a HIM Bezel (20-HIM-B1)



Modes of Operation

The WIM reports its operating status using a tri-color status indicator (Figure 1.4).

Figure 1.4 Status Indications of the WIM



(NEMA 1 WIM shown)

The following table describes the status indications under normal operation:

Item	Status Indication	Description
1	Solid Blue	The WIM is receiving data from the *Bluetooth* wireless technology enabled Pocket PC or computer, or transmitting data to the Pocket PC or computer.
	Flickering Blue	The WIM is receiving a ping from the *Bluetooth* wireless technology enabled Pocket PC or computer as WIM data is transmitted back to the Pocket PC or computer.
	Flashing Green	The WIM is operating, but has not established wireless communication with the *Bluetooth* wireless technology enabled Pocket PC or computer.
	Flashing Red	The WIM is attempting to establish communications with the drive. This will occur momentarily during the power-up sequence and is normal.

If any other conditions occur, refer to Chapter 4, Troubleshooting.

Installing the WIM

This chapter provides instructions for installing and removing the WIM.

The WIM is offered in two styles: a NEMA 1 module (20-WIM-N1) and a NEMA 4 module (20-WIM-N4S). Each style is installed differently.

Installing the NEMA 1 WIM (20-WIM-N1)

The NEMA 1 WIM (20-WIM-N1) typically replaces the HIM, and is normally installed in the HIM (Human Interface Module) cradle on the front of the drive. When a HIM is still required and occupies the cradle, the 20-WIM-N1 module can be installed in a HIM bezel (20-HIM-B1) mounted in a remote location.

Installing the WIM in a Drive

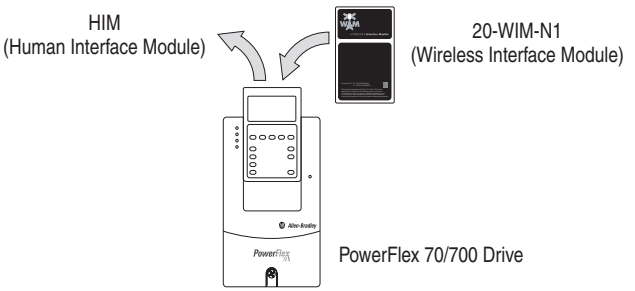
1. If a HIM is installed on the drive, remove the HIM, and replace it with the WIM (Figure 2.1).

   Important: If the drive is mounted in an enclosure, the NEMA 1 WIM must be installed in a HIM bezel or you must use a NEMA 4 WIM. Using the NEMA 1 WIM installed at the drive (DPI Port 1) in the enclosure will decrease wireless signal transfer, resulting in possible intermittent disconnection of the drive.

2. The status LED on the WIM momentarily flashes red on powerup and then flashes green to indicate it is ready to establish wireless communication with the Pocket PC or computer.

3. Establish wireless communication between the WIM and the Pocket PC or computer. For details, refer to Chapter 3, Using Pocket DriveExplorer for Pocket PC, Using DriveExplorer/DriveExplorer Lite, or Using DriveExecutive. When communication is achieved, the WIM status LED will turn solid blue.

Figure 2.1 Installing the WIM in a Drive



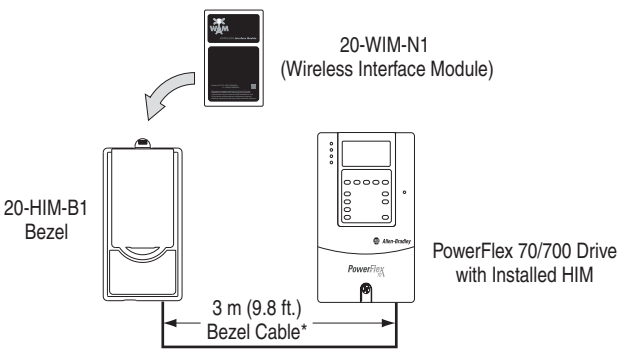
Installing the WIM in a HIM Bezel (20-HIM-B1)

1. If the HIM bezel is not mounted, refer to *Publication 20HIM-IN002...* for bezel installation instructions.

2. Route the bezel cable to the drive. Connect the bezel cable to the DPI port on the bottom of the drive.

3. Install the WIM into the HIM bezel cradle (Figure 2.2).

Figure 2.2 Installing the WIM in a HIM Bezel



Distance can be increased up to 100 m (328 ft.) using 1202-H Extension cable(s) or 1202-CBL-KIT-100M cable.
A cable distance greater than 30 m is not CE compliant.

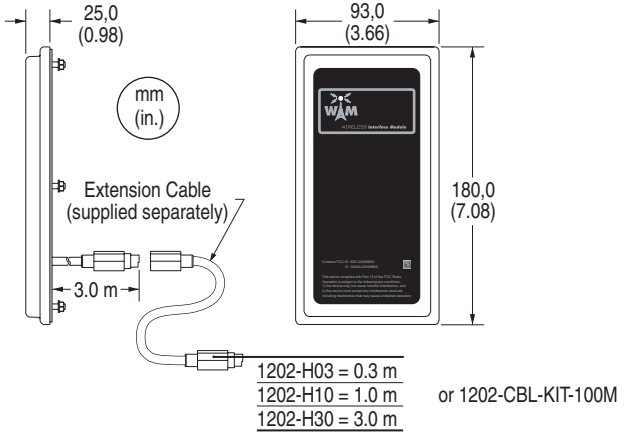
4. The status LED on the WIM momentarily flashes red on powerup and then flashes green to indicate it is ready to establish wireless communication with the Pocket PC or computer.

5. Establish wireless communication between the WIM and the Pocket PC or computer. For details, refer to Chapter 3, Using Pocket DriveExplorer for Pocket PC, Using DriveExplorer/DriveExplorer Lite, or Using DriveExecutive. When communication is achieved, the WIM status LED will turn solid blue.

Installing the NEMA 4 WIM (20-WIM-N4S)

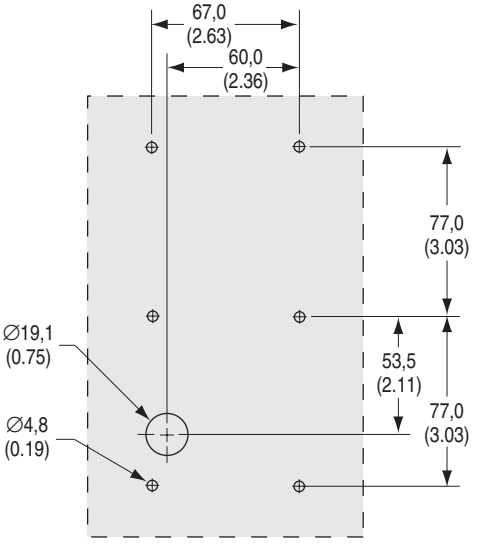
The NEMA 4 WIM (20-WIM-N4S) is designed for remote installation. Refer to Figure 2.3 for overall WIM dimensions. Choose an appropriate location to mount the NEMA 4 WIM. The distance between the WIM and drive can be increased up to 100 m (328 ft.) using 1202-H* extension cable(s) or 1202-CBL-KIT-100M cable. A cable distance greater than 30 m is not CE compliant.

Figure 2.3 NEMA 4 WIM Dimensions



1. Drill the required hole pattern in the panel. See Figure 2.4 for dimensions.

Figure 2.4 Hole Pattern for Mounting NEMA 4 WIM



2. Peel the protective film from the gasketed surface on the back of the WIM (Figure 2.5).

3. Insert the supplied 3 m (9.8 ft.) WIM cable into the mating socket on the back of the WIM.

4. Install the supplied O-ring into the cable routing hole on the panel to protect the cable. Then route the WIM cable through the cable routing hole on the panel.

5. Align the six threaded studs of the WIM with the panel clearance holes, and place the WIM against the panel.

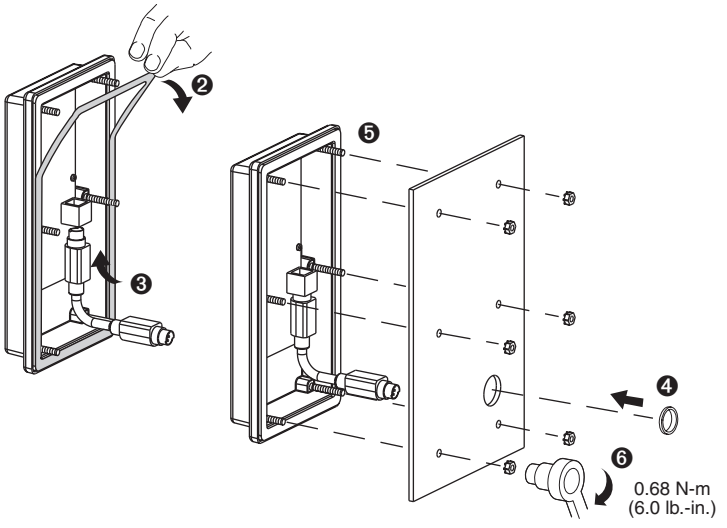
6. Tighten the nuts onto the six threaded studs of the WIM extending behind the panel. Recommended torque is 0.68 N-m (6.0 lb.-in.).

