

# FCC SAR Test Report

Product Name : Bluetooth Headset

Model No. : HSC018Wa

Applicant : GN Audio A/S

Address : Lautrupbjerg 7, 2750 Ballerup, Denmark

Date of Receipt : 2022/03/18

Issued Date : 2022/04/14

Report No. : 2230635R-SAUSSARV01-A

Report Version : V1.0



The test results relate only to the samples tested.

The test results shown in the test report are traceable to the national/international standard through the calibration report of the equipment and evaluated measurement uncertainty herein.

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Report No.: 2230635R-SAUSSARV01-A



# Test Report

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Product Name : Bluetooth Headset

Applicant : GN Audio A/S

Address : Lautrupbjerg 7, 2750 Ballerup, Denmark

Manufacturer : GN Audio A/S Model No. : HSC018Wa

Trade Name : Jabra

FCC ID : BCE-HSC018WA Applicable Standard : IEEE 1528-2013

KDB 447498 D01 v06

KDB 865664 D01 v01r04

Measurement : 47CFR § 2.1093

procedures KDB 248227 D01 v02r02
Test Result : Max. SAR Measurement

BT: 0.149 W/kg

Application Type : Certification

The above equipment has been tested by DEKRA, and found compliance with the requirement of the above standards. The test record, data evaluation & Equipment Under Test (EUT) configurations represented herein are true and accurate accounts of the measurements of the sample's SAR characteristics under the conditions specified in this report.

Documented By	:	Jinn Chen
		( Supervisor / Jinn Chen )
Tested By	:	Luke Cheng
		( Senior Engineer / Luke Cheng )
Approved By	:	Gan Van
		( Supervisor / San Lin )



# TABLE OF CONTENTS

Des	scription Pa	ge
1.	General Information	5
	1.1 EUT Description	5
	1.2 Antenna List	5
	1.3 Test Environment	6
2.	SAR Measurement System	7
	2.1 DASY5 System Description	7
	2.1.1 Applications	8
	2.1.2 Area Scans	
	2.1.3 Zoom Scan (Cube Scan Averaging)	
	2.1.4 Uncertainty of Inter-/Extrapolation and Averaging	
	2.2 DASY5 E-Field Probe	
	2.2.1 Isotropic E-Field Probe Specification	
	2.3 Boundary Detection Unit and Probe Mounting Device	
	2.4 DATA Acquisition Electronics (DAE) and Measurement Server	
	2.5 Robot	
	2.6 Light Beam Unit	
	2.7 Device Holder	
_	2.8 SAM Twin Phantom	
3.	Tissue Simulating Liquid	
	3.1 The composition of the tissue simulating liquid	
	3.2 Tissue Calibration Result	
	3.3 Tissue Dielectric Parameters for Head and Body Phantoms	
4.	SAR Measurement Procedure	
	4.1 SAR System Check	
	4.1.1 Dipoles	
	4.1.2 System Check Result	
_		
5.	SAR Exposure Limits	
6.	Test Equipment List	
7.	Measurement Uncertainty	
8.	Conducted Power Measurement (Including tolerance allowed for production unit	)22
9.	Test Results	23
	9.1 SAR Test Results Summary	23
10.	SAR measurement variability	24
	Appendix	25
	Appendix A. SAR System Check Data	
	Appendix B. SAR measurement Data	
	Appendix C. Test Setup Photographs	
	Appendix D. Probe Calibration Data	
	Appendix E. Dipole Calibration Data	
	Appendix F. Product Photos-Please refer to the file: 2230635R-Product Photos	



# **Revision History**

Report No.	Version	Description	Issued Date
2230635R-SAUSSARV01-A	V1.0	Initial issue of report.	2022/04/14



## 1. General Information

## 1.1 EUT Description

Product Name	Bluetooth Headset
Trade Name	Jabra
Model No.	HSC018Wa
FCC ID	BCE-HSC018WA
TX Frequency	BT: 2402-2480MHz
Channel separation	BT: 1MHz, BLE: 2MHz
Number of Channels	BT: 79, BLE: 40
Type of Modulation	GFSK(1Mbps, 2Mbps) / π /4DQPSK(2Mbps) / 8DPSK(3Mbps)
Device Category	Portable
RF Exposure Environment	Uncontrolled
Test Device Type	Production Unit

## 1.2 Antenna List

No.	Manufacturer	Part No.	Antenna Type	Peak Gain
1	GN Audio A/S	HSC018Wa	PCB antenna	4.16dBi for 2.4GHz

Note: The above EUT information is declared by manufacturer.



## 1.3 Test Environment

Ambient conditions in the laboratory:

Test Date: 23-Mar-22

Items	Required	Actual
Temperature (°C)	18-25	23.1 ± 2
Humidity (%RH)	30-70	53

USA : FCC Registration Number: TW0033

Canada : CAB Identifier Number: TW3023 / Company Number: 26930

Site Description : Accredited by TAF

Accredited Number: 3023

Test Laboratory : DEKRA Testing and Certification Co., Ltd Address : No. 26, Huaya 1st Rd., Guishan Dist.,

Taoyuan City 333411, Taiwan, R.O.C.

Phone number : 886-3-275-7255

Fax number : 866-3-327-8031

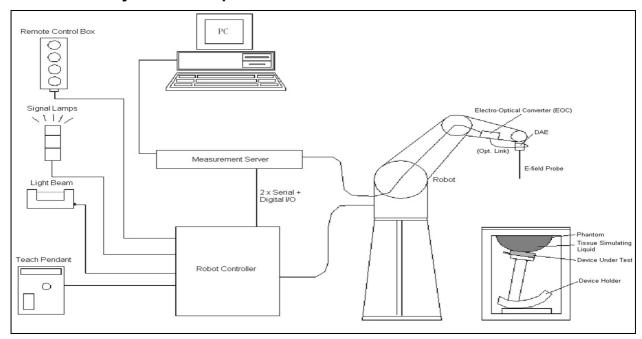
Email address : info.tw@dekra.com

Website : http://www.dekra.com.tw



## 2. SAR Measurement System

## 2.1 DASY5 System Description



The DASY5 system for performing compliance tests consists of the following items:

- A standard high precision 6-axis robot with controller, teach pendant and software. An arm extension for accommodating the data acquisition electronics (DAE).
- A data acquisition electronics (DAE) which performs the signal amplification, signal multiplexing, AD-conversion, offset measurements, mechanical surface detection, collision detection, etc. The unit is battery powered with standard or rechargeable batteries. The signal is optically transmitted to the EOC.
- The Electro-optical converter (EOC) performs the conversion from optical to electrical signals for the digital communication to the DAE. To use optical surface detection, a special version of the EOC is required. The EOC signal is transmitted to the measurement server.
- The Light Beam used is for probe alignment. This improves the (absolute) accuracy of the probe positioning.
- A computer running WinXP and the DASY5 software.
- Remote control and teach pendant as well as additional circuitry for robot safety such as warning lamps, etc.
- > The phantom, the device holder and other accessories according to the targeted measurement.



