

# **FCC SAR TEST REPORT**

**APPLICANT** 

SZ DJI TECHNOLOGY CO., LTD

**PRODUCT NAME** 

Remote Control

**MODEL NAME** 

NPVT581

TRADE NAME

DJI

**BRAND NAME** 

DJI

FCC ID

SS3-WM300U58G

STANDARD(S)

47CFR 2.1093

IEEE 1528-2013

**ISSUE DATE** 

2014-10-16

SHENZHEN MORLAB



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FL1-3, Building A, FeiYang Science Park, No.8 LongChang Road, Block67, BaoAn District, ShenZhen , GuangDong Province, P. R. China Http://www.morlab.com E-mail: service@morlab.cn

Tel: 86-755-36698555

Fax: 86-755-36698525



## DIRECTORY

TEST REPORT DECLARATION			<u></u>			4
1. TECHNICAL INFORMATION	······					···· 5
1.1 IDENTIFICATION OF APPLICANT	<u>,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,</u>	•••••••	<u></u>		· · · · · · · · · · · · · · · · · · ·	5
1.2 IDENTIFICATION OF MANUFACTURER						5
1.3 EQUIPMENT UNDER TEST (EUT)						5
1.3.1 PHOTOGRAPHS OF THE EUT	N			······		5
1.3.2 IDENTIFICATION OF ALL USED EUT						5
1.4 APPLIED REFERENCE DOCUMENTS	<u>,                                    </u>				ø	6
1.5 DEVICE CATEGORY AND SAR LIMITS						6
2. SPECIFIC ABSORPTION RATE (SAR	)			<u>~</u>		7
2.1 Introduction			<u>.</u>			7
2.2 SAR DEFINITION						7
3. SAR MEASUREMENT SETUP	a			<u> </u>		8
ORL MO SE STAR	ORL	Mor	~B	JLAB	ORL	
3.1 THE MEASUREMENT SYSTEM				70	4	8
3.2 PROBE	, <u>10</u>	e			, , , , , ,	8
3.3 PROBE CALIBRATION PROCESS						
3.3.1 DOSIMETRIC ASSESSMENT PROCEDUR	RE		Ø		ov	10
3.3.2 FREE SPACE ASSESSMENT PROCEDU	RE					10
3.3.3 TEMPERATURE ASSESSMENT PROCED	URE					10
3.4 PHANTOM	<u> </u>		·		×	11
3.5 DEVICE HOLDER······						
4. TISSUE SIMULATING LIQUIDS			40			12
Me all class don't	We.	o.B	QLA.	MORL	We.	OB.
5. UNCERTAINTY ASSESSMENT	A <sup>D</sup> .of	gler M	0,	, William California	, OR1	13
AL TOTAL TANK I ACCOUNT IN	N.D	QLAE.	MORLE	III C	68	<u>13</u>
5.1 UNCERTAINTY EVALUATION FOR E	IIT CAD T	EST.	\$ N	LAB	ORLA	13
5.2 UNCERTAINTY FOR SYSTEM PERF						_
J.Z GROCK MINT I TOK STOTEWIFERF	CIVIMINO	- CHECK!	0.0			14



6. SAR MEASUREMENT EVALUATION	<u>16</u>
6.1 SYSTEM SETUP	16
6.2 VALIDATION RESULTS	17
7. OPERATIONAL CONDITIONS DURING TEST	18
7.1 Body-worn Configurations	18
7.2 MEASUREMENT PROCEDURE······	18
7.1 BODY-WORN CONFIGURATIONS	19
8. MEASUREMENT OF CONDUCTED OUTPUT POWER	20
9. TEST RESULTS LIST	<u> 21</u>
ANNEX A GRAPH TEST RESULTS	<u>23</u>
ANNEX B GENERAL INFORMATION	42

3	Change History				
Issue	Date	Reason for change			
1.0	2014-10-16	First edition	A Park		
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## **TEST REPORT DECLARATION**

