Page : 1 of 67

Issued date : December 15, 2003

FCC ID : PZWKCS

SAR EVALUATION REPORT

Report No.: 24DE0125-HO-5

Applicant : DENSO WAVE INCORPORATED

Type of Equipment : Wireless LAN adapter

Model No. : KCS

FCC ID : PZWKCS

Test standard : FCC47CFR 2.1093

FCC OET Bulletin 65, Supplement C

Test Result : Complied

Max SAR Measured : 0.266W/kg(Body, 2412MHz)

- 1. This test report shall not be reproduced except full or partial, without the written approval of UL Apex Co., Ltd.
- 2. The results in this report apply only to the sample tested.
- 3. This equipment is in compliance with above regulation. We hereby certify that the data contain a true representation of the SAR profile.
- 4. The test results in this test report are traceable to the national or international standards.

Date of test : November 28, 2003

Tested by : M. Shutto

Miyo Ikuta Head Office EMC Lab.

Tetsuo Maeno Site Manager of Head Office EMC Lab.

Page : 2 of 67

Issued date : December 15, 2003

FCC ID : PZWKCS

CONTENTS

	PAGE
SECTION 1 : Client information	3
SECTION 2 : Equipment under test (Wireless LAN adapter)	4
SECTION 3: Requirements for compliance testing defined by the FCC	5
SECTION 4 : Dosimetry assessment setup	5
SECTION 5 : Test system specifications	9
SECTION 6 : Measurement outline	10
SECTION 7 : Test setup of EUT	11
SECTION 8: Measurement uncertainty	15
SECTION 9 : Simulated tissue liquid parameter	16
SECTION 10 : System validation data	17
SECTION 11 : Evaluation procedure	18
SECTION 12 : Exposure limit	19
SECTION 13 : SAR Measurement results	20
SECTION 14 : Equipment & calibration information	21
SECTION 15: References	22
APPENDIX 1 : Photographs of test setup	
APPENDIX 2 : SAR Measurement data	32
APPENDIX 3: Validation Measurement data	
APPENDIX 4: System Validation Dipole (D2450V2,S/N: 713)	
APPENDIX 5: Dosimetric E-Field Probe Calibration (ET3DV6,S/N: 1685)	55

4383-326 Asama-cho, Ise-shi, Mie-ken 516-0021 JAPAN

Page : 3 of 67

Issued date : December 15, 2003

FCC ID : PZWKCS

SECTION 1: Client information

Company Name : DENSO WAVE INCORPORATED

Brand Name : DENSO

Address : 1-1, Showa-cho, Kariya-shi, Aichi-ken 448-8661, Japan

Telephone Number : 81-566-61-3858

Facsimile Number : 81-566-25-4741

Contact Person : Noritaka Hirao

 $4383\text{-}326\ Asama\text{-}cho,\ Ise\text{-}shi,\ Mie\text{-}ken\ 516\text{-}0021\ JAPAN$

Page : 4 of 67

Issued date : December 15, 2003

FCC ID : PZWKCS

SECTION 2 : Equipment under test (Wireless LAN adapter)

2.1 Identification of Wireless LAN adapter

APPLICANT : DENSO WAVE INCORPORATED

Type of Equipment : Wireless LAN adapter

Model No. : KCS

Serial No. : K03633100001C01

Country of Manufacture : Taiwan

Receipt Date of Sample : November 20,2003

Condition of EUT : Production model

Category Identified : Portable device

2.2 Product description of Wireless LAN adapter

Tx Frequency : 2412MHz~2462MHz

Modulation : DSSS

Rating : DC3.3 - 3.5V

Max.Output Power Tested : 15.75 dBm Peak Conducted

Antenna Type : Chip Antenna:YOKOWO YCE-5208DN

4383-326 Asama-cho, Ise-shi, Mie-ken 516-0021 JAPAN

Page : 5 of 67

Issued date : December 15, 2003

FCC ID : PZWKCS

SECTION 3: Requirements for compliance testing defined by the FCC

The US Federal Communications Commission has released the report and order "Guidelines for Evaluating the Environmental Effects of RF Radiation", ET Docket No. 93-62 in August 1996. The order requires routine SAR evaluation prior to equipment authorization of portable transmitter devices, including portable telephones. For consumer products, the applicable limit is 1.6 mW/g for an uncontrolled environment and 8.0 mW/g for an occupational/controlled environment as recommended by the ANSI/IEEE standard C95.1-1992. According to the Supplement C of OET Bulletin 65 "Evaluating Compliance with FCC Guide-lines for Human Exposure to Radio frequency Electromagnetic Fields", released on Jun 29, 2001 by the FCC, the device should be evaluated at maximum output power (radiated from the antenna) under "worst-case" conditions for normal or intended use, incorporating normal antenna operating positions, device peak performance frequencies and positions for maximum RF energy coupling.

1 Specific Absorption Rate (SAR) is a measure of the rate of energy absorption due to exposure to an RF transmitting source (wireless portable device).

