SAR TEST REPORT

No. I17N00498-SAR

For

DIGITAL SECURITY CONTROLS LTD.

IoTega Touchscreen

Model Name: WS9TCHW

With

Hardware Version: 1.0

Software Version: Android OS V4.4

Issued Date: 2017-07-21

Note:

The test results in this test report relate only to the devices specified in this report. This report shall not be reproduced except in full without the written approval of CTTL.

Test Laboratory:

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REPORT HISTORY

Report Number	Revision	Issue Date	Description
I17N00498-SAR	Rev.0	2017-07-21	Initial creation of test report

TABLE OF CONTENT

1 Test Laboratory

1.1 Testing Location

Company Name:	CTTL(Shenzhen)
Address:	TCL International E City No.1001 Zhongshanyuan Road, Nanshan District, Shenzhen, Guangdong Province P.R.China
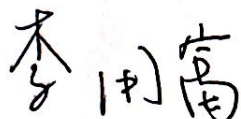
1.2 Testing Environment

Temperature:	18°C~25 °C
Relative humidity:	30%~ 70%
Ground system resistance:	< 4Ω
Ambient noise & Reflection:	< 0.012 W/kg

1.3 Project Data

Project Leader:	Zhang Yunzhuan
Test Engineer:	Li Yongfu
Testing Start Date:	May 20, 2017
Testing End Date:	May 20, 2017

1.4 Signature

_____

Li Yongfu

(Prepared this test report)

_____

Zhang Yunzhuan

(Reviewed this test report)

_____

Cao Junfei

Deputy Director of the laboratory

(Approved this test report)

2 Statement of Compliance

The maximum results of Specific Absorption Rate (SAR) found during testing for DIGITAL SECURITY CONTROLS LTD. IoTega Touchscreen WS9TCHW are as follows:

Table 2.1: Highest Reported SAR (1g)

Exposure Configuration	Technology Band	Highest Reported SAR 1g(W/Kg)	Equipment Class
Body (Data) (Separation Distance 5mm)	WLAN 2.4GHz	**0.51**	DTS

The SAR values found for the DUT are below the maximum recommended levels of 1.6 W/kg as averaged over any 1g tissue according to the ANSI C95.1-1999.

For body worn operation, this device has been tested and meets FCC RF exposure guidelines when used with any accessory that contains no metal and which provides a minimum separation distance of 5 mm between this device and the body of the user. Use of other accessories may not ensure compliance with FCC RF exposure guidelines.

The EUT battery must be fully charged and checked periodically during the test to ascertain uniform power output.

The measurement together with the test system set-up is described in annex C of this test report. A detailed description of the equipment under test can be found in chapter 4 of this test report.

The highest reported SAR value is obtained at the case of **(Table 2.1),** and the values are**: 0.51W/kg(1g).**

3 Client Information

3.1 Applicant Information

Company Name:	Digital Security Controls LTD.
Address /Post:	3301 Langstaff Rd. Concord Ontario Canada
Contact:	Dan Nita
Email:	dnita@tycoint.com
Telephone:	905-760-3000
Fax:	905-760-3020

3.2 Manufacturer Information

Company Name:	WELCO WONG'S TECHNOLOGY (SHENZHEN) LIMITED
Address /Post:	2-3 floor of block 14,1-4 floor of block 34,No2 of WanFeng WanZhangPu Industrial Estate.ShaJing Bao'an ShenZhen,China
Contact:	Samuel Chan
Email:	Samuel.Chan@wongswec.com
Telephone:	86-0755-82215112
Fax:	86-755-82215189

4 Equipment Under Test (EUT) and Ancillary Equipment (AE)

4.1 About EUT

Description:	IoTega Touchscreen
Model Name:	WS9TCHW
Operating mode(s):	Wi-Fi 2.4G
Tested Tx Frequency:	2412 – 2462 MHz (Wi-Fi 2.4G)
Test device Production information:	Production unit
Antenna type:	Integrated antenna

4.2 Internal Identification of EUT used during the test

EUT ID*	SN or IMEI	HW Version	SW Version
EUT1	/	1.0	Android OS V4.4

*EUT ID: is used to identify the test sample in the lab internally.

Note: It is performed to test SAR with the EUT 1, and conducted power with the EUT 2.

4.3 Internal Identification of AE used during the test

AE ID*	Description	Model	SN	Manufacturer
AE1	Battery	SP414257	/	HONGKONG HIGHPOWER TECHNOLOGY CO.,LTD

*AE ID: is used to identify the test sample in the lab internally.

5 TEST METHODOLOGY

5.1 Applicable Limit Regulations

ANSI C95.1–1999:IEEE Standard for Safety Levels with Respect to Human Exposure to Radio Frequency Electromagnetic Fields, 3 kHz to 300 GHz.

It specifies the maximum exposure limit of **1.6 W/kg** as averaged over any 1 gram of tissue for portable devices being used within 20 cm of the user in the uncontrolled environment.

5.2 Applicable Measurement Standards

IEEE 1528–2013: Recommended Practice for Determining the Peak Spatial-Average Specific Absorption Rate (SAR) in the Human Head from Wireless Communications Devices: Experimental Techniques.

KDB 447498 D01 General RF Exposure Guidance v06: Mobile and Portable Devices RF Exposure Procedures and Equipment Authorization Policies.

KDB 248227 D01 802.11 Wi-Fi SAR v02r02: SAR Guidance for IEEE 802.11 (Wi-Fi) Transmitters.

KDB 865664 D01 SAR measurement 100 MHz to 6 GHz v01r04: SAR Measurement Requirements for 100 MHz to 6 GHz.

KDB 865664 D02 RF Exposure Reporting v01r02: RF Exposure Compliance Reporting and Documentation Considerations

KDB 616217 D04 SAR for laptop and tablets v01r02: SAR EVALUATION CONSIDERATIONS FOR LAPTOP, NOTEBOOK, NETBOOK AND TABLET COMPUTERS

6 Specific Absorption Rate (SAR)

6.1 Introduction

SAR is related to the rate at which energy is absorbed per unit mass in an object exposed to a radio field. The SAR distribution in a biological body is complicated and is usually carried out by experimental techniques or numerical modeling. The standard recommends limits for two tiers of groups, occupational/controlled and general population/uncontrolled, based on a person's awareness and ability to exercise control over his or her exposure. In general, occupational/controlled exposure limits are higher than the limits for general population/uncontrolled.

6.2 SAR Definition

The SAR definition is the time derivative (rate) of the incremental energy (dW) absorbed by (dissipated in) an incremental mass (dm) contained in a volume element (dv) of a given density (ρ). The equation description is as below:

$$SAR = \frac{d}{dt}(\frac{dW}{dm}) = \frac{d}{dt}(\frac{dW}{\rho dv})$$

SAR is expressed in units of Watts per kilogram (W/kg)

SAR measurement can be either related to the temperature elevation in tissue by

$$SAR = c(\frac{\delta T}{\delta t})$$

Where: C is the specific head capacity, δT is the temperature rise and δt is the exposure duration, or related to the electrical field in the tissue by

$$SAR = \frac{\sigma |E|^2}{\rho}$$

Where: σ is the conductivity of the tissue, ρ is the mass density of tissue and E is the RMS electrical field strength.

However for evaluating SAR of low power transmitter, electrical field measurement is typically applied.

7 Tissue Simulating Liquids

7.1 Targets for tissue simulating liquid

Table 7.1: Targets for tissue simulating liquid

Frequency (MHz)	Liquid Type	Conductivity (σ)	± 5% Range	Permittivity (ε)	± 5% Range
2450	Body	1.95	1.85～2.05	52.7	50.1～55.3

7.2 Dielectric Performance

Table 7.2: Dielectric Performance of Tissue Simulating Liquid

Measurement Date (yyyy-mm-dd)	Type	Frequency	Conductivity σ (S/m)	Drift (%)	Permittivity ε	Drift (%)
2017-5-20	Body	2450	1.968	0.92	51.66	-1.97

Note: The liquid temperature is 22.0^{o}C
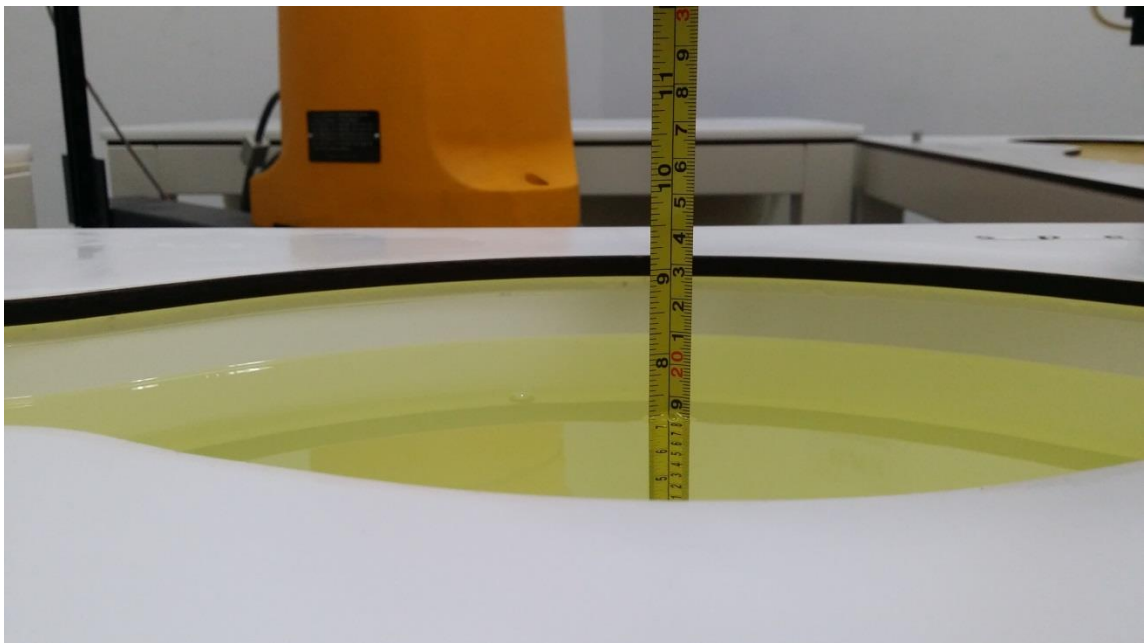
Picture 7-1: Liquid depth in the Flat Phantom(2450MHz)