Applicant	SZ DJI TECHNOLOGY CO., LTD			
Applicant Address	17th floor, West Wing, Skyworth Semiconductor Design Building NO.18 Gaoxin South 4th Ave, Nanshan District, Shenzhen, China			
Manufacturer	SZ DJI TECHNO	LOGY CO., LTD		
Manufacturer Address	17th floor, West Wing, Skyworth Semiconductor Design Building NO.18 Gaoxin South 4th Ave, Nanshan District, Shenzhen, China			
Product Name	Remote Control			
Model Name	NPVT581			
Brand Name	DJI			
HW Version	1.01			
SW Version	1.0.2.24			
Test Standards	47CFR 2.1093; IEEE 1528-2013			
Test Date	2014-10-10			
The Highest Reported	Hand	0.032W/kg(10g)		
SAR(W/kg)	SAR(W/kg) Body 0.098W/kg(1g)			

Tested by

Reviewed by

Peng Huarui

Approved by



### 1. TECHNICAL INFORMATION

Note: the Following data is based on the information by the applicant.

#### 1.1 Identification of Applicant

Company Name:	SZ DJI TECHNOLOGY CO., LTD
Address:	17th floor, West Wing, Skyworth Semiconductor Design Building
B ORLAN MORE	NO.18 Gaoxin South 4th Ave, Nanshan District, Shenzhen, China

#### 1.2 Identification of Manufacturer

Company Name:	SZ DJI TECHNOLOGY CO., LTD
Address:	17th floor, West Wing, Skyworth Semiconductor Design Building
E N. SLAE JORLA	NO.18 Gaoxin South 4th Ave, Nanshan District, Shenzhen, China

## 1.3 Equipment Under Test (EUT)

Model Name:	NPVT581
Trade Name:	DJI 10 HAR HORE HIS ALLE
Brand Name:	DJI north the no
Hardware Version:	1.01
Software Version:	1.0.2.24
Tx Frequency Bands:	5728-5844MHz
Uplink Modulations:	GFSK 40 40 40 40 40 40 40 40 40 40 40 40 40
DTM:	Not support
Antenna type:	External Antenna
Development Stage:	Identical prototype
Hotspot function:	Not Support
	The state of the s

#### 1.3.1 Photographs of the EUT

Please refer to the External Photos for the Photos of the EUT

#### 1.3.2 Identification of all used EUT

The EUT identity consists of numerical and letter characters, the letter character indicates the test sample, and the Following two numerical characters indicate the software version of the test sample.

EUT Identity	Hardware Version	Software Version
1#	1.01	1.0.2.24





#### 1.4 Applied Reference Documents

Leading reference documents for testing:

No.	Identity	Document Title		
IRI T	47 CFR§2.1093	Radiofrequency Radiation Exposure Evaluation: Portable		
	No.	Devices		
2	IEEE 1528-2013	IEEE Recommended Practice for Determining the Peak		
	TLAB TORLY MO	Spatial-Average Specific Absorption Rate (SAR) in the		
	HOPE IN SLAE	Human Head from Wireless Communications Devices:		
	ORLA" MORE	Measurement Techniques		
3	KDB 447498 D01v05r02	General RF Exposure Guidance		
10	KDB 941225 D07v01r01	UMPC Mini Tablet		
11	KDB 865664 D01v01r02	SAR Measurement 100 MHz to 6 GHz		
12	KDB 865664 D02v01r01	SAR Reporting		

#### 1.5 Device Category and SAR Limits

This device belongs to portable device category because its radiating structure is allowed to be used within 20 centimeters of the body of the user. Limit for General Population/Uncontrolled exposure should be applied for this device, it is 1.6 W/kg as averaged over any 1 gram of tissue for body, and 4.0W/kg as averaged over any 10 grams of tissue for hands, wrists, feet and ankles.