## 2.1.1 Applications

Predefined procedures and evaluations for automated compliance testing with all worldwide standards, e.g., IEEE 1528, OET 65, IEC 62209-1, IEC 62209-2, EN 50360, EN 50383 and others.

#### 2.1.2 Area Scans

Area scans are defined prior to the measurement process being executed with a user defined variable spacing between each measurement point (integral) allowing low uncertainty measurements to be conducted. Scans defined for FCC applications utilize a 10mm<sup>2</sup> step integral, with 1mm interpolation used to locate the peak SAR area used for zoom scan assessments.

When an Area Scan has measured all reachable points, it computes the field maxima found in the scanned area, within a range of the global maximum. The range (in dB) is specified in the standards for compliance testing. For example, a 2 dB range is required in IEEE 1528-2013, EN 50361 and IEC 62209 standards, whereby 3 dB is a requirement when compliance is assessed in accordance with the ARIB standard (Japan).

## 2.1.3 Zoom Scan (Cube Scan Averaging)

Zoom Scans are used to assess the peak spatial SAR values within a cubic averaging volume containing 1 g and 10 g of simulated tissue. A density of 1000 kg/m³ is used to represent the head and body tissue density and not the phantom liquid density, in order to be consistent with the definition of the liquid dielectric properties, i.e. the side length of the 1 g cube is 10mm, with the side length of the 10 g cube 21,5mm.

The zoom scan integer steps can be user defined so as to reduce uncertainty, but normal practice for typical test applications (including FCC) utilize a physical step of 5x5x7 (8mmx8mmx5mm) providing a volume of 32mm in the X & Y axis, and 30mm in the Z axis.

## 2.1.4 Uncertainty of Inter-/Extrapolation and Averaging

In order to evaluate the uncertainty of the interpolation, extrapolation and averaged SAR calculation algorithms of the Postprocessor, DASY5 allows the generation of measurement grids which are artificially predefined by analytically based test functions. Therefore, the grids of area scans and zoom scans can be filled with uncertainty test data, according to the SAR benchmark functions of IEEE 1528. The three analytical functions shown in equations as below are used to describe the possible range of the expected SAR distributions for the tested handsets. The field gradients are covered by the spatially flat

Page: 8 of 25



distribution f1, the spatially steep distribution f3 and f2 accounts for H-field cancellation on the phantom/tissue surface.

$$f_1(x,y,z) = Ae^{-\frac{z}{2a}}\cos^2\left(\frac{\pi}{2}\frac{\sqrt{x'^2 + y'^2}}{5a}\right)$$

$$f_2(x,y,z) = Ae^{-\frac{z}{a}}\frac{a^2}{a^2 + x'^2}\left(3 - e^{-\frac{2z}{a}}\right)\cos^2\left(\frac{\pi}{2}\frac{y'}{3a}\right)$$

$$f_3(x,y,z) = A\frac{a^2}{\frac{a^2}{4} + x'^2 + y'^2}\left(e^{-\frac{2z}{a}} + \frac{a^2}{2(a+2z)^2}\right)$$

#### 2.2 DASY5 E-Field Probe

The SAR measurement is conducted with the dosimetric probe manufactured by SPEAG. The probe is specially designed and calibrated for use in liquid with high permittivity. The dosimetric probe has special calibration in liquid at different frequency.

SPEAG conducts the probe calibration in compliance with international and national standards (e.g. IEEE 1528, EN 62209-1, IEC 62209, etc.) under ISO 17025. The calibration data are in Appendix D.

## 2.2.1 Isotropic E-Field Probe Specification

Model	Ex3DV4		
Construction	Symmetrical design with triangular core Built-in shielding against static charges PEEK enclosure material (resistant to organic solvents, e.g., DGBE)		
Frequency	10 MHz to 6 GHz Linearity: ± 0.2 dB (30 MHz to 6 GHz)		
Directivity	± 0.3 dB in HSL (rotation around probe axis) ± 0.5 dB in tissue material (rotation normal to probe axis)	/	
Dynamic Range	10 μW/g to 100 mW/g Linearity: ± 0.2 dB (noise: typically < 1 μW/g)		
Dimensions	Overall length: 330 mm (Tip: 20 mm) Tip diameter: 2.5 mm (Body: 12 mm) Typical distance from probe tip to dipole centers: 1 mm		
Application	High precision dosimetric measurements in any e (e.g., very strong gradient fields). Only probe which compliance testing for frequencies up to 6 GHz w 30%.	ch enables	



## 2.3 Boundary Detection Unit and Probe Mounting Device

The DASY probes use a precise connector and an additional holder for the probe, consisting of a plastic tube and a flexible silicon ring to center the probe. The connector at the DAE is flexibly mounted and held in the default position with magnets and springs. Two switching systems in the connector mount detect frontal and lateral probe collisions and trigger the necessary software response.

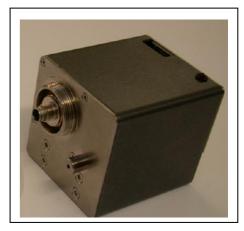


## 2.4 DATA Acquisition Electronics (DAE) and Measurement Server

The data acquisition electronics (DAE) consists of a highly sensitive electrometer-grade preamplifier with auto-zeroing, a channel and gain-switching multiplexer, a fast 16 bit AD-converter and a command decoder and control logic unit.

Transmission to the measurement server is accomplished through an optical downlink for data and status information as well as an optical uplink for commands and the clock. The input impedance of the DAE4 is 200M Ohm; the inputs are symmetrical and floating. Common mode rejection is

above 80dB.



The DASY5 measurement server is based on a PC/104 CPU board with a 400MHz intel ULV Celeron, 128MB chipdisk and 128MB RAM. The necessary circuits for communication with the DAE electronics box, as well as the 16 bit AD converter system for optical detection and digital I/O interface are contained on the DASY5 I/O board, which is directly connected to the PC/104 bus of the CPU board.





#### 2.5 Robot

The DASY5 system uses the high precision robots TX90 XL type out of the newer series from Stäubli SA (France). For the 6-axis controller DASY5 system, the CS8C robot controller version from Stäubli is used.

The XL robot series have many features that are important for our application:

- High precision (repeatability 0.02 mm)
- High reliability (industrial design)
- Jerk-free straight movements
- Low ELF interference (the closed metallic construction shields against motor control fields)
- ➢ 6-axis controller



## 2.6 Light Beam Unit

The light beam switch allows automatic "tooling" of the probe. During the process, the actual position of the probe tip with respect to the robot arm is measured, as well as the probe length and the horizontal probe offset. The software then corrects all movements, such that the robot coordinates are valid for the probe tip.