8 System verification

8.1 System Setup

In the simplified setup for system evaluation, the DUT is replaced by a calibrated dipole and the power source is replaced by a continuous wave that comes from a signal generator. The calibrated dipole must be placed beneath the flat phantom section of the SAM twin phantom with the correct distance holder. The distance holder should touch the phantom surface with a light pressure at the reference marking and be oriented parallel to the long side of the phantom. The equipment setup is shown below:
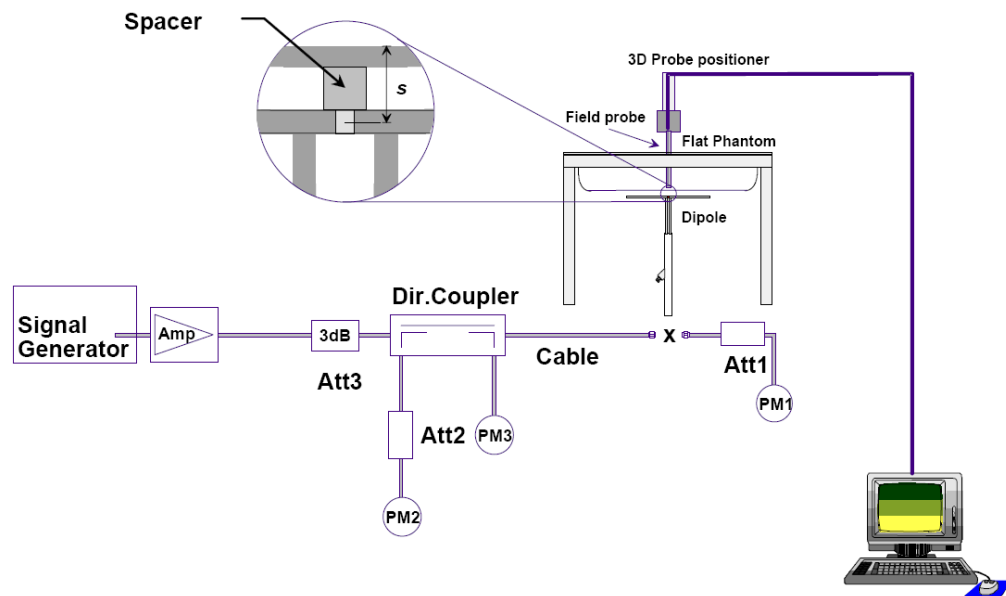
Picture 8.1 System Setup for System Evaluation

Picture 8.2 Photo of Dipole Setup

8.2 System Verification

SAR system verification is required to confirm measurement accuracy, according to the tissue dielectric media, probe calibration points and other system operating parameters required for measuring the SAR of a test device. The system verification must be performed for each frequency band and within the valid range of each probe calibration point required for testing the device.

The system verification results are required that the area scan estimated 1-g SAR is within 3% of the zoom scan 1-g SAR. The details are presented in annex B.

Table 8.2: System Verification of Body

Measurement Date (yyyy-mm-dd)	Frequency	Target value (W/kg)		Measured value (W/kg)		Deviation (%)	
		10 g Average	1 g Average	10 g Average	1 g Average	10 g Average	1 g Average
2017-5-20	2450 MHz	24.4	52.3	24.64	52.8	-0.98	0.96

9 Measurement Procedures

9.1 Tests to be performed

In order to determine the highest value of the peak spatial-average SAR of a handset, all device positions, configurations and operational modes shall be tested for each frequency band according to steps 1 to 3 below. A flowchart of the test process is shown in picture 9.1.

Step 1: The tests described in 9.2 shall be performed at the channel that is closest to the center of the transmit frequency band (f_c) for:

a) all device positions (cheek and tilt, for both left and right sides of the SAM phantom, as described in annex D),
b) all configurations for each device position in a), e.g., antenna extended and retracted, and
c) all operational modes, e.g., analogue and digital, for each device position in a) and configuration in b) in each frequency band.

If more than three frequencies need to be tested according to 11.1 (i.e., N_c > 3), then all frequencies, configurations and modes shall be tested for all of the above test conditions.

Step 2: For the condition providing highest peak spatial-average SAR determined in Step 1, perform all tests described in 9.2 at all other test frequencies, i.e., lowest and highest frequencies. In addition, for all other conditions (device position, configuration and operational mode) where the peak spatial-average SAR value determined in Step 1 is within 3 dB of the applicable SAR limit, it is recommended that all other test frequencies shall be tested as well.

Step 3: Examine all data to determine the highest value of the peak spatial-average SAR found in Steps 1 to 2.
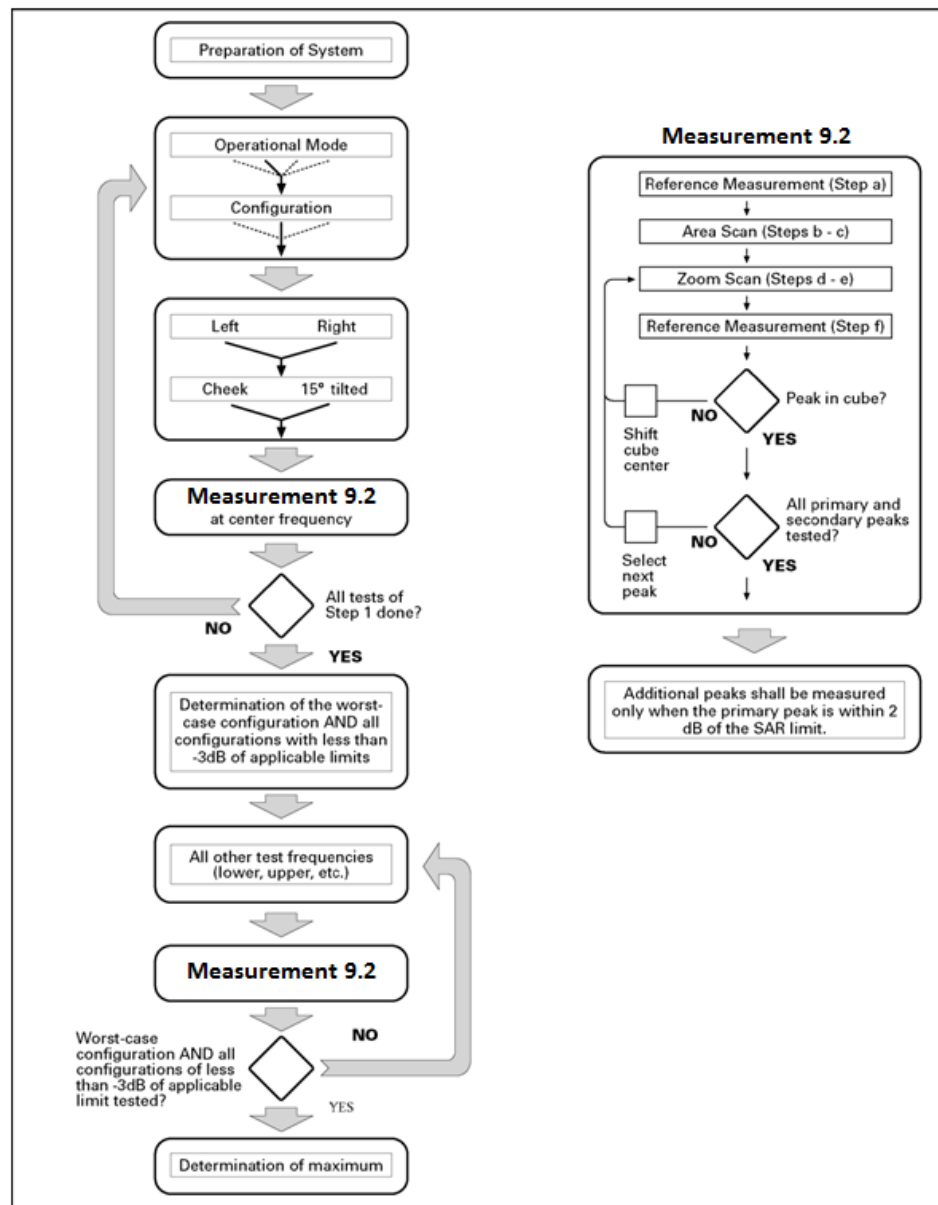
Picture 9.1Block diagram of the tests to be performed

9.2 General Measurement Procedure

The area and zoom scan resolutions specified in the table below must be applied to the SAR measurements and fully documented in SAR reports to qualify for TCB approval. Probe boundary effect error compensation is required for measurements with the probe tip closer than half a probe tip diameter to the phantom surface. Both the probe tip diameter and sensor offset distance must satisfy measurement protocols; to ensure probe boundary effect errors are minimized and the higher fields closest to the phantom surface can be correctly measured and extrapolated to the phantom surface for computing 1-g SAR. Tolerances of the post-processing algorithms must be verified by the test laboratory for the scan resolutions used in the SAR measurements, according to the reference distribution functions specified in IEEE Std 1528-2013. The results should be documented as part of the system validation records and may be requested to support test results

when all the measurement parameters in the following table are not satisfied.

	$\leq$ 3 GHz	> 3 GHz
Maximum distance from closest measurement point (geometric center of probe sensors) to phantom surface	5 $\pm$ 1 mm	½·δ·ln(2) $\pm$ 0.5 mm
Maximum probe angle from probe axis to phantom surface normal at the measurement location	30° $\pm$ 1°	20° $\pm$ 1°
Maximum area scan spatial resolution: Δx_{Area}, Δy_{Area}	$\leq$ 2 GHz: $\leq$ 15 mm 2 – 3 GHz: $\leq$ 12 mm	3 – 4 GHz: $\leq$ 12 mm 4 – 6 GHz: $\leq$ 10 mm
		When the x or y dimension of the test device, in the measurement plane orientation, is smaller than the above, the measurement resolution must be $\leq$ the corresponding x or y dimension of the test device with at least one measurement point on the test device.
Maximum zoom scan spatial resolution: Δx_{Zoom}, Δy_{Zoom}	$\leq$ 2 GHz: $\leq$ 8 mm 2 – 3 GHz: $\leq$ 5 mm*	3 – 4 GHz: $\leq$ 5 mm* 4 – 6 GHz: $\leq$ 4 mm*
Maximum zoom scan spatial resolution, normal to phantom surface	uniform grid: $\Delta z_{Zoom}(n)$	$\leq$ 5 mm	3 – 4 GHz: $\leq$ 4 mm 4 – 5 GHz: $\leq$ 3 mm 5 – 6 GHz: $\leq$ 2 mm
	graded grid — $\Delta z_{Zoom}(1)$: between 1st two points closest to phantom surface	$\leq$ 4 mm	3 – 4 GHz: $\leq$ 3 mm 4 – 5 GHz: $\leq$ 2.5 mm 5 – 6 GHz: $\leq$ 2 mm
	graded grid — $\Delta z_{Zoom}(n>1)$: between subsequent points	$\leq$ 1.5·$\Delta z_{Zoom}(n-1)$	
Minimum zoom scan volume	x, y, z	$\geq$ 30 mm	3 – 4 GHz: $\geq$ 28 mm 4 – 5 GHz: $\geq$ 25 mm 5 – 6 GHz: $\geq$ 22 mm

Note: δ is the penetration depth of a plane-wave at normal incidence to the tissue medium; see draft standard IEEE P1528-2011 for details.
* When zoom scan is required and the *reported* SAR from the area scan based *1-g SAR estimation* procedures of KDB 447498 is $\leq$ 1.4 W/kg, $\leq$ 8 mm, $\leq$ 7 mm and $\leq$ 5 mm zoom scan resolution may be applied, respectively, for 2 GHz to 3 GHz, 3 GHz to 4 GHz and 4 GHz to 6 GHz.

