

# SAR Evaluation Report

IN ACCORDANCE WITH THE REQUIREMENTS OF FCC REPORT AND ORDER: ET DOCKET 93-62, AND OET BULLETIN 65 SUPPLEMENT C

FOR

802.11b/g Half Size Mini-PCI WLAN Module

MODEL: PA3426U-1MPC

FCC ID: CJ6UPA3426WL

**REPORT NUMBER: 04U3194-5** 

ISSUE DATE: February 16, 2005

Prepared for

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#### **Revision History**

Rev. Revisions

Revised By

# CERTIFICATE OF COMPLIANCE (SAR EVALUATION)

#### DATES OF TEST: February 15 - 16, 2005

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APPLICANT:	Toshiba Corporation Digital Media Network Company
ADDRESS:	Ome Complex, 2-9, Suehiro-cho, Tokyo, 198-8710, Japan
FCC ID:	CJ6UPA3426WL
MODEL:	PA3426U-1MPC
DEVICE CATEGORY:	Portable Device
EXPOSURE CATEGORY:	General Population/Uncontrolled Explosure

802.11b/g Half Size Mini-PCI WLAN Module installed in Toshiba Firebolt 10 (PortegeM200) Laptop, including co-location with the Toshiba PA3232U-1BTM (BC02) and PA3418U-1BTM (BC04) Bluetooth radio cards.

Test Sample is a:	Production unit						
Modulation type:	Direct Sequence Spread Spectrum (DSSS) for 802.11b Orthogonal Frequency Division Multiplexing (OFDM) for 802.11g						
Antenna(s)	The radio utilizes two antennas for diversity (main and auxiliary). HTL004 (PIFA Film Antenna): 4.18 dBi @ 2.4GHz w/o cable loss HTL008 (PIFA Film Antenna): 2.89 dBi @ 2.4GHz w/o cable loss HTL017 (PIFA Film Antenna): 4.24 dBi @ 2.4GHz w/o cable loss TIAN01 (PIFA Film Antenna): 4.02 dBi @ 2.4GHz w/o cable loss						
FCC Rule Parts	Frequency Range [MHz]	The Highest SAR Values [1g_mW/g]		Max. Power Output [dBm]			
47 CFR 15.247	2412 - 2462		0.0170	16.6			
		Co-location:	0.0191				

This wireless portable device has been shown to be capable of compliance for localized specific absorption rate (SAR) for General Population/Uncontrolled Explosure limits specified in ANSI/IEEE Std. C95.1-1992 and had been tested in accordance with the measurement procedures specified in FCC OET 65 Supplement C (Edition 01-01).

Note: The results documented in this report apply only to the tested sample, under the conditions and modes of operation as described herein. This document may not be altered or revised in any way unless done so by Compliance Certification Services and all revisions are duly noted in the revisions section. Any alteration of this document not carried out by Compliance Certification Services will constitute fraud and shall nullify the document. No part of this report may be used to claim product certification, approval, or endorsement by NVLAP, NIST, or any government agency.

Released For CCS By:

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## 1 EQUIPMENT UNDER TEST (EUT) DESCRIPTION

802.11b/g Half Size Mini-PCI WLAN Module installed in Toshiba Firebolt 10 (PortegeM200) Laptop, including co-location with the Toshiba PA3232U-1BTM (BC02) and PA3418U-1BTM (BC04) Bluetooth radio cards.

The Bluetooth radio card has a modular approval, FCC ID: CJ6UPA3232BT and CJ6UPA3418BT. The Bluetooth radio utilizes a film antenna with a maximum gain of 1.22 dBi.

Normal operation:	Lap-held position
Accessory:	N/A
Earphone/Headset Jack:	N/A
Duty cycle:	100% for DSSS & OFDM
Host Device(s):	Toshiba, Firebolt10 (PORTEGE M200)
Power supply:	Power supplied through the laptop computer (host device)

## 2 FACILITIES AND ACCREDITATION

The test sites and measurement facilities used to collect data are located at 561F Monterey Road, Morgan Hill, California, USA. The sites are constructed in conformance with the requirements of ANSI C63.4, ANSI C63.7 and CISPR Publication 22. All receiving equipment conforms to CISPR Publication 16-1, "Radio Interference Measuring Apparatus and Measurement Methods."



CCS is accredited by NVLAP, Laboratory Code 200065-0. The full scope of accreditation can be viewed at http://www.ccsemc.com.

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## **3 SYSTEM DESCRIPTION**



## The DASY4 system for performing compliance tests consists of the following items:

- A standard high precision 6-axis robot (Stäubli RX family) with controller, teach pendant and software. An arm extension for accommodating the data acquisition electronics (DAE).
- A dosimetric probe, i.e., an isotropic E-field probe optimized and calibrated for usage in tissue simulating liquid. The probe is equipped with an optical surface detector system.
- A data acquisition electronics (DAE) which performs the signal amplification, signal multiplexing, ADconversion, offset measurements, mechanical surface detection, collision detection, etc. The unit is battery powered with standard or rechargeable batteries. The signal is optically transmitted to the EOC.
- The function of the measurement server is to perform the time critical tasks such as signal filtering, control of the robot operation and fast movement interrupts.
- A probe alignment unit which improves the (absolute) accuracy of the probe positioning.
- A computer operating Windows 2000 or Windows XP.
- DASY4 software.
- Remote controls with teach pendant and additional circuitry for robot safety such as warning lamps, etc.
- The SAM twin phantom enabling testing left-hand and right-hand usage.
- The device holder for handheld mobile phones.
- Tissue simulating liquid mixed according to the given recipes.
- Validation dipole kits allowing to validate the proper functioning of the system.