The repeatability of this process is better than 0.1 mm. If a position has been taught with an aligned probe, the same position will be reached with another aligned probe within 0.1 mm, even if the other probe has different dimensions. During probe rotations, the probe tip will keep its actual position.





#### 2.7 Device Holder

The DASY5 device holder is designed to cope with different positions given in the standard. It has two scales for the device rotation (with respect to the body axis) and the device inclination (with respect to the line between the ear reference points). The rotation center for both scales is the ear reference point (EPR).

Thus the device needs no repositioning when changing the angles.

The DASY5 device holder has been made out of low-loss POM material having the following dielectric parameters: relative permittivity  $\varepsilon r = 3$  and loss tangent  $\delta = 0.02$ . The amount of dielectric material has been reduced in the closest vicinity of the device, since measurements have suggested that the influence of the clamp on the test results could thus be lowered.



#### 2.8 SAM Twin Phantom

The SAM twin phantom is a fiberglass shell phantom with 2mm shell thickness (except the ear region where shell thickness increases to 6mm). It has three measurement areas:

- Left head
- Right head
- > Flat phantom



The bottom plate contains three pair of bolts for locking the device holder. The device holder positions are adjusted to the standard measurement positions in the three sections. A white cover is provided to tap the phantom during off-periods to prevent water evaporation and changes in the liquid parameters. On the phantom top, three reference markers are provided to identify the phantom position with respect to the robot.



# 3. Tissue Simulating Liquid

## 3.1 The composition of the tissue simulating liquid

INGREDIENT	2450MHz
(% Weight)	Head
Water	46.70
Salt	0
Sugar	0
HEC	0
Preventol	0
DGBE	53.30
Triton X-100	0

## 3.2 Tissue Calibration Result

The dielectric parameters of the liquids were verified prior to the SAR evaluation using Dielectric Probe Kit and Vector Network Analyzer.

Head Tissue Simulate Measurement					
Frequency	Decembries	Dielectric Pa	Tissue Temp.		
[MHz]	Description	٤r	σ [s/m]	[°C]	
2450 MHz	Reference result ± 5% window	39.2 37.24 to 41.16	1.8 1.71 to 1.89	N/A	
	23-Mar-22	40.19	1.77	22.1	
2402 MHz	Channel 0	40.37	1.71	22.1	
2441 MHz	Channel 39	40.22	1.75	22.1	
2480 MHz	Channel 78	40.07	1.81	22.1	

Page: 13 of 25



## 3.3 Tissue Dielectric Parameters for Head and Body Phantoms

The head tissue dielectric parameters recommended by the IEC 62209-1 have been incorporated in the following table. These head parameters are derived from planar layer models simulating the highest expected SAR for the dielectric properties and tissue thickness variations in a human head. Other head tissue parameters that have not been specified are interpolated according to the head parameters specified in IEC 62209-1

Target Frequency	Н	ead
(MHz)	εr	σ (S/m)
300	45.3	0.87
450	43.5	0.87
750	41.9	0.89
835	41.5	0.90
900	41.5	0.97
1450	40.5	1.20
1640	40.2	1.31
1750	40.1	1.37
1800 – 2000	40.0	1.40
2450	39.2	1.80
3000	38.5	2.40
5000	36.2	4.45
5200	36.0	4.66
5400	35.8	4.86
5600	35.3	5.27
5800	35.3	5.27
6000	35.1	5.48

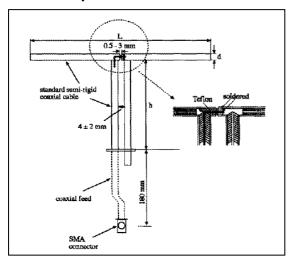
( $\varepsilon_r$  = relative permittivity,  $\sigma$  = conductivity and  $\rho$  = 1000 kg/m<sup>3</sup>)



## 4. SAR Measurement Procedure

## 4.1 SAR System Check

## 4.1.1 Dipoles



The dipoles used is based on the IEEE-1528 standard, and is complied with mechanical and electrical specifications in line with the requirements of both IEEE and FCC Supplement C. the table below provides details for the mechanical and electrical specifications for the dipoles.

Frequency	L (mm)	h (mm)	d (mm)
2450MHz	51.5	30.4	3.6

## 4.1.2 System Check Result

System Performance Check at 2450MHz Dipole Kit: D2450V2					
Frequency [MHz] Description SAR [w/kg] SAR [w/kg] Tissue Temp. 10g [°C]					
2450 MHz	Reference result ± 10% window	53.1 47.79 to 58.41	24.6 22.14 to 27.06	N/A	
	23-Mar-22	54	25.16	22.1	

Note: (1) The power level is used 250mW

- (2) All SAR values are normalized to 1W forward power.
- (3) The reference result is from Appendix E.



#### 4.2 SAR Measurement Procedure

The Dasy5 calculates SAR using the following equation,

$$SAR = \frac{\sigma |E|^2}{\rho}$$

σ: represents the simulated tissue conductivity

p: represents the tissue density

The EUT is set to transmit at the required power in line with product specification, at each frequency relating to the LOW, MID, and HIGH channel settings.

Pre-scans are made on the device to establish the location for the transmitting antenna, using a large area scan in either air or tissue simulation fluid.

The EUT is placed against the Universal Phantom where the maximum area scan dimensions are larger than the physical size of the resonating antenna. When the scan size is not large enough to cover the peak SAR distribution, it is modified by either extending the area scan size in both the X and Y directions, or the device is shifted within the predefined area.

The area scan is then run to establish the peak SAR location (interpolated resolution set at 1mm<sup>2</sup>) which is then used to orient the center of the zoom scan. The zoom scan is then executed and the 1g and 10g averages are derived from the zoom scan volume (interpolated resolution set at 1mm<sup>3</sup>).



# 5. SAR Exposure Limits

SAR assessments have been made in line with the requirements of IEEE-1528, FCC Supplement C, and comply with ANSI/IEEE C95.1-1992 "Uncontrolled Environments" limits. These limits apply to a location which is deemed as "Uncontrolled Environment" which can be described as a situation where the general public may be exposed to an RF source with no prior knowledge or control over their exposure.