## 2. SPECIFIC ABSORPTION RATE (SAR)

#### 2.1 Introduction

SAR is related to the rate at which energy is absorbed per unit mass in an object exposed to a radio field. The SAR distribution in a biological body is complicated and is usually carried out by experimental techniques or numerical modeling. The standard recommends limits for two tiers of groups, occupational/controlled and general population/uncontrolled, based on a person's awareness and ability to exercise control over his or her exposure. In general, occupational/controlled exposure limits are Middle than the limits for general population/uncontrolled.

#### 2.2 SAR Definition

The SAR definition is the time derivative (rate) of the incremental energy (dW) absorbed by (dissipated in) an incremental mass (dm) contained in a volume element (dv) of a given density. ( $\rho$ ). The equation description is as below:

$$SAR = \frac{d}{dt} \Big( \frac{dW}{dm} \Big) = \frac{d}{dt} \Big( \frac{dW}{\rho dv} \Big)$$

SAR is expressed in units of Watts per kilogram (W/kg)

SAR measurement can be either related to the temperature elevation in tissue by,

$$SAR = C\left(\frac{\delta T}{\delta t}\right)$$

Where C is the specific head capacity,  $\delta T$  is the temperature rise and  $\delta t$  the exposure duration, or related to the electrical field in the tissue by

$$SAR = \frac{\sigma |E|^2}{\rho}$$

Where  $\sigma$  is the conductivity of the tissue,  $\rho$  is the mass density of the tissue and |E| is the rms electrical field strength.

However for evaluating SAR of low power transmitter, electrical field measurement is typically applied.





#### 3. SAR MEASUREMENT SETUP

#### 3.1 The Measurement System

Comosar is a system that is able to determine the SAR distribution inside a phantom of human being according to different standards. The Comosar system consists of the Following items:

- Main computer to control all the system
- 6 axis robot
- Data acquisition system
- Miniature E-field probe
- Phone holder
- Head simulating tissue

The Following figure shows the system.



The EUT under test operating at the maximum power level is placed in the phone holder, under the phantom, which is filled with head simulating liquid. The E-Field probe measures the electric field inside the phantom. The OpenSAR software computes the results to give a SAR value in a 1g or 10g mass.

#### 3.2 Probe

For the measurements the Specific Dosimetric E-Field Probe SN 27/13 EPG193 with following specifications is used

- Dynamic range: 0.01-100 W/kg

-Probe Tip Ecternal Diameter: 2.5 mm





- Distance between probe tip and sensor center: 2.5mm

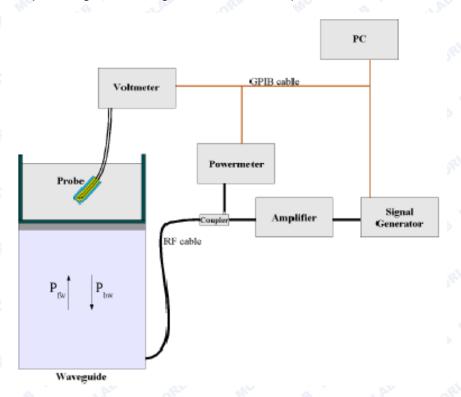
 Distance between sensor center and the inner phantom surface: 4 mm (repeatability better than +/- 1mm)

- Probe linearity: <0.25 dB</li>- Axial Isotropy: <0.25 dB</li>- Spherical Isotropy: <0.25 dB</li>

- Calibration range: 5200 to 5800MHz for head & body simulating liquid.

Angle between probe axis (evaluation axis) and surface normal line: less than 30°

Probe calibration is realized, in compliance with CENELEC EN 62209 and IEEE 1528 std, with CALISAR, Antennessa proprietary calibration system. The calibration is performed with the EN 622091 annex technique using reference guide at the five frequencies.



$$SAR = \frac{4\left(P_{fw} - P_{bw}\right)}{ab\delta} \cos^2\left(\pi \frac{y}{a}\right) e^{-(2z/\delta)}$$

Where:

Pfw = Forward Power Pbw = Backward Power

a and b = Waveguide dimensions

s = Skin depth





#### Keithley configuration:

Rate = Medium; Filter =ON; RDGS=10; FILTER TYPE =MOVING AVERAGE; RANGE AUTO After each calibration, a SAR measurement is performed on a validation dipole and compared with a NPL calibrated probe, to verify it.

