Operation Manual for THE NTG-560 SOLID STATE TRANSMITTER / RECEIVER

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SAFETY INFORMATION

To prevent harm to those who use this product or other people and damages to property, safety precautions to be followed are described as follows.

★ The degrees of harm and damages caused by misuse with neglecting indications are classified and described as follows.



 \star Kinds of precautions to be followed are classified and described with the following icons. (A few examples of icons are as follows.)



This icon is to call attentions.





This icon is to force some actions.



Plug in completely



Incomplete plugging may generate heat to cause a shock or a fire.

In case of malfunctions or abnormal conditions (smoke, foul odor, sound, etc.), turn the power off and turn off the breaker of the power distributor.



Unplug

Turn the power off and consult with our company. Do not repair the device by yourself because it is dangerous.

Do not put the device on unstable places(a shaky stand, tilted place, etc.).



Dropping or falling down of the device may cause injury.

Prohibition

Do not wet or water the device.



Wetting the device may cause a shock or a fire.

Do not wet

Do not put things (containers with liquid, flower pots, etc.) or creatures on the device.



Entering of liquid or excrement may cause a shock or a fire.

Prohibition

★ In case of entering, unplug from the outlet and consult with our company. Do not put liquid such as water, metals or inflammable objects inside the device.



Entering may cause a shock or a fire.

Prohibition

In case of entering, unplug from the outlet and consult with our company.



DANGER

Do not drop or bump the device.



Physical shock may cause a s hock or a fire.

Prohibition

other than the indicated power-supply voltage.

Do not use the device under a voltage



Malfunction may occur to cause a shock or a fire.

Prohibition

Do not remove the back lid, the cabinet or the cover, or do not modify the device.



Consult with our company for internal inspection and repair.

Do not decompose

When thunder has started, do not touch the power cables, the signal cables and the device.



Touching will cause a shock

Do not touch

Do not damage the power cord or the plug.



Damaging, processing, loading, heating, bending and twisting forcedly or pulling may deteriorate insulation of coating, expose cores or break the cord to cause a shock or a fire.

Prohibition

 \star In the case of damages, unplug from the outlet and ask our company



Carry the CRT monitor by more than one people since the monitor is heavy.



Stumbling, etc. may cause injury.

Disconnect the plug and the connection lines when moving the device.



Damage of cords may cause a shock or a fire.

Unplug

Unplug with holding the plug.



Damage of cords may cause a shock or a fire.

Unplua

Unplug from the outlet for safety when maintaining



A shock may be caused.

Unplug



Do not put the device where much moisture or dust exists, and greasy fumes or steam is generated.



Putting the device on a cooking table or near a heater may cause a shock or a fire.

Ask our company for internal inspection and cleaning periodically.



Without cleaning for a long time, dust gathered inside the device may cause malfunction or a fire.

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Unplug from the outlet when not using for a long time.



Dust gathered on the plug may cause a fire or a shock.

Unplug

CAUTIONS

plug.

Do not put other devices (a TV, a display device, etc.) or magnetized objects near the CRT monitor. Installing the CRT monitor near those may have an effect on the screen (disturbing colors or swaying the screen).

★ Move the device seemed to effect away as possible. In case the phenomenon does not stop even so A shock may be caused without grounding the earth wire.

Ground the earth wire of the

Furthermore, poor reception for TV's, radios,

Do not put the device in direct sunshine or in the heat of heating apparatus.

Heat may cause deformation of the cabinet or malfunction of parts.

Do not use the device in a dark place at close range for a long time. Using the device in a dark place at close range for long time may weary eyes or weaken eyesight.

★Use the device at a distance of 40 or 50 cm in a bright place where newspaper can read easily. Take a rest for eyes every 30 minutes.

Do not contact the cabinet with rubber or plastic products for a long time. The quality of the cabinet may alter or the coating may come off.

1. Overview

This manual describes operation function of the NTG-560 Solid State Transmitter-Receiver that is used for the land based radar surveillance system.

Figure-1.1 shows total system illustration diagram of the NTG-560 and peripheral equipments. And Figure-1.2 shows functional data flow of the NTG-560.



Figure-1.1 Total System Illustration Diagram of the Radar System.



Fig. 1.2 Functional Data flow of the Radar System

2. Operation

2.1 How to start the system

1) Turn on the DC48V Power Supply by it's switch or attached NFB.