7. Route the WIM cable to the drive. Connect the WIM cable to the DPI port on the bottom of the drive.

8. Apply power to the drive. The status LED on the WIM momentarily flashes red on powerup and then flashes green to indicate it is ready to establish wireless communication with the Pocket PC or computer.

9. Establish wireless communication between the WIM and the Pocket PC or computer. For details, refer to Chapter 3, Using Pocket DriveExplorer for Pocket PC, Using DriveExplorer/DriveExplorer Lite, or Using DriveExecutive. When communication is achieved, the WIM status LED will turn solid blue.

Figure 2.5 Mounting NEMA 4 WIM onto Panel



Removing the NEMA 1 WIM (20-WIM-N1)

ATTENTION: Risk of injury or equipment damage exists. If the HIM bezel cable (for a bezel-mounted WIM) is disconnected from Port 2 on the bottom of the drive, the drive may fault. Determine how the drive will respond before disconnecting the cable.

The drive can remain powered when removing a WIM.

Remove the WIM from the drive HIM cradle or the remote-mounted HIM bezel.

Notes:

Configuring the WIM

This chapter provides information about configuring the WIM.

TIP: The WIM is provided ready for use. It is only necessary to configure the WIM if you want to change the default setting (0 = Fault) for **Parameter 02 - [Comm Flt Action]**, or enable the security mode using **Parameter 03 - [Security Mode]** and **Parameter 04 - [Security PIN]**.

For a list of parameters, refer to Appendix B, WIM Parameters. For definitions of terms in this chapter, refer to the Glossary.

Configuration Tools

The WIM stores parameters and other information in its own Non-Volatile Storage (NVS). You must, therefore, access the WIM to view and edit its parameters. The following table lists tools that you can use to access the WIM and edit its parameters.

Device Type	Tool	Refer to...
Pocket PC	Pocket DriveExplorer for Pocket PC (version 1.01 or higher)	page 3-2
Laptop or Desktop Computer	DriveExplorer software (version 4.04 or higher)	page 3-10
	DriveExecutive software (version 3.01 or higher)	page 3-15
	PowerFlex HIM	—

Using Pocket DriveExplorer for Pocket PC

With Pocket DriveExplorer for Pocket PC software running on a Pocket PC equipped with *Bluetooth* wireless technology, you can edit parameters in the WIM, connected drive, and any of the attached peripherals.

If you are unsure how to use Pocket DriveExplorer for Pocket PC, refer to the online help (select **Help > Help Topics**).

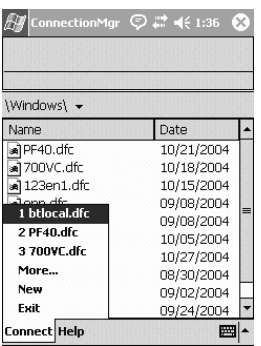
ATTENTION: Risk of injury or death exists from machine motion when using wireless communications and software to Start/Stop/Jog, configure or otherwise communicate with a drive.

Using the control bar feature in Pocket DriveExplorer for Pocket PC (version 2.01 or higher) with wireless communications may present safety hazards due to potential loss of the wireless connection. For example, if the wireless connection is interrupted after a start or jog command is initiated from the control bar, the drive cannot be stopped using the control bar until the wireless connection is restored. For this reason, it is required to always use an additional hard-wired stop circuit to disable the drive.

Establishing Wireless Communication Between the WIM and Pocket PC

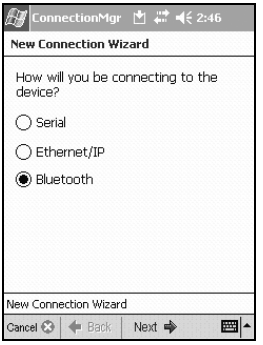
1. Launch Pocket DriveExplorer for Pocket PC from the Today Screen to create a new connection using the Connection Manager (Figure 3.1).

Figure 3.1 Connection Manager Screen



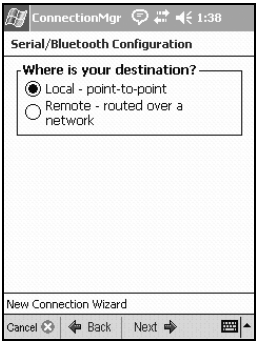
2. Select **Connect > New** from the menu list. The New Connection Wizard appears (Figure 3.2).

Figure 3.2 New Connection Wizard Screen



3. Select the "Bluetooth" radio button and click **Next ->**. The "Where is your destination?" screen appears (Figure 3.3).

Figure 3.3 "Where is your destination?" Screen



4. Select one of the radio button choices:

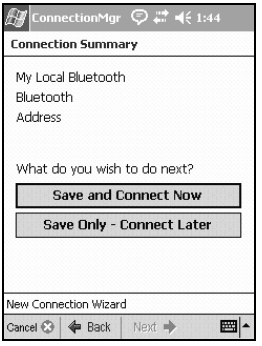
   - **Remote - routed over a network:** Choose “Remote” if you want to connect to a local drive using the 20-WIM and then route through it to a DeviceNet (via 20- COMM-D adapter), ControlNet (via 20-COMM-C adapter) or Ethernet (via 20-COMM-E adapter) remote device. If you select “Remote,” go to Step 10 on Page 3-7. Step 10 must be performed before proceeding with Step 5 on Page 3-4.

   - **Local - point-to-point:** Choose “Local” if you want to connect only to a local drive using the 20-WIM. Selecting “Local” and clicking **Next ->** displays the “Local Connection” screen (Figure 3.4) which requests you to name the connection for later reuse.

Figure 3.4 Local Connection Screen

5. Enter a name and click **Next ->**. The “Connection Summary” screen appears (Figure 3.5).

Figure 3.5 Connection Summary Screen



6. You can save the connection information and connect immediately, or save the connection for connecting later. Note that the top of this screen contains temporary diagnostic information.

   After clicking a choice, the "Location for saved connection" screen (Figure 3.6) appears, enabling you to navigate to a convenient location on the Pocket PC to store connections.

Figure 3.6 "Location for saved connection" Screen

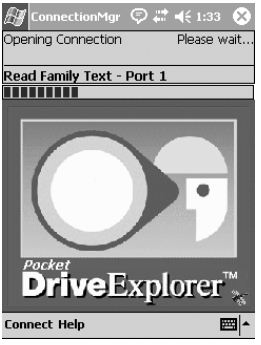
7. Click **OK** to save the connection file and begin the connection process. The "Searching for Bluetooth Connections" screen appears (Figure 3.7), asking you to select a detected Bluetooth device.

Figure 3.7 Searching for Bluetooth Connections Screen

8. Select the Bluetooth device from this screen and click **OK**. This screen only appears the first time you connect to this Bluetooth device. Its address is saved to the connection file. The next time you open the connection, if this same device is within range, Pocket DriveExplorer for Pocket PC will immediately connect.

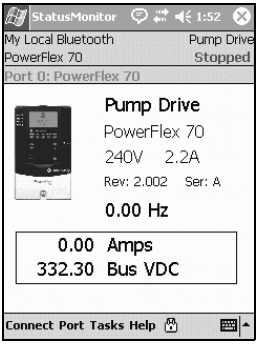
   The connection process then begins (Figure 3.8).

Figure 3.8 Opening Connection Screen



9. The status bar will update and then when connection is complete, the Status Monitor application will launch and show the "Status Monitor" screen (Figure 3.9).

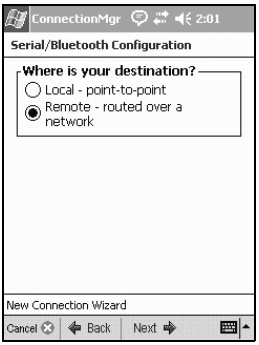
Figure 3.9 Status Monitor Screen



You can then select other devices from the Port menu, or other functions from the Tasks menu.

