

# SAR TEST REPORT

**REPORT NO.:** SA940915L13

MODEL NO.: MC7090

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# 1. CERTIFICATION

**PRODUCT:** EDA (Enterprise Digital Assistant)

**MODEL NO.** : MC7090

**BRAND NAME:** Symbol

APPLICANT: Symbol Technologies, Inc.

**TESTED:** Sep. 28 ~ Oct. 06 2005

**TEST SAMPLE:** ENGINEERING SAMPLE

**STANDARDS:** FCC Part 2 (Section 2.1093), FCC OET Bulletin 65,

Supplement C (01-01), RSS-102

The above equipment has been tested by **Advance Data Technology Corporation**, and found compliance with the requirement of the above standards. The test record, data evaluation & Equipment Under Test (EUT) configurations represented herein are true and accurate accounts of the measurements of the sample's EMC characteristics under the conditions specified in this report.

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# 2. GENERAL INFORMATION

# 2.1 GENERAL DESCRIPTION OF EUT

PRODUCT	EDA (Enterprise Digital Assistant)
MODEL NO.	MC7090
POWER SUPPLY	3.7Vdc from rechargeable lithium battery 5.4Vdc from power adapter for charger 12.0Vdc from power adapter for cradle
CLASSIFICATION	Portable device, production unit
MODULATION TYPE	WLAN: CCK, DQPSK, DBPSK for DSSS 64QAM, 16QAM, QPSK, BPSK for OFDM Bluetooth: GFSK for FHSS
TRANSFER RATE	WLAN: 802.11b:11/5.5/2/1Mbps 802.11g: 54/48/36/24/18/12/9/6Mbps 802.11a: 54/48/36/24/18/12/9/6Mbps Bluetooth: 723Kbps
FREQUENCY RANGE	WLAN: 802.11b & 802.11g: 2412 ~ 2462MHz 802.11a: 5745 ~ 5825MHz Bluetooth: 2402 ~ 2480MHz
ANTENNA TYPE	WLAN: PIFA antenna with 2.0dBi gain (for 2.4GHz) PIFA antenna with 2.5dBi gain (for 5.0GHz) Bluetooth: Chip antenna with 2.0dBi gain



	Bluetooth: 0.873mW / 2402.0MHz for channel 0 0.979mW / 2441.0MHz for channel 39 1.057mW / 2480.0MHz for channel 78		
CHANNEL FREQUENCIES UNDER TEST AND ITS MAX. CONDUCTED OUTPUT POWER	2.4GHz WLAN: 22.699mW / 2412.0MHz for channel 1 for DSSS 40.551mW / 2437.0MHz for channel 6 for DSSS 25.468mW / 2462.0MHz for channel 11 for DSSS 22.699mW / 2412.0MHz for channel 1 for OFDM 44.771mW / 2437.0MHz for channel 6 for OFDM 25.410mW / 2462.0MHz for channel 11 for OFDM		
	5.0GHz WLAN: 26.730mW / 5180.0MHz for channel 36 19.454mW / 5240.0MHz for channel 48 18.578mW / 5260.0MHz for channel 52 17.298mW / 5320.0MHz for channel 64 40.365mW / 5745.0MHz for channel 149 40.0.87mW / 5785.0MHz for channel 157 40.551mW / 5825.0MHz for channel 165		
MAX. AVERAGE SAR (1g)	Head: 0.021W/kg (Bluetooth band) 0.436W/kg (2.4GHz WLAN band) 1.270W/kg (5.0GHz WLAN band)		
MAX. AVEITAGE GAIT (19)	Body: 0.000171W/kg (Bluetooth band) 0.127W/kg (2.4GHz WLAN band) 0.223W/kg (5.0GHz WLAN band)		
DATA CABLE	0.92m non-shielded cable for earphone		
I/O PORTS	Refer to user's manual		
ASSOCIATED DEVICES	EVICES Earphone, cradle		



#### NOTE:

- 1. The EUT is an EDA (Enterprise Digital Assistant) with wireless LAN and bluetooth functions.
- 2. The EUT operates in both the 5.0GHz and 2.4GHz Bands and compatibility with 802.11a and 802.11b, 802.11g technology.
- 3. The wireless LAN included two dual band antennas. After pre-testing both primary and auxiliary antennas, the former as the worst case, was chosen for final test.
- 4. The EDA supports two battery options, Heavy (high capacity) and Main (normal). Both options were assessed and the heavy battery was found to be worst case and was selected for the final test configuration.

HEAVY BATTERY:					
BRAND: Symbol					
MODEL: 82-71364-01					
RATING: 3.7Vdc, 3800mAh					

MAIN BATTERY:					
BRAND: Symbol					
MODEL: 82-71363-01					
RATING: 3.7Vdc, 1900mAh					

5. The cradle was operated with following power adapter:

BRAND:	HIPRO		
MODEL: HP-O2040D43			
INPUT:	100-240Vac, 50-60Hz, 1.5A		
OUTPUT:	12Vdc, 3.33A		
	AC 1.8m non-shielded cable without core DC 1.8m non-shielded cable with one core		

6. The EUT was operated with following charging cable:

BRAND:	Delta			
MODEL:	ADP-16GB A			
INPUT: 100-240Vac, 50-60Hz, 0.4A				
OUTPUT: 5.4Vdc, 3A				
POWER LINE:	AC 0.7m non-shielded cable without core DC 1.87m non-shielded cable with one core			

- 7. The EDA supports two keypad options, Querty or Numeric. Both options were assessed and the Numeric was found to be worst case and was selected for the final test configuration.
- 8. The above EUT information was declared by manufacturer and for more detailed features description, please refer to the manufacturer's specifications or User's Manual.



# 2.2 GENERAL DESCRIPTION OF APPLIED STANDARDS

According to the specifications of the manufacturer, this product must comply with the requirements of the following standards:

FCC Part 2 (2.1093)

FCC OET Bulletin 65, Supplement C (01-01)

**RSS-102** 

IEEE 1528-2003

All test items have been performed and recorded as per the above standards.



### 2.3 GENERAL INOFRMATION OF THE SAR SYSTEM

DASY4 (software 4.5 Build 19) consists of high precision robot, probe alignment sensor, phantom, robot controller, controlled measurement server and near-field probe. The robot includes six axes that can move to the precision position of the DASY4 software defined. The DASY4 software can define the area that is detected by the probe. The robot is connected to controlled box. Controlled measurement server is connected to the controlled robot box. The DAE includes amplifier, signal multiplexing, AD converter, offset measurement and surface detection. It is connected to the Electro-optical coupler (ECO). The ECO performs the conversion form the optical into digital electric signal of the DAE and transfers data to the PC.

### ET3DV6 ISOTROPIC E-FIELD PROBE (FREQUENCY BAND < 3GHz)

**CONSTRUCTION** Symmetrical design with triangular core.

Built-in optical fiber for surface detection system.

Built-in shielding against static charges.

PEEK enclosure material (resistant to organic solvents,

e.g., glycolether).

**FREQUENCY** 10 MHz to 3 GHz; Linearity: ± 0.2 dB (30 MHz to 3 GHz)

**DYNAMIC RANGE** 5  $\mu$ W/g to > 100 mW/g; Linearity:  $\pm$  0.2 dB

**OPTICAL SURFACE DETECTION** ± 0.2 mm repeatability in air and clear liquids over diffuse

reflecting surfaces

**DIMENSIONS** Overall length: 330 mm (Tip Length: 16 mm)

Tip diameter: 6.8 mm (Body diameter: 12 mm) Distance from probe tip to dipole centers: 2.7 mm

**APPLICATION** General dosimetric measurements up to 3 GHz

Fast automatic scanning in arbitrary phantoms (ET3DV6)

### EX3DV3 ISOTROPIC E-FIELD PROBE (FREQUENCY BAND 5 ~ 6GHz)

**DIMENSIONS** Overall length: 330 mm (Tip Length: 20 mm)

Tip diameter: 2.5 mm (Body diameter: 12 mm)
Distance from probe tip to dipole centers: 1.0 mm

**APPLICATION** General dosimetric measurements range 5 ~ 6 GHz.

Fast automatic scanning in arbitrary phantoms (EX3DV3)

NOTE: The Probe parameters have been calibrated by the SPEAG. Please reference "APPENDIX D"

for the Calibration Certification Report.



### SYSTEM VALIDATION KITS:

**CONSTRUCTION** Symmetrical dipole with I/4 balun

Enables measurement of feedpoint impedance with NWA Matched for use near flat phantoms filled with brain

simulating solutions

Includes distance holder and tripod adaptor

**CALIBRATION** Calibrated SAR value for specified position and input

power at the flat phantom in brain simulating solutions

**FREQUENCY** 2450, 5200, 5800MHz

**RETURN LOSS** > 20 dB at specified validation position

**POWER CAPABILITY** > 100 W (f < 1 GHz); > 40 W (f > 1 GHz)

**OPTIONS** Dipoles for other frequencies or solutions and other

calibration conditions upon request

**OPTIONS** Dipoles for other frequencies or solutions and other

calibration conditions upon request

**TWIN SAM V4.0** 

**CONSTRUCTION** The shell corresponds to the specifications of the Specific

Anthropomorphic Mannequin (SAM) phantom defined in IEEE 1528-2003, CENELEC 50361 and IEC 62209. It enables the dosimetric evaluation of left and right hand phone usage as well as body mounted usage at the flat phantom region. A cover prevents evaporation of the liquid. Reference markings on the phantom allow the complete

setup of all predefined phantom positions and

measurement grids by manually teaching three points with

the robot.

SHELL THICKNESS  $2 \pm 0.2 \text{ mm}$ 

FILLING VOLUME Approx. 25 liters

**DIMENSIONS** Height: 810 mm; Length: 1000 mm; Width: 500 mm



#### **DEVICE HOLDER FOR SAM TWIN PHANTOM**

#### CONSTRUCTION

The device holder for the mobile phone device is designed to cope with different positions given in the standard. It has two scales for the device rotation (with respect to the body axis) and the device inclination (with respect to the line between the ear reference points). The rotation centers for both scales is the ear reference point (ERP). Thus the device needs no repositioning when changing the angles. The holder has been made out of low-loss POM material having the following dielectric parameters: relative permittivity  $\varepsilon$  =3 and loss tangent  $\delta$  =0.02. The amount of dielectric material has been reduced in the closest vicinity of the device, since measurements have suggested that the influence of the clamp on the test results could thus be lowered. The device holder for the portable device makes up of the polyethylene foam. The dielectric parameters of material close to the dielectric parameters of the air.

### **DATA ACQUISITION ELECTRONICS**

#### CONSTRUCTION

The data acquisition electronics (DAE3) consists of a highly sensitive electrometer grade preamplifier with autozeroing, a channel and gain-switching multiplex, a fast 16 bit AD converter and a command decoder and control logic unit. Transmission to the measurement server is accomplished through an optical downlink for data and status information as well as an optical uplink for commands and the clock. The mechanical probe is mounting device includes two different sensor systems for frontal and sideways probe contacts. They are used for mechanical surface detection and probe collision detection. The input impedance of the DAE3 box is 200MOhm; the inputs are symmetrical and floating. Common mode rejection is above 80 dB.



