

## MANUAL DYNAMIC LINE

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	<table border="1"><tr><td><b>CAUTION</b></td></tr><tr><td>RISK OF ELECTRIC SHOCK</td></tr><tr><td>DO NOT OPEN</td></tr></table>	<b>CAUTION</b>	RISK OF ELECTRIC SHOCK	DO NOT OPEN	
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# 1 Introduction

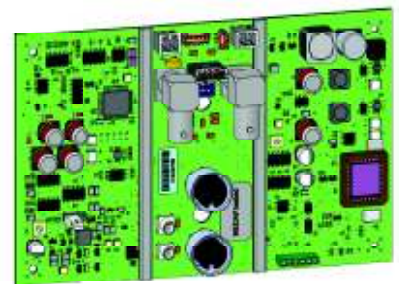
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The XQ MK2 Units are the successors of the XQ series internal OS/T electronics. The complete redesign has many new features:

- Powerful transmitter (4 watt)
- Attenuator setting can be done for every aisle separately
- Attenuation jumpers are replaced by a firmware setting
- Integral customer counting
- Integral Metal detection, fully (remote) configurable with OS/T configurator

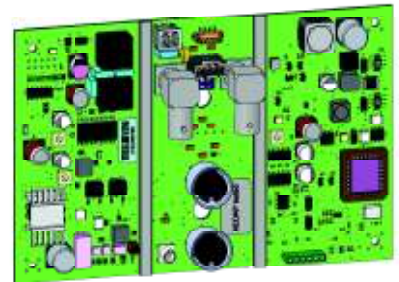
## 1.1 XQ MK2 RX (R2)

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## 1.2 XQ MK2 Tx (T2)

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## 1.3 Watt transmitter

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The advantages of the new transmitter are:

- Aisle width between panels can be proximally 10 % more for the same label  
OR
- Distance between the panels will be the same and smaller labels can be used  
OR
- To suppress interference from other systems

In combination with an AIM module (Aisle Improvement Module) the full features of the transmitter can be used.

The module increases the power up to 4Watt.

All antennas suitable for the XQ Mk2 internal units with metal detection will be suitable for 4 Watt (effective power). The outside of the antenna will be marked with a '4W' addition to the serial label. Inside the antenna there will be a label "Suitable for 4 W"

### 1.4 New Attenuator

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The advantages for the attenuator are:

- Easy installation
- Additional external attenuators are not necessary anymore
- Hardware jumper settings are replaced through software settings
- Useful for aisles with different aisle width, example system with 2 aisles
  - First aisle width is 1.60 meters
  - Second aisle width is 1.00 meters

### 1.5 Performance Indicator

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Firmware version 1.8xx and up contains performance indicators. This means that it is possible to actually trace the delivered system performance.

A Nedap EAS system contains several different signal processing functions, which are mapped to several different hardware units. For example we have a power supply, a sweep generator, a transmitter, a receiver, and deactivation units. To monitor the performance of the system from bird's eye view we have to look at and integrate all performance indicators of each comprising unit. The actual data integration is done off line, in the TOPserver and or Easinet.

For all OST units we need performance indicators:

1. Performance indicator for a power supply.  
A measure which indicates in time the actual delivery of good power. In practice as long as the system is working the power is considered to be good. So this performance is not separately monitored. System uptime is used as indicator.
2. Performance indicator for a sweep generator.  
A measure which indicates in time the actual delivery of good sweeps to the system. In practice as long as the system is working the sweep generator is considered to be good. This performance is not separately monitored. System uptime is used as indicator.
3. Performance indicator for transmitters.  
A measure which indicates in time the actual delivery of good sweeps to the transmitter panel. Interruptions of the power delivery due to AGC actions are monitored. This is a new performance indicator.
4. Performance indicator for receivers.  
A measure which indicates in time the actual reception of clean sweeps from the panel. This is not explicitly monitored. And a measure which indicates in times the actual level of external noise. This level must contain all detection prohibiting signals. This signal is monitored. This is the second new performance indicator.  
With these performance indicators it should be possible to monitor accurately the performance of the system. These indicators cover the primary detection function. Also the communication is checked continuously of course.

Altogether it is expected that the most frequent occurring disturbances and failures are covered. Some mechanical failures are not covered, like receiver antennae wire failures. To cover these type of events it is sufficient to look at the occurrence of label detection events at all. If alarm events occurs one can safely assume that the system is not dead yet.

The most important feature is the logging of EAS detection performance over time. Covered events are downtime due to power outages, loss of transmit signal due to AGC events, occurrence of alarms, and environmental noise which degrades the detection performance's. Of course it is not possible to distinguish between false alarms and true label alarms, because if that would be possible then all false alarms could be eliminated beforehand.

5. Performance indicator for standalone label deactivation units.

A measure which indicates in time:

- the actual delivery of good power
- the actual delivery of good sweeps to the system
- the actual delivery of good sweeps to the antenna

These parameters are covered by the system uptime indicator.

- the actual reception of clean sweeps from the panel

This parameter is monitored by the receiver (type) performance indicator.

## 2 Block diagrams

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The XQ MK2 Transmitter with integral customer counting and metal detection.

### 2.1 Network communication and sync

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The XQ units are slave-only, they need an RF signal originating from a master output . This could be an NCC, SQ unit or TDC unit. The RF signal has a frequency of four times 8.2 MHz and sweeps between 30.... 36 MHz. The RF signal is used to drive the transmitters as well as the receivers. The Coaxial cable between master-output and slave input is also used to distribute DC power and data-communication

#### 2.1.1 Data communication over coax

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One of the important features from the OS/T system is the data-com over the coax-cable. With this feature it's no longer necessary to use an extra data-cable between the units, which simplifies the installation of the system. All the connected units are interrogated periodically by the master. If there are messages like an alarm on a connected Rx unit, then the master unit will process this and takes the necessary action: Sending a command to turn on the lamps on the activated aisle.

The XQ MK2 unit has two slave-sync connectors (K101 and K102) from which the unit can be driven from a NCC-4, SQ, or TDC unit. DC supply is from the sync-connectors.

The Transmitter generates an 8.2 MHz RF signal with a maximum power level of 4 Watt to feed the transmitter antenna. The transmitter receives its RF reference signal and configuration data from the local communication control section.

The start-pulse is distributed as a 1 microsecond break of the RF signal (32 periods) and indicates the start of the 1.6 ms sweep. All timing of the OS/T-system is related to this start-pulse.

The RF signal (with a 30 till 36 MHz sweep) for the power amplifier is divided by 4 to create the 8.2 MHz transmitter signal. The power amplifier consists of a class D MOSFET driver stage. The square wave output is filtered to achieve a cleaner carrier. The 50 ohm output impedance is regulated by measuring output current and output voltage and adjusting the drive signal of the MOSFET power stage accordingly. These two output parameters are measured with a current transformer and a capacitive voltage divider circuit at the output stage. From these signals a phase control signal and the amplitude control signal are derived. Both signals can be seen on the test connector. The signals are the feedback to the driver stage.

### 2.2.1 Anti-deactivation regulation

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If a RF label comes close to the antenna, it could be deactivated by the transmitter field. To prevent this phenomenon a tag detection circuit is used. A tag close to the antenna can be detected by looking at the antenna signal. A resonating tag in proximity causes a small phase-disturbance in the antenna impedance, which can be seen on the phase control signal of the transmitter. When in a sweep a tag pulse is found the processor can reduce the transmit power in the next sweep to prevent deactivation of the tag. After the tag signal disappeared the transmit power is gradually increased to the desired power level.

### 2.2.2 Output multiplexer

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The transmitter can feed one antenna. The RF signal is switched during the fly-back period of the RF sweep. The multiplexer is a 1 out of 2 type build with PIN diodes. In the fly-back-period the antenna is switched off. The second output of the multiplexer goes to an internal dummy load. This is used for multiplexing when more than one aisle is used. The “unused” phases can be dumped in the dummyload.

The antenna-output has his own lamp-control-circuit and can be switched on or off individually. The lamps are controlled by software. The outputs have open, overload and short-circuit detection. These signals are under processor control.

The lamp control circuit is also used for driving the new-style (two-wire) buzzer.

### 2.2.3 Tx output power setting

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Default power setting is 2 Watts. This is suitable for almost every situation. With large aisle widths (2 meters or more) it can be useful to increase the power to 4 watts.

The Receiver detects the tag signals generated by tags in the aisle formed by a transmitter panel and a receiver panel. Even very small signals can be detected to achieve a very high pick rate. Aided by heavy use of digital signal processing the false alarm rate is very low, even under difficult noise conditions. The receiver receives its RF reference signal and configuration data from the local communication control section. The antenna is connected to K202. Every sweep the antenna can be connected to the receiver. This is done in the multiplexer circuit. After the multiplexer an attenuation stage can be used to reduce the level of direct feed through in case of very close antenna distance. The attenuator can be selected as 0, -6dB, -12dB and -18dB. The setting is possible with the hand terminal (under the sensitivity menu) or with the OS/T Configuration Manager.

A new feature is the possibility to set the attenuator per phase. The reference RF signal is split in four phases and fed to two mixers together with antenna input. Each mixer generates a LF signal which is filtered, amplified and muted in the fly back period of the RF carrier. The mute circuitry consists of several stages which are controlled by software. The mixers are fed with 90 degrees phase shift. The resulting LF signals are further processed by the digital signal processor (DSP).

The DSP uses digital memory to store the past quarter of a second to compare different sweeps and improve on noise level and other unwanted signals components. The filtered signal after processing can be seen on the scope by looking at the DAC signal.

### 2.3.1 Input multiplexer

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The receiver can process two antenna signals. This means that at most 2 antennas can be connected. The antenna signal is switched during the fly back period of the RF sweep. The multiplexer is a 1 out of 2 type build with PIN diodes. In the fly back period all antennas are switched off.

Antenna input 1 (K202) has his own lamp control circuit and can be switched on or off individually. The lamps are controlled by software. The outputs have an open, overload, and short circuit detection. These signals are under processor control.

The secondary antenna input (K201) is only meant for floor antennas and has no lamp/buzzer functionality.

### 2.3.2 Processor

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The XQ MK2 series boards (Tx and Rx) have only one processor for RX, TX and Communication control. The processor has several different tasks. It must maintain the status of the transmitter and receiver and controls several functions:

- lamp detection
- lamp/lamp overload
- multiplexer
- data communication
- handheld terminal communication
- customer-counting 1x2 inputs
- metal detection

All the processor software and all the settings (including the network address) are contained in flash memory. Software is downloadable in runtime. A new version can be distributed over the network. After downloading, flashing and verifying a new version the unit resets and is operational again. This can be done remotely.

### 2.3.3 Customer counting

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The XQ MK2 PCB has customer counting on board. A customer counter module can be connected to monitor the entrance with direction sensitivity.

The passage between sensors is shaped and buffered and processed by the processor. In this way incoming and outgoing label alarms can be counted for separately.

### 2.3.4 Service connectors

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K100: A standard NEDAP RS Service handheld terminal (HT) may be connected to connector K100. With this HT you can edit the various local settings. With this terminal all digital settings can be made, even if the network is nonfunctional. Some settings can only be adjusted by using an OS/T Configuration Manager. Especially the Metal detection settings are only possible with the configurator.

