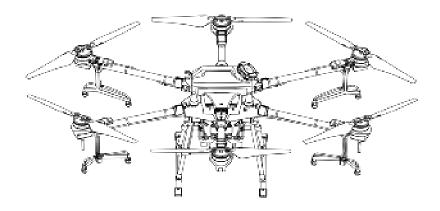
# AGRAS T20

# Quick Start Guide

VI.0







### Aircraft

The AGRAS<sup>M</sup> T20 features a brand-new design including a foldable frame and a quick-release spray tank and flight bettery, making replacement, installation, and storage easy. The stable and miliable modular agrial-electronics system is integrated with a dedicated industrial flight controller, OCUSYNC<sup>56</sup> 2.0 HD transmission system, and RTK module. If has dual IMUs and baremeters and adopts a propulsion control system redundancy design including both digital and analog signals to ensure flight safety.

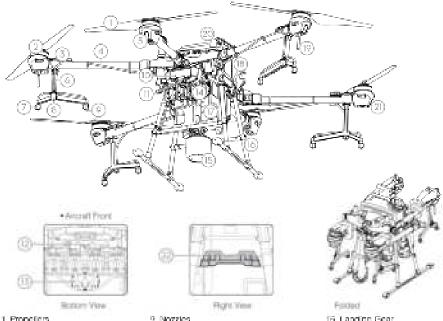
The GNSS+HTK dual-redundancy system is compatible with GPS, GLONASS, BelDou, and Galleo. The T20 also supports centimeter-level positioning" when used with the onboard D-RTK™. Dust-entenne technology provides strong resistance against magnetic interference.

The upgraded spraying system teatures an improvement in paylead, it also has a 4-channel electromagnetic flow meter to ensure consistent spraying for all sprinklers.

The new-generation omnidirectional digital radar provides functions such as terrain following and obstacle sensing and dircumventing in all horizontal directions. The aircraft is equipped with a wide-angle FPV camers that enables users to observe the landscape from the front of the aircraft.

The sircraft has a backup power system, which supplies power to the aircraft for approximately 20 seconds when the Intelligent Flight Battery is powered off due to malfunction during flight. This allows the aircraft to avoid accident and land safety.

Due to its industrial design and material, the T20 is dustproof, waterproof, and conceion-resistant. The aircraft has a protection rating of IPX6 (IEC standard 60529), while the protection rating of the aerial electronics system, spray control system, propulsion ESC system, and radar module is up to IP67.

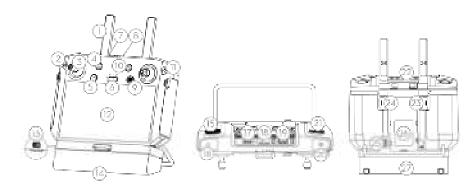


- 1. Propellers
- 2. Motors
- 3. ESCs
- 4. Frame Arms.
- 5. Aircraft Front Indicators (on the three front arms)
- 6. Hoses
- 7. Sprinklers
- 8. Electromagnetic Exhaust. Valves:
- 9. Nozzies
- 10. Aerial-Electronics System.
- 11. FPV Camera
- 12. USB-C Port (on the bottom of the aerial-electronics system, under the waterproof cover)
- 13. 4-Channel Electromagnetic Flow Meter
- 14. Delivery Pumps
- 15. Omnidirectional Digital Radar
- 16. Landing Gear
- 17. Spray Tank
- Battery Compartment.
- 19, OcuSync Antennas
- 20. Onboard D-RTK Antennas.
- 21. Aircraft Status Indicators (on the three rear arms):
- 22. Barnote Controller Holder.

<sup>\*</sup> Must be used with a DJI D-FTK 2 High Precision SNSS Mobile Station (sold separately) or a DJ-approved Network RTK service.