9.3 Bluetooth & Wi-Fi Measurement Procedures for SAR

Normal network operating configurations are not suitable for measuring the SAR of 802.11 transmitters in general. Unpredictable fluctuations in network traffic and antenna diversity conditions can introduce undesirable variations in SAR results. The SAR for these devices should be measured using chipset based test mode software to ensure that the results are consistent and reliable.

Chipset based test mode software is hardware dependent and generally varies among manufacturers. The device operating parameters established in a test mode for SAR measurements must be identical to those programmed in production units, including output power levels, amplifier gain settings and other RF performance tuning parameters. The test frequencies should correspond to actual channel frequencies defined for domestic use. SAR for devices with switched diversity should be measured with only one antenna transmitting at a time during each SAR measurement, according to a fixed modulation and data rate. The same data pattern should be used for all measurements.

9.4 Power Drift

To control the output power stability during the SAR test, DASY5 system calculates the power drift by measuring the E-field at the same location at the beginning and at the end of the measurement for each test position. These drift values can be found in Section 14 labeled as: (Power Drift [dB]). This ensures that the power drift during one measurement is within 5%.

10 Area Scan Based 1-g SAR

10.1 Requirement of KDB

According to the KDB447498 D01, when the implementation is based the specific polynomial fit algorithm as presented at the 29th Bioelectromagnetics Society meeting (2007) and the estimated 1-gSAR is ≤ 1.2 W/kg, a zoom scan measurement is not required provided it is also not needed for any other purpose; for example, if the peak SAR location required for simultaneous transmission SAR test exclusion can be determined accurately by the SAR system or manually to discriminate between distinctive peaks and scattered noisy SAR distributions from area scans.

There must not be any warning or alert messages due to various measurement concerns identified by the SAR system; for example, noise in measurements, peaks too close to scan boundary, peaks are too sharp, spatial resolution and uncertainty issues etc. The SAR system verification must also demonstrate that the area scan estimated 1-g SAR is within 3% of the zoom scan 1-g SAR (See Annex B). When all the SAR results for each exposure condition in a frequency band and wireless mode are based on estimated 1-g SAR, the 1-g SAR for the highest SAR configuration must be determined by a zoom scan.

10.2 Fast SAR Algorithms

The approach is based on the area scan measurement applying a frequency dependent attenuation parameter. This attenuation parameter was empirically determined by analyzing a large number of phones. The MOTOROLA FAST SAR was developed and validated by the MOTOROLA Research Group in Ft. Lauderdale.

In the initial study, an approximation algorithm based on Linear fit was developed. The accuracy of the algorithm has been demonstrated across a broad frequency range (136-2450 MHz) and for both 1- and 10-g averaged SAR using a sample of 264 SAR measurements from 55 wireless handsets. For the sample size studied, the root-mean-squared errors of the algorithm are 1.2% and 5.8% for 1- and 10-g averaged SAR, respectively. The paper describing the algorithm in detail is expected to be published in August 2004 within the Special Issue of Transactions on MTT.

In the second step, the same research group optimized the fitting algorithm to an Polynomial fit whereby the frequency validity was extended to cover the range 30-6000MHz. Details of this study can be found in the BEMS 2007 Proceedings.

Both algorithms are implemented in DASY software.

11 Conducted Output Power

11.1 Manufacturing tolerance

Table 11.1: Wi-Fi

Mode	Channel/Data rate	Target (dBm)	Tolerance ±(dB)
802.11 b (2.4GHz)	1Mbps	14	1
	2Mbps	14	1
	5.5Mbps	14	1
	11Mbps	14	1
802.11 g (2.4GHz)	6-18Mbps	13	1
	24-36Mbps	13	1
	48-54Mbps	13	1
802.11 n (2.4GHz HT20)	MCS0- MCS4	12	1
	MCS5- MCS7	12	1

11.2 Wi-Fi Measurement result

The average conducted power for Wi-Fi is as following:

802.11b（dBm）

Channel\data rate	1Mbps	2Mbps	5.5Mbps	11Mbps
1(2412MHz)	14.44	14.40	14.43	14.45
6(2437MHz)	14.45	14.48	14.51	14.33
11(2462MHz)	**14.58**	14.51	14.49	14.46

802.11g（dBm）

Channel\data rate	6Mbps	9Mbps	12Mbps	18Mbps	24Mbps	36Mbps	48Mbps	54Mbps
1(2412MHz)	12.49	12.41	12.39d	12.25d	12.25	12.05	12.09	12.03
6(2437MHz)	12.42	12.46	12.34	12.25	12.20	12.04	12.04	12.03
11(2462MHz)	12.36	12.49	12.40	12.27	12.20	12.05	12.03	12.04

802.11n（dBm）- HT20 (2.4G)

Channel\data rate	MCS0	MCS1	MCS2	MCS3	MCS4	MCS5	MCS6	MCS7
1(2412MHz)	11.90	11.73	11.59	11.54	11.33	11.10	11.00	11.08
6(2437MHz)	11.78	11.64	11.54	11.62	11.34	11.18	11.12	11.05
11(2462MHz)	11.83	11.65	11.57	11.53	11.36	11.19	11.02	11.02

12 Antenna Location

Top Edge

Right Edge

220mm

185mm

199mm

Left Edge

WLAN Antenna

90mm

114mm

Bottom Edge

Rear View
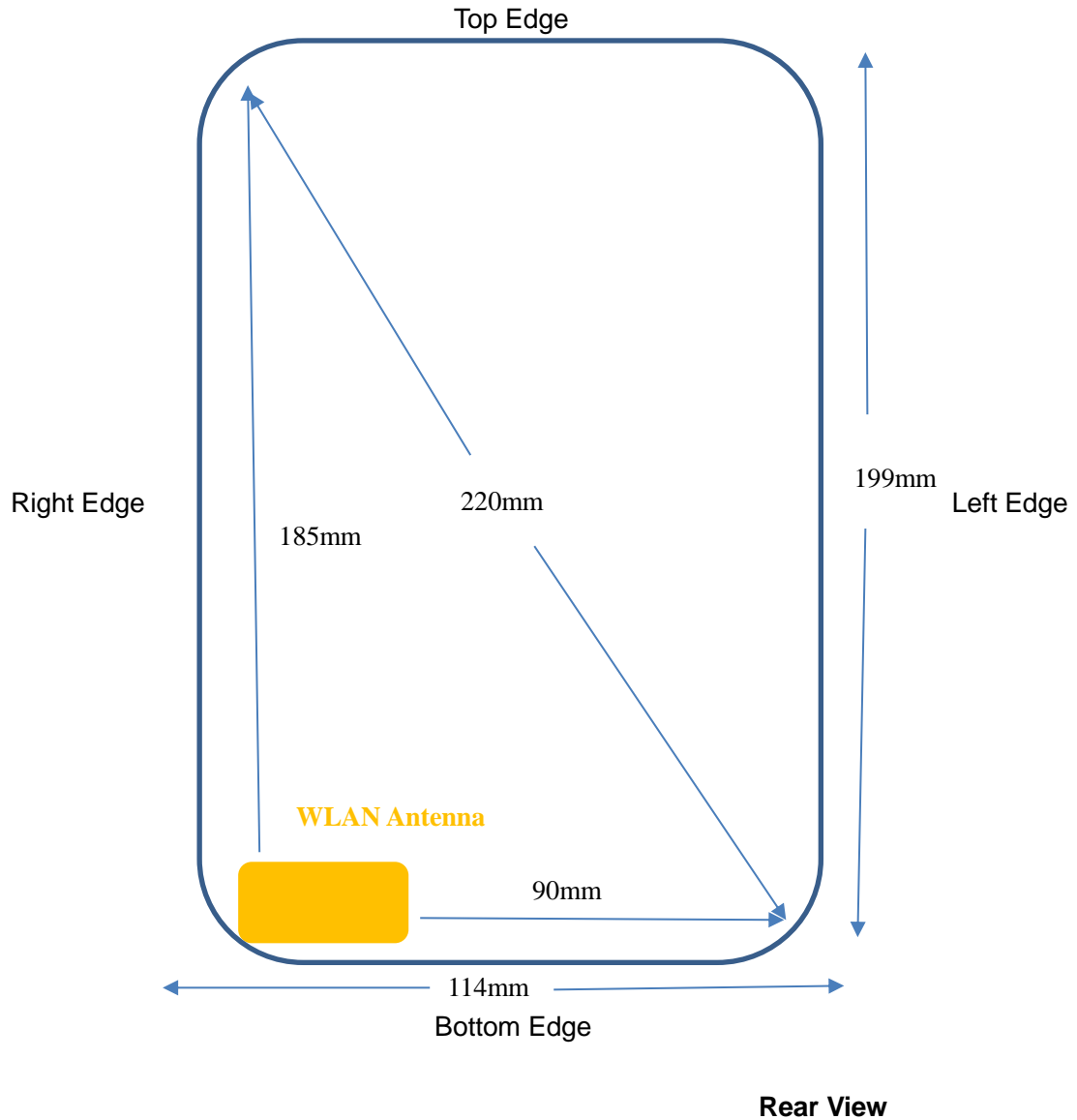
The Antenna position		
Exposure Position	Wireless interface	WLAN 2.4GHz
	Tune-up Maximum power（dBm）	15
	Tune-up Maximum rated power（mw）	31.62
Front	Antenna to user（mm）	5
	SAR exclusion threshold（mw）	10
	SAR testing request?	YES
Rear	Antenna to user（mm）	5
	SAR exclusion threshold（mw）	10
	SAR testing request?	YES
Bottom Edge	Antenna to user（mm）	5
	SAR exclusion threshold（mw）	10
	SAR testing request?	YES
Top Edge	Antenna to user（mm）	190
	SAR exclusion threshold（mw）	1496
	SAR testing request?	NO
Left Edge	Antenna to user（mm）	95
	SAR exclusion threshold（mw）	546
	SAR testing request?	NO
Right Edge	Antenna to user（mm）	5
	SAR exclusion threshold（mw）	10
	SAR testing request?	YES