X-band Radar Antenna



- 2) Turn on the power switch on the NCD-2247-1B
- Open the main menu Window (CDC-1469 control module by LAN (NMEA). See paragraph 2.3
- 4) Confirm the no error indication on main menu.
- 5) Turn on Antenna motor NFB.

Before turn on, It checks that there are no people near the antenna.

- 6) Click the Transmit ON button on the main menu
- 7) Echo will appear on the "Solid State radar Signal Input Module window". See paragraph 2.4

2.2 How stop the System.

1) Stop the system by reverse procedure of the how to start.

2.3 Radar Control Module (N_Cont. exe) Main Window

The following indication will be displayed when NTG-560 and NCD-2247-1B are connected normally.

CDC-1469 Control module by LAN (NMEA) Version 1.3						
Control / Ma	phitor	Failure State				
		Initialization Failure				
Main	TRX-1	PLL Lock Failure				
		Antenna Switch Failure				
Trapsmit		ARP Signal Failure				
		ACP Signal Failure				
Stagger Transmit		Direction of Rotation Failure				
		Trigger Signal Failure				
Range Table	1 2 3 4 5 6 7 8	Video Signal Failure				
		Internal Power Supply Failure				
Interference Rejection	OFF LOW MID HIGH	IF Light Signal Failure				
TRX Inform	High-speed IF Board Failure					
Encoder Type	Request	TRX Monitor				
Unit Type	FPGA	FPGA Temperature				
Interface Revision		SP-Board Temperature				
CPU Software Version		Communication State				
FPGA Software Version						
SINGLE MODE (1) Sect	or Blank Advance Setting	Maker Setting				

SIGNAL MODE(1) window menu

Control/Monitor

Main :TRX-1 displayed

Transmit : OFF: Transition turned off, ON: Transmission turned on

Stagger Transmit : OFF: Stagger Transition turned off, ON: Stagger Transmission turned on Range Table : Selects Range Table shown as table below.

Table	No1. T	ransmit	No.2 T	ransmit	PRF	Tm1
No.	PW(us)	FM(MHz)	PW(us)	FM(MHz)	(Hz)	(us)
1	0.07	0	2.8	30	2280	97.52
2	0.15	0	4.6	30	2280	97.52
3	0.3	0	9.1	20	2280	97.52
4	0.15	0	18.3	30	1280	97.52
5	0.15	0	28.0	30	640	97.52
6	0.3	0	9.1	30	1864	97.52
7	0.6	0	9.1	30	1280	97.52
8	0.07	0	2.8	30	4100	97.52

Remarks;

PW: Pulse Width, FM: Frequency Modulation range,

PRF: Pulse Repetition Frequency,

TM1: Time interval between No.1 and No.2 transmission



Interference Rejection: Adjusts the interference rejection strength level Off / Low / Middle / High

TRX Information

Encoder Type: 2048 (Encoder pulse numbers)Unit Type: CDC-1469 (Signal Processor Model)Interface Revision: 00CPU Software Version: 0000FPGA Software Version: 0000

Request : Updated when click this button

Failure State

Initialization Failure: FPGA initialization failure.PLL Lock Failure: PLL lock faiture on the master clock of signal processor.Antenna Switch Failure: Antenna Safety Switch turned ON.ARP Signal Failure: Lacked the Antenna encoder reference pulse.ACP Signal Failure: Lacked the Antenna encoder pulse.Direction of Rotation Failure: Antenna is reverse rotation.Trigger Signal Failure: Lacked the Radar trigger signal.Video Signal Failure: Lacked the radar video signal during specified period.Internal Power Supply Failure: TRX internal power supply became abnormal condition. TRX.

IF Light Signal Failure: IF Optical Fiber signal Lost.High-speed IF Board Failure: AVAL Optical Board is Failure.