Limits for General Population/Uncontrolled Exposure (W/kg)

Type Exposure	Uncontrolled Environment Limit
Spatial Peak SAR (1g cube tissue for brain or body)	1.60 W/kg
Spatial Average SAR (whole body)	0.08 W/kg
Spatial Peak SAR (10g for hands, feet, ankles and wrist)	4.00 W/kg

Page: 17 of 25



# 6. Test Equipment List

Instrument	Manufacturer	Model No.	Serial No.	Last	Next
				Calibration	Calibration
Reference Dipole 2450MHz	Speag	D2450V2	930	2019/11/21	2022/11/20
Device Holder	Speag	N/A	N/A	N/A	N/A
Data Acquisition Electronic	Speag	DAE4	1651	2022/02/04	2023/02/03
E-Field Probe	Speag	EX3DV4	7631	2022/01/24	2023/01/23
SAR Software	Speag	DASY52	V52.10.0.1446	N/A	N/A
Power Amplifier	Mini-Circuit	ZHL-42	D051404-20	N/A	N/A
Directional Coupler	Agilent	87300C	MY44300353	N/A	N/A¹
Attenuator	Woken	WATT-218FS-10	N/A	N/A	N/A <sup>1</sup>
Attenuator	Mini-Circuit	BW-S20W2+	N/A	N/A	N/A <sup>1</sup>
Vector Network Analyzer	Keysight	E5071C	MY46106342	2021/10/18	2022/10/17
Signal Generator	Anritsu	MG3694A	041902	2021/08/26	2022/08/25
Power Meter	Anritsu	ML2487A	6K00001447	2021/11/02	2022/11/01
Power Sensor	Anritsu	MA2411B	1339194	2021/11/02	2022/11/01

Note: 1. System Check, the path loss measured by the network analyzer, includes the signal generator, amplifier, cable, attenuator and directional coupler.

Page: 18 of 25



### Note:

Per KDB 865664 D01 requirements for dipole calibration, the following are recommended FCC procedures for SAR dipole calibration.

- 1. After a dipole is damaged and properly repaired to meet required specifications
- 2. When the measured SAR deviates from the calibrated SAR value by more than 10% due to changes in physical, mechanical, electrical or other relevant dipole conditions;
- 3. When the most recent return-loss, measured at least annually, deviates by more than 20% from the previous measurement (i.e. 0.2 of the dB value) or not meeting the required -20 dB return-loss specification

	Frequency	Tissue	Return loss	Limit	Verified Date
Calibration	2450	Head	-25.16dB		2019.11.21
Measurement	2450	Head	-24.77dB	Within 20%	2020.11.18
Measurement	2450	Head	-25.29dB		2021.11.16

4. When the most recent measurement of the real or imaginary parts of the impedance, measured at least annually, deviates by more than 5  $\Omega$  from the previous measurement

	Frequency	Tissue	Impedance	Limit	Verified Date
Calibration	2450	Head	54.37		2019.11.21
Measurement	2450	Head	56.58	Within 5Ω	2020.11.18
Measurement	2450	Head	55.9		2021.11.16



# 7. Measurement Uncertainty

Measu	rement u	ncerta	inty f	or 30	MHz 1	to 3 GHz		
Error Description	Uncert.	Prob.	Div.	(Ci)	(Ci)	Std. Unc.	Std. Unc.	(Vi)
	value	Dist.		1g	10g	(1g)	(10g)	Veff
Measurement System		•					•	
Probe Calibration	±6%	N	1	1	1	±6.0%	±6.0%	∞
Axial Isotropy	±4.7%	R	√3	0.7	0.7	±1.9%	±1.9%	∞
Hemispherical Isotropy	±9.6%	R	√3	0.7	0.7	±3.9%	±3.9%	∞
Boundary Effects	±1.0%	R	√3	1	1	±0.6%	±0.6%	∞
Linearity	±4.7%	R	√3	1	1	±2.7%	±2.7%	∞
System Detection Limits	±1.0%	R	√3	1	1	±0.6%	±0.6%	∞
Modulation Response	±2.4%	R	√3	1	1	±1.4%	±1.4%	∞
Readout Electronics	±0.3%	N	1	1	1	±0.3%	±0.3%	∞
Response Time	±0.8%	R	√3	1	1	±0.5%	±0.5%	∞
Integration Time	±2.6%	R	√3	1	1	±1.5%	±1.5%	∞
RF Ambient Noise	±3.0%	R	√3	1	1	±1.7%	±1.7%	∞
RF Ambient Reflections	±3.0%	R	√3	1	1	±1.7%	±1.7%	∞
Probe Positioner	±0.4%	R	√3	1	1	±0.2%	±0.2%	∞
Probe Positioning	±2.9%	R	√3	1	1	±1.7%	±1.7%	∞
Max. SAR Eval.	±4.0%	R	√3	1	1	±1.2%	±1.2%	∞
Test Sample Related			•	•	1	•		
Device Positioning	±2.9%	N	1	1	1	±2.9%	±2.9%	145
Device Holder	±3.6%	N	1	1	1	±3.6%	±3.6%	5
Power Drift	±5.0%	R	√3	1	1	±2.9%	±2.9%	∞
Power Scaling	±0%	R	√3	1	1	±0.0%	±0.0%	
Phantom and Setup								
Phantom Uncertainty	±6.1%	R	√3	1	1	±3.5%	±3.5%	∞
SAR correction	±1.9%	R	√3	1	0.84	±1.1%	±0.9%	∞
Liquid Conductivity (meas.)	±2.5%	R	√3	0.78	0.71	±1.1%	±1.0%	∞
Liquid Permittivity (meas.)	±2.5%	R	√3	0.26	0.26	±0.3%	±0.4%	∞
Temp. unc Conductivity	±3.4%	R	√3	0.78	0.71	±1.5%	±1.4%	∞
Temp. unc Permittivity	±0.4%	R	√3	0.23	0.26	±0.1%	±0.1%	∞
Combined Std. Uncertainty	•	•	•	•	•	±11.2%	±11.1%	361
Expanded STD Uncertainty						±22.3%	±22.2%	