The calibration factors, CF(N), for the 3 sensors corresponding to dipole 1, dipole 2 and dipole 3 are:

$$CF(N)=SAR(N)/Vlin(N)$$

(N=1,2,3)

The linearised output voltage Vlin(N) is obtained from the displayed output voltage V(N) using

$$Vlin(N)=V(N)*(1+V(N)/DCP(N))$$

(N=1,2,3)

Where DCP is the diode compression point in mV.

#### 3.3 Probe Calibration Process

#### 3.3.1 Dosimetric Assessment Procedure

Each E-Probe/Probe Amplifier combination has unique calibration parameters. SATIMO Probe calibration procedure is conducted to determine the proper amplifier settings to enter in the probe parameters. The amplifier settings are determined for a given frequency by subjecting the probe to a known E-field density (1 mW/cm²) using an with CALISAR, Antenna proprietary calibration system.

#### 3.3.2 Free Space Assessment Procedure

The free space E-field from amplified probe outputs is determined in a test chamber. This calibration can be performed in a TEM cell if the frequency is below 1 GHz and in a waveguide or other methodologies above 1 GHz for free space. For the free space calibration, the probe is placed in the volumetric center of the cavity and at the proper orientation with the field. The probe is rotated 360 degrees until the three channels show the maximum reading. The power density readings equates to 1 mW/cm<sup>2</sup>.

#### 3.3.3 Temperature Assessment Procedure

E-field temperature correlation calibration is performed in a flat phantom filled with the appropriate simulating head tissue. The E-field in the medium correlates with the temperature rise in the dielectric medium. For temperature correlation calibration a RF transparent thermistor-based temperature probe is used in conjunction with the E-field probe.

Where:

 $\delta t = \text{exposure time (30 seconds)},$ 





$$SAR = C\left(\frac{\delta T}{\delta t}\right)$$

C = heat capacity of tissue (brain or muscle),

 $\delta T$  = temperature increase due to RF exposure.

SAR is proportional to  $\Delta T/\Delta t$ , the initial rate of tissue heating, before thermal diffusion takes place. The electric field in the simulated tissue can be used to estimate SAR by equating the thermally derived SAR to that with the E- field component.

Where:

$$SAR = \frac{\sigma |E|^2}{\rho}$$

 $\sigma$  = simulated tissue conductivity,

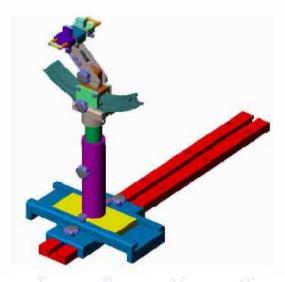
ρ = Tissue density (1.25 g/cm³ for brain tissue)

#### 3.4 Phantom

For the measurements the Specific Anthropomorphic Mannequin (SAM) defined by the IEEE SCC-34/SC2 group is used. The phantom is a polyurethane shell integrated in a wooden table. The thickness of the phantom amounts to 2mm +/- 0.2mm. It enables the dosimetric evaluation of left and right phone usage and includes an additional flat phantom part for the simplified performance check. The phantom set-up includes a cover, which prevents the evaporation of the liquid.

#### 3.5 Device Holder

The positioning system allows obtaining cheek and tilting position with a very good accuracy. In compliance with CENELEC, the tilt angle uncertainty is Middle than 1°.



Device holder

System Material	Permittivity	Loss Tangent		
Delrin	3.7	0.005		





#### 4. TISSUE SIMULATING LIQUIDS

For SAR measurement of the field distribution inside the phantom, the phantom must be filled with homogeneous tissue simulating liquid to a depth of at least 15 cm. For head SAR testing, the liquid height from the ear reference point (ERP) of the phantom to the liquid top surface is larger than 15 cm. For body SAR testing, the liquid height from the center of the flat phantom to the liquid top surface is larger than 15 cm. The nominal dielectric values of the tissue simulating liquids in the phantom and the tolerance of 5% are listed in below table.