## 4 SYSTEM COMPONENT

## 4.1 DASY4 MEASUREMENT SERVER



The DASY4 measurement server is based on a PC/104 CPU board with a 166MHz low-power Pentium, 32MB chip disk and 64MB RAM. The necessary circuits for communication with either the DAE3 electronic box as well as the 16-bit AD-converter system for optical detection and digital I/O interface are contained on the DASY4 I/O-board, which is directly connected to the PC/104 bus of the CPU board.

The measurement server performs all real-time data evaluation for field measurements and surface detection, controls robot movements and handles safety operation. The PC-operating system cannot interfere with these time critical processes. All connections are supervised by a watchdog, and disconnection of any of the cables to the measurement server will automatically disarm the robot and disable all program-controlled robot movements. Furthermore, the measurement server is equipped with two expansion slots which are reserved for future applications. Please note that the expansion slots do not have a standardized pinout and therefore only the expansion cards provided by SPEAG can be inserted. Expansion cards from any other supplier could seriously damage the measurement server. Calibration: No calibration required.

## 4.2 DATA ACQUISITION ELECTRONICS (DAE)

The data acquisition electronics (DAE3) consists of a highly sensitive electrometer grade preamplifier with auto-zeroing, a channel and gain-switching multiplexer, a fast 16 bit AD converter and a command decoder and control logic unit. Transmission to the measurement server is accomplished through an optical downlink for data and status information as well as an optical uplink for commands and the clock. The mechanical probe mounting device includes two different sensor systems for frontal and sideways probe contacts. They are used for mechanical surface detection and



probe collision detection. The input impedance of the DAE3 box is 200MOhm; the inputs are symmetrical and floating. Common mode rejection is above 80 dB.

## 4.3 EX3DV3 ISOTROPIC E-FIELD PROBE FOR DOSIMETRIC MEASUREMENTS

Construction:	Symmetrical design with triangular core Built-in shielding against static charges PEEK enclosure material (resistant to organic solvents, e.g., DGBE)
Frequency:	10 MHz to > 6 GHz; Linearity: ± 0.2 dB (30 MHz to 3 GHz)
Directivity:	± 0.3 dB in HSL (rotation around probe axis);
•	± 0.5 dB in tissue material (rotation normal to probe axis)
<b>Dynamic Range:</b>	10 $\mu$ W/g to > 100 mW/g; Linearity: ± 0.2 dB (noise:
	typically < 1 µW/g)
Dimensions:	Overall length: 330 mm (Tip: 20 mm)
	Tip diameter: 2.5 mm (Body: 12 mm)
	Typical distance from probe tip to dipole centers: 1 mm
Application:	High precision dosimetric measurements in any exposure
	scenario (e.g., very strong gradient fields). Only probe
	which enables compliance testing for
	frequencies up to 6 GHz with precision of
	better 30%.

## 4.4 LIGHT BEAM UNIT

The light beam switch allows automatic "tooling" of the probe. During the process, the actual position of the probe tip with respect to the robot arm is measured, as well as the probe length and the horizontal probe offset. The software then corrects all movements, so that the robot coordinates are valid for the probe tip. The repeatability of this process is better than 0.1 mm. If a position has been taught with an aligned probe, the same position will be reached with another aligned probe within 0.1 mm, even if the other probe has different dimensions. During probe rotations, the probe tip will keep its actual position.



## 4.5 SAM PHANTOM (V4.0)

**Construction:** The shell corresponds to the specifications of the Specific Anthropomorphic Mannequin (SAM) phantom defined in IEEE 1528-200X, CENELEC 50361 and IEC 62209. It enables the dosimetric evaluation of left and right hand phone usage as well as body mounted usage at the flat phantom region. A cover prevents evaporation of the liquid. Reference markings on the phantom allow the complete setup of all predefined phantom positions and measurement grids by manually teaching three points with the robot.

Shell Thickness:2 ±0.2 mmFilling Volume:Approx. 25 litersDimensions:Height: 810mm; Length: 1000mm; Width: 500mm



## 4.6 DEVICE HOLDER FOR SAM TWIN PHANTOM

**Construction:** In combination with the Twin SAM Phantom V4.0 or Twin SAM, the Mounting Device (made from POM) enables the rotation of the mounted transmitter in spherical coordinates, whereby the rotation point is the ear opening. The devices can be easily and accurately positioned according to IEC, IEEE, CENELEC, FCC or other specifications. The device holder can be locked at different phantom locations (left head, right head, flat phantom).