### 2.4 GENERAL DESCRIPTION OF THE SPATIAL PEAK SAR EVALUATION

The DASY4 post-processing software (SEMCAD) automatically executes the following procedures to calculate the field units from the micro-volt readings at the probe connector. The parameters used in the evaluation are stored in the configuration modules of the software:

Probe parameters: - Sensitivity Norm<sub>i</sub>, a<sub>i0</sub>, a<sub>i1</sub>, a<sub>i2</sub>

 $\hbox{- Conversion factor} \qquad \qquad \hbox{ConvF}_i$ 

- Diode compression point dcp<sub>i</sub>

Device parameters: - Frequency F

- Crest factor cf

Media parameters: - Conductivity  $\sigma$ 

- Density  $\rho$ 

The first step of the evaluation is a linearization of the filtered input signal to account for the compression characteristics of the detector diode. The compensation depends on the input signal, the diode type and the DC-transmission factor from the diode to the evaluation electronics. If the exciting field is pulsed, the crest factor of the signal must be known to correctly compensate for peak power. The formula for each channel can be given as:

$$V_i = U_i + U_i^2 \bullet \frac{cf}{dcp_i}$$

 $V_i$  =compensated signal of channel i (i = x, y, z)

 $U_i$  =input signal of channel I (i = x, y, z)

cf =crest factor of exciting field (DASY parameter)

dcp<sub>i</sub> =diode compression point (DASY parameter)



From the compensated input signals the primary field data for each channel can be evaluated:

E-field  
probes : 
$$E_i = \sqrt{\frac{V_1}{Norm_i \cdot ConvF}}$$

H-fieldprobes: 
$$H_i = \sqrt{V_i} \cdot \frac{a_{i0} + a_{i1}f + a_{i2}f^2}{f}$$

 $V_i$  = compensated signal of channel I (i = x, y, z)

Norm<sub>i</sub> =sensor sensitivity of channel i  $\mu V/(V/m)$ 2 for E-field Probes (i = x, y, z)

ConvF = sensitivity enhancement in solution

a<sub>ii</sub> = sensor sensitivity factors for H-field probes

F = carrier frequency [GHz]

E<sub>i</sub> = electric field strength of channel i in V/m

H<sub>i</sub> = magnetic field strength of channel i in A/m

The RSS value of the field components gives the total field strength (Hermitian magnitude):

$$E_{tot} = \sqrt{E_x^2 + E_y^2 + E_z^2}$$

The primary field data are used to calculate the derived field units.

$$SAR = E_{tot}^2 \cdot \frac{o}{p \cdot 1'000}$$

SAR = local specific absorption rate in mW/g

E<sub>tot</sub> = total field strength in V/m

o = conductivity in [mho/m] or [Siemens/m]

p = equivalent tissue density in g/cm3



Note that the density is set to 1, to account for actual head tissue density rather than the density of the tissue simulating liquid. The entire evaluation of the spatial peak values is performed within the Post-processing engine (SEMCAD). The system always gives the maximum values for the 1 g and 10 g cubes. The algorithm to find the cube with highest averaged SAR is divided into the following stages:

- 1. The extraction of the measured data (grid and values) from the Zoom Scan
- 2. The calculation of the SAR value at every measurement point based on all stored data (A/D values and measurement parameters)
- 3. The generation of a high-resolution mesh within the measured volume
- 4. The interpolation of all measured values from the measurement grid to the high-resolution grid
- 5. The extrapolation of the entire 3-D field distribution to the phantom surface over the distance from sensor to surface
- 6. The calculation of the averaged SAR within masses of 1g and 10g.

The probe is calibrated at the center of the dipole sensors that is located 1 to 2.7mm away from the probe tip. During measurements, the probe stops shortly above the phantom surface, depending on the probe and the surface detecting system. Both distances are included as parameters in the probe configuration file. The software always knows exactly how far away the measured point is from the surface. As the probe cannot directly measure at the surface, the values between the deepest measured point and the surface must be extrapolated. The angle between the probe axis and the surface normal line is less than 30 degree.

In the Area Scan, the gradient of the interpolation function is evaluated to find all the extreme of the SAR distribution. The uncertainty on the locations of the extreme is less than 1/20 of the grid size. Only local maximum within –2 dB of the global maximum are searched and passed for the Cube Scan measurement. In the Cube Scan, the interpolation function is used to extrapolate the Peak SAR from the lowest measurement points to the inner phantom surface (the extrapolation distance). The uncertainty increases with the extrapolation distance. To keep the uncertainty within 1% for the 1 g and 10 g cubes, the extrapolation distance should not be larger than 5mm.



The maximum search is automatically performed after each area scan measurement. It is based on splines in two or three dimensions. The procedure can find the maximum for most SAR distributions even with relatively large grid spacing. After the area scanning measurement, the probe is automatically moved to a position at the interpolated maximum. The following scan can directly use this position for reference, e.g., for a finer resolution grid or the cube evaluations. The 1g and 10g peak evaluations are only available for the predefined cube 7x7x7 scans. The routines are verified and optimized for the grid dimensions used in these cube measurements. The measured volume of 30x30x30mm contains about 30g of tissue. The first procedure is an extrapolation (incl. Boundary correction) to get the points between the lowest measured plane and the surface. The next step uses 3D interpolation to get all points within the measured volume in a 1mm grid (42875 points). In the last step, a 1g cube is placed numerically into the volume and its averaged SAR is calculated. This cube is the moved around until the highest averaged SAR is found. If the highest SAR is found at the edge of the measured volume, the system will issue a warning: higher SAR values might be found outside of the measured volume. In that case the cube measurement can be repeated, using the new interpolated maximum as the center.

# 3. DESCRIPTION OF SUPPORT UNITS

NA

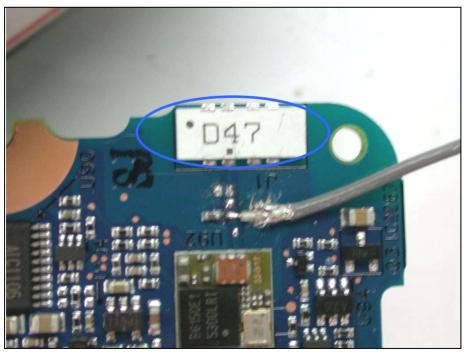


# 4. DESCRIPTION OF TEST POSITION

# 4.1. DESCRIPTION OF ANTENNA LOCATION

# **BLUETOOTH ANTENNA:**







# **WIRELESS LAN ANTENNA: MAIN ANTENNA**

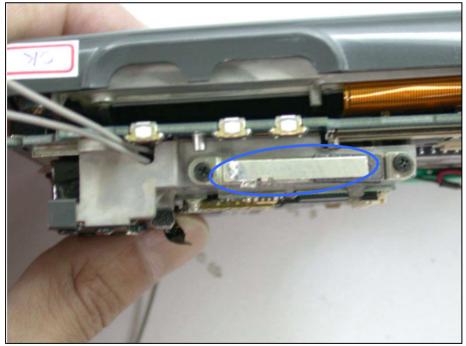






# **AUXILIARY ANTENNA**







# 4.2. DESCRIPTION OF TEST POSITION

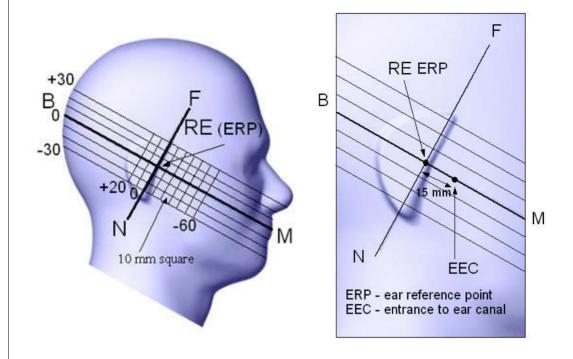
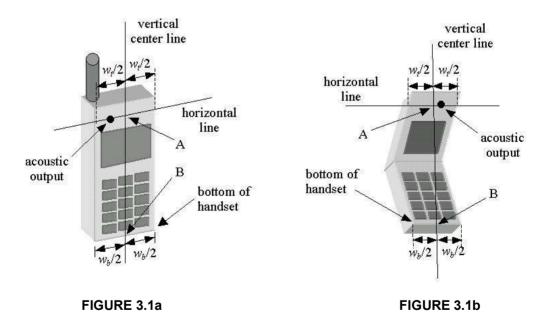


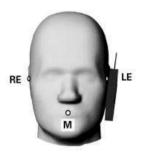
FIGURE 3.1



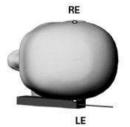


### 4.2.1. TOUCH/CHEEK TEST POSITION

The head position in Figure 3.1, the ear reference points ERP are 15mm above entrance to ear canal along the B-M line. The line N-F (Neck-Front) is perpendicular to the B-M (Back Mouth) line. The handset device in Figure 3.1a and 3.1b, The vertical centerline pass through two points on the front side of handset: the midpoint of the width wt of the handset at the level of the acoustic output (point A) and the midpoint of the width Wb of the bottom of the handset (point B). The vertical centerline is perpendicular to the horizontal line and pass through the center of the acoustic output. The point A touches the ERP and the vertical centerline of the handset is parallel to the B-M line. While maintaining the point A contact with the ear(ERP), rotate the handset about the line NF until any point on handset is in contact with the cheek of the phantom







**TOUCH/CHEEK POSITION FIGURE** 

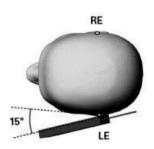


#### 4.2.2. TILT TEST POSITION

Adjust the device in the cheek position. While maintaining a point of the handset contact in the ear, move the bottom of the handset away from the mouth by an angle of 15 degrees.







**TILT POSITION FIGURE** 

### 4.2.3. BODY-WORN CONFIGURATION

The handset device attached the belt clip or the holster. The keypad face of the handset is against with the bottom of the flat phantom face and the bottom of the keypad face contact to the bottom of the flat phantom.

When multiple accessories that do not contain metallic components are supplied with the device, the device may be tested with only the accessory that dictates the closest spacing to the body. When multiple accessories that contain metallic components are supplied with the device, the device must be tested with each accessory that contains a unique metallic component. If multiple accessories share an identical metallic component (e.g., the same metallic belt-clip used with different holsters with no other metallic components), only accessory that dictates the closest spacing to the body must be tested.



# 4.3. DESCRIPTION OF ASSESSMENT POSITION

The following test configurations have been applied in this test report:

# A. RIGHT HEAD POSITION:



# **B. LEFT HEAD POSITION:**





# **C. BODY POSITION:**

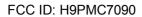
The front of the EUT with belt clip, contacted to the flat phantom with 0mm separation distance.





