#### **HYUNDAI CALIBRATION & CERTIFICATION TECH. CO., LTD.**



PRODUCT COMPLIANCE DIVISION SAN 136-1, AMI-RI, BUBAL-EUP, ICHEON-SI, KYOUNGKI-DO, 467-701, KOREA

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### HEARING AID COMPATIBILITY CERTIFICATE

HYUNDAI CURITEL INC.

SAN 136-1, AMI-RI, BUBAL-EUP, ICHEON-SI,

KYOUNGKI-DO, 467-701, KOREA

FRN: 0006278469

Date of Issue: October 07, 2005 Test Report No.: HCT-SAR05-1003

Test Site: HYUNDAI CALIBRATION & CERTIFICATION

TECHNOLOGIES CO., LTD.

FRN: 0005866421

FCC ID : PP4TX-230

APPLICANT: HYUNDAI CURITEL INC.

**Application Type:** Class II Permissive Change (Adding HAC Rating)

Change of contents: Case/ Camera / LCD Module have been changed

**EUT Type:** Dual-Mode CDMA Phone (CDMA/ PCS CDMA) - Prototype

Tx Frequency: 824.70 — 848.31 MHz (CDMA)

1851.25 — 1908.75 MHz (PCS CDMA)

Maximum Conducted 0.316W CDMA (25.0dBm) Power (EMC/SAR/HAC): 0.316W PCS CDMA (25.0dBm)

HYUNDAI / TX-230 Trade Name/Model(s):

FCC Classification: Licensed Portable Transmitter Held to Ear (PCE)

FCC Rule Part(s): §20.19(b), §6.3(V), §7.3(V) HAC Standard: ANSI PC63.19-2005 D3.6

## **Hearing Aid Near-Field Category:**

This wireless portable device has been shown to be compatible with hearing aids under the above rated category, specified in ANSI/IEEE Std. PC63.19 and had been tested in accordance with the specified measurement procedures. Hearing-Aid Compatibility is based on the assumption that all production units will be designed electrically identical to the device tested in this report.

I attest to the accuracy of data. All measurements reported herein were performed by me or were made under my supervision and are correct to the best of my knowledge and belief. I assume full responsibility for the completeness of these measurements and vouch for the qualifications of all persons taking them.

Hyundai C-Tech Co., Ltd. Certifies that no party to this application has been denied FCC benefits pursuant to section 5301 of the Anti-Drug Abuse Act of 1998, 21 U.S. C. 853(a)

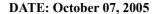
Report prepared by: Ki-Soo Kim

**Manager of Product Compliance Team** 

Xi SOO Xim

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# **Table of Contents**

1. APLICANT / EUT DESCRIPTION	3
2. HAC MEASUREMENT SET- UP	4
3. SYSTEM SPECIFICATIONS	5-6
4. EUT ARRANGEMENT	7
5. TEST SETUP PHOTOGRAPHS	8
6. SYSTEM VALIDATION	9-10
7. PROBE MODULATION FACTOR	11-12
B. TEST PROCEDURE	13-14
9. ANSI-PC 63.19-2001 LIMITS	15
10. MEASUREMENT UNCERTAINTIES	16-17
11. HAC TEST DATA SUMMARY	18-19
12. HAC TEST EQUIPMENT LIST	20
12 CONCLUSION	21

**APPENDIX A - HAC TEST PLOTS** 

**APPENDIX B - DIPOLE VALIDATION PLOTS** 

APPENDIX C - PROBE MODULATION FACTOR

**APPENDIX D - PROBE CALIBRATION DATA** 

APPENDIX E - DIPOLE CALIBRATION DATA

# HAC MEASUREMENT REPORT

#### 1. APPLICANT / EUT DESCRIPTION

### 1.1 Applicant

• Company Name: HYUNDAI CURITEL INC.