## 4.7 SYSTEM VALIDATION KITS

Construction:	Symmetrical dipole with I/4 balun Enables measurement of feedpoint impedance with
	NWA Matched for use near flat phantoms filled with brain simulating solutions
	Includes distance holder and tripod adaptor.
Frequency:	450, 900, 1800, 2450, 5800 MHz
Return loss:	> 20 dB at specified validation position
Power capability:	> 100 W (f < 1GHz); > 40 W (f > 1GHz)
Dimensions:	450V2: dipole length: 270 mm; overall height: 330 mm
	D900V2: dipole length: 149 mm; overall height: 330 mm
	D1800V2: dipole length: 72 mm; overall height: 300 mm
	D835V2: dipole length: 161; overall height: 330
	D1900V2: dipole length: 68; overall height: 300
	D2450V2: dipole length: 51.5 mm; overall height: 300 mm D5GHzV2: dipole length:
	25.5 mm; overall height: 290 mm

## 4.8 COMPOSITION OF INGREDIENTS FOR TISSUE SIMULATING LIQUID

The following tissue formulations are provided for reference only as some of the parameters have not been thoroughly verified. The composition of ingredients may be modified accordingly to achieve the desired target tissue parameters required for routine SAR evaluation.

Ingredients		Frequency (MHz)								
(% by weight)	45	50	83	35	915		1900		2450	
Tissue Type	Head	Body	Head	Body	Head	Body	Head	Body	Head	Body
Water	38.56	51.16	41.45	52.4	41.05	56.0	54.9	40.4	62.7	73.2
Salt (NaCl)	3.95	1.49	1.45	1.4	1.35	0.76	0.18	0.5	0.5	0.04
Sugar	56.32	46.78	56.0	45.0	56.5	41.76	0.0	58.0	0.0	0.0
HEC	0.98	0.52	1.0	1.0	1.0	1.21	0.0	1.0	0.0	0.0
Bactericide	0.19	0.05	0.1	0.1	0.1	0.27	0.0	0.1	0.0	0.0
Triton X-100	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	36.8	0.0
DGBE	0.0	0.0	0.0	0.0	0.0	0.0	44.92	0.0	0.0	26.7
Dielectric Constant	43.42	58.0	42.54	56.1	42.0	56.8	39.9	54.0	39.8	52.5
Conductivity (S/m)	0.85	0.83	0.91	0.95	1.0	1.07	1.42	1.45	1.88	1.78

Salt: 99+% Pure Sodium Chloride

Sugar: 98+% Pure Sucrose HEC: Hydroxyethyl Cellulose

Water: De-ionized, 16 M $\Omega$ + resistivity HEC: Hydroxyethyl Cellulose DGBE: 99+% Di(ethylene glycol) butyl ether, [2-(2-butoxyethoxy)ethanol] Triton X-100 (ultra pure): Polyethylene glycol mono [4-(1,1,3,3-tetramethylbutyl)phenyl]ether

## 5 TEST POSITIONS FOR DEVICES OPERATING NEXT TO A PERSON'S EAR

This category includes most wireless handsets with fixed, retractable or internal antennas located toward the top half of the device, with or without a foldout, sliding or similar keypad cover. The handset should have its earpiece located within the upper ¼ of the device, either along the centerline or off-centered, as perceived by its users. This type of handset should be positioned in a normal operating position with the "test device reference point" located along the "vertical centerline" on the front of the device aligned to the "ear reference point". The "test device reference point" should be located at the same level as the center of the earpiece region. The "vertical centerline" should bisect the front surface of the handset at its top and bottom edges. A "ear reference point" is located on the outer surface of the head phantom on each ear spacer. It is located 1.5 cm above the center of the ear reference point" (left and right) and the tip of the mouth.

A handset should be initially positioned with the earpiece region pressed against the ear spacer of a head phantom. For the SCC-34/SC-2 head phantom, the device should be positioned parallel to the "N-F" line defined along the base of the ear spacer that contains the "ear reference point". For interim head phantoms, the device should be positioned parallel to the cheek for maximum RF energy coupling. The "test device reference point" is aligned to the "ear reference point" on the head phantom and the "vertical centerline" is aligned to the "phantom reference plane". This is called the "initial ear position". While maintaining these three alignments, the body of the handset is gradually adjusted to each of the following positions for evaluating SAR:



## 5.1 CHEEK/TOUCH POSITION

The device is brought toward the mouth of the head phantom by pivoting against the "ear reference point" or along the "N-F" line for the SCC-34/SC-2 head phantom.

This test position is established:

- i. When any point on the display, keypad or mouthpiece portions of the handset is in contact with the phantom.
- ii. (or) When any portion of a foldout, sliding or similar keypad cover opened to its intended selfadjusting normal use position is in contact with the cheek or mouth of the phantom.

For existing head phantoms – when the handset loses contact with the phantom at the pivoting point, rotation should continue until the device touches the cheek of the phantom or breaks its last contact from the ear spacer.



