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Dosimetric Assessment Test Report

for the

Viavi Solutions

**Tested and Evaluated In Accordance With
IEEE 1528:2013, KDB 248227 & KDB 594280**

Prepared for

Viavi Solutions Inc
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Engineering Statement: The measurements shown in this report were made in accordance with the procedures specified in IEEE1528:2013, KDB 248227 and KDB 594280 for RF exposure. I assume full responsibility for the accuracy and completeness of these measurements, and for the qualifications of all persons taking them. It is further stated that upon the basis of the measurements made, the equipment evaluated is capable of compliance for localized specific absorption rate (SAR) for uncontrolled environment/general population exposure limits specified in ANSI/IEEE Std. C95.1-1999.



SAR Evaluation Certificate of Compliance

APPLICANT: Viavi Solutions Inc

Applicant Name and Address: Viavi Solutions Inc – Jaryk Kuzel
20250 Century Blvd.
Germantown, MD 20874

Test Location: MET Laboratories, Inc.
3162 Belick Street
Santa Clara, CA 95054
USA

EUT:	TB/MTS-5800-100G	
Test Dates:	November 28 th - December 1 th	
RF exposure environment:	Uncontrolled Exposure/General Population	
RF exposure category:	Portable	
Power supply:	Internal battery	
Antenna:	Internal	
Production/prototype:	Production	
Modes of operation tested:	2.4 GHz (802.11b, g, n)	
Modulation tested:	DSSS	
Duty Cycle tested:	99%	
TX Range:	2412-2462 MHz WiFi 2402-2480MHz BTLE (Exempt from SAR Evaluation)	
Max SAR Measured	SAR 1g (W/kg)	
	Phantom Body Section(0cm)	0.367

Asad Bajwa
Director, EMC





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1 INTRODUCTION

This measurement report demonstrates that TB/MTS-5800-100G unit as described within this report complies with the Specific Absorption Rate (SAR) RF exposure requirements specified in ANSI/IEEE Std. C95.1-1999, FCC 47 CFR §2.1093 and Industry Canada RSS-102 for the Uncontrolled Exposure/General population environment. The test procedures described in IEEE 1528-2013, KDB 594280 and KDB 248227 were employed.

A description of the device under test, device operating configuration and test conditions, measurement and site description, methodology and procedures used in the evaluation, equipment used, detailed summary of the test results and the various provisions of the rules are included in this dosimetric assessment test report.

1.1 SAR DEFINITION

Specific Absorption Rate (SAR) is defined as the time derivative (rate) of the incremental energy (dU) absorbed by (dissipated in) an incremental mass (dm) contained in a volume element (dV) of a given density (ρ). It is also defined as the rate of RF energy absorption per unit mass at a point in an absorbing body (see Fig. 1.1).

$$SAR = \frac{d}{dt} \left(\frac{dU}{dm} \right) = \frac{d}{dt} \left(\frac{dU}{\rho dv} \right)$$

SAR is expressed in units of Watts per Kilogram (W/kg).

$$SAR = \sigma E^2 / \rho$$

where:

- σ - conductivity of the tissue - simulant material (S/m)
- ρ - mass density of the tissue - simulant material (kg/m³)
- E - Total RMS electric field strength (V/m)

NOTE: The primary factors that control rate of energy absorption were found to be the wavelength of the incident field in relations to the dimensions and geometry of the irradiated organism, the orientation of the organism in relation to the polarity of field vectors, the presence of reflecting surfaces, and whether conductive contact is made by the organism with a ground plane.

1.2 DESCRIPTION OF DEVICE UNDER TEST (EUT)

Applicant:	Viavi Solutions Inc
Description of Test Item:	The Test-passer/5000 is a rack mounted networking device for verification of multiple protocol transmission. While monitoring the selected protocols, the Test-passer saves error files on its onboard disk drives or through a network connection. It is intended to be used by IT professionals within an office building.
Supply Voltage:	Internal Battery
Antenna Type(s) Tested:	Integral
Accessories:	none
Modes of Operation:	2.4 GHz b, n, g (20MHz) Bluetooth
Duty Cycles:	99%
Application Type:	Evaluation for aggregated SAR levels
Exposure Category:	Uncontrolled Exposure/General Population
FCC and IC Rule Part(s):	FCC 47 CFR §2.1093, Industry Canada RSS-102
Standards:	IEEE Std. 1528-2013, KDB 248227, KDB 594280

Table 1: Description of device under test.

1.3 SAR MEASUREMENT SYSTEM

MET Laboratories, Inc SAR measurement facility utilizes the DASY4 Professional Dosimetric Assessment System (DASY™) manufactured by Schmid & Partner Engineering AG (SPEAG™) of Zurich, Switzerland for performing SAR compliance tests. The DASY4 measurement system is comprised of the measurement server, robot controller, computer, near-field probe, probe alignment sensor, specific anthropomorphic mannequin (SAM) phantom, and various planar phantoms for brain and/or body SAR evaluations. The robot is a six-axis industrial robot performing precise movements to position the probe to the location (points) of maximum electromagnetic field (EMF). The Cell controller system contain the power supply, robot controller, teach pendant (Joystick), and remote control, is used to drive the robot motors. The Staubli robot is connected to the cell controller to allow software manipulation of the robot. A data acquisition electronic (DAE) circuit performs the signal amplification, signal multiplexing, AD-conversion, offset measurements, mechanical surface detection, collision detection, etc. is connected to the Electro-optical coupler (EOC). The EOC performs the conversion from the optical into digital electric signal of the DAE and transfers data to the DASY4 measurement server. The DAE4 utilizes a highly sensitive electrometer-grade preamplifier with auto-zeroing, a channel and gain-switching multiplexer, a fast 16-bit AD-converter and a command decoder and control logic unit.

Transmission to the DASY4 measurement server is accomplished through an optical downlink for data and status information and an optical uplink for commands and clock lines. The mechanical probe-mounting device includes two different sensor systems for frontal and sidewise probe contacts. The sensor systems are also used for mechanical surface detection and probe collision detection. The robot uses its own controller with a built in VME-bus computer.

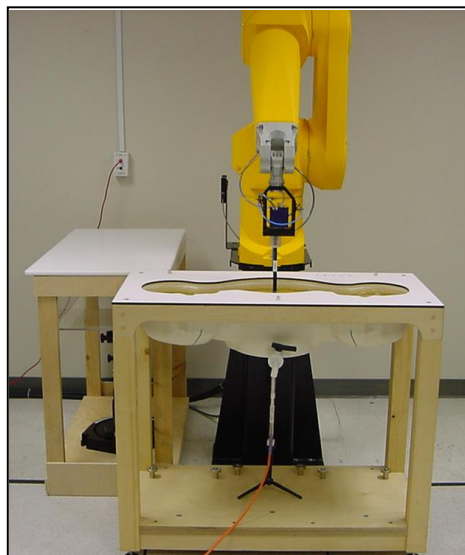


Figure 1: Staubli Robotic Arm

2 EUT ANTENNA PLACEMENT



Figure 2: Antenna placement (single antenna)



Figure 3: Antenna cable connection.

3 SAR MEASUREMENT SUMMARY

SAR BODY MEASUREMENT RESULTS						
Channel #	Frequency (MHz)	mode	Position	Power Drift %	Measured SAR 1g (W/kg)	Worst case tune-up corrected SAR 1g (W/kg)
1	2412	802.11b	Front	1.15	0.035	0.247
1	2412	802.11b	Back	4.47	0.015	0.106
1	2412	802.11b	Left	2.99	0.052	0.367

Table 2: 2.4GHz SAR head measurement results

Note 1: Duty cycle correction is not required 2.4 GHz because the duty cycle is 99%.

Note 2: Power drift correction is only applicable if it is more than 5%

Note 3: Worst case tune up tolerance corrected SAR

$$= [(Target Power + 1dBm) \text{ in mW} / (\text{Measured Power in mW})] \times DC \text{ corrected SAR}$$

2412MHz Front

Measured Power = 12.05dBm = 16.03 mW

Target = 19.54 dBm + 1dBm = 20.54 dBm = 113.24 mW

Worst case tune up tolerance corrected SAR = $[(113.24 \text{ mW} / (16.03 \text{ mW})) \times 0.035] = 0.247$

2412MHz Back

Measured Power = 12.05dBm = 16.03 mW

Target = 19.54 dBm + 1dBm = 20.54 dBm = 113.24 mW

Worst case tune up tolerance corrected SAR = $[(113.24 \text{ mW} / (16.03 \text{ mW})) \times 0.014] = 0.106$

2412MHz Left side

Measured Power = 12.05dBm = 16.03 mW

Target = 19.54 dBm + 1dBm = 20.54 dBm = 113.24 mW

Worst case tune up tolerance corrected SAR = $[(113.24 \text{ mW} / (16.03 \text{ mW})) \times 0.052] = 0.367$

4 CONDUCTED POWER MEASUREMENT SUMMARY

Since the EUT is capable of communicating via a large number of channels in various 802.11 modes, SAR testing for all the configurations is not desirable. KDB 248227 which is the SAR guidance for IEEE 802.11 WiFi transmitters was consulted to reduce the number of SAR tests without compromising the validity of the tested channel's applicability to the whole range of EUT supported channels.

So according to the KDB 248227, channels with the highest output conducted power were tested for SAR first. If the SAR number was greater than 1.2 W/kg then the next highest power channel was test for SAR. Below are the measured conducted output powers from the EUT for the 2.4 GHz channels.

As highlighted below, channel 1 was first selected. Since the SAR value was less than 1.2 W/kg, further testing for other modes was not necessary.

The main goal of SAR test reduction method as prescribed in KDB 248227 is to save time and not test unnecessarily for a very large number of channels.

2.4GHz WIFI Conducted Power

Channel	Mode	Conducted Power(dBm)	Target Power(dBm)
Channel 1	802.11b	12.05	19.54
Channel 6	802.11b	11.83	19.67
Channel 11	802.11b	11.6	18.8
Channel 1	802.11g	11.55	N/A
Channel 6	802.11g	11.61	N/A
Channel 11	802.11g	11.14	N/A
Channel 1	802.11n	11	13.07
Channel 6	802.11n	10.91	12.66
Channel 11	802.11n	10.61	12.22

Table 3: 802.11b, n, g 2.4 GHz conducted power measurements

2.4GHz BT Conducted Power

Channel	Mode	Conducted Power(dBm)	Target Power(dBm)
Channel 0	BR	4.128	8
Channel 39	BR	3.317	7.7
Channel 78	BR	1.588	7.3
Channel 0	EDR2	3.275	N/A
Channel 39	EDR2	2.234	N/A
Channel 78	EDR2	0.37	N/A
Channel 0	EDR3	3.852	N/A
Channel 39	EDR3	2.899	N/A
Channel 78	EDR3	1.128	N/A

Table 4: Bluetooth conducted power measurements.

The highest power for 2.4 GHz is 4.36 mW. Below is the SAR exclusion equation from KDB 447498:

$$\frac{\text{Max Power of Channel (mW)}}{\text{Test Separation Dist (mm)}} * \sqrt{\text{Frequency(GHz)}} \leq 3.0$$

For BT Basic (1 mbps) : Target = 8 dBm + 1dBm = 9 dBm = 7.94 mW

$$(7.94 \text{ mW} / 9.1 \text{ mm}) * \sqrt{2.4} = 0.563$$

Therefore BT channels are exempt from SAR testing.

5 DETAILS OF SAR EVALUATION

The Viavi Solutions Inc Tablet PC was determined to be compliant for localized Specific Absorption Rate based on the test provisions and conditions described below.

1. Due to the curved edge of the tablet a PBA was generated for any additional testing requirements. Please see attached PBA exhibit for FCC's response.
2. The Viavi Solutions Inc Corporation Tablet PC contains a pre-approved module FCC ID: TFB-TiWi1-01.
3. The EUT was tested for SAR against the planar section of the phantom in three different orientations. The front and back sides as well as the lower bottom edge were placed at 0.0cm separation from the phantom surface.
4. The EUT was placed into Test Mode at maximum duty cycle transmissions using software commands provided by Viavi. First channel was tested in 802.11b modes.
5. All SAR evaluations were performed with a fully charged battery.
6. There was no external method of measuring the RF output power before and after the SAR tests. The power drift measurement routine of the SAR system was used to determine if the power of the EUT stayed within the allowable limits.
7. The dielectric parameters of the simulated head and body fluid were measured prior to the evaluation using an 85070D Dielectric Probe Kit and an 8722D Network Analyzer.
8. The fluid and air temperature was measured prior to and after each SAR evaluation to ensure the temperature remained within ± 2 deg C of the temperature of the fluid when the dielectric properties were measured.
9. During the SAR evaluations if a distribution produced several hotspots over the course of the area scan, each hotspot was evaluated separately.