• Address: San 136-1, Ami-Ri, Bubal-Eub, Ichon-Si,

Kyoungki-Do, KOREA 467-701

• Attention: Mr. Hong-Ki Kim

• Tel. / Fax: 82- 31- 630- 3296 / 82- 31- 630- 8085

• E-Mail : honggikim@curitel.com

#### **1.2 EUT Description**

• EUT Type: Dual-Mode CDMA Phone (CDMA/ PCS CDMA) - Prototype

Trade Name: HYUNDAI
Model(s): TX-230
FCC ID: PP4TX-230
Serial Number(s): PP4230-1

• Tx Frequency: 824.70 – 848.31 MHz (CDMA)

1851.25 - 1908.75 MHz (PCS CDMA)

• FCC Classification: Licensed Portable Transmitter Held to Ear (PCE)

• FCC Rule Part(s): §20.19(b), §6.3(V), §7.3(V)

Modulation(s): CDMA/ PCS CDMA

• Antenna Type: Retractable (Retracted/Extended)

• Date(s) of Tests: October 07, 2005

• Place of Tests: Hyundai C-Tech. EMC Lab.

Icheon, Kyounki-Do, KOREA

• Report Serial No.: HCT-SAR05-1003

• Change of Contents: 1. Case cover change

2. Camera vendor change (Power Logics→MCNEX)

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3. LCD vendor change (Hye LCD→Innertech)

• Max E-Field Emission: channel 384, 836.52 MHz= 60.9 V/m (M4)

• Max H-Field Emission: channel 777, 848.31 MHz= 0.107 A/m (M4)

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### 2. HAC MEASUREMENT SET-UP

These measurements are performed using the DASY4 automated dosimetric assessment system. It is made by Schmid & Partner Engineering AG (SPEAG) in Zurich, Switzerland. It consists of high precision robotics system (Staubli), robot controller, Pentium IV computer, near-field probe, probe alignment sensor. The robot is a six-axis industrial robot performing precise movements.

A cell controller system contains the power supply, robot controller, teach pendant (Joystick), and remote control, is used to drive the robot motors. The PC consists of the HP Pentium IV 3.0 GHz computer with Windows XP system and HAC Measurement Software DASY4, A/D interface card, monitor, mouse, and keyboard. The Staubli Robot is connected to the cell controller to allow software manipulation of the robot. A data acquisition electronic (DAE) circuit performs the signal amplification, signal multiplexing, AD-conversion, offset measurements, mechanical surface detection, collision detection, etc. is connected to the Electro-optical coupler (EOC). The EOC performs the conversion from the optical into digital electric signal of the DAE and transfers data to the PC plug-in card.

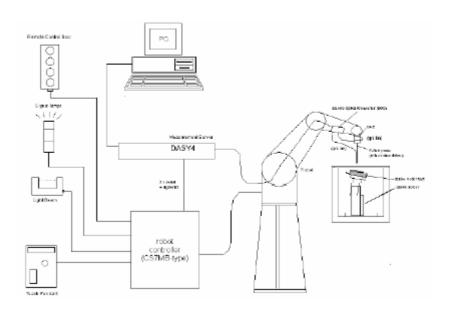


Figure 1. HAC Test Measurement Set-up

The DAE4 consists of a highly sensitive electrometer-grade preamplifier with auto-zeroing, a channel and gain-switching multiplexer, a fast 16 bit AD-converter and a command decoder and control logic unit. Transmission to the PC-card is accomplished through an optical downlink for data and status information and an optical uplink for commands and clock lines. The mechanical probe mounting device includes two different sensor systems for frontal and sidewise probe contacts. They are also used for mechanical surface detection and probe collision detection. The robot uses its own controller with a built in VME-bus computer.

