SAR Test Report

Report No.: AGC01039140701-1FH01

FCC ID : PODDM-UVF10

APPLICATION PURPOSE: Original Equipment

Product Designation : DPMR Digital Transceiver

Brand Name : TYT

Model Name : DM-UVF10

Client : TYT ELECTRONICS CO., LTD.

Date of Issue : Oct. 30,2014

IEEE Std. 1528:2003

STANDARD(S) : 47CFR § 2.1093

IEEE/ANSI C95.1

REPORT VERSION : V1.0

Attestation of Global Compliance(Shenzhen) Co., Ltd.

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Report Revise Record

Report Version	Revise Time	Issued Date	Valid Version	Notes
V1.0	/	Oct. 30,2014	Valid	Original Report

Test Report Certification				
Applicant Name	TYT ELECTRONICS CO., LTD.			
Applicant Address	Block 39-1, Optoelectronics-Information Industry Base, Nan'an, Quanzhou, Fujian China			
Manufacturer Name	TYT ELECTRONICS CO., LTD.			
Manufacturer Address	Block 39-1, Optoelectronics-Information Industry Base, Nan'an, Quanzhou, Fujian China			
Product Name	DPMR Digital Transceiver			
Brand Name	TYT			
Model Name	DM-UVF10			
Difference Description	N/A			
EUT Voltage	DC7.4 V by battery			
Applicable Standard	IEEE Std. 1528:2003 47CFR § 2.1093 IEEE/ANSI C95.1			
Test Date	Sep. 24,2014; Oct. 30,2014			
	Attestation of Global Compliance (Shenzhen)Co., Ltd.			
Performed Location	2F, Building 2, No.1-No.4, Chaxi Sanwei Technical Industrial Park, Gushu, Xixiang Street, Bao'an District, Shenzhen, China			
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1. SUMMARY OF MAXIMUM SAR VALUE

The maximum results of Specific Absorption Rate (SAR) found during testing for EUT are as follows:

Highest Report tested & scaled SAR Summary (with 50% duty cycle)

Exposure Position	Separation	Highest Tested 1g-SAR(W/Kg)	Highest Reported 1g-SAR(W/Kg)
Face Up	12.5 KHz	3.524	3.900
	6.25 KHz	3.234	3.505
Back Touch	12.5 KHz	5.093	5.661
	6.25 KHz	5.133	5.564

This device is compliance with Specific Absorption Rate (SAR) for Occupational / Controlled Exposure Environment limits (8.0W/Kg) specified in 47 CFR part 2 (2.1093) and ANSI/IEEE C95.1, and had been tested in accordance with measurement methods and procedures specified in IEEE 1528-2003 and the following specific FCC Test Procedures:

KDB 865664 D01 SAR Measurement 100MHz to 6GHz v01r03

KDB 643646 D01 SAR Test for PTT Radios V01r01

2. GENERAL INFORMATION

2.1. EUT Description

General Information				
Product Name	DPMR Digital Transceiver			
Test Model	DM-UVF10			
Hardware Version	N/A			
Software Version	N/A			
Exposure Category:	Occupational/Controlled Exposure			
Device Category	UHF Portable Transceiver			
Modulation Type	FM, 4FSK			
TX Frequency Range	400-480MHz			
Rated Power	5W (It was fixed by the manufacturer, any individual can't arbitrarily change it)			
Max. Peak Power	36.93dBm			
Channel Spacing	12.5 KHz&6.25KHz			
Antenna Type	Detachable			
Antenna Gain	1.5dBi			
Body-Worn Accessories:	Belt Clip with headset			
Face-Head Accessories:	None			
Battery Type (s) Tested:	DC 7.4V, 1800mAh (by battery)			

Draduot	Туре	
Floudel	□ Production unit □	Identical Prototype

2.2. Test Procedure

1	Setup the EUT for two typical configuration of hold to face and body worn individually
2	Power on the EUT and make it continuously transmitting on required operating channel
3	Make sure the EUT work normally during the test

2.3. Test Environment

Ambient conditions in the laboratory:

Items	Required	Actual
Temperature (°C)	18-25	21 ± 2
Humidity (%RH)	30-70	56

3. SAR MEASUREMENT SYSTEM

3.1. Specific Absorption Rate (SAR)

SAR is related to the rate at which energy is absorbed per unit mass in object exposed to a radio field. The SAR distribution in a biological body is complicated and is usually carried out by experimental techniques or numerical modeling. The standard recommends limits for two tiers of groups, occupational/controlled and occupational/uncontrolled, based on a person's awareness and ability to exercise control over his or her exposure. In general, occupational/controlled exposure limits are higher than the limits for general population/uncontrolled.

The SAR definition is the time derivative (rate) of the incremental energy (dW) absorbed by (dissipated in) an incremental mass (dm) contained in a volume (dv) of given mass density (ρ). The equation description is as below:

$$SAR = \frac{d}{dt} \left(\frac{dW}{dm} \right) = \frac{d}{dt} \left(\frac{dW}{\rho dV} \right)$$

SAR is expressed in units of Watts per kilogram (W/Kg)

SAR can be obtained using either of the following equations:

$$SAR = \frac{\sigma E^2}{\rho}$$

$$SAR = c_h \frac{dT}{dt}\Big|_{t=0}$$

Where

SAR is the specific absorption rate in watts per kilogram;

E is the r.m.s. value of the electric field strength in the tissue in volts per meter;

σ is the conductivity of the tissue in siemens per metre:

ρ is the density of the tissue in kilograms per cubic metre;

c_h is the heat capacity of the tissue in joules per kilogram and Kelvin;

 $\frac{dT}{dt}$ | t = 0 is the initial time derivative of temperature in the tissue in kelvins per second

3.2. SAR Measurement Procedure

The EUT is set to transmit at the required power in line with product specification, at each frequency relating to the LOW, MID, and HIGH channel settings.

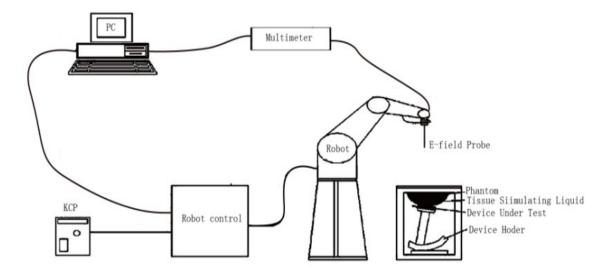
Pre-scans are made on the device to establish the location for the transmitting antenna, using a large area scan in either air or tissue simulation fluid.

The EUT is placed against the Universal Phantom where the maximum area scan dimensions are larger than the physical size of the resonating antenna. When the scan size is not large enough to cover the peak SAR distribution, it is modified by either extending the area scan size in both the X and Y directions, or the device is shifted within the predefined area.

The area scan is then run to establish the peak SAR location (interpolated resolution set at 1mm²) which is then used to orient the center of the zoom scan. The zoom scan is then executed and the 1g and 10g averages are derived from the zoom scan volume (interpolated resolution set at 1mm³).

When multiple peak SAR location were found during the same configuration or test mode, Zoom scan shall performed on each peak SAR location, only the peak point with maximum SAR value will be reported for the configuration or test mode.

3.3. COMOSAR System Description



The COMOSAR system for performing compliance tests consists of the following items:

- The PC. It controls most of the bench devices and stores measurement data. A computer running WinXP and the Opensar software.
- The E-Field probe. The probe is a 3-axis system made of 3 distinct dipoles. Each dipole returns a voltage in function of the ambient electric field.
- · The Keithley multimeter measures each probe dipole voltages.
- The SAM phantom simulates a human head. The measurement of the electric field is made inside the phantom.
- The liquids simulate the dielectric properties of the human head tissues.
- The network emulator controls the mobile phone under test.
- The validation dipoles are used to measure a reference SAR. They are used to periodically check the bench to make sure that there is no drift of the system characteristics over time.
- •The phantom, the device holder and other accessories according to the targeted measurement.

3.3.1. Applications

Predefined procedures and evaluations for automated compliance testing with all worldwide standards, e.g., IEEE 1528, IEC 62209-1, IEC 62209-2, EN 50360, EN 50383 and others.

3.3.2. Area Scans

Area scans are defined prior to the measurement process being executed with a user defined variable spacing between each measurement point (integral) allowing low uncertainty measurements to be conducted. Scans defined for FCC applications utilize a 10mm² step integral, with 1mm interpolation used to locate the peak SAR area used for zoom scan assessments. When an Area Scan has measured all reachable points, it computes the field maxima found in the scanned area, within a range of the global maximum. The range (in dB) is specified in the standards for compliance testing. For example, a 2 dB range is required in IEEE 1528-2003, EN 50361 and IEC 62209 standards, whereby 3 dB is a requirement when compliance is assessed in accordance with the ARIB standard (Japan).

3.3.3. Zoom Scan (Cube Scan Averaging)

Zoom Scans are used to assess the peak spatial SAR values within a cubic averaging volume containing 1 g and 10 g of simulated tissue. A density of 1000 kg/m^3 is used to represent the head and body tissue density and not the phantom liquid density, in order to be consistent with the definition of the liquid dielectric properties, i.e. the side length of the 1 g cube is 10 mm, with the side length of the 10 g cube 21,5 mm. The zoom scan integer steps can be user defined so as to reduce uncertainty, but normal practice for typical test applications utilize a physical step of 7 x 7 x 7 (5 mm x 5 mm x 5 mm) providing a volume of 30 mm in the X & Y axis, and 30 mm in the Z axis.

3.3.4. Uncertainty of Inter-/Extrapolation and Averaging

In order to evaluate the uncertainty of the interpolation, extrapolation and averaged SAR calculation algorithms of the Post processor, COMOSAR allows the generation of measurement grids which are artificially predefined by analytically based test functions. Therefore, the grids of area scans and zoom scans can be filled with uncertainty test data, according to the SAR benchmark functions of IEEE 1528. The three analytical functions shown in equations as below are used to describe the possible range of the expected SAR distributions for the tested handsets. The field gradients are covered by the spatially flat distribution f1, the spatially steep distribution f3 and f2 accounts for H-field cancellation on the phantom/tissue surface.

$$f_1(x,y,z) = Ae^{-\frac{z}{2a}}\cos^2\left(\frac{\pi}{2}\frac{\sqrt{x'^2 + y'^2}}{5a}\right)$$

$$f_2(x,y,z) = Ae^{-\frac{z}{a}}\frac{a^2}{a^2 + x'^2}\left(3 - e^{-\frac{2z}{a}}\right)\cos^2\left(\frac{\pi}{2}\frac{y'}{3a}\right)$$

$$f_3(x,y,z) = A\frac{a^2}{\frac{a^2}{4} + x'^2 + y'^2}\left(e^{-\frac{2z}{a}} + \frac{a^2}{2(a+2z)^2}\right)$$

3.4. COMOSAR E-Field Probe

The SAR measurement is conducted with the dissymmetric probe manufactured by SATIMO. The probe is specially designed and calibrated for use in liquid with high permittivity. The dissymmetric probe has special calibration in liquid at different frequency. SATIMO conducts the probe calibration in compliance with international and national standards (e.g. IEEE 1528, EN62209-1, IEC 62209, etc.) Under ISO17025. The calibration data are in Appendix D.