Page: 20 of 25



Meası	urement u	uncerta	ainty	for 30	SHz to	6 GHz		
Error Description	Uncert.	Prob.	Div.	(Ci)	(Ci)	Std. Unc.	Std. Unc.	(Vi)
	value	Dist.		1g	10g	(1g)	(10g)	Veff
Measurement System			•	1	1			•
Probe Calibration	±6.55%	N	1	1	1	±6.55%	±6.55%	∞
Axial Isotropy	±4.7%	R	√3	0.7	0.7	±1.9%	±1.9%	∞
Hemispherical Isotropy	±9.6%	R	√3	0.7	0.7	±3.9%	±3.9%	∞
Boundary Effects	±2.0%	R	√3	1	1	±1.2%	±1.2%	∞
Linearity	±4.7%	R	√3	1	1	±2.7%	±2.7%	∞
System Detection Limits	±1.0%	R	√3	1	1	±0.6%	±0.6%	∞
Modulation Response	±2.4%	R	√3	1	1	±1.4%	±1.4%	∞
Readout Electronics	±0.3%	N	1	1	1	±0.3%	±0.3%	∞
Response Time	±0.8%	R	√3	1	1	±0.5%	±0.5%	∞
Integration Time	±2.6%	R	√3	1	1	±1.5%	±1.5%	∞
RF Ambient Noise	±3.0%	R	√3	1	1	±1.7%	±1.7%	∞
RF Ambient Reflections	±3.0%	R	√3	1	1	±1.7%	±1.7%	∞
Probe Positioner	±0.8%	R	√3	1	1	±0.5%	±0.5%	∞
Probe Positioning	±6.7%	R	√3	1	1	±3.9%	±3.9%	∞
Post-processing	±4.0%	R	√3	1	1	±2.3%	±2.3%	∞
Test Sample Related								
Device Positioning	±2.9%	N	1	1	1	±2.9%	±2.9%	145
Device Holder	±3.6%	N	1	1	1	±3.6%	±3.6%	5
Power Drift	±5.0%	R	√3	1	1	±2.9%	±2.9%	∞
Power Scaling	±0%	R	√3	1	1	±0.0%	±0.0%	
Phantom and Setup		•					•	
Phantom Uncertainty	±6.6%	R	√3	1	1	±3.8%	±3.8%	∞
SAR correction	±1.9%	R	√3	1	1	±1.1%	±0.9%	∞
Liquid Conductivity (meas.)	±2.5%	R	√3	1	0.84	±1.1%	±1.0%	∞
Liquid Permittivity (meas.)	±2.5%	R	√3	0.26	0.26	±0.3%	±0.4%	∞
Temp. unc Conductivity	±3.4%	R	√3	0.78	0.71	±1.5%	±1.4%	∞
Temp. unc Permittivity	±0.4%	R	√3	0.23	0.26	±0.1%	±0.1%	∞
Combined Std. Uncertainty	•	•	•			±12.3%	±12.2%	748
Expanded STD Uncertainty						±24.6%	±24.5%	



# 8. Conducted Power Measurement (Including tolerance allowed for production unit)

ВТ	ВТ							
				SISO-Main(TX1)				
ut power	Frequency	Mode	de Modulation		AV Power	AV Target		
outp	BIT 2.4GHz				0	10.69	11.5	
mnı		BR	BR GFSK  EDR 8DPSK	39	10.88	11.5		
axin				78	10.79	11.5		
E H				0	8.78	9.0		
шос	BT 2.4GHz	EDR		39	8.76	9.0		
ooth				78	8.99	9.0		
lueto				0	4.84	5.0		
	Δ	BLE	GFSK	19	4.82	5.0		
				39	4.92	5.0		

Page: 22 of 25



# 9. Test Results

# 9.1 SAR Test Results Summary

SAR MEA	SAR MEASUREMENT									
Liquid Ten	Liquid Temperature (°C): 22.1 ±2 Relative Humidity (%): 53									
Ambient T	emperatur	e (°C)	23.1 ±2			Dep	oth of Liquid (cr	n) : >15		
Test	Conducted Power SAR 1g (W/kg)									
Position	Position	(mm)	Channel	MHz	Measurement	Tune-up		Tune-up Scaled	Plot No.	
Test Mode	: BT-1M									
Back	Fixed	0	39	2441	10.88	11.5	0.096	0.143		
Front	Fixed	0	0	2402	10.69	11.5	0.086	0.133		
Front	Fixed	0	39	2441	10.88	11.5	0.101	0.149	1	
Front	Front Fixed 0 78 2480 10.79 11.5 0.083 0.125								-	
Note: Duty	cycle: 78%	1								

Page: 23 of 25



## 10. SAR measurement variability

- 1) Repeated measurement is not required when the original highest measured SAR is < 0.80 W/kg; steps 2) through 4) do not apply.
- 2) When the original highest measured SAR is ≥ 0.80 W/kg, repeat that measurement once.
- 3) Perform a second repeated measurement only if the ratio of largest to smallest SAR for the original and first repeated measurements is > 1.20 or when the original or repeated measurement is ≥ 1.45 W/kg (~ 10% from the 1-g SAR limit).
- 4) Perform a third repeated measurement only if the original, first or second repeated measurement is ≥ 1.5 W/kg and the ratio of largest to smallest SAR for the original, first and second repeated measurements is > 1.20.

Freque	ency		SAR 1g (W/kg)							
				First Repeated		epeated	Second Repeated		Third Repeated	
Channel	MHz	Original	Value	Ratio	Value	Ratio	Value	Ratio		
39	2441	0.101	N/A	N/A	N/A	N/A	N/A	N/A		



## **Appendix**

Appendix A. SAR System Check Data

Appendix B. SAR measurement Data

**Appendix C. Test Setup Photographs** 

**Appendix D. Probe Calibration Data** 

Appendix E. Dipole Calibration Data

Appendix F. Product Photos-Please refer to the file: 2230635R-Product Photos



## Appendix A. SAR System Check Data

Date: 2022/03/23 Test Laboratory: DEKRA

## System Performance Check\_2450MHz-Head

**DUT:** D2450V2; Type: D2450V2

Communication System: UID 0, CW; Frequency: 2450 MHz;

Communication System PAR: 0 dB

Medium parameters used: f = 2450 MHz;  $\sigma = 1.77 \text{ S/m}$ ;  $\varepsilon_r = 40.19$ ;  $\rho = 1000 \text{ kg/m}^3$ 

Phantom section: Flat Section

Ambient Temperature (°C): 23.1, Liquid Temperature (°C): 22.1 Measurement Standard: DASY5 (IEEE/IEC/ANSI C63.19-2011)

DASY5 Configuration:

- Probe: EX3DV4 SN7631; ConvF(8.24, 8.24, 8.24); Calibrated: 2022/01/24;
- Sensor-Surface: 1.4mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn1651; Calibrated: 2022/02/24
- Phantom: Twin-SAM V8.0; Type: QD 000 P41 AA; Serial: 2030
  Measurement SW: DASY52, Version 52.10 (0); SEMCAD X Version 14.6.10 (7417)

# Configuration/2450MHz Head/Area Scan (10x10x1): Measurement grid: dx=12mm,

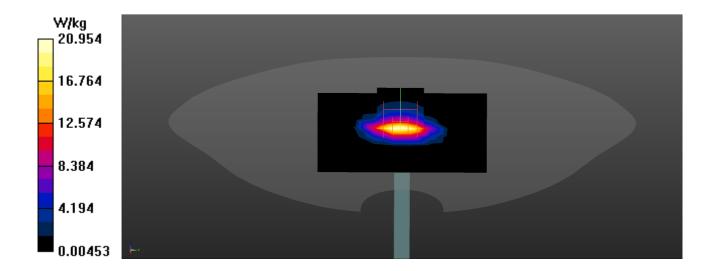
Maximum value of SAR (measured) = 21.0 W/kg