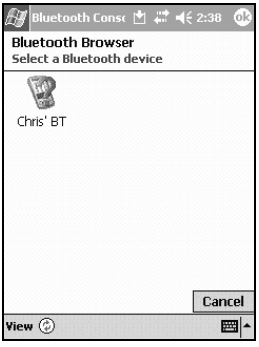
10. If you will be routing to a remote networked device, this additional step will need to be done using the New Connection Wizard. This requires that you are able to connect to the Bluetooth card/module (cannot be done offline) because Pocket DriveExplorer for Pocket PC must interrogate the device and determine what kinds of network adapters are present.

Figure 3.10 "Where is your destination?" Screen



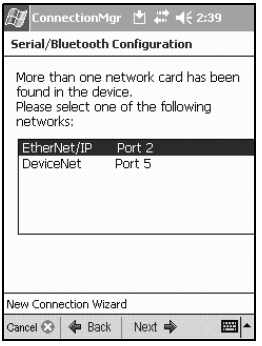
A. After selecting "Remote," click the **Next ->** button. Pocket DriveExplorer for Pocket PC will connect to the Bluetooth device (Figure 3.11).

Figure 3.11 Bluetooth Browser Screen



B. If the device has more than one network card, you will be prompted to select one (Figure 3.12), otherwise Pocket DriveExplorer for Pocket PC will present the next screen based on single network card detected.

Figure 3.12 "More than one network card..." Screen



C. You will need to select the address of the remote device on its network. See Figure 3.13 for DeviceNet and ControlNet, or Figure 3.14 for EtherNet/IP.

Figure 3.13 DeviceNet and ControlNet Remote Configuration Address Screen

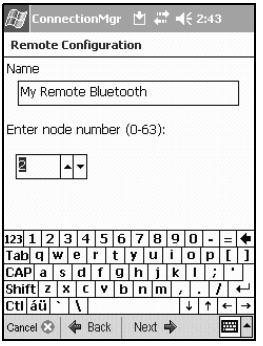
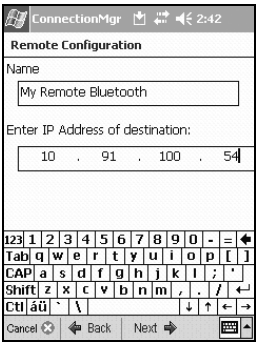


Figure 3.14 EtherNet/IP Remote Configuration Address Screen



D. Click the **Next ->** button and return back to Step 5 on Page 3-4 to continue.

Using DriveExplorer/DriveExplorer Lite

With DriveExplorer software running on a computer equipped with *Bluetooth* wireless technology, you can edit parameters in the WIM, connected drive, and any of the attached peripherals. DriveExplorer Lite, a free, limited-feature version of DriveExplorer, can be downloaded from http://www.ab.com/drives/driveexplorer.

If you are unsure how to use DriveExplorer or DriveExplorer Lite, refer to the online help (select **Help > Help Topics**).

ATTENTION: Risk of injury or death exists from machine motion when using wireless communications and software to Start/Stop/Jog, configure or otherwise communicate with a drive.

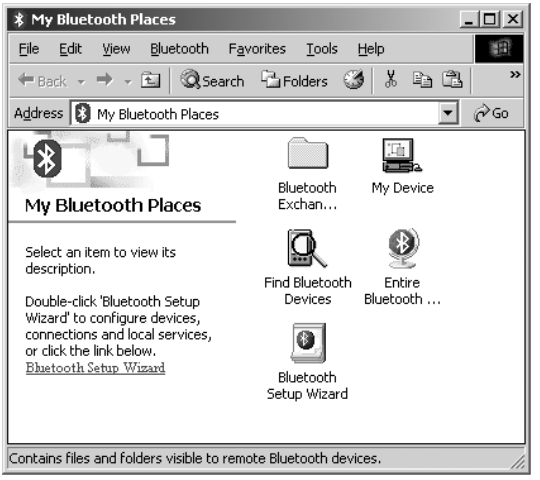
Using the control bar feature in DriveExplorer (version 2.01 or higher) with wireless communications may present safety hazards due to potential loss of the wireless connection. For example, if the wireless connection is interrupted after a start or jog command is initiated from the control bar, the drive cannot be stopped using the control bar until the wireless connection is restored. For this reason, it is required to always use an additional hard-wired stop circuit to disable the drive.

Establishing Wireless Communication Between the WIM and Computer

Bluetooth wireless technology enabled cards/modules installed in a computer are typically provided with a software program to establish communication with other wireless devices. The following example procedure describes how to establish communication using the software program “My Bluetooth Places” (version 1.4.2), which was included with a specific brand *Bluetooth* wireless technology module. Different versions of this software and different programs may differ in appearance and procedures.

1. Launch the “My Bluetooth Places” program. The program window will appear (Figure 3.15).

Figure 3.15 My Bluetooth Places Program Window



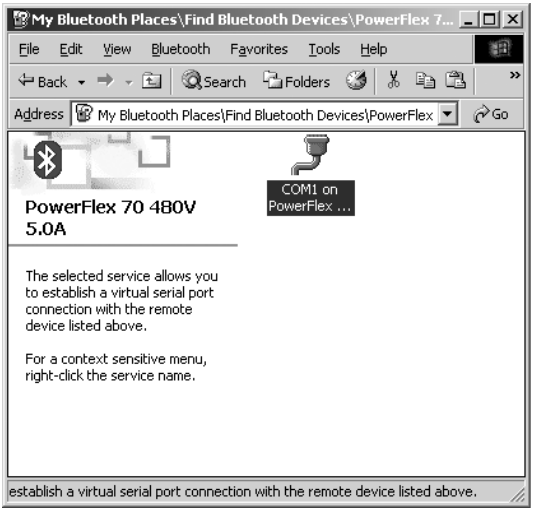
2. In the "My Bluetooth Places" program window, double-click the "Find Bluetooth Devices" icon, which starts a search to find the device to which you want to connect. The "Entire Bluetooth Neighborhood" window appears (Figure 3.16), displaying icons of all *Bluetooth* wireless technology enabled devices detected by the computer card or module that are within its reception range.

Important: Wait for the search to complete before proceeding.

Figure 3.16 Entire Bluetooth Neighborhood Window

3. In the “Entire Bluetooth Neighborhood” window, double-click on the device icon to which you want to establish wireless communication (for this example, the “PowerFlex 70” icon). The “PowerFlex 70” connection window will appear (Figure 3.17).

Figure 3.17 PowerFlex 70 Connection Window



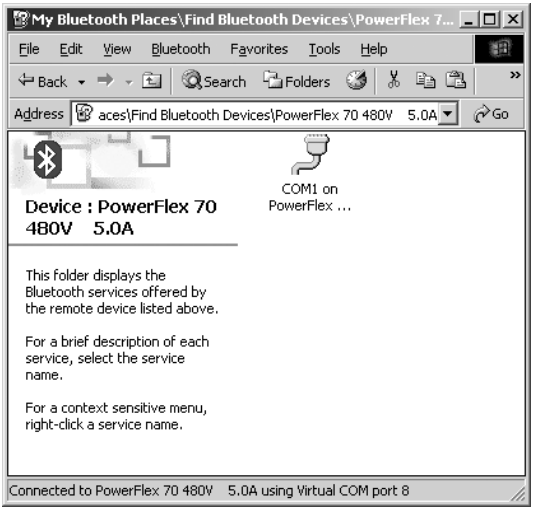
4. In the “PowerFlex 70” connection window, double-click the “COM1 on PowerFlex…” icon to initiate the wireless communication connection. A pop-up dialog box appears (Figure 3.18), indicating the specific COM port to use for the connection (COM8 for this example). Click **OK**.

Important: Always note the COM port shown in the dialog box because this same specific port must be selected in the DriveExplorer/DriveExplorer Lite Configure Communication window (Step 6).

Figure 3.18 COM8 Dialog Box

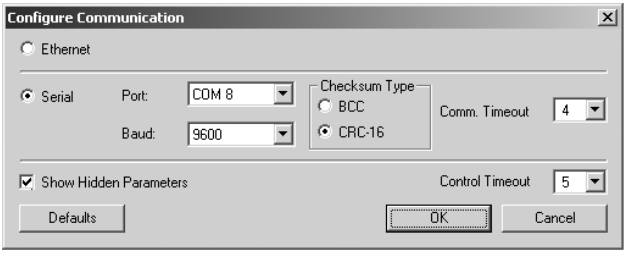
The “PowerFlex 70” connection window re-appears (Figure 3.19), but this time with the “COM1 on PowerFlex…” icon lit up in green, indicating that a wireless communication connection now exists.