2 IEEE/ANSI Std. C95.1-1992 limits are used to determine compliance with FCC ET Docket 93-62.

SECTION 4 : Dosimetry assessment setup

These measurements were performed with the automated near-field scanning system DASY4 from Schmid & Partner Engineering AG (SPEAG). The system is based on a high precision robot (working range greater than 0.9 m), which positions the probes with a positional repeatability of better than +/- 0.02 mm. Special E- and H-field probes have been developed for measurements close to material discontinuity, the sensors of which are directly loaded with a Schottky diode and connected via highly resistive lines to the data acquisition unit. The SAR measurements were conducted with the dosimetry probe ET3DV6, SN: 1685 (manufactured by SPEAG), designed in the classical triangular configuration and optimized for dosimetric evaluation. The probe has been calibrated according to the procedure described in [2] with accuracy of better than +/-10%. The spherical isotropy was evaluated with the procedure described in [3] and found to be better than +/-0.25 dB. The phantom used was the SAM Twin Phantom as described in FCC supplement C, IEE P1528 and CENELEC EN50361.

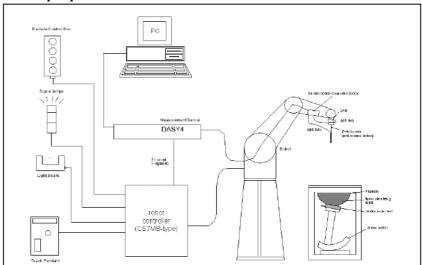
4383-326 Asama-cho, Ise-shi, Mie-ken 516-0021 JAPAN

Page : 6 of 67

Issued date : December 15, 2003

FCC ID : PZWKCS

4.1 Configuration and peripherals



The DASY4 system for performing compliance tests consist of the following items:

- 1. A standard high precision 6-axis robot (Stäubli RX family) with controller and software. An arm extension for accommodating the data acquisition electronics (DAE).
- 2. A dosimetric probe, i.e., an isotropic E-field probe optimized and calibrated for usage in tissue simulating liquid. The probe is equipped with an optical surface detector system.
- 3. A data acquisition electronic (DAE), which performs the signal amplification, signal multiplexing, AD-conversion, offset measurements, mechanical surface detection, collision detection, etc. The unit is battery powered with standard or rechargeable batteries. The signal is optically transmitted to the EOC.
- 4. The Electro-optical converter (EOC) performs the conversion between optical and electrical of the signals for the digital communication to the DAE and for the analog signal from the optical surface detection. The EOC is connected to the measurement server.
- 5. The function of the measurement server is to perform the time critical tasks such as signal filtering, control of the robot operation and fast movement interrupts.
- 6. A probe alignment unit which improves the (absolute) accuracy of the probe positioning.
- 7. A computer operating Windows 2000.
- 8. DASY4 software.
- 9. Remote control with teaches pendant and additional circuitry for robot safety such as warning lamps, etc.
- 10. The SAM twin phantom enabling testing left-hand and right-hand usage.
- 11. The device holder for handheld mobile phones.
- 12. Tissue simulating liquid mixed according to the given recipes.
- 13. Validation dipole kits allowing to validate the proper functioning of the system.

UL Apex Co., Ltd. Head Office EMC Lab.

4383-326 Asama-cho, Ise-shi, Mie-ken 516-0021 JAPAN

Page : 7 of 67

Issued date : December 15, 2003

FCC ID : PZWKCS

4.2 System components

4.2.1 ET3DV6 Probe Specification

Construction:

Symmetrical design with triangular core

Built-in optical fiber for surface detection System

Built-in shielding against static charges

PEEK enclosure material (resistant to organic solvents, e.g., glycol ether)

Calibration:

Basic Broad Band calibration in air from 10 MHz to 2.5 GHz

In brain and muscle simulating tissue at

Frequencies of 450 MHz, 900 MHz, 1.8 GHz and 2.45GHz (accuracy +/-8%)

Frequency:

10 MHz to 3GHz; Linearity: +/-0.2 dB

(30 MHz to 3 GHz)

Directivity:

+/-0.2 dB in brain tissue (rotation around probe axis)

+/-0.4 dB in brain tissue (rotation normal probe axis)

Dynamic Range:

5 mW/g to > 100 mW/g;Linearity: +/-0.2 dB

Optical Surface Detection:

+/-0.2 mm repeatability in air and clear liquids over diffuse reflecting surfaces.

Dimensions:

Overall length: 330 mm (Tip: 16 mm)

Tip length: 16 mm

Body diameter: 12 mm (Body: 12 mm)

Tip diameter: 6.8 mm

Distance from probe tip to dipole centers: 2.7 mm

Application:

General dosimetric up to 3 GHz Compliance tests of mobile phones

Fast automatic scanning in arbitrary phantoms





Inside view of ET3DV6 E-field Probe

4383-326 Asama-cho, Ise-shi, Mie-ken 516-0021 JAPAN

Page : 8 of 67

Issued date : December 15, 2003

FCC ID : PZWKCS

4.2.2 SAM Phantom

Construction:

The shell corresponds to the specifications of the Specific Anthropomorphic Mannequin (SAM) phantom defined in IEEE 1528-200X, CENELEC 50361 and IEC 62209. It enables the dosimetric evaluation of left and right hand phone usage as well as body mounted usage at the flat phantom region. A cover prevents evaporation of the liquid. Reference markings on the phantom allow the complete setup of all predefined phantom positions and measurement grids by manually teaching three points with the robot.