K200: The receiver test-connector shows 3 analogue signals to aid in installing and servicing the receiver section. For easy external triggering a start pulse is available.

The transmitter test connector shows the analogue signals needed to align and verify the transmitter.

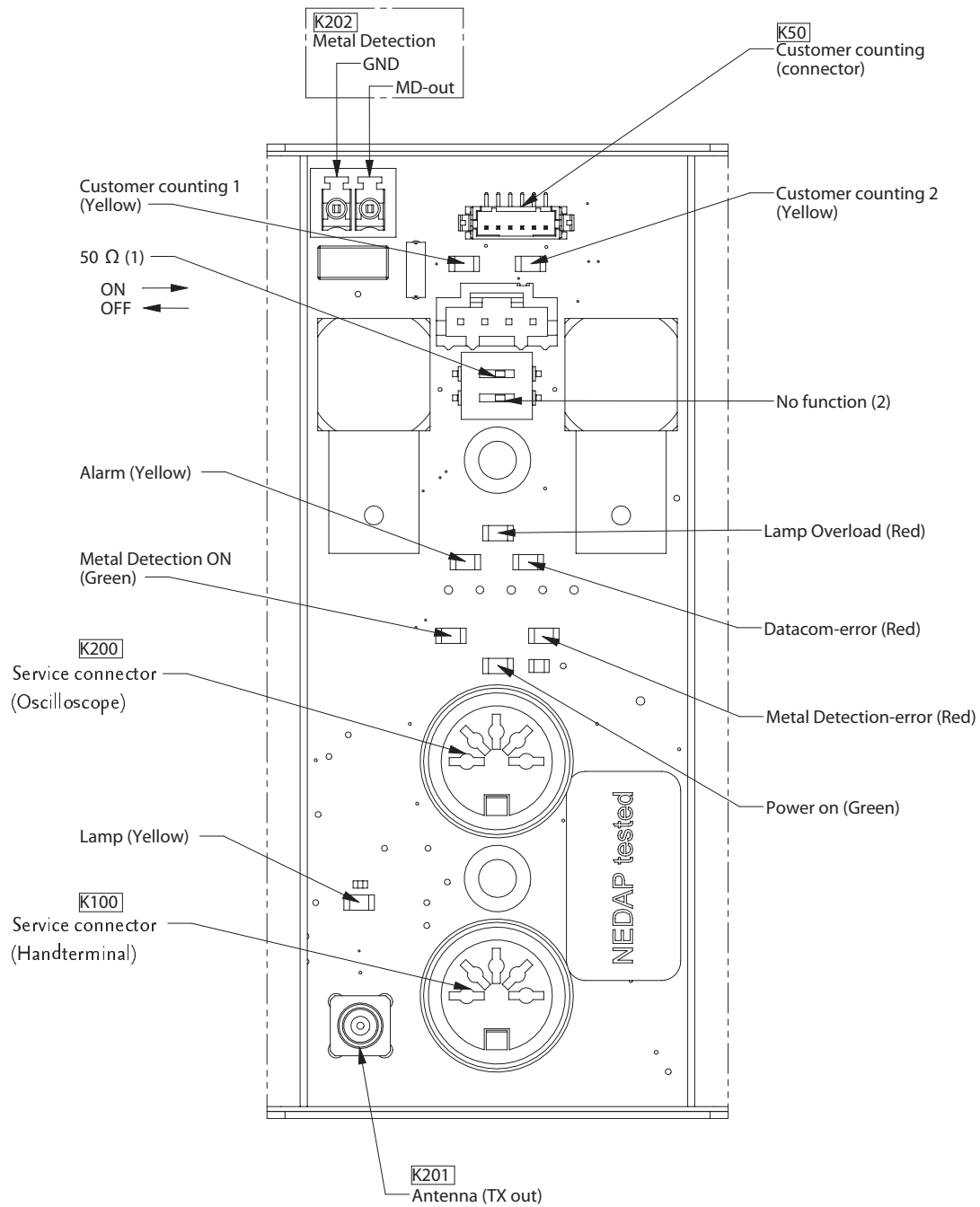
### 2.4 Dummy loads

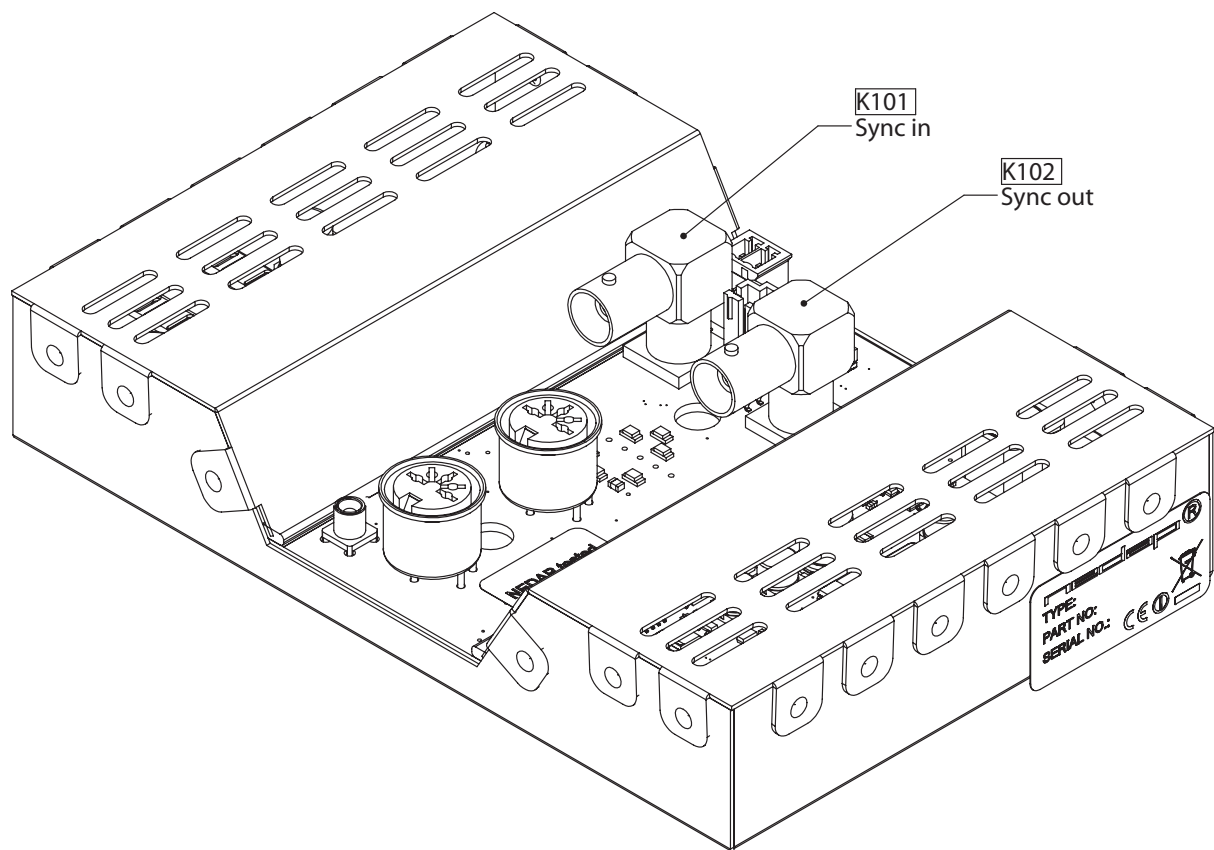
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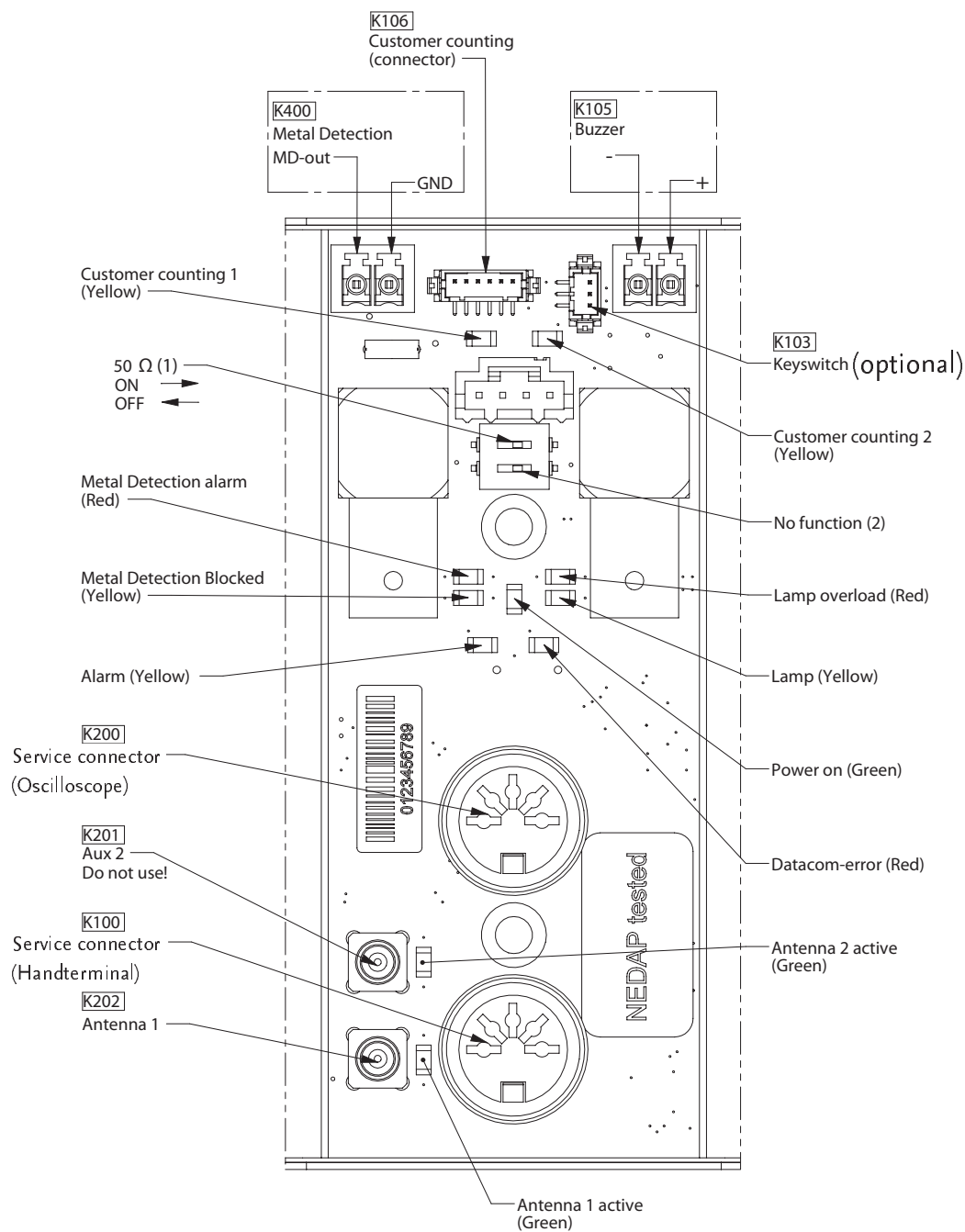
Dummy loads are no longer needed for the XQ MK2 PCB's. Unused channels will be programmed as channel "0".