## Cheek / Touch Position

## 5.2 EAR/TILT POSITION

With the handset aligned in the "Cheek/Touch Position":

- i. If the earpiece of the handset is not in full contact with the phantom's ear spacer (in the "Cheek/Touch position") and the peak SAR location for the "Cheek/Touch" position is located at the ear spacer region or corresponds to the earpiece region of the handset, the device should be returned to the "initial ear position" by rotating it away from the mouth until the earpiece is in full contact with the ear spacer.
- ii. (otherwise) The handset should be moved (translated) away from the cheek perpendicular to the line passes through both "ear reference points" (note: one of these ear reference points may not physically exist on a split head model) for approximate 2-3 cm. While it is in this position, the device handset is tilted away from the mouth with respect to the "test device reference point" until the inside angle between the vertical centerline on the front surface of the phone and the horizontal line passing through the ear reference point isby 15°. After the tilt, it is then moved (translated) back toward the head perpendicular to the line passes through both "ear reference points" until the device touches the phantom or the ear spacer. If the antenna touches the head first, the positioning process should be repeated with a tilt angle less than 15° so that the device and its antenna would touch the phantom simultaneously. This test position may require a device holder or positioner to achieve the translation and tilting with acceptable positioning repeatability.

If a device is also designed to transmit with its keypad cover closed for operating in the head position, such positions should also be considered in the SAR evaluation. The device should be tested on the left and right side of the head phantom in the "Cheek/Touch" and "Ear/Tilt" positions. When applicable, each configuration should be tested with the antenna in its fully extended and fully retracted positions. These test configurations should be tested at the high, middle and low frequency channels of each operating mode; for example, AMPS, CDMA, and TDMA. If the SAR measured at the middle channel for each test configuration (left, right, Cheek/Touch, Tile/Ear, extended and retracted) is at least 3.0 dB lower than the SAR limit, testing at the high and low channels is optional for such test configuration(s). If the transmission band of the test device is less than 10 MHz, testing at the high and low frequency channels is optional.



## 6 TEST POSITIONS FOR BODY-WORN AND OTHER SIMILAR CONFIGURATIONS

#### With the belt-clips or holsters

Body-worn operating configurations should be tested with the belt-clips and holsters attached to the device and positioned against a flat phantom in normal use configurations. Devices with a headset output should be tested with a headset connected to the device. For purpose of determining test requirements, accessories may be divided into two categories: those that do not contain metallic components and those that do.

#### When multiple accessories

When multiple accessories that do not contain metallic components are supplied with the device, the device may be tested with only the accessory that dictates the closest spacing to the body. When multiple accessories that contain metallic components are supplied with the device, the device must be tested with each accessory that contains a unique metallic component. If multiple accessories share an identical metallic component (e.g., the same metallic belt-clip used with different holsters with no other metallic components), only the accessory that dictates the closest spacing to the body must be tested.

#### Without the belt-clips or holsters

Body-worn accessories may not always be supplied or available as options for some devices that are intended to be authorized for body-worn use. A separation distance of 1.5 cm between the back of the device and a flat phantom is recommended for testing body-worn SAR compliance under such circumstances. Other separation distances may be used, but they should not exceed 2.5 cm. In these cases, the device may use body-worn accessories that provide a separation distance greater than that tested for the device provided however that the accessory contains no metallic components.

#### Transmitter that is designed to operate in front of a person's face (face-held)

Transmitters that are designed to operate in front of a person's face, in push-to-talk configurations, should be tested for SAR compliance with the front of the device positioned at 2.5 cm from a flat phantom. Frontal face-phantoms are typically not recommended because of the potential of higher E-field probe boundary-effects errors in the non-smooth regions of these face phantoms, such as the nose, lips and eyes etc. For devices that are carried next to the body, such as shoulder, waist or chest-worn transmitters, SAR compliance should be tested with the accessories, including headsets and microphones, attached to the device and positioned against a flat phantom in normal use configurations.

#### With neck-strap or lanyard

SAR data is requested for cellphones designed to be used with a headset while worn next to the body using a neck-strap or lanyard; device should be tested with front and back sides in contact with a flat phantom

#### 🛛 Lap-held

SAR is tested for a lap-held position with the bottom of the computer in direct contact against a flat phantom.

## 7 SIMULATING LIQUID PARAMETERS CHECK

The simulating liquids should be checked at the beginning of a series of SAR measurements to determine of the dielectric parameters are within the tolerances of the specified target values. The relative permittivity and conductivity of the tissue material should be within  $\pm$  5% of the values given in the table below.



Set-up for liquid parameters check

## Reference Values of Tissue Dielectric Parameters for Head and Body Phantom

The head tissue dielectric parameters recommended by the IEEE SCC-34/SC-2 in IEEE Standard 1528 have been incorporated in the following table. These head parameters are derived from planar layer models simulating the highest expected SAR for the dielectric properties and tissue thickness variations in a human head. Other head and body tissue parameters that have not been specified in P1528 are derived from the tissue dielectric parameters computed from the 4-Cole-Cole equations and extrapolated according to the head parameters specified in IEEE Standard 1528.