3.5. Isotropic E-Field Probe Specification

3.5. Isotropic E-Field Probe Specification					
Model	SSE5				
Manufacture	SATIMO				
Frequency	0.3GHz-3GHz Linearity:±0.09dB(300 MHz-3GHz)	5/15/			
Dynamic Range	0.01W/Kg-100W/Kg Linearity:±0.09dB	7555			
Dimensions	Overall length:330mm Length of individual dipoles:4.5mm Maximum external diameter:8mm Probe Tip external diameter:5mm Distance between dipoles/ probe extremity:2.7mm				
Application	High precision dosimetric measurements in any exp (e.g., very strong gradient fields). Only probe which compliance testing for frequencies up to 3 GHz with	enables			

3.6. Robot

The COMOSAR system uses the KUKA robot from SATIMO SA (France). For the 6-axis controller COMOSAR system, the KUKA robot controller version from SATIMO is used.

The XL robot series have many features that are important for our application:

High precision (repeatability 0.02 mm)

High reliability (industrial design)

Jerk-free straight movements

Low ELF interference (the closed metallic

construction shields against motor control fields)

6-axis controller

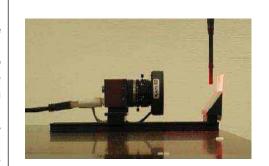


3.7. Video Positioning System

The video positioning system is used in OpenSAR to check the probe. Which is composed of a camera, LED, mirror and mechanical parts. The camera is piloted by the main computer with firewire link.

During the process, the actual position of the probe tip with respect to the robot arm is measured, as well as the probe length and the horizontal probe offset. The software then corrects all movements, such that the robot coordinates are valid for the probe tip.

The repeatability of this process is better than 0.1 mm. If a position has been taught with an aligned probe, the same position will be reached with another aligned probe within 0.1 mm, even if the other probe has different dimensions. During probe rotations, the probe tip will keep its actual position.



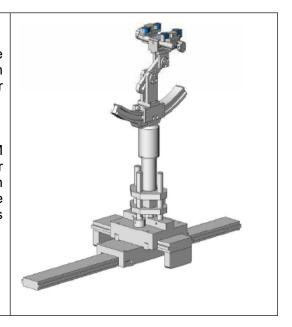
3.8. Device Holder

The COMOSAR device holder is designed to cope with different positions given in the standard. It has two scales for the device rotation (with respect to the body axis) and the device inclination (with

respect to the line between the ear reference points). The rotation center for both scales is the ear reference point (EPR).

Thus the device needs no repositioning when changing the angles.

The COMOSAR device holder has been made out of low-loss POM material having the following dielectric parameters: relative permittivity ϵr =3 and loss tangent δ = 0.02. The amount of dielectric material has been reduced in the closest vicinity of the device, since measurements have suggested that the influence of the clamp on the test results could thus be lowered.



3.9. SAM Twin Phantom

The Elliptic Phantom is a fiberglass shell flat phantom with 2mm+/- 0.2 mm shell thickness. It has only one measurement area for Flat phantom



The bottom plate contains three pair of bolts for locking the device holder. The device holder positions are adjusted to the standard measurement positions in the three sections. A white cover is provided to tap the phantom during off-periods to prevent water evaporation and changes in the liquid parameters. On the phantom top, three reference markers are provided to identify the phantom position with respect to the robot.

4. TISSUE SIMULATING LIQUID

For SAR measurement of the field distribution inside the phantom, the phantom must be filled with homogeneous tissue simulating liquid to a depth of at least 15cm. For head SAR testing the liquid height from the ear reference point (ERP) of the phantom to the liquid top surface is larger than 15cm For body SAR testing, the liquid height from the center of the flat phantom to the liquid top surface is larger than 15cm. The nominal dielectric values of the tissue simulating liquids in the phantom and the tolerance of 5% are listed in 4.2

4.1. The composition of the tissue simulating liquid

Ingredient (% Weight) Tissue Type	450 MHz
Water	38.56
Salt (NaCI)	3.95
Sugar	56.32
HEC	0.98
Bactericide	0.19
Triton X-100	0.0
DGBE	0.0

4.2. Tissue Calibration Result

The dielectric parameters of the liquids were verified prior to the SAR evaluation using COMOSAR Dielectric Probe Kit and R&S Network Analyzer ZVL6 .

	Tissue Stimulant Measurement for 450MHz						
Fr. (MHz) Ch.		Dielectric Parameters (±5%)				Tissue	
	head		body				
	er 43.50 41.325 to 45.675	δ[s/m] 0.87 0.8265 to 0.9135	εr 56.7 53.865 to 59.535	δ[s/m] 0.94 0.893 to 0.987	Temp [°C]	Test time	
450	Low	43.15	0.86	56.56	0.92	21	Sep. 24,2014
450	Mid	43.21	0.87	56.34	0.93	21	Sep. 24,2014
450	High	42.87	0.84	56.27	0.92	21	Sep. 24,2014

	Tissue Stimulant Measurement for 450MHz					
		Dielectric Parameters (±5%)				
Fr. (MHz)	Ch.	body		Tissue Temp	Test time	
		εr 56.7	δ[s/m] 0.94	[°C]	rest time	
		53.865 to 59.535	0.893 to 0.987			
450	Low	56.62	0.94	21	Oct. 30,2014	
450	Mid	56.33	0.95	21	Oct. 30,2014	
450	High	56.49	0.95	21	Oct. 30,2014	

4.3. Tissue Dielectric Parameters for Head and Body Phantoms

The head tissue dielectric parameters recommended by the IEEE SCC-34/SC-2 in P1528 have been incorporated in the following table. These head parameters are derived from planar layer models simulating the highest expected SAR for the dielectric properties and tissue thickness variations in a human head. Other head and body tissue parameters that have not been specified in P1528 are derived from the tissue dielectric parameters computed from the 4-Cole-Cole equations described in Reference [12] and extrapolated according to the head parameters specified in P1528.

Target Frequency		head	bo	ody
(MHz)	εr	σ (S/m)	εr	σ (S/m)
300	45.3	0.87	58.2	0.92
450	43.5	0.87	56.7	0.94
835	41.5	0.90	55.2	0.97
900	41.5	0.97	55.0	1.05
915	41.5	0.98	55.0	1.06
1450	40.5	1.20	54.0	1.30
1610	40.3	1.29	53.8	1.40
1800 – 2000	40.0	1.40	53.3	1.52
2450	39.2	1.80	52.7	1.95
3000	38.5	2.40	51.6	2.73
5800	35.3	5.27	48.2	6.00

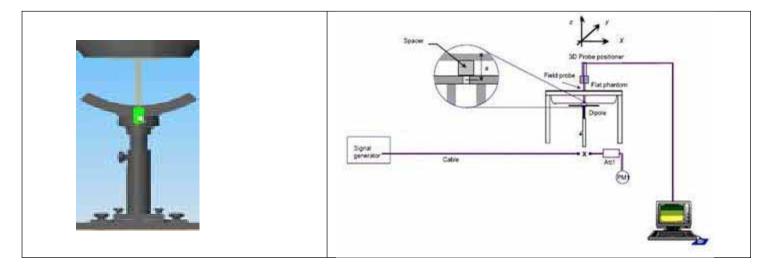
(ε_r = relative permittivity, σ_r = conductivity and ρ_r = 1000 kg/m₃)

5. SAR MEASUREMENT PROCEDURE

5.1. SAR System Validation Procedures

Each SATIMO system is equipped with one or more system validation kits. These units, together with the predefined measurement procedures within the SATIMO software, enable the user to conduct the system performance check and system validation. System kit includes a dipole, and dipole device holder.

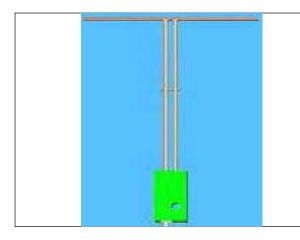
The system check verifies that the system operates within its specifications. It's performed daily or before every SAR measurement. The system check uses normal SAR measurement in the flat section of the phantom with a matched dipole at a specified distance. The system validation setup is shown as below.



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5.2. SAR System Validation

5.2.1. Validation Dipoles



The dipoles used is based on the IEEE-1528 standard, and is complied with mechanical and electrical specifications in line with the requirements of both IEEE and FCC Supplement C. the table below provides details for the mechanical and electrical Specifications for the dipoles.

Frequency	L (mm)	h (mm)	d (mm)
450MHz	290	166.7	6.35

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5.2.2. Validation Result

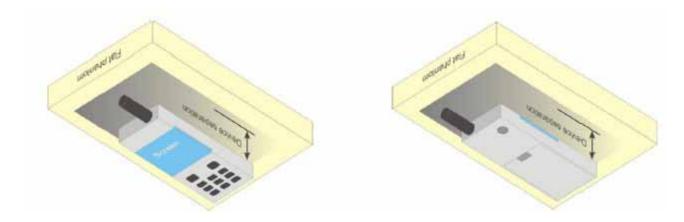
System Per	System Performance Check at 450MHz										
Validation K	Validation Kit: SN 46/11DIP 0G450-184										
Frequency	Target Value(W/Kg)			ce Result 0%)		sted Tissue (W/Kg) Temp.		Test time			
[MHz]	1g	10g	1g	10g	1g	10g	[°Cj				
450	5.07	3.25	4.563-5.577	2.925-3.575	5.433	3.345	21	Sep. 24,2014			
450	5.07	3.25	4.563-5.577	2.925-3.575	5.516	3.391	21	Oct. 30,2014			

6. EUT TEST POSITION

This EUT was tested in Front Face and Rear Face.

6.1. Body Worn Position

- (1) To position the EUT parallel to the phantom surface.(2) To adjust the EUT parallel to the flat phantom.
- (3) To adjust the distance between the EUT surface and flat phantom to 25mm while used in front of face, and **0mm** while used at body back touch.



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7. SAR EXPOSURE LIMITS

SAR assessments have been made in line with the requirements of IEEE-1528, FCC Supplement C, and comply with ANSI/IEEE C95.1-1992 "Controlled Exposure Environment" limits. These limits apply to a location which is deemed as "Controlled Exposure Environment" which can be described as a situation where the general public may be exposed to an RF source with no prior knowledge or control over their exposure.

