

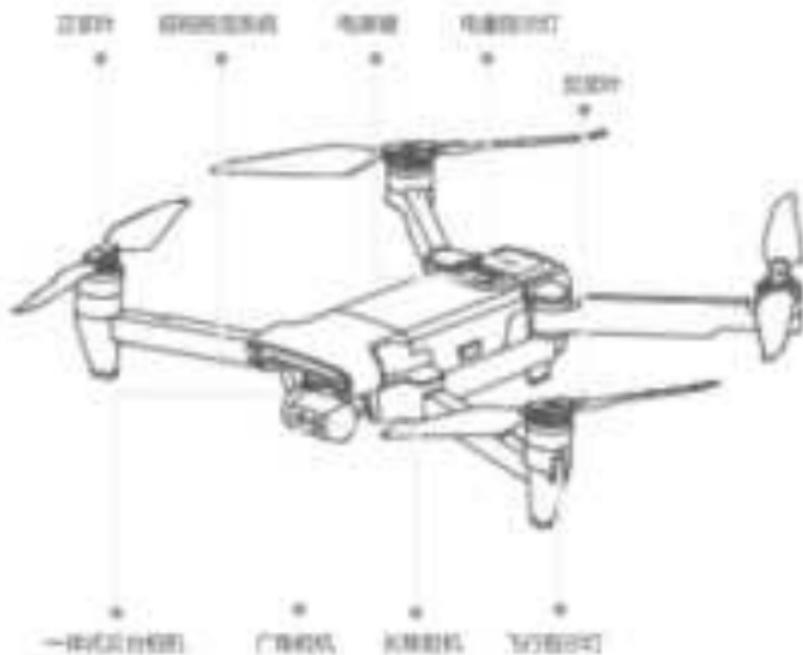


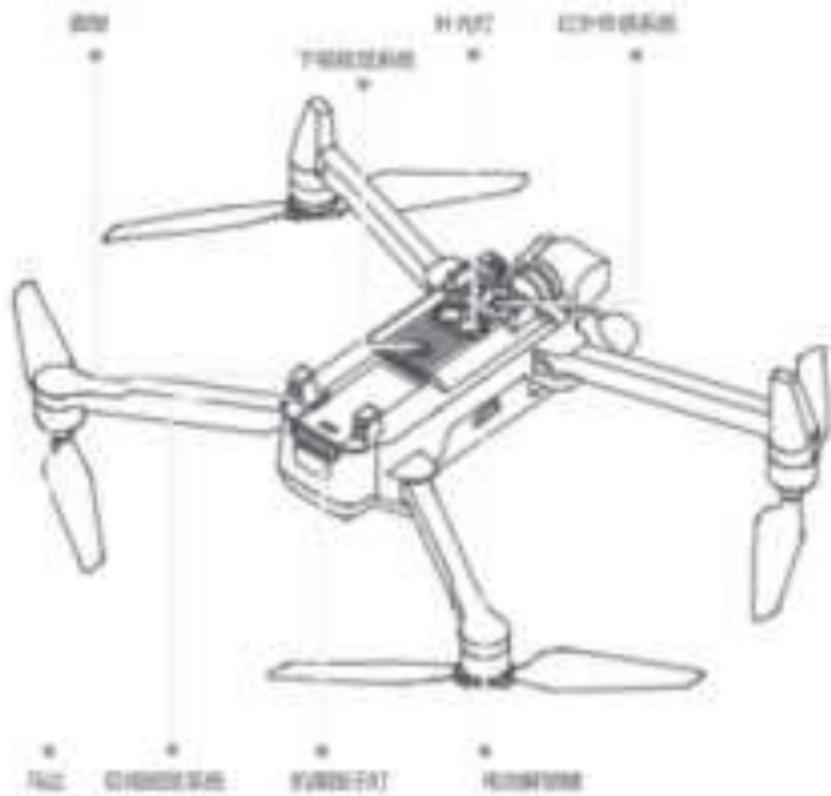
飞米 FIMI X8 Tele 系列飞行器快速入门指南  
请阅读产品随附的快速启动手册并妥善保管

FIMI X8 Tele Series Drone Quick Start Manual  
Please read the quick start manual carefully before using and keep it for future reference.