# 3. SYSTEM SPECIFICATIONS

## 3.1 Probe

### 3.1.1 E-Field Probe Description

Construction	One dipole parallel, two dipoles normal to probe axis  Built-in shielding against static charges	
Calibration	In air from 100 MHz to 3.0 GHz (absolute accuracy $\pm 6.0\%$ , k=2)	
Frequency	100 MHz to > 6 GHz; Linearity:± 0.2dB (100 MHz to 3 GHz)	
Directivity	$\pm 0.2$ dB in air (rotation around probe axis) $\pm 0.4$ dB in air (rotation normal to probe axis)	ME
Dynamic Range	2 V/m to > 1000 V/m  (M3 or better device readings fall well below diode compression point)	
Linearity	±0.2 dB	
Dimensions	Overall length: 330 mm (Tip: 16mm)	[ E-Field Probe ]
	Tip diameter: 8 mm (Body: 12 mm)	
	Distance from probe tip to dipole centers: 2.5 mm	

## 3.1.2 H-Field Probe Description

Construction	Three concentric loop sensors with 3.8 mm loop diameters resistively loaded detector diodes for linear response Built-in shielding against static charges PEEK enclosure material (resistant to organic solvents, e.g., glycolether)	
Frequency	200 MHz to > 3 GHz (absolute accuracy $\pm 6.0\%$ , k=2); Output linearized	
Directivity	±0.25 dB (spherical isotropy error)	#
Dynamic Range	10 mA/m to 2 A/m at 1 GHz	
E-Field Interference	< 10% at 3 GHz (for plane wave)	[H-Field Probe]
Dimensions	Overall length: 330 mm (Tip: 40mm)	
	Tip diameter: 6 mm (Body: 12 mm)	
	Distance from probe tip to dipole centers: 3 mm	
	The closest part of the sensor element is 1.9 mm closer to the tip	

#### 3.2 Phantom & Device Holder



Figure 2. HAC Phantom & Device Holder

The Test Arch phantom should be positioned horizontally on a stable surface. Reference markings on the Phantom allow the complete setup of all predefined phantom positions and measurement grids by manually teaching three points in the robot.

The devices can be easily, accurately, and repeatable positioned according to the FCC specifications.

## 3.3 Robotic System Specifications

**Specifications** 

**POSITIONER:** Stäubli Unimation Corp. Robot Model: RX90LB

Repeatability: 0.02 mm

No. of axis: 6

Data Acquisition Electronic (DAE) System

**Cell Controller** 

Processor: Pentium IV
Clock Speed: 3.0 GHz
Operating System: Windows XP
Data Card: DASY4 PC-Board

**Data Converter** 

**Features:** Signal Amplifier, multiplexer, A/D converter, and control logic

**Software:** DASY4 software

Connecting Lines: Optical downlink for data and status info.

Optical uplink for commands and clock

**PC Interface Card** 

**Function:** 24 bit (64 MHz) DSP for real time processing

Link to DAE3

16 bit A/D converter for surface detection system

serial link to robot

direct emergency stop output for robot

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### 4. EUT ARRANGEMENT

#### 4.1 WD RF Emission Measurements Reference and Plane

Figure 3. Illustrate the references and reference plane that shall be used in the WD emissions measurement.

- The grid is 5 cm by 5 cm area that is divided into 9 evenly sized blocks or sub-grids.
- The grid is centered on the audio frequency output transducer of the WD (speaker or T-coil).
- The grid is in a reference plane, which is defined as the planar area that contains the highest point in the area of the phone that normally rests against the user's ear. It is parallel to the centerline of the receiver area of the phone and is defined by the points of the receiver-end of the WD handset, which, in normal handset use, rest against the ear.
- The measurement plane is parallel to, and 1.0 cm in front of, the reference plane.



Figure 3. WD reference and plane for RF emission measurements

# **5. TEST SET-UP PHOTOGRAPHS**





Figure 4. Test Set-up Photo

### 6. SYSTEM VALIDATION

The test setup was validated when confabulated and verified periodically thereafter to ensure proper function. The procedure is a validation procedure using dipole antennas for which the field levels were computed by FDTD modeling.