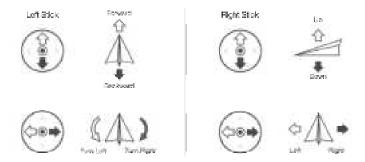
## Remote Controller

The Smart Controller 2.0 uses the DJT<sup>M</sup> OcuSyno 2.0 transmission system, has a maximum control distance of up to 3 km², and supports Wi-Fi and Biurcooth functions. The remote controller is equipped with a 5.5-inch bright, decicated screen that has the DJ Agras app built in, significantly improving amorthness and stability. When the RTK dongle is connected to the remote controller, users can plan operations to continuer-level precision. The Multi-Alreati Control mode of the remote controller can be used to coordinate the operation of up to five storage the same time, enabling pilots to work efficiently. Both the built-in battery and external battery can be used to supply power to the isomete controller. The total working time is up to 4 hours, which fully meets the requirements for long and high-intensity operations.



- 1. Amerinas
- 2. Back Button / Function Button
- 3. Control Sticks
- 4. BTH Button
- 5. Button C3 (oustomizable)
- 6. Flight Mode Switch
- 7. Status LED
- 8. Battery Level LEDs.
- 9.5D Button (oustomizable)
- 10. Power Button
- 11. Confirm Button
- 12. Touch Screen
- 13. US8-C Charging Port 14. Dongle Compartment Cover
- 15. Spray Bate Dial
- 16. Spray Button
- 17. HDMI Port
- 18. microSD Card Slot
- 19. USB-A Port
- 20. RPV / Map Switch Button
- 21. Wark Efficiency Dial
- 22. Air Outlet
- 23. Button C1 (customizable).
- 24. Button C2 (customizable)
- 25. Battery Release Button 26. Bettery Compartment
- 27. Handle

The figure below shows the function that each control stick movement performs, using Mode 1 as an example. In Mode 1, the left stick controls the singraff's forward and backward movements and heading while the right stick controls its attitude and left and right movements.



<sup>\*</sup> The remote controller is able to mach its maximum transmission distance (FCC / NCC; 6 km (8, 11 m); CE / KCC / MC / SRRC; 3 km (1.86 mi) in an open area with no electromagnetic interference, and at an attitude of approximately 2.5 m (8.2 ft).

# Fly Safe

It is important to understand some basic flight guidelines, both for your protection and for the safety of those around you.

- Hying in Open Areas: Pay attention to utility poles, power lines, and other destacles. DO NOT ty near or above water, people, or animals.
- Maintain Control at All Times: Keep your hands on the remote controller and maintain control of your aircraft when it is in flight, even when using intelligent functions such as the Route and A-B Route operation modes and Smart Paturn to Home.
- Maintein Line of Sight: Maintain visual line of sight (VLOS) with your aircraft at all times and avoid flying behind buildings or other obstacles that may block your view.
- Monitor Your Altitude: For the safety of manned aircraft and other air traffic, fly at altitudes lower than 30 m (96 ff) and in accordance with all local laws and regulations.



Visit https://www.di.com/flysale for more information on critical safety features such as GED gones.

#### Flying Considerations

- 1. DO NOT use the alteratioto spray in winds exceeding 18 kph (11 mph).
- DO NOT use the aircraft in adverse weather conditions such as winds exceeding 28 kph (17 mph), heavy rain (precipitation rate exceeding 25 mm (0.96 iri) in 12 hours), snow, or feg.
- The recommended maximum operating altitude is 2 km (6,590 ft) above sea level. DO NOT fly over 3 km (9,842 ft)
  above sea level.
- Once the operating allitude reaches 1 km (3.280 ft), the payload capacity of the spray tank is reduced by 2 kg. For every additional km, the payload capacity will reduce by a further 2 kg.
- 5. Make sure that there is a strong GNSS signal and the D-RTK enterms are unobstructed during operation.

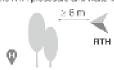
#### Return to Home (RTH)

The sincreft will automatically return to the Home Point in the following situations:

Smart RTH: You press the RTH button.

Falsafe FTH: The remote controller signal is lost.1

If there is an obstacle within 20 m of the aircraft, the aircraft decalerates and then stops and hovers. If the aircraft comes within 6 m of the obstacle while decalerating, the aircraft stops, files backward to a distance of approximately 6 m from the obstacle, and hovers. The aircraft exits the RTH procedure and waits for further commands.