Shell Thickness:

2 +/-0.2 mm

Filling Volume:

Approx. 25 liters

Dimensions:

(H x L x W): 810 x 1000 x 500 mm



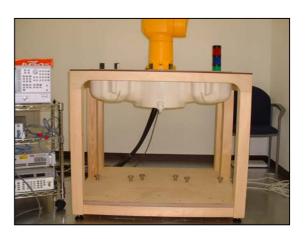
In combination with the SAM Twin Phantom V4.0, the Mounting Device enables the rotation of the mounted transmitter

in spherical coordinates whereby the rotation points is the ear opening. The devices can be easily, accurately, and repeatedly positioned according to the FCC and CENELEC specifications. The device holder can be locked at different phantom locations (left head, right head, flat phantom).

* Note: A simulating human hand is not used due to the complex anatomical and geometrical structure of the hand that may produced infinite number of configurations.

To produce the worst-case condition (the hand absorbs antenna output power), the hand is omitted during the tests.

Device holder couldn't be used at this SAR measurement.



SAM Phantom



Device Holder

4383-326 Asama-cho, Ise-shi, Mie-ken 516-0021 JAPAN

Page : 9 of 67

Issued date : December 15, 2003

FCC ID : PZWKCS

SECTION 5 : Test system specifications

Robot RX60L

Number of Axes : 6
Payload : 1.6 kg
Reach : 800mm
Repeatability : +/-0.025mm
Control Unit : CS7M
Programming Language : V+

Manuafacture : Stäubli Unimation Corp. Robot Model: RX60

DASY4 Measurement sever

Features: 166MHz low power Pentium MMX

32MB chipdisk and 64MB RAM Serial link to DAE (with watchdog supervision)

16 Bit A/D converter for surface detection system

Two serial links to robot (one for real-time communication which is supervised

by watchdog)

Ethernet link to PC (with watchdog supervision)

Emergency stop relay for robot safety chainTwo expansion slots for future

applications

Manufacture : Schimid & Partner Engineering AG

Data Acquisition Electronic (DAE)

Features : Signal amplifier, multiplexer, A/D converter and control logic

Serial optical link for communication with DASY4 embedded system (fully remote controlled) 2 step probe touch detector for mechanical surface detection

and emergency robot stop (not in -R version)

Measurement Range : $1 \mu V$ to > 200 mV (16 bit resolution and two range settings: 4mV,

400mV)

Input Offset voltage : $$<1~\mu V$ (with auto zero)$

Input Resistance : $200 \text{ M}\Omega$

Battery Power : > 10 h of operation (with two 9 V accus)

Dimension : 60 x 60 x 68 mm

Manufacture : Schimid & Partner Engineering AG

Software

Item : Dosimetric Assesment System DASY4

Type No. : SD 000 401A, SD 000 402A

Software version No. : 4.1

Manufacture / Origin : Schimid & Partner Engineering AG

E-Field Probe

 Model
 :
 ET3DV6

 Serial No.
 :
 1685

Construction : Triangular core fiber optic detection system

Frequency: 10 MHz to 6 GHz

Linearity : +/-0.2 dB (30 MHz to 3 GHz)

Manufacture : Schimid & Partner Engineering AG

Phantom

Type : SAM Twin Phantom V4.0

Shell Material:FiberglassThickness:2.0 +/-0.2 mmVolume:Approx. 20 liters

Manufacture : Schimid & Partner Engineering AG

UL Apex Co., Ltd. Head Office EMC Lab.

4383-326 Asama-cho, Ise-shi, Mie-ken 516-0021 JAPAN

Page : 10 of 67

Issued date : December 15, 2003

FCC ID : PZWKCS

SECTION 6 : Measurement outline

This EUT was manufactured by DENSO and will be inserted into only Bar-code Handy Terminal which was manufactured by DENSO.

The detail of host device that we used for SAR testing is shown in the following.

6.1 Information of PC

Type of Equipment : Bar-code Handy Terminal

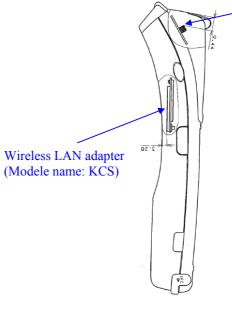
Model No. : BHT-7500W

Serial No. : None

Manufacture : DENSO CORPORATION







Transmitting antenna

UL Apex Co., Ltd. Head Office EMC Lab.

4383-326 Asama-cho, Ise-shi, Mie-ken 516-0021 JAPAN

Page : 11 of 67

Issued date : December 15, 2003

FCC ID : PZWKCS

SECTION 7 : Test setup of EUT

7.1 Photographs of test setup

We tested the Bar-code Handy Terminal (Model No.: BHT-7500W) with which this EUT was inserted. When users operate or carry the Bar-code Handy Terminal, it could be considered to touch or get close to their bodies. In order to assume this situation, we performed the test at the following positions. Please refer to "APPENDIX 1" for more details.