The following table gives the recipes for tissue simulating liquids

Frequency Band (MHz)	5800		
Tissue Type	Body		
Ingredients (% by weight )	ORLAND HORN B MO		
Deionised Water	78.60		
Salt(NaCl)	0.00		
Sugar	0.00		
Tween 20	0.00		
HEC	0.00		
Bactericide	0.00		
Triton X-100	10.70		
DGBE	0.00		
Diethylenglycol monohexylether	10.70		
Measured dielectric parameters	NORT MO AE		
Dielectric Constant	ORLAN NAMORE N		
Conductivity (S/m)	Note		

Note: Please refer to the validation results for dielectric parameters of each frequency band.

The dielectric properties of the tissue simulating liquids were verified prior to the SAR evaluation using an Agilent 85033E Dielectric Probe Kit and an Agilent Network Analyzer.

Table 1: Dielectric Performance of Tissue Simulating Liquid

Temperature: 22.0~23.8°C, humidity: 54~60%.						
Date Freq.(MHz) Liquid Parameters Meas. Target Delta(%) Limit±				Limit±(%)		
2014/10/10	Body 5800	Relative Permittivity(cr):	48.13	48.20	-0.15	5
		Conductivity(σ):	6.07	6.00	1.17	5





## 5. UNCERTAINTY ASSESSMENT

The Following table includes the uncertainty table of the IEEE 1528. The values are determined by Antennessa.

## **5.1 UNCERTAINTY EVALUATION FOR EUT SAR TEST**

20,	Ma.	. 80		.0		100	. 6		
a mortage in mortage	b more	C	d	e= f(d,k)	f MORLA	g	h= c*f/e	i= c*g/ e	k
Uncertainty Component	Sec.	Tol (+- %)	Prob Dist.	Div.	Ci (1g)	Ci (10g)	1g Ui (+-%)	10g Ui (+- %)	Vi
Measurement System	A.E	ORLAN	170	a a	MO.	AB	ORLAB	70)	Oak
Probe calibration	E.2.1	4.76	N	1.08	1 1	1	4.76	4.7	∞
Axial Isotropy	E.2.2	2.5	R	$\sqrt{3}$	0.7	0.7	1.01	1.0	∞
Hemispherical Isotropy	E.2.2	4.0	R	$\sqrt{3}$	0.7	0.7	1.62	1.6	∞
Boundary effect	E.2.3	1.0	R	$\sqrt{3}$	1	1.0	0.58	0.5	∞
Linearity	E.2.4	5.0	R	$\sqrt{3}$	1 👊	1	2.89	2.8	∞
System detection limits	E.2.5	1.0	R	$\sqrt{3}$	1	1,084	0.58	0.5	∞
Readout Electronics	E.2.6	0.02	N	1 100	1 3	1	0.02	0.0	∞
Reponse Time	E.2.7	3.0	R	$\sqrt{3}$	101111111111111111111111111111111111111	1 . "	1.73	1.7	∞
Integration Time	E.2.8	2.0	R	$\sqrt{3}$	1	1	1.15	1.1	∞
RF ambient Conditions	E.6.1	3.0	R	$\sqrt{3}$	10	1 ala	1.73	1.7	∞ 1
Probe positioner  Mechanical Tolerance	E.6.2	2.0	R	$\sqrt{3}$	1	1"	1.15	1.1	∞
Probe positioning with respect to Phantom Shell	E.6.3	0.05	R	$\sqrt{3}$	1	1.E	0.03	0.0	8
Extrapolation, interpolation and integration Algoritms for Max. SAR Evaluation	E.5.2	5.0	R	$\sqrt{3}$	AB W	1 MORLAR	2.89	2.8	∞
Test sample Related	A	UOKE.	III.	AB.		RLAN	MORE	THI THI	
Test sample positioning	E.4.2.	0.03	N	1 <sub>MORE</sub>	1 1111	1 AP	0.03	0.0	N- 1
Device Holder Uncertainty	E.4.1.	5.00	N	1 100	1 💸	1	5.00	5.0	N-