Target Frequency (MHz)	He	ad	Body		
raiget i requeitcy (Miliz)	ε <sub>r</sub>	σ (S/m)	ε <sub>r</sub>	σ (S/m)	
150	52.3	0.76	61.9	0.80	
300	45.3	0.87	58.2	0.92	
450	43.5	0.87	56.7	0.94	
835	41.5	0.90	55.2	0.97	
900	41.5	0.97	55.0	1.05	
915	41.5	0.98	55.0	1.06	
1450	40.5	1.20	54.0	1.30	
1610	40.3	1.29	53.8	1.40	
1800 – 2000	40.0	1.40	53.3	1.52	
2450	39.2	1.80	52.7	1.95	
3000	38.5	2.40	52.0	2.73	
5800	35.3	5.27	48.2	6.00	

( $\varepsilon_r$  = relative permittivity,  $\sigma$  = conductivity and  $\rho$  = 1000 kg/m<sup>3</sup>)

## 7.1 SIMULATING LIQUID PARAMETER CHECK RESULT

Simulating Liquid Dielectric Parameter Check Result @ Muscle 2450 MHz

Room Ambient Temperature =24.5°C; Relative humidity = 35%

Measured by: Sunny Shih

Simulating Liquid		Parameters		Target	Measured	Deviation (%)	Limit (%)				
f (MHz)	Temp. (°C)	Depth (cm)		T didificitio	raiget	Medodred	Deviation (70)	Linit (70)			
2450 23.5		15	с"	Relative Permittivity ( $\varepsilon_r$ ):	52.7	51.9324	-1.46	± 5			
2400	20.0	10	14.0411	Conductivity ( $\sigma$ ):	1.95	1.91375	-1.86	± 5			
Simulating	Simulating Liquid Dielectric Parameters Check @ 2450 MHz										
Room Am	bient Terr	perature:	24.5 deg	. C, Liquid temperatu	re: 23.5 d	eg. C					
February	15, 2005 <i>°</i>	10:26 AM									
<b>F</b>		- 1		- "							
Frequenc	y Noo	e <sup>r</sup>	004	e" 40.0055							
24000000	00.	52.2	234	13.8055							
24100000	00.	52.1	246	13.8677							
24200000	000.	52.0	399	13.9129							
24300000	000.	51.9	661	13.9418							
24400000	000.	51.9	423	14.0057							
<mark>24500000</mark>	00.	51.9	324	14.0411							
24600000	000.	51.9	187	14.0896							
24700000	00.	51.9	332	14.0945							
24800000	00.	51.9	549	14.1094							
24900000	00.	51.9	645	14.1517							
25000000	000.	51.9	294	14.1847							
The condu	uctivity (ơ)	can be gi	ven as:								
$\sigma = \omega \varepsilon_{\theta}  \mathbf{e}'' = 2  \pi f  \varepsilon_{\theta}  \mathbf{e}''$											
where $f$	= target f *	· 10 <sup>6</sup>									
<b>E</b> 0	= 8.854 * 1	0-12									

#### Simulating Liquid Dielectric Parameter Check Result @ Muscle 2450 MHz

Room Ambient Temperature =24.5°C; Relative humidity = 38%

Measured by: Sunny Shih

Simulating Liquid			Parameters	Target	Measured	Deviation (%)	Limit (%)		
f (MHz)	Temp. (°C)	Depth (cm)			-				
2450 23.5		15	с"	Relative Permittivity ( $\varepsilon_r$ ):	52.7	51.7075	-1.88	± 5	
1.00			14.1472         Conductivity (σ):         1.95         1.92822         -1.12					± 5	
Simulating Liquid Dielectric Parameters Check @ 2450 MHz									
Room Am	bient Terr	perature:	24.5 deg	. C, Liquid temperatu	re: 23.5 d	eg. C			
February	16, 2005 <sup>-</sup>	10:07 AM	-			-			
Frequenc	у	e'		e"					
24000000	00.	52.0	020	13.9213					
24100000	00.	51.9	117	13.9661					
24200000	00.	51.8	181	14.0159					
24300000	00.	51.7	623	14.0528					
24400000	00.	51.7	204	14.1143					
<mark>24500000</mark>	00.	51.7	075	14.1472					
24600000	00.	51.6	822	14.2043					
24700000	00.	51.6	954	14.2199					
24800000	000.	51.7	'155	14.2307					
24900000	000.	51.7	'129	14.2752					
25000000	000.	51.6	942	14.2917					
The conductivity ( $\sigma$ ) can be given as:									
$\sigma = \omega \varepsilon_{\theta}  \mathbf{e}'' = 2  \pi f  \varepsilon_{\theta}  \mathbf{e}''$									
where $f$	= target f *	$10^{6}$							
EO	= 8.854 * 1	10-12							

## 8 SYSTEM PERFORMANCE CHECK

The system performance check is performed prior to any usage of the system in order to guarantee reproducible results. The system performance check verifies that the system operates within its specifications of  $\pm 10\%$ .

#### System Performance Check Measurement Conditions

- The measurements were performed in the flat section of the SAM twin phantom filled with Body simulating liquid of the following parameters.
- The DASY4 system with an Isotropic E-Field Probe EX3DV3-SN: 3531 was used for the measurements.
- The dipole was mounted on the small tripod so that the dipole feed point was positioned below the center marking of the flat phantom section and the dipole was oriented parallel to the body axis (the long side of the phantom). The standard measuring distance was 10 mm (above 1 GHz) and f 15 mm (below 1 GHz) from dipole center to the simulating liquid surface.
- The coarse grid with a grid spacing of 15 mm was aligned with the dipole.
- Special 5 x 5 x 7 fine cube was chosen for cube integration(dx=dy=7.5mm; dz=5mm).
- Distance between probe sensors and phantom surface was set to 2.5 (below 3 G) mm.
- The dipole input power (forward power) was 250 mW±3%.
- The results are normalized to 1 W input power.

