REPORT No. : SZ14080041S01

FCC SAR TEST REPORT

APPLICANT	:	SZ DJI TECHNOLOGY CO., LTD
PRODUCT NAME	:	Remote Control
MODEL NAME	:	NDJ6
TRADE NAME	:	DJI
BRAND NAME	:	DJI
FCC ID	:	SS3-WM300U24G
STANDARD(S)	:	47CFR 2.1093 IEEE 1528-2013
ISSUE DATE	:	2014-10-11

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SHENZHEN MORLAB COMMUNICATIONS TECHNOLOGY Co., Ltd.

DIRECTORY

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Change History		
Issue	Date	Reason for change
1.0	2014-10-11	First edition

TEST REPORT DECLARATION

Applicant	SZ DJI TECHNOLOGY CO., LTD	
Applicant Address	17th floor, West Wing, Skyworth Semiconductor Design Building NO.18 Gaoxin South 4th Ave, Nanshan District, Shenzhen, China	
Manufacturer	SZ DJI TECHNOLOGY CO., LTD	
Manufacturer Address	17th floor, West Wing, Skyworth Semiconductor Design Building NO.18 Gaoxin South 4th Ave, Nanshan District, Shenzhen, China	
Product Name	Remote Control	
Model Name	NDJ6	
Brand Name	DJI	
HW Version	1.01	
SW Version	1.0.1.14	
Test Standards	47CFR 2.1093; IEEE 1528-2013	
Test Date	2014-10-10	
The Highest Reported SAR(W/kg)	Hand	0.114W/kg(10g)
	Body	0.095W/kg(1g)

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1. TECHNICAL INFORMATION

Note: the Following data is based on the information by the applicant.

1.1 Identification of Applicant

Company Name:	SZ DJI TECHNOLOGY CO., LTD
Address:	17th floor, West Wing, Skyworth Semiconductor Design Building NO.18 Gaoxin South 4th Ave, Nanshan District, Shenzhen, China

1.2 Identification of Manufacturer

Company Name:	SZ DJI TECHNOLOGY CO., LTD
Address:	17th floor, West Wing, Skyworth Semiconductor Design Building NO.18 Gaoxin South 4th Ave, Nanshan District, Shenzhen, China

1.3 Equipment Under Test (EUT)

Model Name:	NDJ6
Trade Name:	DJI
Brand Name:	DJI
Hardware Version:	1.01
Software Version:	1.0.1.14
Tx Frequency Bands:	2405.375-2477.055MHz
Uplink Modulations:	GFSK
DTM:	Not support
Antenna type:	External Antenna
Development Stage:	Identical prototype
Hotspot function:	Not Support

1.3.1 Photographs of the EUT

Please refer to the External Photos for the Photos of the EUT

1.3.2 Identification of all used EUT

The EUT identity consists of numerical and letter characters, the letter character indicates the test sample, and the Following two numerical characters indicate the software version of the test sample.

EUT Identity	Hardware Version	Software Version
1#	1.01	1.0.1.14

1.4 Applied Reference Documents

Leading reference documents for testing:

No.	Identity	Document Title
1	**47 CFR§2.1093**	Radiofrequency Radiation Exposure Evaluation: Portable Devices
2	**IEEE 1528-2013**	IEEE Recommended Practice for Determining the Peak Spatial-Average Specific Absorption Rate (SAR) in the Human Head from Wireless Communications Devices: Measurement Techniques
3	**KDB 447498 D01v05r02**	General RF Exposure Guidance
10	**KDB 941225 D07v01r01**	UMPC Mini Tablet
11	**KDB 865664 D01v01r02**	SAR Measurement 100 MHz to 6 GHz
12	**KDB 865664 D02v01r01**	SAR Reporting

1.5 Device Category and SAR Limits

This device belongs to portable device category because its radiating structure is allowed to be used within 20 centimeters of the body of the user. Limit for General Population/Uncontrolled exposure should be applied for this device, it is 1.6 W/kg as averaged over any 1 gram of tissue for body, and 4.0W/kg as averaged over any 10 grams of tissue for hands, wrists, feet and ankles.