#### **6.1 Validation Procedure**

Place a dipole antenna meeting the requirements given in ANSI-PC63.19 in the position normally occupied by the WD. The dipole antenna serves as a known source for an electrical and magnetic output. Position the E-field and H-field probes so that:

- the probes and their cables are parallel to the coaxial feed of the dipole antenna
- the probe cables and the coaxial feed of the dipole antenna approach the measurement area from opposite directions; and
- the probes are 10 mm from the surface of the dipole elements.

Scan the length of the dipole with both E-field and H-field probes and record the maximum values for each. Compare the readings to expected values.

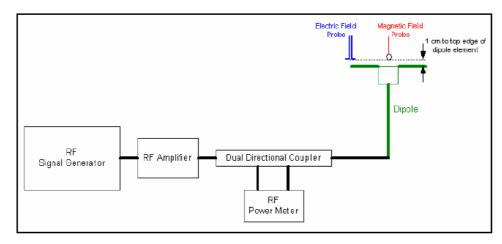


Figure 5. WD dipole calibration procedure E - Field H - Field Probe Probe Nearest point on the probe element Nearest point on the probe Off Set Off Set Gauge Gauge Top surface of dipole Top surface of EU1 Center of Center of dipole dipole

Figure 6. Gauge Block with E-Field Probe

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Figure 7. Gauge Block with H-Field Probe

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## **6.2 Validation Result**

### 6.2.1 E-Field Scan

Input	Input	nput Power		Measured Value (V/m)		Target Value	Deviation	Limit	
Mode	Mode Freq. [MHz]	Power (mW)	Drift (dB)	Above high end (V/m)	Above low end (V/m)	above (V/m) arm (V/m) SPEAG	[%]	[%]	
CW	835	100	-0.048	181.0	178.3	179.65	163.0	+10.21	±25
CW	1880	100	-0.064	143.7	143.1	143.4	138.0	+3.62	±25

#### 6.2.2 H-Field Scan

Mode	Freq. [MHz]	Input Power (mW)	Power Drift (dB)	Measured Value (V/m)	Target Value (V/m) SPEAG	Deviation [%]	Limit [%]
CW	835	100	-0.048	0.459	0.453	+1.32	±25%
CW	1880	100	-0.016	0.481	0.455	+5.71	±25%

#### Notes:

- 1) Deviation (%) = 100 \* (Measured value minus Target value) divided by Target value.

  ANSI-PC63.19 requires values to be within 25% of their targets. 12% is deviation and 13% is measurement uncertainty.
- 2) The maximum E-field or H-field were evaluated and compared to the target values provided by SPEAD in the calibration certificate of specific dipoles.
- 3) Please refer to the attachment for detailed measurement data and plot.

## 7. Probe Modulation Factor

The Probe Modulation Factor (PMF) is defined as the ratio of the field readings for a CW and a modulated signal with the equivalent Field Envelope Peak as defined in the Standard (Chapter C.3.1).

Calibration shall be made of the modulation response of the probe and its instrumentation chain. This Calibration shall be performed with the field probe, attached to the instrumentation that is to be used with it during the measurement. The response of the probe system to a CW field at the frequency(s) of interest is compared to its response to a modulated signal with equal peak amplitude. The field level of the test signals shall be more than 10dB above the ambient level and the noise floor of the instrumentation being used. The ratio of the CW reading to that taken with a modulated field shall be applied to the readings taken of modulated fields of the specified type.