TRX Monitor

FPGA Temperature	:xxx°	shows temperature
SP-Board Temperature	:xxx°	shows temperature

Communication State

1 192.168.1.32(50000) SD RD : Green :Normal condition, Red :Abnormal(See below)

CDC-1469 Control module by LAN (NMEA) Version 1.3					
Control / Mc	pnitor	Failure State			
Main	TRX-1	Initialization Failure PLL Lock Failure			
Transmit		Antenna Switch Failure ARP Signal Failure ACP Signal Failure Direction of Potetion Failure			
Stagger Transmit Range Table	OFF ON 1 2 3 4 5 6 7 8	Trigger Signal Failure Video Signal Failure			
Interference Rejection TRX Inform	OFF LOW MID HIGH	Internal Power Supply Failure IF Light Signal Failure High-speed IF Board Failure			
Encoder Type Unit Type Interface Revision CPU Software Version FPGA Software Version	Request	TRX Monitor FPGA Temperature SP-Board Temperature Communication State 1 192.168.1.32 (50000) SD RD			
SINGLE MODE (1) Sector Blank Advance Setting Maker Setting					

		Current I	Parame	eters			Setting Change
No	Start	Blank	No	Start	Blank	No	123456
1	116	1219	1	116	1219	Cont	
2	174	1161	2	174	1161	Start	
3	697	2148	3	697	2148		
4			4			Blank	214
5			5				
6			6				
7			7				SET
tart a	nd Blank unit	[0,1 dea]					

Sector Blank window menu

Transmission Sector blanking angle can be presentable.

This radar system has 7(seven) sector blanking area which are presentable individually.

		Current P	aram	eters			
No	Start	Blank	No	Start	Blank	1	
1	116	1219	1	116	1219		Input preset angle data
2	174	1161	2	174	1161		
3	697	2148	3	697	2148		Actual preset angle
4			4				data(response from
5			5				TRX)
6			6				
7			7				
* Start a	and Blank unit	: [0.1 deg]				_	

No	1234	5	6
Cont	OFF	(N
Start	•	۲	697
Blank		+	214

The blanking data of an input is reflected by pushing a SET button.

Advanced Setting window menu



Fine Tuning : Reserved Function.

Sweep Integration Mode : ON or OFF (Reduce the Noise and Clutter echo) CFAR : ON or OFF (Constant False Alarm Rate)

Maker Setting window menu

This menu is presented by manufacture's factory, so that please do not change recklessly..

35571010	
•••	Enter

A password input is required when open the maker setting window.

Initial password is "admin".

Operati	on Mode		Pulse Transmit	Mode
FD	Single		TRX-1 P+Q *P:Non-Chirp *Q:Chirp	P+Q P Q
Main	TRX	Set	Encoder Typ	e
TRX-1	TRX-2		2048 4096	2048

Setting of Password

Password	V Hidden ENT
Hidden The mask of the in	putted password is canceled temporarily.
Password] Hidden
Password Admin] Hidden
ENT Click the ENT butte	on and password will be memorized.

* It is enciphered and the inputted password is saved at an initialization file.

Operation Mode

FD : Not	used
Single	This system can be used Single only

Main TRX

Not used in this system.

Pulse Transmit Mode (Default is P+Q)

TRX-1 : P+Q (Indicate current transmission mode)

P+Q: Select Both P(non-chirp) and Q(chirp) transmission pulse

P : Select P pulse only

Q : Select Q pulse only

Encoder Type

2048 : Select antenna encoder 2048 pulse type

4096 : Select antenna encoder 4096 pulse type

2048 Green indication (Indicate current selected encoder type)

Communication Preset Window

	TCP	Client	
		Server Addr	192.168.1.32
Close	Open	Server Port	50000
Open Link	SD RD	Send : #C112*	71
[15:16:53] Send : [15:16:53] Receive [15:16:53] Send : [15:16:53] Receive	#C102~70¥r¥n 2 : #S102,00,000 #C112*71¥r¥n 2 : #S112,000000	0,00000000*4C¥r¥ 100*4D¥r¥n	'n
	State State Colle	1211 N	

TCP Client	
Close Open	Open/Close a socket
Open Socket open stat	e
Link Socket connection	nstate
SD RD Flashing at s	ending and receiveing
Server Addr 192.168.1.32	Server IP address
Server Port 50000	Server port number
Send : #C102*70	Indicate the communication event



Communication Event Log indication



Update of the log of a communication event is stopped.

Clear

The log of a communication event is cleared.

X If you want to save the contents that are displayed in the file, copy it to the clipboard using such as Ctrl + A and Ctrl + C, please save the file using Memo-pad etc.