# 4.4. DESCRIPTION OF TEST MODE

TEST MODE	COMMUNICATION MODE	MODULATION TECHNOLOGY	ASSESSMENT POSTITION	TESTED CHANNEL	REMARK
1		DSSS	A / Cheek	L, M, H	-
2		DSSS	A / Tilt	L, M, H	-
3		DSSS	B / Cheek	L, M, H	-
4		DSSS	B / Tilt	L, M, H	-
5	)MI AN (0 40H-)	DSSS	С	L, M, H	-
6	WLAN (2.4GHz)	OFDM	A / Cheek	L, M, H	-
7		OFDM	A / Tilt	L, M, H	-
8		OFDM	B / Cheek	L, M, H	-
9		OFDM	B / Tilt	L, M, H	-
10		OFDM	С	L, M, H	-
11		GFSK	A / Cheek	L, M, H	-
12		GFSK	A / Tilt	L, M, H	-
13	Bluetooth	GFSK	B / Cheek	L, M, H	-
14		GFSK	B / Tilt	L, M, H	-
15		GFSK	С	L, M, H	-
16		OFDM	A / Cheek	36, 48, 52, 64, 149, 157, 165	-
17		OFDM	A / Tilt	36, 48, 52, 64, 149, 157, 165	-
18	WLAN (5.0GHz)	OFDM	B / Cheek	36, 48, 52, 64, 149, 157, 165	-
19		OFDM	B / Tilt	36, 48, 52, 64, 149, 157, 165	-
20		OFDM	С	36, 48, 52, 64, 149, 157, 165	-





TEST MODE	COMMUNICATION MODE	MODULATION TECHNOLOGY	ASSESSMENT POSTITION	TESTED CHANNEL	REMARK
21	WLAN (2.4GHz) + Bluetooth	NOTE	A / Cheek	NOTE	Co-located mode
22	WLAN (5.0GHz) + Bluetooth	NOTE	B / Tilt	NOTE	Co-located mode
23	WLAN (2.4GHz) + Bluetooth	NOTE	С	NOTE	Co-located mode
24	WLAN (5.0GHz) + Bluetooth	NOTE	С	NOTE	Co-located mode

**NOTE:** The combination is from the worst situation of each communication mode.



# 4.5. SUMMARY OF TEST RESULT

PART OF ASSESSMENT		HEAD POSITION						
COMMUNICATION		WLAN (2.4GHz)						
MODE		DSSS OFDM						
		MEASURED VALUE OF 1g SAR ( W/kg)						
	RIG	НТ	LE	FT	RIG	НТ	LE	FT
CHANNEL	CHEEK	TILT	CHEEK	TILT	CHEEK	TILT	CHEEK	TILT
LOW	0.251	0.174	0.180	0.149	0.156	0.122	0.108	0.095
MIDDLE	0.436	0.315	0.331	0.213	0.343	0.252	0.245	0.217
HIGH	0.206	0.153	0.149	0.132	0.189	0.128	0.124	0.121

**NOTE:** The worst value of each battery has been marked by boldface.

PART OF ASSESSMENT	BODY POSITION					
COMMUNICATION	WLAN (	2.4GHz)				
MODE	DSSS	OFDM				
CHANNEL	MEASURED VALUE OF 1g SAR ( W/kg)					
LOW	0.073	0.064				
MIDDLE	0.127	0.120				
HIGH	0.052 0.056					

**NOTE:** The worst value of each battery has been marked by boldface.



PART OF ASSESSMENT	HEAD POSITION							
COMMUNICATION MODE	BLUETOOTH							
	MEASURED VALUE OF 1g SAR ( W/kg)							
	RIG	ЭНТ	LEFT					
CHANNEL	CHEEK	TILT	CHEEK	TILT				
LOW	0.00764	0.00386	0.01600	0.00880				
MIDDLE	0.01300	0.00130	0.02000	0.00384				
HIGH	0.01500	0.00101	0.02100	0.00468				

**NOTE:** The worst value of each battery has been marked by boldface.

PART OF ASSESSMENT	BODY POSITION					
COMMUNICATION MODE	BLUETOOTH					
CHANNEL	MEASURED VALUE OF 1g SAR ( W/kg)					
LOW	0.0000566					
MIDDLE	0.0001090					
HIGH	0.0001710					

**NOTE:** The worst value of each battery has been marked by boldface.



PART OF ASSESSMENT	HEAD POSITION										
COMMUNICATION MODE		WLAN (5.0GHz)									
	MEASURED VALUE OF 1g SAR ( W/kg)										
	RIG	ЭНТ	LEFT								
CHANNEL	CHEEK	TILT	CHEEK	TILT							
36	0.744	0.876	0.959	1.010							
48	0.908	0.986	1.030	1.120							
52	0.892	1.010	1.050	1.150							
64	0.901	0.999	1.070	1.270							
149	0.309	0.342	0.359	0.469							
157	0.374	0.460	0.475	0.569							
165	0.462	0.533	0.552	0.658							

**NOTE:** The worst value of each battery has been marked by boldface.

PART OF ASSESSMENT	BODY POSITION
COMMUNICATION MODE	WLAN (5.0GHz)
CHANNEL	MEASURED VALUE OF 1g SAR ( W/kg)
36	0.169
48	0.223
52	0.213
64	0.184
149	0.059
157	0.057
165	0.112

**NOTE:** The worst value of each battery has been marked by boldface.



# TEST RESULT OF MULTI-BANDS CO-LOCATED ASSESSMENT:

The worst situation has been chosen from the above table, and make up 4 combinations for the test of co-location listed as below.

TEST MODE	DESCRIPTION	MEASURED VALUE OF 1g SAR ( W/kg)
41	WLAN (2.4GHz) middle channel + Bluetooth high channel	0.436
42	WLAN (5.0GHz) channel 64 + Bluetooth Low channel	1.270
43	WLAN (2.4GHz) middle channel + Bluetooth high channel	0.127
44	WLAN (5.0GHz) channel 48 + Bluetooth high channel	0.223



# 5. TEST RESULTS

#### 5.1 TEST PROCEDURES

Use the software to control the EUT channel and transmission power. Then record the conducted power before the testing. Place the EUT to the specific test location. After the testing, must writing down the conducted power of the EUT into the report. The SAR value was calculated via the 3D spline interpolation algorithm that has been implemented in the software of DASY4 SAR measurement system manufactured and calibrated by SPEAG. According to the IEEE P1528 standards, the recommended procedure for assessing the peak spatial-average SAR value consists of the following steps:

- Power reference measurement
- Area scan
- Zoom scan
- Power reference measurement

The area scan with 15mm x 15mm grid was performed for the highest spatial SAR location. The zoon scan with 30mm x 30mm x 30mm volume was performed for SAR value averaged over 1g and 10g spatial volumes.



In the zoon scan, the distance between the measurement point at the probe sensor location (geometric center behind the probe tip) and the phantom surface is 4.0 mm and maintained at a constant distance of  $\pm 1.0$  mm during a zoon scan to determine peak SAR locations. The distance is 4mm between the first measurement point and the bottom surface of the phantom. The secondary measurement point to the bottom surface of the phantom is with 9mm separation distance. The cube size is 7 x 7 x 7points consist of 343 points and the grid space is 5mm.

The measurement time is 0.5 s at each point of the zoon scan. The probe boundary effect compensation shall be applied during the SAR test. Because of the tip of the probe to the Phantom surface separated distances are longer than half a tip probe diameter

In the area scan, the separation distance is 4mm between the each measurement point and the phantom surface. The scan size shall be included the transmission portion of the EUT. The measurement time is the same as the zoon scan. At last the reference power drift shall be less than  $\pm 5\%$ .



# 5.2 MEASURED SAR RESULTS

# WLAN (2.4GHz) BAND RIGHT HEAD POSITION

EUT			EDA (Enterprise Digital Assistant)					EL	MC7090	MC7090		
	RONMENTA DITION	\L		Air Temperature:22.8°C, Liquid Temperature:21.5°C Humidity:61%RH								
TEST	ED BY		Sam C	)nn			DATE	=	Sep. 28	, 2005		
OUAN	EDEO (MIL)		ODE		ED POWER NW)	POV	VER	DEVICE USE	DEVICE TEST	MEASURED		
CHAN.	FREQ. (MHz)	IVI	ODE	BEGIN TEST	AFTER TEST	DRIF	Т (%)	POWER	POSITION MODE	1g SAR (W/kg)		
1	2412.00 (Low)	D	esss	22.699	22.265	-1.	91	Standard Battery	1	0.251		
6	2437.00 (Mid.)	D	esss	40.551	39.687	-2.	.13	Standard Battery	1	0.436		
11	2462.00 (High)	D	esss	25.468	25.020	-1.	76	Standard Battery	1	0.206		
1	2412.00 (Low)	D	sss	22.699	22.163	-2.	.36	Standard Battery	2	0.174		
6	2437.00 (Mid.)	DSSS		40.551	39.910	-1.	1.58 Standard Battery		2	0.315		
11	2462.00 (High)	D	esss	25.468	24.933	-2.10		-2.10 Standard Battery		0.153		

- 1. Test configuration of each mode is described in section 3.
- $2. \ \ In this testing, the limit for General Population Spatial Peak averaged over {\it 1g, 1.6W/kg}, is applied.$
- 3. Please see the Appendix A for the data, and Appendix E for the photo of the test configuration.
- 4. The variation of the EUT conducted power measured before and after SAR testing should not over 5%.



# WLAN (2.4GHz) BAND LEFT HEAD POSITION

EUT			EDA (Enterprise Digital Assistant)					EL	MC7090	MC7090	
	RONMENTA DITION	\L	Air Temperature:22.8°C, Liquid Temperature:21.5°C Humidity:61%RH								
TEST	ED BY		Sam C	)nn			DATI	<b>=</b>	Sep. 28,	2005	
CHAN	FREQ. (MHz)		ODE		ED POWER W)	POV	VER	DEVICE USE	DEVICE TEST	MEASURED	
CHAN.	FREQ. (MHZ)	IV	ODE	BEGIN TEST	AFTER TEST	DRIF	T (%)	POWER	POSITION MODE	1g SAR (W/kg)	
1	2412.00 (Low)	D	esss	22.699	22.097	-2.	65	Standard Battery	3	0.180	
6	2437.00 (Mid.)	D	esss	40.551	40.105	-1.	10	Standard Battery	3	0.331	
11	2462.00 (High)	D	esss	25.468	24.905	-2.	21	Standard Battery	3	0.149	
1	2412.00 (Low)	D	sss	22.699	22.204	-2.	18	Standard Battery	4	0.149	
6	2437.00 (Mid.)	D	esss	40.551	39.635	-2.	26	Standard Battery	4	0.213	
11	2462.00 (High)	D	esss	25.468	25.142	-1.	28	Standard Battery	4	0.132	

- 1. Test configuration of each mode is described in section 3.
- $2. \ \ In this testing, the limit for General Population Spatial Peak averaged over {\it 1g, 1.6W/kg}, is applied.$
- 3. Please see the Appendix A for the data, and Appendix E for the photo of the test configuration.
- 4. The variation of the EUT conducted power measured before and after SAR testing should not over 5%.



# WLAN (2.4GHz) BAND BODY POSITION

EUT	EUT			EDA (Enterprise Digital Assistant)				MODEL			MC7090	
	RONMENTA DITION	L		Air Temperature : 22.6°C, Liquid Temperature : 21.4°C Humidity : 60%RH								
TESTI	ED BY		Sam C	)nn			DATE	<b>=</b>	(	Oct. 01,	2005	
СНАМ	CHAN. FREQ. (MHz)	M	ODE		TED POWER mW)		VER	DEVICE USE		DEVICE TEST	MEASURED 1g SAR	
OHAII.	1 NE 92. (WI12)	IV.	ODL	BEGIN TEST	AFTER TEST	DRIFT (%)		POWER	POSITION MODE		(W/kg)	
1	2412.00 (Low)	D	esss	22.699	22.143	-2.	.45	Standard Battery		5	0.073	
6	2437.00 (Mid.)	D	esss	40.551	38.945	-3	Standard Battery			5	0.127	
11	2462.00 (High)	D	esss	25.468	24.793	-2.	2.65 Standard Battery			5	0.052	

- 1. Test configuration of each mode is described in section 3.
- 2. In this testing, the limit for General Population Spatial Peak averaged over 1g, 1.6W/kg, is applied.
- 3. Please see the Appendix A for the data, and Appendix E for the photo of the test configuration.
- 4. The variation of the EUT conducted power measured before and after SAR testing should not over 5%.