#### 7.1 Modulation Factor Test Procedure

This may be done using the following procedure:

- 1. Fixing the probe in a set location relative to a field generating device, such as a reference dipole antenna or
- 2. Illuminate the probe with a CW signal at the intended measurement frequency.
- 3. Record the reading of the probe measurement system of the CW signal.
- 4. Determine the level of the CW signal being used to drive the field generating device.
- 5. Substitute a signal using the same modulation as that used by the intended WD for the CW signal.
- 6. Set the amplitude during transmission of the modulated signal to equal the amplitude of the CW signal.
- 7. Record the reading of the probe measurement system of the modulated signal.
- 8. Calculate the Probe Modulation Factor as the ratio between the CW multimeter field readings and the reading for the applicable modulation. PMF = CW/WD\_CDMA

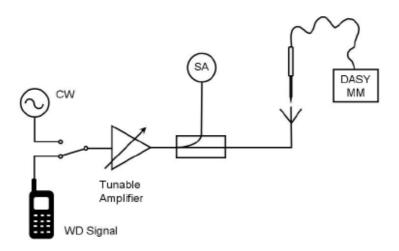


Figure 8. Probe modulation Setup Photo

## **7.2 Modulation Factor**

#### **7.2.1 E-Field**

Mode	Freq. [MHz]	Input Power (dB)	E-Field measured value (V/m)	Probe Modulation Factor
CW		25	316.5	1.00
WD	835 MHz	25	324.6	0.98
80% AM		25	204.1	1.55
CW		25	249.95	1.00
WD	1880MHz	25	256.0	0.98
80% AM		25	159.0	1.57

### 7.2.2 H-Field

Mode	Freq. [MHz]	Input Power (dB)	H-Field measured value (A/m)	Probe Modulation Factor
CW		25	0.872	1.00
WD	835 MHz	25	0.886	0.98
80% AM		25	0.567	1.54
CW		25	1.09	1.00
WD	1880MHz	25	1.16	0.94
80% AM		25	0.691	1.57

#### Notes:

1) Modulation Factor = CW / WD\_CDMA

## 8. TEST PROCEDURE

## **Test Instructions** Confirm proper operation of probes and instrumentation Position WD Configure WD Tx Operation Per Section 4.3.1.2.2 (1-3) Initialize field probe and take first reading Scan Area Per Section 4.3.1.2.2 (4-6) Rescan for E or H-Field, Identify exclusion area and as needed then identify and record maximum reading for Per Section 4.3.1.2.2 (11) remaining area in V/m or A/m Per Section 4.3.1.2.2 (7-9) Both E & H Field No Scanned? Yes Identify & Record Category Per Section 4.3.1.2.2 (10) & 7.2

Figure 9. WD near-field emission automated test flowchart

#### The evaluation was performed with the following procedure:

- 1. Confirm proper operation of the field probe, probe measurement system and other instrumentation and the positioning system.
- 2. Position the WD in its intended test position. The gauge block, depicted in Section A.2.1, can simplify this positioning. Note that a separate E- and H-field gauge block will be needed if the edges of the probe sensors are at different distances from the tip of the probe.
- 3. Configure the WD normal operation for maximum rated RF output power, at the desired channel and other operating parameters, (e.g. test mode) as intended for the test.
- 4. The center sub-grid shall be centered on the center of the WD output (acoustic or T-Coil output), as appropriate. Locate the field probe at the initial test position in the 5 x 5 cm grid, which is contained in the measurement plane.
- 5. Record the reading.
- 6. Scan the entire 5 x 5 cm region in equally spaced increments and record the reading at each measurement point. The distance between measurement points shall be sufficient to assure the identification of the peak reading.
- 7. Identify the five contiguous sub-grids around the center sub-grid with the lowest maximum field strength readings. Thus the 6 areas to be used to determine the WD's peak emissions are identified and outlined for the final manual scan. Please note that a maximum of five blocks can be excluded for both E- and H-field measurements for the WD output being measured. State another way, the center sub-grid and 3 other must be common to both the E- and H-field measurements.
- 8. Identify the highest field reading within the non-excluded sub-grids identified in step 7.
- 9. Convert the highest field strength reading identified in step 8 to peak V/m or A/m, as appropriate. This conversion shall be done using the appropriate probe modulation factor.
- 10. Repeat steps 1-10 for both the E- and H-field measurements.
- 11. Compare this reading to the categories in ANSI-PC63.19 and record the resulting category. The lowest category number listed in ANSI-PC63.19, obtained in step 10 for either E or H field determines the M category for the audio coupling mode assessment. Record the WD category rating.