\* If Falkaria BTH is disabled (the default setting in the CJI Agras ago), the aircraft howers in place when the remote controller signal is lost.



 Obstacle availables is disabled in Afflude mode (which the arcraft orders in shurters such as when the GNSS signal is whilst and is not available if the operating environment is not substitute for the radia module. Extra couldon is required in such situations.

## Pesticide Usage

- 1. Avoid the use of powder pesticides as much as possible as they may reduce the service file of the soraving system.
- 2. Pesticides are poisonous and pose serious risks to safety. Only use them in strict accordance with their specifications.
- Use clean water to mix the pesticide and filter the mixed liquid before pouring into the spray tank to avoid blocking the strainer.
- Effective use of postfoldes depends on postfolde density spray rate, spray distance, alreraft speed, wind speed, and wind direction. Consider all factors when using postfoldes.
- 5. DO NOT compromise the safety of people, animals, or the environment during operation.



It is important to understand some basic flight guidelines, both for your protection and for the safety of these around you.

Make sure to read the discleimer and safety guidelines.

# Specifications

20000025-15-10 Product Model

• Airframe

Max Diagonal Wheelbase 1000 mm

Dimensions: 2509×2213×732 mm (Arms and propellers unfolded). 1795×1610×732 mm (Arms unfolded and propellers folded)

1100×570×732 mm (Arms and propellers folded).

\* Propulsion System

Motors

100×15 mm Stator Size KW. 75 rpm/V Max Thrust 13.5 kg/kater 2400 Wileton Max Power Weight  $666\,\mathrm{g}$ 

E90s

Max Working Ourrent

40 A (Continuous)

Max Working Voltage 58.8 V (148 LIPt)

Foldable Propellers (F3390)

 $Dlameter \times Pltch.$ 33×9 in Weight (Single propeller)  $90\,\mathrm{g}$ 

Spraying System

Spray Tenk

Valume Rated: 15.1 L, Ruit 16 L Ratect 15.1 kg, Full: 16 kg Operating Payload

Nozzies Model

XR11001\/S (Standard; XR110015\/S, XR11002\/S (Optional, purchase separately)

Quartity

XR11001VS; 8.6 L/min, XR110016VS; 4.8 L/min, XR11002VS; 6 L/min Max Spray Rate

Spray Width 4 - 7 m (9 nozzles, at a height of 1.5 - 3 m above grops).

XP11001VS: 130 - 250 μm, XP110015VS: 170 - 265 μm, XP(1002VS: 190 - 300 μm. Droplet Size

(Subject to operating environment and spray rate)

Flow Meter

Messurement Frange 0.25 - 20 L/min Error  $< \pm 2\%$ 

Moneuroble Llouid Conductivity > 50 pS/cm (Liquido such as top water or posticidos that contain water)

Omnidirectional Digital Radar

Marie

Operating Frequency CE (Europe) / FOC (America): 24.00 - 24.25 GHz.

MIC (Japan) / KOC (Korsa): 24,05 - 24,25 GHz

 $MIC/KOC/CE/FCC: < 20\,\mathrm{dBm}$ Transmitter Power (ERP)

18.99 Power Consumption:

Afritude Detection & Terrain Afritude detection range: 1 - 30 m. Follow<sup>III</sup> Stabilization working range: 1.5 - 15 m. Max slope in Mountain mode: 35°

Obstacle Avoidance System<sup>(1)</sup> Obstacle sensing range: 1.5 - 30 m.

FOV: Horizontal: 380°, Vertical: ±15°.

Working conditions: Flying higher than 1.5 m over the surface below at a speed lower

then 7 m/s.

Salety distance: 2.5 m (Distance between the front of propellers and the obstacle after

Obstacle avoidance directors Omnidirectional obstacle avoidance in the horizontal direction

IP Feting JP87

FPV Camera

Horizontal: 96°, Vertical: 76° EOV.