# WLAN (2.4GHz) BAND RIGHT HEAD POSITION

EUT			EDA (Enterprise Digital Assistant)					EL	MC7090	MC7090	
	RONMENTA DITION	\L	Air Temperature:22.8°C, Liquid Temperature:21.5°C Humidity:61%RH								
TEST	ED BY		Sam C	)nn			DATI	<b>=</b>	Sep. 28,	2005	
CHAN	FREQ. (MHz)	M	ODE		ED POWER W)	POV	VER	DEVICE USE	DEVICE TEST	MEASURED	
CHAN.	FREQ. (MHZ)	IV	ODE	BEGIN TEST	AFTER TEST	DRIF	Т (%)	POWER	POSITION MODE	1g SAR (W/kg)	
1	2412.00 (Low)	0	FDM	22.699	21.830	-3.	83	Standard Battery	6	0.156	
6	2437.00 (Mid.)	0	FDM	44.771	42.703	-4.	62	Standard Battery	6	0.343	
11	2462.00 (High)	O	FDM	25.410	24.358	-4.	14	Standard Battery	6	0.189	
1	2412.00 (Low)	0	FDM	22.699	21.689	-4.	45	Standard Battery	7	0.122	
6	2437.00 (Mid.)	O	FDM	44.771	43.141	-3.	64	Standard Battery	7	0.252	
11	2462.00 (High)	O	FDM	25.410	24.404	-3.	.96 Standard Battery		7	0.128	

- 1. Test configuration of each mode is described in section 3.
- $2. \ \ In this testing, the limit for General Population Spatial Peak averaged over {\it 1g, 1.6W/kg}, is applied.$
- 3. Please see the Appendix A for the data, and Appendix E for the photo of the test configuration.
- 4. The variation of the EUT conducted power measured before and after SAR testing should not over 5%.



# WLAN (2.4GHz) BAND LEFT HEAD POSITION

EUT			EDA (Enterprise Digital Assistant)					EL	MC7090	MC7090	
	RONMENTA DITION	\L	Air Temperature:22.8°C, Liquid Temperature:21.5°C Humidity:61%RH								
TEST	ED BY		Sam C	)nn			DATI	<b>E</b>	Sep. 28,	2005	
CHAN	FREQ. (MHz)	M	ODE		ED POWER W)	POV	VER	DEVICE USE	DEVICE TEST	MEASURED	
CHAN.	FREQ. (MHZ)	IV	ODE	BEGIN TEST	AFTER TEST	DRIF	Т (%)	POWER	POSITION MODE	1g SAR (W/kg)	
1	2412.00 (Low)	0	FDM	22.699	22.386	-1.	.38	Standard Battery	8	0.108	
6	2437.00 (Mid.)	0	FDM	44.771	44.131	-1.	43	Standard Battery	8	0.245	
11	2462.00 (High)	O	FDM	25.410	25.034	-1.	48	Standard Battery	8	0.124	
1	2412.00 (Low)	0	FDM	22.699	22.352	-1.	.53	Standard Battery	9	0.095	
6	2437.00 (Mid.)	O	FDM	44.771	44.064	-1.	.58	Standard Battery	9	0.217	
11	2462.00 (High)	O	FDM	25.410	24.996	-1.	.63 Standard Battery		9	0.121	

- 1. Test configuration of each mode is described in section 3.
- $2. \ \ In this testing, the limit for General Population Spatial Peak averaged over {\it 1g, 1.6W/kg}, is applied.$
- 3. Please see the Appendix A for the data, and Appendix E for the photo of the test configuration.
- ${\it 4. } \ \ {\it The variation of the EUT conducted power measured before and after SAR testing should not over 5\%.}$



# WLAN (2.4GHz) BAND BODY POSITION

EUT	EUT			EDA (Enterprise Digital Assistant)				MODEL			MC7090	
	RONMENTA DITION	\L		Air Temperature:22.6°C, Liquid Temperature:21.4°C Humidity:60%RH								
TESTED BY			Sam C	)nn			DATE	<b>=</b>		Oct. 01,	2005	
СНАМ	CHAN. FREQ. (MHz)	M	ODE		ED POWER aW)	POWER		DEVICE USE POWER		DEVICE TEST	MEASURED 1g SAR	
OTIAIT.	1112 g. (11112)		ODL	BEGIN TEST	AFTER TEST	DRIFT (%)				OSITION MODE	(W/kg)	
1	2412.00 (Low)	0	FDM	22.699	22.186	-2.	.26	Standard Battery		10	0.064	
6	2437.00 (Mid.)	0	FDM	44.771	44.198	-1.	1.28 Standard Battery			10	0.120	
11	2462.00 (High)	0	FDM	25.410	25.072	-1.	.33	Standard Battery		10	0.056	

- 1. Test configuration of each mode is described in section 3.
- 2. In this testing, the limit for General Population Spatial Peak averaged over 1g, 1.6W/kg, is applied.
- 3. Please see the Appendix A for the data, and Appendix E for the photo of the test configuration.
- 4. The variation of the EUT conducted power measured before and after SAR testing should not over 5%.



# **BLUETOOTH BAND RIGHT HEAD POSITION**

EUT			EDA (I	Enterprise D	igital Assist	ant)	MOD	EL	MC7090	)
	RONMENTA DITION	L		mperature: ity:65%RF	•	uid Te	emper	ature:21.4	°C	
TEST	ED BY		Sam C	)nn			DATI	E	Sep. 29	, 2005
CHAN	FREQ. (MHz)	. N	IODE	CONDUCTED POWER (mW)		POW	VER	DEVICE USE	DEVICE TEST	MEASURED 1g SAR
CHAN.	FREQ. (MHZ)	IV	IODE	BEGIN TEST	AFTER TEST	DRIF	T (%)	POWER	POSITION MODE	(W/kg)
0	2402.00 (Low)	G	<b>GFSK</b>	0.873	0.870	-0.	31	Standard Battery	11	0.00764
39	2441.00 (Mid.)	G	FSK	0.979	0.973	-0.63		Standard Battery	11	0.01300
78	2480.00 (High)	G	GFSK	1.057	1.044	-1.	25	Standard Battery	11	0.01500
0	2402.00 (Low)	G	<b>GFSK</b>	0.873	0.866	-0.	82	Standard Battery	12	0.00386
39	2441.00 (Mid.)	G	FSK	0.979	0.970	-0.	93	Standard Battery	12	0.00130
78	2480.00 (High)	G	FSK	1.057	1.030	-2.	51	Standard Battery	12	0.00101

- 1. Test configuration of each mode is described in section 3.
- $2. \ \ In this testing, the limit for General Population Spatial Peak averaged over {\it 1g, 1.6W/kg}, is applied.$
- 3. Please see the Appendix A for the data, and Appendix E for the photo of the test configuration.
- 4. The variation of the EUT conducted power measured before and after SAR testing should not over 5%.



# **BLUETOOTH BAND LEFT HEAD POSITION**

EUT			EDA (I	Enterprise D	igital Assist	ant)	MOD	EL	N	ЛС7090	
	RONMENTA DITION	L		mperature: ity:65%RF	•	uid Te	emper	ature:21.4	°C		
TEST	ED BY		Sam C	)nn			DATI	E	S	Sep. 29, 2005	
CHAN	FREQ. (MHz)	. N	IODE	CONDUCTED POWER (mW)		POV	VER	DEVICE USE		EVICE TEST	MEASURED 1g SAR
CHAN.	FREQ. (MHZ)	IV	IODE	BEGIN TEST	AFTER TEST	DRIF	T (%)	POWER		SITION	(W/kg)
0	2402.00 (Low)	G	<b>GFSK</b>	0.873	0.856	-1.	96	Standard Battery		13	0.01600
39	2441.00 (Mid.)	G	FSK	0.979	0.960	-1.	92	Standard Battery		13	0.02000
78	2480.00 (High)	G	GFSK	1.057	1.045	-1.	.11	Standard Battery		13	0.02100
0	2402.00 (Low)	G	FSK	0.873	0.862	-1.	24	Standard Battery		14	0.00880
39	2441.00 (Mid.)	G	GFSK	0.979	0.968	-1.	08	Standard Battery		14	0.00384
78	2480.00 (High)	G	FSK	1.057	1.046	-1.	01	Standard Battery		14	0.00468

- 1. Test configuration of each mode is described in section 3.
- $2. \ \ In this testing, the limit for General Population Spatial Peak averaged over {\it 1g, 1.6W/kg}, is applied.$
- 3. Please see the Appendix A for the data, and Appendix E for the photo of the test configuration.
- 4. The variation of the EUT conducted power measured before and after SAR testing should not over 5%.



# **BLUETOOTH BAND BODY POSITION**

EUT			EDA (l	Enterprise D	ant)	MOD	EL	M	/IC7090			
	RONMENTA DITION	\L		mperature: ity:60%RH	•	uid Te	emper	ature:21.4	°C			
TESTI	ED BY		Sam Onn				DATE			Oct. 01, 2005		
СПУИ	FREQ. (MHz)	M	ODE		ED POWER W)	POV	WER	DEVICE USE		EVICE TEST	MEASURED 1g SAR	
CHAN.	FREQ. (MHZ)	IVI	ODE	BEGIN TEST	AFTER TEST	DRIFT (%)		POWER		SITION IODE	(W/kg)	
0	2402.00 (Low)	G	FSK	0.873	0.861	-1.	37	Standard Battery		15	0.0000566	
39	2441.00 (Mid.)	G	FSK	0.979	0.975	-0.	.43	Standard Battery		15	0.0001090	
78	2480.00 (High)	G	FSK	1.057	1.054	-0.	28	Standard Battery		15	0.0001710	

- 1. Test configuration of each mode is described in section 3.
- 2. In this testing, the limit for General Population Spatial Peak averaged over 1g, 1.6W/kg, is applied.
- 3. Please see the Appendix A for the data, and Appendix E for the photo of the test configuration.
- 4. The variation of the EUT conducted power measured before and after SAR testing should not over 5%.



# WLAN (5.0GHz) BAND RIGHT HEAD POSITION

EUT			EDA (I	Enterprise D	igital Assist	ant)	MOD	EL	ľ	MC7090	
	RONMENTA DITION	L		mperature: ity:60%RF		uid Te	emper	ature:22.1	°C		
TEST	ED BY		Sam C	)nn			DATI	<b>=</b>	Oct. 05, 2005		2005
CHAN	FREQ. (MHz)	M	ODE		ED POWER aW)	_	VER	DEVICE USE		EVICE TEST	MEASURED 1g SAR
On Aut	rice. (mile)		ODL	BEGIN TEST	AFTER TEST	DRIF	Т (%)	POWER	_	DSITION MODE	(W/kg)
36	5180.00	0	FDM	26.730	26.161	-2.	.13	Standard Battery		16	0.744
48	5240.00	0	FDM	19.454	19.112	-1.76		Standard Battery		16	0.908
52	5260.00	0	FDM	18.578	18.140	-2.	.36	Standard Battery		16	0.892
64	5320.00	0	FDM	17.298	17.025	-1.	.58	Standard Battery		16	0.901
149	5745.00	0	FDM	40.365	39.517	-2.	.10	Standard Battery		16	0.309
157	5785.00	0	FDM	40.087	39.025	-2.	.65	Standard Battery		16	0.374
165	5825.00	0	FDM	40.551	40.105	-1.	.10	Standard Battery		16	0.462

- 1. Test configuration of each mode is described in section 3.
- 2. In this testing, the limit for General Population Spatial Peak averaged over  ${\bf 1g}$ ,  ${\bf 1.6W/kg}$ , is applied.
- 3. Please see the Appendix A for the data, and Appendix E for the photo of the test configuration.
- 4. The variation of the EUT conducted power measured before and after SAR testing should not over 5%.