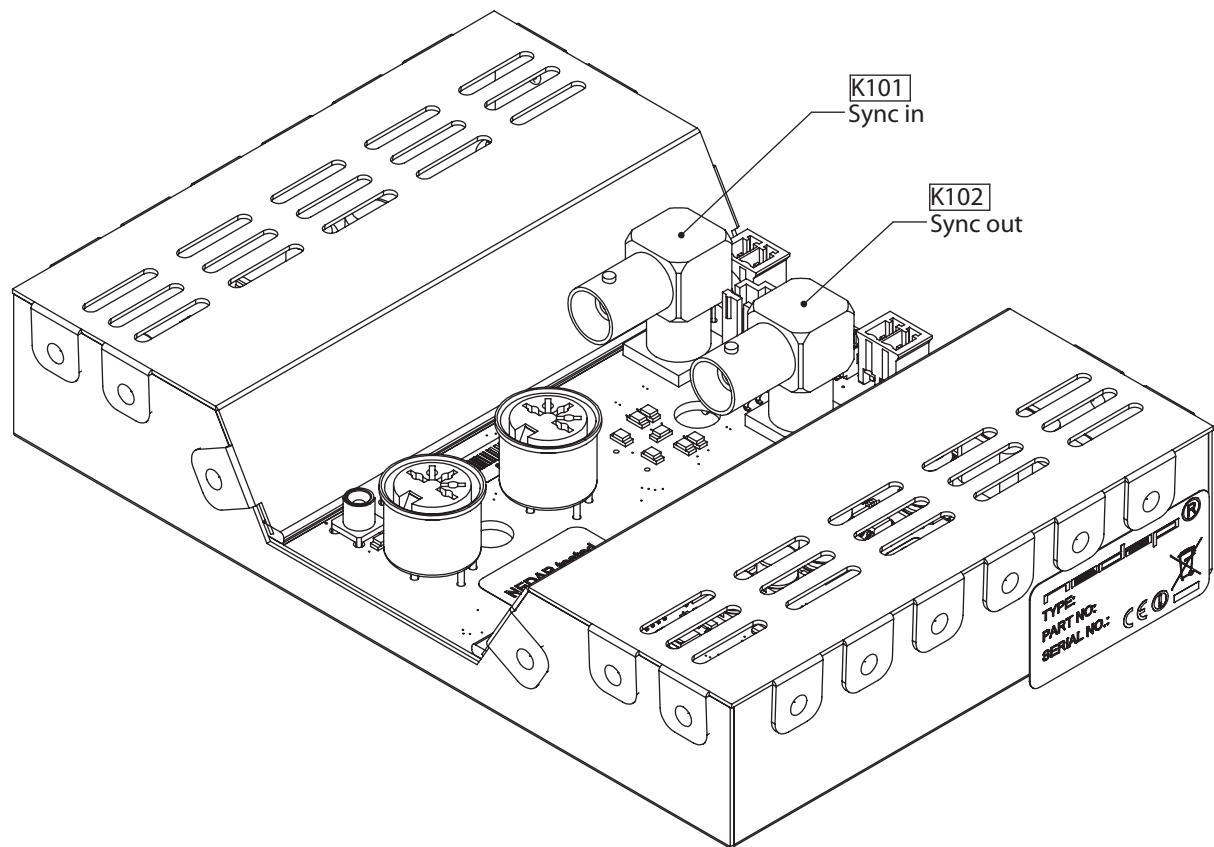
### 3 PCB Components overview

#### 3.1 Connector overview XQ TX









## 4 Unit address

Each XQ MK2 unit has a unique network address. The address is entered in the master unit to enable data communication.

The unit address is an 8 digit address; the last four digits will be a fixed couple of characters, these characters will be used in the OS/T Configuration Manager and in the hand held terminal (for instance slave table etc.)

## 5 Networking with NCC MK2

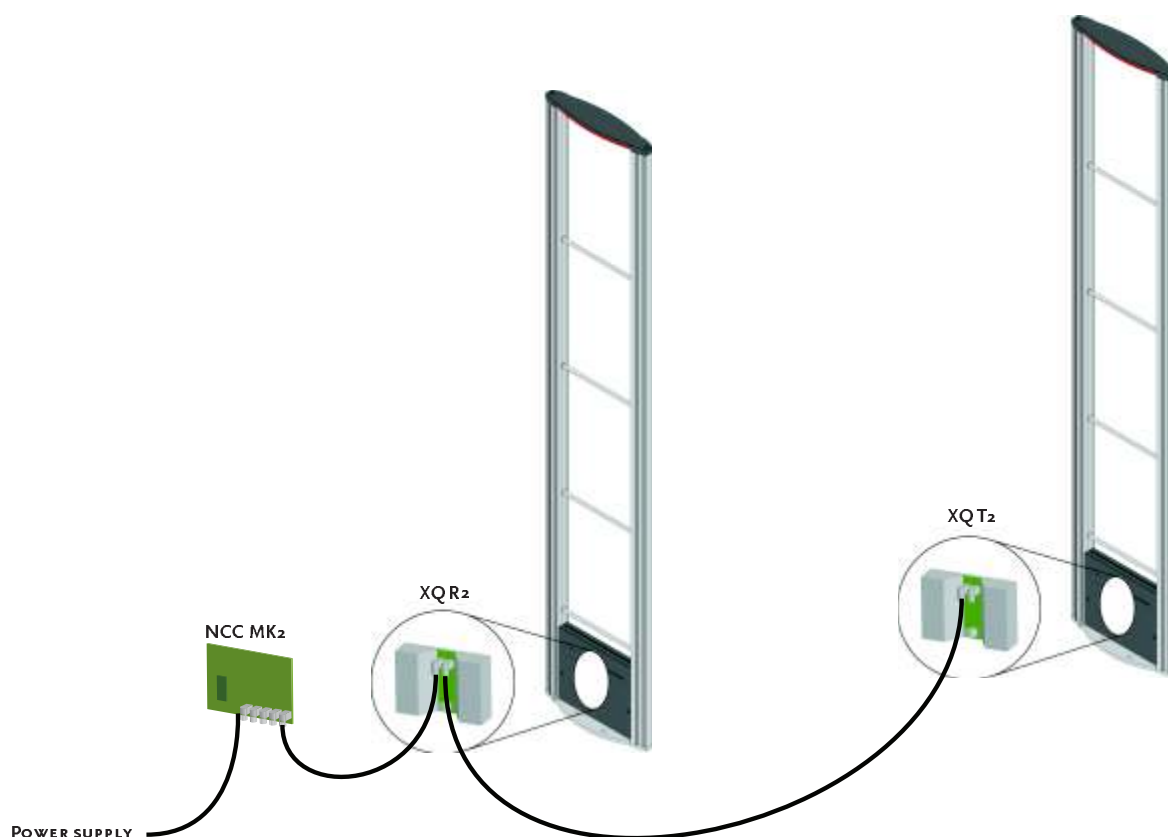
### NCC (networking electronics)

- including power supply
- synchronization of upto 16 antennas (max. 6 antennas per output)
- The NCC MK2 can deliver power for a maximum 4 antennas with XQ MK2 electronics. In case of >4 antennas, a power inserter is needed for the next 4 antennas with XQ MK2 electronics.

Numbers of antennas	Required
1 t/m 4	NCC
5 t/m 8	NCC + 1 power inserter
9 t/m 12	NCC + 2 power inserter
13 t/m 16	NCC + 3 power inserter

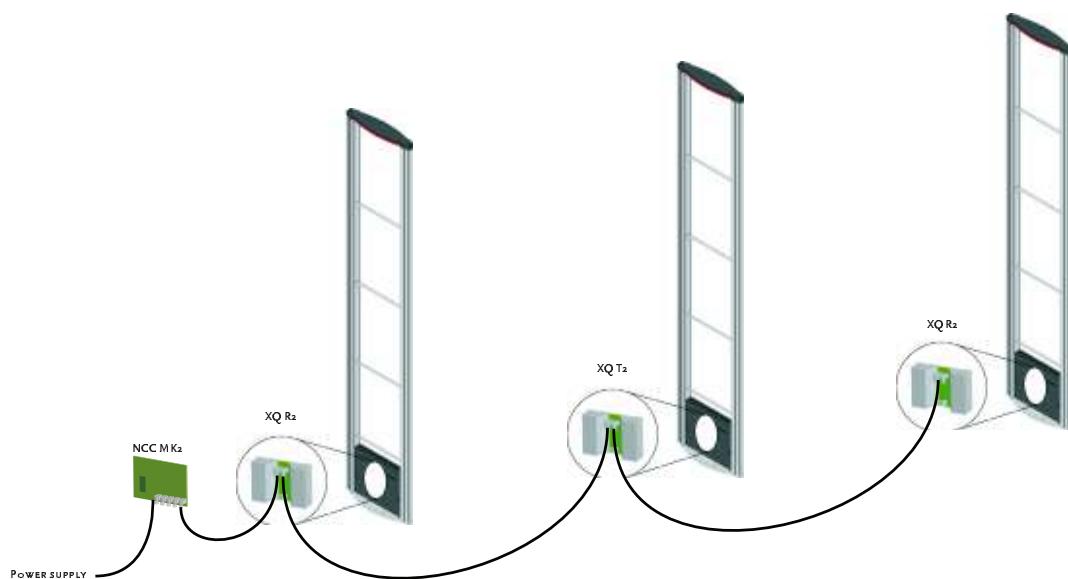
In case of large configurations, we advice you to contact Nedap Retail