1.Front : The test was performed in touch with front surface of Bar-code Handy Terminal to the flat phantom.

2.Back : The test was performed in touch with back surface of Bar-code Handy Terminal to the flat phantom.

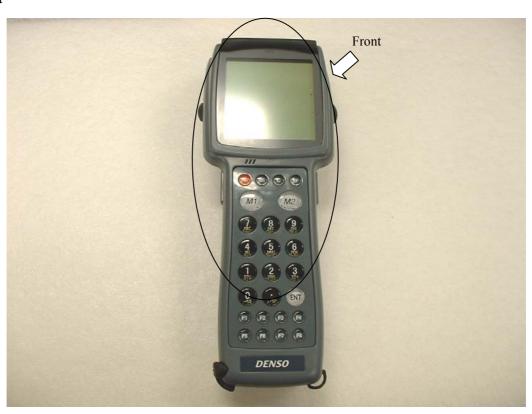
3. Right Side : The test was performed in touch with right side of Bar-code Handy Terminal to the flat phantom.

4.Left Side : The test was performed in touch with left side of Bar-code Handy Terminal to the flat phantom.

5.Top : The test was performed in touch and distanced 5mm, 10mm and 15mm with top of Bar-code Handy

Terminal to the flat phantom.

1. Front



UL Apex Co., Ltd. Head Office EMC Lab.

4383-326 Asama-cho, Ise-shi, Mie-ken 516-0021 JAPAN

Page : 12 of 67

Issued date : December 15, 2003

FCC ID : PZWKCS

2. Back



3. Right Side



UL Apex Co., Ltd. Head Office EMC Lab.

 $4383\text{-}326\ Asama\text{-}cho,\ Ise\text{-}shi,\ Mie\text{-}ken\ 516\text{-}0021\ JAPAN$

Page : 13 of 67

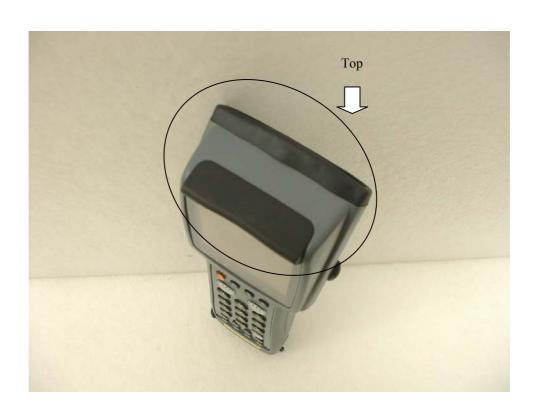
Issued date : December 15, 2003

FCC ID : PZWKCS

4. Left Side



5. Top



UL Apex Co., Ltd. Head Office EMC Lab.

4383-326 Asama-cho, Ise-shi, Mie-ken 516-0021 JAPAN

Page : 14 of 67

Issued date : December 15, 2003

FCC ID : PZWKCS

7.2 EUT Tune-up procedure

We determined following conditions;

Transmitter was continuous mode.

Crest Factor = 1

Frequency channel were low, middle and high (2412MHz, 2437MHz and 2462MHz)

7.3 Distance between Bar-code Handy Terminal and Phantom

The position for the highest SAR value of this EUT was at "Top" position.

The measurement was performed with the distance, 5mm, 10mm, and 15mm to check if the distance 0mm may not have the worst value. As a result, the distance 0mm had the worst value.

4383-326 Asama-cho, Ise-shi, Mie-ken 516-0021 JAPAN

Page : 15 of 67

Issued date : December 15, 2003

FCC ID : PZWKCS

SECTION 8: Measurement uncertainty

The uncertainty budget has been determined for the DASY4 measurement system according to the NIS81 [13] and the

NIST1297 [6] documents and is given in the following Table.

Error Description	Uncertainty	Probability	divisor	(ci)1	Standard	vi
	value ± %	distribution		1g	Uncertainty	or
					(1g)	veff
Measurement System						
Probe calibration	±4.8	Normal	1	1	±4.8	∞
Axial isotropy of the probe	±4.7	Rectangular	$\sqrt{3}$	$(1-c_p)^{1/2}$	±1.9	∞
Spherical isotropy of the probe	±9.6	Rectangular	$\sqrt{3}$	(cp)1/2	±3.9	∞
Boundary effects	±1.0	Rectangular	√3	1	±0.6	∞
Probe linearity	±4.7	Rectangular	$\sqrt{3}$	1	±2.7	∞
Detection limit	±1.0	Rectangular	$\sqrt{3}$	1	±0.6	∞
Readout electronics	±1.0	Normal	1	1	±1.0	∞
Response time	±0.8	Rectangular	$\sqrt{3}$	1	±0.5	∞
Integration time	±2.6	Rectangular	$\sqrt{3}$	1	±1.5	∞
RF ambient conditions	±3.0	Rectangular	$\sqrt{3}$	1	±1.7	∞
Mech. constraints of robot	±0.4	Rectangular	$\sqrt{3}$	1	±0.2	∞
Probe positioning	±2.9	Rectangular	$\sqrt{3}$	1	±1.7	∞
Extrap. and integration	±1.0	Rectangular	$\sqrt{3}$	1	±0.6	∞
Test Sample Related						
Device positioning	±2.9	Rectangular	$\sqrt{3}$	1	±2.9	6
Device holder uncertainty	±3.6	Rectangular	$\sqrt{3}$	1	±3.6	4
Power drift	±5.0	Rectangular	$\sqrt{3}$	1	±2.9	∞
Phantom and Setup						
Phantom uncertainty	±4.0	Rectangular	$\sqrt{3}$	1	±2.3	∞
Liquid conductivity (target)	±5.0	Rectangular	$\sqrt{3}$	0.64	±1.8	∞
Liquid conductivity (meas.)	±5.0	Rectangular	$\sqrt{3}$	0.64	±3.7	∞
Liquid permittivity (target)	±10.0	Rectangular	$\sqrt{3}$	0.6	±3.5	∞
Liquid permittivity (meas.)	±10.0	Rectangular	$\sqrt{3}$	0.6	±1.7	∞
Combined Standard Uncertainty	X7				±11.26	
Expanded Uncertainty (k=2)	<u>y</u>		+	<u> </u>	±11.26 ±22.5	+