Figure 3.19 PowerFlex 70 Connection Window with Lit Green Icon



5. Launch DriveExplorer or DriveExplorer Lite to access parameters in the WIM, connected drive, and any of the attached peripherals. Then select **Explore > Configure Communication**. The Configure Communication screen will appear (Figure 3.20).

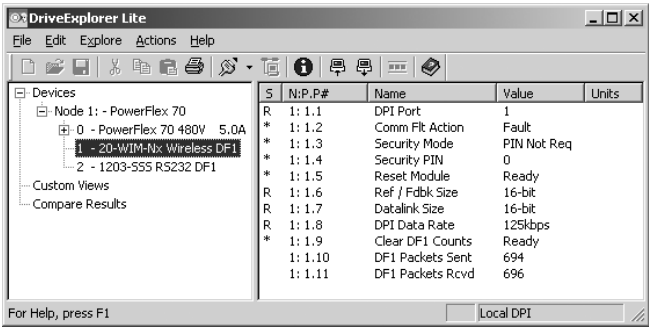
Figure 3.20 DriveExplorer/DriveExplorer Lite Configure Communication Screen



6. Select the same COM port established by the *Bluetooth* wireless technology enabled computer (noted in Step 4). For this example, COM8 is used. Then click **OK**.

7. In the DriveExplorer or DriveExplorer Lite window, select **Explore > Connect > Serial Point-to-Point** to display the DriveExplorer menu tree window. In the left pane, click the + signs to expand the tree. For this example, click on “20-WIM-Nx Wireless DF1” to display the WIM parameters in the right pane (Figure 3.21). Double-click a parameter to edit it.

Figure 3.21 DriveExplorer/DriveExplorer Lite Menu Tree Window



Using DriveExecutive

With DriveExecutive software running on a computer equipped with *Bluetooth* wireless technology, you can edit parameters in the WIM, connected drive, and any of the attached peripherals.

If you are unsure how to use DriveExecutive, refer to the online help (select **Help > Help Topics**).

ATTENTION: Risk of injury or death exists from machine motion when using wireless communications and software to Start/Stop/Jog, configure or otherwise communicate with a drive.

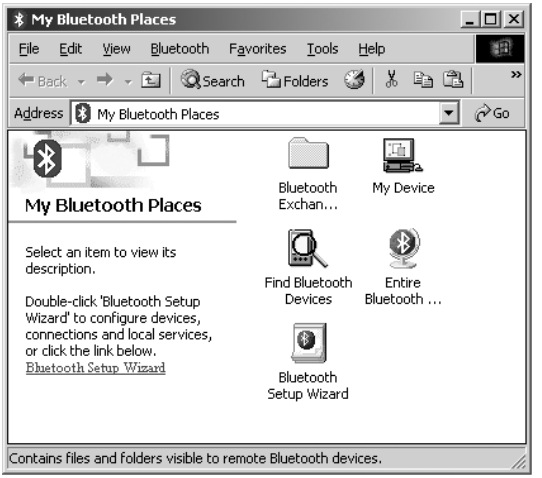
Using the control bar feature in DriveExecutive (version 4.01 or higher) with wireless communications may present safety hazards due to potential loss of the wireless connection. For example, if the wireless connection is interrupted after a start or jog command is initiated from the control bar, the drive cannot be stopped using the control bar until the wireless connection is restored. For this reason, it is required to always use an additional hard-wired stop circuit to disable the drive.

Establishing Wireless Communication Between the WIM and Computer

Bluetooth wireless technology enabled cards/modules installed in a computer are typically provided with a software program to establish communication with other wireless devices. The following example procedure describes how to establish communication using the software program “My Bluetooth Places” (version 1.4.2), which was included with a specific brand *Bluetooth* wireless technology module. Different versions of this software and different programs may differ in appearance and procedures.

1. Launch the “My Bluetooth Places” program. The program window will appear (Figure 3.22).

Figure 3.22 My Bluetooth Places Program Window



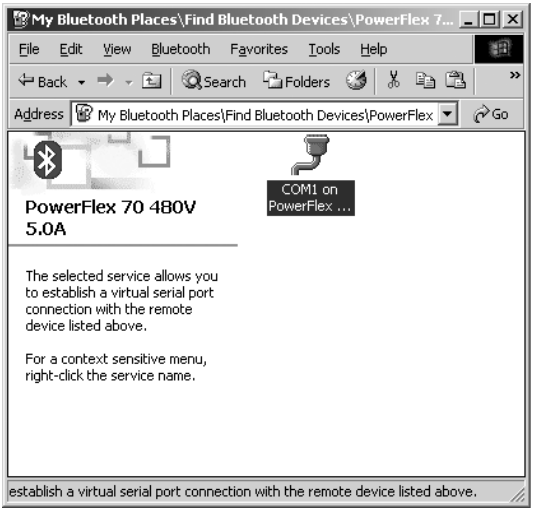
2. In the “My Bluetooth Places” program window, double-click the “Find Bluetooth Devices” icon, which starts a search to find the device to which you want to connect. The “Entire Bluetooth Neighborhood” window appears (Figure 3.23), displaying icons of all *Bluetooth* wireless technology enabled devices detected by the computer card or module that are within its reception range.

   Important: Wait for the search to complete before proceeding.

Figure 3.23 Entire Bluetooth Neighborhood Window

3. In the “Entire Bluetooth Neighborhood” window, double-click on the device icon to which you want to establish wireless communication (for this example, the “PowerFlex 70” icon). The “PowerFlex 70” connection window will appear (Figure 3.24).

Figure 3.24 PowerFlex 70 Connection Window



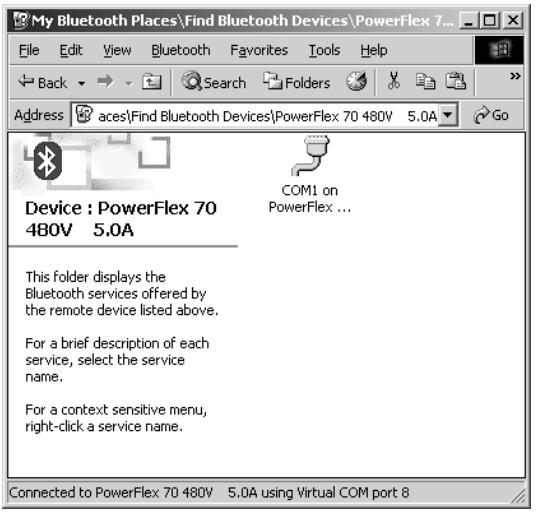
4. In the “PowerFlex 70”connection window, double-click the “COM1 on PowerFlex…” icon to initiate the wireless communication connection. A pop-up dialog box appears (Figure 3.25), indicating the specific COM port to use for the connection (COM8 for this example). Click **OK**.

Important: Always note the COM port shown in the dialog box because this same specific port must be selected in the RSLinx Configure RS-232 DF1 Devices window (Step 6).

Figure 3.25 COM8 Dialog Box

The “PowerFlex 70” connection window re-appears (Figure 3.26), but this time with the “COM1 on PowerFlex…” icon lit up in green, indicating that a wireless communication connection now exists.

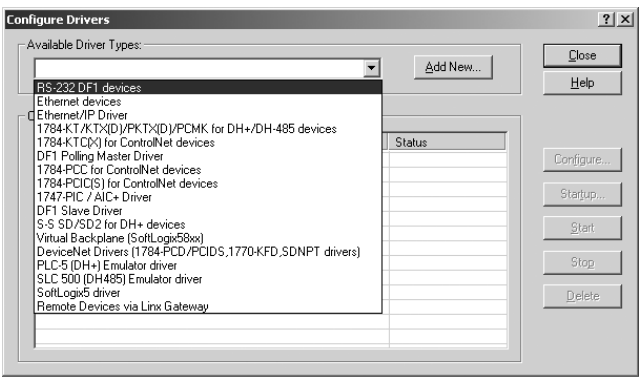
Figure 3.26 PowerFlex 70 Connection Window with Lit Green Icon



5. Launch RSLinx to create a driver to represent the connection on COM8 (communication port assigned in Step 4 on Page 3-17).