Limits for Occupational / Controlled Exposure Environment

Type Exposure Limits	Occupational / Controlled Exposure Environment(W/Kg)
Spatial Average SAR (whole body)	8.0

8. TEST EQUIPMENT LIST

Equipment description	Manufacturer/ Model	Identification No.	Current calibration date	Next calibration date	
SAR Probe	SATIMO	SN 22/12 EP159	01/12/2014	01/11/2015	
TISSUE Probe	SATIMO	SN 45/11 OCPG45	11/14/2013	11/13/2015	
Phantom	SATIMO	SN_4511_SAM90	Validated. No cal required.	Validated. No cal required.	
Liquid	SATIMO	-	Validated. No cal required.	Validated. No cal required.	
Comm Tester	R&S - CMU200	069Y7-158-13-712	02/17/2014	02/16/2015	
Comm Tester	Agilent-8960	GB46310822	02/17/2014	02/16/2015	
Multimeter	Keithley 2000	1188656	02/17/2014	02/16/2015	
Dipole	SATIMO SID450	SN46/11 DIP 0G450-184	11/14/2013	11/13/2015	
Signal Generator	Agilent-E4438C	MY44260051	02/23/2014	02/22/2015	
Power Sensor	NRP-Z23	US38261498	02/17/2014	02/16/2015	
Spectrum Analyzer	Agilent/ E4440	US41421290	05/27/2014	05/26/2015	
Network Analyzer	Rhode & Schwarz ZVA	SN100132	02/17/2014	02/16/2015	

Note: Per KDB 865664 Dipole SAR Validation Verification, AGC Lab has adopted 3 years calibration intervals. On annual basis, every measurement dipole has been evaluated and is in compliance with the following criteria:

- 1. There is no physical damage on the dipole;
- 2. System validation with specific dipole is within 10% of calibrated value;
- 3. Return-loss is within 20% of calibrated measurement;
- 4. Impedance is within 5Ω of calibrated measurement.

9. MEASUREMENT UNCERTAINTY

The component of uncertainly may generally be categorized according to the methods used to evaluate them. The evaluation of uncertainly by the statistical analysis of a series of observations is termed a Type An evaluation of uncertainty. The evaluation of uncertainty by means other than the statistical analysis of a series of observation is termed a Type B evaluation of uncertainty. Each component of uncertainty, however evaluated, is represented by an estimated standard deviation, termed standard uncertainty, which is determined by the positive square root of the estimated variance.

A Type A evaluation of standard uncertainty may be based on any valid statistical method for treating data. This includes calculating the standard deviation of the mean of a series of independent observations; using the method of least squares to fit a curve to the data in order to estimate the parameter of the curve and their standard deviations; or carrying out an analysis of variance in order to identify and quantify random effects in certain kinds of measurement.

A type B evaluation of standard uncertainty is typically based on scientific judgment using all of the relevant information available. These may include previous measurement data, experience, and knowledge of the behavior and properties of relevant materials and instruments, manufacture's specification, data provided in calibration reports and uncertainties assigned to reference data taken from handbooks. Broadly speaking, the uncertainty is either obtained from an outdoor source or obtained from an assumed distribution, such as the normal distribution, rectangular or triangular distributions indicated in Table 12.1

Uncertainty Distributions	Normal	Rectangular	Triangular	U-Shape
Multi-plying Factor(a)	1/k(b)	1/√3	1/√6	1/√2

- (a) standard uncertainty is determined as the product of the multiplying factor and the estimated range of variations in the measured quantity
- (b) κ is the coverage factor

Table 13.1 Standard Uncertainty for Assumed Distribution

The combined standard uncertainty of the measurement result represents the estimated standard deviation of the result. It is obtained by combining the individual standard uncertainties of both Type A and Type B evaluation using the usual "root-sum-squares" (RSS) methods of combining standard deviations by taking the positive square root of the estimated variances.

Expanded uncertainty is a measure of uncertainty that defines an interval about the measurement result within which the measured value is confidently believed to lie. It is obtained by multiplying the combined standard uncertainty by a coverage factor. Typically, the coverage factor ranges from 2 to 3. Using a coverage factor allows the true value of a measured quantity to be specified with a defined probability within the specified uncertainty range. For purpose of this document, a coverage factor two is used, which corresponds to confidence interval of about 95 %. The SATIMO uncertainty Budget is shown in the following tables.

Measure	ement un	certa	inty e	valua	tion temp	late for D	UT SAR t	est	
Source of Uncertainty	Sec	Sec	Tol (±%)	Prob. Dist.	(Ci) 1g	(Ci) 10g	Std. Unc. (1g) (±%)	Std. Unc. (10g)(± %)	(Vi) Veff
Measurement System									
Probe Calibration	7.2.2.1	6	N	1	1	1	6	6	∞
Axial Isotropy	7.2.2.2	3	R	$\sqrt{3}$	$(1-C_p)^{1/2}$	$(1-C_p)^{1/2}$	1.22474	1.22474	8
Hemispherical Isotropy	7.2.2.2	5	R	$\sqrt{3}$	$\sqrt{C_p}$	$\sqrt{C_p}$	2.04124	2.04124	∞
Probe modulation response	7.2.2.4	0.5	R	$\sqrt{3}$	1	1	0.56542	0.56542	∞
Boundary Effects	7.2.2.6	1	R	$\sqrt{3}$	1	1	0.57735	0.57735	∞
Linearity	7.2.2.3	5	R	$\sqrt{3}$	1	1	2.88675	2.88675	∞
Detection Limits	7.2.2.5	1	R	$\sqrt{3}$	1	1	0.57735	0.57735	∞
Readout Electronics	7.2.2.7	0.5	N	1	1	1	0.5	0.5	∞
Response Time	7.2.2.8	0.2	R	$\sqrt{3}$	1	1	0.11547	0.11547	∞
Integration Time	7.2.2.9	2	R	$\sqrt{3}$	1	1	1.1547	1.1547	∞
RF ambient conditions-noise	7.2.4.5	3	R	$\sqrt{3}$	1	1	1.73205	1.73205	∞
RF ambient conditions-reflections	7.2.4.5	3	R	$\sqrt{3}$	1	1	1.73205	1.73205	∞
Probe Positioner Mechanical Tolerance	7.2.3.1	2	R	$\sqrt{3}$	1	1	1.1547	1.1547	∞
Probe Positioning with Respect to Phantom Shell	7.2.3.3	1	R	$\sqrt{3}$	1	1	0.57735	0.57735	∞
Extrapolation,interpolati on and Integration Algorithms for Max. SAR Evaluation	7.2.5.3	1.5	R	$\sqrt{3}$	1	1	0.86603	0.86603	∞
Test sample related									
Device holder uncertainty	7.2.3.4.2	1.0	N	1	1	1	1	1	N-1
Test sample positioning	7.2.3.4.3	2.6	N	1	1	1	2.6	2.6	N-1
Power scaling	L.3	2.0	R	$\sqrt{3}$	1	1	1.15	1.15	∞
Drift of output power (measured SAR Drift)	7.2.2.10	5.0	R	$\sqrt{3}$	1	1	2.89	2.89	∞
Phantom and Tissue Pa	rameters								
Phantom Uncertainty	7.2.3.2	4	R	$\sqrt{3}$	1	1	2.3094	2.3094	∞
Algorithm for correcting SAR for deviations in permittivity and conductivity	7.2.4.3	1,9	N	1	1	0.84	1,9	1,6	∞
Liquid Conductivity (meas.)	7.2.4.3	2.5	N	1	0.64	0.43	1.6	1.075	∞
Liquid Permittivity (meas.)	7.2.4.3	2.5	N	1	0.6	0.49	1.5	1.225	М
Liquid	7.2.4.4	3	R	$\sqrt{3}$	0.78	0.71	1.03923	0.8487	∞

permitticity-temperature uncertainty									
Liquid conductivity-temperatur e uncertainty	7.2.4.4	5	R	$\sqrt{3}$	0.23	0.26	1.84752	1.2413	8
Combined Standard Uncertainty	7.3.1		RSS				8.09272	7.9296	
Expanded Uncertainty (95%CONFIDENCE INTERVAL)	7.3.2		K=2				24.18544	20.8592	

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10. CONDUCTED POWER MEASUREMENT

Eroguonov		Measured Conducted Output power				
Frequency (MHz)	Channel Spacing	Max. Peak Power (dBm)	Avg. Power (dBm)			
400.025		36.85				
440.025	12.5KHz	36.92	36.62			
479.975		36.87	36.56			
400.025		36.91	36.61			
440.025	6.25KHz	36.93	36.65			
479.975		36.92	36.60			

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11. TEST RESULTS

11.1. SAR Test Results Summary

11.1.1. Test position and configuration

Head SAR was performed with the device configured in the positions according to KDB 643646 and Body SAR was performed with the device configurated with all accessories close to the Flat Phantom.

11.1.2. Operation Mode

Set the EUT to maximum output power level and transmit on lower, middle and top channel with 100% duty cycle individually during SAR measurement.

11.1.3. Co-located SAR

The following KDB was used for assessing this device. KDB 643646 and KDB 865664

The EUT only contains the Testing antenna, Standard battery and default body-worn accessory specified by customer. The earphone is only for testing

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11.1.4. Test Result

SAR MEASUREMENT

Ambient Temperature (°C): 21 ±2

Liquid Temperature (°C): 21 ±2

Liquid Temperature (°C): 21 ±2

Product: DPMR Digital Transceiver

Test Mode: Hold to Face with 2.5 cm separation(UHF)

	0.4 10 1 400 1	=		()					
Position	(MHz) (KHz) (<±5%)		SAR 1g with 100% duty Cycle (W/kg)	SAR 1g with 50% duty cycle (W/Kg)	Max. Turn-up Power (dBm)	Meas. output Power (dBm)	Scaled SAR (W/Kg)	Limit W/kg	
Face Up	400.025	12.5	1.02	6.806	3.403	37.00	36.54	3.783	8.0
Face Up	440.025	12.5	0.56	7.025	3.513	37.00	36.62	3.834	8.0
Face Up	479.975	12.5	-0.85	7.048	3.524	37.00	36.56	3.900	8.0
Face Up	400.025	6.25	0.49	6.387	3.194	37.00	36.61	3.494	8.0
Face Up	440.025	6.25	-2.01	6.468	3.234	37.00	36.65	3.505	8.0
Face Up	479.975	6.25	0.75	5.849	2.925	37.00	36.60	3.207	8.0

Note:

During the test, EUT power is 5 W with 100% duty cycle;

When the 1-g SAR of middle channel is ≤ 3.5 W/kg, testing for other channel is optional. refer to KDB 643646.

SAR MEASUREMENT	
Ambient Temperature (°C) : 21 ±2	Ambient Temperature (°C) : 21 ±2
Liquid Temperature (°C) : 21 ±2	Liquid Temperature (°C): 21 ±2

Product: DPMR Digital Transceiver

Test Mode: Body worn with all accessories(UHF)

1 Oot Mode. D	ody worm with	an accesso		/					
Position	Frequency (MHz)	Separati on (KHz)	Power Drift (<±5%)	SAR 1g with 100% duty Cycle (W/kg)	SAR 1g with 50% duty cycle (W/Kg)	Max. Turn-up Power (dBm)	Meas. output Power (dBm)	Scaled SAR (W/Kg)	Limit W/kg
Back Touch	400.025	12.5	-0.22	10.185	5.093	37.00	36.54	5.661	8.0
Back Touch	440.025	12.5	0.79	9.840	4.920	37.00	36.62	5.370	8.0
Back Touch	479.975	12.5	1.06	10.182	5.091	37.00	36.56	5.634	8.0
Back Touch	400.025	6.25	0.77	9.413	4.707	37.00	36.61	5.149	8.0
Back Touch	440.025	6.25	-0.62	10.265	5.133	37.00	36.65	5.564	8.0
Back Touch	479.975	6.25	-0.46	9.739	4.870	37.00	36.60	5.340	8.0

Note:

During the test, EUT power is 5 W with 100% duty cycle;

When the 1-g SAR of middle channel is ≤ 3.5 W/kg, testing for other channel is optional. refer to KDB 643646.