### 2 antennas XQ MK2 configuration



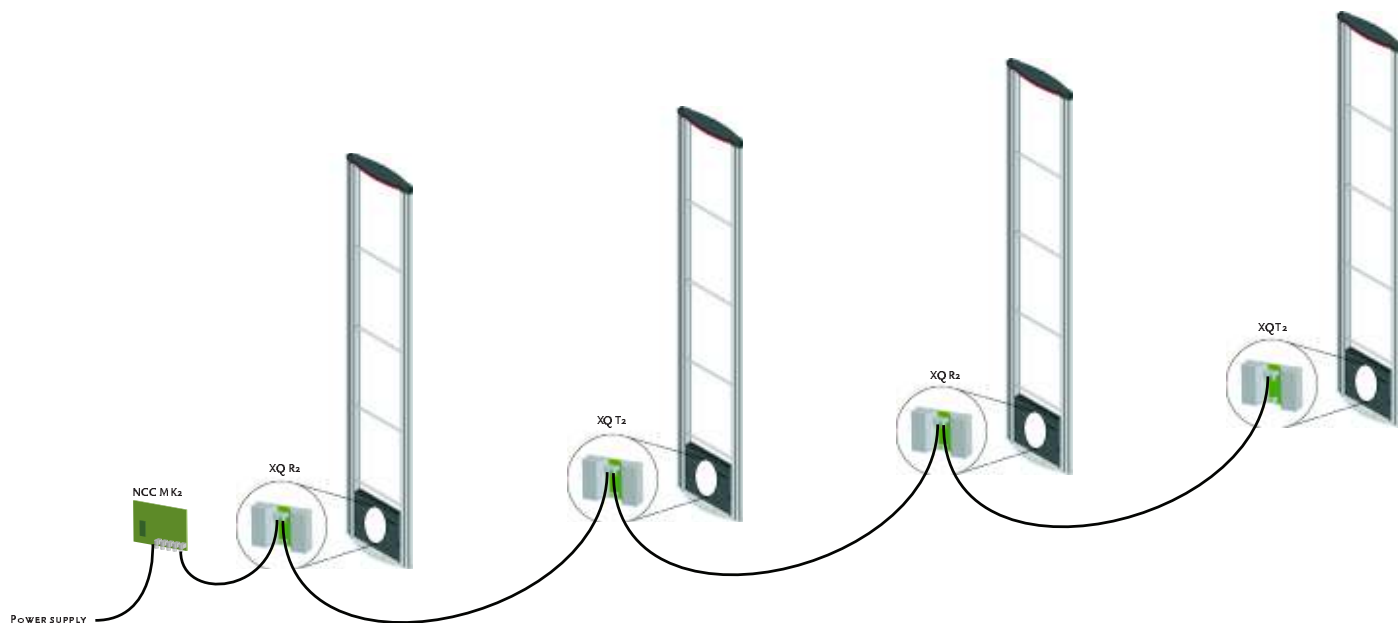
### 3 antennas XQ MK2 configuration

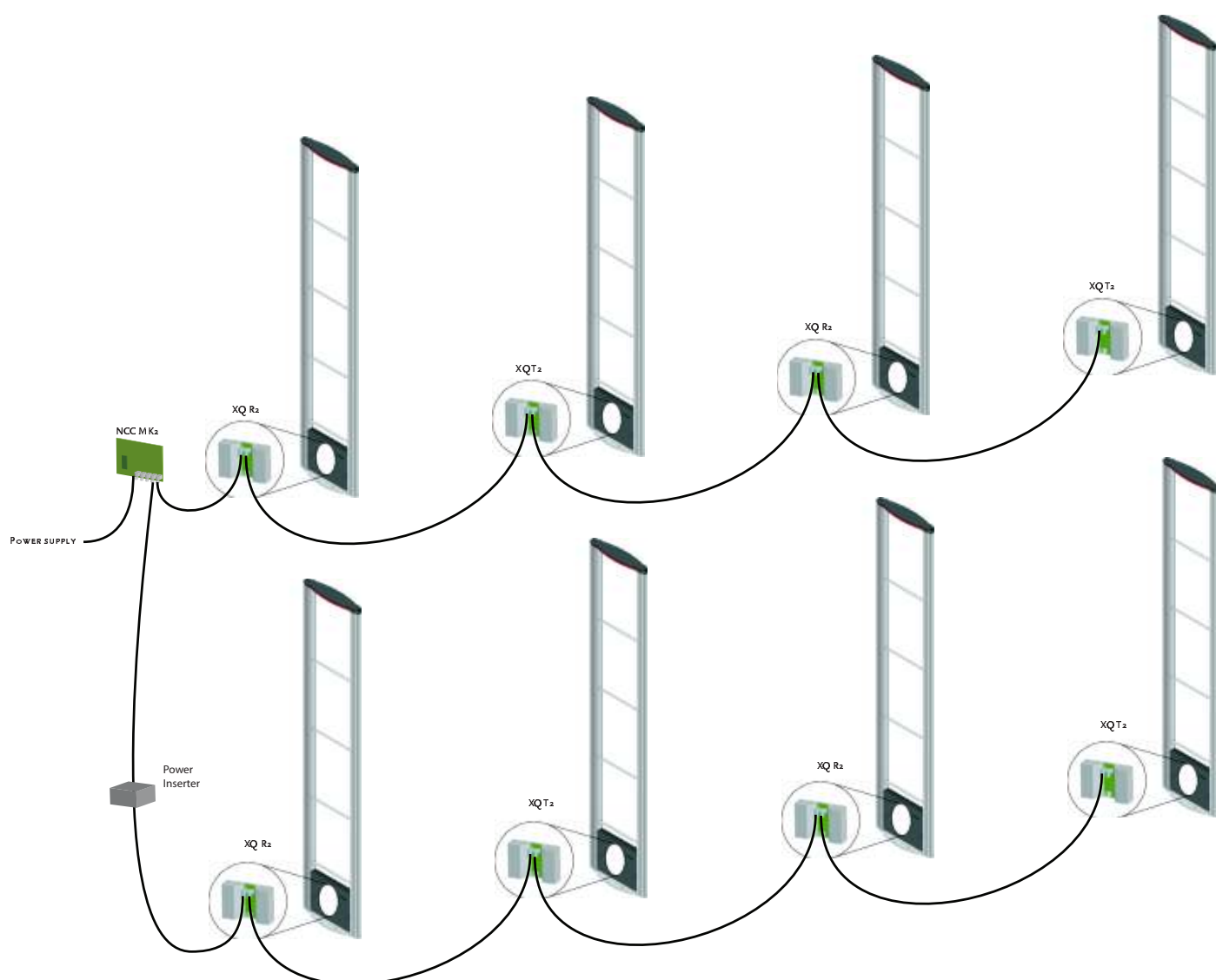
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### 4 antennas XQ MK2 configuration

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## 6 Configuration Manager (CM)

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All real-time data displayed in the configuration manager, is a subset from the real data. The data communication is not showing all data, to limit the load on the data bus.

## 7 Installation instructions

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The NCC shall be installed near a socket outlet. The socket outlet shall be easily accessible, also after installation.

### 7.1 Installation

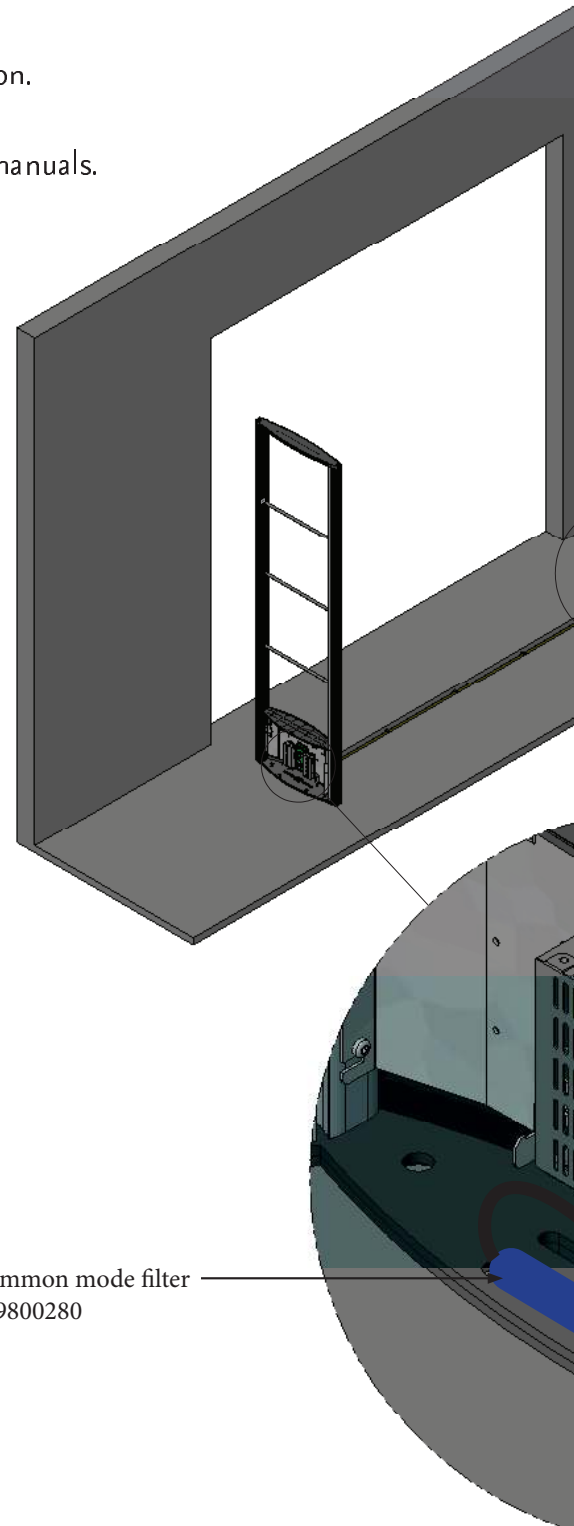
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The power cord shall be prevented from damage and not secured permanently to the building construction. Always use a power outlet with grounding and install according to local regulations ! Installation and service only by qualified personnel.