Note:

1. Per KDB 447498 D01, the 1-g SAR test exclusion thresholds for 100 MHz to 6 GHz at *test separation distances* ≤ 50 mm are determined by:

[(*max. power of channel, including tune-up tolerance, mW*) / (*min. test separation distance, mm*)] · [$\sqrt{f(GHz)}$] ≤ 3.0 for 1-g SAR, where

f(GHz) is the RF channel transmit frequency in GHz

Power and distance are rounded to the nearest mW and mm before calculation

The result is rounded to one   decimal place for comparison

2. Per KDB 447498 D01v06, For 100 MHz to 6 GHz and *test separation distances* > 50 mm, the 1-g and 10-g *SAR test exclusion thresholds* are determined by the following

1) {[Power allowed at *numeric threshold* for 50 mm in step a)] + [(test separation distance – 50   mm)·(f(MHz)/150)]} mW, for 100 MHz to 1500 MHz

2) {[Power allowed at *numeric threshold* for 50 mm in step a)] + [(test separation distance – 50 mm)·10]} mW, for > 1500 MHz and ≤ 6 GHz

13 SAR Test Result

It is determined by user manual for the distance between the EUT and the phantom bottom.
The distance is 5mm and just applied to the condition of body worn accessory.
It is performed for all SAR measurements with area scan based 1-g SAR estimation (Fast SAR). A zoom scan measurement is added when the estimated 1-g SAR is the highest measured SAR in each exposure configuration, wireless mode and frequency band combination or >1.2W/kg.
The calculated SAR is obtained by the following formula:

$$\text{Reported SAR} = \text{Measured SAR} \times 10^{(P_{Target} - P_{Measured})/10}$$

Where P_{Target} is the power of manufacturing upper limit;

$P_{Measured}$ is the measured power in chapter 11.

13.1 WLAN Evaluation

According to the KDB248227 D01, SAR is measured for 2.4GHz 802.11b DSSS using the initial test position procedure.

Body Evaluation

Table 14.1: SAR Values (WLAN - Body)– 802.11b 11Mbps (Fast SAR)-AP ON

Frequency		Test Position	Figure No.	Conducted Power (dBm)	Max. tune-up Power (dBm)	Measured SAR(10g) (W/kg)	Reported SAR(10g) (W/kg)	Measured SAR(1g) (W/kg)	Reported SAR(1g)(W/kg)	Power Drift (dB)
MHz	Ch.									
2462	11	Front	/	14.58	15	0.218	**0.24**	0.422	**0.46**	0.06
2462	11	Rear	/	14.58	15	0.171	**0.19**	0.330	**0.36**	-0.04
2462	11	Right	/	14.58	15	0.110	**0.12**	0.214	**0.24**	0.11
2462	11	Top	/	14.58	15	0.047	**0.05**	0.092	**0.10**	0.14

Note1: The distance between the EUT and the phantom bottom is 5mm.

As shown above table, the initial test position for body is "Front". So the body SAR of WLAN is presented as below:

Table 14.2: SAR Values (WLAN - Body) – 802.11b 11Mbps (Full SAR)

Frequency		Test Position	Figure No.	Conducted Power (dBm)	Max. tune-up Power (dBm)	Measured SAR(10g) (W/kg)	Reported SAR(10g) (W/kg)	Measured SAR(1g) (W/kg)	Reported SAR(1g)(W/kg)	Power Drift (dB)
MHz	Ch.									
2462	11	Front	Fig.1	14.58	15	0.231	**0.25**	0.466	**0.51**	0.05

According to the KDB248227 D01, The reported SAR must be scaled to 100% transmission duty factor to determine compliance at the maximum tune-up tolerance limit. A maximum transmission duty factor of 98% is achievable for WLAN in this project and the scaled reported SAR is presented as below.

Table 14.3: SAR Values (WLAN - Body) – 802.11b 11Mbps (Scaled Reported SAR)

Ambient Temperature: 22.3^{o}C				Liquid Temperature: 21.8^{o}C	
Frequency		Test	Actual duty	maximum duty	Reported SAR	Scaled reported SAR
MHz	Ch.	Position	factor	factor	(1g)(W/kg)	(1g)(W/kg)
2462	11	Front	98%	100%	0.15	**0.52**

SAR is not required for OFDM because the 802.11b adjusted SAR $\leq$ 1.2 W/kg.
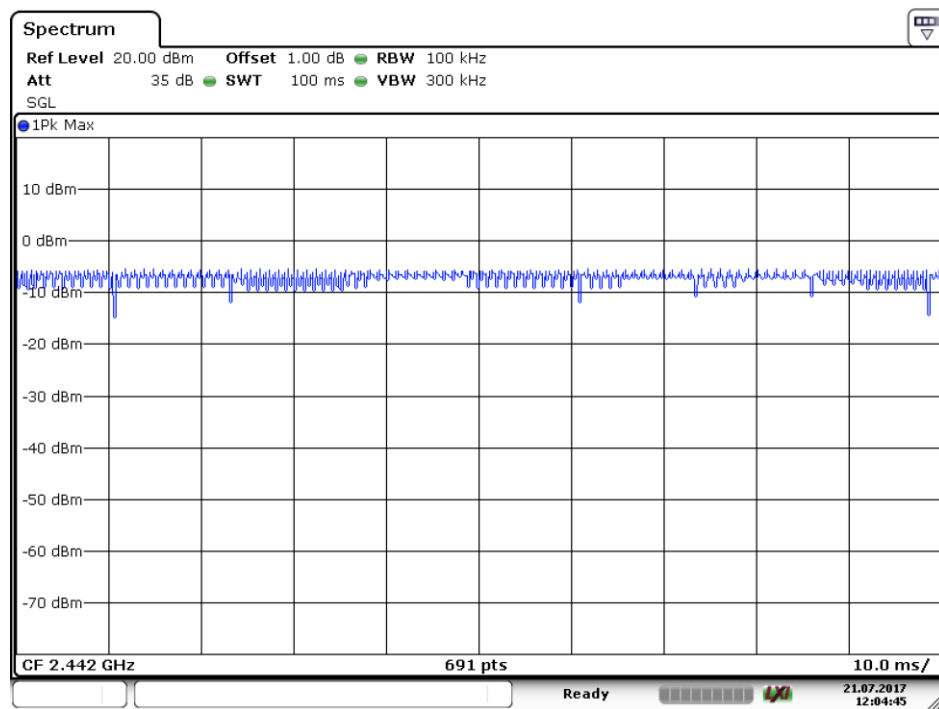
Picture 13.1: The plot of duty factor

14 Measurement Uncertainty

14.1 Measurement Uncertainty for Normal SAR Tests (300MHz~3GHz)

No.	Error Description	Type	Uncertainty value	Probably Distribution	Div.	(Ci) 1g	(Ci) 10g	Std. Unc. (1g)	Std. Unc. (10g)	Degree of freedom
Measurement system										
1	Probe calibration	B	12	N	2	1	1	6.0	6.0	∞
2	Isotropy	B	7.4	R	$\sqrt{3}$	1	1	4.3	4.3	∞
3	Boundary effect	B	1.1	R	$\sqrt{3}$	1	1	0.6	0.6	∞
4	Linearity	B	4.7	R	$\sqrt{3}$	1	1	2.7	2.7	∞
5	Detection limit	B	1.0	R	$\sqrt{3}$	1	1	0.6	0.6	∞
6	Readout electronics	B	1.0	N	1	1	1	1.0	1.0	∞
7	Response time	B	0.0	R	$\sqrt{3}$	1	1	0.0	0.0	∞
8	Integration time	B	1.7	R	$\sqrt{3}$	1	1	1.0	1.0	∞
9	RF ambient conditions-noise	B	3.0	R	$\sqrt{3}$	1	1	1.7	1.7	∞
10	RF ambient conditions-reflection	B	3.0	R	$\sqrt{3}$	1	1	1.7	1.7	∞
11	Probe positioned mech. restrictions	B	0.35	R	$\sqrt{3}$	1	1	0.2	0.2	∞
12	Probe positioning with respect to phantom shell	B	2.9	R	$\sqrt{3}$	1	1	1.7	1.7	∞
13	Post-processing	B	1.0	R	$\sqrt{3}$	1	1	0.6	0.6	∞
Test sample related										
14	Test sample positioning	A	3.3	N	1	1	1	3.3	3.3	5
15	Device holder uncertainty	A	3.4	N	1	1	1	3.4	3.4	5
16	Drift of output power	B	5.0	R	$\sqrt{3}$	1	1	2.9	2.9	∞
Phantom and set-up										
17	Phantom uncertainty	B	1.0	R	$\sqrt{3}$	1	1	0.6	0.6	∞
18	Liquid conductivity (target)	B	5.0	R	$\sqrt{3}$	0.64	0.43	1.8	1.2	∞
19	Liquid conductivity (meas.)	A	1.3	N	1	0.64	0.43	0.83	0.56	9
20	Liquid permittivity (target)	B	5.0	R	$\sqrt{3}$	0.6	0.49	1.7	1.4	∞
21	Liquid permittivity (meas.)	A	1.6	N	1	0.6	0.49	0.96	0.78	9
Combined standard uncertainty	$u_c^{'} = \sqrt{\sum_{i=1}^{21} c_i^2 u_i^2}$							10.4	10.3	95.5
Expanded uncertainty (Confidence interval of 95 %)	$u_e = 2u_c$							20.8	20.6	