Resolution 1280×960 30lps FPV Spotlight FCM 1102, Max brightness: 12 lux at 5 m of direct light

- Flight Parameters

OcuSync 2.0 Operating 2,4000 - 2,4835 GHz Frequency<sup>PL</sup> 5.725 - 5.850 GHz OcuSvije 2.0 Transmitter 2.4 GHz

5.8 GHz

SEBC/ECQ. 25.5 dBm.

Total Weight (Excluding)

21.1 kg battery) Standard Takeoff Weight 44.6 kg

Max Takeoff Weight 45.5 kg (At sea level)

Max Thrust-Weight Ratio 1.78 (Takeoff weight of 45.5 kg)

Hovering Accuracy Range D-RTK enabled: Horizontal:  $\pm 10$  cm, Vertical:  $\pm 10$  cm

(with strong GNSS signal) D-RTK disabled:

Horizontal:  $\pm 0.6$  m, Vertical:  $\pm 0.3$  m (Fladar module enabled:  $\pm 0.1$  m) RTIC GPS L1/L2, GLONASS F1/F2, Bellou B1/B2, Galloo E1/E5<sup>B</sup> RTK / GNSS Operating

GNSS, GRS L1, GLONASS F1, Galleo F1<sup>P</sup> Frequency: Battery DJI-approved flight battery (ABS-18000mAh-61.8V).

Max Power Consumption 8000W

Hovering Power 6000 W (Takeoff weight of 45.5 kg). Consumption.

Hovering Time<sup>31</sup> 16 min (Takeoff weight of 29.5 kg with an 19000 m/th battery).

8.5 min (Takeoff weight of 45.5 kg with an 18000 mAh battery).

Max Tilt Angle Max Operating Speed 7 m/s

Max Rying Speed 10 m/s (With a strong GNSS signal)

Max Wind Fresistance  $8\,m/8$ Max Service Ceiling Above 2000 m

Sea Level

Recommended Operating

0° to 40° C (32° to 104° F) Temperature:

Homte Controller

Moder PIMEOUNAG

5.5-inch screen , 1920  $\!\times\!$  1090, 1000 act/m², Android system. Screen

**BAM** 4 GB LPDDR4 BOM: 32 GB + scalable storage; microSD carda supported.

Max Capacity: 128 GB, UHS4 Speed Grade 3 rating required.

Built-in Battery 19650 Lilion (5000 mAh © 7.2 V).

GNSS. GPS+GLONASS

Power Consumption 19.99

Operating Temperature  $-10^{\circ}$  to  $40^{\circ}$  C (14° to  $104^{\circ}$  F) 5° to 40° C (40° to 104° F). Charging Temperature -30° to 25° C (-22° to 77° F) Storage Temperature

Oou8yne 2.0

Operating Frequency<sup>(3)</sup> 2,4000 - 2,4836 GHz 5.725 - 5.850 GHz

Max Transmission Distance - SERC / MIC/ KCC / CE 3 km, ECC: 5 km (Unobstructed, free of interference)

Transmitter Power (EIRP) 2.4 GHz

8FRC / GE / MIC / KOQ, 18.5 dBm, FQQ, 25.5 dBm.

5.8 GHz.

8FBC/FCC: 25.5 dBm

WHE

Protocol Wi-Fi Display, 902.11a/g/m/ac

Wi-Fi with 2×2 MIMO is supported

Operating Frequency<sup>(4)</sup>

2,4000 - 2,4835 GHz 5,150 - 5,250 GHz 5,725 - 6,850 GHz

Transmitter Power (EIRP) 2.4 GHz

SERC / CE: 18.5 dBm, FCC / MIC / KCC; 20.5 dBm.

5.2 GHz.

SEBC / ECC / CE / MIC: 14 dBm, KCC: 10 dBm.