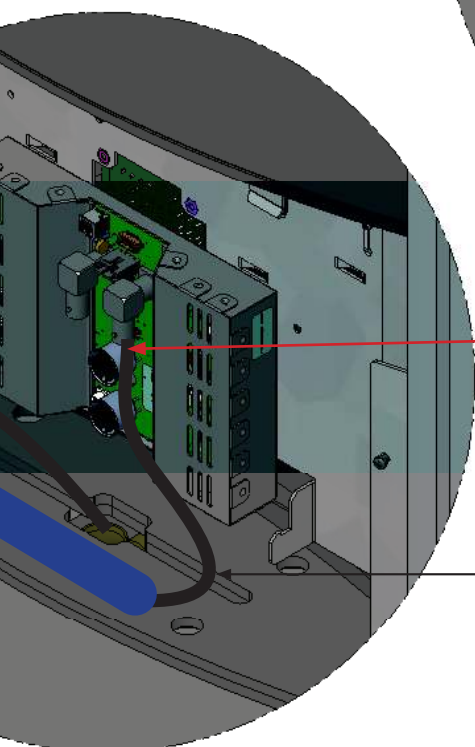
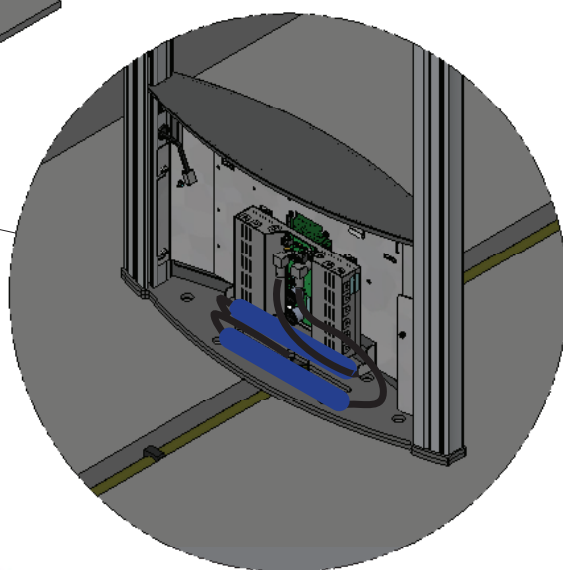
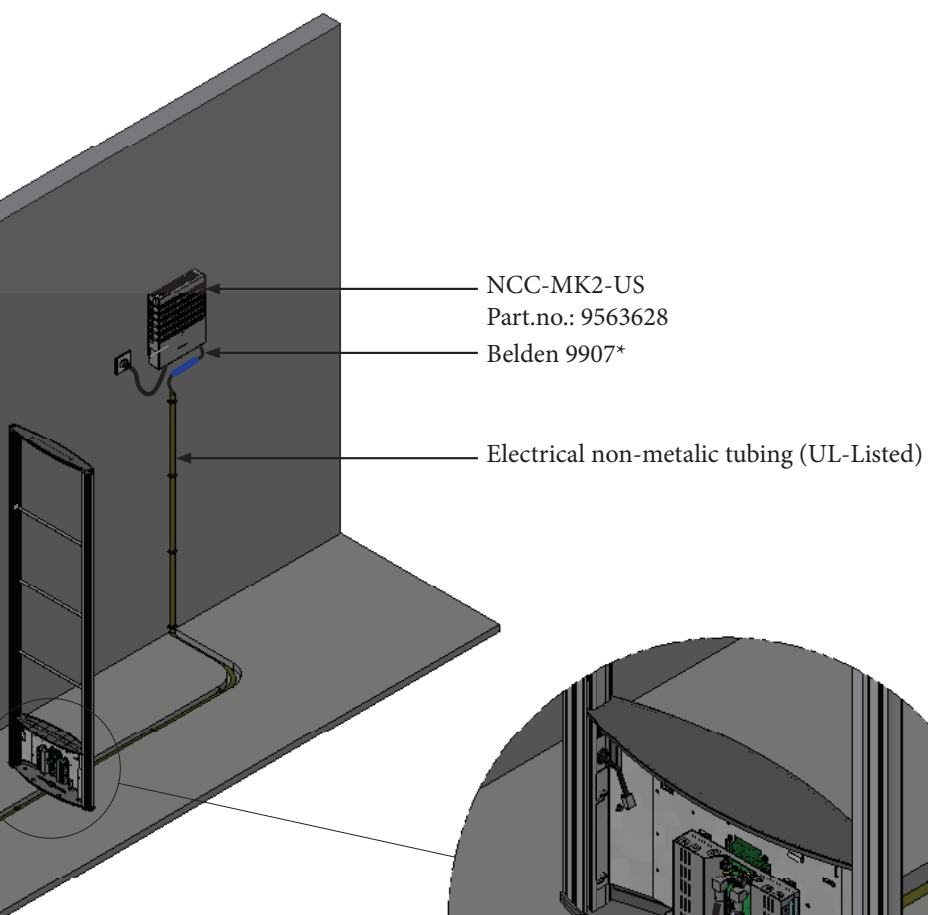
Always turn off the main power when working on the electrical installation.

The guarantee-regulations are only valid when installed as indicated in manuals.

All wiring should be done according to local regulations!



\* Communication cable Belden 9907 (UL-Listed CM rated)  
If routed in plenum spaces use Belden 89907 (UL-Listed CMP rated)



Belden 9907\*

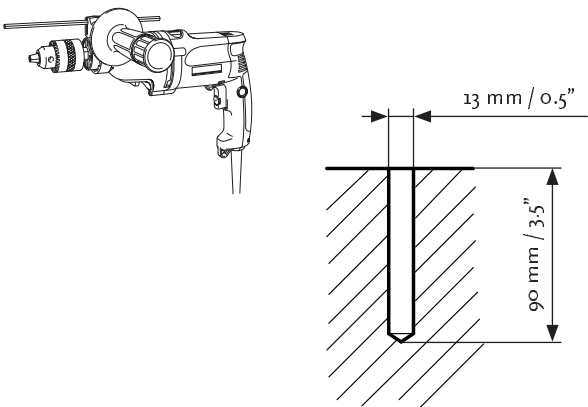


BNC connector Radiall R 141.082.161

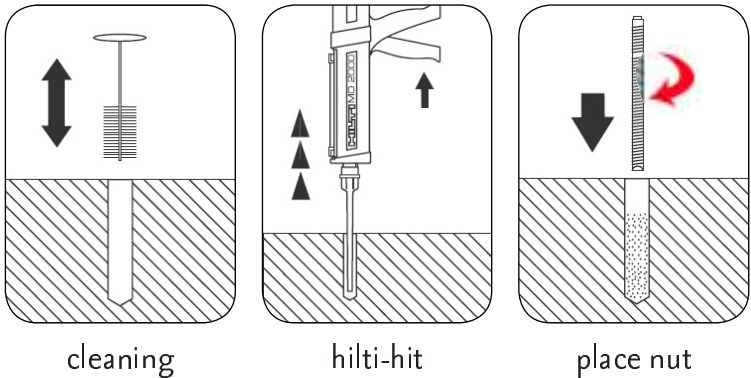


Crimp-tool Radiall R 282-223

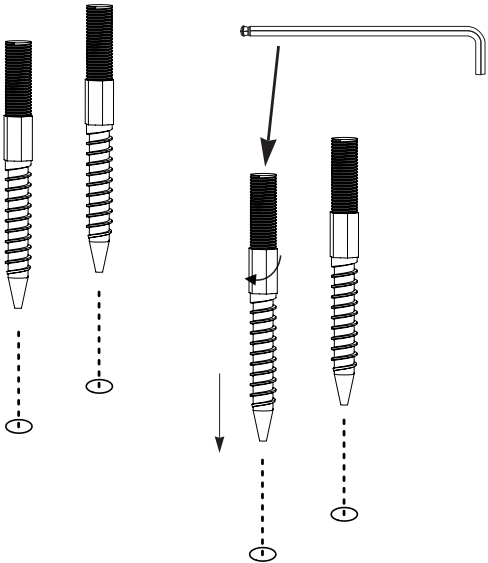
7.2 Drill the holes (4x)



7.3 Use Hilti hit

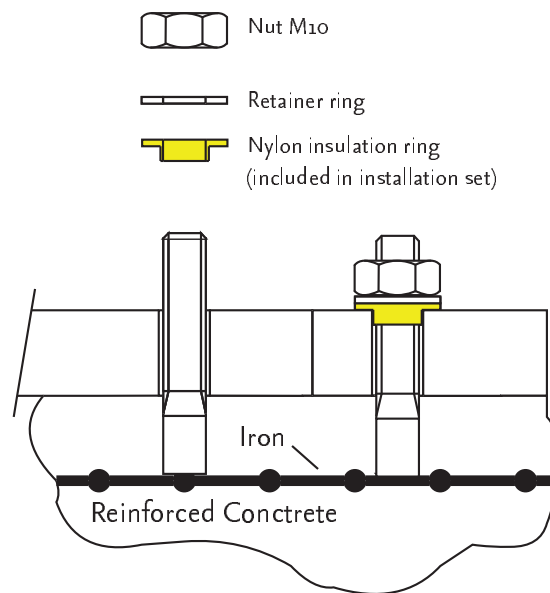
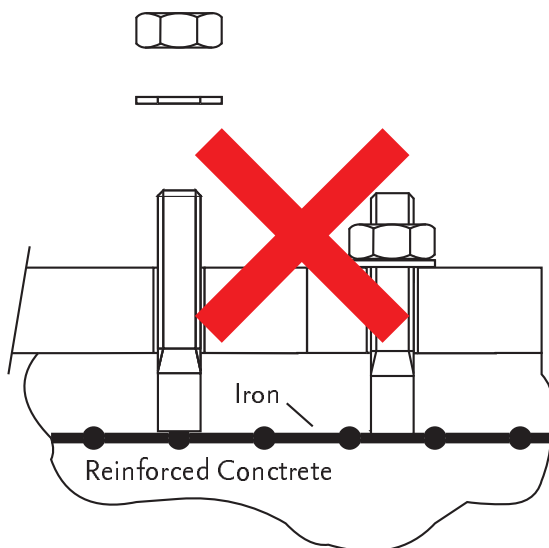
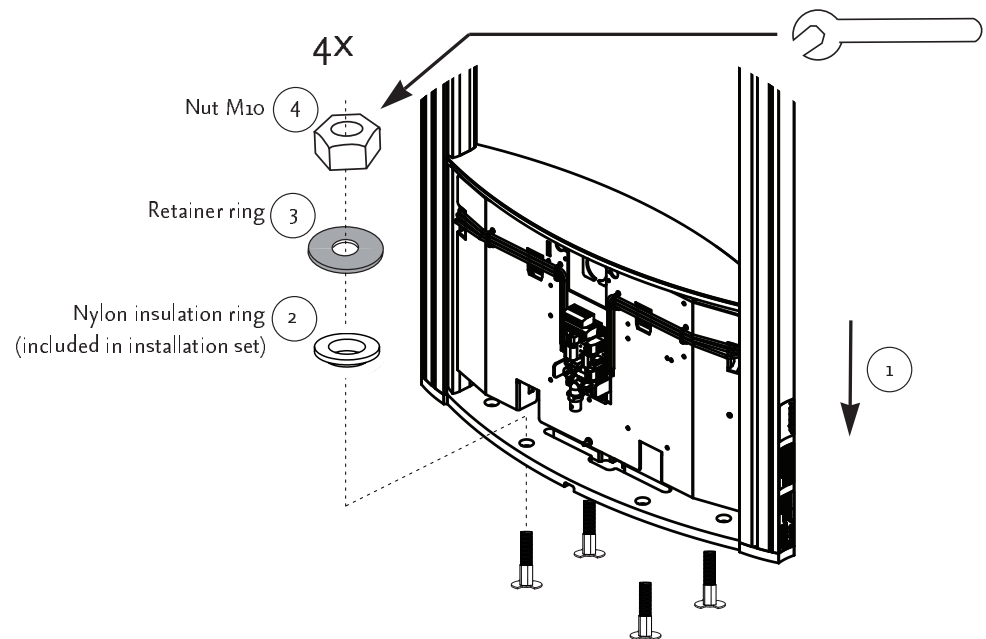


7.4 Place the bolts



## 7.5 Place the antenna

### 7.5.1 Follow step 1 to 4



Always mount an antenna insulated to the floor or wall.

## 8 Metal Detection (MD)

### 8.1 T2 settings

#### 8.1.1 Tx Enable

Enables or disables the metaldetection transmitter. Default is disabled.

#### 8.1.2 Application Version

Firmware version of the metaldetection. This firmware can be remotely updated.

#### 8.1.3 Bootloader version

Firmware version of the bootloader. This firmware can only be programmed in the factory.