2LAE CRL	1	VB In.	all a	40	A. P. Contraction of the Contrac	MOL	"B M.	0	1
Output power Power drift -	6.6.2	4.04	R	$\sqrt{3}$	1	1	2.33	2.3	∞
SAR drift measurement	" B W	CLAP		PLA	Moke	B	LAB	3	ORL
Phantom and Tissue Para	meters	MOL	· @	LAB		ORLA	Mole	.6	
Phantom Uncertainty	E.3.1	0.05	R	$\sqrt{3}$	1.	1	.09	0.0	∞
(Shape and thickness	NOE.	S W	. 9	8	LA	MORE	0.03		6
tolerances)	O.P.	ALL	MORL	E MIC	. 6	9	RLAB	3	
Liquid conductivity -	E.3.2	4.57	R	$\sqrt{3}$	0.64	0.43	1.69	1.1	∞
deviation from target value	ALL	MORL	11/	Q.B		QLAD.	MORL	3	9.
Liquid conductivity -	E.3.3	5.00	N	1,08	0.64	0.43	3.20	2.1	М
measurement uncertainty	MORL	Mo	6	3	LAB	MORL	MO.	5	8
Liquid permittivity -	E.3.2	3.69	R	$\sqrt{3}$	0.6	0.49	1.28	1.0	∞
deviation from target value	Mo.	68	la.	QLAB	MORL	Mc		4	all
Liquid permittivity -	E.3.3	10.0	N 🐠	1 💉	0.6	0.49	6.00	4.9	М
measurement uncertainty	.0	0	LAB	JORLA	111		la.	0	
Combined Standard	ORL	Mo	RSS	B	LAB	ORL	11.55	10.	18
Uncertainty	in.	AB	ORLA	WO.		3	LAB	67	
Expanded Uncertainty	Mor	.0	K=2	LAB	ORLA	<sup>l</sup> ll <sub>C</sub>	23.11	21.	26
(95% Confidence interval)	AB	ORLA	M	Ole.	Mi	LAB	ORLAN	33	Olera

#### 5.2 UNCERTAINTY FOR SYSTEM PERFORMANCE CHECK

a	b mora	С	d	e=	f	g	h=	j=	k
	AB	OPLA	~B 4119	f(d,k)	in.	RLAE	c*f/e	c*g/ e	Ole.
Uncertainty Component	Sec.	Tol	Prob	Div.	Ci	Ci	1g Ui	10g	Vi
	More	(+-	- ALA	, OP	(1g)	(10g)	(+-%)	Ui	8
	ORI	%)	Dist.	B	AF		RLA	(+-	<
3 ORLAN MORE	BIND	LAB	.0	RLA	MORE	S MIC	AB	%)	RLA
Measurement System	Like	NOFE	· · · · · · · · · · · · · · · · · · ·	LAB	.0	RLA	MORE	S 111	
Probe calibration	E.2.1	4.76	N	1,101	1, 1	1 1	4.76	4.7	8
Axial Isotropy	E.2.2	2.5	R	$\sqrt{3}$	0.7	0.7	1.01	1.0	∞
Hemispherical Isotropy	E.2.2	4.0	R	$\sqrt{3}$	0.7	0.7	1.62	1.6	∞
Boundary effect	E.2.3	1.0	R	$\sqrt{3}$	1	1.0	0.58	0.5	∞
Linearity	E.2.4	5.0	R	$\sqrt{3}$	1 110	1 💦	2.89	2.8	∞
System detection limits	E.2.5	1.0	R	$\sqrt{3}$	1	10RL	0.58	0.5	∞
Readout Electronics	E.2.6	0.02	N	1,5	1 ALAS	1	0.02	0.0	∞



