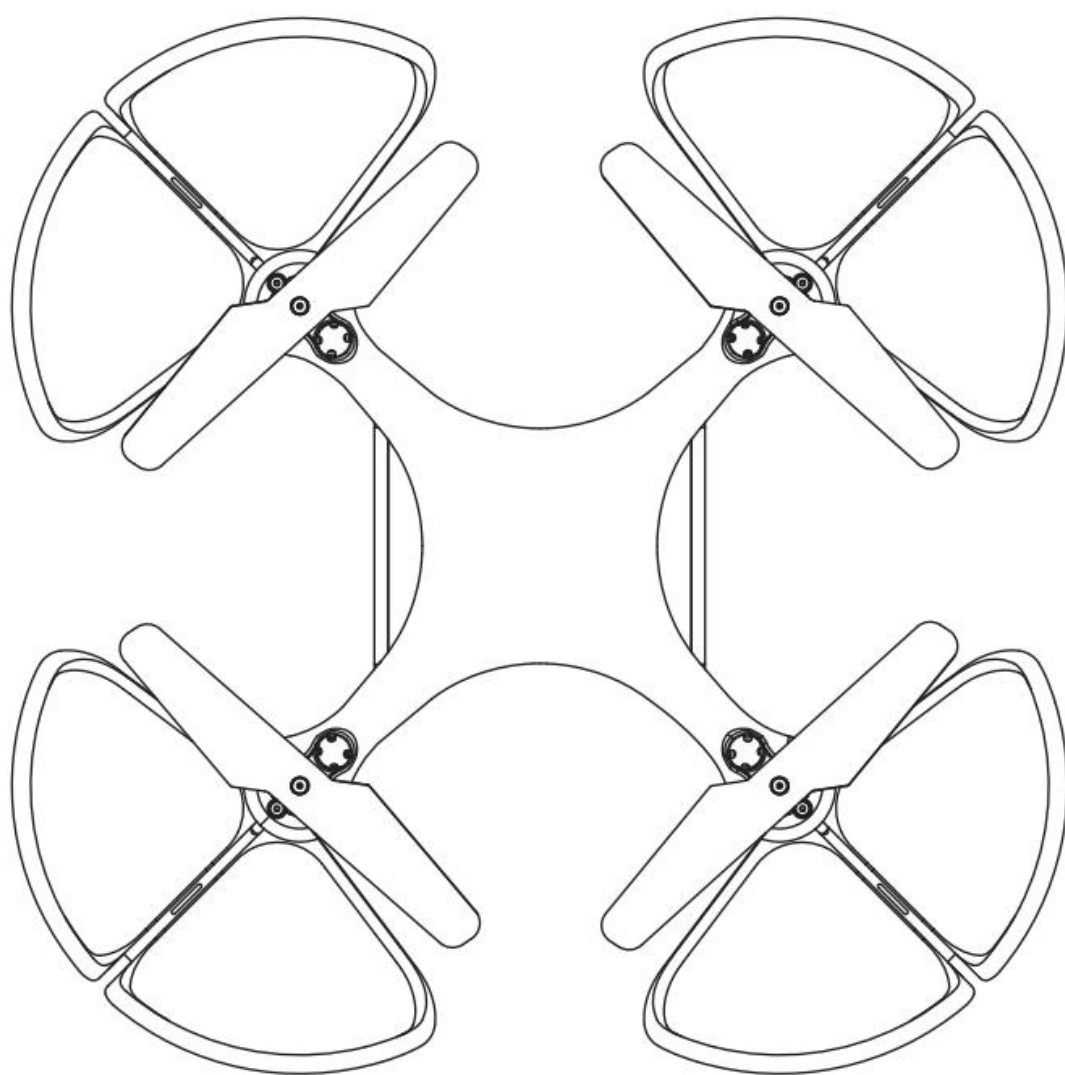


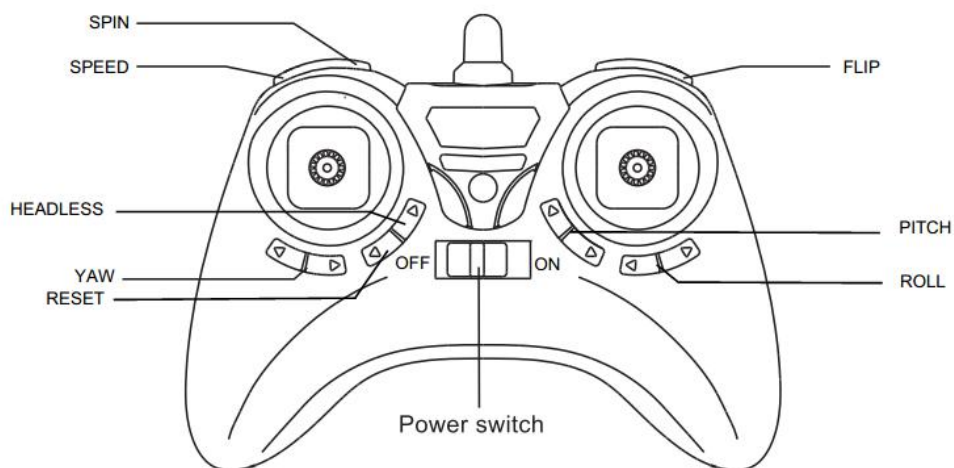
Instruction Manual



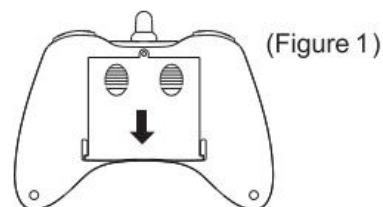
Key features of quadcopter

- Four-axis struture makes the quadcopter more flexible and rapid when flying. It is wind-resistant and can be flown indoor or outdoor.
- Built-in 6 axis gyroscope for precise hovering in the sky.
- Simple modular design makes changing parts easy.
- With 360° 3D eversion and throwing flight function.
- Headless Flight Mode · Reset ·
- Three flying speed and Spin.

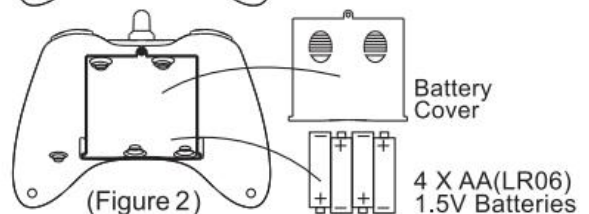
GET TO KNOW YOUR TRANSMITTER



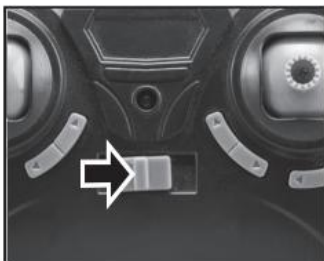
1. Remove the battery cover (Figure 1).



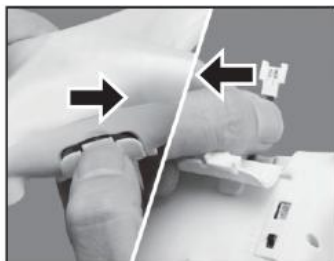
2. Install 4 AA batteries (not included) to the transmitter with the correct polarity, then reattach the battery cover (Figure 2).



READY TO FLY YOUR QUADCOPTER



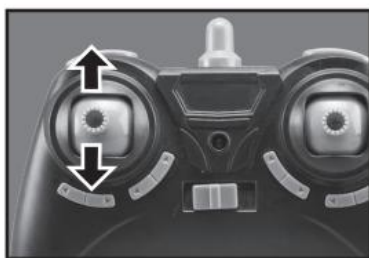