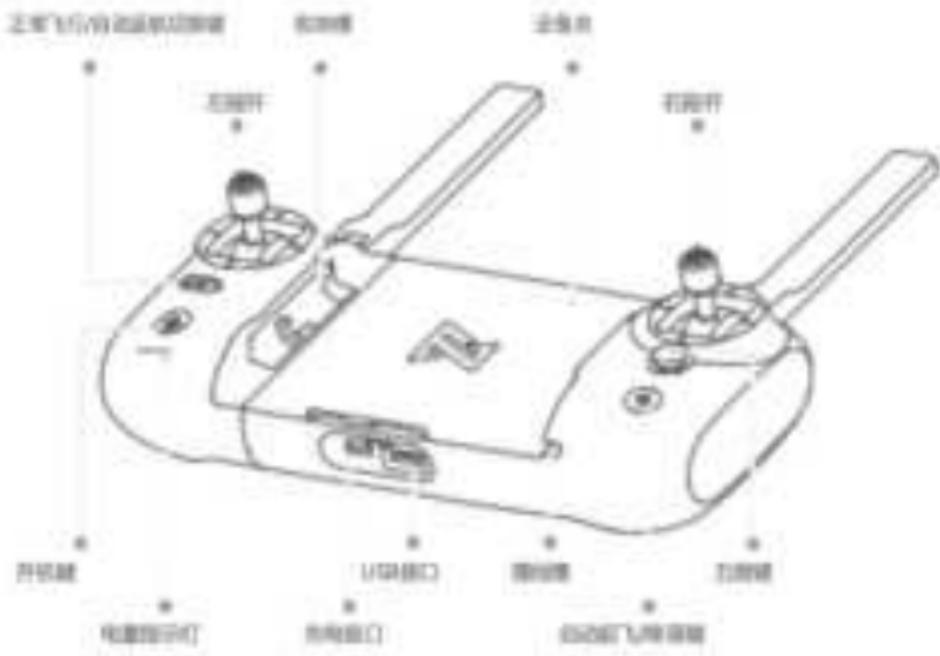
## 产品介绍

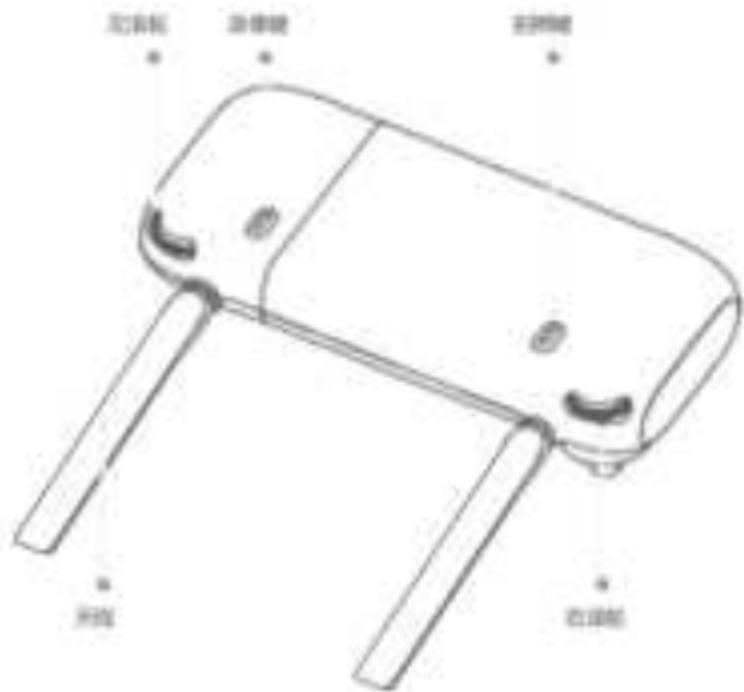
### 1 飞行器





## 2. 遥控器





## 遥控器按键功能说明

	功能键	功能描述	
1	左摇杆	提升机上升，飞行器上升；提升机下拉，飞行器下降 提升机左，飞行器向左倾斜；提升机右，飞行器向右倾斜	
2	右摇杆	提升机上升，飞行器前飞；提升机下拉，飞行器后退 提升机左，飞行器向左飞行；提升机右，飞行器向右飞行	
3	四轴进气键	前后轴进气键飞行，前后轴出气键减速	
4	四轴飞行动态键	左右轴进气键起飞降落	
5	翻转键	翻转进气减速	
6	急停键	紧急刹车/停止速度	
7	五维键	上	默认向前UV进气
		下	默认向后UV进气
		左	默认左升/左进气
		右	默认右升/右进气
		中	默认打死/进气减速
8	左滚转	离开地面保持高度	
9	右滚转	离开地面UV偏航/CCW	
10	地速键	相对地面UV速度；相对+向后相对上升	
11	补偿平衡键/姿态锁定键	调节姿态平衡参数	

注：五维键功能可通过Tello App 3D App 进行设置

提升机进气键以模式1，可通过 Tello App 3D App 进行设置

# 充电

## 1 飞行器智能电池充电

如图示，将升降舵桨叶与地面接触，开机后灯闪灯亮时，电池插入充电座进行充电。电池插好灯闪亮，开机后灯灭时，电池充满电。



## 2 遥控器充电

如图示，将遥控器连接到遥控器充电接口。充电时，电量指示灯闪烁；充满后熄灭。电量指示灯熄灭且无其他动作时，阅读完成后请断开连接。



## 3 充电盒对外充电

智能机架底部的插孔可对智能机架进行充电。先将智能机架插入充电盒，打开电源开关即可对智能机架进行充电。



注：部分手机及平板无法识别此功能，具体以设备支持为准。如同时使用智能机架和POC套件，请根据POC套件的连接线。

# 安装与拆卸

## 1 螺旋桨

请开始前请勿启动机翼

任何在螺旋桨或叶片上附着的油污都必须在叶片上

清除螺旋桨的灰尘或机翼底部

并确保机翼和螺旋桨完全干燥，直到螺旋桨停止转动

拆卸螺旋桨时，用力拉扯螺旋桨以确保其内部有螺母锁紧。请勿使用锤子



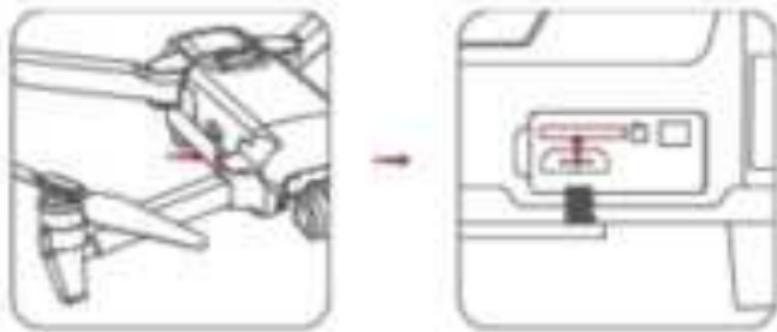
### 安全提示:

立即停止飞行，清洁叶片，干燥机翼，以及飞行安全的步骤。  
每次飞行前请检查螺旋桨是否完全安装牢固，操作出现异常情况

注：以逆时针方向转动

## 2 飞行器 SD卡安装

- 安装飞行器SD卡时,请断开飞行器的电源线,打开接口保护盖
- 将SD卡插入飞行器背面插槽,飞行器卡槽
- 取出SD卡时,按下SD卡即可弹出



### 3 电池

当电量不足时，电力驱动停止。电池的状态会有“电量”声  
音提示，这时需要将电池的插头拔出并断开，即可取出电池。



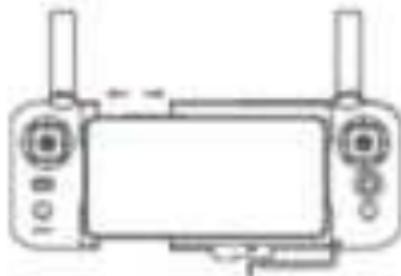
### 4 遥控器

先开始遥控器入宇的键

短按4、短按4+拉杆抬起支架，再短按两次支架上，连接线插入遥控器

打开遥控器下方接口保护盖，将连接线插入接口端

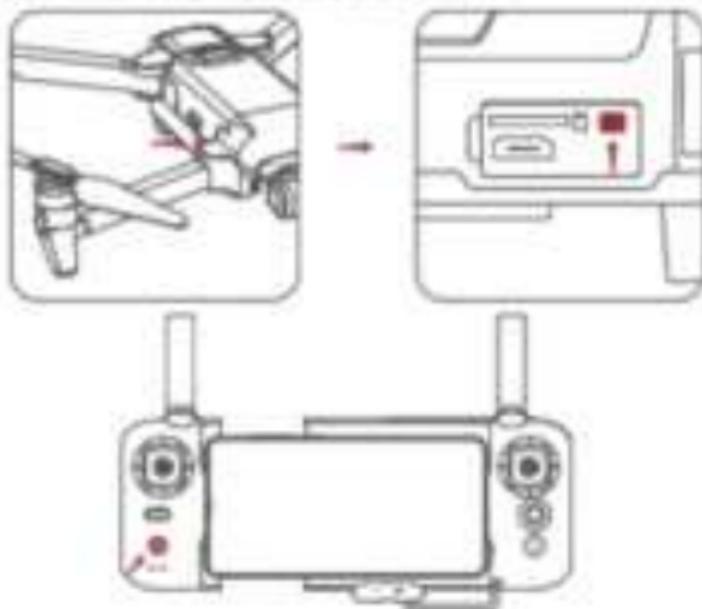
连接飞行器，根据 DJI Mavic 2 APP 的提示进行飞行器连接，遥控器即开始



注：若遥控器和飞行器连接

## 5 遥控器与飞行器对频

飞行器开机后，长按遥控器上的对频键约10秒，直到黄色指示灯熄灭进入对频状态。遥控器开机后，长按遥控器上的对频键约10秒，直到发出“滴滴...”声，表示对频成功。对频成功后，遥控器上的黄色指示灯常亮，飞行器上的黄色指示灯常亮。

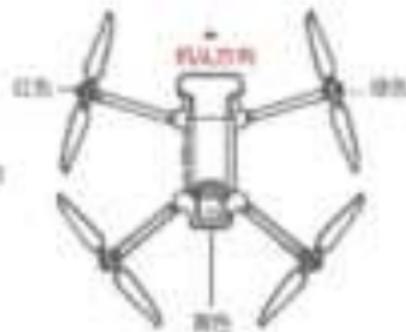


注：产品包装内已装有锂电池，无需拆卸。

## 准备飞行

### 1 确认飞行器方向

- 云台相机朝向为机头方向
- 飞行器开孔位置可以确认机的下方进气口为黑色和相对方向
- 红色面朝上，绿色面朝下为机头方向，黑色面朝左方向为机尾方向



### 2 打开/关闭飞行器和遥控器

- 短按+长按 2秒电源键开机关机
- 短按电源键让遥控器开机



飞行器



遥控器

安全提示：操作飞行器时保持机身对准操作者，避免飞向人群或障碍物。

## 指示灯说明

### 1 飞行器指示灯

	指示状态	飞行器状态
1	红绿黄灯常亮	启动中
2	红绿黄灯闪烁	飞行器空中，姿态稳定
3	红绿灯常亮，黄灯常亮	可飞离飞行器 50m
4	红绿黄灯常亮	姿态低垂且颤动
5	红绿黄灯常亮	飞行器姿态低，其姿态不稳定
6	红绿灯常亮	姿态抬高
7	红绿灯常亮，黄灯闪亮	未连接到遥控器
8	红绿色	禁锢于固定点，无法进行手动操作

### 2 调控器指示灯

	指示灯状态	遥控器状态
1	红绿黄灯常亮	遥控器待机
2	红绿黄灯闪烁	未连接到飞行器
3	红绿黄灯常亮	进入遥控器低电量待机
4	红绿黄灯常亮	遥控器与飞行器连接成功
5	红绿黄灯闪烁	满电待机
6	白绿红黄四色灯常亮	无线遥控器与遥控器连接
7	白绿红黄四色灯常亮	允许遥控器与遥控器连接

# 飞行

## 1 自动起飞/降落

当遥控器“自动起飞/降落”按键被按下时，无人机将执行“自动起飞”或“自动降落”。按此键时“飞”字将可能被“升”或“降”代替。



自动起飞



自动降落

## 2 手动起飞/降落



左提升



右提升



左提升



右提升



左提升



右提升

在遥控器两个提升杆内的下方移动摇杆最大程度，且无人机离开地面10米以上，螺旋桨开始转动。

松开提升杆时，再将提升杆向提升杆中心，左提升杆上按钮，“飞行模式”