Figure 2: Viavi Tablet PC

5.1 FLOWCHART OF THE RECOMMENDED PRACTICES AND PROCEDURES

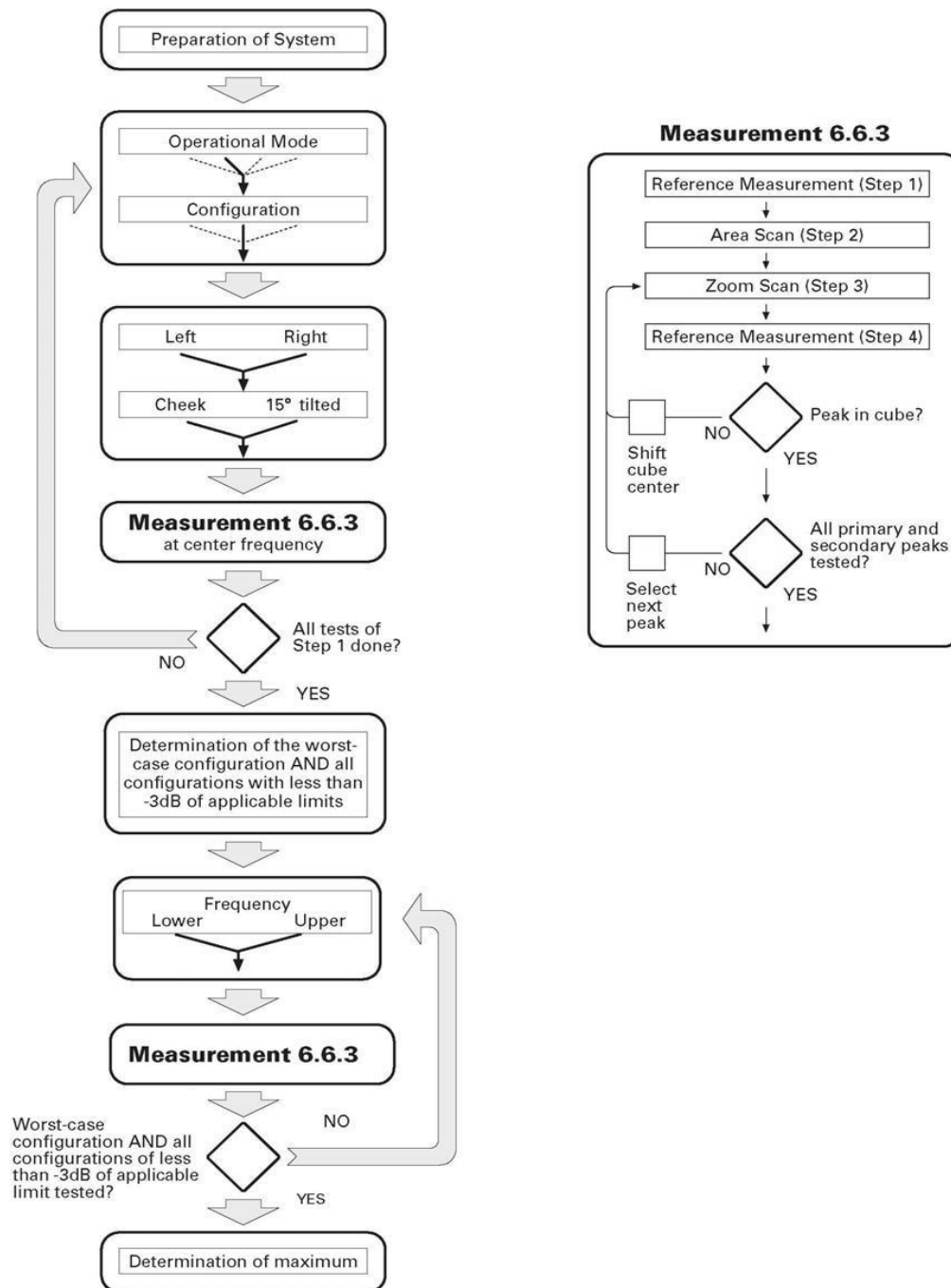


Figure 3: Flowchart of the recommended practices and procedures

5.2 EAR REFERENCE POINTS

Figure 12.1 shows the front, back and side views of the SAM Twin Phantom. The point M is the reference point for the center of the mouth, LE is the left ear reference point (ERP), and RE is the right ERP. The ERPs are 15mm posterior to the entrance to the ear canal (EEC) along the B-M line (Back-Mouth), as shown in Figure 12.2. The plane passing through the two ear canals and M is defined as the Reference Plane. The line N-F (Neck-Front) is perpendicular to the reference plane and passing through the RE (or LE) is called the Reference Pivoting. Line B-M is perpendicular to the N-F line. Both N-F and B-M lines are marked on the external phantom shell to facilitate handset positioning.



Figure 4: Front, back and side view of SAM Twin Phantom

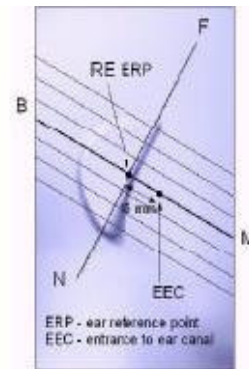


Figure 5: Side view of ERPs

5.3 EVALUATION PROCEDURES

The evaluation was performed in the head area of the phantom in both left and right sides. The SAR was determined by a pre-defined procedure within the DASY4 software. Upon completion of a reference check, the exposed region of the phantom was scanned near the inner surface with a grid spacing of 10mm x 10mm.

An area scan was determined as follows:

Based on the defined area scan grid, a more detailed grid is created to increase the points by a factor of 10. The interpolation function then evaluates all field values between corresponding measurement points.

A linear search is applied to find all the candidate maxima. Subsequently, all maxima are removed that are >2 dB from the global maximum. The remaining maxima are then used to position the cube scans.

A 1g and 10g spatial peak SAR was determined as follows:

For frequencies $\leq 4.5\text{GHz}$ a 32mm x 32mm x 34mm (7x7x7 data points) zoom scan was assessed at the position where the greatest V/m was detected. For frequencies $\geq 4.5\text{GHz}$ a 28mm x 28mm x 24mm (7x7x9 data points) zoom scan was assessed at the position where the greatest V/m was detected. The data at the surface was extrapolated since the distance from the probes sensors to the surface is 3.9cm. A least squares fourth-order polynomial was used to generate points between the probe detector and the inner surface of the phantom.

Interpolated data is used to calculate the average SAR over 1g and 10g cubes by spatially discretizing the entire measured cube. The volume used to determine the averaged SAR is a 1mm grid (42875 interpolated points).

Z-Scan was determined as follows:

The Z-scan measures points along a vertical straight line. The line runs along a line normal to the inner surface of the phantom surface.

5.4 DATA EVALUATION PROCEDURES

The DASY4 post processing software (SEMCAD) automatically executes the following procedures to calculate the field units from the microvolt readings at the probe connector. The parameters used in the evaluation are stored in the configuration modules of the software:

Probe Parameters:	- Sensitivity	$Norm_i, a_{i0}, a_{i1}, a_{i2}$
	- Conversion Factor	$ConvF_i$
	- Dipole Compression Point	dcp_i
Device parameters:	- Frequency	f
	- Crest factor	cf
Media parameters:	- Conductivity	σ
	- Density	ρ

These parameters must be set correctly in the software. They can be found in the component documents or can be imported into the software from the configuration files issued for the DASY components. In the direct measuring mode of the multimeter option, the parameters of the actual system setup are used. In the scan visualization and export modes, the parameters stored in the corresponding document files are used. The first step of the evaluation is a linearization of the filtered input signal to account for the compression characteristics of the detector diode. The compensation depends on the input signal, the diode type and the DC - transmission factor from the diode to the evaluation electronics. If the exciting field is pulsed, the crest factor of the signal must be known to correctly compensate for peak power. The formula for each channel can be given as:

$$V_i = U_i + U_i^2 \cdot \frac{cf}{dcp_i}$$

with V_i = Compensated signal of channel i (i = x, y, z)
 U_i = Input signal of channel i (i = x, y, z)
 cf = Crest factor of exciting field (DASY parameter)
 dcp_i = Diode compression point (DASY parameter)

From the compensated input signals the primary field data for each channel can be evaluated:

$$\text{E - fieldprobes : } E_i = \sqrt{\frac{V_i}{Norm_i \cdot ConvF}}$$

$$\text{H - fieldprobes : } H_i = \sqrt{V_i} \cdot \frac{a_{i0} + a_{i1}f + a_{i2}f^2}{f}$$

With V_i = Compensated signal of channel i (i = x, y, z)
 $Norm_i$ = Sensor sensitivity of channel i (i = x, y, z)
 $\mu V/(V/m)^2$ for E-field probes
 $ConvF$ = Sensitivity enhancement in solution
 a_{ij} = Sensor sensitivity factors for H-field probes

f = Carrier frequency (GHz)
 E_i = Electric field strength of channel i in V/m
 H_i = Magnetic field strength of channel i in A/m

The RSS value of the field components gives the total field strength (Hermitian magnitude):

$$E_{tot} = \sqrt{E_x^2 + E_y^2 + E_z^2}$$

The primary field data are used to calculate the derived field units.

$$SAR = E_{tot}^2 \cdot \frac{\sigma}{\rho \cdot 1'000}$$

with SAR = local specific absorption rate in mW/g
 E_{tot} = total field strength in V/m
 σ = conductivity in [mho/m] or [Siemens/m]
 ρ = equivalent tissue density in g/cm³

Note that the density is normally set to 1 (or 1.06), to account for actual brain density rather than the density of the simulation liquid.

The power flow density is calculated assuming the excitation field as a free space field.

$$P_{pwe} = \frac{E_{tot}^2}{3770} \quad \text{or} \quad P_{pwe} = H_{tot}^2 \cdot 37.7$$

With P_{pwe} = Equivalent power density of a plane wave in mW/cm²
 E_{tot} = total electric field strength in V/m
 H_{tot} = total magnetic field strength in A/m

5.5 SAR SAFETY LIMITS

EXPOSURE LIMITS	SAR 1g (W/kg)	
	(General Population / Uncontrolled Exposure Environment)	(Occupational / Controlled Exposure Environment)
Spatial Average (averaged over the whole body)	0.08	0.4
Spatial Peak (averaged over any 1g of tissue)	1.60	8.0

Table 5: SAR safety limits for FCC.

Notes:

1. Uncontrolled exposure environments are locations where there is potential exposure of individuals who have no knowledge or control of their potential exposure.
2. Controlled exposure environments are locations where there is potential exposure of individuals who have knowledge of their potential exposure and can exercise control over their exposure.

6 SYSTEM PERFORMANCE CHECK

Prior to the SAR evaluation a system check was performed in the planar section of the SAM phantom with a 2450MHz dipole. The dielectric parameters of the simulated body were measured prior to the system performance check using an 85070D Dielectric Probe Kit and an 8722D Network Analyzer. A forward power of 250 mW for 2.4 GHz was applied to the dipole and the system was verified to a tolerance of $\pm 10\%$.

Test Date	Fluid Type (MHz)	SAR 1g (W/kg)		Permittivity Constant ϵ_r		Conductivity σ (mho/m)		Ambient Temp. (C)	Fluid Temp. (C)	Fluid Depth (cm)
		Calibrated Target	Measured	IEEE Target	Measured	IEEE Target	Measured			
11/30/2016	2450 body	12.9 $\pm 5\%$	13.0	52.7 $\pm 5\%$	50.54	1.95 $\pm 10\%$	2.03	23.0	22.0	≥ 15

Table 6: System performance and head simulating fluid parameter check results

Note1: The ambient temperature, 23°C, and the fluid temperatures, 22°C, were measured prior to the fluid parameter check and the system performance check and kept consistent during the measurement periods.

Note2: Fluid Depth was ≥ 15 cm.

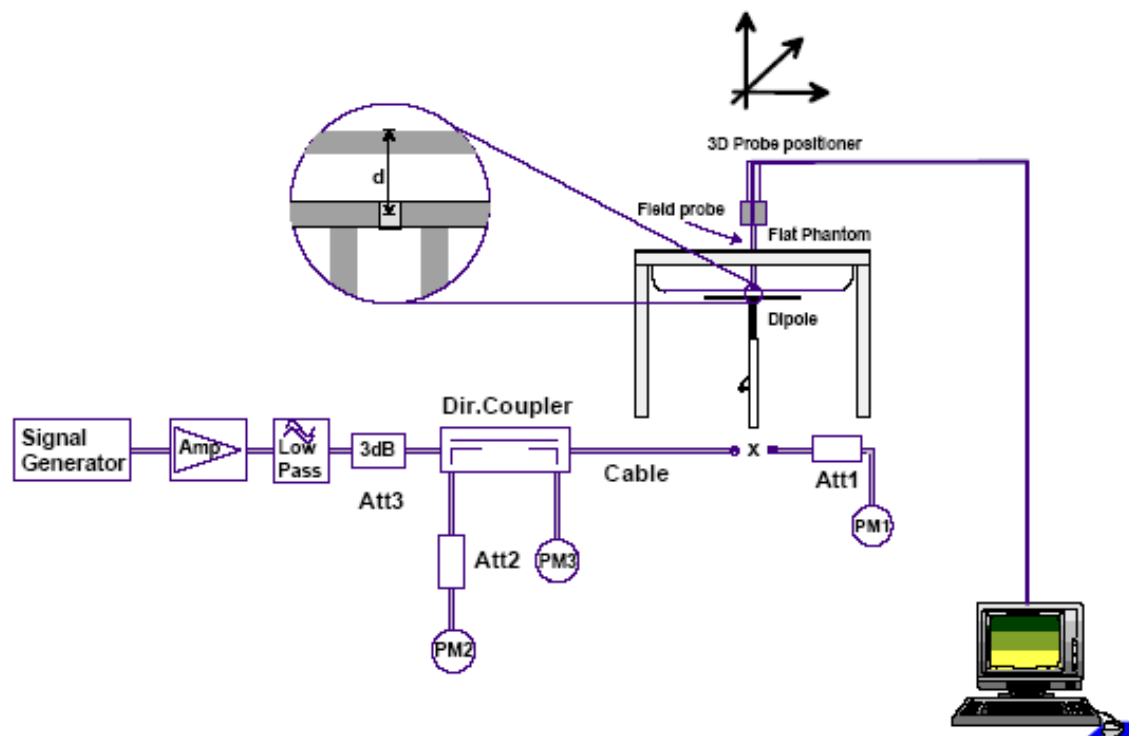


Figure 6: System performance check components

7 SIMULATED EQUIVALENT TISSUE

For the measurement of the field distribution inside the SAM phantom with DASY4, the phantom must be filled with 25 liters of homogeneous body simulating liquid. Target dielectric parameters for the body simulating liquid at 2450 MHz are defined in the standards for compliance testing (e.g CENELEC EN50361, IEEE P1528)

Liquid Type	M 2450-B	
Ingredient	Weight (g)	Weight (%)
Water	686.35	68.64
DGBE	313.65	31.37
Salt	0.00	0.00
Total amount	1000.00	100.00
Goal Dielectric Parameters		
Frequency (MHz)	2450	
Relative Permittivity	52.70	
Conductivity (S/m)	1.95	

Table 7: Recipe for body tissue simulating fluid for 2450 MHz.

The 2.4 GHz fluids for body tissue simulation were prepared in-house.