## Configuration/2450MHz Head/Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dv=5mm. dz=5mm

Reference Value = 104.3 V/m; Power Drift = 0.04 dB

Peak SAR (extrapolated) = 26.9 W/kg

SAR(1 g) = 13.5 W/kg; SAR(10 g) = 6.29 W/kg Maximum value of SAR (measured) = 22.7 W/kg





## Appendix B. SAR measurement Data

Test Laboratory: DEKRA Date: 2022/03/23

### BT-1M 39-Front

DUT: Bluetooth Headset: Type: HSC018Wa

Communication System: UID 0, BT 1M&3M&BLE; Frequency: 2441 MHz;

Communication System PAR: 0 dB

Medium parameters used: f = 2441 MHz;  $\sigma = 1.75$  S/m;  $\varepsilon_r = 40.22$ ;  $\rho = 1000$  kg/m<sup>3</sup>

Phantom section: Flat Section

Ambient Temperature (°C): 23.1, Liquid Temperature (°C): 22.1 Measurement Standard: DASY5 (IEEE/IEC/ANSI C63.19-2011)

DASY5 Configuration:

- Probe: EX3DV4 SN7631; ConvF(8.24, 8.24, 8.24); Calibrated: 2022/01/24;
- Sensor-Surface: 1.4mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn1651; Calibrated: 2022/02/24 Phantom: Twin-SAM V8.0; Type: QD 000 P41 AA; Serial: 2030
- Measurement SW: DASY52, Version 52.10 (0); SEMCAD X Version 14.6.10 (7417)

Configuration/Flat/Area Scan (10x11x1): Measurement grid: dx=12mm, dy=12mm Maximum value of SAR (measured) = 0.134 W/kg

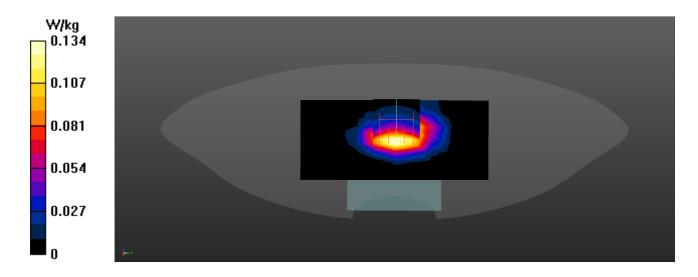
Configuration/Flat/Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 9.323 V/m; Power Drift = -0.04 dB

Peak SAR (extrapolated) = 0.171 W/kg

SAR(1 g) = 0.101 W/kg; SAR(10 g) = 0.056 W/kg

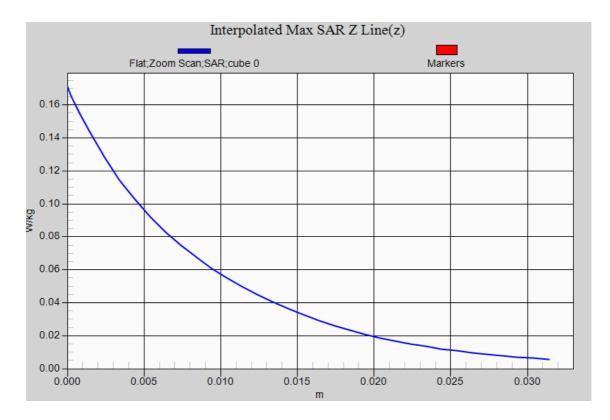
Maximum value of SAR (measured) = 0.145 W/kg





# **BT-1M EUT Front Z-Axis plot**

## Channel: 39





# **Appendix D. Probe Calibration**

## Calibration Laboratory of Schmid & Partner Engineering AG Zeughausstrasse 43, 8004 Zurich, Switzerland





S Schweizerischer Kalibrierdienst
C Service suisse d'étalonnage
Servizio svizzero di taratura
Swiss Calibration Service

Accreditation No.: SCS 0108

Certificate No: EX3-7631\_Jan22

Accredited by the Swiss Accreditation Service (SAS)

The Swiss Accreditation Service is one of the signatories to the EA

Multilateral Agreement for the recognition of calibration certificates

Client

Dekra-TW (Auden)

## **CALIBRATION CERTIFICATE**

Object

EX3DV4 - SN:7631

Calibration procedure(s)

QA CAL-01.v9, QA CAL-12.v9, QA CAL-14.v6, QA CAL-23.v5,

**QA CAL-25.v7** 

Calibration procedure for dosimetric E-field probes

Calibration date:

January 24, 2022

This calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI). The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

All calibrations have been conducted in the closed laboratory facility: environment temperature (22 ± 3)°C and humidity < 70%.

Calibration Equipment used (M&TE critical for calibration)

Primary Standards	ID	Cal Date (Certificate No.)	Scheduled Calibration
Power meter NRP	SN: 104778	09-Apr-21 (No. 217-03291/03292)	Apr-22
Power sensor NRP-Z91	SN: 103244	09-Apr-21 (No. 217-03291)	Apr-22
Power sensor NRP-Z91	SN: 103245	09-Apr-21 (No. 217-03292)	Apr-22
Reference 20 dB Attenuator	SN: CC2552 (20x)	09-Apr-21 (No. 217-03343)	Apr-22
DAE4	SN: 660	13-Oct-21 (No. DAE4-660_Oct21)	Oct-22
Reference Probe ES3DV2	SN: 3013	27-Dec-21 (No. ES3-3013_Dec21)	Dec-22
Secondary Standards	ID	Check Date (in house)	Scheduled Check
Power meter E4419B	SN: GB41293874	06-Apr-16 (in house check Jun-20)	In house check: Jun-22
Power sensor E4412A	SN: MY41498087	06-Apr-16 (in house check Jun-20)	In house check: Jun-22
Power sensor E4412A	SN: 000110210	06-Apr-16 (in house check Jun-20)	In house check: Jun-22
RF generator HP 8648C	SN: US3642U01700	04-Aug-99 (in house check Jun-20)	In house check: Jun-22
Network Analyzer E8358A	SN: US41080477	31-Mar-14 (in house check Oct-20)	In house check: Oct-22

	Name	Function	Signature	
Calibrated by:	Jeton Kastrati	Laboratory Technician	+=le	
Approved by:	Sven Kühn	Deputy Manager	5.4	

Issued: January 28, 2022

This calibration certificate shall not be reproduced except in full without written approval of the laboratory