## Reference SAR Values

The reference SAR values were using measurement results indicated in the dipole calibration document (See attached dipole certificate).

f (MHz)	Head	Tissue	Body Tissue		
	SAR <sub>1g</sub>	SAR 10g	SAR <sub>1g</sub>	SAR 10g	
2450	52.0	23.8	54.8	25.4	

## 8.1 SYSTEM PERFORMANCE CHECK RESULTS

@ System Validation Dipole: D2450V2 SN: 748

Ambient Temperature = 24.5°C, Relative humidity = 35%

Body Simulating Liquid			Mrasured	Target	Deviation[%]	Limit [%]	
f(MHz)	Temp.[°C]	Depth [cm]	1 g	Normalized to 1 W	Target_1g	Deviation[%]	LIIIIIL [70]
2450	23.5	15	12.7	50.8	54.8	-7.30	± 10

@ System Validation Dipole: D2450V2 SN: 748

Ambient Temperature = 24.5°C, Relative humidity = 38%

Date: February 16, 2005

Date: February 15, 2005

Measured by: Sunny Shih

Measured by: Sunny Shih

Body Simulating Liquid				Mrasured	Target .	Doviation[%]	lim it [0/]
f(MHz)	Temp.[°C]	Depth [cm]	1 g	Normalized to 1 W	Target_1g	Deviation[%]	Emit [ /0 ]
2450	23.5	15	12.9	51.6	54.8	-5.84	± 10

## 9 SAR MEASUREMENT PROCEDURE

A summary of the procedure follows:

- a) A measurement of the SAR value at a fixed location is used as a reference value for assessing the power drop of the EUT. The SAR at this point is measured at the start of the test, and then again at the end of the test.
- b) The SAR distribution at the exposed flat section of the flat phantom is measured at a distance of 2.5 (below 3 G) mm from the inner surface of the shell. The area covers the entire dimension of the EUT and the horizontal grid spacing is 15 mm x 15 mm. Based on this data, the area of the maximum absorption is determined by Spline interpolation. The first Area Scan covers the entire dimension of the EUT to ensure that the hotspot was correctly identified.
- c) Around this point, a volume of X=Y=Z=30 mm is assessed by measuring 5 x 5 x 7 (below 5 G) mm points. On the basis of this data set, the spatial peak SAR value is evaluated with the following procedure:
  - (i) The data at the surface are extrapolated, since the centre of the dipoles is 1.2 mm away from the tip of the probe and the distance between the surface and the lowest measuring point is 1.3 mm. The extrapolation is based on a least square algorithm. A polynomial of the fourth order is calculated through the points in z-axes. This polynomial is then used to evaluate the points between the surface and the probe tip.
  - (ii) The maximum interpolated value is searched with a straightforward algorithm. Around this maximum the SAR values averaged over the spatial volumes (1 g and 10 g) are computed using the 3D-Spline interpolation algorithm. The 3D-Spline is composed of three one-dimensional splines with the "Not a knot"- condition (in x, y and z-direction). The volume is integrated with the trapezoidal algorithm. One thousand points (10 x 10 x 10) are interpolated to calculate the averages.
  - (iii) All neighbouring volumes are evaluated until no neighbouring volume with a higher average value is found.
  - (iv) The SAR value at the same location as in Step (a) is again measured to evaluate the actual power drift.

## DASY4 SAR MEASUREMENT PROCEDURE

#### **Step 1: Power Reference Measurement**

The Power Reference Measurement and Power Drift Measurements are for monitoring the power drift of the device under test in the batch process. The Minimum distance of probe sensors to surface determines the closest measurement point to phantom surface. The minimum distance of probe sensors to surface is 2.1 mm. This distance cannot be smaller than the Distance of sensor calibration points to probe tip as defined in the probe properties (for example, 1.2 mm for an EX3DV3 probe type).

#### Step 2: Area Scan

The Area Scan is used as a fast scan in two dimensions to find the area of high field values, before doing a fine measurement around the hot spot. The sophisticated interpolation routines implemented in DASY4 software can find the maximum locations even in relatively coarse grids. When an Area Scan has measured all reachable points, it computes the field maximal found in the scanned area, within a range of the global maximum. The range (in dB) is specified in the standards for compliance testing. For example, a 2 dB range is required in IEEE Standard 1528, EN 50361 and IEC 62209 standards, whereby 3 dB is a requirement when compliance is assessed in accordance with the ARIB standard (Japan). If only one Zoom Scan follows the Area Scan, then only the absolute maximum will be taken as reference. For cases where multiple maximums are detected, the number of Zoom Scans has to be increased accordingly.

#### Step 3: Zoom Scan

Zoom Scans are used to assess the peak spatial SAR values within a cubic averaging volume containing 1 g and 10 g of simulated tissue. The Zoom Scan measures  $5 \times 5 \times 7$  (below 5 G) points within a cube whose base faces are centered on the maxima found in a preceding area scan job within the same procedure. When the measurement is done, the Zoom Scan evaluates the averaged SAR for 1 g and 10 g and displays these values next to the job's label.