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Repeated SAR								
Ambient Temperature (°C): 21 ±2				Ambient Temperature (°C): 21 ±2				
Liquid Tempe	erature (°C) :	21 ±2		Liquid Temperature (°C): 21 ±2				
Product: DPN	Product: DPMR Digital Transceiver							
Test Mode: Body worn with all accessories(UHF)								
Position On Drift						Limit W/kg		
Back Touch	400.025	12.5	0.12	10.184	5.092			8.0
Back Touch	440.025	6.25	-1.05	10.251	5.126			8.0

APPENDIX A. SAR SYSTEM VALIDATION DATA

Test Laboratory: AGC Lab Date: Sep. 24,2014

System Check Body 450MHz DUT: Dipole 450 MHz Type: SID 450

Communication System: CW; Communication System Band: CW 450 MHz; Duty Cycle: 1:1; Conv.F=4.83 Frequency: 450 MHz; Medium parameters used: f = 450 MHz; $\sigma = 0.96$ mho/m; $\epsilon r = 56.93$; $\rho = 1000$ kg/m³;

Phantom Type: Elliptical Phantom; Input Power=30dBm Ambient temperature ($^{\circ}$ C): 21.0, Liquid temperature ($^{\circ}$ C): 21.0

SATIMO Configuration:

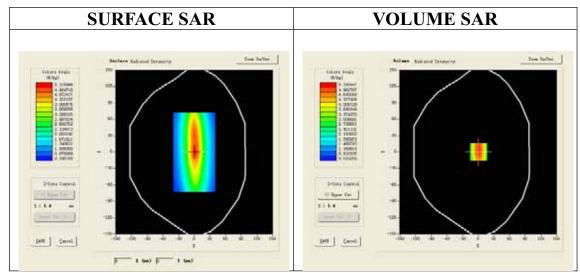
• Probe: SSE5; Calibrated: 01/12/2014; Serial No.:SN 22/12 EP159

· Sensor-Surface: 4mm (Mechanical Surface Detection)

Phantom: Flat Phantom; Type: Elliptical Phantom

Measurement SW: OpenSAR V4_02_0

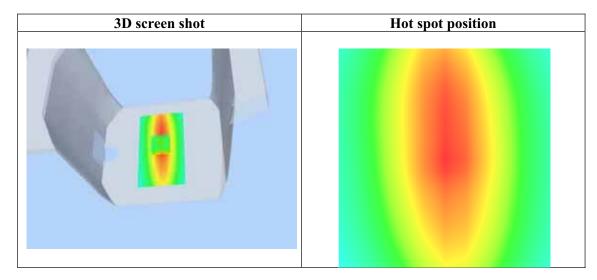
Configuration/System Check CW 450 MHz Body/Area Scan: Measurement grid: dx=8mm,dy=8mm Configuration/System Check CW 450 MHz Body /Zoom Scan: Measurement grid: dx=8mm,dy=8mm, dz=5mm,



Maximum location: X=1.00, Y=0.00

SAR 10g (W/Kg)	3.344711		
SAR 1g (W/Kg)	5.433312		

Z (mm)	0.00	4.00	9.00	14.00	19.00				
SAR (W/Kg)	0.0000	5.2804	3.2840	2.1205	1.4677				
_	SAR, Z Axis Scan $(X = 1, Y = 0)$								
5	i.3-								
4	5-								
R (#/kg)	.5-								
] = 3	.0-				-				
SAR 2	5-				-				
2	0 -		+		-				
1	.5-				_				
1	.0-				.				
		.0 7.5 10.0	12.5 15.0 17.9	5 20.0 22.5 25	5.0				
Z (mm)									



Test Laboratory: AGC Lab Date: Oct. 30,2014

System Check Body 450MHz DUT: Dipole 450 MHz Type: SID 450

Communication System: CW; Communication System Band: CW 450 MHz; Duty Cycle: 1:1; Conv.F=4.83 Frequency: 450 MHz; Medium parameters used: f = 450 MHz; $\sigma = 0.95$ mho/m; $\epsilon r = 56.33$; $\rho = 1000$ kg/m³;

Phantom Type: Elliptical Phantom; Input Power=30dBm

Ambient temperature (°C): 21.0, Liquid temperature (°C): 21.0

SATIMO Configuration:

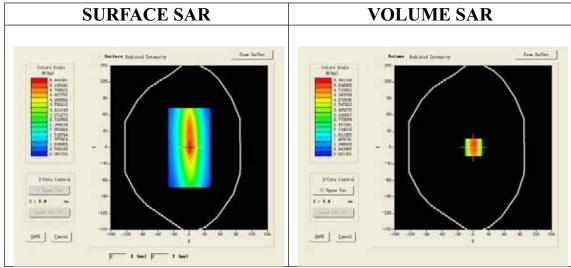
• Probe: SSE5; Calibrated: 01/12/2014; Serial No.:SN 22/12 EP159

· Sensor-Surface: 4mm (Mechanical Surface Detection)

· Phantom: Flat Phantom; Type: Elliptical Phantom

· Measurement SW: OpenSAR V4 02 0

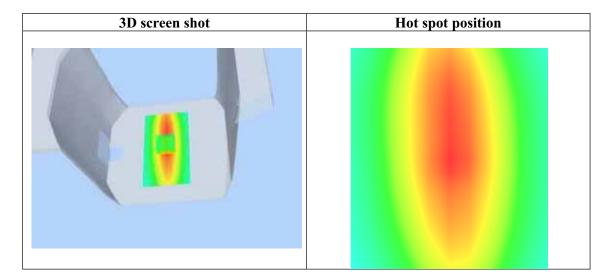
Configuration/System Check CW 450 MHz Body/Area Scan: Measurement grid: dx=8mm,dy=8mm Configuration/System Check CW 450 MHz Body /Zoom Scan: Measurement grid: dx=8mm,dy=8mm, dz=5mm,



Maximum location: X=1.00, Y=0.00

SAR 10g (W/Kg)	3.391024
SAR 1g (W/Kg)	5.515570

Z (mm)	0.00	4.00	9.00	14.00	19.00			
SAR (W/Kg)	0.0000	5.3615	3.3281	2.1462	1.4857			
	SAR, Z Axis Scan $(X = 1, Y = 0)$							
	5. 36 -							
,kg)	1.00-	+						
SAR (W/kg)	3. 00 -							
	2. 00 -			+	-			
1.06- 0.0 2.5 5.0 7.5 10.0 12.5 15.0 17.5 20.0 22.5 25.0 Z (mm)								



APPENDIX B. SAR MEASUREMENT DATA

Test Laboratory: AGC Lab Date: Sep. 24,2014

CW450 Low- Face up 2.5 cm separation (12.5 KHz)
DUT: DPMR Digital Transceiver; Type: DM-UVF10

Communication System: CW; Communication System Band: CW 450 MHz; Duty Cycle: 1:1; Conv.F=4.71 Frequency: 400.025MHz; Medium parameters used: f = 450 MHz; $\sigma = 0.86 mho/m$; $\epsilon r = 43.15$; $\rho = 1000 kg/m^3$;

Phantom Type: Elliptical Phantom

Ambient temperature (°C): 21.5, Liquid temperature (°C): 21.0

SATIMO Configuration:

Probe: SSE5; Calibrated: 01/12/2014; Serial No.:SN 22/12 EP159

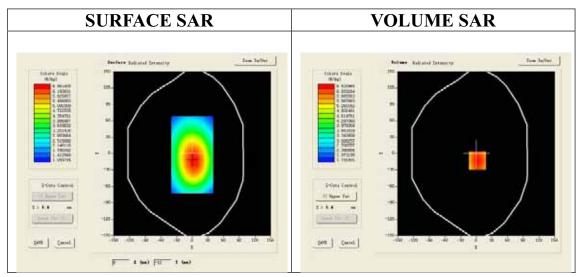
· Sensor-Surface: 4mm (Mechanical Surface Detection)

· Phantom: Flat Phantom; Type: Elliptical Phantom

Measurement SW: OpenSAR V4_02_0

Configuration/CW 450 for Low head/Area Scan: Measurement grid: dx=8mm, dy=8mm Configuration/CW 450 for Low head/Zoom Scan: Measurement grid: dx=8mm,dy=8mm,dz=5mm;

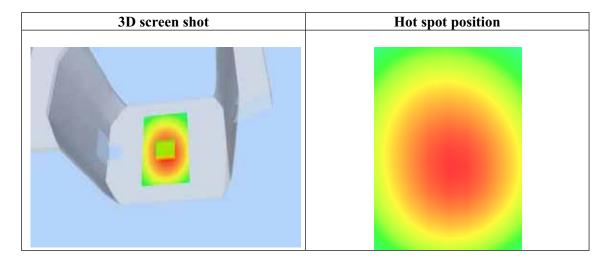
Area Scan	ep direct droit2 surf8mm.txt		
Zoom Scan	5x5x7,dx=8mm dy=8mm dz=5mm,Very fast		
Phantom	Elliptical Phantom		
Device Position	Face up 2.5 cm separation to Phantom		
Band	CW 450		
Channels	Low		
Signal	Crest factor: 1		



Maximum location: X=2.00, Y=-13.00

	,	
SAR 10g (W/Kg)	4.997359	
SAR 1g (W/Kg)	6.806027	

Z (mm)	0.00	4.00	9.00	14.00	19.00			
SAR (W/Kg)	0.0000	6.5210	4.9037	3.7195	2.8511			
	SAR, Z Axis Scan (X = 2, Υ = -13)							
e	6. 52 –							
6	5. 00 -				-			
		$ \ \ \ $						
/kg	j. 00 –							
. E ≪ 4	s. 00 -							
SAR								
3	3.00-	+ + +	++		-			
9	2. 16 -							
	0.0 2.5 5	5.0 7.5 10.0	12.5 15.0 17.	5 20.0 22.5 25	5.0			
Z (mm)								



CW450 Mid- Face up 2.5 cm separation (12.5 KHz) DUT: DPMR Digital Transceiver; Type: DM-UVF10

Communication System: CW; Communication System Band: CW 450 MHz; Duty Cycle: 1:1; Conv.F=4.71 Frequency: 440.025 MHz; Medium parameters used: f = 450 MHz; $\sigma = 0.87$ mho/m; $\epsilon r = 43.21$; $\rho = 1000$ kg/m³;

Phantom Type: Elliptical Phantom

Ambient temperature (°C): 21.5, Liquid temperature (°C): 21.0

SATIMO Configuration:

Probe: SSE5; Calibrated: 01/12/2014; Serial No.:SN 22/12 EP159

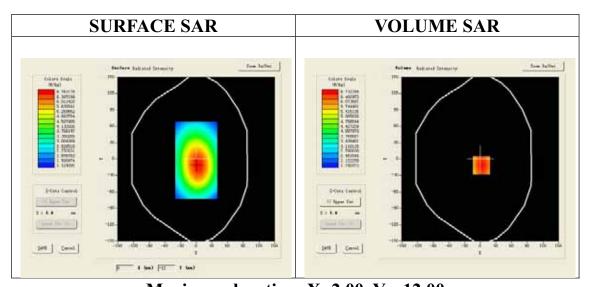
· Sensor-Surface: 4mm (Mechanical Surface Detection)

· Phantom: Flat Phantom; Type: Elliptical Phantom

· Measurement SW: OpenSAR V4_02_0

Configuration/CW 450 for Mid head/Area Scan: Measurement grid: dx=8mm, dy=8mm Configuration/CW 450 for Mid head/Zoom Scan: Measurement grid: dx=8mm, dy=8mm, dy=8mm, dy=8mm;

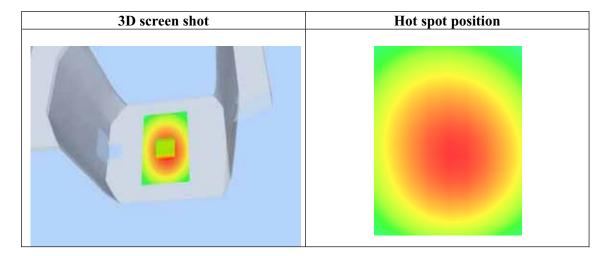
Area Scan	ep_direct_droit2_surf8mm.txt			
Zoom Scan	5x5x7,dx=8mm dy=8mm dz=5mm,Very fast			
Phantom	Elliptical Phantom			
Device Position	Face up 2.5 cm separation to Phantom			
Band	CW 450			
Channels	Middle			
Signal	Crest factor: 1			



Maximum location: X=2.00, Y=-12.00

SAR 10g (W/Kg)	5.152080
SAR 1g (W/Kg)	7.025173

Z (mm)	0.00	4.00	9.00	14.00	19.00
SAR (W/Kg)	0.0000	6.7323	5.0629	3.8401	2.9429
	SAR, Z	Axis Scan	(X = 2, Y)	7 = −12)	
6	. 73 –				
ε	. 00 -	\longrightarrow			.
(W/kg)	i. 00 –				
	. 00 -				
3	3.00-		++		
2	2.23- 0.0 2.5 5	5.0 7.5 10.0	12.5 15.0 17.	5 20.0 22.5 25	5.0
			Z (mm)		
					_



CW450 High- Face up 2.5 cm separation (12.5 KHz) DUT: DPMR Digital Transceiver; Type: DM-UVF10

Communication System: CW; Communication System Band: CW 450 MHz; Duty Cycle: 1:1; Conv.F=4.71 Frequency: 479.975MHz; Medium parameters used: f = 450 MHz; $\sigma = 0.84 mho/m$; $\epsilon r = 42.87$; $\rho = 1000 kg/m^3$;

Phantom Type: Elliptical Phantom

Ambient temperature (°C): 21.5, Liquid temperature (°C): 21.0

SATIMO Configuration:

Probe: SSE5; Calibrated: 01/12/2014; Serial No.:SN 22/12 EP159

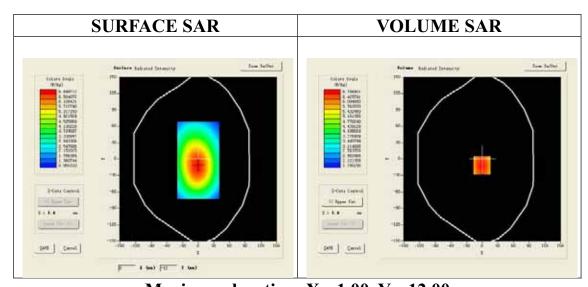
· Sensor-Surface: 4mm (Mechanical Surface Detection)

· Phantom: Flat Phantom; Type: Elliptical Phantom

· Measurement SW: OpenSAR V4_02_0

Configuration/CW 450 for High head/Area Scan: Measurement grid: dx=8mm, dy=8mm Configuration/CW 450 for High head/Zoom Scan: Measurement grid: dx=8mm, dy=8mm, dz=5mm;

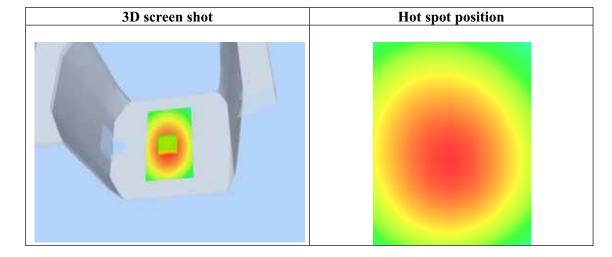
Area Scan	ep_direct_droit2_surf8mm.txt		
Zoom Scan	5x5x7,dx=8mm dy=8mm dz=5mm,Very fast		
Phantom	Elliptical Phantom		
Device Position	Face up 2.5 cm separation to Phantom		
Band	CW 450		
Channels	High		
Signal	Crest factor: 1		



Maximum location: X=-1.00, Y=-12.00

SAR 10g (W/Kg)	5.144520
SAR 1g (W/Kg)	7.048259

Z (mm)	0.00	4.00	9.00	14.00	19.00
SAR (W/Kg)	0.0000	6.7505	5.0483	3.8075	2.9055
	SAR, Z	Axis Scan	(X = −1,	Y = -12)	
e	5. 76 -				
e	5. 00 -	\longrightarrow			-
(W/kg)	5. 00 -				-
SAR	1.00-				1
3	3. 00 -				-
2	2.20- 0.0 2.5 5	5.0 7.5 10.0	12.5 15.0 17.	5 20.0 22.5 25	5. 0
			Z (mm)		
					_



Test Laboratory: AGC Lab Date: Oct. 30,2014

CW450 Low -Body -Touch (12.5 KHz)

DUT: DPMR Digital Transceiver; Type: DM-UVF10

Communication System: CW; Communication System Band: CW 450 MHz; Duty Cycle: 1:1; Conv.F=4.83 Frequency: 400.025MHz; Medium parameters used: f = 450 MHz; $\sigma = 0.94$ mho/m; $\epsilon r = 56.62$; $\rho = 1000$ kg/m³;

Phantom Type: Elliptical Phantom

Ambient temperature (°ℂ): 21.5, Liquid temperature(°ℂ): 21.0

SATIMO Configuration:

Probe: SSE5; Calibrated: 01/12/2014; Serial No.:SN 22/12 EP159

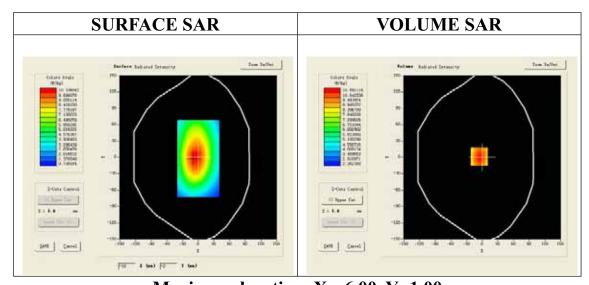
· Sensor-Surface: 4mm (Mechanical Surface Detection)

· Phantom: Flat Phantom; Type: Elliptical Phantom

· Measurement SW: OpenSAR V4_02_0

Configuration/CW 450 for Low Touch/Area Scan: Measurement grid: dx=8mm, dy=8mm Configuration/CW 450 for Low Touch/Zoom Scan: Measurement grid: dx=8mm, dy=8mm, dz=5mm,

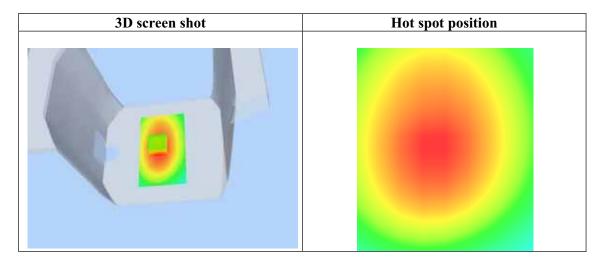
Area Scan	ep_direct_droit2_surf8mm.txt			
Zoom Scan	5x5x7,dx=8mm dy=8mm dz=5mm,Very fast			
Phantom	Elliptical Phantom			
Device Position	Back close to Phantom with Accessories			
Band	CW 450			
Channels	Low			
Signal	Crest factor: 1			



Maximum location: X=-6.00, Y=1.00

SAR 10g (W/Kg)	7.219841
SAR 1g (W/Kg)	10.185162

Z (mm) SAR (W/Kg)	0.00 0.0000	4.00 10.5916	9.00 7.7137	14.00 5.6949	19.00 4.2820
	I	l	_	_	1,11011
	SAK, Z	AXIS SCAL	$\mathbf{X} = -6,$	1 – 1)	
1	.0.59-				
	9.00-	\longrightarrow			
	8.00-	$+\lambda$			
(W/kg)	7.00-	++			-
SAR	6.00-				-
	5.00-				-
	4.00-	+ + +			-
	3.20- 0.0 2.5		12 5 15 0 17	5 20.0 22.5 25	5.0
	0.0 2.0		Z (mm)	0 20.0 22.0 20	



Test Laboratory: AGC Lab Date: Oct. 30,2014

CW450 Mid -Body -Touch (12.5 KHz)

DUT: DPMR Digital Transceiver; Type: DM-UVF10

Communication System: CW; Communication System Band: CW 450 MHz; Duty Cycle: 1:1; Conv.F=4.83 Frequency: 440.025 MHz; Medium parameters used: f = 450 MHz; $\sigma = 0.95$ mho/m; $\epsilon r = 56.33$; $\rho = 1000$ kg/m³;

Phantom Type: Elliptical Phantom

Ambient temperature (°ℂ): 21.5, Liquid temperature(°ℂ): 21.0

SATIMO Configuration:

Probe: SSE5; Calibrated: 01/12/2014; Serial No.:SN 22/12 EP159

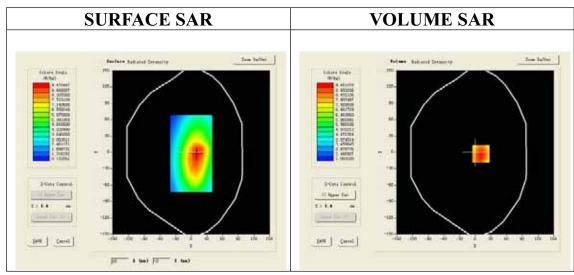
· Sensor-Surface: 4mm (Mechanical Surface Detection)

· Phantom: Flat Phantom; Type: Elliptical Phantom

· Measurement SW: OpenSAR V4_02_0

Configuration/CW 450 for Mid Touch/Area Scan: Measurement grid: dx=8mm, dy=8mm Configuration/CW 450 for Mid Touch/Zoom Scan: Measurement grid: dx=8mm, dy=8mm, dz=5mm,