#### 8.1.4 Sync Period

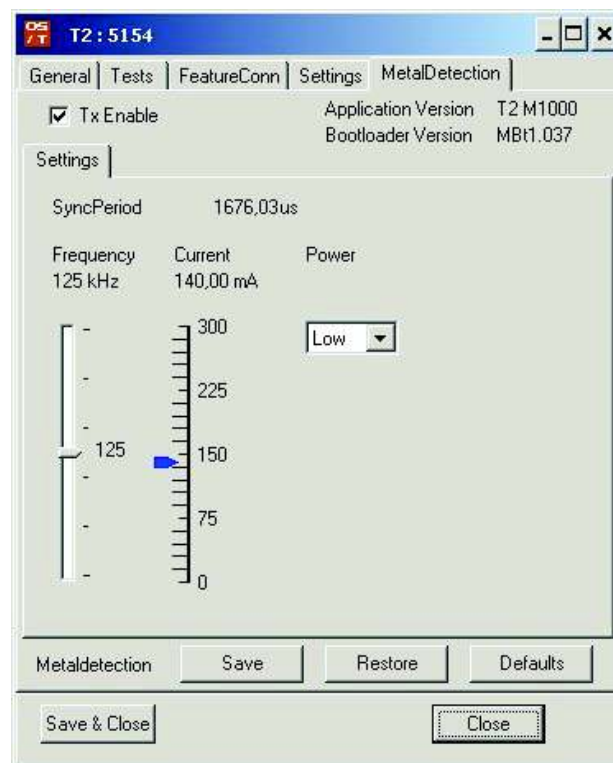
The measured period time of the OST sync pulse (Sweep setting 0 1 2 3).

#### 8.1.5 Frequency

The required metal detection frequency. In the future the range will be limited from 120..130 kHz. Now the range is from 100..150kHz for testing the PLL and filters. In the field only use the range of 120..130kHz. The Frequency is only an indication. The actually generated frequency is calculated from the measured period time of the sync pulse.

#### 8.1.6 Current

An indication of the mean current drawn by the Tx Transmitter stage. The amount of current drawn depends very much on the frequency that is set, the type of antenna in use and the tolerance in the filtering components used. Therefore this is only a very rough indication. The current in the Tx transmitter stage is also limited by hardware.



The output power of the transmitter output stage. Low and high power are available. Step between Low and High is 6dB. The High power setting does not give any advantage in the sense of increased metal detection sensitivity. High Power is only needed at extreme distances between the panels and in Panels where the Antenna PCB is in the center of the antenna like EQ45 and D50. These antenna's give half the field compared with antenna's with their PCB at the end of the eight antenna . Current coming from the center will flow equally in both loops of the eight loop. In an antenna with antenna PCB at the end of the eight loop The High power setting could be used when there is extreme environmental noise. When this is the case it is better to use another frequency setting.

### 8.1.8 Adjusting the transmitter settings

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- Check the Tx Enable box to enable the transmitter
- Adjust the frequency (Default 125kHz will be ok normally)
- Adjust the Power Setting (Default Low is preferred)
- Save the metal detection settings by pushing the Metal detection Save button. In the future this button will be combined with the save & close button

## 8.2 R2 settings

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### 8.2.1 Rx Enable

---

Enables or disables the metaldetection receiver. Default is disabled.

### 8.2.2 Application Version

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Firmware version of the metaldetection. This firmware can be remotely updated.

### 8.2.3 Bootloader version

---

Firmware version of the bootloader. This firmware can only be programmed in the factory.

### 8.2.4 Sync Period

---

The measured period time of the OST sync pulse (Sweep setting 0 1 2 3).

### 8.2.5 Sync Voltage

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This is the measured voltage at the output of the phase-correction integrator. The Phase-correction will adjust the phase error caused by phaseshift through the air (little) and phaseshift caused by the receivers input filter (much and depending on the frequency that is set). The Voltage that is displayed is only an indication and does not always have to be the same with the same frequency setting. In a correct working system it will be stable.

### 8.2.6 Frequency

---

The required metal detection frequency. In the future the range will be limited from 120..130 kHz. Now the range is from 100..150kHz for testing the PLL and filters. In the field only use the range of 120..130kHz. The Frequency is only an indication. The actually generated frequency is calculated from the measured period time of the sync pulse.

### 8.2.7 Gain

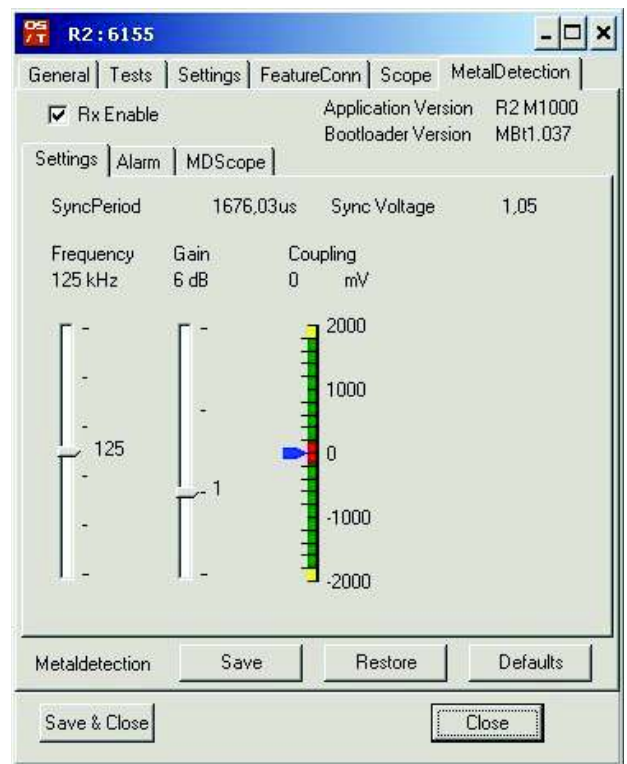
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This is the gain of the preamplifier stage. It wil influence the direct coupling as well as the metaldetection signal equally.

### 8.2.8 Coupling

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The measured direct coupling at the receiver Mixer (Vtop). The direct coupling has to be 200mV minimal. When the coupling is less than 200mV the Phase correction integrator does not function properly. The receiver will be blocked by the software and generate no alarms.



### 8.3 R2 Alarm

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#### 8.3.1 Alarm

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Indicates if there is a metal detection alarm.

#### 8.3.2 Blocked

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Indicates if the receiver is blocked. This happens after a reboot and if the direct coupling runs below 200mV.

#### 8.3.3 Sensitivity

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The Sensitivity together with the Threshold give the Threshold for the Metal detection alarm. The Sensitivity is related to the direct coupling. Large Direct coupling gives us a large metal signal. For alarming the Metal signal has to be a Sensitivity (dB) amount of the direct coupling. By relating to the direct coupling the distance of antenna's and the power setting have no influence on the calculated alarm threshold. (This is not totally correct yet but will be in the near future). Good setting of the sensitivity is about 10..20dB.

#### 8.3.4 Threshold

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This setting determines by what factor the measured Noise is multiplied and the alarm threshold is raised. Noise is caused by Rx and Tx PLL jitter and noise picked up from the environment. Noise is measured continuously and dynamically increases the Alarm threshold. A lot of noise results in a less sensitive system. By decreasing the Noise Threshold the system becomes more sensitive but the probability of false alarm is increased. Good setting for the Noise threshold is 3..9dB.

#### 8.3.5 Noise level

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Indication of the measured noise.

#### 8.3.6 Signal level

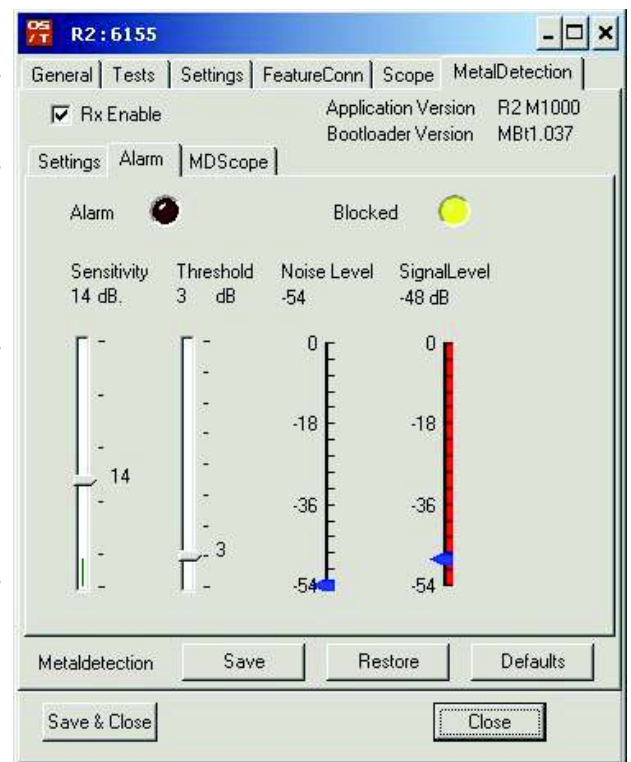
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Indication of the measured Metal signal

#### 8.3.6 Signal level

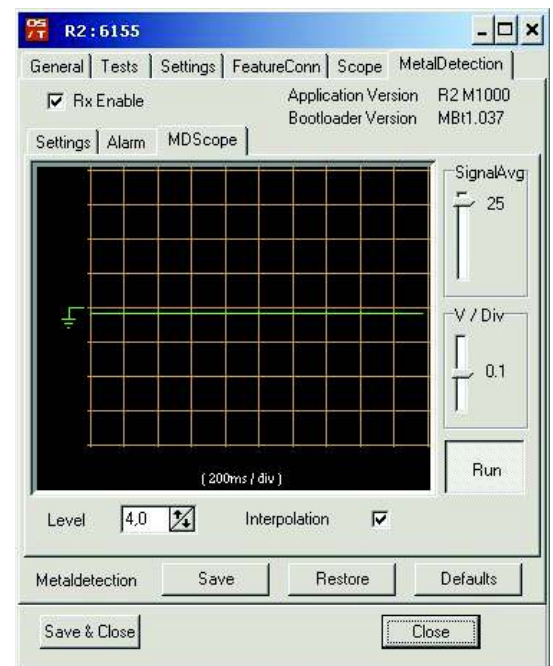
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Check Rx Enable to enable the receiver. Adjust the frequency so that it is the same as the transmitters frequency. Adjust the Gain until the direct coupling indicator is in the green area. Green is ok but preferably about 1000mV. Wait until the receiver is recovered from changing the settings. When it is recovered On the Alarm Tab you will see that the Noise level is Low (about -54dB). Adjust the sensitivity to the required sensitivity. Save the metal detection settings by pushing the Metal detection Save button. In the future this button will be combined with the save & close button.