#### Step 4: Power drift measurement

The Power Drift Measurement measures the field at the same location as the most recent power reference measurement within the same procedure, and with the same settings. The Power Drift Measurement gives the field difference in dB from the reading conducted within the last Power Reference Measurement. This allows a user to monitor the power drift of the device under test within a batch process. The measurement procedure is the same as Step 1.

## Step 5: Z-Scan

The Z Scan measures points along a vertical straight line. The line runs along the Z-axis of a onedimensional grid. In order to get a reasonable extrapolation, the extrapolated distance should not be larger than the step size in Z-direction.

## 10 PROCEDURES USED TO ESTABLISH TEST SIGNAL

The following procedures had been used to prepare the EUT for the SAR test.

The client supplied a special driving program (ART\_v5.2 Build # 55) to program the EUT to continually transmit the specified maximum power and also to change the channel frequency.

Maximum conducted power was measured prior to SAR measurement.

The cable assembly insertion loss of 11 dB (including 10 dB pad and 1dB cable) was entered as an offset in the power meter to allow for direct reading of power.

#### 802.11b Mode

Channel	Frequency	Average Power		
	(MHz)	(dBm)		
Low	2412	16.60		
Middle	2437	16.60		
High	2462	16.45		

802.11g Mode

Channel	Frequency	Average Power
	(MHz)	(dBm)
Low	2412	15.20
Middle	2437	15.50
High	2462	15.12

802.11g Turbo Mode

Channel	Frequency	Average Power
	(MHz)	(dBm)
Middle	2437	15.30

#### 11 SAR MEASUREMENT RESULTS

#### 11.1 TEST POSITION 1 – MAIN ANTENNA (HTL017)



3) The SAR measured at the middle channel for this configuration is at least 3 dB lower than SAR limit, testing at low & high channel is optional.

4) Please see attachment for the detailed measurement data and plots showing the maximum SAR location of the EUT.

## 11.2 TEST POSITION 2 – AUX ANTENNA (HTL017)



5) The SAR measured at the middle channel for this configuration is at least 3 dB lower than SAR limit, testing at low & high channel is optional.

6) Please see attachment for the detailed measurement data and plots showing the maximum SAR location of the EUT.

## COMPLIANCE CERTIFICATION SERVICES

This report shall not be reproduced except in full, without the written approval of CCS.

# 11.3 TEST POSITION 1 - MAIN ANTENNA (HTL004)

					O O Main Antenna		
802.11b mode - D	uty cycle: 100%;	Crest factor: 1		Deptho	of liquid: 15 cm		
	, , , , , , , , , , , , , , , , , , ,	a "	(1) 4 1 1	Power refer	ence (V/m)* <sup>1)</sup>	SAR 10	a[mW/a]
Sep. aist. [mm]	Antenna	Cn.#	t [IVHz]	Before	After	Measured	Limit
	main	1	2412				1.6
0	main	6	2437	1.58	1.47	0.0110	1.6
	main	11	2462			-	1.6
802.11g mode - D	uty cycle: 100%	Crest factor: 1					
Ŭ	main	1	2412				1.6
	main	6	2437				1.6
0	main	turbo mode	2437	1.44	1.39	0.00557	1.6
	main	11	2462				1.6
Notes: 1) Power refer 2) SAR is teste 3) The SAR m channel is c 4) Please see	ence - The power ed for a lap-held p easured at the mi optional. attachment for the	drift measured position with the ddle channel fo e detailed meas	at same position bottom of the r this configura surement data a	on in liquid befo computer in dire tion is at least 3 and plots showin	re and after eacl ect contact again 3 dB lower than S ng the maximum	h SAR measurer st a flat phanton SAR limit, testing SAR location of	ment n. j at low & high i the EUT.

# 11.4 TEST POSITION 2 – AUX ANTENNA (HTL004)

802.11b mode - D	uty cycle: 100%;	Orest factor: 1		Depth o	f liquid: 15 cm				
Sep. dist. [mm]	Antenna	Ch.#	f[MHz]	Power refere	ence (V/m)* <sup>1)</sup>	SAR_1g[mW/g]			
		-	0140	Before	After	Measured	Limit		
	aux	1	2412	0.05	0.00	0.0450	10		
0	aux	0	2437	0.85	0.86	0.0159	1.0		
0	aux	6	2437	1.11	1.02	0.0160*-/	1.6		
			2462						
802.11g mode - D	uty cycle: 100%;	urest factor: 1	0440						
	aux	1	2412						
	aux	6	2437	0.00	0.00	0.0400	10		
0	aux	turbo mode	2437	0.90	0.89	0.0130	1.6		
Nataai	aux	11	2462						
<ol> <li>Power refer</li> <li>Power refer</li> <li>Co-located 3</li> <li>SAR is teste</li> <li>The SAR muchannel is o</li> <li>Please see</li> </ol>	ence - The power SAR measurement ad for a lap-held p easured at the mit potional.	drift measured nt result with the osition with the ddle channel fo	at same position WLAN and Bi bottom of the of this configura	on in liquid befor luetooth radio ca computer in dire tion is at least 3 and plots showir	re and after each ard (BC04). (Trai ct contact again: dB lower than S og the maximum	n SAR measuren nsmitting simulta st a flat phantom SAR limit, testing	nent. neously) at low & high the EUT		