# WLAN (5.0GHz) BAND RIGHT HEAD POSITION

EUT			EDA (I	Enterprise D	igital Assist	ant)	MOD	EL	MC7090	)
	RONMENTA DITION	\L		mperature: ity:60%RF	•	uid Te	emper	ature:22.1	°C	
TEST	ED BY		Sam C	)nn			DATI	E	Oct. 05,	2005
CHAN.	FREQ. (MHz)	ı M	ODE		ED POWER W)		VER	DEVICE USE	DEVICE TEST	MEASURED 1g SAR
				BEGIN TEST	AFTER TEST	DRIF	Т (%)	POWER	POSITION MODE	(W/kg)
36	5180.00	0	FDM	26.730	26.139	-2.	.21	Standard Battery	17	0.876
48	5240.00	0	FDM	19.454	19.030	-2.	.18	Standard Battery	17	0.986
52	5260.00	0	FDM	18.578	18.158	-2.26		Standard Battery	17	1.010
64	5320.00	0	FDM	17.298	17.077	-1.	.28	Standard Battery	17	0.999
149	5745.00	0	FDM	40.365	39.828	-1.	.33	Standard Battery	17	0.342
157	5785.00	0	FDM	40.087	39.534	-1.	.38	Standard Battery	17	0.460
165	5825.00	0	FDM	40.551	39.971	-1.	.43	Standard Battery	17	0.533

- 1. Test configuration of each mode is described in section 3.
- 2. In this testing, the limit for General Population Spatial Peak averaged over  ${\bf 1g}$ ,  ${\bf 1.6W/kg}$ , is applied.
- 3. Please see the Appendix A for the data, and Appendix E for the photo of the test configuration.
- 4. The variation of the EUT conducted power measured before and after SAR testing should not over 5%.



# WLAN (5.0GHz) BAND LEFT HEAD POSITION

EUT			EDA (I	Enterprise D	igital Assist	ant)	MOD	EL	М	IC7090	
	RONMENTA DITION	L		mperature: ity:60%RF	•	uid Te	emper	ature : 22.1	°C		
TESTI	ED BY		Sam C	)nn			DATI	<b>=</b>	Oct. 05, 2005		2005
CHAN.	FREQ. (MHz)	м	ODE		ED POWER W)	POV		DEVICE USE		VICE EST	MEASURED 1g SAR
OTIAIT.	1 (L S. (W112)			BEGIN TEST	AFTER TEST	DRIF	Т (%)	POWER		ODE .	(W/kg)
36	5180.00	0	FDM	26.730	26.334	-1.	48	Standard Battery		18	0.959
48	5240.00	0	FDM	19.454	19.156	-1.	53	Standard Battery		18	1.030
52	5260.00	0	FDM	18.578	18.284	-1.	58	Standard Battery		18	1.050
64	5320.00	0	FDM	17.298	17.016	-1.	63	Standard Battery		18	1.070
149	5745.00	0	FDM	40.365	38.819	-3.	83	Standard Battery		18	0.359
157	5785.00	0	FDM	40.087	38.235	-4.	62	Standard Battery		18	0.475
165	5825.00	0	FDM	40.551	38.872	-4.	.14	Standard Battery		18	0.552

- 1. Test configuration of each mode is described in section 3.
- 2. In this testing, the limit for General Population Spatial Peak averaged over  ${\bf 1g}$ ,  ${\bf 1.6W/kg}$ , is applied.
- 3. Please see the Appendix A for the data, and Appendix E for the photo of the test configuration.
- 4. The variation of the EUT conducted power measured before and after SAR testing should not over 5%.



# WLAN (5.0GHz) BAND LEFT HEAD POSITION

EUT			EDA (E	Enterprise D	igital Assist	ant) MC	ODE	≣L	MC7090	
	RONMENTA DITION	\L		nperature: ity:60%RF	23.2°C, Liq I	uid Temp	oera	ature : 22.1°	°C	
TEST	ED BY		Sam C	)nn		DA	ΛTE	:	Oct. 05, 2005	
CHAN.	FREQ. (MHz)	M	ODE		ED POWER	POWER	- 1	DEVICE USE	DEVICE TEST	MEASURED 1g SAR
	( )			BEGIN TEST	AFTER TEST	DRIFT (%	%)	POWER	POSITION MODE	(W/kg)
36	5180.00	0	FDM	26.730	26.075	-2.45		Standard Battery	19	1.010
48	5240.00	0	FDM	19.454	18.684	-3.96		Standard Battery	19	1.120
52	5260.00	0	FDM	18.578	18.086	-2.65		Standard Battery	19	1.150
64	5320.00	0	FDM	17.298	17.073	-1.30		Standard Battery	19	1.270
149	5745.00	0	FDM	40.365	39.699	-1.65		Standard Battery	19	0.469
157	5785.00	0	FDM	40.087	39.357	-1.82		Standard Battery	19	0.569
165	5825.00	0	FDM	40.551	39.776	-1.91		Standard Battery	19	0.658

- 1. Test configuration of each mode is described in section 3.
- 2. In this testing, the limit for General Population Spatial Peak averaged over 1g, 1.6W/kg, is applied.
- 3. Please see the Appendix A for the data, and Appendix E for the photo of the test configuration.
- 4. The variation of the EUT conducted power measured before and after SAR testing should not over 5%.



# **WLAN (5.0GHz) BAND BODY POSITION**

EUT			EDA (I	Enterprise D	igital Assist	ant) I	MOD	EL	MC7090	
	RONMENTA DITION	۱L		nperature: ity:63%RF	•	uid Ter	mper	ature : 21.6	°C	
TEST	ED BY		Sam C	)nn		ı	DATI	<b>=</b>	Oct. 06,	2005
CHAN.	FREQ. (MHz)	M	ODE		ED POWER nW)	POW		DEVICE USE	DEVICE TEST	MEASURED 1g SAR
				BEGIN TEST	AFTER TEST	DRIFT	(%)	POWER	POSITION MODE	(W/kg)
36	5180.00	0	FDM	26.730	26.647	-0.3	31	Standard Battery	20	0.169
48	5240.00	0	FDM	19.454	19.331	-0.6	63	Standard Battery	20	0.223
52	5260.00	0	FDM	18.578	18.346	-1.2	25	Standard Battery	20	0.213
64	5320.00	0	FDM	17.298	17.156	-0.8	32	Standard Battery	20	0.184
149	5745.00	0	FDM	40.365	39.990	-0.9	93	Standard Battery	20	0.059
157	5785.00	0	FDM	40.087	39.081	-2.5	51	Standard Battery	20	0.057
165	5825.00	0	FDM	40.551	39.756	-1.9	96	Standard Battery	20	0.112

- 1. Test configuration of each mode is described in section 3.
- 2. In this testing, the limit for General Population Spatial Peak averaged over  ${\bf 1g}$ ,  ${\bf 1.6W/kg}$ , is applied.
- ${\it 3. \ Please see} \ the \ Appendix \ A \ for \ the \ data, \ and \ Appendix \ E \ for \ the \ photo \ of \ the \ test \ configuration.$
- 4. The variation of the EUT conducted power measured before and after SAR testing should not over 5%.



# WLAN (2.4GHz) + BLUETOOTH RIGHT HEAD POSITION

EUT			EDA (I	Enterprise D	igital Assist	ant)	MOD	EL	MC7090	
					ED POWER NW)	POV	VER	DEVICE USE	DEVICE TEST	MEASURED
CHAN.	FREQ. (MHz)	М	ODE	BEGIN TEST	AFTER TEST	DRIF	Т (%)	POWER	OSITION MODE	1g SAR (W/kg)
6	2437.00 (Mid.)	D	esss	40.551	39.687	-2.	.13	Standard	21	0.436
78	2480.00 (High)	G	FSK	1.057	1.044	-1.	25	Battery	21	0.430

- 1. Test configuration of each mode is described in section 3.
- 2. In this testing, the limit for General Population Spatial Peak averaged over  ${\bf 1g}$ ,  ${\bf 1.6W/kg}$ , is applied.
- 3. Please see the Appendix A for the data, and Appendix E for the photo of the test configuration.
- 4. The variation of the EUT conducted power measured before and after SAR testing should not over 5%.



# WLAN (5.0GHz) + BLUETOOTH LEFT HEAD POSITION

EUT			EDA (Enterprise Digital Assista			ant)	MODEL			MC7090	
OU AN	FDF0 (MIL)		ODE		ED POWER W)			DEVICE USE		DEVICE TEST	MEASURED
CHAN.	FREQ. (MHz)	M	ODE	BEGIN TEST	AFTER TEST	DRIF	Т (%)	POWER		OSITION MODE	1g SAR (W/kg)
64	5320.00	0	FDM	17.298	17.073	-1.	.30	Standard		22	1.270
0	2402.00 (Low)	G	FSK	0.873	0.862	-1.	24	Battery		22	1.270

- 1. Test configuration of each mode is described in section 3.
- 2. In this testing, the limit for General Population Spatial Peak averaged over  ${\bf 1g}$ ,  ${\bf 1.6W/kg}$ , is applied.
- 3. Please see the Appendix A for the data, and Appendix E for the photo of the test configuration.
- 4. The variation of the EUT conducted power measured before and after SAR testing should not over 5%.



# WLAN (2.4GHz) + BLUETOOTH BODY POSITION

EUT			EDA (Enterprise Digital Assist			ant)	nt) MODEL			MC7090		
011441	EDEO (MIL)	Q. (MHz) N			ED POWER W)	POV	VER	DEVICE USE		DEVICE TEST	MEASURED	
CHAN.	FREQ. (MHz)	М	ODE	BEGIN TEST	AFTER TEST		Т (%)	6) POWER		OSITION MODE	1g SAR (W/kg)	
6	2437.00 (Mid.)	D	sss	40.551	38.945	-3.	.96	Standard	23	23	0.127	
78	2480.00 (High)	G	FSK	1.057	1.054	-0.	28	Battery		23	0.127	

- 1. Test configuration of each mode is described in section 3.
- 2. In this testing, the limit for General Population Spatial Peak averaged over  ${\bf 1g}$ ,  ${\bf 1.6W/kg}$ , is applied.
- 3. Please see the Appendix A for the data, and Appendix E for the photo of the test configuration.
- 4. The variation of the EUT conducted power measured before and after SAR testing should not over 5%.



# WLAN (5.0GHz) + BLUETOOTH BODY POSITION

EUT			EDA (I	Enterprise D	igital Assist	ant)	MOD	EL		MC7090	
01144	FDF0 (MIL)		ODE		ED POWER W)	POV	VER	DEVICE USE		DEVICE TEST	MEASURED
CHAN.	FREQ. (MHz)	M	ODE	BEGIN TEST	AFTER TEST		Т (%)	POWER		OSITION MODE	1g SAR (W/kg)
48	5240.00	0	FDM	19.454	19.331	-0.	.63	Standard	24	24	0.223
78	2480.00 (High)	G	FSK	1.057	1.054	-0.	28	Battery		24	0.223

- 1. Test configuration of each mode is described in section 3.
- 2. In this testing, the limit for General Population Spatial Peak averaged over 1g, 1.6W/kg, is applied.
- 3. Please see the Appendix A for the data, and Appendix E for the photo of the test configuration.
- 4. The variation of the EUT conducted power measured before and after SAR testing should not over 5%.