灯灭后，松开提升杆飞行器上升

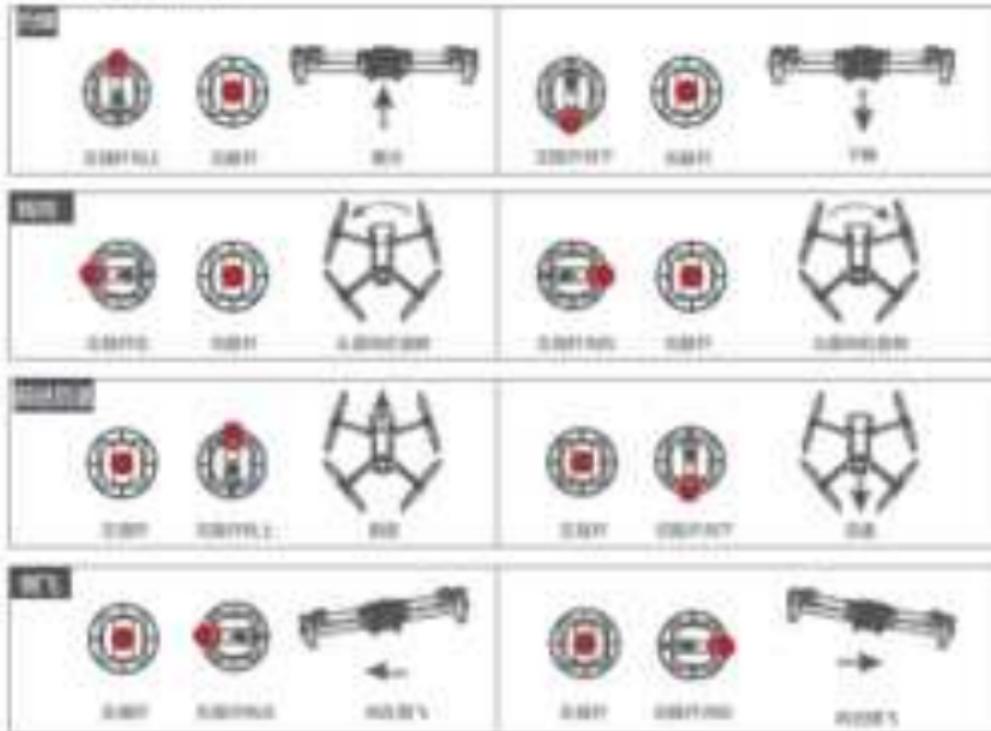
在飞行模式杆，松开提升杆约两个来回，“飞行模式”按钮下方的指示灯

亮起时，无人机悬停或往下飞。要将飞行器降落到地面

在飞行模式杆地面上，同样将提升杆上升到约两个来回

发生撞击，“飞行模式”防水功能，将飞离落水水面。为安全起见，切勿操作在水面上。

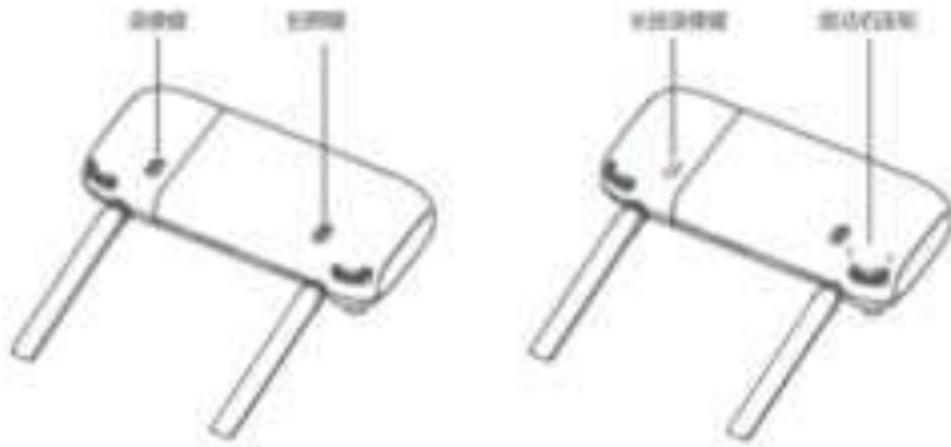
### 3 基本飞行操作



(注：遥控器杆的设置可以在遥控器设置菜单中进行更改或认为是出厂）

## 4 拍照与录像

- 按一个拍照键，听到一声短鸣，相机拍摄一张照片
- 按一下录像键，开始录像，再按一下录像键，相机自动停止，并上传
- 在屏幕上下方的可以拉伸调节舞台的横向跨度
- 右侧摇杆以调节地掷球WPSO撞
- 左侧摇杆前后、上下滚动在调整摄像头视角，可调节相机聚焦距离



## 5 紧急停机

如果出现飞行器失控不能正常停止时，通过左摇杆向下方快速来回摇摆，并同时快速向两侧摇摆以使飞机会进入降落架放下状态，使飞机停止。



安全提示：正常飞行时，切勿进行上述操作，以免无人机空中停顿。

## X8 Tele 系列三包政策

飞乐公司郑重承诺对产品提供三年整机保修期和三年质保期。三年质保期内因产品质量问题进行维修三包服务，服务内容如下：

1. 在保修期内出现的机身、本产品由质保中心负责维修或更换；出现飞乐标志的部件由质保中心负责维修，可能需要寄送质保中心维修。
2. 在保修期内出现的机架、电源、本产品由质保中心负责维修或更换；出现飞乐标志的部件由质保中心负责维修，可能需要寄送质保中心维修。
3. 在保修期内出现的飞乐部件，本产品由质保中心负责维修或更换；出现飞乐标志的部件由质保中心负责维修，可能需要寄送质保中心维修。

名称	维修范围
X8 Tele	飞乐机无法开机，不能正常飞行
	遥控器无法开机，不能正常操作
	电池不能开机，不能充电
	录像机不能正常工作
	相机不能正常拍照，成像质量差或识别不出要抓拍的物体
	本产品非人为损坏后，且经维修后能正常使用