## 8.4 R2 Scope

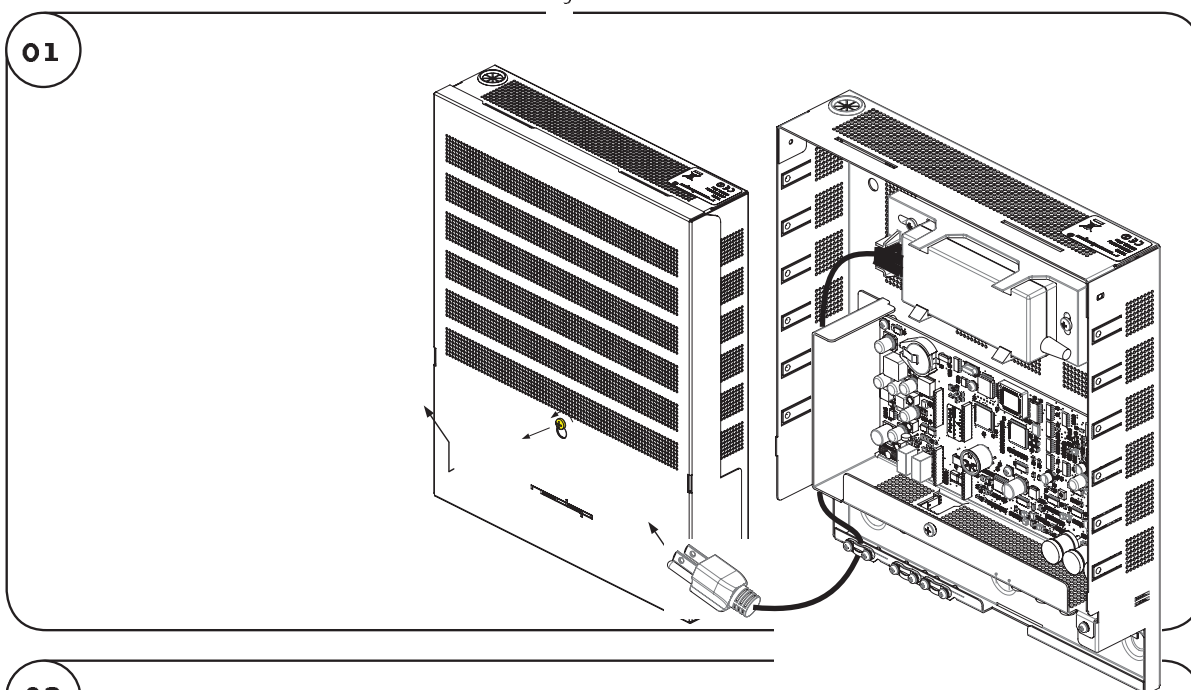
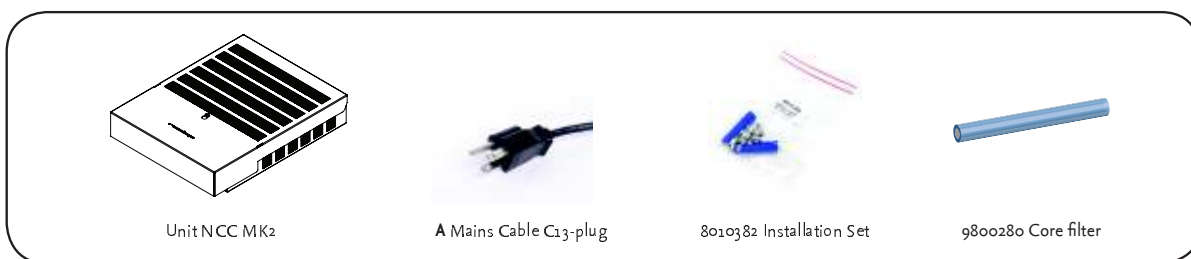
This scope displays the Metal signal that is measured. It gives a good indication of what is happening in the system.



## 8.5 Pager


If a pager is connected to relay 1, use the settings in this screenshot.



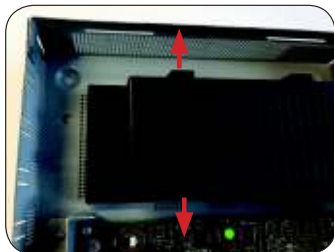


02

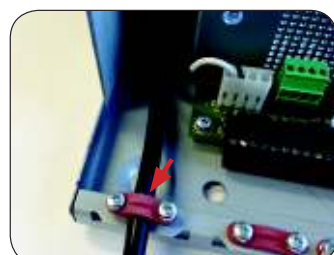
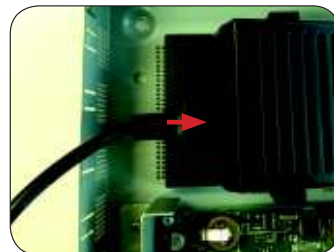
Use the 8010382 Installation Set and 9800280 Core Filter for the connection of a Nedap EAS electronics unit to the NCC MK2.

 <b>nedap</b>   retail	<b>GROENLO</b> THE NETHERLANDS	DRW: CB 2014/01/02
		CHK:
<b>QUICK REFERENCE NCC MK2</b>		DOC. ARTICLE NO: 5275563
		REV. : A.02
Copyright © by N.V. Nederlandsche Apparatenfabriek NEDAP. No part of this drawing may be reproduced or distributed in any form or by any means, or stored in a data base or retrieval system without the prior written permission of NEDAP.		SHEET: 45.01 OF 1
		DRAWING: T5275563


**03** place mains cable

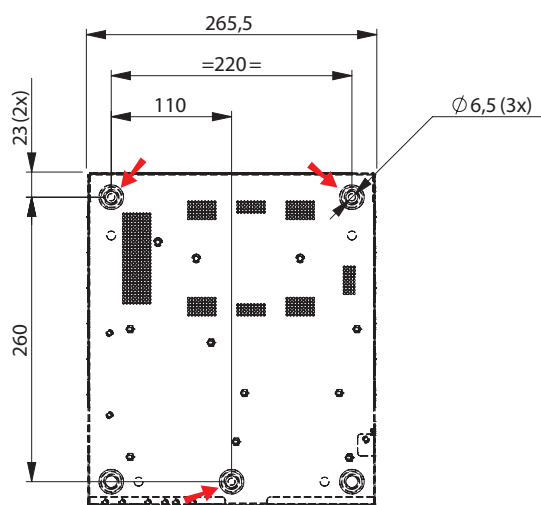


6-18 x 5/8" Philips flat  
head screw

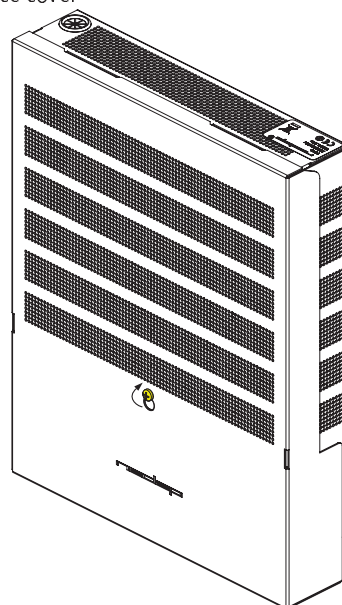


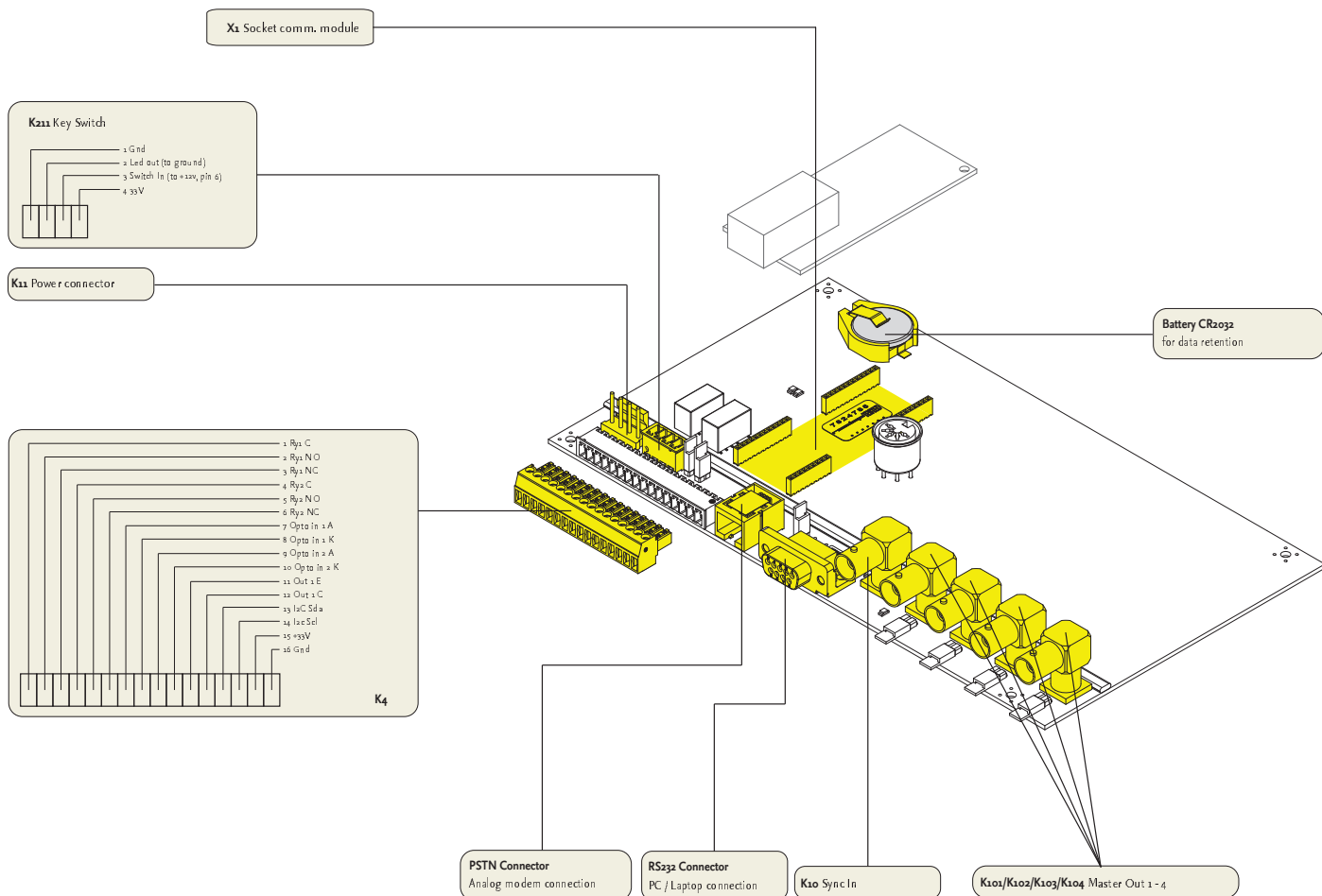
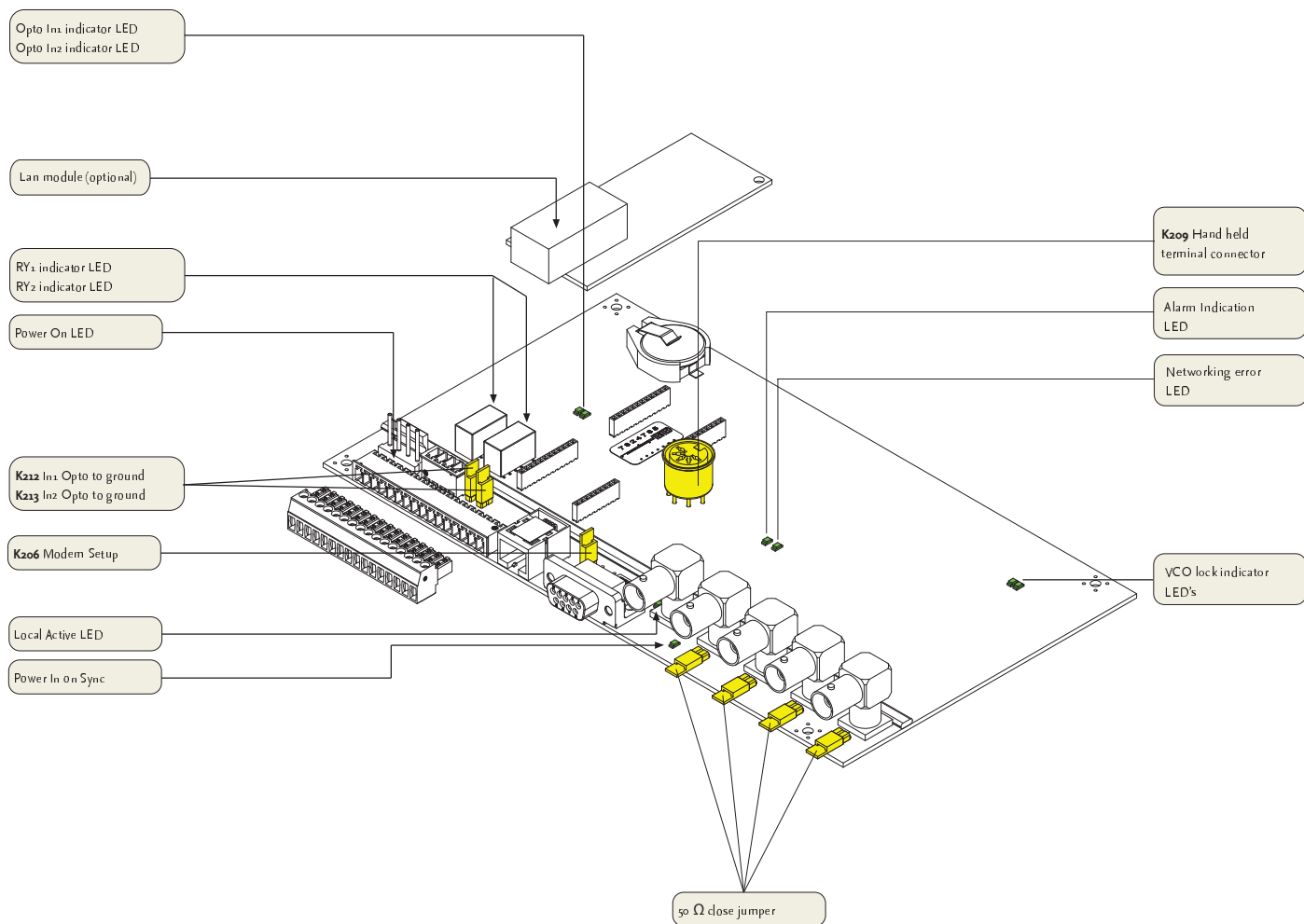
**04** Mount housing to solid surface