# 5.3 SAR LIMITS

	SAR (W/kg)				
HUMAN EXPOSURE	(General Population / Uncontrolled Exposure Environment)	(Occupational / controlled Exposure Environment)			
Spatial Average ( whole body)	0.08	0.4			
Spatial Peak (averaged over 1 g)	1.6	8.0			
Spatial Peak (hands/wrists/feet/ankles averaged over 10 g)	4.0	20.0			

### NOTE:

- 1. This limits accord to 47 CFR 2.1093 Safety Limit.
- 2. The EUT property been complied with the partial body exposure limit under the general population environment.

### 5.4 RECIPES FOR TISSUE SIMULATING LIQUIDS

For the measurement of the field distribution inside the SAM phantom, the phantom must be filled with 25 litters of tissue simulation liquid.

The following ingredients are used:

- Water- Deionized water (pure H20), resistivity 16 M as basis for the liquid
- Sugar- Refined sugar in crystals, as available in food shops to reduce

relative permittivity

- Salt- Pure NaCl to increase conductivity
- Cellulose- Hydroxyethyl-cellulose, medium viscosity (75-125 mPa.s, 2% in

water, 20 C), CAS # 54290 - to increase viscosity and to keep sugar

in solution

• Preservative- Preventol D-7 Bayer AG, D-51368 Leverkusen, CAS # 55965-84-9 -

to prevent the spread of bacteria and molds

• DGMBE- Diethylenglycol-monobuthyl ether (DGMBE), Fluka Chemie GmbH,

CAS # 112-34-5 - to reduce relative permittivity

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# THE RECIPES FOR 2450MHz SIMULATING LIQUID TABLE

INGREDIENT	HEAD SIMULATING LIQUID 2450MHz (HSL-2450)	MUSCLE SIMULATING LIQUID 2450MHz (MSL-2450)
Water	45%	69.83%
DGMBE	55%	30.17%
Salt	NA	NA
Dielectric Parameters at 22°C	f= 2450MHz ε= 39.2 ± 5% $\sigma$ = 1.80 ± 5% S/m	f= 2450MHz ε= 52.7 ± 5% σ= 1.95 ± 5% S/m

# THE INFORMATION FOR 5GHz SIMULATING LIQUID

The 5 GHz liquids was purchased from SPEAG.

Body liquid model: HSL 5800, P/N: SL AAH 5800 AA

Head liquid model: M 5800, P/N: SL AAM 580 AD

5GHz liquids contain the following ingredients:

Water 64 - 78%

Mineral Oil 11 - 18%

Emulsifiers 9 - 15%

Additives and Salt 2 - 3%



The liquid nature is tested by Agilent Network Analyzer E8358A and Agilent Dielectric Probe Kit 85070D. Here are the procedure.

- 1. Turn Network Analyzer on and allow at least 30 min. warm up.
- 2. Mount dielectric probe kit so that interconnecting cable to Network Analyzer will not be moved during measurements or calibration.
- 3. Pour de-ionized water and measure water temperature (±1°).
- 4. Set water temperature in Agilent-Software (Calibration Setup).
- 5. Perform calibration.
- 6. Validate calibration with dielectric material of known properties (e.g. polished ceramic slab with >8mm thickness  $\varepsilon$ '=10.0,  $\varepsilon$ "=0.0). If measured parameters do not fit within tolerance, repeat calibration (±0.2 for  $\varepsilon$ ': ±0.1 for  $\varepsilon$ ").
- 7. Conductivity can be calculated from  $\varepsilon''$  by  $\sigma = \omega \varepsilon_0 \varepsilon'' = \varepsilon'' f [GHz] / 18.$
- 8. Measure liquid shortly after calibration. Repeat calibration every hour.
- 9. Stir the liquid to be measured. Take a sample (~50ml) with a syringe from the center of the liquid container.
- 10. Pour the liquid into a small glass flask. Hold the syringe at the bottom of the flask to avoid air bubbles.
- 11. Put the dielectric probe in the glass flask. Check that there are no air bubbles in front of the opening in the dielectric probe kit.
- 12. Perform measurements.
- 13. Adjust medium parameters in DASY4 for the frequencies necessary for the measurements ('Setup Config', select medium (e.g. Brain 900 MHz) and press 'Option'-button.
- 14. Select the current medium for the frequency of the validation (e.g. Setup Medium Brain 900 MHz).



# FOR 2.4GHz BAND SIMULATING LIQUID

LIQUID TYPE		HSL-	-2450	MSL-2450		
SIMULATING LIQUID TEMP.		21	1.5	21.4		
TEST DA	TE	Sep. 28	8, 2005	Oct. 0	1, 2005	
TESTED	BY	Sam	Onn	Sam	Onn	
FREQ. (MHz)	LIQUID PARAMETER	STANDARD VALUE	MEASUREMENT VALUE	STANDARD VALUE	MEASUREMENT VALUE	
2412.0		39.267	39.600	52.750	52.100	
2437.0	Permitivity	39.223	39.400	52.710	52.100	
2450.0	(ε)	39.200	39.300	52.700	52.000	
2462.0		39.184	39.200	52.680	52.000	
2412.0	Conductivity	1.766	1.750	1.913	1.930	
2437.0	Conductivity	1.788	1.780	1.937	1.970	
2450.0	(σ) S/m	1.800	1.810	1.950	1.980	
2462.0	3/111	1.813	1.810	1.967	2.000	
Dielectric Parameters Required at 22°℃		f= 2450MHz ε= 39.2 ± 5% σ= 1.80 ± 5% S/m		ε= 52.	50MHz 7 ± 5% ± 5% S/m	



LIQUID TYPE		HSL-	-2450	MSL-2450		
SIMULATING LIQUID TEMP.		21	1.4	21.4		
TEST DA	TE	Sep. 29	9, 2005	Oct. 0	1, 2005	
TESTED	BY	Sam	Onn	Sam	Onn	
FREQ. (MHz)	LIQUID PARAMETER	STANDARD VALUE	MEASUREMENT VALUE	STANDARD VALUE	MEASUREMENT VALUE	
2402.0		39.28	39.60	52.76	52.20	
2441.0	Permitivity	39.21	39.40	52.71	52.10	
2450.0	(ε)	39.20	39.40	52.70	52.00	
2480.0		39.16	39.30	52.66	52.00	
2402.0	Conductivity	1.75	1.70	1.90	1.91	
2441.0	Conductivity	1.79	1.78	1.94	1.97	
2450.0	(σ) S/m	1.80	1.78	1.95	1.98	
2480.0	3/111	1.83	1.80	1.99	2.02	
Dielectric Parameters Required at 22°℃		f= 2450MHz ε= 39.2 ± 5% σ= 1.80 ± 5% S/m		f= 2450MHz ε= 52.7 ± 5% σ= 1.95 ± 5% S/m		



# FOR 5.0GHz BAND SIMULATING LIQUID

LIQUID 1	TYPE	HSL-	-5800	MSL-5800		
SIMULAT	TING LIQUID	22	2.1	21.6		
TEST DA	NTE .	Oct. 05	5, 2005	Oct. 06	6, 2005	
TESTED	BY	Sam	Onn	Sam	Onn	
FREQ. (MHz)	LIQUID PARAMETER	STANDARD VALUE	MEASUREMENT VALUE	STANDARD VALUE	MEASUREMENT VALUE	
5180.0		36.00	37.10	49.04	48.70	
5200.0		35.98	37.10	49.01	48.70	
5240.0		35.94	37.00	48.96	48.60	
5260.0	Permitivity $(\varepsilon)$	35.91	37.00	48.93	48.50	
5320.0		35.84	36.80	48.85	48.40	
5745.0		35.36	36.00	48.27	47.40	
5785.0		35.31	35.90	48.22	47.30	
5800.0		35.30	35.90	48.20	47.30	
5825.0		35.27	35.90	48.16	47.30	
5180.0		4.63	4.62	5.27	5.30	
5200.0		4.65	4.67	5.29	5.33	
5240.0		4.69	4.70	5.34	5.39	
5260.0	Conductivity	4.71	4.72	5.36	5.42	
5320.0	(σ)	4.77	4.79	5.43	5.50	
5745.0	S/m	5.21	5.29	5.93	6.13	
5785.0		5.25	5.33	5.98	6.19	
5800.0		5.27	5.36	6.00	6.21	
5825.0		5.29	5.38	6.02	6.25	
		Dielectric Para	meters Required	l at 22℃		



# 5.5 TEST EQUIPMENT FOR TISSUE PROPERTY

I	TEM	NAME	AME BAND TYPE SERIES NO.		CALIBRATED UNTIL	
	1	Network Analyzer	Agilent	E8358A	US41480538	Oct. 25, 2005
	2	Dielectric Probe	Agilent	85070D	US01440176	NA

- 1. Before testing the measurement, all test equipment shall have 30 min warm up.
- 2. The tolerance (k=1) specified by Agilent for general dielectric measurements, deriving from inaccuracies in the calibration data, analyzer drift, and random errors, are usually ±2.5% and ±5% for measured permittivity and conductivity, respectively. However, the tolerances for the conductivity is smaller for material with large loss tangents, i.e., less than ±2.5% (k=1). It can be substantially smaller if more accurate methods are applied.



# 6. SYSTEM VALIDATION

The system validation was performed in the flat phantom with equipment listed in the following table. Since the SAR value is calculated from the measured electric field, dielectric constant and conductivity of the body tissue, and the SAR is proportional to the square of the electric field. So, the SAR value will be also proportional to the RF power input to the system validation dipole under the same test environment. In our system validation test, 250mW RF input power was used.

## **6.1 TEST EQUIPMENT**

ITEM	NAME BAND TYPE S		SERIES NO.	CALIBRATED UNTIL	
1	SAM Phantom	S&P	QD000 P40 CA	PT-1150	NA
2	Signal Generator	Anritsu	68247B	984703	May 04, 2006
3	E-Field Probe	S&P	ET3DV6	1790	Dec. 19, 2006
3		Speaq	EX3DV3	3506	Mar. 18, 2006
4	DAE	S&P	DAE3 V1	579	Mar. 22, 2006
5	Robot Positioner	Staubli Unimation	NA	NA	NA
6	Validation Dinale	S&P	D2450V2	737	Mar. 15, 2006
6	Validation Dipole	S&P	D5GHzV2	1019	Mar. 22, 2006

NOTE: 1. Before starting the measurement, all test equipment shall be warmed up for 30min.

<sup>2.</sup> System validation was performed to check the condition during each test. According to this situation, calibrated period for the validation dipole back to the original factory is one year, and the others will be two.



## **6.2 TEST PROCEDURE**

Before you start the system performance check, need only to tell the system with which components (probe, medium, and device) are performing the system performance check; the system will take care of all parameters. The dipole must be placed beneath the flat section of the SAM Twin Phantom with the correct distance holder in place. The distance holder should touch the phantom surface with a light pressure at the reference marking (little cross) and be oriented parallel to the long side of the phantom. Accurate positioning is not necessary, since the system will search for the peak SAR location, except that the dipole arms should be parallel to the surface. The device holder for mobile phones can be left in place but should be rotated away from the dipole.