- Cantrol / N	lonitor :		Faluri State			
Man	TRX	-1	Initialization Failure PLL Lock Failure Antonna Sentub Failure			
Transmit		ON:	ARP Signal Tubure ACP Signal Tellure			
Stagger Transmit	-	97	Deaction of Rotation Falls Tripper Statual Falls	1185		
Range Table	in last	+1.4.	Video Signal Failure Internal Property Failure			
Interference Rejection	in in in	00.11 Heldel	IF Light Signal Failure			
TRX Infor	nablen :		High-speed IF Board Fails	me : .		
Encoder Type Unit Type Interface Revision CPU Software Version	2048 CDC-1469 00 0000	Request	FPGA Temperature SP-Board Temperature	-128° -128°		
FPGA Software Version	0000		1 Otabilat (Smith 1)			
NGLE MODE (1)	antes () (nie	un Geffra	Man Selling		Click the	he

History of Failures Log Window indication

The history of failure window displayed.

Log Lisl]					Reload		All Clear
Date	(yy/mm/dd)	Time (hh:mm:ss)		Message		Fon
Date (15/12/17),	Time(15:01:19):	******* < Start > *	* <mark>***</mark> ***	** (Sj
Date (15/12/17	1,	Time(15:01:19):	[N_Cont.exe, Version 1	1.0,2015	5/12/1
Date (15/12/17),	Time(15:01:23):	Sock1:Winsock(10061)	: WSAEC	CONNRE
Date (15/12/17	1.	Time(15:01:23):	Sock2:Winsock(10061)	: WSAEC	CONNRE
Date (15/12/17),	Time(15:02:23):	Sock1:Winsock(10061)	: WSAEC	CONNRE
Date (15/12/17	1.	Time(15:02:23):	Sock2:Winsock(10061)	: WSAE(CONNRE
Date (15/12/17	1,	Time(15:03:24):	Sock2:Winsock(10061)	: WSAEC	CONNRE
Date (15/12/17	1,	Time(15:05:55):	Sock1:Winsock(10061)	: WSAEC	CONNRE
Date (15/12/17),	Time(15:06:55):	Sock1:Winsock(10061)	: WSAEC	CONNRE
Date (15/12/17	1.	Time(15:07:56):	Sock1:Winsock(10061)	: WSAEC	CONNRE

2.4 Solid State Radar Signal Input Module(N_Solid.exe)

This module captures in a radar picture using an UDP socket (TCP/IP) from a solid-state TRX signal processing circuit (CDC-1469). The captured radar picture is provided through a shared memory to other applications. Also, Radar PPI image can be monitored using this module.



2.4.1 Icon



2.4.2 Start-up the Screen



2.4.3 Main Menu

📴 Solid State Radar Signal Input	Module			
File View Help				
E-■ Radar signal input module È-■ Radar Image È-■ A Scope		+ ∉	▷ 🔍	Q
R Scope	12	A Storage	- Charles	

2.4.3.1 File



(1) Exit

Exit the Application

Note: When this application is started according to the launcher process (Stater2.exe) of exclusive use, a window is closed and it operates in the background.

2.4.3.2 View



Data Link : Display the Data Link Screen Tool Bar : Display on/off of the tool bar Tree Menu : Display on/off of the tree menu Input Panel : Display on/off the input panel Status Bar : Display on/off of the status bar

(1) Data Link screen

1800	Group Name	Link Name	Status	Size	T/pe	Value	Notice
Listener	(no name)	bRemote	Enabled	1001101	bool	talue	Uモート制御入/(5) (trus/labs)
Slave	(no name)	wGAN	Enabled		WORD	0x0000	利得制御レイル (1-285)
Broadcact	(no name)	wA2IMUTH	Enabled		WORD	0x0000	方位オフセント (0-285)
Slave	(no name)	bQyroAdjust	Enabled		bool	talue	Gyrolこよる方位制御 方式 (trus/labs)
Slave	(no name)	bQyroAdjust	Enabled		bool	talue	Gyrolこよる方位制御 方式 (trusでスムース制御)
Slave	(no name)	dQyroAdjust	Enabled		double	0	Gyrolこよる方位制御 船首方位度)
Broadcast	(no name)	bQyroAdjust	Enabled		bool	true	Si N,Seldeon active 7

Other applications and the state of InterProcess communication are displayed.