8 ROBOT SYSTEM SPECIFICATIONS

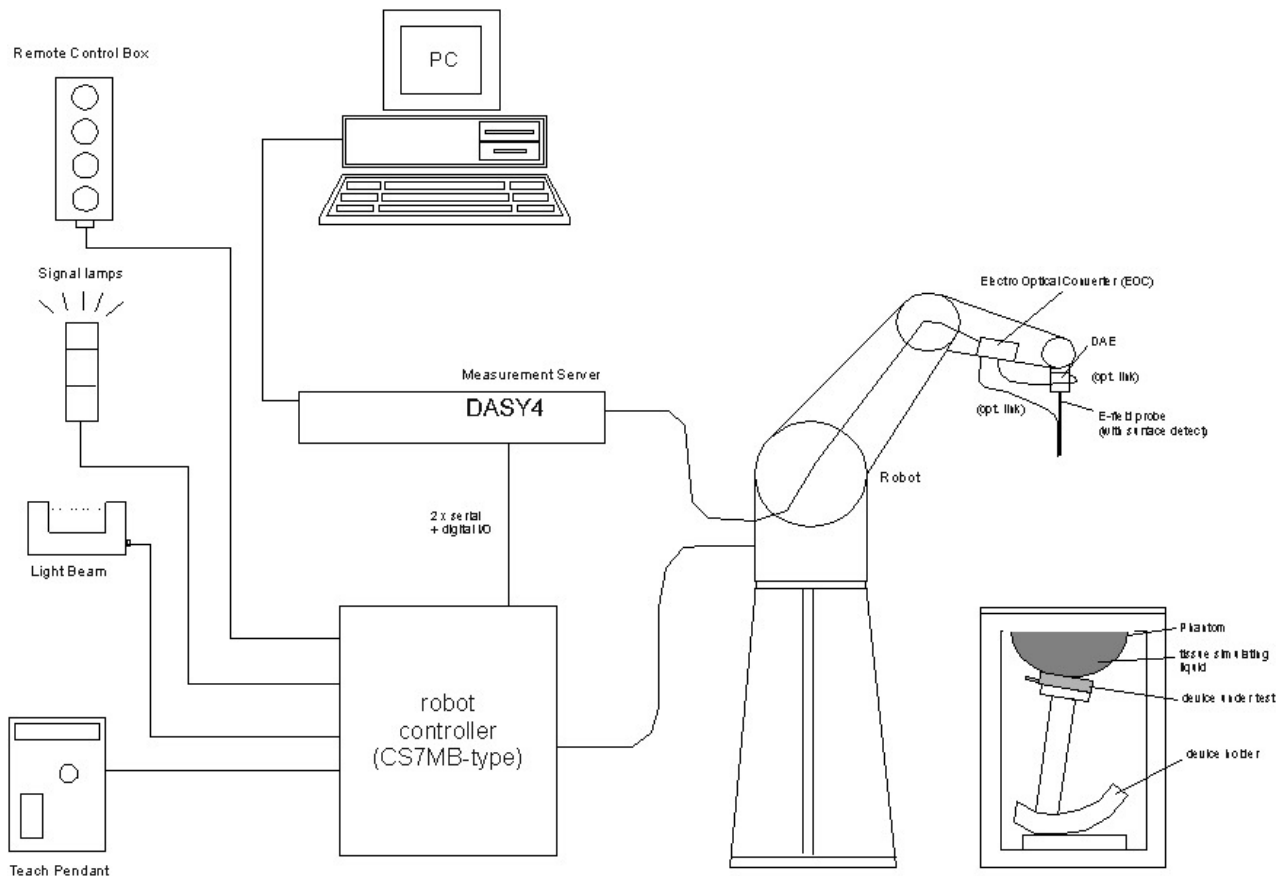


Figure 7: SAR Measurement System

8.1 Specifications

Positioner:

Robot:	Staubli Unimation Corp. Robot Model: RX90
Repeatability:	0.02 mm
No. of axis:	6

8.2 Data Acquisition Electronic (DAE) System:

Cell Controller

Processor:	Compaq Evo
Clock Speed:	2.4 GHz
Operating System:	Windows XP Professional

Data Converter

Features: Signal Amplifier, multiplexer, A/D converter, and control logic
Software: DASY4 software
Connecting Lines: Optical downlink for data and status info.
Optical uplink for commands and clock

Dasy4 Measurement Server

detection Function: Real-time data evaluation for field measurements and surface
Hardware: PC/104 166MHz Pentium CPU; 32 MB chipdisk; 64 MB RAM
Connections: COM1, COM2, DAE, Robot, Ethernet, Service Interface

E-Field Probe

Model: ET3DV6
Serial No.: 1793
Construction: Triangular core fiber optic detection system
Frequency: 10 MHz to 6 GHz
Linearity: ± 0.2 dB (30 MHz to 3 GHz)

EX-Probe

Model: EX3DV4
Serial No. 3511
Construction: Triangular core
Frequency: 10 MHz to > 6 GHz
Linearity: ± 0.2 dB (30 MHz to 3 GHz)

8.3 Phantom(s):

Validation & Evaluation Phantom

Type: SAM V4.0C
Shell Material: Fiberglass
Thickness: 2.0 ± 0.1 mm
Volume: Approx. 20 liters

8.4 RX90BL Robot

The Stäubli RX90BL Robot is a standard high precision 6-axis robot with an arm extension for accommodating the data acquisition electronics (DAE).

8.5 Robot Controller

The CS7MB Robot Controller system drives the robot motors. The system consists of a power supply, robot controller, and remote control with teach pendant and additional circuitry for robot safety such as warning lamps, etc.

8.6 Light Beam Switch

The Light Beam Switch (Probe alignment tool) allows automatic “tooling” of the probe. During the process, the actual position of the probe tip with respect to the robot arm is measured as well as the probe length and the horizontal probe offset. The software then corrects all movements, so that the robot coordinates are valid for the probe tip. The repeatability of this process is better than 0.1 mm. If a position has been taught with an aligned probe, the same position will be reached with another aligned probe within 0.1 mm, even if the other probe has different dimensions. During probe rotations, the probe tip will keep its actual position.



Figure 8: Light beam switch

8.7 Data Acquisition Electronics

The Data Acquisition Electronics consists of a highly sensitive electrometer grade preamplifier with auto-zeroing, a channel and gain switching multiplexer, a fast 16-bit A/D converter and a command decoder and control logic unit. Some of the tasks the DAE performs are signal amplification, signal multiplexing, A/D conversion, and offset measurements.

The DAE also contains the mechanical probe-mounting device, which contains two different sensor systems for frontal and sideways probe contacts used for probe collision detection and mechanical surface detection for controlling the distance between the probe and the inner surface of the phantom shell. Transmission from the DAE to the measurement server, via the EOC, is

through an optical downlink for data and status information as well as an optical uplink for commands and the clock.



Figure 9: Data acquisition electronics

8.8 Electro-Optical Converter (EOC)

The Electro-Optical Converter performs the conversion between the optical and electrical of the signals for the digital communication to the DAE and for the analog signal from the optical surface detection. The EOC connects to, and transfers data to, the DASY4 measurement server. The EOC also contains the fiber optical surface detection system for controlling the distance between the probe and the inner surface of the phantom shell.



Figure 10: Electro optical converter

8.9 Measurement Server

The Measurement Server performs time critical tasks such as signal filtering, all real-time data evaluation for field measurements and surface detection, controls robot movements, and handles safety operation. The PC-operating system cannot interfere with these time critical processes. A watchdog supervises all connections, and disconnection of any of the cables to the measurement server will automatically disarm the robot and disable all program-controlled robot movements.



Figure 11: DASY4 measurement server

8.10 Dosimetric Probe

Dosimetric Probe is a symmetrical design with triangular core that incorporates three 3 mm long dipoles arranged so that the overall response is close to isotropic. The probe sensors are covered by an outer protective shell, which is resistant to organic solvents i.e. glycol. The probe is equipped with an optical multi-fiber line, ending at the front of the probe tip, for optical surface detection. This line connects to the EOC box on the robot arm and provides automatic detection of the phantom surface. The optical surface detection works in transparent liquids and on diffuse reflecting surfaces with a repeatability of better than $\pm 0.1\text{mm}$.

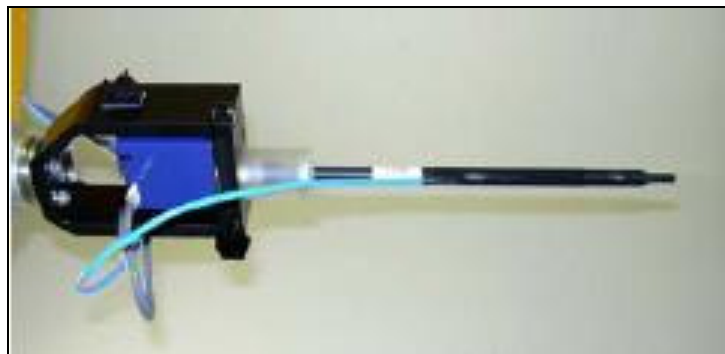


Figure 12: Electric field probe

8.11 SAM Phantom

The SAM (Specific Anthropomorphic Mannequin) twin phantom is a fiberglass shell phantom with 2mm shell thickness (except the ear region where shell thickness increases to 6mm) integrated into a wooden table. The shape of the shell corresponds to the phantom defined by SCC34-SC2. It enables the dosimetric evaluation of left hand, right hand phone usage as well as body mounted usage at the flat phantom region. The flat section is also used for system validation and the length and width of the flat section are at least $0.75 \lambda_0$ and $0.6 \lambda_0$ respectively at frequencies of 824 MHz and above (λ_0 = wavelength in air).



Figure 13: Specific anthropomorphic mannequin twin phantom

Reference markings on the phantom top allow the complete setup of all predefined phantom positions and measurement grids by manually teaching three points in the robot. A white cover is provided to cover the phantom during off-periods preventing water evaporation and changes in the liquid parameters. Free space scans of devices on the cover are possible. The phantom is filled with a tissue simulating liquid to a depth of at least 15 cm at each ear reference point. The bottom plate of the wooden table contains three pair of bolts for locking the device holder.

8.12 Planar Phantom

The planar phantom is constructed of Plexiglas material with a 2.0 mm shell thickness for face-held and body-worn SAR evaluations of handheld radio transceivers. The planar phantom is mounted on the wooden table of the DASY4 system.

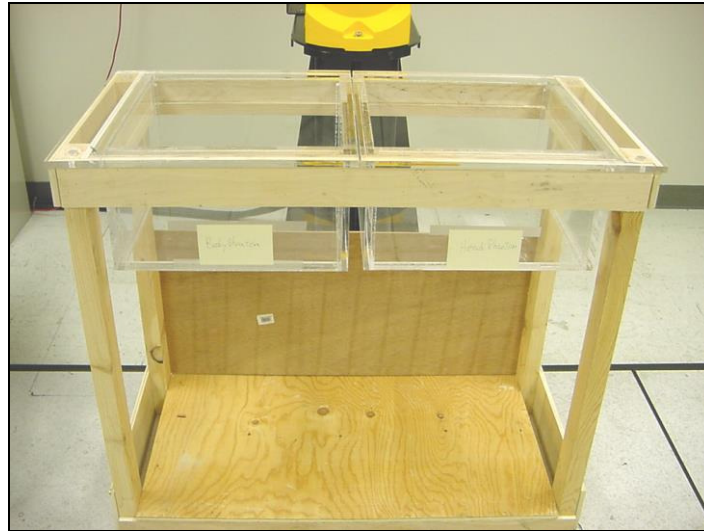


Figure 14: Planner phantom

8.13 Validation Planar Phantom

The validation planar phantom is constructed of Plexiglas material with a 6.0 mm shell thickness for system validations at 450MHz and below. The validation planar phantom is mounted on the wooden table of the DASY4 system.

8.14 Device Holder

The device holder is designed to cope with the different measurement positions in the three sections of the SAM phantom given in the standard. It has two scales, one for device rotation (with respect to the body axis) and one for device inclination (with respect to the line between the ear openings). The rotation center for both scales is the ear opening, thus the device needs no repositioning when changing the angles. The plane between the ear openings and the mouth tip has a rotation angle of 65°.

The DASY device holder has been made out of low-loss POM material having the following dielectric parameters: relative permittivity $\epsilon = 3$ and loss tangent $\delta = 0.02$. The amount of dielectric material has been reduced in the closest vicinity of the device, since measurements have suggested that the influence of the clamp on the test results could thus be lowered.

The dielectric properties of the liquid conform to all the tabulated values [2-5]. Liquids are prepared according to Annex A and dielectric properties are measured according to Annex B.



Figure 15: Device holder

8.15 System Validation Kits

Power Capability: > 100 W ($f < 1\text{GHz}$); > 40 W ($f > 1\text{GHz}$)

Construction: Symmetrical dipole with 1/4 balun Enables measurement of feed point impedance with NWA Matched for use near flat phantoms filled with brain simulating solutions Includes distance holder and tripod adaptor.