14.2 Measurement Uncertainty for Fast SAR Tests (300MHz~3GHz)

No.	Error Description	Type	Uncertainty value	Probably Distribution	Div.	(Ci) 1g	(Ci) 10g	Std. Unc. (1g)	Std. Unc. (10g)	Degree of freedom
				Measurement system						
1	Probe calibration	B	12	N	2	1	1	6.0	6.0	∞
2	Isotropy	B	7.4	R	$\sqrt{3}$	1	1	4.3	4.3	∞
3	Boundary effect	B	1.1	R	$\sqrt{3}$	1	1	0.6	0.6	∞
4	Linearity	B	4.7	R	$\sqrt{3}$	1	1	2.7	2.7	∞
5	Detection limit	B	1.0	R	$\sqrt{3}$	1	1	0.6	0.6	∞
6	Readout electronics	B	1.0	N	1	1	1	1.0	1.0	∞
7	Response time	B	0.0	R	$\sqrt{3}$	1	1	0.0	0.0	∞
8	Integration time	B	1.7	R	$\sqrt{3}$	1	1	1.0	1.0	∞
9	RF ambient conditions-noise	B	3.0	R	$\sqrt{3}$	1	1	1.7	1.7	∞
10	RF ambient conditions-reflection	B	3.0	R	$\sqrt{3}$	1	1	1.7	1.7	∞
11	Probe positioned mech. Restrictions	B	0.35	R	$\sqrt{3}$	1	1	0.2	0.2	∞
12	Probe positioning with respect to phantom shell	B	2.9	R	$\sqrt{3}$	1	1	1.7	1.7	∞
13	Post-processing	B	1.0	R	$\sqrt{3}$	1	1	0.6	0.6	∞
14	Fast SAR z-Approximation	B	7.0	R	$\sqrt{3}$	1	1	4.0	4.0	∞
				Test sample related						
15	Test sample positioning	A	3.3	N	1	1	1	3.3	3.3	5
16	Device holder uncertainty	A	3.4	N	1	1	1	3.4	3.4	5
17	Drift of output power	B	5.0	R	$\sqrt{3}$	1	1	2.9	2.9	∞
				Phantom and set-up						
18	Phantom uncertainty	B	1.0	R	$\sqrt{3}$	1	1	0.6	0.6	∞
19	Liquid conductivity (target)	B	5.0	R	$\sqrt{3}$	0.64	0.43	1.8	1.2	∞
20	Liquid conductivity (meas.)	A	1.3	N	1	0.64	0.43	0.83	0.56	43
21	Liquid permittivity (target)	B	5.0	R	$\sqrt{3}$	0.6	0.49	1.7	1.4	∞
22	Liquid permittivity (meas.)	A	1.6	N	1	0.6	0.49	0.96	0.78	521
Combined standard uncertainty		$u_c^{'} = \sqrt{\sum_{i=1}^{22} c_i^2 u_i^2}$						11.1	11.0	257
Expanded uncertainty (Confidence interval of 95 %)		$u_e = 2u_c$						22.2	22.0	

15 MAIN TEST INSTRUMENTS

Table 15.1: List of Main Instruments

No.	Name	Type	Serial Number	Calibration Date	Valid Period
01	Network analyzer	Agilent E5071C	MY46103759	2016-11-19	One year
02	Dielectric probe	85070E	MY44300317	/	
03	Power meter	NRP	102603	2017-01-06	One year
04	Power sensor	NRP-Z51	102211		
05	Signal Generator	E8257D	MY47461211	2016-06-15	One year
06	Amplifier	VTL5400	0404	/	
07	DAE	SPEAG DAE4	786	2016-12-08	One year
08	E-field Probe	SPEAG EX3DV4	3633	2017-01-23	One year
09	Dipole Validation Kit	SPEAG D2450V2	873	2015-10-30	Three year

END OF REPORT BODY

ANNEX A Graph Results

Wi-Fi 802.11b Body Front Channel 11

Date: 2017-5-20

Electronics: DAE4 Sn786

Medium: Body 2450 MHz

Medium parameters used (interpolated): f = 2462 MHz; σ = 1.982 S/m; $ε_r$ = 51.625; ρ = 1000 kg/m^3

Ambient Temperature: 22.0^{o}C   Liquid Temperature: 21.5^{o}C

Communication System: UID 0, WiFi (0) Frequency: 2462 MHz Duty Cycle: 1:1

Probe: EX3DV4 - SN3633 ConvF (7.37, 7.37, 7.37);

Front side High/Area Scan (91x151x1): Interpolated grid: dx=1.000 mm, dy=1.000 mm

Maximum value of SAR (interpolated) = 0.573 W/kg

Front side High/Zoom Scan (5x5x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 4.615 V/m; Power Drift = 0.05 dB

Peak SAR (extrapolated) = 0.845 W/kg

SAR(1 g) = 0.466 W/kg; SAR(10 g) = 0.231 W/kg

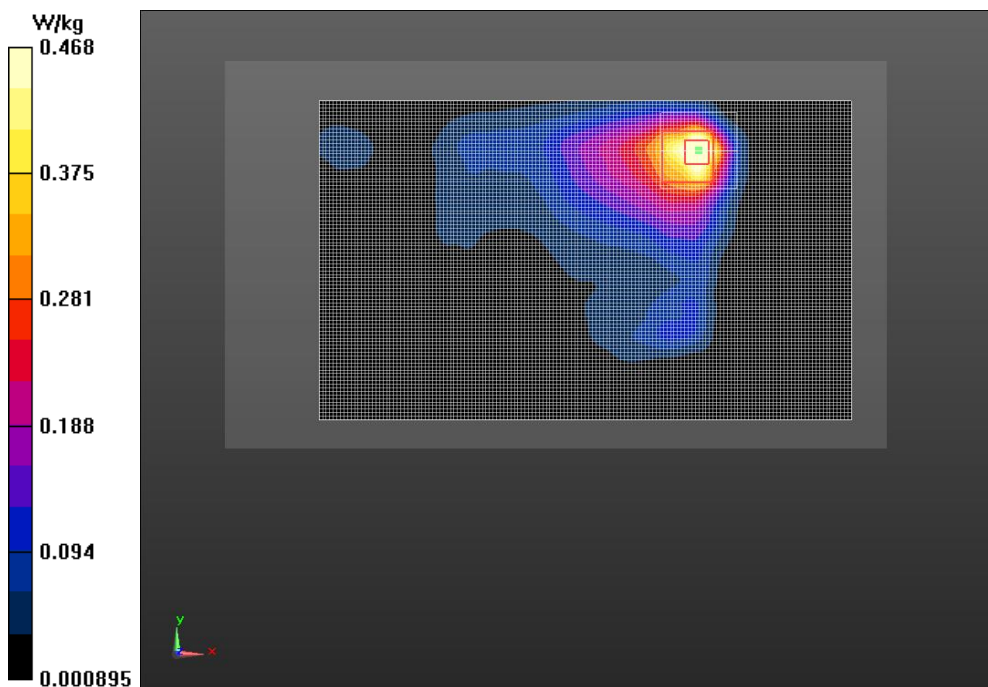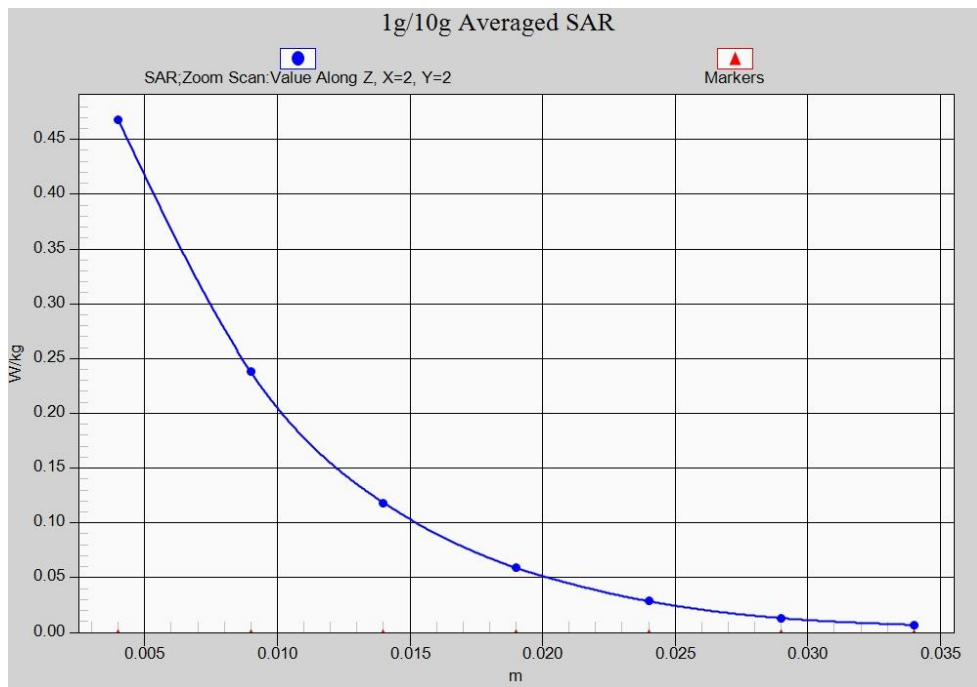Maximum value of SAR (measured) = 0.468 W/kg

Fig.15 Wi-Fi 2450 MHz

Fig.1-1 Z-Scan at power reference point (Wi-Fi 2450 MHz)

ANNEX B SystemVerification Results

2450MHz

Date: 2017-5-20

Electronics: DAE4 Sn786

Medium: Body 2450 MHz

Medium parameters used: f = 2462MHz; σ = 1.968 S/m; ε_r = 51.663; ρ = 1000 kg/m^3

Ambient Temperature: 22.0^{o}C   Liquid Temperature: 21.6^{o}C

Communication System: CW Frequency: 2450 MHz Duty Cycle: 1:1

Probe: EX3DV4 - SN3633 ConvF (7.37, 7.37, 7.37)

System Validation/Area Scan (81x101x1): Interpolated grid: dx=1.000 mm, dy=1.000 mm