Step 1: Press the ON/OFF power switch up.



Step 2: Open the battery cover and insert the battery into power port.



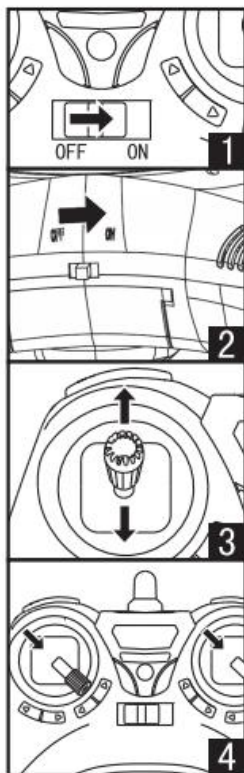
Step 3: Close the battery cover and turn on the quadcopter.



Step 4: Push the throttle lever to the highest position, and then pull it back to the lowest position. There will be one clear sound from the transmitter, this shows that the quadcopter has entered into the pre-fly state.

Calibration function:

In case of flight disorder or sideward flight, restore factory default settings by the following



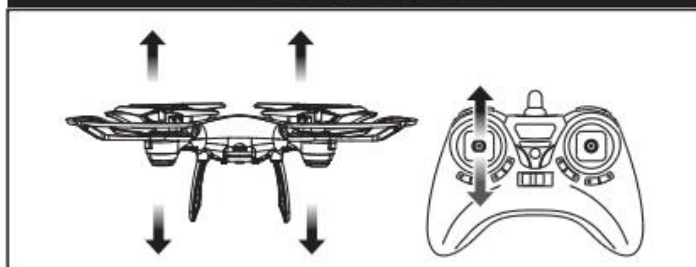
1. Press the power switch to turn on the transmitter.

2. Press the power switch to turn on the quadcopter.

3. When the quadcopter indicator quickly flashing to slowly flashing, please push the throttle lever to the highest position, and then pull it back to the lowest position. Then the quadcopter indicator changed from slowly flashing to normal lights up.