 $4383\text{-}326\ Asama\text{-}cho,\ Ise\text{-}shi,\ Mie\text{-}ken\ 516\text{-}0021\ JAPAN$

Page : 16 of 67

Issued date : December 15, 2003

FCC ID : PZWKCS

SECTION 9 : Simulated tissue liquid parameter

8.1 Simulated Tissue Liquid Parameter confirmation

The dielectric parameters were checked prior to assessment using the HP85070D dielectric probe kit. The dielectric parameters measurement are reported in each correspondent section.

8.1.1 Head 2450MHz

Type of liquid : Head 2450 MHz

Ambient temperature (deg.c.) : 24.5 Relative Humidity (%) : 48 Lquid depth (cm) : 15.9

Date : November 28,2003

Measured By : Miyo Ikuta

DIELECTRIC PARAMETERS MEASUREMENT RESULTS											
Liquid Temp [deg.c]		Parameters	Target Value	Measured	Deviation [%]	Limit [%]					
Before	After										
23.2	23.2	Relative Permittivity er	39.2	35.9	-8.4	+/-10					
23.2	23.2	Coductivity σ [mho/m]	1.80	1.87	3.9	+/-5					

8.1.2 Muscle 2450MHz

Type of liquid : Muscle 2450 MHz

Ambient temperature (deg.c.) : 24.5 Relative Humidity (%) : 41 Liquid depth (cm) : 15.6

> Date : November 28,2003 Measured By : Miyo Ikuta

DIELECTRIC PARAMETERS MEASUREMENT RESULTS Liquid Temp [deg.c] Target Value Deviation [%] Limit [%] **Parameters** Measured Before After Relative Permittivity 52.7 50.2 -4.7+/-10er 23.0 23.0 Coductivity 1.95 1.93 -1.0 +/-5 σ [mho/m]

8.2 Simulated Tissues

Ingredient	MiXTURE(%)						
	Head 2450MHz	Muscle 2450MHz					
Water	45.0	69.83					
DGMBE	55.0	30.17					

Note:DGMBE(Diethylenglycol-monobuthyl ether)

UL Apex Co., Ltd. Head Office EMC Lab.

4383-326 Asama-cho, Ise-shi, Mie-ken 516-0021 JAPAN

Page : 17 of 67

Issued date : December 15, 2003

FCC ID : PZWKCS

SECTION 10: System validation data

Prior to the assessment, the system validation kit was used to test whether the system was operating within its specifications of $\pm 10\%$. The validation results are tabulated below. Please refer to APPENDIX 3.

Type of liquid : **HEAD 2450MHz**Frequency : **2450MHz**

Frequency : 2450 Liquid depth (cm) : 15.9 Ambient temperature (deg.c.) : 24.5 Relative Humidity (%) : 48

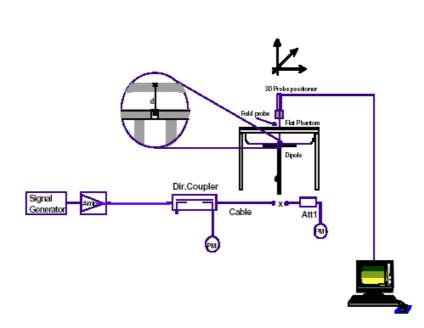
Dipole : **D2450V2** SN:713

Power : 250mW

Date : November 28,2003 Measured By : Miyo Ikuta

	SYSTEM PERFORMANCE CHECK										
	Liquid (HEAD 2450MHz)							System dipole validation target & measured			
Liquid	l Temp	Relative P	ermittivity	Condu	ictivity			Deviation	Limit		
[deg	[deg.c.] εr		r	σ [mho/m]		SAR 1g [W/kg]		[%]	[%]		
Before	After	Target	Measured	Target	Measured	Target	Measured				
23.2	23.2	39.2	35.9	1.80	1.87	13.1	13.5	3.1	+/-10		

Note: Please refer to Attachment for the result representation in plot format





2450MHz System performance check setup

Test system for the system performance check setup diagram

UL Apex Co., Ltd. Head Office EMC Lab.