Frequency: 300, 450, 835, 1900, 2450 MHz, 5-6GHz

Return loss: >20 dB at specified validation position

Dimensions: 300 MHz Dipole: Length: 396mm; Overall Height: 430 mm; Diameter: 6 mm
450 MHz Dipole: Length: 270 mm; Overall Height: 347 mm; Diameter: 6 mm
835 MHz Dipole: Length: 161 mm; Overall Height: 270 mm; Diameter: 3.6 mm
1900 MHz Dipole: Length: 68 mm; Overall Height: 219 mm; Diameter: 3.6 mm
2450 MHz Dipole: Length: 51.5 mm; Overall Height: 300 mm; Diameter: 3.6 mm
5-6GHz Dipole: Length: 26.0 mm; Overall Height: 170 mm; Diameter: 3.6 mm

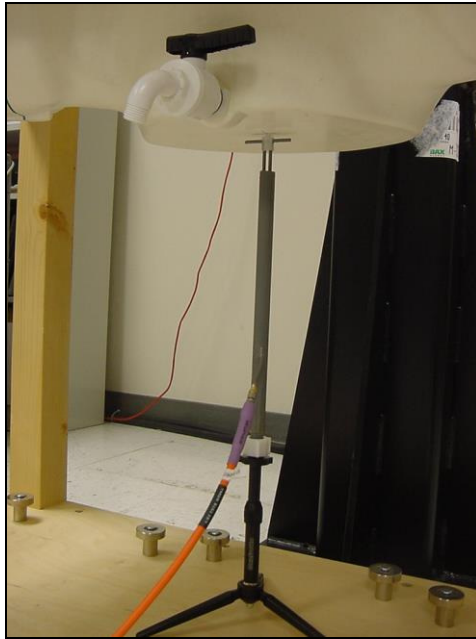


Figure 16: System validation using dipole antenna

9 TEST EQUIPMENT LIST

Test Equipment	Serial Number	Calibration Date	Calibration Due
DASY4 System Robot RX90	FO3/SX19A1/A/01	N/A	NA
EX3DV4	3722	9/23/2016	9/23/2017
DAE	584	9/21/2016	9/21/2017
2450MHz Dipole	857	9/23/2016	9/23/2017
SAM Phantom V4.0C	N/A	N/A	NA
Keysight Vector Signal Generator	1S3905	3/30/2015	3/30/2017
EMCO Horn Antenna	1S2208	Functional Verification	
Agilent E4407B Spectrum Analyzer	1S2607	3/23/2016	3/23/2017
Agilent 8722D Network Analyzer	1S2272	9/3/2015	3/3/2017
Extech Power Supply (30 VDC)	4S3771	Functional Verification	
Mini-Circuits power amplifier	1S2447	Functional Verification	
Agilent power meter	1S2276	10/22/2015	4/22/2017
Mini-Circuits USB power sensor	1S3838	06/29/2015	12/29/2016
Krytar Directional Coupler (1-20Ghz)	1S2034	Functional Verification	
AR dual Directional Coupler (9Khz-1Ghz)	1S2542	Functional Verification	
HP High Temperature Dielectric Probe Kit 85070D Opt 1 (stand)	1T4366	04/30/2015	12/29/2016

Table 8: Test equipment list details.

9.1 MEASUREMENT UNCERTAINTIES

UNCERTAINTY ASSESSMENT 300MHz-3GHz

Error Description	Tol. ±%	Prob. Dist.	Div.	c_i 1g	c_i 10g	Std Unc ±% (1g)	Std Unc ±% (10g)	v_i or v_{eff}
Measurement System								
Probe calibration	4.8	N	1	1	1	4.8	4.8	N/A
Axial isotropy of the probe	4.7	R	$\sqrt{3}$	0.7	0.7	1.9	1.9	N/A
Spherical isotropy of the probe	9.6	R	$\sqrt{3}$	0.7	0.7	3.9	3.9	N/A
Boundary effects	1.0	R	$\sqrt{3}$	1	1	4.8	4.8	N/A
Probe linearity	4.7	R	$\sqrt{3}$	1	1	2.7	2.7	N/A
Detection limit	1.0	R	$\sqrt{3}$	1	1	0.6	0.6	N/A
Readout electronics	1.0	N	1	1	1	1.0	1.0	N/A
Response time	0.8	R	$\sqrt{3}$	1	1	0.5	0.5	N/A
Integration time	2.6	R	$\sqrt{3}$	1	1	0.8	0.8	N/A
RF ambient conditions	3.0	R	$\sqrt{3}$	1	1	0.43	0.43	N/A
Mech. constraints of robot	0.4	R	$\sqrt{3}$	1	1	0.2	0.2	N/A
Probe positioning	2.9	R	$\sqrt{3}$	1	1	1.7	1.7	N/A
Extrapolation & integration	1.0	R	$\sqrt{3}$	1	1	2.3	2.3	N/A
Test Sample Related								
Device positioning	2.9	N	1	1	1	2.23	2.23	145
Device holder uncertainty	3.6	N	1	1	1	5.0	5.0	5
Power drift	5.0	R	$\sqrt{3}$			2.9	2.9	N/A
Phantom and Setup								
Phantom uncertainty	4.0	R	$\sqrt{3}$	1	1	2.3	2.3	N/A
Liquid conductivity (target)	5.0	R	$\sqrt{3}$	0.64	0.43	1.8	1.2	N/A
Liquid conductivity (measured)	2.5	N	1	0.64	0.43	1.6	1.1	N/A
Liquid permittivity (target)	5.0	R	$\sqrt{3}$	0.6	0.5	1.7	1.4	N/A
Liquid permittivity (measured)	2.5	N	1	0.6	0.5	1.5	1.2	N/A
Combined Standard Uncertainty (k=1)		RSS				10.3	10.0	
Expanded Uncertainty (k=2) 95% Confidence Level						20.6	20.1	

Table 9: Worst-case uncertainty for DASY4 assessed according to IEEE P1528.

The budget is valid for the frequency range 300MHz to 3GHz and represents a worst-case analysis.

9.2 UNCERTAINTY FOR SYSTEM PERFORMANCE CHECK

Error Description	Tol. ±%	Prob. Dist.	Div.	c_i 1g	c_i 10g	Std Unc ±% (1g)	Std Unc ±% (10g)	v_i or v_{eff}
Measurement System								
Probe calibration	5.9	N	1	1	1	5.9	5.9	∞
Axial Isotropy	4.7	R	√3	1	1	2.7	2.7	∞
Hemispherical Isotropy	9.6	R	√3	0	0	0	0	∞
Boundary effects	1.0	R	√3	1	1	0.6	0.6	∞
Linearity	4.7	R	√3	1	1	2.7	2.7	∞
System Detection limit	1.0	R	√3	1	1	0.6	0.6	∞
Readout electronics	0.3	N	1	1	1	0.3	0.3	∞
Response time	0	R	√3	1	1	0	0	∞
Integration time	0	R	√3	1	1	0	0	∞
RF Ambient Noise	3.0	R	√3	1	1	1.7	1.7	∞
RF Ambient Reflections	3.0	R	√3	1	1	1.7	1.7	∞
Probe Positioner	0.4	R	√3	1	1	0.2	0.2	∞
Probe positioning	2.9	R	√3	1	1	1.7	1.7	∞
Algorithms for Max. SAR Eval.	1.0	R	√3	1	1	0.6	0.6	∞
Dipole								
Dipole Axis to Liquid Distance	2.0	R	√3	1	1	1.2	1.2	∞
Input power and SAR drift meas.	4.7	R	√3	1	1	2.7	2.7	∞
Phantom and Tissue Parameters								
Phantom uncertainty	4.0	R	√3	1	1	2.3	2.3	∞
Liquid conductivity (target)	5.0	R	√3	0.64	0.43	1.8	1.2	∞
Liquid conductivity (measured)	2.5	N	1	0.64	0.43	1.6	1.1	∞
Liquid permittivity (target)	5.0	R	√3	0.6	0.5	1.7	1.4	∞
Liquid permittivity (measured)	2.5	N	1	0.6	0.5	1.5	1.2	∞
Combined Standard Uncertainty						9.2	8.9	
Coverage Factor for 95%		kp=2						
Expanded Uncertainty						18.4	17.8	

Table 10: Uncertainty of a system performance check with DASY4 system.

The budget is valid for the frequency range 300MHz to 3GHz and represents a worst-case analysis.

10 REFERENCES

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11 EUT TEST SETUP PHOTOS

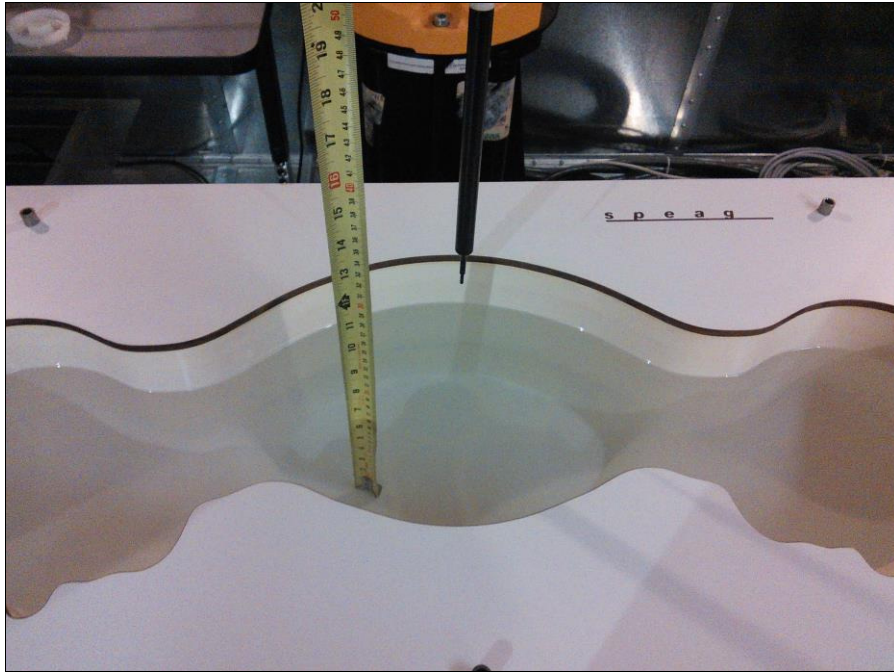


Figure 17: 2.4GHz body tissue simulating fluid



Figure 18: EUT Left Edge, Side against Phantom



Figure 19: EUT with Face of EUT against Phantom



Figure 20: EUT with Back of EUT against Phantom



ANNEX A 2.4 GHz SAR MEASUREMENT DATA

CH1 Body 2412MHz 802.11b_1Mbps Front

Date/Time: 11/30/2016 6:43:51 PM

DUT: Viavi; Type: Device

Communication System: 1Mbps; ; Frequency: 2412 MHz; Duty Cycle: 1:1

Medium: M2450 Medium parameters used: $f = 2412$ MHz; $\sigma = 2.03$ mho/m; $\epsilon_r = 50.54$; $\rho = 1000$ kg/m³

Phantom section: Flat Section

- Probe: EX3DV4 - SN3722; ConvF(6.97, 6.97, 6.97); Calibrated: 9/23/2016

- Sensor-Surface: 2mm (Mechanical Surface Detection)

- Electronics: DAE3 Sn584; Calibrated: 9/21/2016

- Phantom: SAM with CRP; Type: SAM; Serial: TP 1310

- Measurement SW: DASY4, V4.7 Build 71; Postprocessing SW: SEMCAD, V1.8 Build 184

Ch-1 SAR Body/Area Scan (141x161x1):

Measurement grid: $dx=10$ mm, $dy=10$ mm

Maximum value of SAR (interpolated) = 0.031 mW/g

Ch-1 SAR Body/Zoom Scan (7x7x7)/Cube 0:

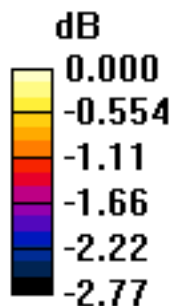
Measurement grid: $dx=5$ mm, $dy=5$ mm, $dz=5$ mm

Reference Value = 3.62 V/m; Power Drift = 0.050 dB

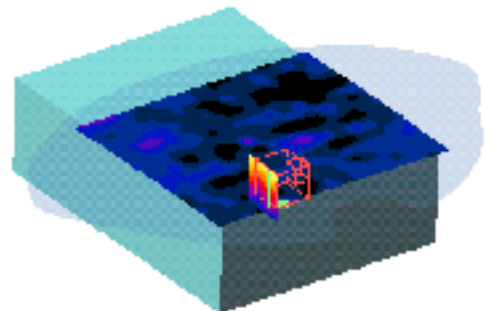
Peak SAR (extrapolated) = 0.040 W/kg

SAR(1 g) = 0.035 mW/g

Maximum value of SAR (measured) = 0.040 mW/g



0 dB = 0.040mW/g



CH1 Body 2412MHz 802.11b_1Mbps Back

Date/Time: 12/1/2016 11:50:12 AM

DUT: Viavi; Type: Device

Communication System: 1Mbps; ; Frequency: 2412 MHz; Duty Cycle: 1:1

Medium: M2450 Medium parameters used: $f = 2412$ MHz; $\sigma = 2.03$ mho/m; $\epsilon_r = 50.54$; $\rho = 1000$ kg/m³

Phantom section: Flat Section

- Probe: EX3DV4 - SN3722; ConvF(6.97, 6.97, 6.97); Calibrated: 9/23/2016
- Sensor-Surface: 2mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn584; Calibrated: 9/21/2016
- Phantom: SAM with CRP; Type: SAM; Serial: TP 1310
- Measurement SW: DASY4, V4.7 Build 71; Postprocessing SW: SEMCAD, V1.8 Build 184

Ch-1 SAR Body/Area Scan (141x161x1):

Measurement grid: $dx=10$ mm, $dy=10$ mm

Maximum value of SAR (interpolated) = 0.017 mW/g

Ch-1 SAR Body/Zoom Scan (7x7x7)/Cube 0:

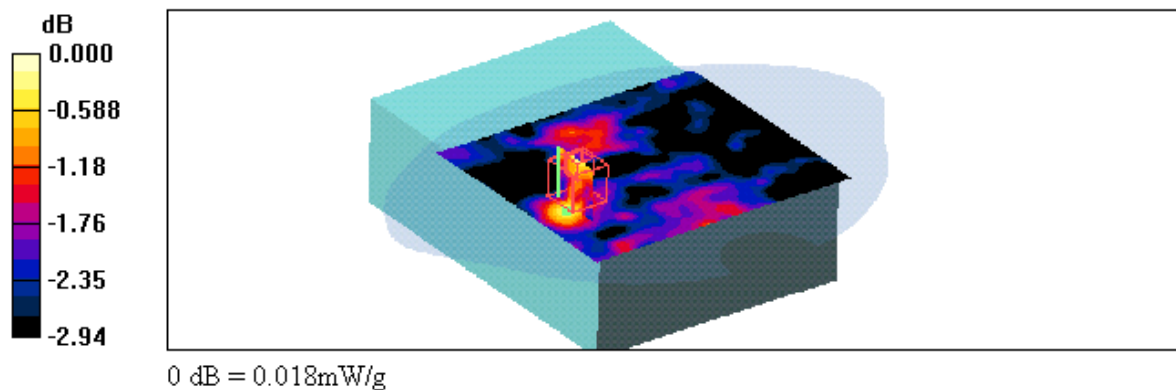
Measurement grid: $dx=5$ mm, $dy=5$ mm, $dz=5$ mm