6. Select **Communications > Configure Drivers…** to display the Configure Drivers screen. From the Available Driver Types pulldown list, select “RS-232 DF1 devices” as shown in Figure 3.27.

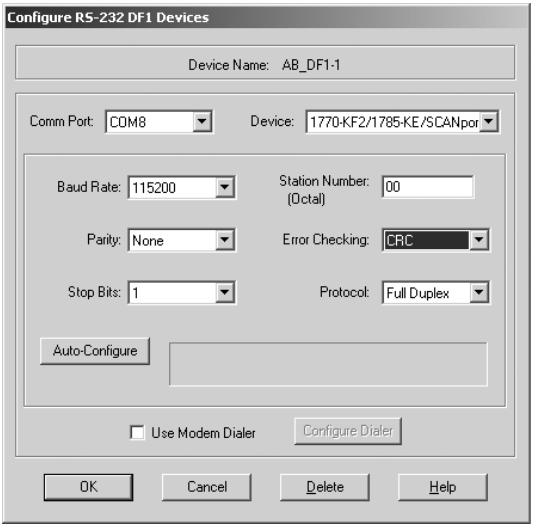
Figure 3.27 Configure Drivers Screen



7. After the driver is selected, click "Add New…." The Add New RSLinx Driver screen will appear. Create a name for the new driver or use the default name, and click **OK**.

8. The Configure RS-232 DF1 Devices window appears (Figure 3.28).

Figure 3.28 Configure RS-232 DF1 Devices Window



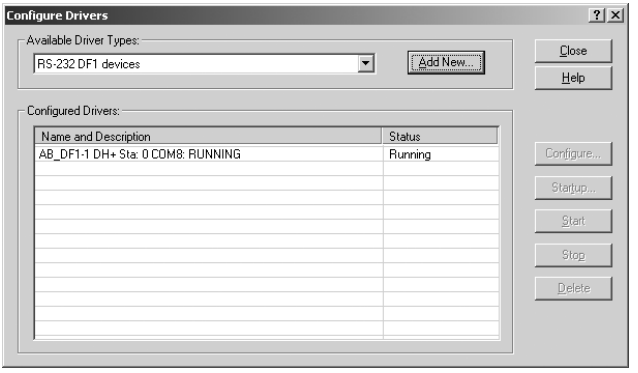
Use the following settings:

Configuration Field	Setting
Comm Port	Select the same COM port established by the *Bluetooth* wireless technology enabled computer (noted in Step 4). For this example, COM8 is used.
Device	1770-KF2/1785-KE/SCANport
Baud Rate	Any setting
Station Number	00
Parity	None
Error Checking	**Important:** Change to "CRC."
Stop Bits	1
Protocol	Full Duplex

Then click **OK.**

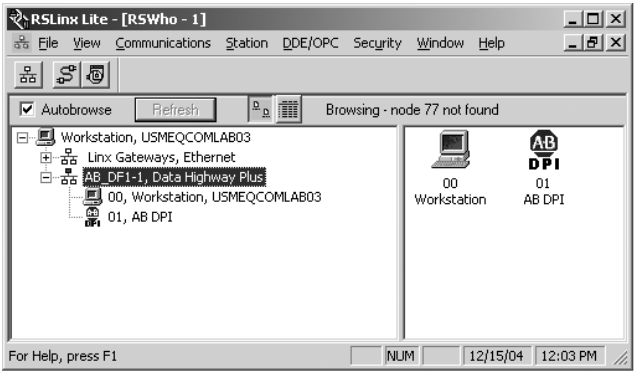
9. The Configure Drivers window will re-appear (Figure 3.29). Verify that the status of the newly created driver is "Running." Then click **Close**.

Figure 3.29 Configure Drivers Window



10. Select **Communications > RSWho** to display the browse window. Then expand the menu tree in the left pane for the drive name assigned in Step 7 to verify that the driver is communicating with the device. The screen should look similar to Figure 3.30.

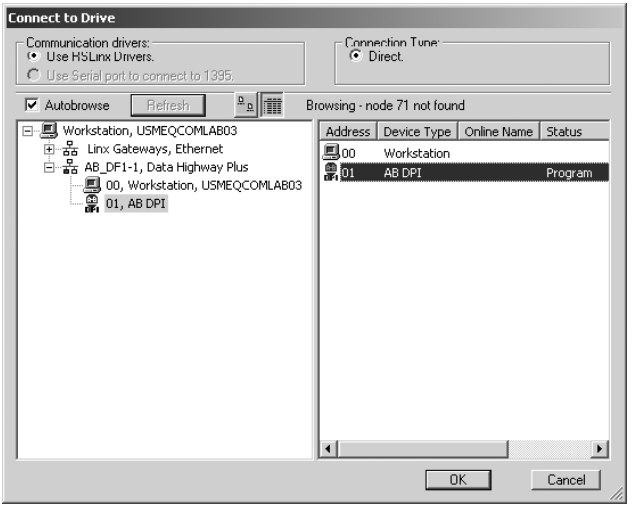
Figure 3.30 RSLinx Browse Window



11. Launch DriveExecutive to access parameters in the WIM, connected drive, and any of the attached peripherals.

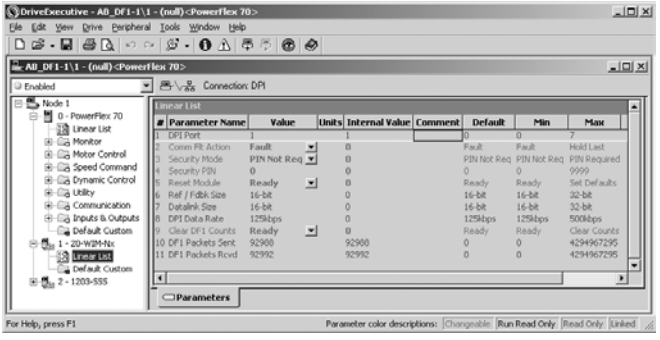
12. In the DriveExecutive window, select **Drive > Connect to Drive…** to display the Connect to Drive menu tree window. Then expand the menu tree in the left pane for the drive name assigned in Step 7. The screen should look similar to Figure 3.31. Then click **OK**. DriveExecutive will begin updating drive information such as parameter names, diagnostics, etc. and store them in a DriveExecutive directory established for this purpose.

Figure 3.31 Connect to Drive Window



13. In the left pane of the DriveExecutive menu tree window, click the + signs to expand the tree. For this example, click on "20-WIM-Nx Linear List" to display the WIM parameters in the right pane (Figure 3.32). To edit a parameter, double-click it or use the Value column pulldown menu.

Figure 3.32 DriveExecutive Menu Tree Window



Setting the Fault Action

By default, when communications are disrupted (for example, loss of wireless communication), the WIM and connected drive respond by faulting. You can configure a different response to communication disruptions using **Parameter 02 - [Comm Flt Action]**.

ATTENTION: Risk of injury or equipment damage exists. **Parameter 02 - [Comm Flt Action]** lets you determine the action of the WIM and connected drive if communications are disrupted. By default, this parameter faults the drive. You can set this parameter so that the drive continues to run. Precautions should be taken to ensure that the setting of this parameter does not create a risk of injury or equipment damage. When commissioning the drive, verify that your system responds correctly to various situations (for example, disruption of wireless communication).

To change the fault action

- Set the value of **Parameter 02 - [Comm Flt Action]** to the desired response:

Value	Action	Description
0	Fault	The drive will fault.
1	Stop	The drive will stop and not fault (DPI host products only).
2	Zero Data	The drive is sent 0 for output data after a communications disruption. This does not command a stop.
3	Hold Last	The drive continues in its present state after a communications disruption.

Changes to this parameter take effect immediately. A reset is not required.

Enabling and Setting the Security Mode

The WIM has a security mode to prevent access to its configuration and the connected drive. You can enable the security mode using **Parameter 03 - [Security Mode],** and set a desired PIN number using **Parameter 04 - [Security PIN]**.

To enable the WIM security mode

1. Set **Parameter 03 - [Security Mode]** to "PIN Required."

Value	Description
0	PIN Not Required (Default)
1	PIN Required

2. Reset the WIM. See Resetting the WIM section in this chapter.

To set a PIN number

1. Set **Parameter 04 - [Security PIN]** to a desired number (0-9999). The default is "0."

   For your convenience, please write down your assigned PIN number and store it in a safe place:

   PIN Number = ___ ___ ___ ___

2. Reset the WIM. See Resetting the WIM section in this chapter.

To reset a PIN number when misplaced or forgotten

If you misplaced or forgot the assigned PIN number, you will not be able to connect to the WIM using drive software.