5.8 GHz

SERC / FCC: 18 dSm, CE / KCC: 12 dBm

Bluetooth

Protocal Bluelcoth 42 Operating Frequency 2,4000 - 2,4835 GHz

Transmitter Power (EIRP) 8FBC / FCC / CE / MIC / KCC: 6.5 dBm

\* Remote Controller Intelligent Battery

Model W837-4820mAh-7.8V

 Battery Type
 25 LiPo

 Capacity
 4820 mAh

 Voltage
 7.6 V

 Energy
 57.88 Wh

Charging Temperature  $6^{\circ}$  to  $40^{\circ}$  G  $(40^{\circ}$  to  $104^{\circ}$  F)

\* Intelligent Battery Charging Hub

World WCH2
Input Voltage 17.8 - 26.2 V
Output Voltage and Current 8.7 V, 6 A

AC Power Adapter

Model A14-057N1A Input Voltage 100 - 240 V, 50/60 Hz

Output Vallage 17.4 V Rated Power 57 W

- [1] The effective radar range varies depending on the material, position, shape, and other properties of the obstacle.
- [2] Local regulations in some countries prohibit the use of the 5.8 GHz and 5.2 GHz frequencies. In some countries, the 5.2 GHz frequency band is only allowed for indoor use.
- [3] Support for Galleo will be available at a later date.
- [4] Hovering time acquired at sea level with wind speeds lower than 3 m/s.

Download the Agras T29 User Manual for more information: http://www.djl.com/20

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Petroln One.

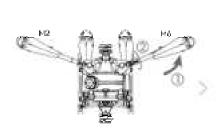
# Using the T20

# 1. Preparing the Intelligent Flight Battery

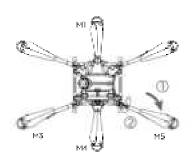
Only use official Bull flight batteries (model: AB3-18000mAh-51.ffV). Check the battery level before flying, and charge it according to the corresponding document.



# 2. Preparing the Aircraft



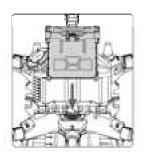
Unfold the M2 and M8 arms, and tighten the two arm sleeves.



Unfold the M3 and M5 arms followed by M1 and M4, and then tighten the four arm sleeves.



Unfold the propeller blades.



Insert the Intelligent Flight Battery into the aircraft umi i you haar a click.

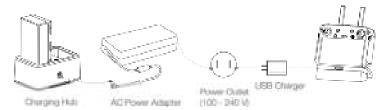


- -Before using the already, make sure to mount the backup before. Otherwise, the amount cannot take off. Mount and use the trackup before in other accordance with the Agree TSG Blockup Before User Guide.
  - -Make sure that the battery is firmly inserted into the alterat. Only insert or remove the battery when the alterat is powered off.
  - To remove the battery, press and hold the clamp, and then lift the battery up.
  - When loking the arms, make sure to feld the W8 and W5 arms first, and firen the M5 and M6 arms. Otherwise, the arms may be damaged. Lift and lower the M1 and M4 arms gently to reclude wear and test:

# 3. Preparing the Remote Controller

#### Charging the Batteries

Charge the external Intelligent Battery using the charging hub and AC power adapter. Charge the internal battery of the remote controller using the USS charger and USS C sable. Fully charge the batteries before using for the first time.



#### Mounting the External Battery

- Proce and hold the battery release button.
- The Interest the Intelligent Bottery into the battery compartment. Make sure the bottom of the battery is aligned to the marking line in the compartment.
- Push the bettery to the bottom.





\*To remove the Intelligent Eletery, press and hold the battery researce button, their push the battery upward.

#### Mounting the 4G Dongle and SIM Card



- Only use a DJ-approved dongle. The congre supports various network standards. Use a DM-card that is competitive with the chosen mobile network provider, and select a mobile data plan according to the plannest level of usuage.
- The dongle and SIM dard enable the remote controller to access specific networks and platforms, such as the DJ 7/3 distribute. Make sure to employ them correctly. Otherwise, network access will not be available.



Plemove the dongle compartment cover.



Insert the dongle into the USB port with the SIM card inserted into the dongle, and test the dongle."



Fleataich the cover firmly.