Reference Value = 2.41 V/m; Power Drift = 0.190 dB

Peak SAR (extrapolated) = 0.021 W/kg

SAR(1 g) = 0.015 mW/g

Maximum value of SAR (measured) = 0.018 mW/g



CH1 Body 2412MHz FCC_1Mbps Leftside

Date/Time: 12/1/2016 1:29:13 PM

DUT: Viavi; Type: Device

Communication System: 1Mbps; ; Frequency: 2412 MHz; Duty Cycle: 1:1

Medium: M2450 Medium parameters used: $f = 2412$ MHz; $\sigma = 2.03$ mho/m; $\epsilon_r = 50.54$; $\rho = 1000$ kg/m³

Phantom section: Flat Section

- Probe: EX3DV4 - SN3722; ConvF(6.97, 6.97, 6.97); Calibrated: 9/23/2016
- Sensor-Surface: 2mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn584; Calibrated: 9/21/2016
- Phantom: SAM with CRP; Type: SAM; Serial: TP 1310
- Measurement SW: DASY4, V4.7 Build 71; Postprocessing SW: SEMCAD, V1.8 Build 184

Ch-1 SAR Body/Area Scan (141x161x1):

Measurement grid: $dx=10$ mm, $dy=10$ mm

Maximum value of SAR (interpolated) = 0.069 mW/g

Ch-1 SAR Body/Zoom Scan (7x7x7)/Cube 0:

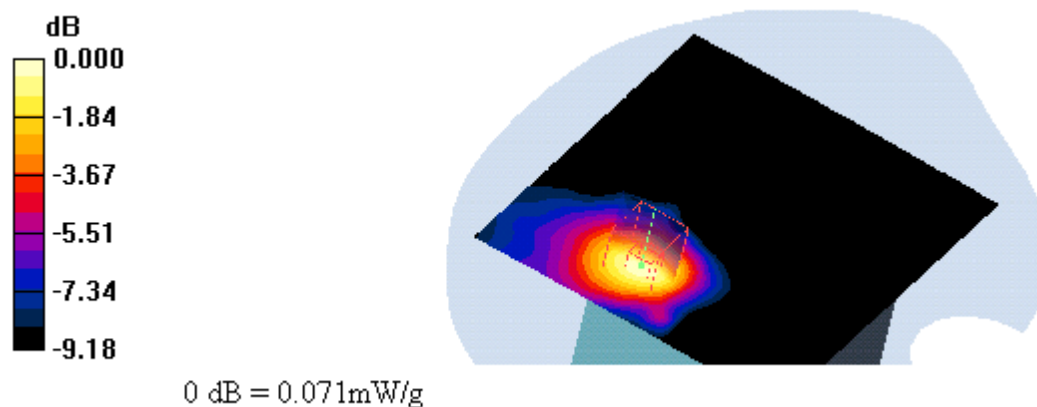
Measurement grid: $dx=5$ mm, $dy=5$ mm, $dz=5$ mm

Reference Value = 5.43 V/m; Power Drift = -0.128 dB

Peak SAR (extrapolated) = 0.090 W/kg

SAR(1 g) = 0.052 mW/g

Maximum value of SAR (measured) = 0.071 mW/g





ANNEX B 2.4 GHz SYSTEM PERFORMANCE CHECK

2450MHz Body Validation

Date/Time: 11/30/2016 5:37:25 PM

DUT: D2450; Type: 1S2672

Communication System: CW; ; Frequency: 2450 MHz; Duty Cycle: 1:1

Medium: BSL2450 Medium parameters used: $f = 2450$ MHz; $\sigma = 2.03$ mho/m; $\epsilon_r = 50.54$; $\rho = 1000$ kg/m³

Phantom section: Flat Section

- Probe: EX3DV4 - SN3722; ConvF(6.97, 6.97, 6.97); Calibrated: 9/23/2016
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn584; Calibrated: 9/21/2016
- Phantom: SAM with CRP; Type: SAM; Serial: TP 1310
- Measurement SW: DASY4, V4.7 Build 71; Postprocessing SW: SEMCAD, V1.8 Build 184

d=10mm, Pin=250mW/Area Scan (81x51x1):

Measurement grid: dx=10mm, dy=10mm

Maximum value of SAR (interpolated) = 15.7 mW/g

d=10mm, Pin=250mW/Zoom Scan (7x7x7) (7x7x7)/Cube 0:

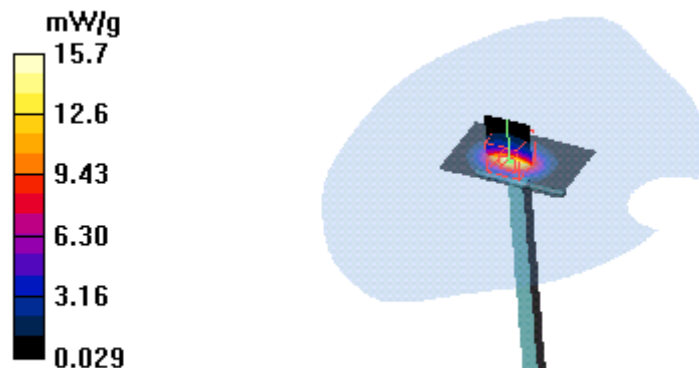
Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 84.4 V/m; Power Drift = -0.009 dB

Peak SAR (extrapolated) = 27.5 W/kg

SAR(1 g) = 13 mW/g

Maximum value of SAR (measured) = 14.8 mW/g





ANNEX C 2.4 DIPOLE CALIBRATION CERTIFICATE

Calibration Laboratory of
Schmid & Partner
Engineering AG
 Zeughausstrasse 43, 8004 Zurich, Switzerland



S Schweizerischer Kalibrierdienst
C Service suisse d'étalonnage
S Servizio svizzero di taratura
S Swiss Calibration Service

Accredited by the Swiss Accreditation Service (SAS)
 The Swiss Accreditation Service is one of the signatories to the EA
 Multilateral Agreement for the recognition of calibration certificates

Accreditation No.: **SCS 0108**

Client **MET Laboratories**

Certificate No: **D2450V2-857_Sep16**

CALIBRATION CERTIFICATE

Object **D2450V2 - SN:857**

Calibration procedure(s) **QA CAL-05.v9**
 Calibration procedure for dipole validation kits above 700 MHz



Calibration date: **September 23, 2016**

This calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI).
 The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

All calibrations have been conducted in the closed laboratory facility: environment temperature (22 ± 3)°C and humidity < 70%.

Calibration Equipment used (M&TE critical for calibration)

Primary Standards	ID #	Cal Date (Certificate No.)	Scheduled Calibration
Power meter NRP	SN: 104778	06-Apr-16 (No. 217-02288/02289)	Apr-17
Power sensor NRP-Z91	SN: 103244	06-Apr-16 (No. 217-02288)	Apr-17
Power sensor NRP-Z91	SN: 103245	06-Apr-16 (No. 217-02289)	Apr-17
Reference 20 dB Attenuator	SN: 5058 (20k)	05-Apr-16 (No. 217-02292)	Apr-17
Type-N mismatch combination	SN: 5047.2 / 06327	05-Apr-16 (No. 217-02295)	Apr-17
Reference Probe EX3DV4	SN: 7349	15-Jun-16 (No. EX3-7349_Jun16)	Jun-17
D4E4	SN: 601	30-Dec-15 (No. D4E4-601_Dec15)	Dec-16
Secondary Standards	ID #	Check Date (in house)	Scheduled Check
Power meter EPM-442A	SN: GB37480704	07-Oct-15 (No. 217-02222)	In house check: Oct-16
Power sensor HP 8481A	SN: US37292783	07-Oct-15 (No. 217-02222)	In house check: Oct-16
Power sensor HP 8481A	SN: MY41092317	07-Oct-15 (No. 217-02223)	In house check: Oct-16
RF generator R&S SMT-06	SN: 100972	15-Jun-15 (in house check Jun-15)	In house check: Oct-16
Network Analyzer HP 8753E	SN: US37390585	18-Oct-01 (in house check Oct-15)	In house check: Oct-16

	Name	Function	Signature
Calibrated by:	Leif Klysner	Laboratory Technician	
Approved by:	Katja Pokovic	Technical Manager	

Issued: September 26, 2016

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Multilateral Agreement for the recognition of calibration certificates

Accreditation No.: **SCS 0108**

Glossary:

TSL tissue simulating liquid
ConvF sensitivity in TSL / NORM x,y,z
N/A not applicable or not measured

Calibration is Performed According to the Following Standards:

- IEEE Std 1528-2013, "IEEE Recommended Practice for Determining the Peak Spatial-Averaged Specific Absorption Rate (SAR) in the Human Head from Wireless Communications Devices: Measurement Techniques", June 2013
- IEC 62209-1, "Procedure to measure the Specific Absorption Rate (SAR) for hand-held devices used in close proximity to the ear (frequency range of 300 MHz to 3 GHz)", February 2005
- IEC 62209-2, "Procedure to determine the Specific Absorption Rate (SAR) for wireless communication devices used in close proximity to the human body (frequency range of 30 MHz to 6 GHz)", March 2010
- KDB 865664, "SAR Measurement Requirements for 100 MHz to 6 GHz"

Additional Documentation:

- DASY4/5 System Handbook

Methods Applied and Interpretation of Parameters:

- Measurement Conditions:** Further details are available from the Validation Report at the end of the certificate. All figures stated in the certificate are valid at the frequency indicated.
- Antenna Parameters with TSL:** The dipole is mounted with the spacer to position its feed point exactly below the center marking of the flat phantom section, with the arms oriented parallel to the body axis.
- Feed Point Impedance and Return Loss:** These parameters are measured with the dipole positioned under the liquid filled phantom. The impedance stated is transformed from the measurement at the SMA connector to the feed point. The Return Loss ensures low reflected power. No uncertainty required.
- Electrical Delay:** One-way delay between the SMA connector and the antenna feed point. No uncertainty required.
- SAR measured:** SAR measured at the stated antenna input power.
- SAR normalized:** SAR as measured, normalized to an input power of 1 W at the antenna connector.
- SAR for nominal TSL parameters:** The measured TSL parameters are used to calculate the nominal SAR result.

The reported uncertainty of measurement is stated as the standard uncertainty of measurement multiplied by the coverage factor $k=2$, which for a normal distribution corresponds to a coverage probability of approximately 95%.

Measurement Conditions

DASY system configuration, as far as not given on page 1.

DASY Version	DASY5	V52.8.8
Extrapolation	Advanced Extrapolation	
Phantom	Modular Flat Phantom	
Distance Dipole Center - TSL	10 mm	with Spacer
Zoom Scan Resolution	dx, dy, dz = 5 mm	
Frequency	2450 MHz \pm 1 MHz	

Head TSL parameters

The following parameters and calculations were applied.

	Temperature	Permittivity	Conductivity
Nominal Head TSL parameters	22.0 °C	39.2	1.80 mho/m
Measured Head TSL parameters	(22.0 \pm 0.2) °C	37.9 \pm 6 %	1.88 mho/m \pm 6 %
Head TSL temperature change during test	< 0.5 °C	----	----

SAR result with Head TSL

SAR averaged over 1 cm ³ (1 g) of Head TSL	Condition	
SAR measured	250 mW input power	13.3 W/kg
SAR for nominal Head TSL parameters	normalized to 1W	51.7 W/kg \pm 17.0 % (k=2)

SAR averaged over 10 cm ³ (10 g) of Head TSL	condition	
SAR measured	250 mW input power	6.19 W/kg
SAR for nominal Head TSL parameters	normalized to 1W	24.4 W/kg \pm 16.5 % (k=2)

Body TSL parameters

The following parameters and calculations were applied.

	Temperature	Permittivity	Conductivity
Nominal Body TSL parameters	22.0 °C	52.7	1.95 mho/m
Measured Body TSL parameters	(22.0 \pm 0.2) °C	51.6 \pm 6 %	2.04 mho/m \pm 6 %
Body TSL temperature change during test	< 0.5 °C	----	----

SAR result with Body TSL

SAR averaged over 1 cm ³ (1 g) of Body TSL	Condition	
SAR measured	250 mW input power	12.9 W/kg
SAR for nominal Body TSL parameters	normalized to 1W	50.3 W/kg \pm 17.0 % (k=2)

SAR averaged over 10 cm ³ (10 g) of Body TSL	condition	
SAR measured	250 mW input power	6.02 W/kg
SAR for nominal Body TSL parameters	normalized to 1W	23.7 W/kg \pm 16.5 % (k=2)

Appendix (Additional assessments outside the scope of SCS 0108)**Antenna Parameters with Head TSL**

Impedance, transformed to feed point	52.1 Ω + 3.1 j Ω
Return Loss	- 28.7 dB

Antenna Parameters with Body TSL

Impedance, transformed to feed point	48.3 Ω + 5.1 j Ω
Return Loss	- 25.3 dB

General Antenna Parameters and Design

Electrical Delay (one direction)	1.157 ns
----------------------------------	----------

After long term use with 100W radiated power, only a slight warming of the dipole near the feedpoint can be measured.

The dipole is made of standard semirigid coaxial cable. The center conductor of the feeding line is directly connected to the second arm of the dipole. The antenna is therefore short-circuited for DC-signals. On some of the dipoles, small end caps are added to the dipole arms in order to improve matching when loaded according to the position as explained in the "Measurement Conditions" paragraph. The SAR data are not affected by this change. The overall dipole length is still according to the Standard.

No excessive force must be applied to the dipole arms, because they might bend or the soldered connections near the feedpoint may be damaged.