## 产品保修期

名称	保修内容	保修时间
飞行器	飞控系统	12个月
	云台相机	3个月
	螺旋桨	3个月
遥控器	整体	6个月
电池	整体	8个循环不大于1500次或锂电池半年
充电器	整体	12个月
飞行器	机身、电池、机架	主体整机
附件	云台、相机、螺旋桨	无损耗期
摄像头	摄像头	无损耗期

### 维修保养

1. 未经授权的维修、拆卸、碰撞、跌落、震动、高温、潮湿、霉菌、盐雾、风沙、不正确的使用非本产品除外，如划伤、丢失物品、自然损坏。
2. 已超过保修期的维修
3. 由于可抗力造成的损坏

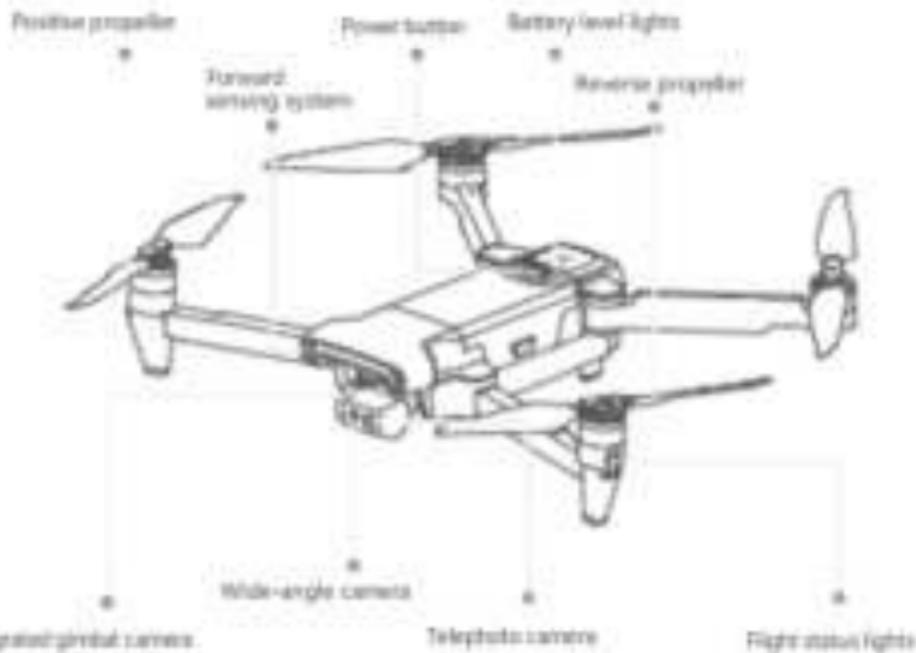
1. 下载飞凡 F-Robot 智能解决方案 开发板固件安装包
2. 请从飞凡官网门户处下载飞凡 F-Robot 智能解决方案 开发板固件  
官方网站: [www.frvic.com](http://www.frvic.com)
3. 邮箱地址: support@frvic.com
4. 客服热线: 400-661-0888
5. 制造商: 深圳市飞凡机器人科技有限公司
- 地址: 广东省深圳市龙华区观澜街道牛湖大道1111号印象大厦B座12层1213-1217室