## **Calibration Laboratory of**

Schmid & Partner
Engineering AG
Zeughausstrasse 43, 8004 Zurich, Switzerland





S Schweizerischer Kalibrierdienst
Service suisse d'étalonnage
Servizio svizzero di taratura
Swiss Calibration Service

Accreditation No.: SCS 0108

Accredited by the Swiss Accreditation Service (SAS)

The Swiss Accreditation Service is one of the signatories to the EA Multilateral Agreement for the recognition of calibration certificates

#### Glossary:

TSL tissue simulating liquid
NORMx,y,z sensitivity in free space
ConvF sensitivity in TSL / NORMx,y,z
DCP diode compression point

CF crest factor (1/duty\_cycle) of the RF signal modulation dependent linearization parameters

Polarization  $\varphi$   $\varphi$  rotation around probe axis

Polarization 9 9 rotation around an axis that is in the plane normal to probe axis (at measurement center),

i.e., 9 = 0 is normal to probe axis

Connector Angle information used in DASY system to align probe sensor X to the robot coordinate system

## Calibration is Performed According to the Following Standards:

- a) IEC/IEEE 62209-1528, "Measurement Procedure For The Assessment Of Specific Absorption Rate Of Human Exposure To Radio Frequency Fields From Hand-Held And Body-Worn Wireless Communication Devices -Part 1528: Human Models, Instrumentation And Procedures (Frequency Range of 4 MHz to 10 GHz)", October 2020.
- b) KDB 865664, "SAR Measurement Requirements for 100 MHz to 6 GHz"

#### **Methods Applied and Interpretation of Parameters:**

- NORMx,y,z: Assessed for E-field polarization θ = 0 (f ≤ 900 MHz in TEM-cell; f > 1800 MHz: R22 waveguide). NORMx,y,z are only intermediate values, i.e., the uncertainties of NORMx,y,z does not affect the E²-field uncertainty inside TSL (see below *ConvF*).
- NORM(f)x,y,z = NORMx,y,z \* frequency\_response (see Frequency Response Chart). This linearization is implemented in DASY4 software versions later than 4.2. The uncertainty of the frequency response is included in the stated uncertainty of ConvF.
- DCPx,y,z: DCP are numerical linearization parameters assessed based on the data of power sweep with CW signal (no uncertainty required). DCP does not depend on frequency nor media.
- PAR: PAR is the Peak to Average Ratio that is not calibrated but determined based on the signal characteristics
- Ax,y,z; Bx,y,z; Cx,y,z; Dx,y,z; VRx,y,z: A, B, C, D are numerical linearization parameters assessed based on the data of power sweep for specific modulation signal. The parameters do not depend on frequency nor media. VR is the maximum calibration range expressed in RMS voltage across the diode.
- ConvF and Boundary Effect Parameters: Assessed in flat phantom using E-field (or Temperature Transfer Standard for f ≤ 800 MHz) and inside waveguide using analytical field distributions based on power measurements for f > 800 MHz. The same setups are used for assessment of the parameters applied for boundary compensation (alpha, depth) of which typical uncertainty values are given. These parameters are used in DASY4 software to improve probe accuracy close to the boundary. The sensitivity in TSL corresponds to NORMx,y,z \* ConvF whereby the uncertainty corresponds to that given for ConvF. A frequency dependent ConvF is used in DASY version 4.4 and higher which allows extending the validity from ± 50 MHz to ± 100 MHz.
- Spherical isotropy (3D deviation from isotropy): in a field of low gradients realized using a flat phantom exposed by a patch antenna.
- Sensor Offset: The sensor offset corresponds to the offset of virtual measurement center from the probe tip (on probe axis). No tolerance required.
- Connector Angle: The angle is assessed using the information gained by determining the NORMx (no uncertainty required).

Certificate No: EX3-7631\_Jan22 Page 2 of 23

EX3DV4 – SN:7631 January 24, 2022

# DASY/EASY - Parameters of Probe: EX3DV4 - SN:7631

## **Basic Calibration Parameters**

	Sensor X	Sensor Y	Sensor Z	Unc (k=2)
Norm (μV/(V/m) <sup>2</sup> ) <sup>A</sup>	0.57	0.61	0.56	± 10.1 %
DCP (mV) <sup>B</sup>	109.2	108.6	109.8	

**Calibration Results for Modulation Response** 

UID	Communication System Name		A dB	B dBõV	С	D dB	VR mV	Max dev.	Max Unc <sup>E</sup> (k=2)
0	CW	Х	0.00	0.00	1.00	0.00	178.5	± 3.3 %	± 4.7 %
		Υ	0.00	0.00	1.00		178.2		
		Z	0.00	0.00	1.00		160.0		
10352-	Pulse Waveform (200Hz, 10%)	Х	1.36	60.00	5.96	10.00	60.0	± 3.6 %	± 9.6 %
AAA		Υ	1.59	61.16	7.03		60.0		
		Z	1.59	60.77	6.20		60.0		
10353-	Pulse Waveform (200Hz, 20%)	X	0.87	60.00	4.94	6.99	80.0	± 2.8 %	± 9.6 %
AAA		Υ	0.83	60.00	5.33		80.0		
		Z	0.85	60.00	4.73		80.0		
10354- AAA	Pulse Waveform (200Hz, 40%)	X	0.50	60.00	3.95	3.98	95.0	± 2.0 %	± 9.6 %
		Υ	2.00	64.00	5.00		95.0		
		Z	0.48	60.00	3.52		95.0		
10355- AAA	Pulse Waveform (200Hz, 60%)	X	15.11	149.95	2.36	2.22	120.0	± 1.9 %	± 9.6 %
		Υ	9.12	158.36	14.54		120.0		
		Z	9.49	84.30	0.54		120.0		
10387- AAA	QPSK Waveform, 1 MHz	Х	0.66	63.80	11.78	1.00	150.0	± 4.9 %	± 9.6 %
		Υ	0.58	62.14	10.35		150.0		
		Z	0.56	65.41	13.25		150.0		
10388-	QPSK Waveform, 10 MHz	Х	1.40	65.24	13.54	0.00	150.0	± 1.2 %	± 9.6 %
AAA			1.26	63.78	12.64		150.0		1
		Z	1.38	67.17	14.43		150.0		
10396- AAA	64-QAM Waveform, 100 kHz	X	1.84	65.65	16.40	3.01	150.0	± 0.7 %	± 9.6 %
		Υ	1.82	65.69	16.48		150.0		
		Z	1.86	66.50	16.93		150.0		
10399- AAA	64-QAM Waveform, 40 MHz	Х	2.88	66.07	14.84	0.00	150.0	± 3.0 %	± 9.6 %
		Υ	2.74	65.19	14.31		150.0		
		Z	2.83	66.81	15.31		150.0		
10414-	WLAN CCDF, 64-QAM, 40MHz	Χ	3.94	65.73	15.09	0.00	150.0	± 5.3 %	± 9.6 %
AAA		Υ	4.02	65.83	15.11		150.0		
		Z	3.76	66.29	15.35		150.0		

Note: For details on UID parameters see Appendix

The reported uncertainty of measurement is stated as the standard uncertainty of measurement multiplied by the coverage factor k=2, which for a normal distribution corresponds to a coverage probability of approximately 95%.