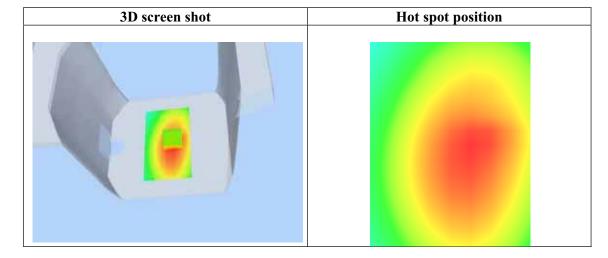
Area Scan	ep_direct_droit2_surf8mm.txt			
Zoom Scan	5x5x7,dx=8mm dy=8mm dz=5mm,Very fast			
Phantom	Elliptical Phantom			
Device Position	Back close to Phantom with Accessories			
Band	CW 450			
Channels	Middle			
Signal	Crest factor: 1			



Maximum location: X=11.00, Y=-3.00

SAR 10g (W/Kg)	6.919956
SAR 1g (W/Kg)	9.839877

Z (mm)	0.00	4.00	9.00	14.00	19.00
SAR (W/Kg)	0.0000	9.4521	6.8489	5.0186	3.7385
	SAR, Z	Axis Scan	(X = 11,	Y = -3)	
9	9. 45 -				
8	3. 00 -				
(2) 7	7. 00 – 3. 00 –	$\vdash \land$			
ළි ි ෙ	3.00-	+	+		-
SAR 5	5. 00 -				
	1.00-		+		
2	2.76 - 0.0 2.5 5	5.0 7.5 10.0	12.5 15.0 17.	5 20.0 22.5 25	- 5. o
	Z (mm)				
					-



Test Laboratory: AGC Lab Date: Oct. 30,2014

CW450 High -Body -Touch (12.5 KHz)

DUT: DPMR Digital Transceiver; Type: DM-UVF10

Communication System: CW; Communication System Band: CW 450 MHz; Duty Cycle: 1:1; Conv.F=4.83 Frequency: 479.975MHz; Medium parameters used: f = 450 MHz; $\sigma = 0.95$ mho/m; $\epsilon = 56.49$; $\rho = 1000$ kg/m³;

Phantom Type: Elliptical Phantom

Ambient temperature (°ℂ): 21.5, Liquid temperature(°ℂ): 21.0

SATIMO Configuration:

Probe: SSE5; Calibrated: 01/12/2014; Serial No.:SN 22/12 EP159

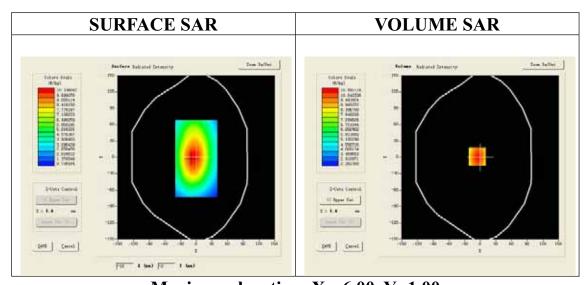
· Sensor-Surface: 4mm (Mechanical Surface Detection)

· Phantom: Flat Phantom; Type: Elliptical Phantom

· Measurement SW: OpenSAR V4_02_0

Configuration/CW 450 for High Touch/Area Scan: Measurement grid: dx=8mm, dy=8mm Configuration/CW 450 for High Touch/Zoom Scan: Measurement grid: dx=8mm, dy=8mm, dz=5mm,

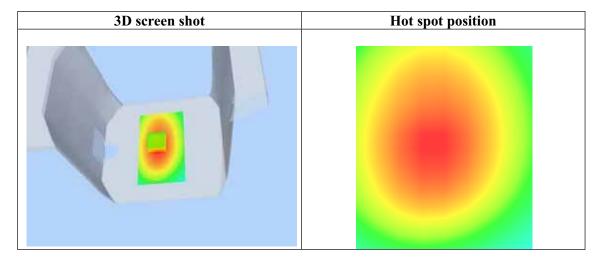
Area Scan	ep_direct_droit2_surf8mm.txt			
Zoom Scan	5x5x7,dx=8mm dy=8mm dz=5mm,Very fast			
Phantom	Elliptical Phantom			
Device Position	Back close to Phantom with Accessories			
Band	CW 450			
Channels	High			
Signal	Crest factor: 1			



Maximum location: X=-6.00, Y=1.00

SAR 10g (W/Kg)	7.218479
SAR 1g (W/Kg)	10.181613

Z (mm)	0.00	4.00	9.00	14.00	19.00
SAR (W/Kg)	0.0000	10.5920	7.7138	5.6949	4.2816
	SAR, 2	Z Axis Scan	(X = -6,	Y = 1)	
1	0.59-				
	9.00-	\longrightarrow			_
(W/kg)	8.00-	+ N			-
≥ ≥	7.00-	+	+	-+-	-
SAR	6.00-				-
	5.00-	+			-
	4.00-	\perp			
	3.20-				
		5.0 7.5 10.0	12.5 15.0 17.	5 20.0 22.5 25	5.0
			Z (mm)		
					_



CW450 Low- Face up 2.5 cm separation (6.25 KHz) DUT: DPMR Digital Transceiver; Type: DM-UVF10

Communication System: CW; Communication System Band: CW 450 MHz; Duty Cycle: 1:1; Conv.F=4.71 Frequency: 400.025MHz; Medium parameters used: f = 450 MHz; $\sigma = 0.86$ mho/m; $\epsilon r = 43.15$; $\rho = 1000$ kg/m³;

Phantom Type: Elliptical Phantom

Ambient temperature (°C): 21.5, Liquid temperature (°C): 21.0

SATIMO Configuration:

Probe: SSE5; Calibrated: 01/12/2014; Serial No.:SN 22/12 EP159

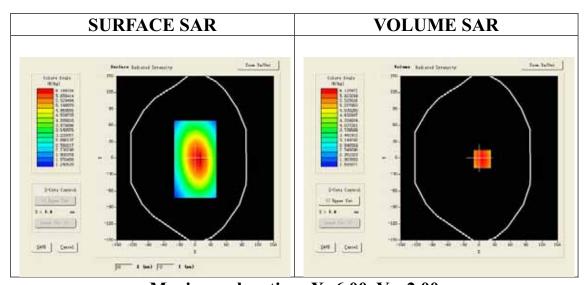
· Sensor-Surface: 4mm (Mechanical Surface Detection)

· Phantom: Flat Phantom; Type: Elliptical Phantom

· Measurement SW: OpenSAR V4_02_0

Configuration/CW 450 for Low head/Area Scan: Measurement grid: dx=8mm, dy=8mm Configuration/CW 450 for Low head/Zoom Scan: Measurement grid: dx=8mm,dy=8mm,dz=5mm;

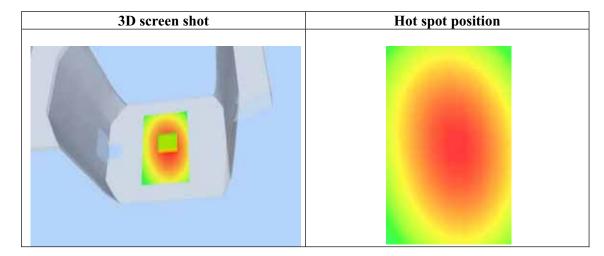
Area Scan	ep_direct_droit2_surf8mm.txt		
Zoom Scan	5x5x7,dx=8mm dy=8mm dz=5mm,Very fast		
Phantom	Elliptical Phantom		
Device Position	Face up 2.5 cm separation to Phantom		
Band	CW 450		
Channels	Low		
Signal	Crest factor: 1		



Maximum location: X=6.00, Y=-2.00

SAR 10g (W/Kg)	4.691344
SAR 1g (W/Kg)	6.386660

Z (mm)	0.00	4.00	9.00	14.00	19.00
SAR (W/Kg)	0.0000	6.1210	4.5903	3.4723	2.6545
	SAR, Z	Axis Scan	(X = 6,	y = −2)	
6	. 1 -				
5	.5-	\longrightarrow			
5	.0-	+	\perp		-
(%//kg) 4	.5-	+	+		-
	.0-		+		-
SAR 3	.5-		\longrightarrow		-
	.0-		+		-
2	.5-			\rightarrow	-
2	.0-				
	0.0 2.5 5		12.5 15.0 17.	5 20.0 22.5 25	5.0



CW450 Mid- Face up 2.5 cm separation (6.25 KHz) DUT: DPMR Digital Transceiver; Type: DM-UVF10

Communication System: CW; Communication System Band: CW 450 MHz; Duty Cycle: 1:1; Conv.F=4.71 Frequency: 440.025 MHz; Medium parameters used: f = 450 MHz; $\sigma = 0.87$ mho/m; $\epsilon r = 43.21$; $\rho = 1000$ kg/m³;

Phantom Type: Elliptical Phantom

Ambient temperature (°C): 21.5, Liquid temperature (°C): 21.0

SATIMO Configuration:

Probe: SSE5; Calibrated: 01/12/2014; Serial No.:SN 22/12 EP159

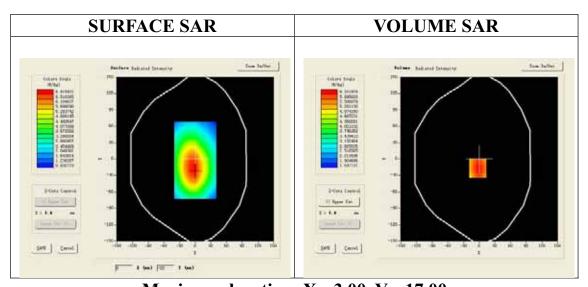
· Sensor-Surface: 4mm (Mechanical Surface Detection)

· Phantom: Flat Phantom; Type: Elliptical Phantom

· Measurement SW: OpenSAR V4_02_0

Configuration/CW 450 for Mid head/Area Scan: Measurement grid: dx=8mm, dy=8mm Configuration/CW 450 for Mid head/Zoom Scan: Measurement grid: dx=8mm, dy=8mm, dy=8mm, dy=8mm;

Area Scan	ep_direct_droit2_surf8mm.txt		
Zoom Scan	5x5x7,dx=8mm dy=8mm dz=5mm,Very fast		
Phantom	Elliptical Phantom		
Device Position	Face up 2.5 cm separation to Phantom		
Band	CW 450		
Channels	Middle		
Signal	Crest factor: 1		



Maximum location: X=-3.00, Y=-17.00

SAR 10g (W/Kg)	4.725829
SAR 1g (W/Kg)	6.468305

Z (mm)	0.00	4.00	9.00	14.00	19.00	
SAR (W/Kg)	0.0000	6.2062	4.6328	3.4941	2.6670	
	SAR, Z	Axis Scan	(X = −3,	Y = -17)		
e	5.2-					
5	5.5-	\longrightarrow				
5	5.0-	+	+		-	
(W/kg)	1.5-	+				
			$\downarrow \downarrow \downarrow \downarrow$			
SAR	3.5-		\rightarrow		_	
	3.0-		\perp		_	
	2.5-					
	2.0-					
		.0 7.5 10.0	12.5 15.0 17.	5 20.0 22.5 25	5.0	
	Z (mm)					



CW450 High- Face up 2.5 cm separation (6.25 KHz) DUT: DPMR Digital Transceiver; Type: DM-UVF10