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# 9. ANSI-PC 63.19-2001 LIMITS

The EUT must meet the following M3 or M4 category:

Category	AWF (dB)	Limits for E-Field Emissions(V/m)	Limits for H-Field Emissions(V/m)
M1	0	199.5 - 354.8	0.6 - 1.07
IVII	-5	149.6 - 266.1	0.45 - 0.8
M2	0	112.2 - 199.5	0.34 - 0.6
IVIZ	-5	84.1 - 149.6	0.25 - 0.45
M3	0	63.1 - 112.2	0.19 - 0.34
IVIO	-5	47.3 - 84.1	0.15 - 0.25
M4	0	< 63.1	< 0.19
1014	-5	< 47.3	< 0.15

Table 1. Telephone near-field categories in linear units

## **10. MEASUREMENT UNCERTAINTIES**

	HAC-Extension Setup Performance Test Using SPEAG Calibration Dipoles									
Error Description	Uncertainty Probability  Value ±% Distribution		Divisor	(Ci)	(Ci)	Std. Unc. E	Std. Unc. H			
Measurement System										
Probe calibration	± 5.1	N	1	1	1	± 5.1	± 5.1			
Axial isotropy	± 4.7	R	√3	1	1	± 2.7	± 2.7			
Sensor Displacement	±16.5	R	√3	1	0.145	±9.5	±1.4			
Boundary effects	± 2.4	R	√3	1	1	± 1.4	± 1.4			
Linearity	± 4.7	R	√3	1	1	± 2.7	± 2.7			
Scaling to Peak Envelope Power	± 0	R	√3	1	1	± 0	± 0			
System Detection Limit	± 1	R	√3	1	1	± 0.6	± 0.6			
Readout electronics	± 0.3	N	1	1	1	± 0.3	± 0.3			
Response time	± 0	R	√3	1	1	± 0	± 0			
Integration time	± 0	R	√3	1	1	± 0	± 0			
RF ambient conditions	± 3.0	R	√3	1	1	± 1.7	± 1.7			
RF Reflections	± 6.0	R	√3	1	1	± 3.5	± 3.5			
Probe Positioner	± 1.2	R	√3	1	0.67	± 0.7	± 0.7			
Probe positioning	± 4.7	R	√3	1	0.67	± 2.7	± 1.8			
Extrap. and integration	± 1.0	R	√3	1	1	± 0.6	± 0.6			
Dipole Related										
Distance Dipole-Scanning Plane	± 5.2	R	√3	1	0.3	± 3.0	± 0.9			
Input power	± 4.7	N	1	1	1	± 4.7	± 4.7			
Combined Standard Uncertainty						± 13.7	± 9.3			
Expanded Std. Uncertainty on Po	wer					± 27.4%	± 18.6%			
Expanded Std. Uncertainty on Fig	eld					± 13.7%	± 9.3%			

Table 2. Breakdown of Errors

#### Notes:

Uncertainty budget for HAC setup performance test. The budget is valid for the Frequency range 800MHz-3GHz and represents a worst-case analysis with respect to power uncertainty of the field. Some of the parameters are dependent on the user situations and need adjustment according to the actual laboratory conditions.