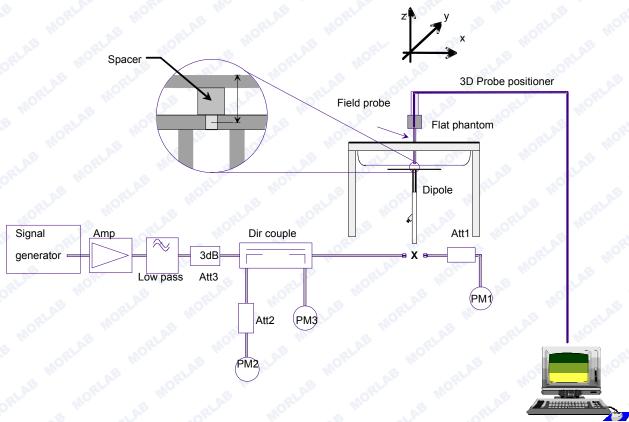
Reponse Time	E.2.7	3.0	R	$\sqrt{3}$	1	1,10	1.73	1.7	∞
Integration Time	E.2.8	2.0	R	$\sqrt{3}$	1 01.0	1	1.15	1.1	∞
RF ambient Conditions	E.6.1	3.0	R	$\sqrt{3}$	1	100	1.73	1.7	∞
Probe positioner  Mechanical Tolerance	E.6.2	2.0	R	$\sqrt{3}$	1 11	1	1.15	1.1	∞
Probe positioning with respect to Phantom Shell	E.6.3	0.05	R	$\sqrt{3}$	1	1	0.03	0.0	8
Extrapolation, interpolation and integration Algoritms for Max. SAR Evaluation	E.5.2	5.0	R	$\sqrt{3}$	LAE W	THORIAL	2.89	2.8	8
Dipole	OR	Library	Mole	S W	. 6	3	RLA	Mole	
Dipole axis to liquid Distance	8,E.4. 2	1.00	N	$\sqrt{3}$	1	1 M	0.58	0.5	∞
Input power and SAR drift measurement	8,6.6. 2	4.04	R	$\sqrt{3}$	1 M	1 NORLAY	2.33	2.3	∞
Phantom and Tissue Para	meters	All	NORT	Me	6	3	RLAR	MORE	
Phantom Uncertainty (Shape and thickness tolerances)	E.3.1	0.05	R	$\sqrt{3}$	10 FE 111	1 M	0.03	0.0	8
Liquid conductivity - deviation from target value	E.3.2	4.57	R	$\sqrt{3}$	0.64	0.43	1.69	1.1	∞
Liquid conductivity - measurement uncertainty	E.3.3	5.00	N	$\sqrt{3}$	0.64	0.43	1.85	1.2	М
Liquid permittivity - deviation from target value	E.3.2	3.69	R	$\sqrt{3}$	0.6	0.49	1.28	1.0	8
Liquid permittivity - measurement uncertainty	E.3.3	10.0	Nati	$\sqrt{3}$	0.6	0.49	3.46	2.8	М
Combined Standard Uncertainty	, B	MORLAN	RSS	PLAE	in_	PALAE	8.83	8.3	Ores
Expanded Uncertainty (95% Confidence interval)	OPLA	E WO	K=2	, m	LAE	MORLA	17.66	16. 73	3



### 6. SAR MEASUREMENT EVALUATION

#### 6.1 System Setup

In the simplified setup for system evaluation, the DUT is replaced by a calibrated dipole and the power source is replaced by a continuous wave which comes from a signal generator. The calibrated dipole must be placed beneath the flat phantom section of the SAM twin phantom with the correct distance holder. The distance holder should touch the phantom surface with a light pressure at the reference marking and be oriented parallel to the long side of the phantom. The system check verifies that the system operates within its specifications. It is performed daily or before every SAR measurement. The system check uses normal SAR measurements in the flat section of the phantom with a matched dipole at a specified distance. The system verification setup is shown as below



The validation dipole is placed beneath the flat phantom with the specific spacer in place. The distance spacer is touch the phantom surface with a light pressure at the reference marking and be oriented parallel to the long side of the phantom. The power meter PM1 measures the forward power at the location of the system check dipole connector. The signal generator is adjusted for the desired forward power (250 mW is used for 700 MHz to 3 GHz,100 mW is used for 3.5 GHz to



6 GHz) at the dipole connector and the power meter PM2 is read at that level. After connecting the cable to the dipole, the signal generator is readjusted for the same reading at power meter PM2.