- **DPI Drive** – To reset the PIN number, you will first need to use a different DPI peripheral (for example, 20-HIM) to access the WIM **Parameter 03 - [Security Mode]** and set it to "0." Then access **Parameter 04 - [Security PIN]** to view the previous PIN number.

- **SCANport Drive** – Since a SCANport drive does not support peripheral routing, you cannot access the WIM parameters using a legacy HIM (for example, 1201-H*). To reset the PIN number, you will need to disconnect the WIM and reconnect it to a DPI drive. This enables access to the WIM parameters to reset or disable the PIN number. For additional assistance, contact Drives Technical Support at the numbers listed on Page P-3.

Resetting the WIM

Changes to some WIM parameters require that you reset the WIM before the new settings take effect. You can reset the WIM by cycling power to the drive or by using **Parameter 05 - [Reset Module]**.

- Set **Parameter 05 - [Reset Module]** to **Reset Module**.

Value	Description
0	Ready (Default)
1	Reset Module
2	Set Defaults

After you enter **1 = Reset Module**, the WIM will be immediately reset. When you enter **2 = Set Defaults**, the WIM will set all WIM parameters to their factory-default settings. After performing a Set Defaults, enter 1 = Reset Module so that the new values take effect. The value of this parameter will be restored to **0 = Ready** after performing the reset or setting the defaults.

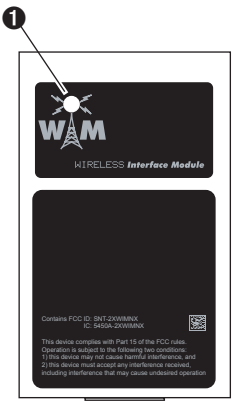
Troubleshooting

This chapter provides information to troubleshoot the WIM.

Understanding the Status Indicator

The WIM reports its operating status using a status indicator (Figure 4.1).

Figure 4.1 Status Indications of the WIM



(NEMA 1 WIM shown)

Status Indications

Status	Cause	Corrective Action
Off	WIM is not powered.	• Securely place WIM in cradle or bezel, or securely connect bezel or WIM cable to the drive. • Apply power to the drive.

Status	Cause	Corrective Action
Flashing Green	WIM is communicating with drive, but not transmitting or receiving wireless signals.	Establish wireless communication with the *Bluetooth* wireless technology enabled Pocket PC or computer. For details, refer to one of these sections in Chapter 3: • Using Pocket DriveExplorer for Pocket PC • Using DriveExplorer/DriveExplorer Lite • Using DriveExecutive.
Flashing Red/Green	WIM is in boot mode, or WIM may have a corrupted flash file.	• No action required. Normal behavior when powering up. • Reflash WIM firmware. If issue persists, return WIM to factory for repair/ replacement.
Solid Blue	WIM is communicating with drive.	No action required.
Flickering Blue	WIM is communicating with drive, and is being pinged by the Pocket PC or computer.	No action required.
Solid Red	Communication error.	• Power cycle the drive. • Check cables and their connections.
Flashing Red (momentary)	WIM is in startup sequence and is initializing communication with the drive.	No action required.
Flashing Red (continuous)	WIM is not communicating with drive.	• Power cycle the drive. • Check cables and their connections.

Viewing WIM Diagnostic Items

WIM Diagnostic Items are viewable with the following tools:

- For Pocket PCs, use Pocket DriveExplorer for Pocket PC software (version 1.01 or higher).
- For laptop or desktop computers, use DriveExplorer software (version 4.04 or higher), DriveExecutive software (version 3.01 or higher).
- An LCD PowerFlex 7-Class HIM.

If you encounter unexpected communications problems, diagnostic items can help you or Rockwell Automation personnel troubleshoot the problem.

No.	Name	Description
1	Common Logic Cmd	Current value of the Common Logic Command being transmitted to the drive by the WIM.
2	Prod Logic Cmd	Current value of the Product Specific Logic Command being transmitted to the drive by the WIM.
3	Reference	Current value of the Product Specific Reference being transmitted to the drive by the WIM.
4	Common Logic Sts	Current value of the Common Logic Status being received from the drive by the WIM.
5	Prod Logic Sts	Current value of the Product Specific Logic Status being received from the drive by the WIM.
6	Feedback	Current value of the Product Specific Feedback being received from the drive by the WIM.
7	DPI Rx Err Cntr	Current value of the DPI CAN Receive Error Counter register.
8	DPI Rx Err Max	Maximum value of the DPI CAN Receive Error Counter register.
9	DPI Tx Err Cntr	Current value of the DPI CAN Transmit Error Counter register.
10	DPI Tx Err Max	Maximum value of the DPI CAN Transmit Error Counter register.
11	Field Flash Cntr	Current value of the Field Flash Counter.

Viewing and Clearing Events

The WIM maintains an event queue that reports the history of its actions. You can view the event queue with the following tools:

- For Pocket PCs, use Pocket DriveExplorer for Pocket PC software (version 1.01 or higher).
- For laptop or desktop computers, use DriveExplorer software (version 4.04 or higher), DriveExecutive software (version 3.01 or higher).
- An LCD PowerFlex 7-Class HIM.

To view the event queue

1. Access the event queue using a configuration tool.
2. Scroll through events in the event queue.

Events

Many events in the Event queue occur under normal operation. If you encounter unexpected communications problems, the events may help you or Allen-Bradley personnel troubleshoot the problem. The following events may appear in the event queue:

Event	Description
Control Disabled	The WIM has sent a “Soft Control Disable” command to the DPI drive.
Control Enabled	The WIM has sent a “Soft Control Enable” command to the DPI drive.
DPI Bus Off Flt	A bus-off condition was detected on DPI. This event may be caused by loose or broken cables or by noise.
DPI Fault Clear	The DPI drive has issued a fault clear message.
DPI Fault Msg	The drive entered a faulted state.
Dup. Port Flt	Another peripheral with the same port number is already in use.
EEPROM Sum Flt	The EEPROM in the WIM is corrupt.
Host Sent Reset	The DPI drive issued this event because it was reset.
Message Timeout	The DPI drive did not respond to a message request. Verify the cables are correct.
No Event	Empty event queue entry.
Normal Startup	WIM initially powered up or was reset.
Online @ 125kbps	The WIM and DPI drive are communicating at 125kbps.
Online @ 500kbps	The WIM and DPI drive are communicating at 500kbps.
PCCC I/O Time Flt	The WIM has not received a PCCC Control message for longer than the specified PCCC Control Time-out.

Event	Description
Ping in Message	An unexpected ping was received.
Ping Time Flt	A ping message was not received on DPI within the specified time.
Port Change Flt	The DPI port changed.
Port ID Flt	The WIM is not connected to a correct port on a DPI drive.
Type 0 Login	The WIM has logged in for type 0 control.
Type 0 Time Flt	The WIM has not received a type 0 status message within the specified time.

To clear the event queue

1. Access the event queue using a configuration tool.
2. Set the value of **1 > Clr Event Queue** to **Enable**, and then press **Enter** to clear the event queue.

Viewing and Clearing DF1 Communication Statistics

If you encounter unexpected communications problems or are creating an application that uses DF1 data, you can view the communications statistics in the WIM. **Parameter 10 - [DF1 Packets Sent]** and **Parameter 11 - [DF1 Packets Rcvd]** store this data.

To view and clear DF1 data, you must access the main menu in the WIM firmware.

To view DF1 data

1. Access the parameters in the WIM using a configuration tool.
2. Scroll through the DF1 Parameters 10 and 11, which contain DF1 data. For a description of each parameter, refer to Appendix B, WIM Parameters.

To clear DF1 data

1. Access the parameters in the WIM using a configuration tool.
2. Set the value of **Parameter 09 - [Clear DF1 Counts]** to “1 = Clear Counts,” and then press **Enter** to clear the DF1 data.

Notes:

Specifications

Appendix A provides the specifications for the WIM.

Communications

Radio	
Transceiver	National Semiconductor LMX9820A Bluetooth Serial Port Module, V1.1 Bluetooth Compliant Component
Frequency	2.402 to 2.480 GHz Frequency Hopping
Power	2.5mW Maximum RF Output
Range	Class II – 10 m (32.8 ft.) anticipated* range (*will vary due to environmental conditions)
Drive	
Protocol	Drive Peripheral Interface (DPI)
Data Rates	125K/500K

Electrical

Consumption	130mA at +12V DC The serial converter draws the required power from the connected product. An external power source is not required.