2.4.3.3 Help



(1) Version



2.4.4 Tree Menu and Functional Description



A function name is displayed in tree form. When a function name is selected, a related picture and a related input panel are displayed.

25

2.4.4.1 Radar Image





: Image update is stopped when this switch turned ON.

Range: Selects radar display range.

0.5 NM, 0.75 NM, 1.5 NM, 3 NM, 6 NM, 12 NM, 24 NM, 48 NM, 96 NM, 192 NM, Fixed: Fixed the display azimuth.

Rng.: Displays distance of cursor position.

Amp.: Displays echo level(amplitude) of the cursor position (reference value).

Input Panel

Radar Azimuth	209	deg	🔽 Range Mark	🔽 Painting Out
			🔽 Amplitude Mark	

Radar Azimuth: Displays the radar antenna azimuth angle.

Range Mark: Selects display on/off of the Range Marker.

Amplitude Mark: Selects display on/off of the amplitude marker.

Paint Out: : Selects painting out on/off.



1) Scale



Amplitude Scale: Selects amplitude scale.(Scale/Marker Interval)

- 0.5 / 0.1 V
- 1.0 / 0.2 V
- 2.0 / 0.5 V
- 5.0 / 1.0 V

(Amplitude(level) is reference value).

2) Display Interval

Interval	100	ms	Lap time	1	ms
----------	-----	----	----------	---	----

Interval: Presets the update interval of radar picture. (Preset range: $10 \sim 1000$ mS) Lap time: Displays the radar picture depiction lap time.

If an updating cycle is shortened, the load of CPU will increase.

(Please preset according to CPU load)



(2) B-Scope



: Image update is stopped when this switch turned ON.



: Shows cursor position in the picture.



Range: Selects radar display range.

Rng.: Displays distance of cursor position.

Azi.: Displays azimuth angle of cursor position.

Input Panel



Radar Azimuth : Displays the radar antenna azimuth angle.

Range Mark : Selects display on/off of the Range Marker.

Azimuth Mark : Selects display on/off of the azimuth marker.

Histogram : Selects display on/off of the histogram.



Split Color: Display on/off of the function to classify a radar picture by color to two gradation is changed.



3D Scope : Selects the 3D display on/off.



1) Scale



Azimuth Scale: Selects azimuth scale. (Scale/Marker interval)

- 30 / 5 deg
- 60 / 10 deg
 90 / 15 deg
 120 / 20 deg
- 180 / 30 deg
- 270 / 45 deg
- 360 / 60 deg

2) Display Interval

Interval 100 ms Lap time 0 ms	;
-------------------------------	---

Interval: Presets the update interval of radar picture. (Preset range:10~1000mS)

Lap time: Displays the radar picture depiction lap time.

If an updating cycle is shortened, the load of CPU will increase.

(Please preset according to CPU load)



3) Color

White Red	Brightness
Green Green	Contrast
Yellow Blue	Reset Gamma

White Button: Sets the radar picture display color to white monochrome. Green Button: Sets the radar picture display color to green monochrome. Yellow Button: Sets the radar picture display color to yellow monochrome.

Red Slide Bar: Adjusts the red level of radar picture color. Green Slide Bar: Adjusts the green level of radar picture color. Blue Slide Bar: Adjusts the blue level of radar picture color.

Reset Button: Resets the gradation curvature. Brightness Scroll Bar: Adjusts the brightness of gradation curvature. Contrast Scroll Bar: Adjusts the contrast of gradation curvature. Gamma Scroll Bar: Adjusts the gamma level of gradation curvature.



4) Stretch Mode

Stretch Mode	Average	•
--------------	---------	---

Stretch Mode: Selects the pixel composite method for B-scope conversion.

- None : Pixel composition is not carried out.
- Peak Hold :Maximum value is used.
- Average : Average value is used.

• Minimum : Minimum value is used.



(3) PPI Scope

u + * a a	2/0.5 NM Rog	2.26 NM Azi	10.8deg		
Radar Azimuth	50 deg 🛛 🖓 Range Mark	Histogram	☐ Split Color ☐ 30 Scope		
: Image update is stop	ped when this switch tu	rned ON.			
: Shows cursor position	: Shows cursor position in the picture.				
: Moves picture position. (Off-Center)					
Expand the position of cursor. (Zoom-in)					
	f cursor. (Zoom-in)				
: Reduce the position of	f cursor. (Zoom-in) of cursor. (Zoom-out)				

- Rng. : Displays distance of cursor position.
- Azi. : Displays azimuth angle of cursor position.