4383-326 Asama-cho, Ise-shi, Mie-ken 516-0021 JAPAN

Page : 18 of 67

Issued date : December 15, 2003

FCC ID : PZWKCS

SECTION 11: Evaluation procedure

The evaluation was performed with the following procedure:

Step 1: Measurement of the SAR value at a fixed location above the ear point or central position of flat phantom was used as a reference value for assessing the power drop.

Step 2: The SAR distribution at the exposed side of head or body position was measured at a distance of each device from the inner surface of the shell. The area covered the entire dimension of the EUT(180 x 260) and the horizontal grid spacing was 20 mm x 20 mm. Based on these data, the area of the maximum absorption was determined by spline interpolation.

- **Step 3:** Around this point found in the Step 2 (area scan), a volume of 32 mm x 32 mm x 30 mm was assessed by measuring 5 x5 x 7 points. And for any secondary peaks found in the Step2 which are within 2dB of maximum peak and not with this Step3 (Zoom scan) is repeated. On the basis of this data set, the spatial peak SAR value was evaluated under the following procedure:
- 1. The data at the surface were extrapolated, since the center of the dipoles is 2.7 mm away from the tip of the probe and the distance between the surface and the lowest measuring point is 1.3 mm. The extrapolation was based on a least square algorithm [4]. A polynomial of the fourth order was calculated through the points in z-axes. This polynomial was then used to evaluate the points between the surface and the probe tip.
- 2. The maximum interpolated value was searched with a straightforward algorithm. Around this maximum the SAR values averaged over the spatial volumes (1 g or 10 g) were computed by the 3D-Spline interpolation algorithm. The 3D-Spline is composed of three one-dimensional splines with the "Not a knot"-condition (in x, y and z-directions) [4], [5]. The volume was integrated with the trapezoidal-algorithm. One thousand points (10 x 10 x 10) were interpolated to calculate the average.
- 3. All neighboring volumes were evaluated until no neighboring volume with a higher average value was found.

Step 4: Re-measurement of the SAR value at the same location as in Step 1. It is measured SAR-drift(the difference between the SAR measured in Step 4 and Step 1)

4383-326 Asama-cho, Ise-shi, Mie-ken 516-0021 JAPAN

Page : 19 of 67

Issued date : December 15, 2003

FCC ID : PZWKCS

SECTION 12: Exposure limit

(A) Limits for Occupational/Controlled Exposure (W/kg)

Spatial Average (averaged over the whole body)	Spatial Peak (averaged over any 1g of tissue)	Spatial Peak (hands/wrists/feet/ankles averaged over 10g)
0.4	8.0	20.0

(B) Limits for General population/Uncontrolled Exposure (W/kg)

	1 \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \			
Spatial Average	Spatial Peak	Spatial Peak		
(averaged over the whole body	(averaged over any 1g of tissue)	(hands/wrists/feet/ankles averaged over 10g)		
0.08	1.6	4.0		

Occupational/Controlled Environments: are defined as locations where there is exposure that may be incurred by people who are aware of the potential for exposure, (i.e. as a result of employment or occupation).

General Population/Uncontrolled Environments: are defined as locations where there is the exposure of individuals who have no knowledge or control of their exposure.

NOTE:GENERAL POPULATION/UNCONTROLLED EXPOSURE SPATIAL PEAK(averaged over any 1g of tissue) LIMIT 1.6 W/kg

4383-326 Asama-cho, Ise-shi, Mie-ken 516-0021 JAPAN

Page : 20 of 67

Issued date : December 15, 2003

FCC ID : PZWKCS

SECTION 13: SAR Measurement results

12.1 Conducted power measurement results

Date : November 28,2003 Measured By : Miyo Ikuta

	CONDUCTED POWER MEASUREMENT RESULTS											
	Before				After							
Frequency	Reading	Att.	Cable loss	Result	Convert	Reading	Att.	Cable loss	Result	Convert	Deviation	Limit
[MHz]	[dBm]	[dB]	[dB]	[dBm]	[mW]	[dBm]	[dB]	[dB]	[dBm]	[mW]	[%]	[%]
2412	3.8	10	1.95	15.75	37.6	3.7	10	1.95	15.65	36.7	-2.3	+/-5
2437	3.4	10	1.95	15.35	34.3	3.2	10	1.95	15.15	32.7	-4.5	+/-5
2462	3.2	10	1.95	15.15	32.7	3.2	10	1.95	15.15	32.7	0.0	+/-5

12.2 Body 2450MHz SAR

Liquid Depth (cm) : 15.6 Model : KCS

Parameters : $\epsilon_r = 50.2$, $\sigma = 1.93$ Serial No. : **K03633100001C01**

Ambient Temperature[deg.c.] : 24.5 Modulation : DSSS Relative Humidity (%) : 41 Crest factor : 1