2. SPECIFIC ABSORPTION RATE (SAR)

2.1 Introduction

SAR is related to the rate at which energy is absorbed per unit mass in an object exposed to a radio field. The SAR distribution in a biological body is complicated and is usually carried out by experimental techniques or numerical modeling. The standard recommends limits for two tiers of groups, occupational/controlled and general population/uncontrolled, based on a person's awareness and ability to exercise control over his or her exposure. In general, occupational/controlled exposure limits are Middle than the limits for general population/uncontrolled.

2.2 SAR Definition

The SAR definition is the time derivative (rate) of the incremental energy (dW) absorbed by (dissipated in) an incremental mass (dm) contained in a volume element (dv) of a given density. (ρ). The equation description is as below:

$$\mathbf{SAR} = \frac{\mathbf{d}}{\mathbf{dt}}\left(\frac{\mathbf{dW}}{\mathbf{dm}}\right) = \frac{\mathbf{d}}{\mathbf{dt}}\left(\frac{\mathbf{dW}}{\boldsymbol{\rho}\mathbf{dv}}\right)$$

SAR is expressed in units of Watts per kilogram (W/kg)

SAR measurement can be either related to the temperature elevation in tissue by,

$$\mathbf{SAR} = \mathbf{C}\left(\frac{\boldsymbol{\delta}\mathbf{T}}{\boldsymbol{\delta}\mathbf{t}}\right)$$

Where C is the specific head capacity, δT is the temperature rise and δt the exposure duration, or related to the electrical field in the tissue by

$$\mathbf{SAR} = \frac{\boldsymbol{\sigma}|\mathbf{E}|^2}{\boldsymbol{\rho}}$$

Where σ is the conductivity of the tissue, ρ is the mass density of the tissue and $|E|$ is the rms electrical field strength.

However for evaluating SAR of low power transmitter, electrical field measurement is typically applied.

3. SAR MEASUREMENT SETUP

3.1 The Measurement System

Comosar is a system that is able to determine the SAR distribution inside a phantom of human being according to different standards. The Comosar system consists of the Following items:

- Main computer to control all the system
- 6 axis robot
- Data acquisition system
- Miniature E-field probe
- Phone holder
- Head simulating tissue

The Following figure shows the system.

The EUT under test operating at the maximum power level is placed in the phone holder, under the phantom, which is filled with head simulating liquid. The E-Field probe measures the electric field inside the phantom. The OpenSAR software computes the results to give a SAR value in a 1g or 10g mass.

3.2 Probe

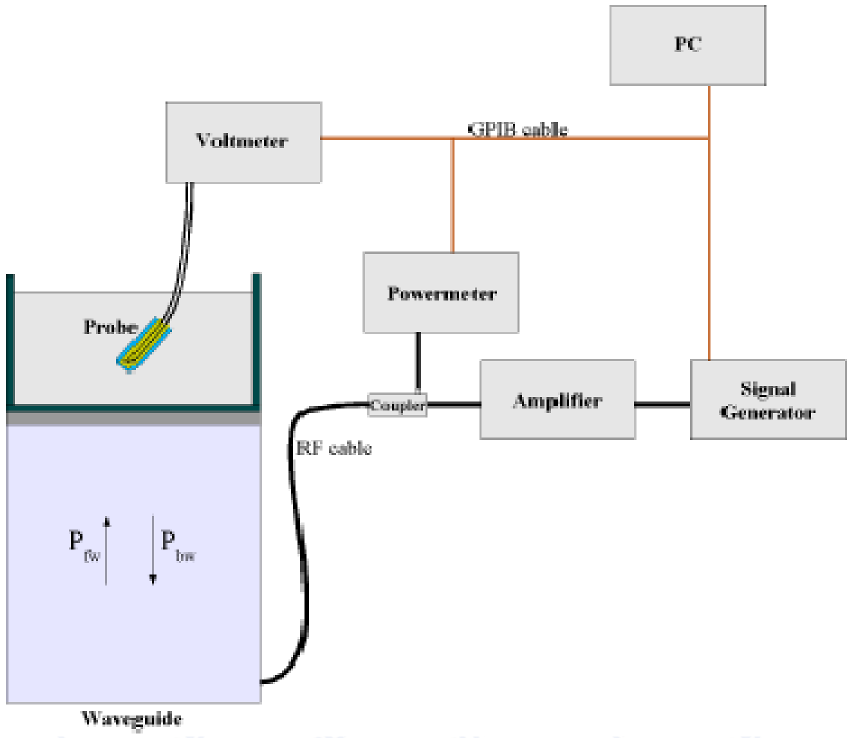
For the measurements the Specific Dosimetric E-Field Probe SN 37/08 EP80 with Following specifications is used