Additional EUT Data

Manufactured by	SPEAG
Manufactured on	April 23, 2010

DASY5 Validation Report for Head TSL

Date: 23.09.2016

Test Laboratory: SPEAG, Zurich, Switzerland

DUT: Dipole 2450 MHz; Type: D2450V2; Serial: D2450V2 - SN:857

Communication System: UID 0 - CW; Frequency: 2450 MHz

Medium parameters used: $f = 2450$ MHz; $\sigma = 1.88$ S/m; $\epsilon_r = 37.9$; $\rho = 1000$ kg/m³

Phantom section: Flat Section

Measurement Standard: DASY5 (IEEE/IEC/ANSI C63.19-2011)

DASY52 Configuration:

- Probe: EX3DV4 - SN7349; ConvF(7.72, 7.72, 7.72); Calibrated: 15.06.2016;
- Sensor-Surface: 1.4mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn601; Calibrated: 30.12.2015
- Phantom: Flat Phantom 5.0 (front); Type: QD000P50AA; Serial: 1001
- DASY52 52.8.8(1258); SEMCAD X 14.6.10(7372)

Dipole Calibration for Head Tissue/Pin=250 mW, d=10mm/Zoom Scan (7x7x7)/Cube 0:

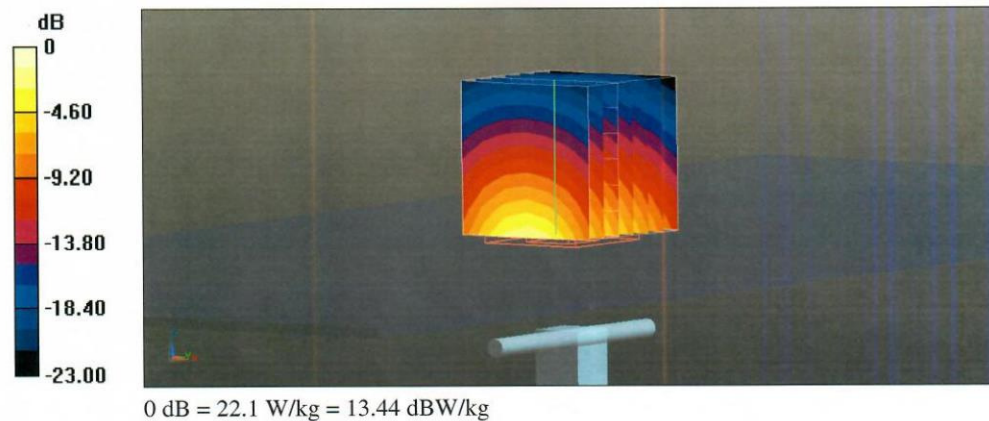
Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 113.0 V/m; Power Drift = -0.06 dB

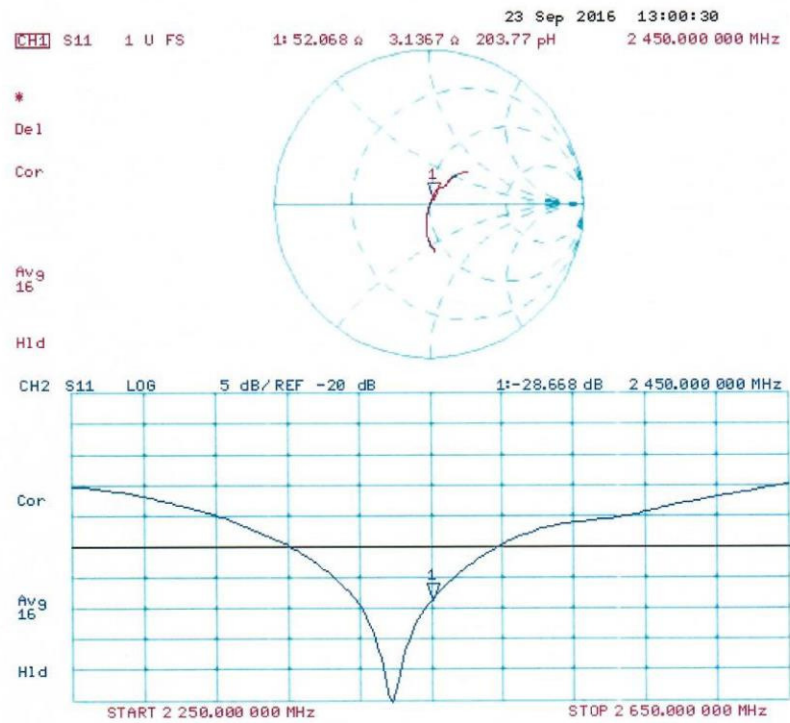
Peak SAR (extrapolated) = 27.2 W/kg

SAR(1 g) = 13.3 W/kg; SAR(10 g) = 6.19 W/kg

Maximum value of SAR (measured) = 22.1 W/kg



Impedance Measurement Plot for Head TSL



DASY5 Validation Report for Body TSL

Date: 23.09.2016

Test Laboratory: SPEAG, Zurich, Switzerland

DUT: Dipole 2450 MHz; Type: D2450V2; Serial: D2450V2 - SN:857

Communication System: UID 0 - CW; Frequency: 2450 MHz

Medium parameters used: $f = 2450$ MHz; $\sigma = 2.04$ S/m; $\epsilon_r = 51.6$; $\rho = 1000$ kg/m³

Phantom section: Flat Section

Measurement Standard: DASY5 (IEEE/IEC/ANSI C63.19-2011)

DASY52 Configuration:

- Probe: EX3DV4 - SN7349; ConvF(7.79, 7.79, 7.79); Calibrated: 15.06.2016;
- Sensor-Surface: 1.4mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn601; Calibrated: 30.12.2015
- Phantom: Flat Phantom 5.0 (back); Type: QD000P50AA; Serial: 1002
- DASY52 52.8.8(1258); SEMCAD X 14.6.10(7372)

Dipole Calibration for Body Tissue/Pin=250 mW, d=10mm/Zoom Scan (7x7x7)/Cube 0:

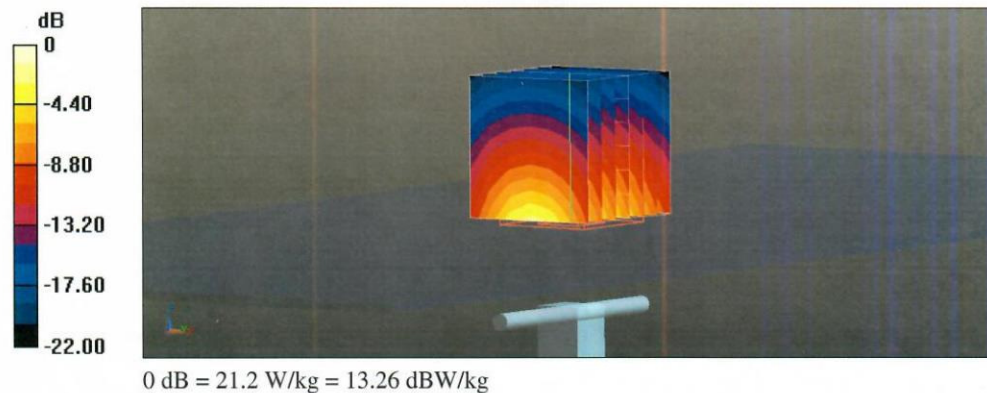
Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 106.2 V/m; Power Drift = -0.02 dB

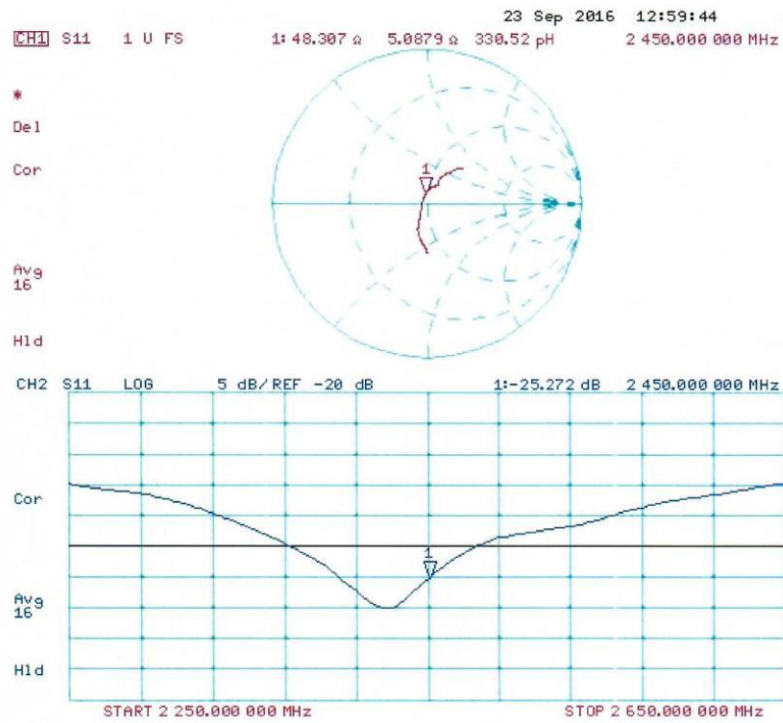
Peak SAR (extrapolated) = 25.8 W/kg

SAR(1 g) = 12.9 W/kg; SAR(10 g) = 6.02 W/kg

Maximum value of SAR (measured) = 21.2 W/kg



Impedance Measurement Plot for Body TSL





ANNEX D PROBE CALIBRATION CERTIFICATE

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Accreditation No.: **SCS 0108**

Client **MET Laboratories**

Certificate No: **EX3-3722_Sep16**

CALIBRATION CERTIFICATE

Object **EX3DV4 - SN:3722**

Calibration procedure(s) **QA CAL-01.v9, QA CAL-14.v4, QA CAL-23.v5, QA CAL-25.v6**
 Calibration procedure for dosimetric E-field probes


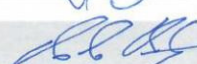
Calibration date: **September 23, 2016**

This calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI).
 The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

All calibrations have been conducted in the closed laboratory facility: environment temperature (22 ± 3)°C and humidity < 70%.

Calibration Equipment used (M&TE critical for calibration)

Primary Standards	ID	Cal Date (Certificate No.)	Scheduled Calibration
Power meter NRP	SN: 104778	06-Apr-16 (No. 217-02288/02289)	Apr-17
Power sensor NRP-Z91	SN: 103244	06-Apr-16 (No. 217-02288)	Apr-17
Power sensor NRP-Z91	SN: 103245	06-Apr-16 (No. 217-02289)	Apr-17
Reference 20 dB Attenuator	SN: S5277 (20x)	05-Apr-16 (No. 217-02293)	Apr-17
Reference Probe ES3DV2	SN: 3013	31-Dec-15 (No. ES3-3013_Dec15)	Dec-16
DAE4	SN: 660	23-Dec-15 (No. DAE4-660_Dec15)	Dec-16
Secondary Standards	ID	Check Date (in house)	Scheduled Check
Power meter E4419B	SN: GB41293874	06-Apr-16 (in house check Jun-16)	In house check: Jun-18
Power sensor E4412A	SN: MY41498087	06-Apr-16 (in house check Jun-16)	In house check: Jun-18
Power sensor E4412A	SN: 000110210	06-Apr-16 (in house check Jun-16)	In house check: Jun-18
RF generator HP 8648C	SN: US3642U01700	04-Aug-99 (in house check Jun-16)	In house check: Jun-18
Network Analyzer HP 8753E	SN: US37390585	18-Oct-01 (in house check Oct-15)	In house check: Oct-16

Calibrated by:	Name Claudio Leubler	Function Laboratory Technician	Signature 
Approved by:	Katja Pokovic	Technical Manager	
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Certificate No: EX3-3722_Sep16

Page 1 of 11

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Glossary:

TSL	tissue simulating liquid
NORM _{x,y,z}	sensitivity in free space
ConvF	sensitivity in TSL / NORM _{x,y,z}
DCP	diode compression point
CF	crest factor (1/duty_cycle) of the RF signal
A, B, C, D	modulation dependent linearization parameters
Polarization ϕ	ϕ rotation around probe axis
Polarization ϑ	ϑ rotation around an axis that is in the plane normal to probe axis (at measurement center), i.e., $\vartheta = 0$ is normal to probe axis
Connector Angle	information used in DASY system to align probe sensor X to the robot coordinate system

Calibration is Performed According to the Following Standards:

- IEEE Std 1528-2013, "IEEE Recommended Practice for Determining the Peak Spatial-Averaged Specific Absorption Rate (SAR) in the Human Head from Wireless Communications Devices: Measurement Techniques", June 2013
- IEC 62209-1, "Procedure to measure the Specific Absorption Rate (SAR) for hand-held devices used in close proximity to the ear (frequency range of 300 MHz to 3 GHz)", February 2005
- IEC 62209-2, "Procedure to determine the Specific Absorption Rate (SAR) for wireless communication devices used in close proximity to the human body (frequency range of 30 MHz to 6 GHz)", March 2010
- KDB 865664, "SAR Measurement Requirements for 100 MHz to 6 GHz"

Methods Applied and Interpretation of Parameters:

- NORM_{x,y,z}**: Assessed for E-field polarization $\vartheta = 0$ ($f \leq 900$ MHz in TEM-cell; $f > 1800$ MHz: R22 waveguide). NORM_{x,y,z} are only intermediate values, i.e., the uncertainties of NORM_{x,y,z} does not affect the E^2 -field uncertainty inside TSL (see below ConvF).
- NORM(f)_{x,y,z}** = NORM_{x,y,z} * frequency_response (see Frequency Response Chart). This linearization is implemented in DASY4 software versions later than 4.2. The uncertainty of the frequency response is included in the stated uncertainty of ConvF.
- DCP_{x,y,z}**: DCP are numerical linearization parameters assessed based on the data of power sweep with CW signal (no uncertainty required). DCP does not depend on frequency nor media.
- PAR**: PAR is the Peak to Average Ratio that is not calibrated but determined based on the signal characteristics
- A_{x,y,z}; B_{x,y,z}; C_{x,y,z}; D_{x,y,z}; VR_{x,y,z}**: A, B, C, D are numerical linearization parameters assessed based on the data of power sweep for specific modulation signal. The parameters do not depend on frequency nor media. VR is the maximum calibration range expressed in RMS voltage across the diode.
- ConvF and Boundary Effect Parameters**: Assessed in flat phantom using E-field (or Temperature Transfer Standard for $f \leq 800$ MHz) and inside waveguide using analytical field distributions based on power measurements for $f > 800$ MHz. The same setups are used for assessment of the parameters applied for boundary compensation (alpha, depth) of which typical uncertainty values are given. These parameters are used in DASY4 software to improve probe accuracy close to the boundary. The sensitivity in TSL corresponds to NORM_{x,y,z} * ConvF whereby the uncertainty corresponds to that given for ConvF. A frequency dependent ConvF is used in DASY version 4.4 and higher which allows extending the validity from ± 50 MHz to ± 100 MHz.
- Spherical isotropy (3D deviation from isotropy)**: in a field of low gradients realized using a flat phantom exposed by a patch antenna.
- Sensor Offset**: The sensor offset corresponds to the offset of virtual measurement center from the probe tip (on probe axis). No tolerance required.
- Connector Angle**: The angle is assessed using the information gained by determining the NORM_x (no uncertainty required).