Reference Value = 88.636 V/m; Power Drift = -0.06 dB

Fast SAR: SAR(1 g) = 13.0 W/kg; SAR(10 g) = 6.12 W/kg

Maximum value of SAR (interpolated) = 14.5 W/kg

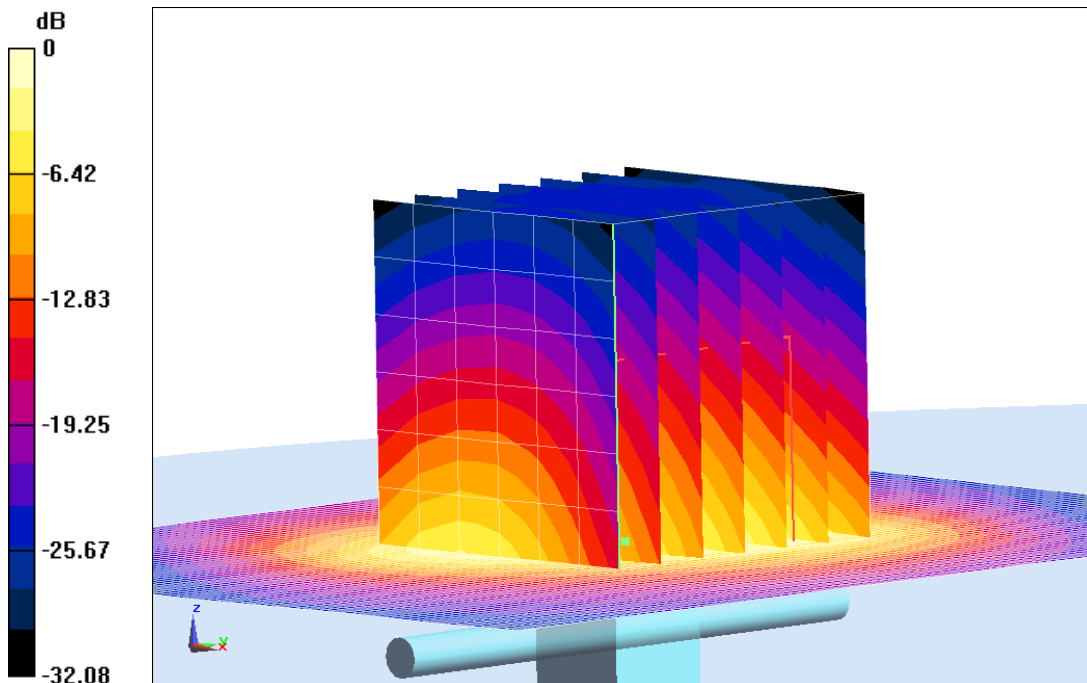**System Validation/Zoom Scan (7x7x7)/Cube 0:** Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 88.636 V/m; Power Drift = -0.06 dB

Peak SAR (extrapolated) = 26.6 W/kg

SAR(1 g) = 13.2 W/kg; SAR(10 g) = 6.16 W/kg

Maximum value of SAR (measured) = 15.2 W/kg

0 dB = 15.2 W/kg = 11.82 dB W/kg

Fig.B.1 validation 2450MHz 250mW

The SAR system verification must be required that the area scan estimated 1-g SAR is within 3% of the zoom scan 1-g SAR.

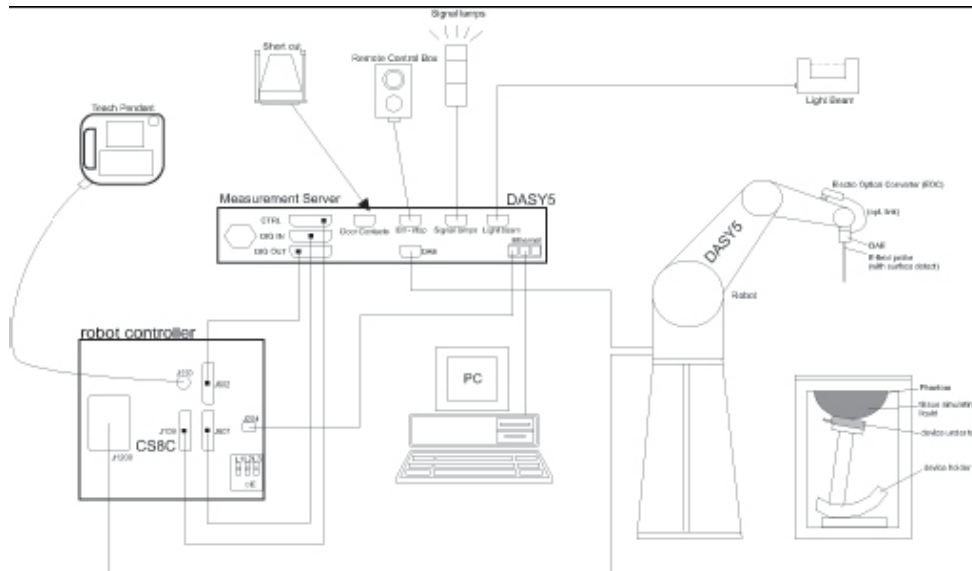**Table B.1 Comparison between area scan and zoom scan for system verification**

Band	Position	Area scan (1g)	Zoom scan (1g)	Drift (%)
2450	Body	13.0	13.2	1.54

ANNEX C SAR Measurement Setup

C.1 Measurement Set-up

DASY5 system for performing compliance tests is illustrated above graphically. This system consists of the following items:

Picture C.1 SAR Lab Test Measurement Set-up

- A standard high precision 6-axis robot (Stäubli TX=RX family) with controller, teach pendant and software. An arm extension for accommodating the data acquisition electronics (DAE).
- An isotropic field probe optimized and calibrated for the targeted measurement.
- A data acquisition electronics (DAE) which performs the signal amplification, signal multiplexing, AD-conversion, offset measurements, mechanical surface detection, collision detection, etc. The unit is battery powered with standard or rechargeable batteries. The signal is optically transmitted to the EOC.
- The Electro-optical converter (EOC) performs the conversion from optical to electrical signals for the digital communication to the DAE. To use optical surface detection, a special version of the EOC is required. The EOC signal is transmitted to the measurement server.
- The function of the measurement server is to perform the time critical tasks such as signal filtering, control of the robot operation and fast movement interrupts.
- The Light Beam used is for probe alignment. This improves the (absolute) accuracy of the probe positioning.
- A computer running WinXP and the DASY5 software.
- Remote control and teach pendant as well as additional circuitry for robot safety such as
- warning lamps, etc.
- The phantom, the device holder and other accessories according to the targeted measurement.

C.2 DASY5 E-field Probe System

The SAR measurements were conducted with the dosimetric probe designed in the classical triangular configuration and optimized for dosimetric evaluation. The probe is constructed using the thick film technique; with printed resistive lines on ceramic substrates. The probe is equipped with an optical multifiber line ending at the front of the probe tip. It is connected to the EOC box on the robot arm and provides an automatic detection of the phantom surface. Half of the fibers are connected to a pulsed infrared transmitter, the other half to a synchronized receiver. As the probe approaches the surface, the reflection from the surface produces a coupling from the transmitting to the receiving fibers. This reflection increases first during the approach, reaches maximum and then decreases. If the probe is flatly touching the surface, the coupling is zero. The distance of the coupling maximum to the surface is independent of the surface reflectivity and largely independent of the surface to probe angle. The DASY5 software reads the reflection durning a software approach and looks for the maximum using 2nd ord curve fitting. The approach is stopped at reaching the maximum.

Probe Specifications:

Model:	**ES3DV3, EX3DV4**
Frequency Range:	**10MHz — 6.0GHz(EX3DV4)**
	10MHz — 4GHz(ES3DV3)
Calibration:	**In head and body simulating tissue at Frequencies from 835 up to 5800MHz**
Linearity:	**± 0.2 dB(30 MHz to 6 GHz) for EX3DV4**
	± 0.2 dB(30 MHz to 4 GHz) for ES3DV3
Dynamic Range:	**10 mW/kg — 100W/kg**
Probe Length:	**330 mm**
Probe Tip Length:	**20 mm**
Body Diameter:	**12 mm**
Tip Diameter:	**2.5 mm (3.9 mm for ES3DV3)**
Tip-Center:	**1 mm (2.0mm for ES3DV3)**
Application:	**SAR Dosimetry Testing Compliance tests of mobile phones Dosimetry in strong gradient fields**

Picture C.2 Near-field Probe

Picture C.3 E-field Probe

C.3 E-field Probe Calibration

Each E-Probe/Probe Amplifier combination has unique calibration parameters. A TEM cell calibration procedure is conducted to determine the proper amplifier settings to enter in the probe parameters. The amplifier settings are determined for a given frequency by subjecting the probe to a known E-field density (1 mW/cm^2) using an RF Signal generator, TEM cell, and RF Power Meter.

The free space E-field from amplified probe outputs is determined in a test chamber. This calibration can be performed in a TEM cell if the frequency is below 1 GHz and inn a waveguide or other methodologies above 1 GHz for free space. For the free space calibration, the probe is placed

in the volumetric center of the cavity and at the proper orientation with the field. The probe is then rotated 360 degrees until the three channels show the maximum reading. The power density readings equates to 1 mW/ cm^2.

E-field temperature correlation calibration is performed in a flat phantom filled with the appropriate simulated brain tissue. The E-field in the medium correlates with the temperature rise in the dielectric medium. For temperature correlation calibration a RF transparent thermistor-based temperature probe is used in conjunction with the E-field probe.

$$SAR = C \frac{\Delta T}{\Delta t}$$

Where:

Δt = Exposure time (30 seconds),

C = Heat capacity of tissue (brain or muscle),

ΔT = Temperature increase due to RF exposure.

$$SAR = \frac{|E|^2 \cdot \sigma}{\rho}$$

Where:

σ = Simulated tissue conductivity,

ρ = Tissue density (kg/m^3).

C.4 Other Test Equipment

C.4.1 Data Acquisition Electronics (DAE)

The data acquisition electronics consist of a highly sensitive electrometer-grade preamplifier with auto-zeroing, a channel and gain-switching multiplexer, a fast 16 bit AD-converter and a command decoder with a control logic unit. Transmission to the measurement server is accomplished through an optical downlink for data and status information, as well as an optical uplink for commands and the clock.

The mechanical probe mounting device includes two different sensor systems for frontal and sideways probe contacts. They are used for mechanical surface detection and probe collision detection.

The input impedance of the DAE is 200 MOhm; the inputs are symmetrical and floating. Common mode rejection is above 80 dB.
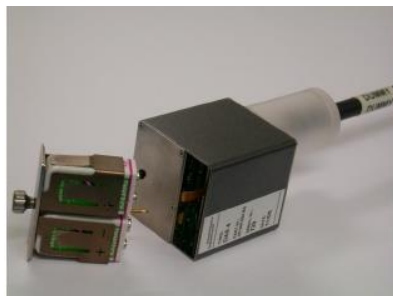
PictureC.4: DAE

C.4.2 Robot

The SPEAG DASY system uses the high precision robots (DASY5: RX160L) type from Stäubli SA (France). For the 6-axis controller system, the robot controller version from Stäubli is used. The Stäubli robot series have many features that are important for our application:

➢ High precision (repeatability 0.02mm)
➢ High reliability (industrial design)
➢ Low maintenance costs (virtually maintenance free due to direct drive gears; no belt drives)
➢ Jerk-free straight movements (brushless synchron motors; no stepper motors)
➢ Low ELF interference (motor control fields shielded via the closed metallic construction shields)

Picture C.5 DASY 5

C.4.3 Measurement Server

The Measurement server is based on a PC/104 CPU broad with CPU (DASY5: 400 MHz, Intel Celeron), chipdisk (DASY5:128MB), RAM (DASY5:128MB). The necessary circuits for communication with the DAE electronic box, as well as the 16 bit AD converter system for optical detection and digital I/O interface are contained on the DASY I/O broad, which is directly connected to the PC/104 bus of the CPU broad.