Date : November 28,2003

Measured By : Miyo Ikuta

	BODY SAR MEASUREMENT RESULTS										
Frequ	iency	Phantom Section	Е	UT Set-up Conditi	Set-up Conditions		mp.[deg.c]	SAR(1g) [W/kg]			
Channel	[MHz]		Antenna	Position	Separation [mm]	Before	After	Maximum value of multi-peak)			
Mid	2437	Flat	Fixed	Front	0	22.7	22.7	0.0526			
Mid	2437	Flat	Fixed	Back	0	22.6	22.6	0.145			
Mid	2437	Flat	Fixed	Right Side	0	22.6	22.6	0.0586			
Mid	2437	Flat	Fixed	Left Side	0	22.6	22.6	0.0714			
Mid	2437	Flat	Fixed	Тор	0	22.7	22.6	0.21			
Low	2412	Flat	Fixed	Top	0	22.6	22.6	0.266			
High	2462	Flat	Fixed	Тор	0	22.9	22.9	0.19			
Low	2412	Flat	Fixed	Тор	5	22.6	22.6	0.216			
Low	2412	Flat	Fixed	Тор	10	22.6	22.6	0.118			
Low	2412	Flat	Fixed	Top	15	22.6	22.6	0.0635			
Spatia	ANSI / IEEE C95.1 1992 - SAFETY LIMIT Body SAR: 1.6 W/kg Spatial Peak Uncontrolled Exposure / General Population (averaged over 1 gram)										

^{*} The position of EUT of the highest SAR value is touch to the flat phantom at Top position and 2412MHz.

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4383-326 Asama-cho, Ise-shi, Mie-ken 516-0021 JAPAN

Page : 21 of 67

Issued date : December 15, 2003

FCC ID : PZWKCS

SECTION 14: Equipment & calibration information

Name of CE and the second	Manager	Madalassakas	Contal arrank ar	Calibration			
Name of Equipment	Manufacture	Model number	Serial number	Last Cal	due date		
Power Meter	Agilent	E4417A	GB41290639	2003/11/12	2004/11/11		
Power Sensor	Agilent	E9327A	US40440544	2003/02/21	2004/02/20		
Power Sensor	Agilent	E9327A	US40440545	2003/03/18	2004/03/17		
S-Parameter Network Analyzer	Agilent	E8358A	US41080381	2003/08/13	2004/08/12		
Signal Generator	Rohde&Schwarz	SML03	100331	2003/09/11	2004/09/10		
RF Amplifier	OPHIR	5056F	1005	2003/02/06	2004/02/05		
Dosimetric E-Field Probe	Schmid&Partner Engineering AG	ET3DV6	1685	2003/10/10	2004/10/09		
Data Acquisition Electronics	Schmid&Partner Engineering AG	DAE3 V1	509	2003/04/10	2004/04/09		
Robot,SAM Phantom	Schmid&Partner Engineering AG	DASY4	I021834	N/A	N/A		
Attenuator	HIROSE ELECTRIC CO.,LTD.	AT-120	901247	2003/02/03	2004/02/02		
Attenuator	Orient Microwave	BX10-0476-00	-	2003/03/31	2004/03/30		
Microwave Cable	Storm	-	90-011-080/03-04- 001	2003/04/30	2004/04/29		
2450MHz System Validation Dipole	Schmid&Partner Engineering AG	D2450V2	713	2002/11/15	2004/11/14		
Dual Directional Coupler	N/A	Narda	03702	N/A	N/A		
Head 2450MHz	N/A	N/A	N/A	N/A	N/A		
Body 2450MHz	N/A	N/A	N/A	N/A	N/A		

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Page : 22 of 67

Issued date : December 15, 2003

FCC ID : PZWKCS

SECTION 15: References

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4383-326 Asama-cho, Ise-shi, Mie-ken 516-0021 JAPAN

Page : 23 of 67

Issued date : December 15, 2003

FCC ID : PZWKCS

APPENDIX 1: Photographs of test setup

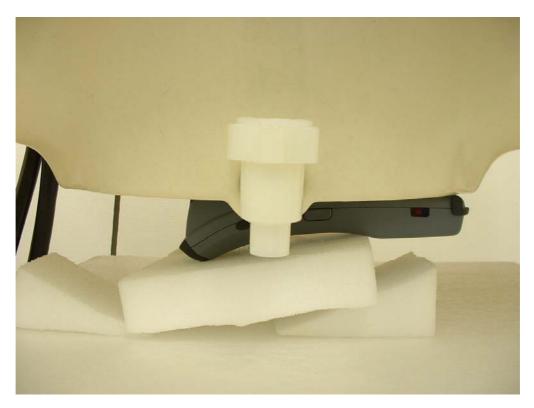
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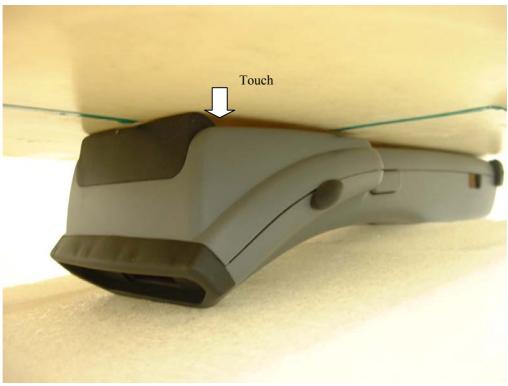
Page : 24 of 67