- Dynamic range: 0.01-100 W/kg
- Tip Diameter: 6.5 mm

- Distance between probe tip and sensor center: 2.5mm
- Distance between sensor center and the inner phantom surface: 4 mm (repeatability better than +/- 1mm)
- Probe linearity: <0.25 dB
- Axial Isotropy: <0.25 dB
- Spherical Isotropy: <0.25 dB
- Calibration range: 835to 2500MHz for head & body simulating liquid.

Angle between probe axis (evaluation axis) and surface normal line: less than 30°

Probe calibration is realized, in compliance with CENELEC EN 62209 and IEEE 1528 std, with CALISAR, Antennessa proprietary calibration system. The calibration is performed with the EN 622091 annex technique using reference guide at the five frequencies.



$$SAR = \frac{4\left(P_{fw} - P_{bw}\right)}{ab\delta} \cos^2\left(\pi \frac{y}{a}\right) e^{(2z/\delta)}$$

Where :

Pfw = Forward Power

Pbw = Backward Power

a and b = Waveguide dimensions

ı = Skin depth

Keithley configuration:

Rate = Medium; Filter =ON; RDGS=10; FILTER TYPE =MOVING AVERAGE; RANGE AUTO
After each calibration, a SAR measurement is performed on a validation dipole and compared with a NPL calibrated probe, to verify it.

The calibration factors, CF(N), for the 3 sensors corresponding to dipole 1, dipole 2 and dipole 3 are:

CF(N)=SAR(N)/Vlin(N) (N=1,2,3)

The linearised output voltage Vlin(N) is obtained from the displayed output voltage V(N) using

Vlin(N)=V(N)*(1+V(N)/DCP(N)) (N=1,2,3)

Where DCP is the diode compression point in mV.

3.3 Probe Calibration Process

3.3.1 Dosimetric Assessment Procedure

Each E-Probe/Probe Amplifier combination has unique calibration parameters. SATIMO Probe calibration procedure is conducted to determine the proper amplifier settings to enter in the probe parameters. The amplifier settings are determined for a given frequency by subjecting the probe to a known E-field density (1 mW/cm^2) using an with CALISAR, Antenna proprietary calibration system.

3.3.2 Free Space Assessment Procedure

The free space E-field from amplified probe outputs is determined in a test chamber. This calibration can be performed in a TEM cell if the frequency is below 1 GHz and in a waveguide or other methodologies above 1 GHz for free space. For the free space calibration, the probe is placed in the volumetric center of the cavity and at the proper orientation with the field. The probe is rotated 360 degrees until the three channels show the maximum reading. The power density readings equates to 1 mW/cm^2.

3.3.3 Temperature Assessment Procedure

E-field temperature correlation calibration is performed in a flat phantom filled with the appropriate simulating head tissue. The E-field in the medium correlates with the temperature rise in the dielectric medium. For temperature correlation calibration a RF transparent thermistor-based temperature probe is used in conjunction with the E-field probe.

Where:

δt = exposure time (30 seconds),

$$SAR = C\left(\frac{\delta T}{\delta t}\right)$$

C = heat capacity of tissue (brain or muscle),

δT = temperature increase due to RF exposure.

SAR is proportional to ΔT/Δt, the initial rate of tissue heating, before thermal diffusion takes place. The electric field in the simulated tissue can be used to estimate SAR by equating the thermally derived SAR to that with the E- field component.

$$SAR = \frac{\sigma|E|^2}{\rho}$$

Where:

σ = simulated tissue conductivity,

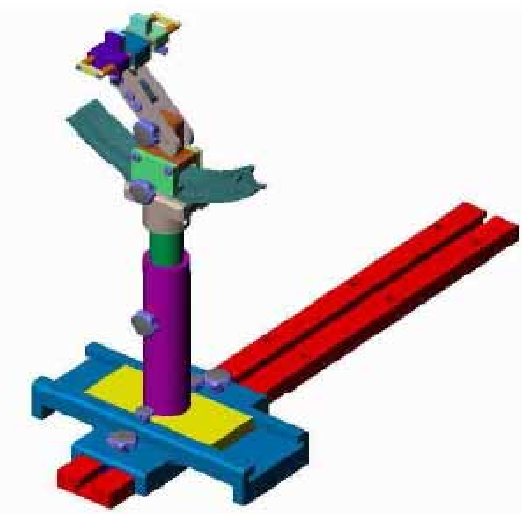
ρ = Tissue density (1.25 g/cm³ for brain tissue)