- 1.The "Power Reference Measurement" and "Power Drift Measurement" jobs are located at the beginning and end of the batch process. They measure the field drift at one single point in the liquid over the complete procedure. The indicated drift is mainly the variation of the amplifier output power. If it is too high (above ±0.1 dB), the system performance check should be repeated; some amplifiers have very high drift during warm-up. A stable amplifier gives drift results in the DASY system below ±0.02 dB.
- 2.The "Surface Check" job tests the optical surface detection system of the DASY system by repeatedly detecting the surface with the optical and mechanical surface detector and comparing the results. The output gives the detecting heights of both systems, the difference between the two systems and the standard deviation of the detection repeatability. Air bubbles or refraction in the liquid due to separation of the sugar-water mixture gives poor repeatability (above ±0.1mm). In that case it is better to abort the system performance check and stir the liquid. The difference between the optical surface detection and the actual surface depends on the probe and is specified with each probe. (It does not depend on the surface reflectivity or the probe angle to the surface within ±30°.) However, varying breaking indices of different liquid compositions might also influence the distance. If the indicated difference varies from the actual setting, the probe parameter "optical surface



- 3. The "Area Scan" job measures the SAR above the dipole on a plane parallel to the surface. It is used to locate the approximate location of the peak SAR. The proposed scan uses large grid spacing for faster measurement; due to the symmetric field, the peak detection is reliable. If a finer graphic is desired, the grid spacing can be reduced. Grid spacing and orientation have no influence on the SAR result.
- 4. The "Zoom Scan" job measures the field in a volume around the peak SAR value assessed in the previous "Area Scan" job (for more information see the application note on SAR evaluation).

About the validation dipole positioning uncertainty, the constant and low loss dielectric spacer is used to establish the correct distance between the top surface of the dipole and the bottom surface of the phantom, the error component introduced by the uncertainty of the distance between the liquid (i.e., phantom shell) and the validation dipole in the DASY4 system is less than ±0.1mm.

$$SAR_{tolerance}[\%] = 100 \times (\frac{(a+d)^2}{a^2} - 1)$$

As the closest distance is 10mm, the resulting tolerance SAR  $_{\rm tolerance} [\%]$  is <2%.



# **6.3 VALIDATION RESULTS**

	SYSTEM VALIDATION TEST OF SIMULATING LIQUID										
FREQUENCY (MHz)	REQUIRED SAR (mW/g)	MEASURED SAR (mW/g)	DEVIATION (%)	SEPARATION DISTANCE	TESTED DATE						
HSL2450	13.70 (1g)	12.50	-8.76	10mm	Sep. 28, 2005						
HSL2450	13.70 (1g)	12.70	-7.30	10mm	Sep. 29, 2005						
MSL2450	13.40 (1g)	12.60	-5.97	10mm	Oct. 01, 2005						
HSL5200	19.80 (1g)	20.10	1.52	10mm	Oct. 05, 2005						
MSL5200	18.60 (1g)	17.40	-6.45	10mm	Oct. 06, 2005						
HSL5800	20.60 (1g)	20.80	0.97	10mm	Oct. 05, 2005						
MSL5800	17.90 (1g)	16.50	-7.82	10mm	Oct. 06, 2005						
TESTED BY	Sam Onn										

**NOTE:** Please sees Appendix for the photo of system validation test.

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# 6.4 SYSTEM VALIDATION UNCERTAINTIES (FOR 2.4GHz)

In the table below, the system validation uncertainty with respect to the analytically assessed SAR value of a dipole source as given in the IEEE P1528 standard is given. This uncertainty is smaller than the expected uncertainty for mobile phone measurements due to the simplified setup and the symmetric field distribution.

Error Description	on Tolerance Probability D		Divisor	(0	C <sub>i</sub> )	Uncei	dard rtainty %)	(v <sub>i</sub> )
	(= / - /			(1g)	(10g)	(1g)	(10g)	
		Measuremen	t System					
Probe Calibration	4.8	Normal	1	1	1	4.8	4.8	8
Axial Isotropy	4.7	Rectangular	√3	1	1	2.7	2.7	8
Hemispherical Isotropy	0.0	Rectangular	√3	1	1	0.0	0.0	$\infty$
Boundary effect	1.0	Rectangular	√3	1	1	0.6	0.6	8
Linearity	4.7	Rectangular	√3	1	1	2.7	2.7	8
System Detection Limit	1.0	Rectangular	√3	1	1	0.6	0.6	8
Readout Electronics	1.0	Normal	1	1	1	1.0	1.0	$\infty$
Response Time	0.0	Rectangular	√3	1	1	0.0	0.0	$\infty$
Integration Time	0.0	Rectangular	√3	1	1	0.0	0.0	8
RF Ambient Conditions	3.0	Rectangular	√3	1	1	1.7	1.7	$\infty$
Probe Positioner	0.4	Rectangular	√3	1	1	0.2	0.2	$\infty$
Probe positioning	2.9	Rectangular	√3	1	1	1.7	1.7	$\infty$
Algorithms for Max. SAR Evaluation	1.0	Rectangular	√3	1	1	0.6	0.6	8
		Dipol	е					
Dipole Axis to Liquid Distance	2.0	Rectangular	√3	1	1	1.2	1.2	$\infty$
Input power and SAR drift measurement	4.7	Rectangular	√3	1	1	2.7	2.7	8
		Phantom and Tissi	ue Paramet	ers				
Phantom Uncertainty	4.0	Rectangular	√3	1	1	2.3	2.3	8
Liquid Conductivity (target)	5.0	Rectangular	√3	0.64	0.43	1.8	1.2	∞
Liquid Conductivity (measurement)	2.5	Normal	1	0.64	0.43	1.6	1.1	8
Liquid Permittivity (target)	5.0	Rectangular	√3	0.60	0.49	1.7	1.4	∞
Liquid Permittivity (measurement)	2.5	Normal	1	0.60	0.49	1.5	1.2	∞
	Combined	Standard Uncertaint	ty			8.4	8.1	$\infty$
	Coveraç	ge Factor for 95%					kp=2	
	Expanded Uncertainty (K=2)							

NOTE: About the system validation uncertainty assessment, please reference the section 7.

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# 6.5 SYSTEM VALIDATION UNCERTAINTIES (FOR 5GHz)

Error Description	Tolerance (±%)	Probability Distribution	Divisor	(0	C <sub>i</sub> )	Uncei	dard rtainty %)	(V <sub>i</sub> )
	(= 70)	Diodribution		(1g)	(10g)	(1g)	(10g)	
		Measuremen	t System					
Probe Calibration	6.6	Normal	1	1	1	4.8	6.6	$\infty$
Axial Isotropy	4.7	Rectangular	√3	1	1	2.7	2.7	$\infty$
Hemispherical Isotropy	0.0	Rectangular	√3	1	1	0.0	0.0	$\infty$
Boundary effect	2.0	Rectangular	√3	1	1	1.2	1.2	$\infty$
Linearity	4.7	Rectangular	√3	1	1	2.7	2.7	~
System Detection Limit	1.0	Rectangular	√3	1	1	0.6	0.6	$\infty$
Readout Electronics	1.0	Normal	1	1	1	1.0	1.0	~
Response Time	0.0	Rectangular	√3	1	1	0.0	0.0	$\infty$
Integration Time	0.0	Rectangular	√3	1	1	0.0	0.0	8
RF Ambient Conditions	3.0	Rectangular	√3	1	1	1.7	1.7	8
Probe Positioner	0.8	Rectangular	√3	1	1	0.5	0.5	8
Probe positioning	5.7	Normal	1	1	1	5.7	5.7	$\infty$
Algorithms for Max. SAR Evaluation	4.0	Rectangular	√3	1	1	2.3	2.3	$\infty$
		Dipol	е					
Dipole Axis to Liquid Distance	2.0	Rectangular	√3	1	1	1.2	1.2	8
Input power and SAR drift measurement	4.7	Rectangular	√3	1	1	2.7	2.7	8
		Phantom and Tissu	ue Parameto	ers				
Phantom Uncertainty	4.0	Rectangular	√3	1	1	2.3	2.3	8
Liquid Conductivity (target)	5.0	Rectangular	√3	0.64	0.43	1.8	1.2	8
Liquid Conductivity (measurement)	2.5	Normal	1	0.64	0.43	1.6	1.1	∞
Liquid Permittivity (target)	5.0	Rectangular	√3	0.60	0.49	1.7	1.4	∞
Liquid Permittivity (measurement)	2.5	Normal	1	0.60	0.49	1.5	1.2	8
	Combined	Standard Uncertaint	y			11.3	11.1	8
	Coveraç	ge Factor for 95%					kp=2	
	Expanded	Uncertainty (K=2)				22.6	22.1	

# **TABLE 6.1**

**NOTE:** 1. Table 6.1 Uncertainty of the system performance check in the 5-6GHz range. Probe calibration error reflects uncertainty of the EX3DV3 probe conversion factor at Calibration Frequency.

2. About the system validation uncertainty assessment, please reference the section 7.



## 7. MEASUREMENT SAR PROCEDURE UNCERTAINTIES

The assessment of spatial peak SAR of the hand handheld devices is according to IEEE 1528. All testing situation shall be met below these requirement.

- The system is used by an experienced engineer who follows the manual and the guidelines taught during the training provided by SPEAG.
- The probe has been calibrated within the requested period and the stated uncertainty for the relevant frequency bands does not exceed 4.8% (k=1).
- The validation dipole has been calibrated within the requested period and the system performance check has been successful.
- The DAE unit has been calibrated within the within the requested period.
- The minimum distance between the probe sensor and inner phantom shell is selected to be between 4 and 5mm.
- The operational mode of the DUT is CW, CDMA, FDMA or TDMA (GSM, DCS, PCS, IS136 and PDC) and the measurement/integration time per point is >500 ms.
- The dielectric parameters of the liquid have been assessed using Agilent 85070D dielectric probe kit or a more accurate method.
- The dielectric parameters are within 5% of the target values.
- The DUT has been positioned as described in section 3.

## 7.1 PROBE CALIBRATION UNCERTAINTY

SPEAG conducts the probe calibration in compliance with international and national standards (e.g. IEEE 1528, EN50361, IEC 62209, etc.) under ISO17025. The uncertainties are stated on the calibration certificate. For the most relevant frequency bands, these values do not exceed 4.8% (k=1). If evaluations of other bands are performed for which the uncertainty exceeds these values, the uncertainty tables given in the summary have to be revised accordingly.



### 7.2 ISOTROPY UNCERTAINTY

The axial isotropy tolerance accounts for probe rotation around its axis while the hemispherical isotropy error includes all probe orientations and field polarizations. These parameters are assessed by SPEAG during initial calibration. In 2001, SPEAG further tightened its quality controls and warrants that the maximal deviation from axial isotropy is  $\pm 0.20$  dB, while the maximum deviation of hemispherical isotropy is  $\pm 0.40$  dB, corresponding to  $\pm 4.7\%$  and  $\pm 9.6\%$ , respectively. A weighting factor of cp equal to 0.5 can be applied, since the axis of the probe deviates less than 30 degrees from the normal surface orientation.

### 7.3 BOUNDARY EFFECT UNCERTAINTY

The effect can be estimated according to the following error approximation formula

$$SAR_{tolerance}[\%] = SAR_{be}[\%] \times \frac{(d_{be} + d_{step})^2}{2d_{step}} \frac{e^{\frac{-d_{be}}{\delta/2}}}{\delta/2}$$

$$d_{be} + d_{step} < 10mm$$

The parameter  $d_{be}$  is the distance in mm between the surface and the closest measurement point used in the averaging process;  $d_{step}$  is the separation distance in mm between the first and second measurement points;  $\delta$  is the minimum penetration depth in mm within the head tissue equivalent liquids (i.e.,  $\delta$ = 13.95 mm at 3GHz); SAR<sub>be</sub> is the deviation between the measured SAR value at the distance  $d_{be}$  from the boundary and the wave-guide analytical value SAR<sub>ref</sub>.DASY4 applies a boundary effect compensation algorithm according to IEEE 1528, which is possible since the axis of the probe never deviates more than 30 degrees from the normal surface orientation. SAR<sub>be</sub>[%] is assessed during the calibration process and SPEAG warrants that the uncertainty at distances larger than 4mm is always less than 1%.In summary, the worst case boundary effect SAR tolerance[%] for scanning distances larger than 4mm is < ± 0.8%.