Issued date : December 15, 2003

FCC ID : PZWKCS

Front





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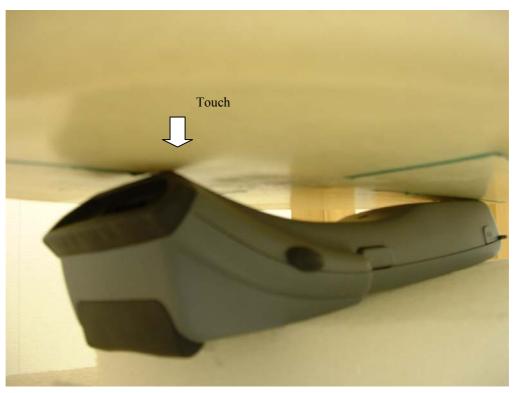
Page : 25 of 67

Issued date : December 15, 2003

FCC ID : PZWKCS

Back





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4383-326 Asama-cho, Ise-shi, Mie-ken 516-0021 JAPAN

: 26 of 67 Page

: December 15, 2003 Issued date

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Right Side





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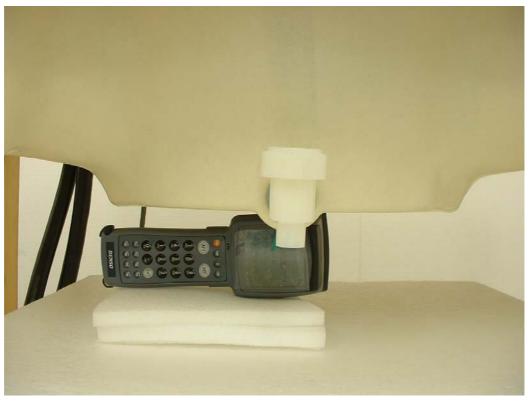
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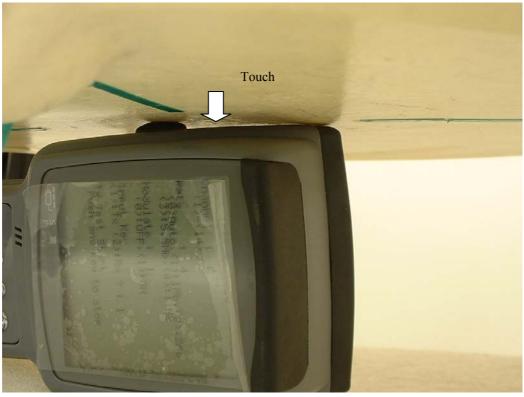
Page : 27 of 67

Issued date : December 15, 2003

FCC ID : PZWKCS

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Page : 28 of 67

: December 15, 2003 Issued date

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Top 0mm





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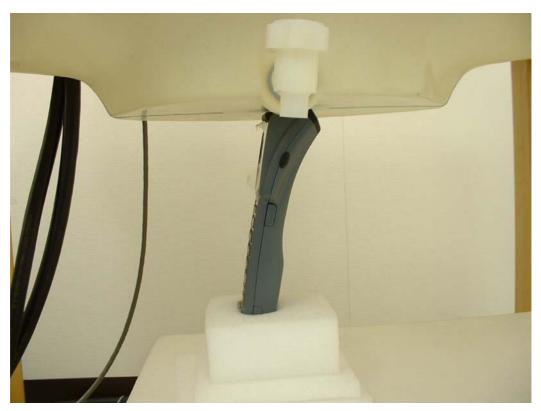
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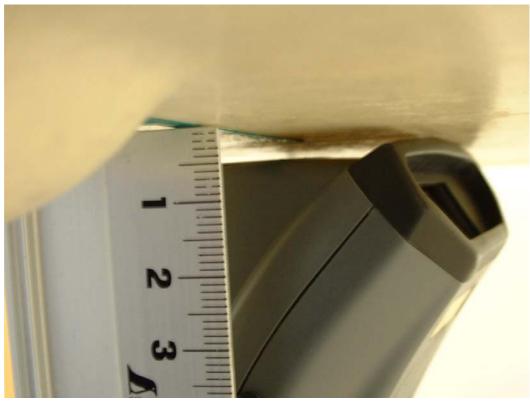
: 29 of 67 Page

: December 15, 2003 Issued date

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Top 5mm





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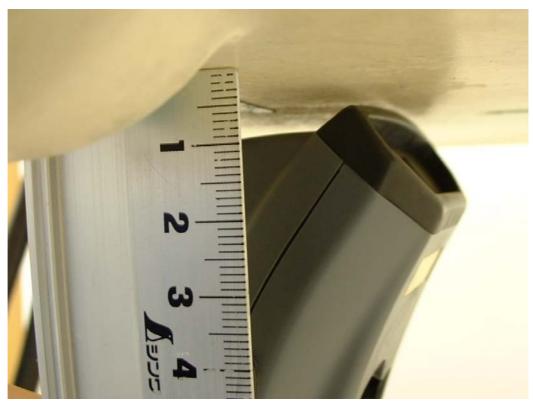
: 30 of 67 Page

: December 15, 2003 **Issued date**

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Top 10mm





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