Mechanical

Dimensions	**NEMA 1 WIM (20-WIM-N1)**	**NEMA 4 WIM (20-WIM-N4S)**
Height	116.0 mm (4.57 in.)	180.0 mm (7.08 in.)
Width	70.0 mm (2.75 in.)	93.0 mm (3.66 in.)
Depth	16.0 mm (0.63 in.)	25.0 mm (0.98 in.)
Weight	85g (3.0 oz.)	161g (5.7 oz.)

Environmental

Temperature	
Operating	0 to +50° C (32 to 122° F)
Storage	-40 to +85° C (-40 to 185° F)
Relative Humidity	5 to 95% non-condensing
Atmosphere	**Important:** The WIM **must not** be installed in an area where the ambient atmosphere contains volatile or corrosive gas, vapors or dust. If the WIM is not going to be installed for a period of time, it must be stored in an area where it will not be exposed to a corrosive atmosphere.
Vibration	
Operating	2.5G @5Hz-2KHz
Non-Operating	5 G @5Hz-2KHz
Shock	
Operating	30 G peak acceleration, 11 (+/-1) ms pulse width
Non-Operating	50 G peak acceleration, 11 (+/-1) ms pulse width

Regulatory Compliance

Certification	Specification
UL	UL508C
cUL	CAN / CSA C22.2 No. 14-M91
CE	EN50178 and EN61800-3
CTick	AS / NZS 2064, Group 1, Class A
FCC ID	SNT-2XWIMNX
IC	5450A-2XWIMNX

NOTE: This is a product of category C2 according to IEC 61800-3. In a domestic environment this product may cause radio interference in which case supplementary mitigation measures may be required.

FCC Statement of Conditions

Compliance Statement (Part 15.19)

This device complies with Part 15 of the FCC rules. Operation is subject to the following two conditions:

1. This device may not cause harmful interference, and
2. This device must accept any interference received, including interference that may cause undesired operation.

Warning (Part 15.21)

Changes or modifications not expressly approved by the party responsible for compliance could void the user's authority to operate this equipment.

This device must not be co-located or operated in conjunction with any other antenna or transmitter.

RF Exposure (OET Bulletin 65)

To comply with FCC RF exposure requirements for mobile transmitting devices, this transmitter should only be used or installed at locations where there is at least 20 cm (7.9 inches) separation distance between the antenna and all persons.

Industry Canada Statement

The term "IC" before the certification/registration number only signifies that the Industry Canada technical specifications were met.

Notes:

WIM Parameters

Appendix B presents information about the WIM parameters.

About Parameter Numbers

The parameters in the WIM are numbered consecutively. You can use the following configuration tools to access the parameters in the WIM.

Configuration Tool	Numbering Scheme
• Pocket DriveExplorer for Pocket PC • DriveExplorer • DriveExecutive • HIM	The adapter parameters begin with parameter 01. For example, Parameter 01 - [DPI Port] is parameter 01 as indicated by this manual.

Parameter List for DPI Products

No.	Name and Description	Details
01	**[DPI Port]** Displays the port on the drive to which the WIM is connected.	Default: 0 Minimum: 0 Maximum: 7 Type: Read Only
02	**[Comm Flt Action]** Sets the action that the WIM and drive will take if the WIM detects that wireless communications are disrupted. This setting is effective only if control I/O is transmitted through the WIM.	Default: 0 = Fault Values: 0 = Fault 1 = Stop 2 = Zero Data 3 = Hold Last Type: Read/Write Reset Required: No
	ATTENTION: Risk of injury or equipment damage exists. **Parameter 02 - [Comm Flt Action]** lets you determine the action of the WIM and connected drive if communications are disrupted. By default, this parameter faults the drive. You can set this parameter so that the drive continues to run. Precautions should be taken to ensure that the setting of this parameter does not create a risk of injury or equipment damage. When commissioning the drive, verify that your system responds correctly to various situations (for example, loss of wireless communication).	
03	**[Security Mode]** Enables/disables the security mode for the WIM, which prevents accessing its parameters and the connected drive for configuration.	Default: 0 Values: 0 = PIN Not Req'd 1 = PIN Required Type: Read/Write Reset Required: Yes
04	**[Security PIN]** Sets the PIN number to access WIM parameters for configuration when Parameter 03 - [Security Mode] is set to 1 = PIN Required. See Page 3-23 for details.	Default: 0 Minimum: 0 Maximum: 9999 Type: Read/Write Reset Required: Yes
05	**[Reset Module]** No action if set to "Ready." Resets the WIM if set to "Reset Module." Restores the WIM to its factory default settings if set to "Set Defaults." This parameter is a command. It will be set to "0 = Ready" after the command has been performed.	Default: 0 = Ready Values: 0 = Ready 1 = Reset Module 2 = Set Defaults Type: Read/Write Reset Required: No
	ATTENTION: Risk of injury or equipment damage exists.The drive will fault when you remove or reset the WIM. Determine how the drive will respond before removing or resetting the WIM.	
06	**[Ref/Fdbk Size]** Displays the size of the Reference/Feedback. The drive determines the size of the Reference/Feedback. The WIM automatically uses the correct size.	Default: 0 = 16-bit Value: 0 = 16-bit 1 = 32-bit Type: Read Only
07	**[Datalink Size]** Displays the size of each Datalink word. The drive determines the size of Datalinks.	Default: 0 = 16-bit Values: 0 = 16-bit 1 = 32-bit Type: Read Only
08	**[DPI Data Rate]** Displays the data rate used by the DPI drive. This data rate is set in the drive, and the WIM autobauds to it.	Default: 0 Values: 0 = 125 kbps 1 = 500 kbps Type: Read Only

No.	Name and Description	Details
09	**[Clear DF1 Counts]** No action if set to “Ready.” Resets the DF1 statistical parameters 10 and 11 to 0 if set to “1 = Clear Counts.” This parameter is a command. It will be reset to “0 = Ready” after a “Clear Counts” command has been performed.	Default: 0 = Ready Values: 0 = Ready 1 = Clear Counts Type: Read/Write Reset Required: No
10	**[DF1 Packets Sent]** Displays the number of DF1 packets sent by the WIM. The value of this parameter is normally approximately equal to the value Parameter 11 - [DFl Packets Rcvd].	Default: 0 Minimum: 0 Maximum: 4294967295 Type: Read Only
11	**[DF1 Packets Rcvd]** Displays the number of DF1 packets received by the WIM. The value of this parameter is normally approximately equal to the value Parameter 10 - [DFl Packets Sent].	Default: 0 Minimum: 0 Maximum: 4294967295 Type: Read Only

Parameter List for SCANport Products

No.	Name and Description	Details
01	**[Adapter Port]** Displays the port on the drive to which the WIM is connected.	Default: 0 Minimum: 0 Maximum: 7 Type: Read Only
02	**[Security Mode]** Enables/disables the security mode for the WIM, which prevents accessing its parameters and the connected drive for configuration.	Default: 0 Values: 0 = PIN Not Req’d 1 = PIN Required Type: Read/Write Reset Required: Yes
03	**[Security PIN]** Sets the PIN number to access WIM parameters for configuration when Parameter 03 - [Security Mode] is set to 1 = PIN Required. See Page 3-23 for details.	Default: 0 Minimum: 0 Maximum: 9999 Type: Read/Write Reset Required: Yes
04	**[Comm Flt Action]** Sets the action that the WIM and drive will take if the WIM detects that wireless communications are disrupted. This setting is effective only if control I/O is transmitted through the WIM.	Default: 0 = Fault Values: 0 = Fault 1 = Stop 2 = Zero Data 3 = Hold Last Type: Read/Write Reset Required: No

ATTENTION: Risk of injury or equipment damage exists. **Parameter 04 - [Comm Flt Action]** lets you determine the action of the WIM and connected drive if communications are disrupted. By default, this parameter faults the drive. You can set this parameter so that the drive continues to run. Precautions should be taken to ensure that the setting of this parameter does not create a risk of injury or equipment damage. When commissioning the drive, verify that your system responds correctly to various situations (for example, loss of wireless communication).