Communication System: CW; Communication System Band: CW 450 MHz; Duty Cycle: 1:1; Conv.F=4.71 Frequency: 479.975MHz; Medium parameters used: f = 450 MHz; $\sigma = 0.84 \text{ mho/m}$; $\epsilon r = 42.87$; $\rho = 1000 \text{ kg/m}^3$;

Phantom Type: Elliptical Phantom

Ambient temperature (°C): 21.5, Liquid temperature (°C): 21.0

SATIMO Configuration:

Probe: SSE5; Calibrated: 01/12/2014; Serial No.:SN 22/12 EP159

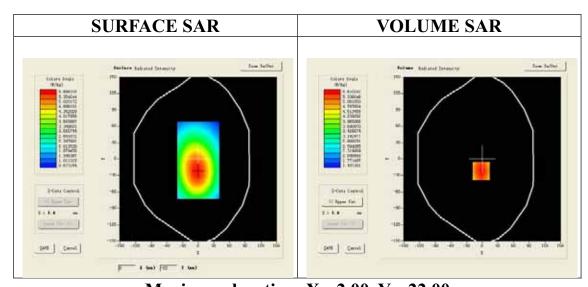
· Sensor-Surface: 4mm (Mechanical Surface Detection)

· Phantom: Flat Phantom; Type: Elliptical Phantom

· Measurement SW: OpenSAR V4_02_0

Configuration/CW 450 for High head/Area Scan: Measurement grid: dx=8mm, dy=8mm Configuration/CW 450 for High head/Zoom Scan: Measurement grid: dx=8mm, dy=8mm, dz=5mm;

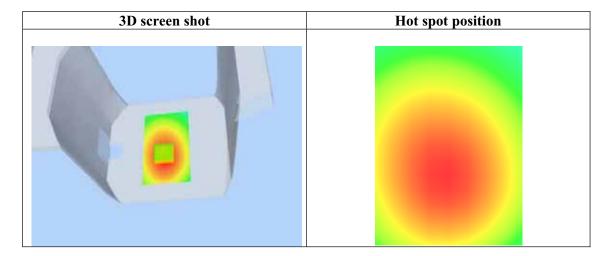
Area Scan	ep_direct_droit2_surf8mm.txt		
Zoom Scan	5x5x7,dx=8mm dy=8mm dz=5mm,Very fast		
Phantom	Elliptical Phantom		
Device Position	Face up 2.5 cm separation to Phantom		
Band	CW 450		
Channels	High		
Signal	Crest factor: 1		



Maximum location: X=-2.00, Y=-22.00

SAR 10g (W/Kg)	4.279238
SAR 1g (W/Kg)	5.849417

Z (mm)	0.00	4.00	9.00	14.00	19.00		
SAR (W/Kg)	0.0000	5.6162	4.1942	3.1655	2.4176		
	SAR, Z	Axis Scan	(X = −2,	y = −22)			
5	5.6-				-		
5	5. 0 -	\longrightarrow					
4	1.5-	$+\lambda+$	+ + +		-		
//kg	i. 0 -	++			-		
ළි _ජ 3	3.5-	 	+		-		
SAR (#/kg)	3.0-		\rightarrow		-		
	2.5-	+	++		-		
	8-						
1		.0 7.5 10.0	12.5 15.0 17.	5 20.0 22.5 25	5.0		
	Z (mm)						



CW450 Low -Body -Touch (6.25 KHz)

DUT: DPMR Digital Transceiver; Type: DM-UVF10

Communication System: CW; Communication System Band: CW 450 MHz; Duty Cycle: 1:1; Conv.F=4.83 Frequency: 400.025MHz; Medium parameters used: f = 450 MHz; $\sigma = 0.92$ mho/m; $\epsilon r = 56.56$; $\rho = 1000$ kg/m³;

Phantom Type: Elliptical Phantom

Ambient temperature (°ℂ): 21.5, Liquid temperature(°ℂ): 21.0

SATIMO Configuration:

Probe: SSE5; Calibrated: 01/12/2014; Serial No.:SN 22/12 EP159

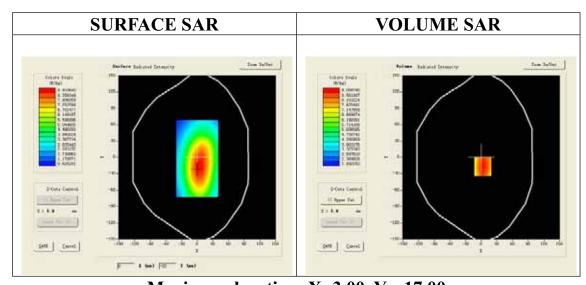
· Sensor-Surface: 4mm (Mechanical Surface Detection)

· Phantom: Flat Phantom; Type: Elliptical Phantom

· Measurement SW: OpenSAR V4_02_0

Configuration/CW 450 for Low Touch/Area Scan: Measurement grid: dx=8mm, dy=8mm Configuration/CW 450 for Low Touch/Zoom Scan: Measurement grid: dx=8mm, dy=8mm, dz=5mm,

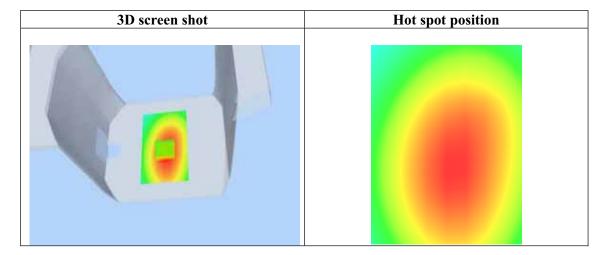
Area Scan	ep_direct_droit2_surf8mm.txt			
Zoom Scan	5x5x7,dx=8mm dy=8mm dz=5mm,Very fast			
Phantom	Elliptical Phantom			
Device Position	Back close to Phantom with Accessories			
Band	CW 450			
Channels	Low			
Signal	Crest factor: 1			



Maximum location: X=3.00, Y=-17.00

SAR 10g (W/Kg)	6.621043
SAR 1g (W/Kg)	9.413088

Z (mm)	0.00	4.00	9.00	14.00	19.00
SAR (W/Kg)	0.0000	9.0579	6.5142	4.7456	3.5227
	SAR, Z	Axis Scan	(X = 3, 7)	7 = -17)	
6	9. 06 -				-
8	3.00-	\longrightarrow			-
	7.00-	$+\lambda$	$\overline{}$		-
(¥/kg	7. 00 -	++	+		
SAR	5. 00 -				-
4	1.00-			\leftarrow	
2	2.59- 0.0 2.5 5			5 20.0 22.5 25	5.0
			Z (mm)		



CW450 Mid -Body -Touch (6.25 KHz)

DUT: DPMR Digital Transceiver; Type: DM-UVF10

Communication System: CW; Communication System Band: CW 450 MHz; Duty Cycle: 1:1; Conv.F=4.83 Frequency: 440.025 MHz; Medium parameters used: f = 450 MHz; $\sigma = 0.93$ mho/m; $\epsilon r = 56.34$; $\rho = 1000$ kg/m³;

Phantom Type: Elliptical Phantom

Ambient temperature (°ℂ): 21.5, Liquid temperature(°ℂ): 21.0

SATIMO Configuration:

Probe: SSE5; Calibrated: 01/12/2014; Serial No.:SN 22/12 EP159

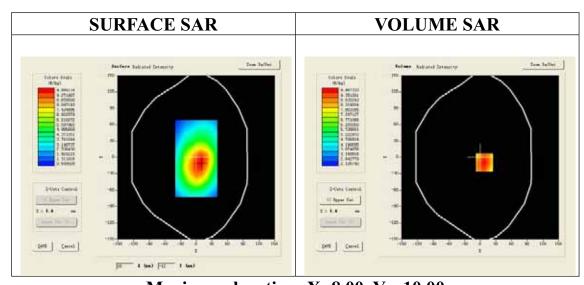
· Sensor-Surface: 4mm (Mechanical Surface Detection)

· Phantom: Flat Phantom; Type: Elliptical Phantom

· Measurement SW: OpenSAR V4_02_0

Configuration/CW 450 for Mid Touch/Area Scan: Measurement grid: dx=8mm, dy=8mm Configuration/CW 450 for Mid Touch/Zoom Scan: Measurement grid: dx=8mm, dy=8mm, dz=5mm,

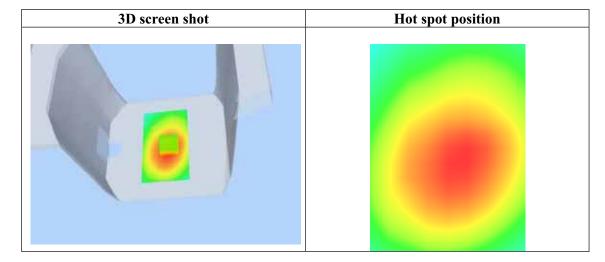
Area Scan	ep_direct_droit2_surf8mm.txt			
Zoom Scan	5x5x7,dx=8mm dy=8mm dz=5mm,Very fast			
Phantom	Elliptical Phantom			
Device Position	Back close to Phantom with Accessories			
Band	CW 450			
Channels	Middle			
Signal	Crest factor: 1			



Maximum location: X=8.00, Y=-10.00

SAR 10g (W/Kg)	7.315766
SAR 1g (W/Kg)	10.265174

Z (mm)	0.00	4.00	9.00	14.00	19.00
SAR (W/Kg)	0.0000	9.8659	7.2628	5.3937	4.0526
	SAR, Z	Axis Scan	(X = 8, Y)	y = −10)	
9). 87 –				
9	0.00-	\longrightarrow	\perp		-
8	3. 00 -				
- To	7. 00 -	+			_
	5. 00 -		$\downarrow \downarrow \downarrow \downarrow$		-
20,5	5. 00 -	+			-
4	i. 00 –		+	\leftarrow	-
3	3. 01 -				
	0.0 2.5 5		12.5 15.0 17. Z (mm)	5 20.0 22.5 25	5.0



CW450 High -Body -Touch (6.25 KHz)

DUT: DPMR Digital Transceiver; Type: DM-UVF10

Communication System: CW; Communication System Band: CW 450 MHz; Duty Cycle: 1:1; Conv.F=4.83 Frequency: 479.975MHz; Medium parameters used: f = 450 MHz; $\sigma = 0.92$ mho/m; $\epsilon r = 56.27$; $\rho = 1000$ kg/m³;

Phantom Type: Elliptical Phantom

Ambient temperature (°ℂ): 21.5, Liquid temperature(°ℂ): 21.0

SATIMO Configuration:

Probe: SSE5; Calibrated: 01/12/2014; Serial No.:SN 22/12 EP159

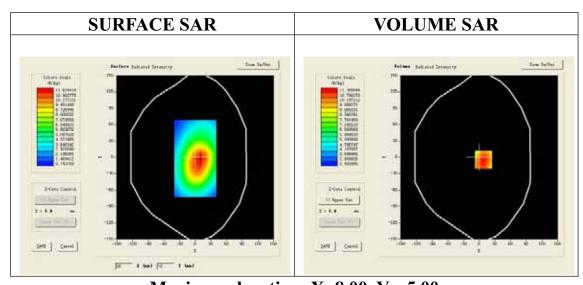
· Sensor-Surface: 4mm (Mechanical Surface Detection)