 3x (not included)

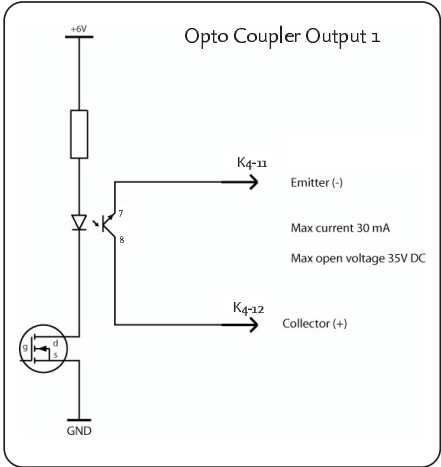
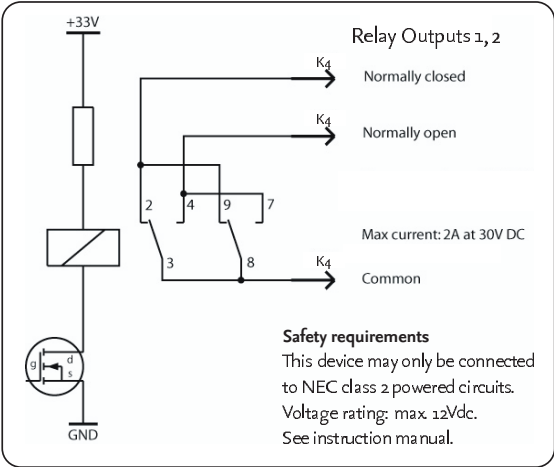
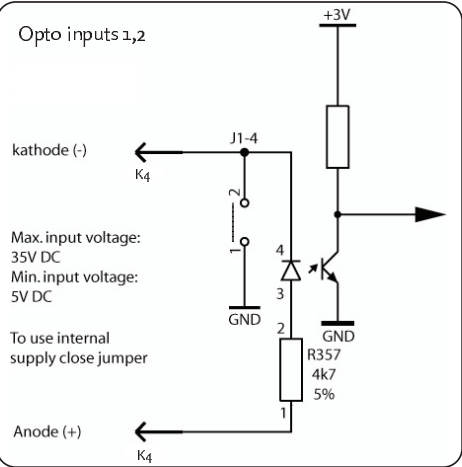


**05** Place cover





NCC MK2 : Inputs / Outputs



Relay contacts:

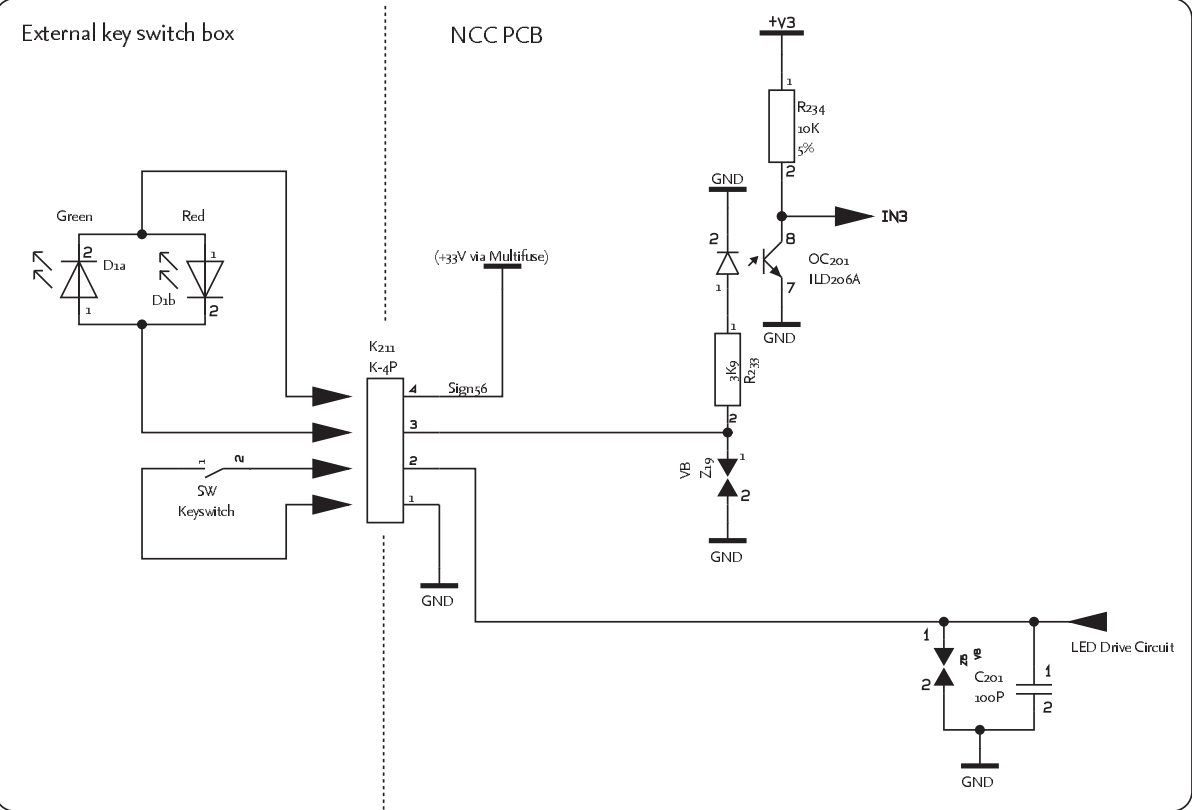
	C	NO	NC
Ry 1	K <sub>4-1</sub>	K <sub>4-2</sub>	K <sub>4-3</sub>
Ry 2	K <sub>4-4</sub>	K <sub>4-5</sub>	K <sub>4-6</sub>

Opto output:

	Collector(+)	Emitter(-)
Opto out 1	K <sub>4-12</sub>	K <sub>4-11</sub>

Opto inputs:

	Anode(+)	Kathode(-)
Input 1	K <sub>4-7</sub>	K <sub>4-8</sub>
Input 2	K <sub>4-9</sub>	K <sub>4-10</sub>



Standard and optional functions

		NCC
Master out		4x
Sync in		Y
Input (opto)		2
Input (opto mute)		1
Output (relay)		2
Output (opto)		1
Data retention		Y
I2C connection		Y
Led status info / key switch option		Y
Buzzer connection		NA
DCM	FM	Y
RSM/NCM	FM	Y

## FCC and IC Declarations

FCC ID: CGDXQMK2UL and IC: CGDXQMK2UL

### Compliance statements (part15.19)

This device complies with part 15 of the FCC Rules and to RSS210 of Industry Canada.

Operation is subject to the following two conditions:

- (1) this device may not cause harmful interference, and
- (2) this device must accept any interference received, including interference that may cause undesired operation.

Cet appareil se conforme aux normes RSS210 exemptés de license du Industry Canada.

L'opération est soumise aux deux conditions suivantes:

- (1) cet appareil ne doit causer aucune interférence, et
- (2) cet appareil doit accepter n'importe quelle interférence, y compris interférence qui peut causer une opération non pas voulu de cet appareil.

### Warning (part15.21)

Changes or modifications not expressly approved by party responsible for compliance could void the user's authority to operate the equipment.

This in particular is applicable for the antenna which can be delivered with the XQMKII System.

### RF Exposure (OET Bulletin 65)

To comply with FCC RF exposure requirements for mobile transmitting devices, this transmitter should only be used or installed at locations where there is at least 20cm separation distance between the antenna and all persons.

### Information to the User (Part 15.106(b))

Note: This equipment has been tested and found to comply with the limits for a class B digital devices, pursuant to part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference in a residential installation. This equipment generates, uses and can radiate radio frequent energy and, if not installed and used in accordance with the instructions, may cause harmful interference to radio communications. However, there is no guarantee that interference will not occur in a particular installation. If this equipment does not cause harmful interference to radio or television reception, which can be determine by turning the equipment off and on , the user is encouraged to try to correct the interference by one or more of the following measures:

- Reorient or relocate the receiving antenna.
- Increase the separation between the equipment and receiver.
- Connect the equipment into an outlet on a circuit different from that to which the receiver is connected.
- Consult the dealer or an experienced radio/TV technician for help.