\*Text procedure: Press the remote controller power button since, then press again and hold to power the remote controller on. In DJI Agrae, tap (6), and select histwork Diagnostics. The dongle and SMI card are functioning properly if the status of all the devices in the retwork chain are shown in green.

## Mounting the RTK Dongle

When using the RTK planning method to plan the operation area, attach the RTK doople to the USB-A port on the remote controller.



#### Checking the Battery Levels



Press the power button on the remote controller once to check the internal battery level. Press once, then press again and hold for two seconds to power on or off.

Press the battery level button on the external intelligent Battery once to check the battery level.



When using an external limitigent Battery, it is all recoverably to make sure that the internal battery has some cover. Otherwise, the remain controller control to provered on.

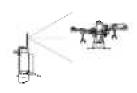
#### Adjusting the Antennas

Lift the antennes and adjust them. The strength of the remote controller signal is affected by the position of the antennes. When the angle between the antennes and the back of the remote controller is 80° or 180°, the connection between the remote controller and aircraft can resch its optimal performance.



Try to keep the alteraft inside the optimal transmission zone. If the signal is weak, adjust the antennas or fly the aircraft closer.

Optimal Transmission Zone





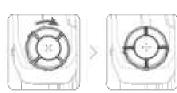




- Avoid using wheless stavious that use the same frequency bands as the remote controller
- If the RTK dangle is used for field planning, the impoles alread be disconnected from the remate controller after planning is completed. Otherwise, it will affect the communication performance of the remate controller.

## 4. Getting Ready for Takeoff

- A. Place the aircraft on open, flat ground with the aircraft rear facing toward you.
- B. Make sure that the propellers are securely mounted, there are no foreign objects in or on the motors and propellers, the propeller blades and arms are unfolded, and the arm sleaves are firmly fightened.
- Make sure that the spray tank and flight battery are firmly in place.
- Pour liquid into the spray tank, and tighten the cover. Make sure that the loar lines on the cover are aligned to the horizonal or vertical election.
- E. Power on the remate controller, make sure that the DUI Agras app is open, and then power on the skroleft.





 When using for the first time, activate the alread using the D.B. Agree app. Your D.B. account and an internet connection are required.

#### Calibrating the Compass

When the app prompts that compass collection is required, tap **o**, then **(**), side to the bottom, and select Advanced Settings, then Sensors. Tap Calibration in the compass calibration section, then follow the on screen instructions.



•CO NOT calibrate your compate where there is a chance of strong regretic Marketone. The industrial areas where there are callby coles or walls with shed reinforcements.

DO NOT carry ferromagnetic materials with you during calibration such as keys or mobile phones.

#### Calibrating the Flow Meter

Make sure to calibrate the flow mater before your first operation. Otherwise, the spraying performance may be adversely affected.

A. Preparation before calibration: Discharging the butbles in the hoses

- (i) Fill the spring tank with approximately 2 L of woter.
- ① Use the automatic bubbles discharge function to discharge the bubbles according to the descriptions in the Discharging the Bubbles in the Hoses section below. Users can also manually discharge the bubbles. Pressthe spray button to spray the bubbles and press the button again once all bubbles are discharged.

#### B. Row Mater Calibration

- ① Calibration starts automatically. After 25 accords, the result of the calibration is displayed in the app.
  -After calibrating successfully, users can proceed with the operation.
  -If calibration fails, top "7" to view and resolve the problem. Afterward, recalibrate.

#### Discharging the Bubbles in the Hoses

The T20 features an automatic bubbles discharge function. When it is necessary to discharge bubbles, press and hold the spray button for two seconds. The aircraft will discharge automatically until the bubbles are fully discharged.

## 5. Flight

In the app, go to Operation View. Make sure that there is a strong GNSS signal, and the system status bar indicates Manual Route (SNSS) or Manual Route (SNSS) o

It is recommended to create a plan for a field and select an operation to enable the aircraft to take off and perform the operation automatically. Refer to the Starting Operations section for more information, in other cases, take off and lend manually.

## Takeoff

Perform a Combination Stick Command (CSC) and push the throttle stick up to take off.