· Phantom: Flat Phantom; Type: Elliptical Phantom

· Measurement SW: OpenSAR V4_02_0

Configuration/CW 450 for High Touch/Area Scan: Measurement grid: dx=8mm, dy=8mm Configuration/CW 450 for High Touch/Zoom Scan: Measurement grid: dx=8mm, dy=8mm, dz=5mm,

Area Scan	ep_direct_droit2_surf8mm.txt			
Zoom Scan	5x5x7,dx=8mm dy=8mm dz=5mm,Very fast			
Phantom	Elliptical Phantom			
Device Position	Back close to Phantom with Accessories			
Band	CW 450			
Channels	High			
Signal	Crest factor: 1			



Maximum location: X=8.00, Y=-5.00

SAR 10g (W/Kg)	7.039075
SAR 1g (W/Kg)	9.738879

Z (mm)	0.00	4.00	9.00	14.00	19.00
SAR (W/Kg)	0.0000	10.1162	7.4775	5.5897	4.2399
:	1	Axis Scan	l		4.2399
SAR (W/kg)	7. 00 - 6. 00 - 5. 00 -		12.5 15.0 17. Z (mm)	5 20.0 22.5 25	5.0



Repeated SAR

Test Laboratory: AGC Lab Date: Oct. 30,2014

CW450 Low -Body -Touch (12.5 KHz)

DUT: DPMR Digital Transceiver; Type: DM-UVF10

Communication System: CW; Communication System Band: CW 450 MHz; Duty Cycle: 1:1; Conv.F=4.83 Frequency: 400.025 MHz; Medium parameters used: f = 450 MHz; $\sigma = 0.94 mho/m$; $\epsilon r = 56.62$; $\rho = 1000 kg/m^3$;

Phantom Type: Elliptical Phantom

Ambient temperature ($^{\circ}$ C): 21.5, Liquid temperature($^{\circ}$ C): 21.0

SATIMO Configuration:

Probe: SSE5; Calibrated: 01/12/2014; Serial No.:SN 22/12 EP159

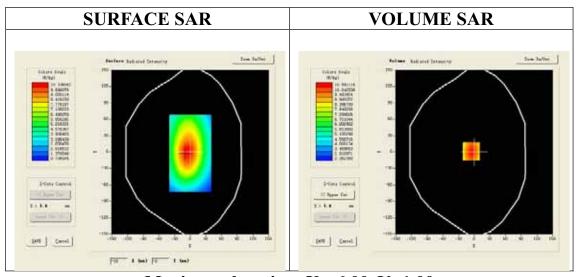
· Sensor-Surface: 4mm (Mechanical Surface Detection)

· Phantom: Flat Phantom; Type: Elliptical Phantom

Measurement SW: OpenSAR V4_02_0

Configuration/CW 450 for Low Touch/Area Scan: Measurement grid: dx=8mm, dy=8mm Configuration/CW 450 for Low Touch/Zoom Scan: Measurement grid: dx=8mm, dy=8mm, dz=5mm,

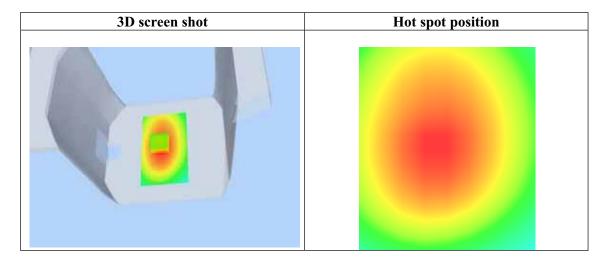
Area Scan	ep_direct_droit2_surf8mm.txt		
Zoom Scan	5x5x7,dx=8mm dy=8mm dz=5mm,Very fast		
Phantom	Elliptical Phantom		
Device Position	Back close to Phantom with Accessories		
Band	CW 450		
Channels	Low		
Signal	Crest factor: 1		



Maximum location: X=-6.00, Y=1.00

SAR 10g (W/Kg)	7.201620
SAR 1g (W/Kg)	10.184245

.0000	10.5923	/ / 1 311		
		7.7130	5.6952	4.2814
SAR. Z A	xis Scan	(X = -6,	Y = 1)	
,		. (/	
				1
	$\overline{}$	+		1
	\rightarrow	+		4
				1
		\		
	\rightarrow			1
				+
.0 2.5 5.0	0 7.5 10.0	12.5 15.0 17.	5 20.0 22.5 25	5.0
	:	Z (mm)		
	0 2.5 5.		0 2.5 5.0 7.5 10.0 12.5 15.0 17.5 Z (mm)	



CW450 Mid -Body -Touch (6.25 KHz)

DUT: DPMR Digital Transceiver; Type: DM-UVF10

Communication System: CW; Communication System Band: CW 450 MHz; Duty Cycle: 1:1; Conv.F=4.83 Frequency: 440.025 MHz; Medium parameters used: f = 450 MHz; $\sigma = 0.93$ mho/m; $\epsilon r = 56.34$; $\rho = 1000$ kg/m³;

Phantom Type: Elliptical Phantom

Ambient temperature (°ℂ): 21.5, Liquid temperature(°ℂ): 21.0

SATIMO Configuration:

Probe: SSE5; Calibrated: 01/12/2014; Serial No.:SN 22/12 EP159

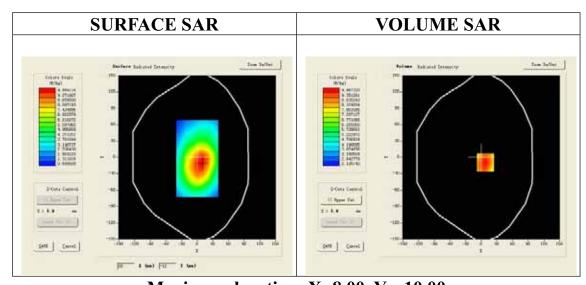
· Sensor-Surface: 4mm (Mechanical Surface Detection)

· Phantom: Flat Phantom; Type: Elliptical Phantom

· Measurement SW: OpenSAR V4_02_0

Configuration/CW 450 for Mid Touch/Area Scan: Measurement grid: dx=8mm, dy=8mm Configuration/CW 450 for Mid Touch/Zoom Scan: Measurement grid: dx=8mm, dy=8mm, dz=5mm,

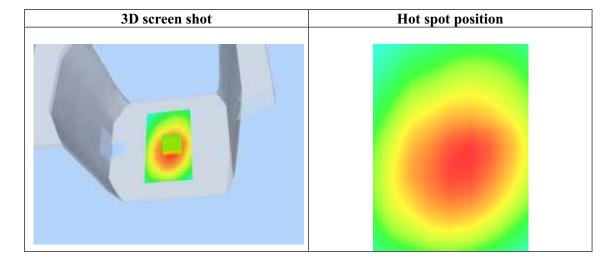
Area Scan	ep_direct_droit2_surf8mm.txt				
Zoom Scan	5x5x7,dx=8mm dy=8mm dz=5mm,Very fast				
Phantom	Elliptical Phantom				
Device Position	Back close to Phantom with Accessories				
Band	CW 450				
Channels	Middle				
Signal	Crest factor: 1				



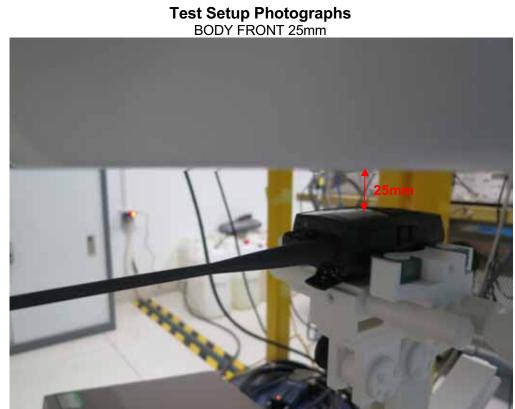
Maximum location: X=8.00, Y=-10.00

SAR 10g (W/Kg)	7.303752
SAR 1g (W/Kg)	10.251346

Z (mm)	0.00	4.00	9.00	14.00	19.00		
SAR (W/Kg)	0.0000	9.8665	7.2634	5.3958	4.0497		
SAR, Z Axis Scan (X = 8, Y = -10)							
9). 87 –						
9	0.00-	$\overline{}$			-		
8	3. 00 -						
	7.00-						
SAR (W/kg)	5.00-		+		-		
2,6	5. 00 -				-		
4	ł. 00 –		+		-		
3	3.01-			5 00 0 00 5 00			
0.0 2.5 5.0 7.5 10.0 12.5 15.0 17.5 20.0 22.5 25.0 Z (mm)							



APPENDIX C. TEST SETUP PHOTOGRAPHS & EUT PHOTOGRAPHS







DEPTH OF THE LIQUID IN THE PHANTOM—ZOOM IN

Note: The position used in the measurement were according to IEEE 1528-2003



EUT PHOTOGRAPHS

TOTAL VIEW OF EUT



TOP VIEW OF EUT



BOTTOM VIEW OF EUT



FRONT VIEW OF EUT



BACK VIEW OF EUT



LEFT VIEW OF EUT



RIGHT VIEW OF EUT



OPEN VIEW OF EUT-1



OPEN VIEW OF EUT-2



INTERNAL VIEW OF EUT-1



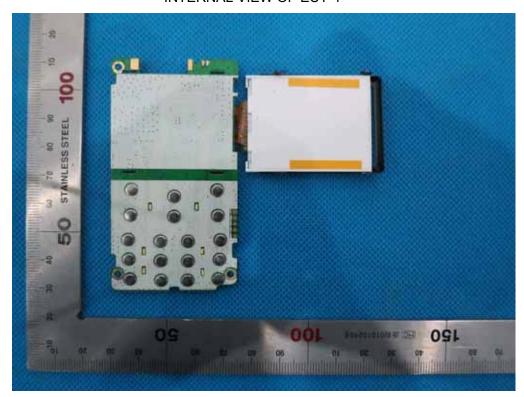
INTERNAL VIEW OF EUT-2



INTERNAL VIEW OF EUT-3



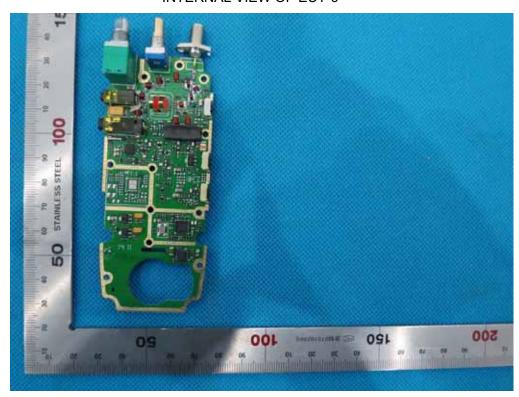
INTERNAL VIEW OF EUT-4



INTERNAL VIEW OF EUT-5



INTERNAL VIEW OF EUT-6



INTERNAL VIEW OF EUT-7