### **HAC Uncertainty Budget** According to ANSI C63.19 [1]

Error Description	Uncertainty Value ±%	Probability Distribution	Divisor	(Ci) E	(Ci) H	Std. Unc. E	Std. Unc. H
Measurement System							
Probe calibration	± 5.1	N	1	1	1	± 5.1	± 5.1
Axial isotropy	± 4.7	R	√3	1	1	± 2.7	± 2.7
Sensor Displacement	±16.5	R	√3	1	0.145	±9.5	±1.4
Boundary effects	± 2.4	R	√3	1	1	± 1.4	± 1.4
Linearity	± 4.7	R	√3	1	1	± 2.7	± 2.7
Scaling to Peak Envelope Power	± 2.0	R	√3	1	1	± 1.2	± 1.2
System Detection Limit	± 1.0	R	√3	1	1	± 0.6	± 0.6
Readout electronics	± 0.3	N	1	1	1	± 0.3	± 0.3
Response time	± 0.8	R	√3	1	1	± 0.5	± 0.5
Integration time	± 2.6	R	√3	1	1	± 1.5	± 1.5
RF ambient conditions	± 3.0	R	√3	1	1	± 1.7	± 1.7
RF Reflections	± 12.0	R	√3	1	1	± 6.9	± 6.9
Probe Positioner	± 1.2	R	√3	1	0.67	± 0.7	± 0.5
Probe positioning	± 4.7	R	√3	1	0.67	± 2.7	± 1.8
Extrap. and Interpolation	± 1.0	R	√3	1	1	± 0.6	± 0.6
Test Sample Related							
Device Positioning Vertical	± 4.7	R	√3	1	1	± 2.7	± 1.8
Device Positioning Lateral	± 1.0	R	√3	1	1	± 0.6	± 0.6
Device Holder and Phantom	± 2.4	R	√3	1	1	± 1.4	± 1.4
Power Drift	± 5.0	R	√3	1	1	± 2.9	± 2.9
Phantom and Setup Related							
Phantom Thickness	± 2.4	R	√3	1	0.67	± 1.4	± 0.89
Combined Standard Uncertainty	1					± 14.7	± 10.9
Expanded Std. Uncertainty on Po	wer					± 29.4%	± 21.8%
Expanded Std. Uncertainty on Fig	eld					± 14.7%	± 10.9%

#### Table 3. Breakdown of Errors

#### Notes:

Worst-Case uncertainty budget for HAC free field assessment according to ANSI-C 63.19[1]. The budget is valid for the frequency range 800MHz-3GHz and represents a worst-Case analysis. For specific test sand configurations, the uncertainty could be considerably smaller. Some of the parameters are dependent on the user situations and need adjustment according to the actual laboratory conditions.

# **11. HAC TEST DATA SUMMARY**

Ambient TEMPERATURE (°C):	21.7
S/N:	PP4230-1

## 11.1 Measurement Results (E-Field CDMA, PCS DATA)

Frequ	uency	Modulation	Conducted	Power	AWF	Ant.	Measured	Category
MHz	Chan.	Woddiation	Power (dBm)	drift (dB)	7,001	Position	Value (V/m)	Outegory
824.70	1013	CDMA	25.0	0.080	0	In	56.4	M4
321.70	(Low)	CDMA	25.0	-0.050	0	Out	57.2	M4
836.52	0384	CDMA	25.0	-0.038	0	In	60.9	M4
000.02	(Middle)	CDMA	25.0	-0.081	0	Out	58.2	M4
848.31	0777	CDMA	25.0	-0.023	0	In	56.9	M4
040.51	(High)	CDMA	25.0	-0.017	0	Out	52.4	M4
1851.25	0025	PCS	25.0	-0.063	0	In	26.1	M4
1031.23	(Low)	PCS	25.0	+0.017	0	Out	16.6	M4
1880.00	0600	PCS	25.0	-0.023	0	In	27.1	M4
1000.00	(Middle)	PCS	25.0	-0.061	0	Out	15.5	M4
1908.75	1175	PCS	25.0	-0.047	0	In	26.0	M4
1900.75	(High)	PCS	25.0	+0.060	0	Out	14.1	M4
			Overall M	l-Rating				M4