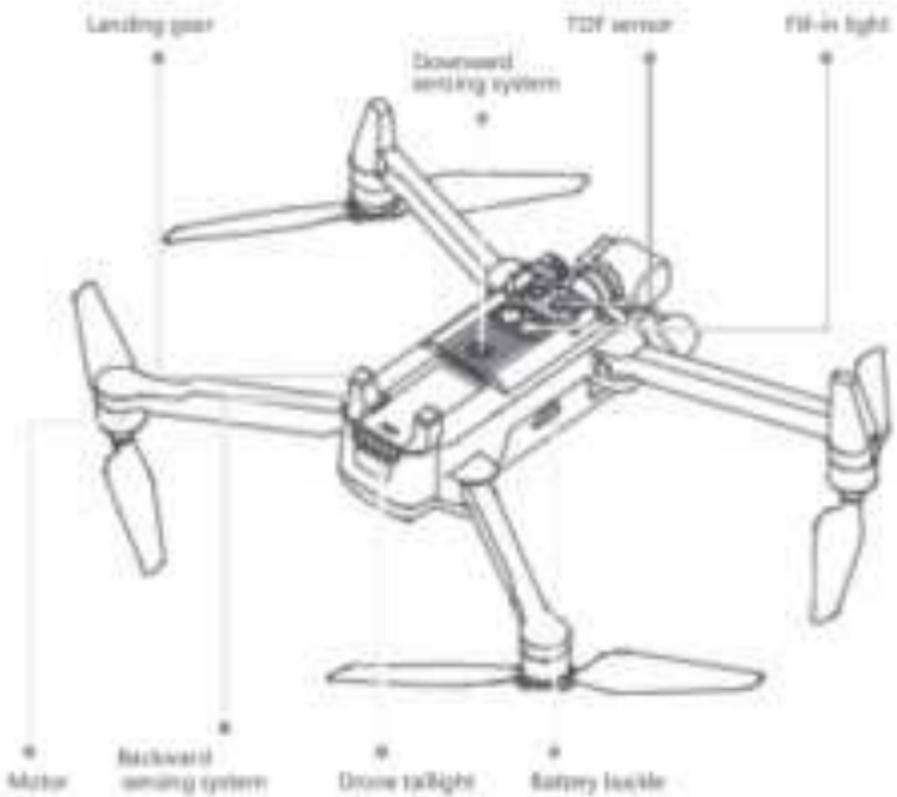


请扫描二维码下载 F-Robot V1.0 固件

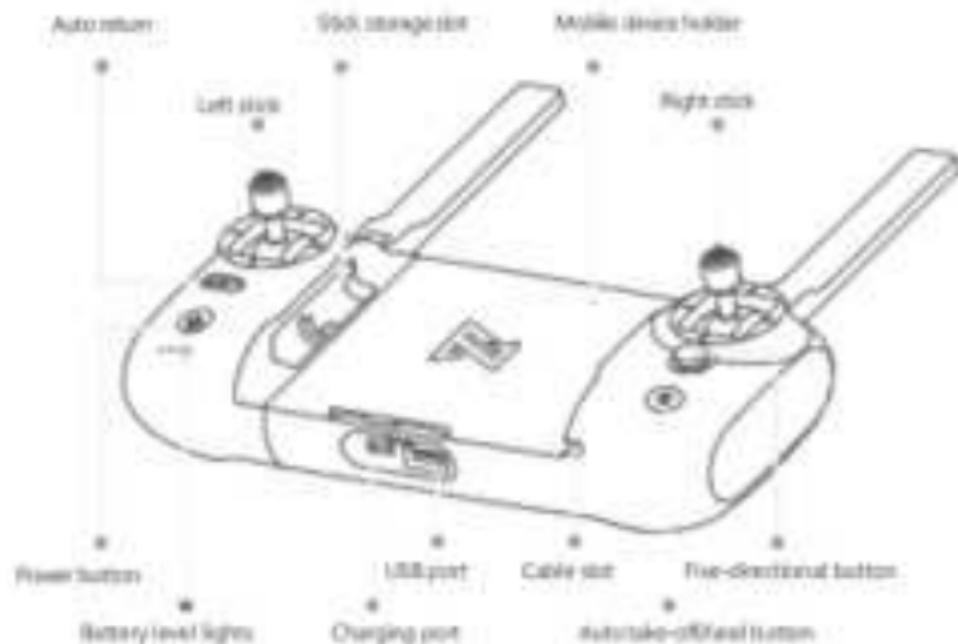
## Product Introduction

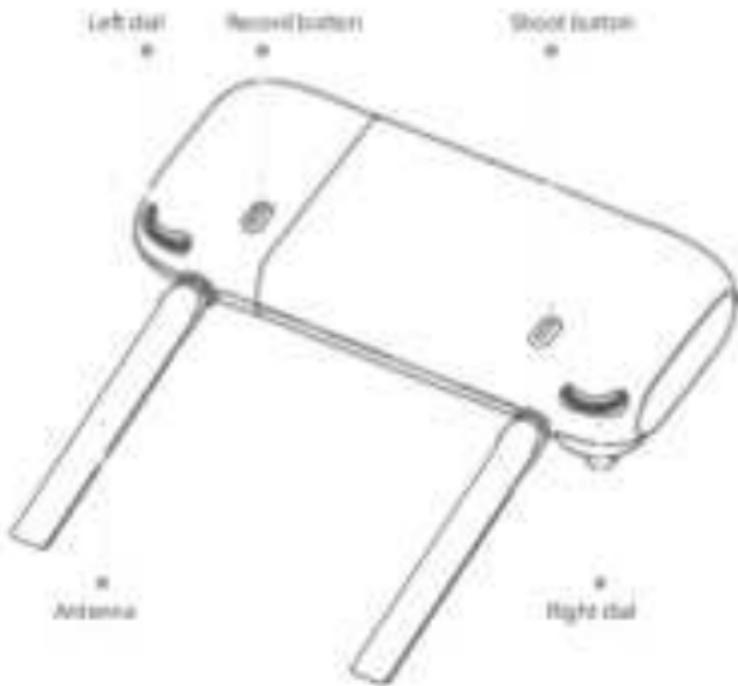
### 1 Drone





## 2 Remote controller





## Function Introduction of RC

Buttons		Function description
1	Left side	Push slightly: the drive goes up parallelly downward. The steering goes down, trigger side to left, the drive goes counter-clockwise. Trigger side to right, the drive goes counter-clockwise.
2	Right side	Push slightly upward: the drive flies forward, pull slightly downward: the drive flies backward. If the steering has been triggered to left, the drive flies to left; trigger side to right, the drive flies to right.
3	Auto return	Toggle the function to the left, switching to manual flight. Toggle the function to the right, switching to auto return.
4	Autosteer/offsteer button	Long press: 2 seconds to autosteer offsteering.
5	Shutter button	Short press to start/stop recording.
6	Rec notification	Short press to start/stop recording.
7	Five directional button	Up: Default to system function or app (+1V)
		Down: Default to switch between initial contact and base
		Left: Default to human-computer interface
		Right: Default to camera/cell wall mounting interface
		Center: Default to turn on/off media library
8	Left dial	Adjust the pitch angle of original
9	Right dial	Adjust the value of the Z axis
10	Power button	Short press to view the battery level Short press long press 2 seconds to power on/off
11	Notification & right side wheel connection key	Push camera/wheel control

Note: The other functions of the five-directional button can be set in the FIM-Navi 2.0 App.

# Charging

## 1 Charge drone battery

- As shown in the diagram, connect the charger to the charging box, and the charging box indicator lights up.
- Insert the battery into the charging box for charging, and the battery indicator flashes.
- After charging is complete, the battery indicator goes out.



## 2 Charge RC

Connect the remote controller to a power adapter as shown below. When the RC is in charge, the battery level lights are flashing. When the RC is fully charged, the battery level lights go out. It takes about 1.5 hours to fully charge the RC at the present resolution.



## 3 Charging case charges externally

- The intelligent battery, when paired with a charging case, can charge other devices.
- First, connect the smart battery to the charging case.
- Turn on the battery switch to charge external devices.



Note: This function may not be available on some mobile phones and tablets. Please refer to the device specifications for accurate information. When using reverse charging, a connecting cable that supports PD and QC protocols is required.