No.	Name and Description	Details
05	**[Reset Adapter]** No action if set to “Ready.” Resets the WIM if set to “Reset Module.” Restores the WIM to its factory default settings if set to “Set Defaults.” This parameter is a command. It will be set to “0 = Ready” after the command has been performed.	Default: 0 = Ready Values: 0 = Ready 1 = Reset Module 2 = Set Defaults Type: Read/Write Reset Required: No
	 **ATTENTION:** Risk of injury or equipment damage exists.The drive will fault when you remove or reset the WIM. Determine how the drive will respond before removing or resetting the WIM.	
06	**[Clear DF1 Counts]** No action if set to “Ready.” Resets the DF1 statistical parameters 10 and 11 to 0 if set to “1 = Clear Counts.” This parameter is a command. It will be reset to “0 = Ready” after a “Clear Counts” command has been performed.	Default: 0 = Ready Values: 0 = Ready 1 = Clear Counts Type: Read/Write Reset Required: No
07	**[DF1 Packets Sent]** Displays the number of DF1 packets sent by the WIM. The value of this parameter is normally approximately equal to the value Parameter 11 - [DFI Packets Rcvd].	Default: 0 Minimum: 0 Maximum: 4294967295 Type: Read Only
08	**[DF1 Packets Rcvd]** Displays the number of DF1 packets received by the WIM. The value of this parameter is normally approximately equal to the value Parameter 10 - [DFI Packets Sent].	Default: 0 Minimum: 0 Maximum: 4294967295 Type: Read Only

A

Application Code

Code that runs in the WIM after the boot code calls it. It performs the normal operations of the system.

B

BCC (Block Check Character)

An error detection scheme where the 2's complement of the 8-bit sum (modulo-256 arithmetic sum) of all data bytes in a transmission block. It provides a means of checking the accuracy of each message transmission.

***Bluetooth* Wireless Technology**

Bluetooth wireless technology enables cable-free connection of devices that would normally be physically linked by wires, such as a drive connected to a computer.

Boot Code

Code that runs when the WIM first receives power. It checks basic operations and then calls the application code.

Bus Off

A bus off condition occurs when an abnormal rate of errors is detected on the Control Area Network (CAN) bus in a device. The bus-off device cannot receive or transmit messages. This condition is often caused by corruption of the network data signals due to noise or data rate mismatch.

C

CAN (Controller Area Network)

A CAN is a serial bus protocol on which DPI is based.

CRC (Cyclic Redundancy Check)

An error detection scheme where all of the characters in a message are treated as a string of bits representing a binary number. This number is divided by a predetermined binary number (a polynomial) and the remainder is appended to the message as a CRC character. A similar operation occurs at the receiving end to prove transmission integrity.

D

DF1 Protocol

A peer-to-peer link layer protocol that combines features of ANSI X3.28-1976 specification subcategories D1 (data transparency) and F1 (two-way simultaneous transmission with embedded responses).

DF1 Rate

A unit of signaling speed equal to the number of discrete conditions or signal events per second. It is also called “baud rate” or “serial port rate.”

DPI (Drive Peripheral Interface)

DPI is a second generation peripheral communication interface used by various Allen-Bradley drives and power products, such as PowerFlex 70 and PowerFlex 700 drives. It is a functional enhancement to SCANport.

DPI Peripheral

A device that provides an interface between DPI and a network or user. Peripheral devices are also referred to as “adapters” or “modules.” The WIM and PowerFlex 7-Class HIMs (20-HIM-xxx) are examples of DPI peripherals.

DPI Product

A device that uses the DPI communications interface to communicate with one or more peripheral devices. For example, a motor drive such as a PowerFlex 7-Class drive is a DPI product. In this manual, a DPI product is also referred to as “drive” or “host.”

DriveExplorer Software

DriveExplorer software is a tool for monitoring and configuring Allen-Bradley products and adapters. It can be run on computers running Microsoft Windows 95, Windows 98, Windows ME, Windows NT 4.0 SP6a, Windows 2000, Windows XP, and Windows CE (version 2.0 or higher) operating systems. DriveExplorer (version 3.xx or higher) can be used to configure the WIM and PowerFlex drives. Information about DriveExplorer and a free Lite version can be accessed at http://www.ab.com/drives/driveexplorer.

DriveTools SP Software

A software suite designed for Microsoft Windows 98 Second Edition, Windows ME, Windows NT 4.0 SP6a, Windows 2000 SP3, and Windows XP operating systems. This software suite provides a family of tools, including DriveExecutive, that you can use to program, monitor, control, troubleshoot, and maintain Allen-Bradley products. DriveTools SP (version 1.01 or higher) can be used with PowerFlex drives. Information about DriveTools SP can be accessed at http://www.ab.com/drives/drivetools.

E

EDS (Electronic Data Sheet) Files

EDS files are simple text files that are used by network configuration tools such as RSNetWorx for DeviceNet to describe products so that you

can easily commission them on a network. EDS files describe a product device type, revision, and configurable parameters. EDS files for many Allen-Bradley products can be found at http://www.ab.com/networks/eds.

F

Flash Update

The process of updating firmware in a device.

H

HIM (Human Interface Module)

A device that can be used to configure and control a SCANport or DPI drive. PowerFlex 7-Class HIMs (20-HIM-xxx) can also be used to configure connected peripherals such as the WIM.

Hold Last

When communications are disrupted (for example, a cable is disconnected), the WIM and PowerFlex drive can respond by holding last. Hold last results in the drive receiving the last data received via the DF1 connection before the disruption. If the drive was running and using the Reference from the module, it will continue to run at the same Reference.

N

NVS (Non-Volatile Storage)

NVS is the permanent memory of a device. Devices such as the WIM and drive store parameters and other information in NVS so that they are not lost when the device loses power. NVS is sometimes called "EEPROM."

P

PCCC (Programmable Controller Communications Command)

PCCC is the protocol used by some controllers to communicate with devices on a network. Some software products (for example, DriveExplorer and DriveTools SP) also use PCCC to communicate.

Ping

A ping is a message that is sent by a SCANport or DPI product to its peripheral devices. They use the ping to gather data about the product, including whether it can receive messages and whether they can log in for control.

Pocket DriveExplorer for Pocket PC Software

Pocket DriveExplorer for Pocket PC software is a Pocket PC tool for monitoring and configuring Allen-Bradley products and adapters. It can be run on a Pocket PC running Microsoft Windows Mobile 2003 (or

higher) operating system. Pocket DriveExplorer for Pocket PC (version 1.xx or higher) can be used to configure the WIM and PowerFlex drives. Information about Pocket DriveExplorer for Pocket PC can be accessed at http://www.ab.com/drives/driveexplorer.

PowerFlex 7-Class Drives

The Allen-Bradley PowerFlex 7-Class family of AC drives includes the PowerFlex 70, PowerFlex 70EC, PowerFlex 700, PowerFlex 700VC, PowerFlex 700H, PowerFlex 700S, and PowerFlex 7000. These drives can be used for applications ranging from 0.37 kW (0.5 HP) to 3,000 kW (4,000 HP). All PowerFlex 7-Class drives support DPI, allowing them to use the WIM. This manual focuses on using the WIM with PowerFlex 7-Class drives.

S

SCANport

SCANport is a standard peripheral communication interface used by various Allen-Bradley drives and power products, such as 1305 and 1336 PLUS II drives.

SCANport Peripheral

A device that provides an interface between SCANport and a network or user. Peripheral devices are also referred to as “modules” and “adapters.” The 1203-SSS serial converter and legacy drive HIMs (1201-H*) are examples of SCANport peripherals.

SCANport Product

A device that uses the SCANport communications interface to communicate with one or more peripheral devices. For example, a motor drive such as a 1336 PLUS II drive is a SCANport product.

Status Indicator

A status indicator is an LED that is used to report the status of a device. The WIM has one status indicator that emits blue, green, or red indications.

T

Type 0/Type 1/Type 2 Control

When transmitting I/O, the adapter can use different types of messages for control. The Type 0, Type 1, and Type 2 events help Allen-Bradley personnel identify the type of messages that an adapter is using.

W

WIM (Wireless Interface Module)

The WIM provides a wireless communications interface between any Allen-Bradley DPI drive and a computer or Pocket PC with an RS-232

port. The WIM uses a full-duplex DF1 protocol. The WIM may also be referred to as “20-WIM-N*,” “DPI peripheral,” or “module.”

Z

Zero Data

When communications are disrupted (for example, a cable is disconnected), the module and drive can respond with zero data. Zero data results in the drive receiving zero as values for Logic Command, Reference, and Datalink data. If the drive was running and using the Reference from the module, it will stay running but at zero Reference.

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Publication 20WIM-UM001A-EN-P – February, 2005

P/N 353368-P01