3.4 Phantom

For the measurements the Specific Anthropomorphic Mannequin (SAM) defined by the IEEE SCC-34/SC2 group is used. The phantom is a polyurethane shell integrated in a wooden table. The thickness of the phantom amounts to 2mm +/- 0.2mm. It enables the dosimetric evaluation of left and right phone usage and includes an additional flat phantom part for the simplified performance check. The phantom set-up includes a cover, which prevents the evaporation of the liquid.

3.5 Device Holder

The positioning system allows obtaining cheek and tilting position with a very good accuracy. In compliance with CENELEC, the tilt angle uncertainty is Middle than 1°.



Device holder

System Material	Permittivity	Loss Tangent
Delrin	3.7	0.005

4. TISSUE SIMULATING LIQUIDS

For SAR measurement of the field distribution inside the phantom, the phantom must be filled with homogeneous tissue simulating liquid to a depth of at least 15 cm. For head SAR testing, the liquid height from the ear reference point (ERP) of the phantom to the liquid top surface is larger than 15 cm. For body SAR testing, the liquid height from the center of the flat phantom to the liquid top surface is larger than 15 cm. The nominal dielectric values of the tissue simulating liquids in the phantom and the tolerance of 5% are listed in below table.

The following table gives the recipes for tissue simulating liquids

Frequency Band (MHz)	2450
Tissue Type	Body
Ingredients (% by weight)	
Deionised Water	73.20
Salt(NaCl)	0.10
Sugar	0.00
Tween 20	0.00
HEC	0.00
Bactericide	0.00
Triton X-100	0.00
DGBE	26.70
Diethylenglycol monohexylether	0.00
Measured dielectric parameters	
Dielectric Constant	52.70
Conductivity (S/m)	1.95

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The dielectric properties of the tissue simulating liquids were verified prior to the SAR evaluation using an Agilent 85033E Dielectric Probe Kit and an Agilent Network Analyzer.

Table 1: Dielectric Performance of Tissue Simulating Liquid

Temperature: 22.0~23.8°C, humidity: 54~60%.						
Date	**Freq.(MHz)**	**Liquid Parameters**	**Meas.**	**Target**	**Delta(%)**	**Limit±(%)**
2014/10/10	Body 2450	Relative Permittivity(εr):	52.46	52.70	-0.46	5
		Conductivity(σ):	1.96	1.95	0.51	5

5. UNCERTAINTY ASSESSMENT

The Following table includes the uncertainty table of the IEEE 1528. The values are determined by Antennessa.

5.1 UNCERTAINTY EVALUATION FOR EUT SAR TEST

a	b	c	d	e= f(d,k)	f	g	h= c*f/e	i= c*g/e	k
Uncertainty Component	Sec.	Tol (+-%)	Prob. Dist.	Div.	Ci (1g)	Ci (10g)	1g Ui (+-%)	10g Ui (+-%)	Vi
Measurement System									
Probe calibration	E.2.1	4.76	N	1	1	1	4.76	4.7	∞
Axial Isotropy	E.2.2	2.5	R	$\sqrt{3}$	0.7	0.7	1.01	1.0	∞
Hemispherical Isotropy	E.2.2	4.0	R	$\sqrt{3}$	0.7	0.7	1.62	1.6	∞
Boundary effect	E.2.3	1.0	R	$\sqrt{3}$	1	1	0.58	0.5	∞
Linearity	E.2.4	5.0	R	$\sqrt{3}$	1	1	2.89	2.8	∞
System detection limits	E.2.5	1.0	R	$\sqrt{3}$	1	1	0.58	0.5	∞
Readout Electronics	E.2.6	0.02	N	1	1	1	0.02	0.0	∞
Reponse Time	E.2.7	3.0	R	$\sqrt{3}$	1	1	1.73	1.7	∞
Integration Time	E.2.8	2.0	R	$\sqrt{3}$	1	1	1.15	1.1	∞
RF ambient Conditions	E.6.1	3.0	R	$\sqrt{3}$	1	1	1.73	1.7	∞
Probe positioner Mechanical Tolerance	E.6.2	2.0	R	$\sqrt{3}$	1	1	1.15	1.15	∞
Probe positioning with respect to Phantom Shell	E.6.3	0.05	R	$\sqrt{3}$	1	1	0.03	0.03	∞
Extrapolation, interpolation and integration Algoritms for Max. SAR Evaluation	E.5.2	5.0	R	$\sqrt{3}$	1	1	2.89	2.89	∞
Test sample Related									
Test sample positioning	E.4.2.1	0.03	N	1	1	1	0.03	0.03	N-1
Device Holder Uncertainty	E.4.1.	5.00	N	1	1	1	5.00	5.0	N-