#### 6.2 Validation Results

After system check testing, the SAR result will be normalized to 1W forward input power and compared with the reference SAR value derived from validation dipole certificate report. The deviation of system check should be within 10 %.

Frequency	5800MHz
Target value 1W (1g)	201.57 W/Kg
Test value 1g (100 mW input power)	19.582 W/Kg (10.10)
Normalized to 1W value(1g)	195.82 W/Kg

Frequency	5800MHz			
Target value 1W (10g)	68.65 W/Kg			
Test value 10g	6.643 W/Kg			
(100 mW input power)	(10.10)			
Normalized to 1W value(10g)	66.43 W/Kg			

Note: System checks the specific test data please see 40~41.

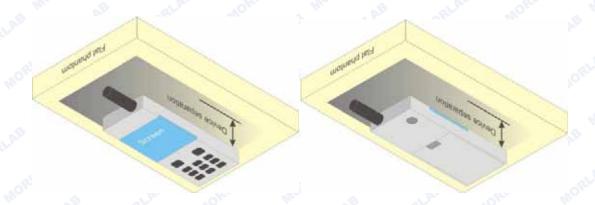


#### 7. OPERATIONAL CONDITIONS DURING TEST

#### 7.1 Body-worn Configurations

The body-worn configurations shall be tested with the supplied accessories (belt-clips, holsters, etc.) attached to the device in normal use configuration.

For body-worn and other configurations a flat phantom shall be used which is comprised of material with electrical properties similar to the corresponding tissues.



**Illustration for Body Worn Position** 

#### 7.2 Measurement procedure

The Following steps are used for each test position

- Establish a call with the maximum output power with a base station simulator. The connection between the mobile and the base station simulator is established via air interface.
- 2. Measurement of the local E-field value at a fixed location. This value serves as a reference value for calculating a possible power drift.
- 3. Measurement of the SAR distribution with a grid of 8 to 16mm \* 8 to 16 mm and a constant distance to the inner surface of the phantom. Since the sensors cannot directly measure at the inner phantom surface, the values between the sensors and the inner phantom surface are extrapolated. With these values the area of the maximum SAR is calculated by an interpolation scheme.
- 4. Around this point, a cube of 30 \* 30 \* 30 mm or 32 \* 32 \* 32 mm is assessed by measuring 5 or 8 \* 5 or 8 \* 4 or 5 mm. With these data, the peak spatial-average SAR value can be calculated.



#### 7.3 Description of interpolation/extrapolation scheme

The local SAR inside the phantom is measured using small dipole sensing elements inside a probe body. The probe tip must not be in contact with the phantom surface in order to minimize measurements errors, but the highest local SAR will occur at the surface of the phantom.

An extrapolation is using to determinate this highest local SAR values. The extrapolation is based on a fourth-order least-square polynomial fit of measured data. The local SAR value is then extrapolated from the liquid surface with a 1mm step.

The measurements have to be performed over a limited time (due to the duration of the battery) so the step of measurement is high. It could vary between 5 and 8 mm. To obtain an accurate assessment of the maximum SAR averaged over 10 grams and 1 gram requires a very fine resolution in the three dimensional scanned data array.





#### 8. MEASUREMENT OF CONDUCTED OUTPUT POWER

#### 1. 5.8G Conducted Output Power

Dand	Channel	Frequency	Output Power(dBm)
Band	Charmer	(MHz)	GFSK
NB III	LAP 1 OP	5728	16.598
5.8G	9	5784	17.055
TLAB	16	5844	17.918