The measurement server performs all real-time data evaluation of field measurements and surface detection, controls robot movements and handles safety operation. The PC operating system cannot interfere with these time critical processes. All connections are supervised by a watchdog, and disconnection of any of the cables to the measurement server will automatically disarm the robot and disable all program-controlled robot movements. Furthermore, the measurement server is equipped with an expansion port which is reserved for future applications. Please note that this expansion port does not have a standardized pinout, and therefore only devices provided by SPEAG can be connected. Devices from any other supplier could seriously damage the measurement server.

Picture C.6 Server for DASY 5

C.4.4 Device Holder for Phantom

The SAR in the phantom is approximately inversely proportional to the square of the distance between the source and the liquid surface. For a source at 5mm distance, a positioning uncertainty of ±0.5mm would produce a SAR uncertainty of ±20%. Accurate device positioning is therefore crucial for accurate and repeatable measurements. The positions in which the devices must be measured are defined by the standards.

The DASY device holder is designed to cope with the different positions given in the standard. It has two scales for device rotation (with respect to the body axis) and device inclination (with respect to the line between the ear reference points). The rotation centers for both scales is the ear reference point (ERP). Thus the device needs no repositioning when changing the angles.

The DASY device holder is constructed of low-loss

POM material having the following dielectric

parameters: relative permittivity ε =3 and loss tangent δ =0.02. The amount of dielectric material

has been reduced in the closest vicinity of the device, since measurements have suggested that the influence of the clamp on the test results could thus be lowered.

<Laptop Extension Kit>

The extension is lightweight and made of POM, acrylic glass and foam. It fits easily on the upper part of the Mounting Device in place of the phone positioner. The extension is fully compatible with the Twin-SAM and ELI phantoms.

Picture C.7-1: Device Holder

Picture C.7-2: Laptop Extension Kit

C.4.5 Phantom

The SAM Twin Phantom V4.0 is constructed of a fiberglass shell integrated in a table. The shape of the shell is based on data from an anatomical study designed to

Represent the 90th percentile of the population. The phantom enables the dissymmetric evaluation of SAR for both left and right handed handset usage, as well as body-worn usage using the flat phantom region. Reference markings on the Phantom allow the complete setup of all predefined phantom positions and measurement grids by manually teaching three points in the robot. The shell phantom has a 2mm shell thickness (except the ear region where shell thickness increases to 6 mm).

Shell Thickness: 2 ± 0. 2 mm
Filling Volume: Approx. 25 liters
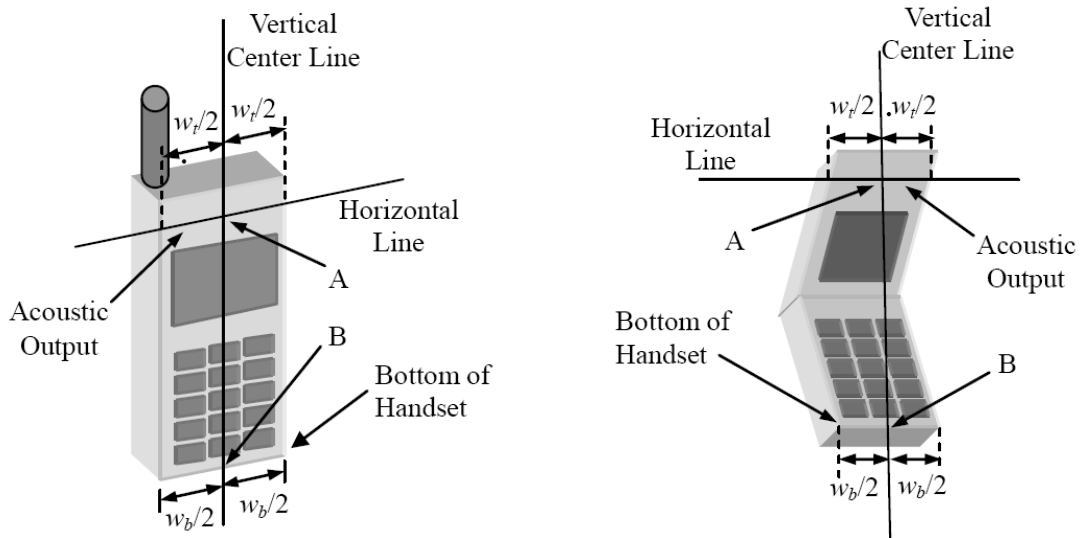Dimensions: 810 x l000 x 500 mm (H x L x W)
Available: Special

Picture C.8: SAM Twin Phantom

ANNEX D Position of the wireless device in relation to the phantom

D.1 General considerations

This standard specifies two handset test positions against the head phantom – the "cheek" position and the "tilt" position.
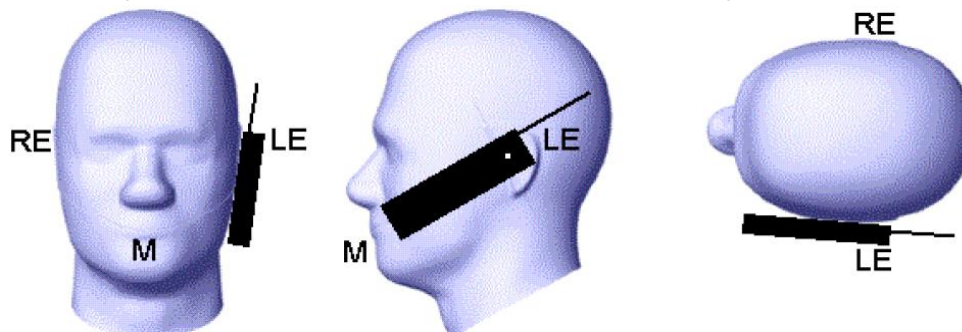

|	
w_t	Width of the handset at the level of the acoustic
w_b	Width of the bottom of the handset
A	Midpoint of the width w_t of the handset at the level of the acoustic output
B	Midpoint of the width w_b of the bottom of the handset

Picture D.1-a Typical "fixed" case handset   Picture D.1-b Typical "clam-shell" case handset


Picture D.2 Cheek position of the wireless device on the left side of SAM
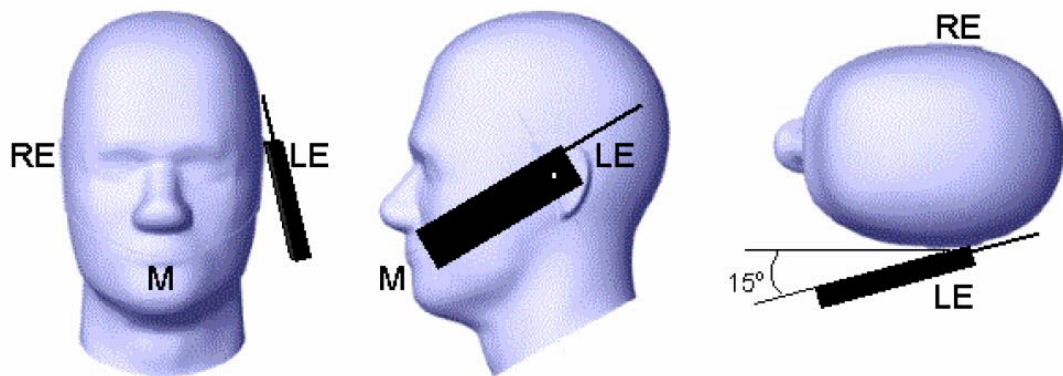
Picture D.3 Tilt position of the wireless device on the left side of SAM

D.2 Body-worn device

A typical example of a body-worn device is a mobile phone, wireless enabled PDA or other battery operated wireless device with the ability to transmit while mounted on a person's body using a carry accessory approved by the wireless device manufacturer.
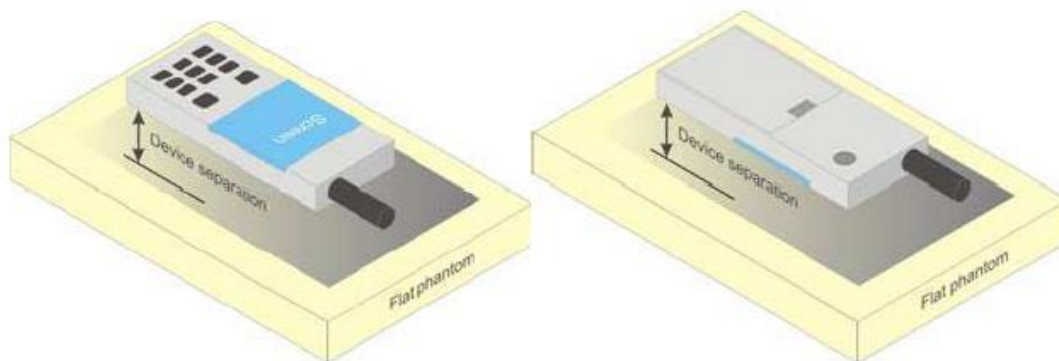
Picture D.4 Test positions for body-worn devices

D.3 Desktop device

A typical example of a desktop device is a wireless enabled desktop computer placed on a table or desk when used.