	1							0	1
Output power Power drift - SAR drift measurement	6.6.2	4.04	R	$\sqrt{3}$	1	1	2.33	2.3 3	∞
Phantom and Tissue Parameters									
Phantom Uncertainty (Shape and thickness tolerances)	E.3.1	0.05	R	$\sqrt{3}$	1	1	0.03	0.0 3	∞
Liquid conductivity - deviation from target value	E.3.2	4.57	R	$\sqrt{3}$	0.64	0.43	1.69	1.1 3	∞
Liquid conductivity - measurement uncertainty	E.3.3	5.00	N	1	0.64	0.43	3.20	2.1 5	M
Liquid permittivity - deviation from target value	E.3.2	3.69	R	$\sqrt{3}$	0.6	0.49	1.28	1.0 4	∞
Liquid permittivity - measurement uncertainty	E.3.3	10.0 0	N	1	0.6	0.49	6.00	4.9 0	M
Combined Standard Uncertainty			RSS				11.55	10. 67	
Expanded Uncertainty (95% Confidence interval)			K=2				23.11	21. 33	

5.2 UNCERTAINTY FOR SYSTEM PERFORMANCE CHECK

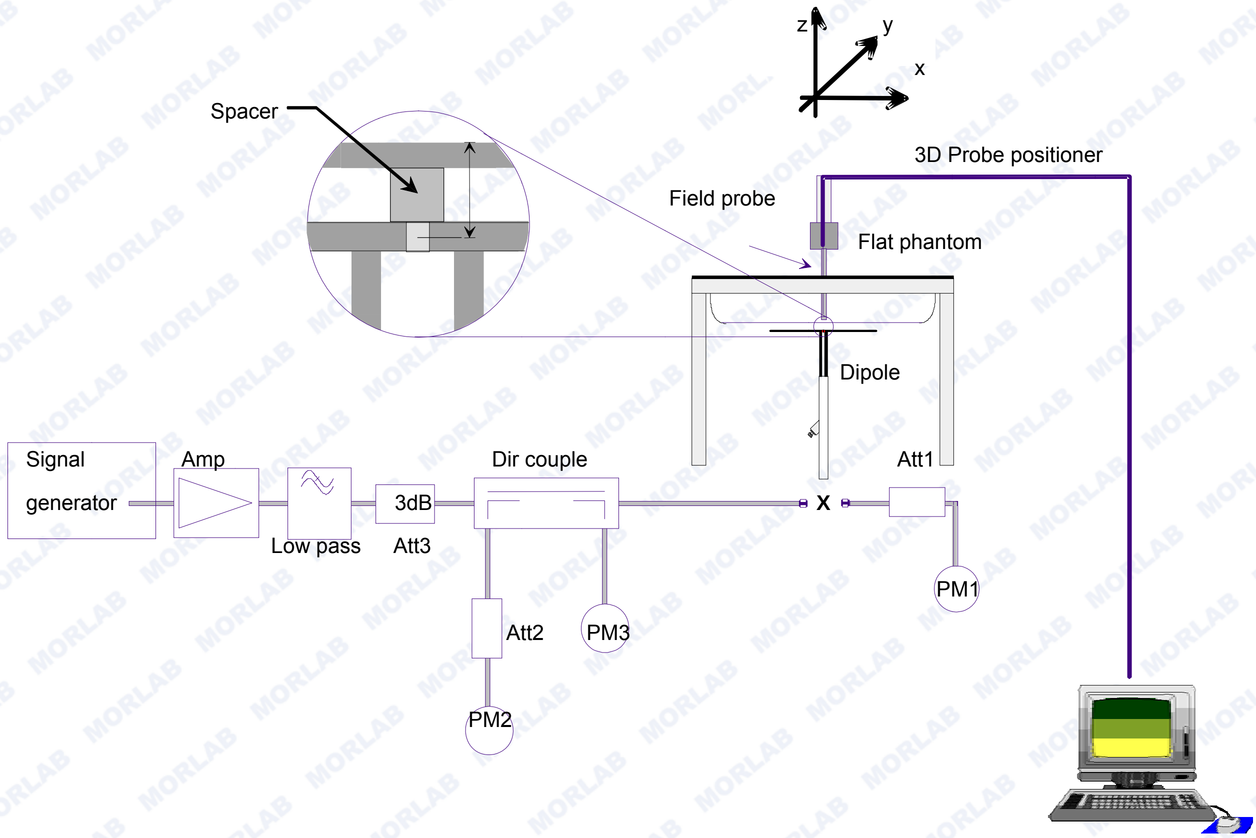
a	b	c	d	e= f(d,k)	f	g	h= c*f/e	i= c*g/ e	k
Uncertainty Component	Sec.	Tol (+- %)	Prob . Dist.	Div.	Ci (1g)	Ci (10g)	1g Ui (+-%)	10g Ui (+- %)	Vi
Measurement System									
Probe calibration	E.2.1	4.76	N	1	1	1	4.76	4.7	∞
Axial Isotropy	E.2.2	2.5	R	$\sqrt{3}$	0.7	0.7	1.01	1.0	∞
Hemispherical Isotropy	E.2.2	4.0	R	$\sqrt{3}$	0.7	0.7	1.62	1.6	∞
Boundary effect	E.2.3	1.0	R	$\sqrt{3}$	1	1	0.58	0.5	∞
Linearity	E.2.4	5.0	R	$\sqrt{3}$	1	1	2.89	2.8	∞
System detection limits	E.2.5	1.0	R	$\sqrt{3}$	1	1	0.58	0.5	∞
Readout Electronics	E.2.6	0.02	N	1	1	1	0.02	0.0	∞