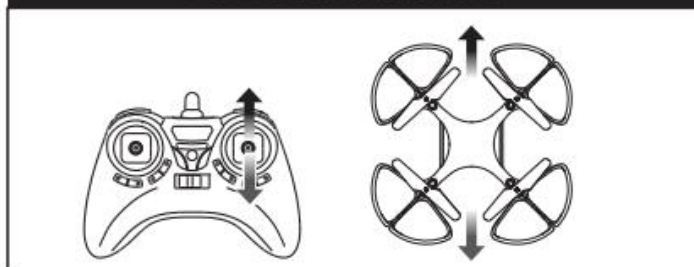
4. Place the quadcopter on a horizontal position, then push transmitter both left and right lever to lowest right corner for about 2-3 second, indicator on the quadcopter changed from normal lights up to quickly flashing; After 2-3 second, the indicator changed to normal lights, it means the quadcopter restarted/reset successfully.

Hover up and down



Push the throttle up or down, the quadcopter flies upward or downward.

Forward and backward



Push the direction lever up or down, the quadcopter flies forward or backward.

Turn Left and Right



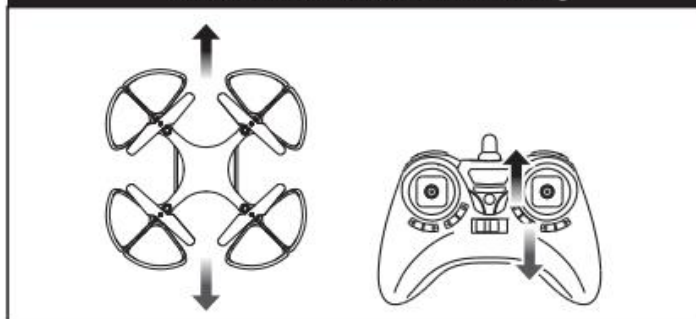
Pull the throttle left or right, the quadcopter turns to left or right.

Sideward fly



Pull the direction lever left or right, the quadcopter flies to left side or right side.

Forward/Backward fine-tuning



When the quadcopter keeps flying forward / backward, you can correct it by pressing fine-tuning button down / up.

Sideward fly fine-tuning

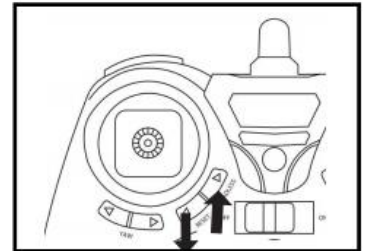


When the quadcopter keeps flying to left / right side, you can correct it by pressing the Fine-tuning button right / left.

HEADLESS FLIGHT MODE/RESET

Headless Flight Mode:

1. Press the headless flight mode button. (Slow light flashing means that you have entered the headless flight mode now.)
2. Locking Course (After course locking, the front and back left and right do not change when the fuselage turns. The fuselage distinguishes these directions of front and back left and right. Regardless of nose direction, front and back left and right of course are always locked in position forever. This function can recall the aircraft back when it distinguishes the course for emergency.)
3. If the course deviates, push down two levers to the lower right corner simultaneously to calibrate. The lights flash fast when calibrating, and turn off when calibration is completed.
4. Press the headless flight mode button again to cancel the headless flight mode.



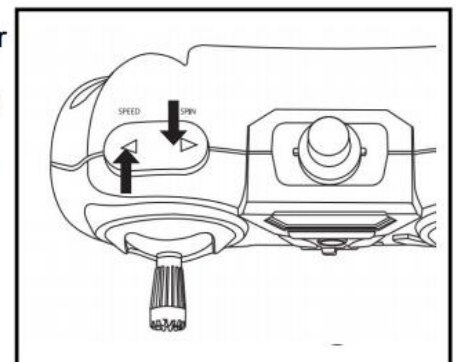
Reset:

1. If the drone deviates its direction when flying, players should press trim buttons to control its directions.
2. After flying, pressing the reset key to recover the original set. The drone will issue a sound of "deep" and lights will be flashing. It means reset is successful.

SPEED/SPIN FUNCTION

Speed:

There are three flying speeds of this quadcopter: Low, medium, and high speed. When pressing the speed button for one time, the controller will issue a sound of "deep". This means low speed. When pressing the button for twice, the controller will issue a sound of "deep deep". This means medium speed. While pressing this button for three times, the controller will issue a sound of "deep deep deep". This means high speed.



Spin:

When pressing this button, the drone will automatically spin. Once pressing again, it will cancel spin.

FCC Warning

Changes or modifications not expressly approved by the party responsible for compliance could void the user's authority to operate the equipment. This equipment has been tested and found to comply with the limits for a Class B digital device, pursuant to Part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference in a residential installation. This equipment generates uses and can radiate radio frequency energy and, if not installed and used in accordance with the instructions, may cause harmful interference to radio communications. However, there is no guarantee that interference will not occur in a particular installation. If this equipment does cause harmful interference to radio or television reception, which can be determined by turning the equipment off and on, the user is encouraged to try to correct the interference by one or more of the following measures:

- - Reorient or relocate the receiving antenna.
- - Increase the separation between the equipment and receiver.
- - Connect the equipment into an outlet on a circuit different from that to which the receiver is connected.
- - Consult the dealer or an experienced radio/TV technician for help.