#### NOTES:

3. Power Measured

1.	All modes of	of operation	were investig	ated and th	ne worst-case	are reported.

2. Battery Type extstyle extstyl

4. Test Signal Call Mode ☐ Manual Test cord ☒ Base Station Simulator

5. SAR Measurement System ☑ SPEAG

□ERP

# **11. HAC TEST DATA SUMMARY**

Ambient TEMPERATURE (°C):	21.7
S/N:	PP4230-1

## 11.2 Measurement Results (H-Field CDMA, PCS DATA)

Frequency  MHz Chan.		Modulation	Conducted	Power	AWF	Ant.	Measured	Category
			Power (dBm)	drift (dB)		Position	Value (V/m)	3 ,
824.70	1013	CDMA	25.0	-0.133	0	In	0.079	M4
021.70	(Low)	CDMA	25.0	-0.013	0	Out	0.101	M4
836.52	0384 (Middle)	CDMA	25.0	0.027	0	In	0.087	M4
000.02		CDMA	25.0	0.010	0	Out	0.100	M4
848.31	0777 (High)	CDMA	25.0	-0.071	0	In	0.088	M4
040.01		CDMA	25.0	-0.064	0	Out	0.107	M4
1851.25	0025	PCS	25.0	+0.066	0	In	0.058	M4
1001.20	(Low)	PCS	25.0	-0.081	0	Out	0.034	M4
1880.00	0600 (Middle)	PCS	25.0	+0.046	0	In	0.069	M4
1000.00		PCS	25.0	-0.168	0	Out	0.032	M4
1908.75	1175	PCS	25.0	+0.001	0	In	0.063	M4
1000.70	(High)	PCS	25.0	+0.006	0	Out	0.033	M4
Overall M-Rating								M4

#### NOTES:

1	I. All	mod	les of	f operatio	n were	invest	igated	and	the	worst	-case	are	report	ed.

2. Battery Type extstyle extstyl

3. Power Measured 

☑ Conducted □ EIRP □ERP

4. Test Signal Call Mode ☐ Manual Test cord ☒ Base Station Simulator

5. SAR Measurement System ☑ SPEAG

# **12. HAC TEST EQUIPMENT LIST**

Type / Model	Calib. Date	S/N
Staubli Robot RX90L	N/A	F01/ 5K09A1/A/01
Staubli Robot ControllerCS7MB	N/A	F99/5A82A1/C/01
Staubli Teach Pendant (Joystick)	N/A	D221340.01
Dell OptiPlex GX100	N/A	HY4640
Windows NT 4.0	N/A	-
SPEAG DAE3V1	May 05	446
SPEAG DAE3V1	June 05	447
SPEAG E-Field Probe	April 05	2343
SPEAG E-Field Probe	July 05	6101
SPEAG HAC Phantom	N/A	-
SPEAG Light Alignment Sensor	N/A	265
SPEAG Validation Dipole D835V2	April 05	1024
SPEAG Validation Dipole D1880V2	April 05	1019
Phone Holder	N/A	-
A/B Power Indicator	N/A	-
Remote Power Switch	N/A	-
NOTE:		

The E-field, H-field probe was calibrated by SPEAG. Dipole Validation measurement is performed by HCT Lab. before each test. The following list of equipment was used to :

Power Meter(A)	E4419B	June 05	MY40511244
Power Sensor(A)	8481	June 05	MY41090680
Signal Generator	8664A (100kHz ~ 3GHz)	April 05	3744A02069
Power Amp	A0825-4343-R	Sep. 05	A00450
Dual Directional C	oupler 778D	August 05	16072
Power divider	1506A	Jan. 05	MD793
Base Station Simu	ılator E5515C	May 05	US41070189



## 13. CONCLUSION

The HAC measurement indicates that the EUT complies with the HAC limits of the ANSI-PC63.19-2001.

These measurements are taken to simulate the RF effects exposure under worst-case conditions. Precise Laboratory measures were taken to assure repeatability of the tests.