Reponse Time	E.2.7	3.0	R	$\sqrt{3}$	1	1	1.73	1.7	∞
Integration Time	E.2.8	2.0	R	$\sqrt{3}$	1	1	1.15	1.1	∞
RF ambient Conditions	E.6.1	3.0	R	$\sqrt{3}$	1	1	1.73	1.7	∞
Probe positioner Mechanical Tolerance	E.6.2	2.0	R	$\sqrt{3}$	1	1	1.15	1.15	∞
Probe positioning with respect to Phantom Shell	E.6.3	0.05	R	$\sqrt{3}$	1	1	0.03	0.03	∞
Extrapolation, interpolation and integration Algoritms for Max. SAR Evaluation	E.5.2	5.0	R	$\sqrt{3}$	1	1	2.89	2.89	∞
Dipole									
Dipole axis to liquid Distance	8,E.4.2	1.00	N	$\sqrt{3}$	1	1	0.58	0.58	∞
Input power and SAR drift measurement	8,6.6.2	4.04	R	$\sqrt{3}$	1	1	2.33	2.33	∞
Phantom and Tissue Parameters									
Phantom Uncertainty (Shape and thickness tolerances)	E.3.1	0.05	R	$\sqrt{3}$	1	1	0.03	0.03	∞
Liquid conductivity - deviation from target value	E.3.2	4.57	R	$\sqrt{3}$	0.64	0.43	1.69	1.13	∞
Liquid conductivity - measurement uncertainty	E.3.3	5.00	N	$\sqrt{3}$	0.64	0.43	1.85	1.24	M
Liquid permittivity - deviation from target value	E.3.2	3.69	R	$\sqrt{3}$	0.6	0.49	1.28	1.04	∞
Liquid permittivity - measurement uncertainty	E.3.3	10.00	N	$\sqrt{3}$	0.6	0.49	3.46	2.83	M
Combined Standard Uncertainty			RSS				8.83	8.37	
Expanded Uncertainty (95% Confidence interval)			K=2				17.66	16.73	