## Landing

To land, pull down on the throttle stick to discend until the straight touches the ground. There are two methods to stop the motors.

Method 1: When the sircraft has landed, push and hold the throttle stick down. The motors will stop after three

Wathod 2: When the alcorat has landed, push the throttle stick down, and perform the same CSC that was used to start the motors. Release both sticks case the motors have stopped.

 RTK positioning is recommended. In the app, go to Operation View, top 3; then RTK to enable Arcraft RTK, and assets a method for receiving RTK argodic.







- ↑ \*Spiriting properties can be dangerous. Blay away from spiriting properties and motors. DO NOT start the motors in confined spaces or when there are people nearby.
  - Keep your hands on the remote controller when the motors are spinning.
  - -DO NOT stop the maters mid-flight unless in an emergency situation where doing so will reduce the risk of damage. calinjury.
  - Method 1 is the recommended method for stopping the motors. When using Method 2 to stop the motors, the aircraft may roll over if it is not completely grounded. Use Method 2 with caution.
  - After landing, power off the aircraft before turning off the remote controller.

#### Starting Operations

After the operation area and obstacles have been measured and settings have been configured, DJI Agras uses a built-in intelligent operation planning system to produce a flight route based on the user's input. Users can invoke an operation after planning a field. The aircraft will begin the operation automatically and follow the planned flight route.

In scenarios with complicated tensin, users can use the PHANTOM $^{\rm M}$ 4 BTK and DJI TERRA $^{\rm M}$  to plan 3D fight routes. and then import the routes to the DJI Agras apprior operation. Refer to the Agras T20 User Manual for more information.

#### Field Planning

The DJI Agras app supports flight route planning by flying the aircraft to waypoints, obstacles, and calibration. points or by welking to these points carrying a remote controller, a remote controller with an RTK dongle, or an RTK device. The following route has been planned by walking to the points with a remote controller that has a RTK dongle connected. Before planning, make sure that the RTK dongle is mounted to the remote controller.







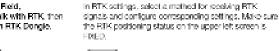




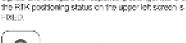


Power on the remote: controller, Launch Dul-Agras.

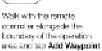
Too Plon Field. select Walk with RTK, then Walk with RTK Dongle.











C2 at turning points.



Walk to each obstacle? in turn and tap **Obstacle** Mode C1.\*











Tap Complete.





Save the

The waypoints and flight route can be edited. Fine-tune waypoint positions, configure distance and line specing, and adjust the route direction by tapping or dragging the & loon.

"If any obstacles are in the

Once you have trisined planning, top: A in the appeniet somer of the screen to return to the forme screen.

operation area.



 Biplanning without an RTK device or remote controller with an RTK dengle, calibration points should be added. before planning is complete so that the offset our be recified when its owns the operation

#### Performing an Operation











Titi Execute Operation in the harne screen of the apg.



Tep (i), select the field from

op add to eat the waypoints and fight rocks again.











Tap Invoke, and then tep Start.

Set the operation parameters. then confirm.

Set the auto-takeoff helpft and move the sider to take off. The aircraft will perform the operation automatically.



- A starting without an HTK device or remete controller with an HTK durigle. It is recovery to rectly the offset after swoking the operation. Take the skoralt to one of the calibration points, and then has Restly Others.
  - Only take off in open areas and set an appropriate auto-takeoff height according to the operating environment.
  - An operation can be paused by moving the control stick alightly. The already will have rand record the breakpoint. and then the aircraft can be controlled manually. To continue the operation, select, it again from the Executing tag in (ii) list, and the snorth will return to the breakpoint automatically and resume the operation. Pay attention to aroust salety when returning to a breakpoint.
  - In Route Operation mode, the stroratt is able to stroumwent obstacles, which is disabled by default and can be onabled in the app. If the function is enabled and the aircraft detects obstacles, the aircraft will slow down and circumvent the obstacles, and then return to the original flight path.
  - ·Users can set the action the aircreft will perform after the operation is completed in the app.