EX3DV4 – SN:3722

September 23, 2016

Probe EX3DV4

SN:3722

Manufactured: August 14, 2009
Calibrated: September 23, 2016

Calibrated for DASY/EASY Systems
(Note: non-compatible with DASY2 system!)

EX3DV4- SN:3722

September 23, 2016

DASY/EASY - Parameters of Probe: EX3DV4 - SN:3722

Basic Calibration Parameters

	Sensor X	Sensor Y	Sensor Z	Unc (k=2)
Norm ($\mu\text{V}/(\text{V/m})^2$) ^A	0.52	0.49	0.56	± 10.1 %
DCP (mV) ^B	102.3	99.1	101.2	

Modulation Calibration Parameters

UID	Communication System Name		A dB	B dB $\sqrt{\mu\text{V}}$	C	D dB	VR mV	Unc ^E (k=2)
0	CW	X	0.0	0.0	1.0	0.00	194.4	±2.7 %
		Y	0.0	0.0	1.0		189.0	
		Z	0.0	0.0	1.0		195.0	

The reported uncertainty of measurement is stated as the standard uncertainty of measurement multiplied by the coverage factor k=2, which for a normal distribution corresponds to a coverage probability of approximately 95%.

^A The uncertainties of Norm X,Y,Z do not affect the E²-field uncertainty inside TSL (see Pages 5 and 6).

^B Numerical linearization parameter: uncertainty not required.

^E Uncertainty is determined using the max. deviation from linear response applying rectangular distribution and is expressed for the square of the field value.

EX3DV4- SN:3722

September 23, 2016

DASY/EASY - Parameters of Probe: EX3DV4 - SN:3722

Calibration Parameter Determined in Head Tissue Simulating Media

f (MHz) ^C	Relative Permittivity ^F	Conductivity (S/m) ^F	ConvF X	ConvF Y	ConvF Z	Alpha ^G	Depth ^G (mm)	Unc (k=2)
750	41.9	0.89	9.67	9.67	9.67	0.54	0.80	± 12.0 %
900	41.5	0.97	9.08	9.08	9.08	0.36	0.99	± 12.0 %
1810	40.0	1.40	7.71	7.71	7.71	0.37	0.80	± 12.0 %
2000	40.0	1.40	7.65	7.65	7.65	0.35	0.80	± 12.0 %
2450	39.2	1.80	6.90	6.90	6.90	0.37	0.80	± 12.0 %
5200	36.0	4.66	5.08	5.08	5.08	0.35	1.80	± 13.1 %
5300	35.9	4.76	4.78	4.78	4.78	0.40	1.80	± 13.1 %
5500	35.6	4.96	4.62	4.62	4.62	0.45	1.80	± 13.1 %
5800	35.3	5.27	4.34	4.34	4.34	0.50	1.80	± 13.1 %

^C Frequency validity above 300 MHz of ± 100 MHz only applies for DASY v4.4 and higher (see Page 2), else it is restricted to ± 50 MHz. The uncertainty is the RSS of the ConvF uncertainty at calibration frequency and the uncertainty for the indicated frequency band. Frequency validity below 300 MHz is ± 10, 25, 40, 50 and 70 MHz for ConvF assessments at 30, 64, 128, 150 and 220 MHz respectively. Above 5 GHz frequency validity can be extended to ± 110 MHz.

^F At frequencies below 3 GHz, the validity of tissue parameters (ϵ and σ) can be relaxed to ± 10% if liquid compensation formula is applied to measured SAR values. At frequencies above 3 GHz, the validity of tissue parameters (ϵ and σ) is restricted to ± 5%. The uncertainty is the RSS of the ConvF uncertainty for indicated target tissue parameters.

^G Alpha/Depth are determined during calibration. SPEAG warrants that the remaining deviation due to the boundary effect after compensation is always less than ± 1% for frequencies below 3 GHz and below ± 2% for frequencies between 3-6 GHz at any distance larger than half the probe tip diameter from the boundary.

EX3DV4- SN:3722

September 23, 2016

DASY/EASY - Parameters of Probe: EX3DV4 - SN:3722

Calibration Parameter Determined in Body Tissue Simulating Media

f (MHz) ^C	Relative Permittivity ^F	Conductivity (S/m) ^F	ConvF X	ConvF Y	ConvF Z	Alpha ^G	Depth ^G (mm)	Unc (k=2)
750	55.5	0.96	8.95	8.95	8.95	0.45	0.80	± 12.0 %
900	55.0	1.05	8.99	8.99	8.99	0.49	0.80	± 12.0 %
1810	53.3	1.52	7.45	7.45	7.45	0.36	0.85	± 12.0 %
2000	53.3	1.52	7.51	7.51	7.51	0.41	0.80	± 12.0 %
2450	52.7	1.95	6.97	6.97	6.97	0.38	0.90	± 12.0 %
5200	49.0	5.30	4.34	4.34	4.34	0.45	1.90	± 13.1 %
5300	48.9	5.42	4.09	4.09	4.09	0.50	1.90	± 13.1 %
5500	48.6	5.65	3.75	3.75	3.75	0.55	1.90	± 13.1 %
5800	48.2	6.00	3.70	3.70	3.70	0.60	1.90	± 13.1 %

^C Frequency validity above 300 MHz of ± 100 MHz only applies for DASY v4.4 and higher (see Page 2), else it is restricted to ± 50 MHz. The uncertainty is the RSS of the ConvF uncertainty at calibration frequency and the uncertainty for the indicated frequency band. Frequency validity below 300 MHz is ± 10, 25, 40, 50 and 70 MHz for ConvF assessments at 30, 64, 128, 150 and 220 MHz respectively. Above 5 GHz frequency validity can be extended to ± 110 MHz.

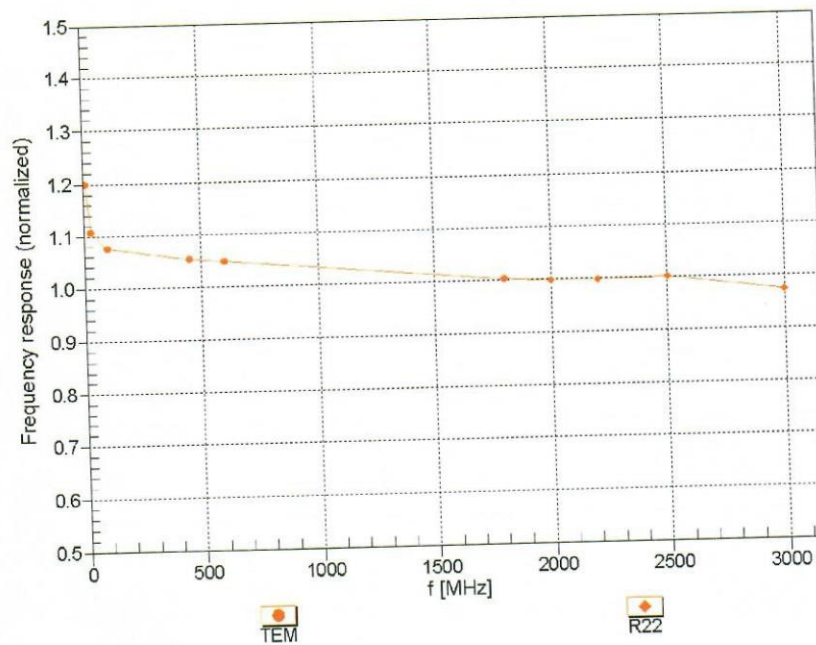
^F At frequencies below 3 GHz, the validity of tissue parameters (ϵ and σ) can be relaxed to ± 10% if liquid compensation formula is applied to measured SAR values. At frequencies above 3 GHz, the validity of tissue parameters (ϵ and σ) is restricted to ± 5%. The uncertainty is the RSS of the ConvF uncertainty for indicated target tissue parameters.

^G Alpha/Depth are determined during calibration. SPEAG warrants that the remaining deviation due to the boundary effect after compensation is always less than ± 1% for frequencies below 3 GHz and below ± 2% for frequencies between 3-6 GHz at any distance larger than half the probe tip diameter from the boundary.

EX3DV4- SN:3722

September 23, 2016

Frequency Response of E-Field (TEM-Cell:ifi110 EXX, Waveguide: R22)

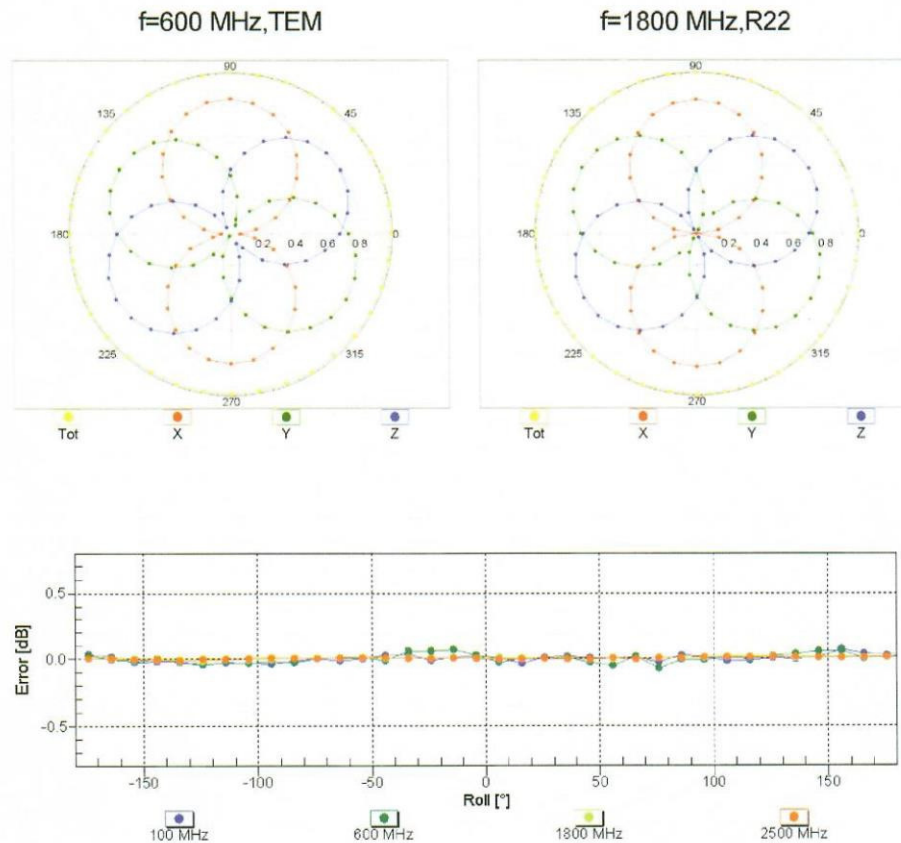


Uncertainty of Frequency Response of E-field: $\pm 6.3\%$ ($k=2$)

EX3DV4- SN:3722

September 23, 2016

Receiving Pattern (ϕ), $\theta = 0^\circ$

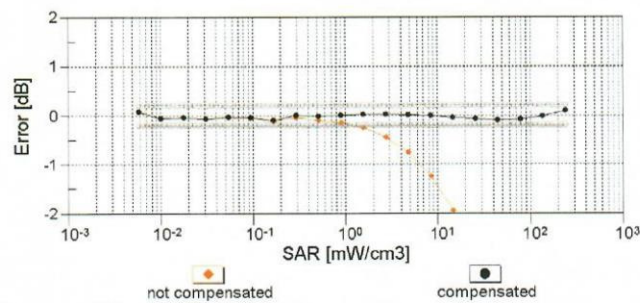
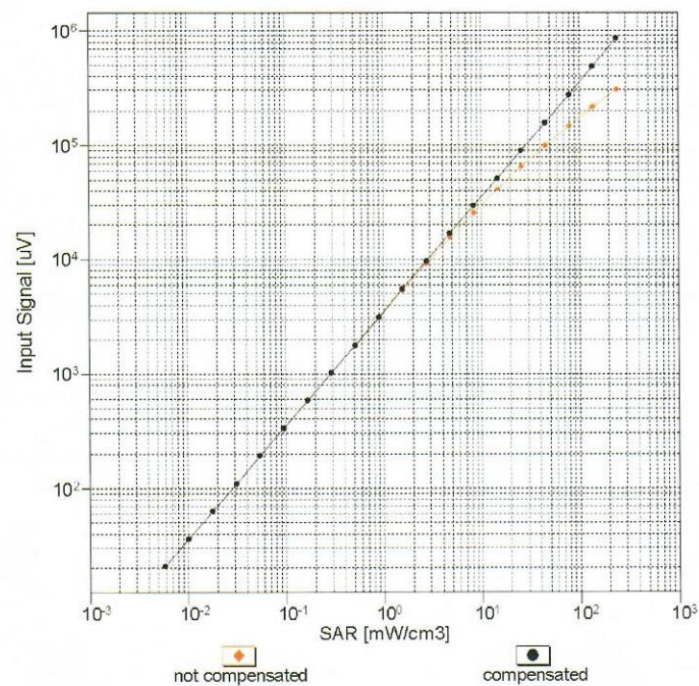


Uncertainty of Axial Isotropy Assessment: $\pm 0.5\%$ ($k=2$)

EX3DV4- SN:3722

September 23, 2016

Dynamic Range $f(\text{SAR}_{\text{head}})$ (TEM cell , $f_{\text{eval}} = 1900 \text{ MHz}$)