6. SAR MEASUREMENT EVALUATION

6.1 System Setup

In the simplified setup for system evaluation, the DUT is replaced by a calibrated dipole and the power source is replaced by a continuous wave which comes from a signal generator. The calibrated dipole must be placed beneath the flat phantom section of the SAM twin phantom with the correct distance holder. The distance holder should touch the phantom surface with a light pressure at the reference marking and be oriented parallel to the long side of the phantom. The system check verifies that the system operates within its specifications. It is performed daily or before every SAR measurement. The system check uses normal SAR measurements in the flat section of the phantom with a matched dipole at a specified distance. The system verification setup is shown as below



The validation dipole is placed beneath the flat phantom with the specific spacer in place. The distance spacer is touch the phantom surface with a light pressure at the reference marking and be oriented parallel to the long side of the phantom. The power meter PM1 measures the forward power at the location of the system check dipole connector. The signal generator is adjusted for the desired forward power (250 mW is used for 700 MHz to 3 GHz,100 mW is used for 3.5 GHz to

6 GHz) at the dipole connector and the power meter PM2 is read at that level. After connecting the cable to the dipole, the signal generator is readjusted for the same reading at power meter PM2.

6.2 Validation Results

After system check testing, the SAR result will be normalized to 1W forward input power and compared with the reference SAR value derived from validation dipole certificate report. The deviation of system check should be within 10 %.

Frequency	2450MHz
Target value 1W (1g)	56.13 W/Kg
Test value 1g (250 mW input power)	12.934 W/Kg (10.10)
Normalized to 1W value(1g)	51.736 W/Kg

Frequency	2450MHz
Target value 1W (10g)	25.34 W/Kg
Test value 10g (250 mW input power)	6.643 W/Kg (10.10)
Normalized to 1W value(10g)	26.572 W/Kg

Note: System checks the specific test data please see 40~41.

7. OPERATIONAL CONDITIONS DURING TEST

7.1 Body-worn Configurations

The body-worn configurations shall be tested with the supplied accessories (belt-clips, holsters, etc.) attached to the device in normal use configuration.

For body-worn and other configurations a flat phantom shall be used which is comprised of material with electrical properties similar to the corresponding tissues.

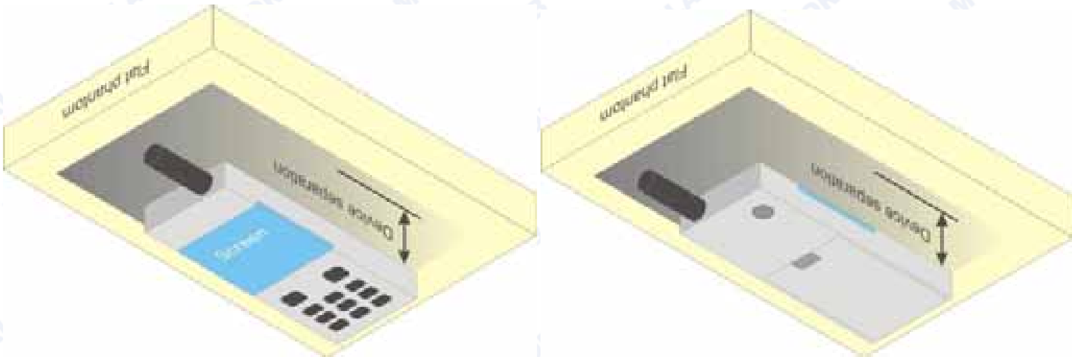


Illustration for Body Worn Position

7.2 Measurement procedure

The Following steps are used for each test position

1. Establish a call with the maximum output power with a base station simulator. The connection between the mobile and the base station simulator is established via air interface.
2. Measurement of the local E-field value at a fixed location. This value serves as a reference value for calculating a possible power drift.
3. Measurement of the SAR distribution with a grid of 8 to 16mm * 8 to16 mm and a constant distance to the inner surface of the phantom. Since the sensors cannot directly measure at the inner phantom surface, the values between the sensors and the inner phantom surface are extrapolated. With these values the area of the maximum SAR is calculated by an interpolation scheme.
4. Around this point, a cube of 30 * 30 * 30 mm or 32 * 32 * 32 mm is assessed by measuring 5 or 8 * 5 or 8*4 or 5 mm. With these data, the peak spatial-average SAR value can be calculated.