Certificate No: EX3-7631\_Jan22 Page 3 of 23

<sup>&</sup>lt;sup>A</sup> The uncertainties of Norm X,Y,Z do not affect the E<sup>2</sup>-field uncertainty inside TSL (see Pages 5 and 6).

<sup>&</sup>lt;sup>B</sup> Numerical linearization parameter: uncertainty not required.

E Uncertainty is determined using the max. deviation from linear response applying rectangular distribution and is expressed for the square of the field value.

# DASY/EASY - Parameters of Probe: EX3DV4 - SN:7631

# **Sensor Model Parameters**

	C1	C2	α	T1	T2	Т3	T4	T5	T6
	fF	fF	V <sup>-1</sup>	ms.V⁻²	ms.V⁻¹	ms	V <sup>-2</sup>	V-1	
X	11.9	85.26	32.65	6.52	0.00	4.90	0.62	0.00	1.00
ΥΥ	13.1	94.65	33.40	4.53	0.00	4.98	0.74	0.00	1.01
Z	9.1	64.06	32.20	4.70	0.00	4.90	0.66	0.00	1.00

## **Other Probe Parameters**

Sensor Arrangement	Triangular
Connector Angle (°)	-151.6
Mechanical Surface Detection Mode	enabled
Optical Surface Detection Mode	disabled
Probe Overall Length	337 mm
Probe Body Diameter	10 mm
Tip Length	9 mm
Tip Diameter	2.5 mm
Probe Tip to Sensor X Calibration Point	1 mm
Probe Tip to Sensor Y Calibration Point	1 mm
Probe Tip to Sensor Z Calibration Point	1 mm
Recommended Measurement Distance from Surface	1.4 mm

Note: Measurement distance from surface can be increased to 3-4 mm for an Area Scan job.

EX3DV4-SN:7631

# DASY/EASY - Parameters of Probe: EX3DV4 - SN:7631

## Calibration Parameter Determined in Head Tissue Simulating Media

f (MHz) <sup>C</sup>	Relative Permittivity <sup>F</sup>	Conductivity (S/m) <sup>F</sup>	ConvF X	ConvF Y	ConvF Z	Alpha <sup>G</sup>	Depth <sup>G</sup> (mm)	Unc (k=2)
450	43.5	0.87	11.88	11.88	11.88	0.16	1.30	± 13.3 %
750	41.9	0.89	10.47	10.47	10.47	0.49	0.84	± 12.0 %
835	41.5	0.90	10.12	10.12	10.12	0.43	0.88	± 12.0 %
900	41.5	0.97	10.01	10.01	10.01	0.49	0.81	± 12.0 %
1450	40.5	1.20	9.15	9.15	9.15	0.55	0.80	± 12.0 %
1640	40.2	1.31	9.10	9.10	9.10	0.32	0.86	± 12.0 %
1750	40.1	1.37	8.76	8.76	8.76	0.27	0.86	± 12.0 %
1950	40.0	1.40	8.35	8.35	8.35	0.25	0.86	± 12.0 %
2000	40.0	1.40	8.28	8.28	8.28	0.25	0.86	± 12.0 %
2300	39.5	1.67	8.33	8.33	8.33	0.30	0.90	± 12.0 %
2450	39.2	1.80	8.24	8.24	8.24	0.32	0.90	± 12.0 %
2600	39.0	1.96	8.04	8.04	8.04	0.21	0.90	± 12.0 %
3300	38.2	2.71	7.50	7.50	7.50	0.30	1.35	± 13.1 %
3500	37.9	2.91	7.45	7.45	7.45	0.35	1.30	± 13.1 %
3700	37.7	3.12	7.20	7.20	7.20	0.35	1.30	± 13.1 %
3900	37.5	3.32	7.10	7.10	7.10	0.40	1.60	± 13.1 %
4100	37.2	3.53	6.98	6.98	6.98	0.40	1.60	± 13.1 %
4200	37.1	3.63	6.75	6.75	6.75	0.40	1.70	± 13.1 %
4400	36.9	3.84	6.68	6.68	6.68	0.40	1.70	± 13.1 %
4600	36.7	4.04	6.65	6.65	6.65	0.40	1.70	± 13.1 %
4800	36.4	4.25	6.46	6.46	6.46	0.40	1.80	± 13.1 %
4950	36.3	4.40	6.27	6.27	6.27	0.40	1.80	± 13.1 %
5250	35.9	4.71	5.94	5.94	5.94	0.40	1.80	± 13.1 %
5600	35.5	5.07	5.24	5.24	5.24	0.40	1.80	± 13.1 %
5800	35.3	5.27	5.40	5.40	5.40	0.40	1.80	± 13.1 %

<sup>&</sup>lt;sup>C</sup> Frequency validity above 300 MHz of  $\pm$  100 MHz only applies for DASY v4.4 and higher (see Page 2), else it is restricted to  $\pm$  50 MHz. The uncertainty is the RSS of the ConvF uncertainty at calibration frequency and the uncertainty for the indicated frequency band. Frequency validity below 300 MHz is  $\pm$  10, 25, 40, 50 and 70 MHz for ConvF assessments at 30, 64, 128, 150 and 220 MHz respectively. Validity of ConvF assessed at 6 MHz is 4-9 MHz, and ConvF assessed at 13 MHz. Above 5 GHz frequency validity can be extended to  $\pm$  110 MHz.

F At frequencies below 3 GHz, the validity of tissue parameters ( $\epsilon$  and  $\sigma$ ) can be relaxed to  $\pm$  10% if liquid compensation formula is applied to

Fat frequencies below 3 GHz, the validity of tissue parameters ( $\epsilon$  and  $\sigma$ ) can be relaxed to  $\pm$  10% if liquid compensation formula is applied to measured SAR values. At frequencies above 3 GHz, the validity of tissue parameters ( $\epsilon$  and  $\sigma$ ) is restricted to  $\pm$  5%. The uncertainty is the RSS of the ConvF uncertainty for indicated target tissue parameters.

<sup>&</sup>lt;sup>G</sup> Alpha/Depth are determined during calibration. SPEAG warrants that the remaining deviation due to the boundary effect after compensation is always less than ± 1% for frequencies below 3 GHz and below ± 2% for frequencies between 3-6 GHz at any distance larger than half the probe tip diameter from the boundary.