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## 7.4 PROBE LINEARITY UNCERTAINTY

Field probe linearity uncertainty includes errors from the assessment and compensation of the diode compression effects for CW and pulsed signals with known duty cycles. This error is assessed using the procedure described in IEEE 1528. For SPEAG field probes, the measured difference between CW and pulsed signals, with pulse frequencies between 10 Hz and 1 kHz and duty cycles between 1 and 100, is  $< \pm 0.20$  dB ( $< \pm 4.7\%$ ).

### 7.5 READOUT ELECTRONICS UNCERTAINTY

All uncertainties related to the probe readout electronics (DAE unit), including the gain and linearity of the instrumentation amplifier, its loading effect on the probe, and accuracy of the signal conversion algorithm, have been assessed accordingly to IEEE 1528. The combination (root-sum-square RSS method) of these components results in an overall maximum error of ±1.0%.

#### 7.6 RESPONSE TIME UNCERTAINTY

The time response of the field probes is assessed by exposing the probe to a well-controlled electric field producing SAR larger than 2.0 W/kg at the tissue medium surface. The signal response time is evaluated as the time required by the system to reach 90% of the expected final value after an on/of switch of the power source. Analytically, it can be expressed as:

$$SAR_{tolerance}[\%] = 100 \times (\frac{T_m}{T_m + \tau e^{-T_m/T} - \tau} - 1)$$

where Tm is 500 ms, i.e., the time between measurement samples, and  $_{\rm T}$  the time constant. The response time  $_{\rm T}$  of SPEAG's probes is <5 ms. In the current implementation, DASY4 waits longer than 100 ms after having reached the grid point before starting a measurement, i.e., the response time uncertainty is negligible.



# 7.7 INTEGRATION TIME UNCERTAINTY

If the device under test does not emit a CW signal, the integration time applied to measure the electric field at a specific point may introduce additional uncertainties due to the discretization and can be assessed as follows

$$SAR_{tolerance} [\%] = 100 \times \sum_{all sub-frames} \frac{t_{frame}}{t_{\text{int egration}}} \frac{slot_{idle}}{slot_{total}}$$

The tolerances for the different systems are given in Table 7.1, whereby the worst-case  $SAR_{tolerance}$  is 2.6%.

System	SAR <sub>tolerance</sub> %
CW	0
CDMA*	0
WCDMA*	0
FDMA	0
IS-136	2.6
PDC	2.6
GSM/DCS/PCS	1.7
DECT	1.9
Worst-Case	2.6

**TABLE 7.1** 



# 7.8 PROBE POSITIONER MECHANICAL TOLERANCE

The mechanical tolerance of the field probe positioner can introduce probe positioning uncertainties. The resulting SAR uncertainty is assessed by comparing the SAR obtained according to the specifications of the probe positioner with respect to the actual position defined by the geometric enter of the probe sensors. The tolerance is determined as:

$$SAR_{tolerance} \ [\%] = 100 \times \frac{d_{ss}}{\delta/2}$$

The specified repeatability of the RX robot family used in DASY4 systems is  $\pm 25 \,\mu m$ . The absolute accuracy for short distance movements is better than  $\pm 0.1 \,mm$ , i.e., the SAR<sub>tolerance</sub>[%] is better than 1.5% (rectangular).

### 7.9 PROBE POSITIONING

The probe positioning procedures affect the tolerance of the separation distance between the probe tip and the phantom surface as:

$$SAR_{tolerance}[\%] = 100 \times \frac{d_{ph}}{\delta/2}$$

where  $d_{ph}$  is the maximum deviation of the distance between the probe tip and the phantom surface. The optical surface detection has a precision of better than 0.2 mm, resulting in an SAR<sub>tolerance</sub>[%] of <2.9% (rectangular distribution). Since the mechanical detection provides better accuracy, 2.9% is a worst-case figure for DASY4 system.



# 7.10 PHANTOM UNCERTAINTY

The SAR measurement uncertainty due to SPEAG phantom shell production tolerances has been evaluated using

$$SAR_{tolerance}[\%] \cong 100 \times \frac{2d}{a}, \qquad d \ll a$$

For a maximum deviation d of the inner and outer shell of the phantom from that specified in the CAD file of  $\pm 0.2$  mm, and a 10mm spacing a between source and tissue liquid, the calculated phantom uncertainty is  $\pm 4.0\%$ .

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# 7.11 DASY4 UNCERTAINTY BUDGET (FOR 2.4GHz)

Error Description	Tolerance (±%)	Probability Distribution	Divisor	(C <sub>i</sub> )		Unce	dard rtainty %)	(v <sub>i</sub> )	
				(1g)	(10g)	(1g)	(10g)		
Measurement System									
Probe Calibration	4.8	Normal	1	1	1	4.8	4.8	$\infty$	
Axial Isotropy	4.7	Rectangular	√3	1	1	1.9	1.9	$\infty$	
Hemispherical Isotropy	9.6	Rectangular	√3	1	1	3.9	3.9	$\infty$	
Boundary effect	1.0	Rectangular	√3	1	1	0.6	0.6	$\infty$	
Linearity	4.7	Rectangular	√3	1	1	2.7	2.7	$\infty$	
System Detection Limit	1.0	Rectangular	√3	1	1	0.6	0.6	$\infty$	
Readout Electronics	1.0	Normal	1	1	1	1.0	1.0	$\infty$	
Response Time	0.8	Rectangular	√3	1	1	0.5	0.5	$\infty$	
Integration Time	2.6	Rectangular	√3	1	1	1.5	1.5	$\infty$	
RF Ambient Conditions	3.0	Rectangular	√3	1	1	1.7	1.7	$\infty$	
Probe Positioner	0.4	Rectangular	√3	1	1	0.2	0.2	$\infty$	
Probe positioning	2.9	Rectangular	√3	1	1	1.7	1.7	$\infty$	
Algorithms for Max. SAR Evaluation	1.0	Rectangular	√3	1	1	0.6	0.6	8	
		Test EUT R	elated						
Device Positioning	2.9	Normal	1	1	1	2.9	2.9	875	
Device Holder	3.6	Normal	1	1	1	3.6	3.6	5	
Power Drift	5	Rectangular	√3	1	1	2.9	2.9	$\infty$	
	F	hantom and Tiss	ue Paramet	ers					
Phantom Uncertainty	4.0	Rectangular	√3	1	1	2.3	2.3	$\infty$	
Liquid Conductivity (target)	5.0	Rectangular	√3	0.64	0.43	1.8	1.2	8	
Liquid Conductivity (measurement)	2.5	Normal	1	0.64	0.43	1.6	1.1	8	
Liquid Permittivity (target)	5.0	Rectangular	√3	0.6	0.49	1.7	1.4	$\infty$	
Liquid Permittivity (measurement)	2.5	Normal	1	0.6	0.49	1.5	1.2	8	
	Combined St	andard Uncertaint	ty			10.3	10	331	
	Coverage	Factor for 95%					kp=2		
	Expanded	Uncertainty (K=2)				20.6	20.1		

## **TABLE 7.2**

The table 7.2: Worst-Case uncertainty budget for DASY4 assessed according to IEEE P1528. The budget is valid for the frequency range 300MHz ~ 3 GHz and represents a worst-case analysis. For specific tests and configurations, the uncertainty could be considerable smaller.

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# 7.12 DASY4 UNCERTAINTY BUDGET (For 5 ~ 6GHz)

Error Description	Tolerance (±%)	Probability Distribution	Divisor	(C <sub>i</sub> )		Standard Uncertainty (±%)		(v <sub>i</sub> )
				(1g)	(10g)	(1g)	(10g)	
Measurement System								
Probe Calibration	6.8	Normal	1	1	1	6.8	6.8	$\infty$
Axial Isotropy	4.7	Rectangular	√3	0.7	0.7	1.9	1.9	$\infty$
Hemispherical Isotropy	9.6	Rectangular	√3	0.7	0.7	3.9	3.9	$\infty$
Boundary effect	2.0	Rectangular	√3	1	1	1.2	1.2	$\infty$
Linearity	4.7	Rectangular	√3	1	1	2.7	2.7	$\infty$
System Detection Limit	1.0	Rectangular	√3	1	1	0.6	0.6	$\infty$
Readout Electronics	1.0	Normal	1	1	1	1.0	1.0	$\infty$
Response Time	0.8	Rectangular	√3	1	1	0.5	0.5	$\infty$
Integration Time	2.6	Rectangular	√3	1	1	1.5	1.5	8
RF Ambient Conditions	3.0	Rectangular	√3	1	1	1.7	1.7	8
Probe Positioner	0.8	Rectangular	√3	1	1	0.5	0.5	8
Probe positioning	5.7	Normal	1	1	1	5.7	5.7	8
Algorithms for Max. SAR Evaluation	4.0	Rectangular	√3	1	1	2.3	2.3	∞
Test EUT Related								
Device Positioning	2.9	Normal	1	1	1	2.9	2.9	145
Device Holder	3.6	Normal	1	1	1	3.6	3.6	5
Power Drift	5.0	Rectangular	√3	1	1	2.9	2.9	~
Phantom and Tissue Parameters								
Phantom Uncertainty	4.0	Rectangular	√3	1	1	2.3	2.3	$\infty$
Liquid Conductivity (target)	5.0	Rectangular	√3	0.64	0.43	1.8	1.2	∞
Liquid Conductivity (measurement)	2.5	Normal	1	0.64	0.43	1.6	1.1	$\infty$
Liquid Permittivity (target)	5.0	Rectangular	√3	0.60	0.49	1.7	1.4	8
Liquid Permittivity (measurement)	2.5	Normal	1	0.60	0.49	1.5	1.2	∞
Combined Standard Uncertainty						12.8	12.7	330
Expanded STD Uncertainty						25.7	25.3	

# **TABLE 7.3**

The table 7.3: Worst-Case uncertainty budget for DASY4 valid for the frequency range  $5 \sim 6$  GHz. Probe calibration error reflects uncertainty of the narrow-bandwidth EX3DV3 probe conversion factor ( $\pm 50$  MHz).



# 8. INFORMATION ON THE TESTING LABORATORIES

We, ADT Corp., were founded in 1988 to provide our best service in EMC, Radio, Telecom and Safety consultation. Our laboratories are accredited and approved by the following approval agencies according to ISO/IEC 17025:

USA FCC, NVLAP, UL, A2LA

**GERMANY** TUV Rheinland

JAPAN VCCI NORWAY NEMKO

CANADA INDUSTRY CANADA, CSA

**R.O.C.** CNLA, BSMI, DGT

**NETHERLANDS** Telefication

**SINGAPORE** PSB , GOST-ASIA (MOU)

RUSSIA CERTIS (MOU)

Copies of accreditation certificates of our laboratories obtained from approval agencies can be downloaded from our web site:

<u>www.adt.com.tw/index.5/phtml</u>. If you have any comments, please feel free to contact us at the following:

Linko EMC/RF Lab:Hsin Chu EMC/RF Lab:Tel: 886-2-26052180Tel: 886-3-5935343Fax: 886-2-26052943Fax: 886-3-5935342

Hwa Ya EMC/RF/Safety/Telecom Lab:Linko RF Lab.Tel: 886-3-3183232Tel: 886-3-3270910Fax: 886-3-3185050Fax: 886-3-3270892

Web Site: www.adt.com.tw

The address and road map of all our labs can be found in our web site also.