# Assembly and Disassembly

## 1 Propellers

- Unfold the front and rear arms of the plane.
- Attach the grey riveted propellers to the motor mounting base with grey marks on the arms.
- Ensure the propeller is mounted to the bottom cold air mounting base.
- Rotate the propeller to the end of the lock direction until the propeller gets loose and locked.
- Press the propeller hub cap out and rotate the propeller along the counter direction to remove the propeller.



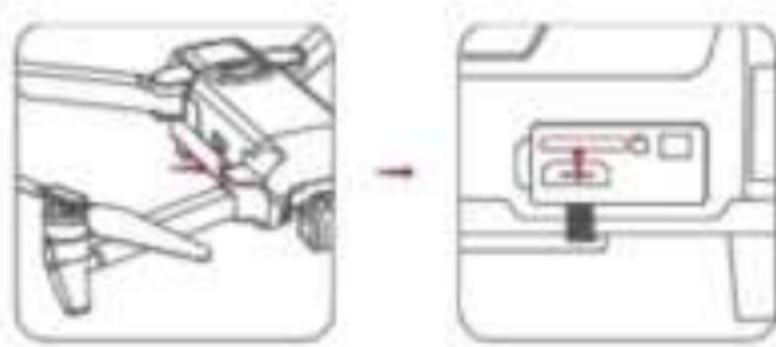
### Safety tips:

If the propeller is damaged, please replace them to ensure flight safety and efficiency. Check if the propeller is properly installed and fastened before each flight. Stay away from the rotating propeller to avoid cutting.

Now take the installation of reverse propeller as an example:

## 2 Drone: Micro SD card

- When installing SD card to the drone please unfold the arms of the drone first and open the protective cover.
- Insert the SD card with the metal contacts into the SD card slot.
- When removing SD card, press the SD card to pull out.



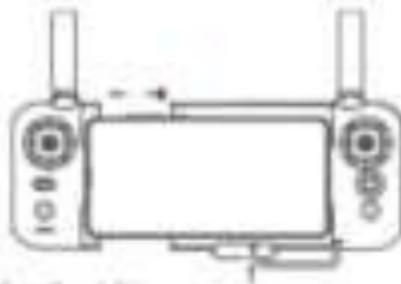
### 3 Battery

- Push hard the battery, after the battery installed in place, there will be a "click" sound.
- To remove the battery you need to press the battery buckle on both sides to pull out.



### 4 Remote controller

- Tighten the mobile or pad-on mobile device holder by extending the holder to the left.
- Open the protective cover on the RC bottom.
- Connect your phone and the RC with a USB cable.
- Connect the drone and update firmware according to instructions in HUB Hand 3D App.



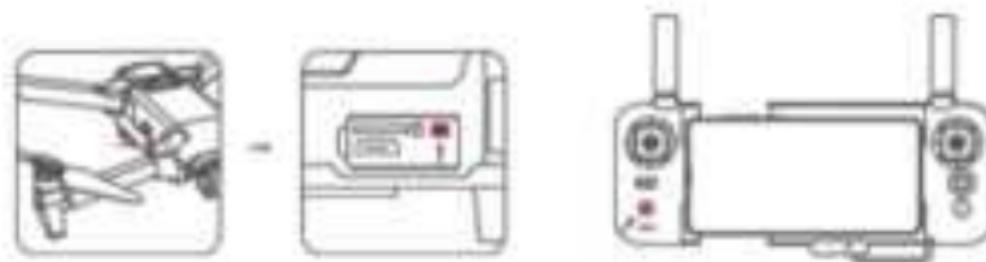
Note: The cable slot is reserved on the right.

## 5 Remote controller synchronizes with the drone

After powering on the aircraft for 10 seconds, short press the frequency pairing button according to the instruction diagram. The yellow indicator light at the tail will go out, indicating that it has entered the frequency pairing state.

After powering on the remote controller for 10 seconds, long press the power button for 3 seconds according to the instruction diagram to enter frequency pairing. The master will emit "BEEP BEEP..." sound, indicating that it has entered the frequency pairing state.

After successful frequency pairing, the remote controller power button will have a steady white light, and the aircraft's yellow indicator light will turn on steadily.



Note: Frequency pairing is already completed during the product's factory setup. No need to pair again.

## Prepare to Fly

### 1 Confirm the drone heading

- The direction of blade in gimbal is the drone heading.
- Once the drone is turned on, the heading can be told by navigation lights.
  - The red light and the green light indicate the heading, and the yellow light is the tail.



### 2 Turning on/off the drone and the RC

- Short press & long press power button 2 seconds to power on/off.
- Short press to check battery level.



**Safety tip:** Always keep the tail pointed at the user to avoid direction misjudging.

# Light Recognition

## 1 Drone lights

	Drone lights	Drone status
1	All lights is lit/dim in interval	Self-checking
2	All lights are off	Drone on the ground & self-check fails
3	The yellow lights are on and the red and green light is flashing at regular intervals	Drone is flying, normal mode
4	All lights flashing twice	Ready to Fly/Ride
5	All lights are flashing quickly	Low battery alert
6	The red and green flashing quickly	Very low battery, identify landing seconds to problem
7	The red and green lights are on and the yellow light is flashing at regular intervals	The firmware of the drone is updating
8	1B or 1H	Not connected to remote control
	1B or 1H	Auxiliary T2T service automatically/transferring connected

## 2 Remote lights

	Remote lights	Remote status
1	Pilot button's red light are on	Reach signal
2	Pilot button's red light flashes	No response from drone
3	Pilot button's red light flashes	RC Pending or Approving Sensors
4	Pilot button's white light are on	Normal signal
5	Pilot button's white light flashes	Recording video
6	Auto take-off/landing button's red light are on	Autotake-off landing not enabled
7	Auto take-off/landing button's white light are on	Ready for auto take-off

## Flying

### 1 Auto take-off/landing

The drone meets the auto take-off/landing condition when the auto take-off/landing button light is white. Press this button for 2 seconds to auto take off/landing.