## 12 EUT PHOTOS

EUT PHOTOS (1/1)





HOST DEVICE (1/2)





HOST DEVICE (2/2)







WLAN MODULE AND BLUETOOTH MODULE

**Bluetooth Module** 

Half Size Mini PCI WLAN Module

**ANTENNAS LOCATION (HTL017)** 





## **ANTENNAS LOCATION (HTL004)**





#### **13 MEASUREMENT UNCERTAINTY**

	Tol (+%) Probe	Div	$O(4\pi)$	C: (40 m)	Std. Unc.(±%)		
	101. (±%)	Dist.	Div.	Ci (1g)	Ci (10g)	Ui (1g)	Ui(10g)
Measurement System							
Probe Calibration	4.80	N	1	1	1	4.80	4.80
Axial Isotropy	4.70	R	1.732	0.707	0.707	1.92	1.92
Hemispherical Isotropy	9.60	R	1.732	0.707	0.707	3.92	3.92
Boundary Effects	1.00	R	1.732	1	1	0.58	0.58
Linearity	4.70	R	1.732	1	1	2.71	2.71
System Detection Limits	1.00	R	1.732	1	1	0.58	0.58
Readout Electronics	1.00	N	1	1	1	1.00	1.00
Response Time	0.80	R	1.732	1	1	0.46	0.46
Integration Time	2.60	R	1.732	1	1	1.50	1.50
RF Ambient Conditions - Noise	1.59	R	1.732	1	1	0.92	0.92
RF Ambient Conditions - Reflections	0.00	R	1.732	1	1	0.00	0.00
Probe Positioner Mechnical Tolerance	0.40	R	1.732	1	1	0.23	0.23
Probe Positioning With Respect to Phantom Shell	2.90	R	1.732	1	1	1.67	1.67
Extrapolation, interpolation, and integration algorithms for							
max. SAR evaluation	3.90	R	1.732	1	1	2.25	2.25
Test sample Related				_			_
Test Sample Positioning	1.10	N	1	1	1	1.10	1.10
Device Holder Uncertainty	3.60	N	1	1	1	3.60	3.60
Power and SAR Drift Measurement	5.00	R	1.732	1	1	2.89	2.89
Phantom and Tissue Parameters							
Phantom Uncertainty	4.00	R	1.732	1	1	2.31	2.31
Liquid Conductivity - Target	5.00	R	1.732	0.64	0.43	1.85	1.24
Liquid Conductivity - Meas.	8.60	Ν	1	0.64	0.43	5.50	3.70
Liquid Permittivity - Target	5.00	R	1.732	0.6	0.49	1.73	1.41
Liquid Permittivity - Meas.	3.30	N	1	0.6	0.49	1.98	1.62
Combined Standard Uncertainty			RSS			11.44	10.49
Expanded Uncertainty (95% Confidence Interval)			K=2			22.87	20.98
Notesfor table 1. Tol tolerance in influence quaitity 2. N - Nomal							

3. R - Rectangular

4. Div. - Divisor used to obtain standard uncertainty

5. Ci - is te sensitivity coefficient

## 14 EQUIPMENT LIST & CALIBRATION

Name of Equipment	Manufacturer	Type/Model	Serial Number	Cal. Due date
Robot - Six Axes	Stäubli	RX90BL	N/A	N/A
Robot Remote Control	Stäubli	CS7MB	3403-91535	N/A
DASY4 Measurement Server	SPEAG	SEUMS001BA	1041	N/A
Probe Alignment Unit	SPEAG	LB (V2)	261	N/A
S-Parameter Network Analyzer	Agilent	8753ES-6	US39173569	8/19/05
Electronic Probe kit	Hewlett Packard	85070C	N/A	N/A
E-Field Probe	SPEAG	EX3DV3	3531	7/18/05
Thermometer	ERTCO	639-1	8402	10/13/2005
Thermometer	ERTCO	639-1	8404	10/21/2005
Thermometer	ERTCO	637-1	8661	10/21/2005
SAM Phantom (SAM1)	SPEAG	TP-1185	QD000P40CA	N/A
SAM Phantom (SAM2)	SPEAG	TP-1015	N/A	N/A
Data Acquisition Electronics	SPEAG	DAE3 V1	427	3/15/05
System Validation Dipole	SPEAG	D2450V2	748	5/14/06
Signal General	R&H	SMP 04	DE34210	5/5/05
Power Meter	Giga-tronics	8651A	8651404	9/16/05
Power Sensor	Giga-tronics	80701A	1834588	9/16/05
Amplifier	Mini-Circuits	ZVE-8G	0360	N/A
Amplifier	Mini-Circuits	ZHL-42W	D072701-5	N/A
Radio Communication Tester	Rohde & Schwarz	CMU 200	838114/032	12/17/05
Simulating Liquid	CCS	M2450	N/A	within 24 hrs of first test

## **15 ATTACHMENT**

No.	Contents	No. of page (s)
1	System Performance Check Plots	4
2	SAR Test Plots	14
3	Certificate of E-filed Probe EX3DV3 SN 3521	8
4	Certificate of System Validation Dipole D2450V2 SN 748	9

#### END OF REPORT