#### More Operation Modes

Perfor to the Agras T20 User Manual for more information about the A-B Poute, Manual, and Manual Plus Operation modes.

#### More Functions







System Data Protection

Empty Tank

Refer to the Agras T20 User Manual for more information.

# Maintenance

Gean all parts of the aircraft and remote controller daily and immediately after spraying:

- Fill the spray tank with clean water or scapy water and spray the water through the nozzles until the tank is empty. Repeat the step two more times.
- Detach the series tank and spray tank connector to clean them. Remove the spray tank strainer, recalle strainers. and nozzles to clean them and clear any blockage. Alterwards, immerse them in clean water for 12 hours.
- 3. Use a water-filled agray washer to clean the aircraft body and wipe it with a soft brush or wet cloth before cleaning. water stains with a dry cloth.
- 4. If there is dust or pesticide liquid on the motors and propellers, wipe them with a wet doth before cleaning water stains with a dry cloth.
- 6. Wipe the surface and sersen of the remote controller with a clean wat cloth that has been wrung out with water daily after operations.

The backup bettery is valid for one year after shipping and can only be used once. Once the backup battery is used or has expired, make sure to contact a BJI authorized dealer to purchase a new battery. Pay attention to the backup battery status notifications in the Bull Agres app.

Refer to the disclaimer and safety guidelines for more information on product maintenance.

# **AGRAS T20**



Featuach

For the senial intervalsion on Agrica products, scan the Exception of Touristics Officials.



#### FCC Compliance Notice(For plane)

This device complies with part 15 of the FCC Rules. Operation is subject to the following two conditions: (1) This device may not cause harmful interference, and (2) this device must accept any interference received, including interference that may cause undesired operation.

Any changes or modifications not expressly approved by the party responsible for compliance could void the user's authority to operate the equipment.

This equipment has been tested and found to comply with the limits for a Class digital device, pursuant to part of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference in a residential installation. This equipment generates uses and can radiate radio frequency energy and, if not installed and used in accordance with the instructions, may cause harmful interference to radio communications. However, there is no guarantee that interference will not occur in a particular installation. If this equipment does cause harmful interference to radio or television reception, which can be determined by turning the equipment off and on, the user is encouraged to try to correct the interference by one or more of the following measures:

- Reorient or relocate the receiving antenna.
- Increase the separation between the equipment and receiver.
- Connect the equipment into an outlet on a circuit different from that to which the receiver is connected.
- Consult the dealer or an experienced radio/TV technician for help.d.

#### **FCC Radiation Exposure Statement**

This equipment complies with FCC radiation exposure limits set forth for an uncontrolled environment .

This transmitter must not be co-located or operating in conjunction with any other antenna or transmitter.

This equipment should be installed and operated with minimum distance 20cm between the radiator & your body.

### IC RSS warning

This device complies with Industry Canada licence-exempt RSS standard (s). Operation is subject to the following two conditions: (1) this device may not cause interference, and (2) this device must accept any interference, including interference that may cause undesired operation of the device. Le présent appareil est conforme aux CNR d'Industrie Canada applicables aux appareils radio exempts de licence.

L'exploitation est autorisée aux deux conditions suivantes:

- (1) l'appareil ne doit pas produire de brouillage, et
- (2) l'utilisateur de l'appareil doit accepter tout brouillage radioélectrique subi, même si le brouillage est susceptible d'en compromettre le fonctionnement.

#### IC Radiation Exposure Statement:

This equipment complies with IC RF radiation exposure limits set forth for an uncontrolled environment. This transmitter must not be co-located or operating in conjunction with any other antenna or transmitter.

This equipment should be installed and operated with minimum distance 20cm between the radiator& vour body.

Cet équipement est conforme aux limites d'exposition aux rayonnements RF IC définies pour un environnement non contrôlé. Cet émetteur ne doit pas être colocalisé ou fonctionner en conjonction avec une autre antenne ou un autre émetteur.

Cet équipement doit être installé et utilisé avec une distance minimale de 20 cm entre le radiateur et votre corps.