Auto take-off



Auto landing

### 2 Manual take-off/landing



Left stick



Right stick



Left stick



Right stick



Left stick



Right stick

Keep both sticks to the bottom until after 2 seconds, the propellers start spinning.

Release both sticks once propellers have been spinning, and firmly push the left stick upward to take off the drone.

During flight, release left stick to hover.

At anytime during controlled flight, release the sticks and the drone will hover automatically. Gently move the left stick downward to land the drone.

Once the drone has landed, push and hold the left stick down over 2 seconds, the motors will stop.

Safety tips: The drone has no waterproof function. Please be careful of landing environment.

Do not land on an inclined plane for safety.

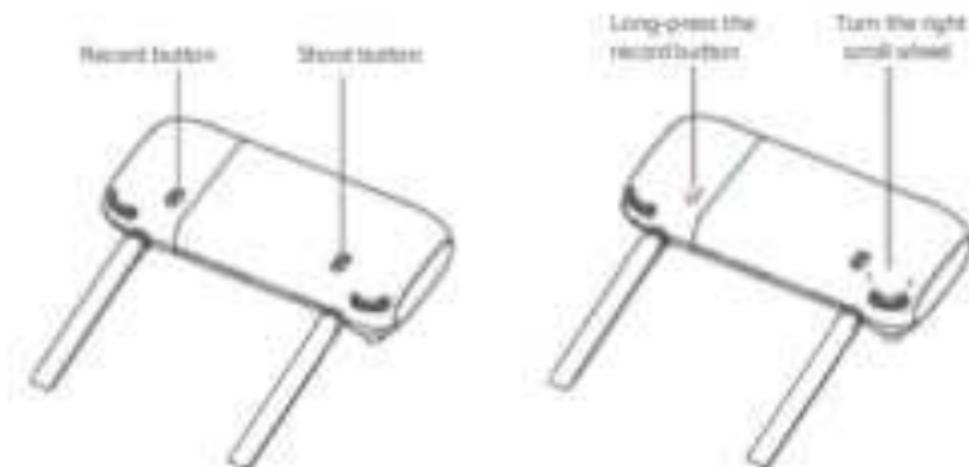
## 3 Basic Flight Operations

Up and down	
 Left stick Up	 Right stick
 Up	 Down
Turn	
 Left stick Left	 Right stick
 Rudder Head Left	 Rudder Head Right
Move forward and backward	
 Left stick	 Right stick Down
 Move Forward	 Move Backward
Sideways flight	
 Left stick	 Right stick Left
 Fly to the left	 Fly to the Right

Note: The stick mode can be set in Tello Fly app (the default is American hand).

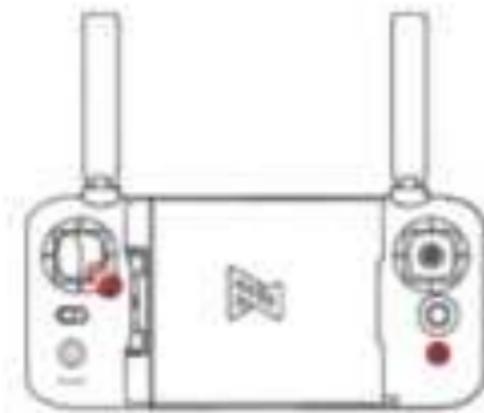
## 5 Shooting and Recording

- Press the shoot button to take a photo. A photo is taken every you press 2 short sounds.
- Press the record button to record video. Recording starts when you hear 2 short sounds. Press again to stop recording with 4 short sounds.
- During recording, short press the shoot button to capture a picture; only support 1080x1080 25/30fps(60fps)
- The pitch angle of the gimbal can be controlled by toggling the left stick up and down.
- The right stick can adjust EV/FD.
- After long pressing the record button, use the up and down movements of the right scroll wheel in combination to adjust the camera zoom factor.



## 4 Stop propellers in an emergency

When motors can't properly turn off, please toggle the left stick to the bottom issue in maximum range, and press Auto take-off/landing button for 1 second; simultaneously, the motors will stop.



**Safety tips:** Do not do the above operation during normal flight to avoid motor being stopped in the air.

FHSS XB Tele Drone FCC ID: 2AWYUWWR004A1

Remote Controller FCC ID: 2AWYUWWR004A1

#### FCC Statement:

This device complies with part 15 of the FCC Rules. Operation is subject to the following two conditions:

- (1) This device may not cause harmful interference, and
- (2) this device must accept any interference received, including interference that may cause undesired operation.

#### FCC warning:

Any changes or modifications not expressly approved by the party responsible for compliance could void the user's authority to operate the equipment.

Note: This equipment has been tested and found

to comply with the limits for a Class B digital

device.

pursuant to part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference in a residential installation. This equipment generates, uses and can radiate radio frequency energy and, if not installed and used in accordance with the instructions, may cause harmful interference to radio communications. However, there is no guarantee that interference will not occur in a particular installation. If this equipment does cause harmful interference to radio or television reception, which can be determined by turning the equipment off and on, the user is encouraged to try to correct the interference by one or more of the following

measures:

-Reorient or relocate the receiving antenna.

-Increase the separation between the equipment and receiver.

-Connect the equipment into an outlet on a circuit different from that to which the receiver is connected.

-Consult the dealer or an experienced radio/TV technician for help.

**Usage** This equipment complies with FCC radiation exposure limits set forth for an uncontrolled environment.  
thus  
equipment should be installed and operated with minimum distance 20cm between the radiator & your body.



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