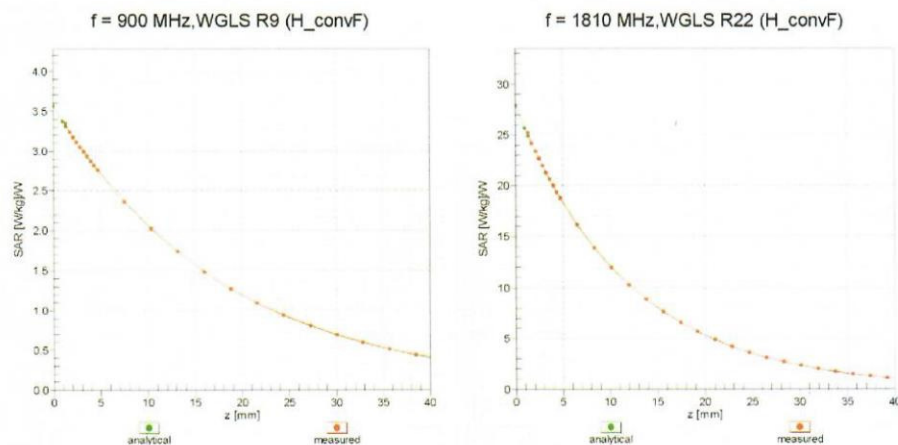


Uncertainty of Linearity Assessment: $\pm 0.6\%$ ($k=2$)

EX3DV4- SN:3722

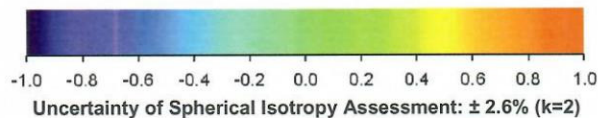
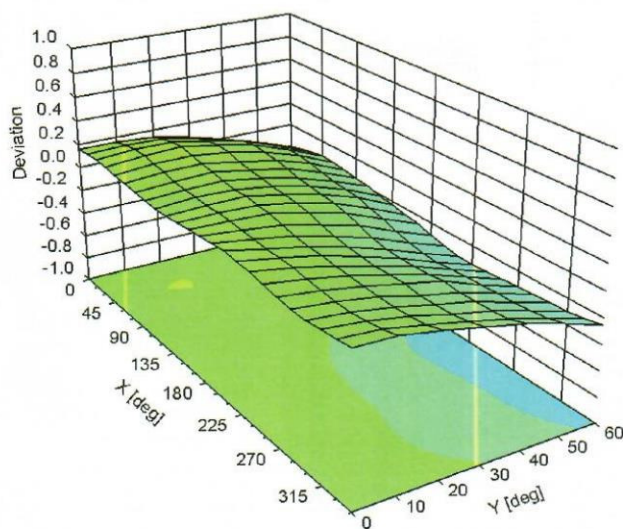
September 23, 2016

Conversion Factor Assessment



Deviation from Isotropy in Liquid

Error (ϕ , θ), f = 900 MHz





EX3DV4- SN:3722

September 23, 2016

DASY/EASY - Parameters of Probe: EX3DV4 - SN:3722**Other Probe Parameters**

Sensor Arrangement	Triangular
Connector Angle (°)	125.9
Mechanical Surface Detection Mode	enabled
Optical Surface Detection Mode	disabled
Probe Overall Length	337 mm
Probe Body Diameter	10 mm
Tip Length	9 mm
Tip Diameter	2.5 mm
Probe Tip to Sensor X Calibration Point	1 mm
Probe Tip to Sensor Y Calibration Point	1 mm
Probe Tip to Sensor Z Calibration Point	1 mm
Recommended Measurement Distance from Surface	1.4 mm



ANNEX E DAE CALIBRATION CERTIFICATE

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Accreditation No.: **SCS 0108**

Client **MET Laboratories**

Certificate No: **DAE3-584_Sep16**

CALIBRATION CERTIFICATE

Object **DAE3 - SD 000 D03 AA - SN: 584**

Calibration procedure(s) **QA CAL-06.v29**
Calibration procedure for the data acquisition electronics (DAE)



Calibration date: **September 21, 2016**

This calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI).
The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

All calibrations have been conducted in the closed laboratory facility: environment temperature $(22 \pm 3)^{\circ}\text{C}$ and humidity $< 70\%$.

Calibration Equipment used (M&TE critical for calibration)

Primary Standards	ID #	Cal Date (Certificate No.)	Scheduled Calibration
Keithley Multimeter Type 2001	SN: 0810278	09-Sep-16 (No:19065)	Sep-17
Secondary Standards	ID #	Check Date (in house)	Scheduled Check
Auto DAE Calibration Unit	SE UWS 053 AA 1001	05-Jan-16 (in house check)	In house check: Jan-17
Calibrator Box V2.1	SE UMS 006 AA 1002	05-Jan-16 (in house check)	In house check: Jan-17

Calibrated by:	Name Eric Hainfeld	Function Technician	Signature 
Approved by:	Fin Bornholt	Deputy Technical Manager	

Issued: September 21, 2016

This calibration certificate shall not be reproduced except in full without written approval of the laboratory.

Calibration Laboratory of
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S Schweizerischer Kalibrierdienst
C Service suisse d'étalonnage
S Servizio svizzero di taratura
S Swiss Calibration Service

Accredited by the Swiss Accreditation Service (SAS)
The Swiss Accreditation Service is one of the signatories to the EA
Multilateral Agreement for the recognition of calibration certificates

Accreditation No.: **SCS 0108**

Glossary

DAE data acquisition electronics
Connector angle information used in DASY system to align probe sensor X to the robot coordinate system.

Methods Applied and Interpretation of Parameters

- *DC Voltage Measurement:* Calibration Factor assessed for use in DASY system by comparison with a calibrated instrument traceable to national standards. The figure given corresponds to the full scale range of the voltmeter in the respective range.
- *Connector angle:* The angle of the connector is assessed measuring the angle mechanically by a tool inserted. Uncertainty is not required.
- The following parameters as documented in the Appendix contain technical information as a result from the performance test and require no uncertainty.
 - *DC Voltage Measurement Linearity:* Verification of the Linearity at +10% and -10% of the nominal calibration voltage. Influence of offset voltage is included in this measurement.
 - *Common mode sensitivity:* Influence of a positive or negative common mode voltage on the differential measurement.
 - *Channel separation:* Influence of a voltage on the neighbor channels not subject to an input voltage.
 - *AD Converter Values with inputs shorted:* Values on the internal AD converter corresponding to zero input voltage
 - *Input Offset Measurement:* Output voltage and statistical results over a large number of zero voltage measurements.
 - *Input Offset Current:* Typical value for information; Maximum channel input offset current, not considering the input resistance.
 - *Input resistance:* Typical value for information: DAE input resistance at the connector, during internal auto-zeroing and during measurement.
 - *Low Battery Alarm Voltage:* Typical value for information. Below this voltage, a battery alarm signal is generated.
 - *Power consumption:* Typical value for information. Supply currents in various operating modes.

DC Voltage Measurement

A/D - Converter Resolution nominal

High Range: 1LSB = 6.1 μ V, full range = -100...+300 mV

Low Range: 1LSB = 61nV, full range = -1.....+3mV

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

Calibration Factors	X	Y	Z
High Range	404.497 \pm 0.02% (k=2)	404.684 \pm 0.02% (k=2)	404.109 \pm 0.02% (k=2)
Low Range	3.92959 \pm 1.50% (k=2)	3.91818 \pm 1.50% (k=2)	3.94514 \pm 1.50% (k=2)

Connector Angle

Connector Angle to be used in DASY system	142.0 $^{\circ}$ \pm 1 $^{\circ}$
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Appendix (Additional assessments outside the scope of SCS0108)

1. DC Voltage Linearity

High Range	Reading (μV)	Difference (μV)	Error (%)
Channel X + Input	199989.98	-6.78	-0.00
Channel X + Input	20002.67	1.05	0.01
Channel X - Input	-20001.03	-0.13	0.00
Channel Y + Input	199994.65	-2.21	-0.00
Channel Y + Input	20003.08	1.53	0.01
Channel Y - Input	-19995.08	5.84	-0.03
Channel Z + Input	199997.75	0.63	0.00
Channel Z + Input	19997.79	-3.79	-0.02
Channel Z - Input	-20002.74	-1.77	0.01

Low Range	Reading (μV)	Difference (μV)	Error (%)
Channel X + Input	2001.49	0.15	0.01
Channel X + Input	201.90	0.26	0.13
Channel X - Input	-198.61	-0.53	0.27
Channel Y + Input	2000.93	-0.41	-0.02
Channel Y + Input	201.53	-0.11	-0.05
Channel Y - Input	-199.00	-0.90	0.46
Channel Z + Input	2000.92	-0.28	-0.01
Channel Z + Input	200.91	-0.65	-0.32
Channel Z - Input	-199.60	-1.43	0.72

2. Common mode sensitivity

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

	Common mode Input Voltage (mV)	High Range Average Reading (μV)	Low Range Average Reading (μV)
Channel X	200	3.25	1.52
	- 200	-1.08	-2.90
Channel Y	200	2.80	2.69
	- 200	-3.39	-3.72
Channel Z	200	-6.34	-6.43
	- 200	4.51	4.34

3. Channel separation

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

	Input Voltage (mV)	Channel X (μV)	Channel Y (μV)	Channel Z (μV)
Channel X	200	-	-0.44	-3.66
Channel Y	200	7.35	-	0.04
Channel Z	200	6.60	5.86	-

4. AD-Converter Values with inputs shorted

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

	High Range (LSB)	Low Range (LSB)
Channel X	16111	16149
Channel Y	16215	16800
Channel Z	16296	17501

5. Input Offset Measurement

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

Input 10M Ω

	Average (μ V)	min. Offset (μ V)	max. Offset (μ V)	Std. Deviation (μ V)
Channel X	1.36	-0.11	3.26	0.52
Channel Y	-0.30	-1.72	1.39	0.51
Channel Z	0.24	-1.16	1.64	0.46

6. Input Offset Current

Nominal Input circuitry offset current on all channels: <25fA

7. Input Resistance (Typical values for information)

	Zeroing (kOhm)	Measuring (MOhm)
Channel X	200	200
Channel Y	200	200
Channel Z	200	200

8. Low Battery Alarm Voltage (Typical values for information)

Typical values	Alarm Level (VDC)
Supply (+ Vcc)	+7.9
Supply (- Vcc)	-7.6

9. Power Consumption (Typical values for information)

Typical values	Switched off (mA)	Stand by (mA)	Transmitting (mA)
Supply (+ Vcc)	+0.01	+6	+14
Supply (- Vcc)	-0.01	-8	-9



ANNEX F 2.4 GHz MEASURED FLUID DIELECTRIC PARAMETERS

Viavi Table PC

Body Simulating Liquid Parameters for 2450MHz

November 30, 2016 04:21 PM

Frequency(Hz)	e'	e''
2400000000	51.0211	14.5133
2402000000	51.0086	14.5076
2404000000	50.9871	14.5115
2406000000	50.9795	14.5102
2408000000	50.9639	14.5214
2410000000	50.9455	14.4991
2412000000	50.9394	14.5099
2414000000	50.9147	14.5213
2416000000	50.8837	14.5115
2418000000	50.8639	14.5273
2420000000	50.8375	14.5378
2422000000	50.828	14.5264
2424000000	50.7964	14.5435
2426000000	50.768	14.5485
2428000000	50.75	14.5558
2430000000	50.7091	14.5687
2432000000	50.7106	14.5735
2434000000	50.6799	14.5841
2436000000	50.6513	14.6002
2438000000	50.6354	14.6084
2440000000	50.6148	14.6122
2442000000	50.5951	14.614
2444000000	50.5908	14.6274
2446000000	50.5615	14.6454
2448000000	50.5468	14.6517
2450000000	50.5424	14.6604
2452000000	50.5343	14.697
2454000000	50.5166	14.6951
2456000000	50.5093	14.7205
2458000000	50.4949	14.7314
2460000000	50.4948	14.751
2462000000	50.503	14.7676



2464000000	50.4969	14.7958
2466000000	50.4955	14.8034
2468000000	50.489	14.8176
2470000000	50.494	14.8416
2472000000	50.4868	14.8624
2474000000	50.4815	14.8793
2476000000	50.4808	14.896
2478000000	50.4764	14.911
2480000000	50.4911	14.9392
2482000000	50.477	14.9407
2484000000	50.486	14.9615
2486000000	50.4877	14.9633
2488000000	50.4927	14.9732
2490000000	50.504	14.979
2492000000	50.5004	14.9828
2494000000	50.5004	14.9836
2496000000	50.5154	14.9864
2498000000	50.5229	14.9859
2500000000	50.531	14.9787



ANNEX G PHANTOM CERTIFICATE OF CONFORMITY

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Certificate of conformity / First Article Inspection

Item	SAM Twin Phantom V4.0
Type No	QD 000 P40 C
Series No	TP-1150 and higher
Manufacturer / Origin	Untersee Composites Hauptstr. 69 CH-8559 Fruthwilen Switzerland

Tests

The series production process used allows the limitation to test of first articles.
Complete tests were made on the pre-series Type No. QD 000 P40 AA, Serial No. TP-1001 and on the series first article Type No. QD 000 P40 BA, Serial No. TP-1006. Certain parameters have been retested using further series units (called samples).

Test	Requirement	Details	Units tested
Shape	Compliance with the geometry according to the CAD model.	IT'IS CAD File (*)	First article, Samples
Material thickness	Compliant with the requirements according to the standards	2mm +/- 0.2mm in specific areas; 6mm +/- 0.2mm at ERP	First article, Samples
Material parameters	Dielectric parameters for required frequencies	200 MHz – 3 GHz Relative permittivity < 5 Loss tangent < 0.05.	Material sample TP 104-5
Material resistivity	The material has been tested to be compatible with the liquids defined in the standards if handled and cleaned according to the instructions	DEGMBE based simulating liquids	Pre-series, First article, Samples

Standards

- [1] CENELEC EN 50361
- [2] IEEE Std 1528-200x Draft CD 1.1 (Dec 02)
- [3] IEC 62209/CD (Nov 02)
- (*) The IT'IS CAD file is derived from [2] and is also within the tolerance requirements of the shapes of [1] and [3].

Conformity

Based on the sample tests above, we certify that this item is in compliance with the uncertainty requirements of SAR measurements specified in standard [1] and draft standards [2] and [3].

Date 7.8.2003

Signature / Stamp

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