The DUT shall be positioned at the distance and in the orientation to the phantom that corresponds to the intended use as specified by the manufacturer in the user instructions. For devices that employ an external antenna with variable positions, tests shall be performed for all antenna positions specified. Picture 8.5 show positions for desktop device SAR tests. If the intended use is not specified, the device shall be tested directly against the flat phantom.
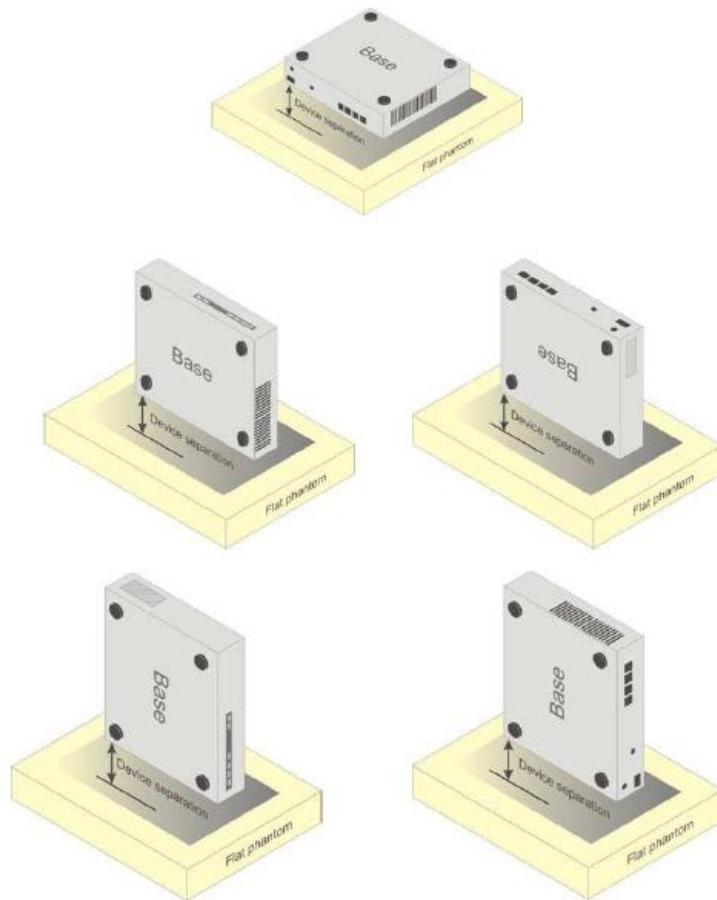
Picture D.5 Test positions for desktop devices

D.4 DUT Setup Photos

Picture D.6

ANNEX E Equivalent Media Recipes

The liquid used for the frequency range of 700-6000 MHz consisted of water, sugar, salt, preventol, glycol monobutyl and Cellulose. The liquid has been previously proven to be suited for worst-case. The Table E.1 shows the detail solution. It's satisfying the latest tissue dielectric parameters requirements proposed by the IEEE 1528 and IEC 62209.

Table E.1: Composition of the Tissue Equivalent Matter

Frequency (MHz)	835 Head	835 Body	1900 Head	1900 Body	2450 Head	2450 Body	5800 Head	5800 Body
Ingredients (% by weight)								
Water	41.45	52.5	55.242	69.91	58.79	72.60	65.53	65.53
Sugar	56.0	45.0	\	\	\	\	\	\
Salt	1.45	1.4	0.306	0.13	0.06	0.18	\	\
Preventol	0.1	0.1	\	\	\	\	\	\
Cellulose	1.0	1.0	\	\	\	\	\	\
Glycol Monobutyl	\	\	44.452	29.96	41.15	27.22	\	\
Diethylenglycol monohexylether	\	\	\	\	\	\	17.24	17.24
Triton X-100	\	\	\	\	\	\	17.24	17.24
Dielectric Parameters Target Value	ε=41.5 σ=0.90	ε=55.2 σ=0.97	ε=40.0 σ=1.40	ε=53.3 σ=1.52	ε=39.2 σ=1.80	ε=52.7 σ=1.95	ε=35.3 σ=5.27	ε=48.2 σ=6.00

Note: There is a little adjustment respectively for 750, 1800 and 2600, based on the recipe of closest frequency in table E.1

ANNEX F System Validation

The SAR system must be validated against its performance specifications before it is deployed. When SAR probes, system components or software are changed, upgraded or recalibrated, these must be validated with the SAR system(s) that operates with such components.

Table F.1: System Validation

Probe SN.	Liquid name	Validation date	Frequency point	Status (OK or Not)
3633	Body 2450MHz	2017-01-30	2450 MHz	OK

ANNEX G DAE Calibration Certificate

DAE4 SN: 786 Calibration Certificate

**Calibration Laboratory of
Schmid & Partner
Engineering AG**
Zeughausstrasse 43, 8004 Zurich, Switzerland

ilac-MRA

S Schweizerischer Kalibrierdienst
C Service suisse d'étalonnage
S Servizio svizzero di taratura
S Swiss Calibration Service

Accredited by the Swiss Accreditation Service (SAS)
**The Swiss Accreditation Service is one of the signatories to the EA
Multilateral Agreement for the recognition of calibration certificates**

Accreditation No.: SCS 0108

Client **CTTL (Auden)**

Certificate No: **DAE4-786_Dec16**

CALIBRATION CERTIFICATE

Object	DAE4 - SD 000 D04 BM - SN: 786
Calibration procedure(s)	QA CAL-06.v29 Calibration procedure for the data acquisition electronics (DAE)
Calibration date:	December 08, 2016

This calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI).
The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

All calibrations have been conducted in the closed laboratory facility: environment temperature (22 ± 3)°C and humidity < 70%.

Calibration Equipment used (M&TE critical for calibration)

Primary Standards	ID #	Cal Date (Certificate No.)	Scheduled Calibration
Keithley Multimeter Type 2001	SN: 0810278	09-Sep-16 (No:19065)	Sep-17

Secondary Standards	ID #	Check Date (in house)	Scheduled Check
Auto DAE Calibration Unit	SE UWS 053 AA 1001	05-Jan-16 (in house check)	In house check: Jan-17
Calibrator Box V2.1	SE UMS 006 AA 1002	05-Jan-16 (in house check)	In house check: Jan-17

	Name	Function	Signature
Calibrated by:	Eric Hainfeld	Technician	
Approved by:	Fin Bomholt	Deputy Technical Manager	

Issued: December 8, 2016

This calibration certificate shall not be reproduced except in full without written approval of the laboratory.

Certificate No: DAE4-786_Dec16   Page 1 of 5

Calibration Laboratory of
Schmid & Partner
  Engineering AG
Zeughausstrasse 43, 8004 Zurich, Switzerland

S Schweizerischer Kalibrierdienst
C Service suisse d'étalonnage
S Servizio svizzero di taratura
   Swiss Calibration Service

Accredited by the Swiss Accreditation Service (SAS)
The Swiss Accreditation Service is one of the signatories to the EA
Multilateral Agreement for the recognition of calibration certificates

Accreditation No.: **SCS 0108**

Glossary

DAE	data acquisition electronics
Connector angle	information used in DASY system to align probe sensor X to the robot coordinate system.

Methods Applied and Interpretation of Parameters

- *DC Voltage Measurement:* Calibration Factor assessed for use in DASY system by comparison with a calibrated instrument traceable to national standards. The figure given corresponds to the full scale range of the voltmeter in the respective range.

- *Connector angle*: The angle of the connector is assessed measuring the angle mechanically by a tool inserted. Uncertainty is not required.

- The following parameters as documented in the Appendix contain technical information as a result from the performance test and require no uncertainty.

  - *DC Voltage Measurement Linearity:* Verification of the Linearity at +10% and -10% of the nominal calibration voltage. Influence of offset voltage is included in this measurement.

  - *Common mode sensitivity:* Influence of a positive or negative common mode voltage on the differential measurement.

  - *Channel separation:* Influence of a voltage on the neighbor channels not subject to an input voltage.

  - *AD Converter Values with inputs shorted:* Values on the internal AD converter corresponding to zero input voltage

  - *Input Offset Measurement:* Output voltage and statistical results over a large number of zero voltage measurements.

  - *Input Offset Current:* Typical value for information; Maximum channel input offset current, not considering the input resistance.

  - *Input resistance:* Typical value for information: DAE input resistance at the connector, during internal auto-zeroing and during measurement.

  - *Low Battery Alarm Voltage:* Typical value for information. Below this voltage, a battery alarm signal is generated.

  - *Power consumption:* Typical value for information. Supply currents in various operating modes.

DC Voltage Measurement

A/D - Converter Resolution nominal

High Range: 1LSB = 6.1μV , full range = -100…+300 mV
Low Range: 1LSB = 61nV , full range = -1…….+3mV

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

Calibration Factors	X	Y	Z
High Range	403.298 ± 0.02% (k=2)	403.491 ± 0.02% (k=2)	403.881 ± 0.02% (k=2)
Low Range	3.96445 ± 1.50% (k=2)	3.96537 ± 1.50% (k=2)	3.95169 ± 1.50% (k=2)

Connector Angle

Connector Angle to be used in DASY system	226.0 ° ± 1 °

Appendix (Additional assessments outside the scope of SCS0108)

1. DC Voltage Linearity

High Range		Reading (µV)	Difference (µV)	Error (%)
Channel X	+ Input	200026.19	-5.79	-0.00
Channel X	+ Input	20005.74	1.53	0.01
Channel X	- Input	-19998.94	6.48	-0.03
Channel Y	+ Input	200029.93	-2.27	-0.00
Channel Y	+ Input	20002.71	-1.40	-0.01
Channel Y	- Input	-20003.56	1.97	-0.01
Channel Z	+ Input	200031.82	-0.21	-0.00
Channel Z	+ Input	20003.07	-0.95	-0.00
Channel Z	- Input	-20004.84	0.72	-0.00

Low Range		Reading (µV)	Difference (µV)	Error (%)
Channel X	+ Input	2002.07	1.48	0.07
Channel X	+ Input	200.89	0.14	0.07
Channel X	- Input	-199.34	-0.07	0.04
Channel Y	+ Input	1999.99	-0.49	-0.02
Channel Y	+ Input	200.10	-0.60	-0.30
Channel Y	- Input	-200.06	-0.69	0.34
Channel Z	+ Input	2000.67	0.22	0.01
Channel Z	+ Input	199.73	-0.77	-0.38
Channel Z	- Input	-201.22	-1.74	0.87

2. Common mode sensitivity

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

	Common mode Input Voltage (mV)	High Range Average Reading (µV)	Low Range Average Reading (µV)
Channel X	200	12.75	10.67
	- 200	-10.14	-11.33
Channel Y	200	20.16	19.71
	- 200	-21.14	-21.51
Channel Z	200	6.53	6.44
	- 200	-9.02	-9.17

3. Channel separation

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

	Input Voltage (mV)	Channel X (µV)	Channel Y (µV)	Channel Z (µV)
Channel X	200	-	-1.43	-3.68
Channel Y	200	10.01	-	-0.12
Channel Z	200	7.49	7.39	-

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