Input Panel



Radar Azimuth : Displays the radar antenna azimuth angle.

Range Mark : Selects display on/off of the Range Marker.

Azimuth Mark : Selects display on/off of the azimuth marker.

Histogram : Selects display on/off of the histogram.



1 x 256



8 x 32

Split Color: Display on/off of the function to classify a radar picture by color to two gradation is changed.



3D Scope : Selects the 3D display on/off.



1) Scale

Range	8/2NM	•

Range: Selects the display range scale. (Range/Range Marker Interval)

- 0.25 / 0.05 NM 0.5 / 0.1 NM 1 / 0.2 NM 2 / 0.5 NM 4 / 1 NM 8 / 2 NM 16 / 5 NM
- 32 / 10 NM 64 / 20 NM
- 128 / 50 NM

2) Display Interval



Interval: Presets the update interval of radar picture. (Preset range:10~1000mS) Lap time: Displays the radar picture depiction lap time.

If an updating cycle is shortened, the load of CPU will increase.

(Please preset according to CPU load)



3) Color

White Red	Brightness
Green Green	Contrast
Yellow Blue	Reset Gamma

White Button: Sets the radar picture display color to white monochrome. Green Button: Sets the radar picture display color to green monochrome. Yellow Button: Sets the radar picture display color to yellow monochrome.

Red Slide Bar: Adjusts the red level of radar picture color. Green Slide Bar: Adjusts the green level of radar picture color. Blue Slide Bar: Adjusts the blue level of radar picture color.

Reset Button: Resets the gradation curvature. Brightness Scroll Bar: Adjusts the brightness of gradation curvature. Contrast Scroll Bar: Adjusts the contrast of gradation curvature. Gamma Scroll Bar: Adjusts the gamma level of gradation curvature.

Example of Adjustin	ang of gamma level

4) Stretch Mode

Stretch Mode	Average	-
	I Hycidge	

Stretch Mode: Selects the pixel composite method for B-scope conversion.

- None : Pixel composition is not carried out.
- Peak Hold :Maximum value is used.
- Average : Average value is used.
- Minimum : Minimum value is used.



2.4.4.2 Input Image

Selectes the input source



Radar (Socket) : Selects radar signal.Simple Pattern : Selects the Test Pattern.Cycle: Presets the test pattern rotation speed.Bitmap File: Makes the bitmap file.

Selects the bitmap file.

Noise++ : Superimpose the noise signal. (This setup is not saved.)

(1) Socket

The TCP/IP UDP client socket for connecting with radar signal processing equipment (CDC-1469) on NTG-560 SSTRX is set up.

Startup Po	rt No Status	(Receive Buff Size
🔽 Auto Open	50010 Open		512 M Byte

Startup – Auto Open: Automatically sets the socket to the application startup in the case to be open. Port No: Presets the receiving port number of UDP socket.

Status : Status of UDP socket.

Open	TX RX : Close
Open	: Open
TX	: Ready for Transmission
TX	: Under transmission
RX	: Waiting the receiving
RX	: Under receiving

Open(or Close) Button : Open (or close) the socket Receive Buff Size : Presets the receiving buffer size. (1 - 512MB)

1) Radar Information

	Azimuth Rotational Period	246 deg ACP Resolution 2048 2.9 s 20.4 r.p.m. Azimuth Resolution 0.175 deg	
A	zimuth	: Displays radar antenna azimuth angle. (Latest sweep message angle)	
A	CP Resolution	: Displays ACP resolution.	
F	Rotational Period : Displays Antenna revolution period and rotation speed(rpm).		
A	zimuth Resolution	n]: Displays azimuth resolution. (The value which divided 360 degrees by the number	

of sweeps)

2) Message1

Messag ID	0×48	Sequence no	0×40	Encoder bit size	0x00	CRC32
Message size	0×0C	Range bin size	0×2000	Antenna angle	0×0340	5FEE1E79

Display the header information of the receiving message.

Туре	Size	Description
Header	12 bytes	Message ID (0x48)
		Message size(12)
		Sequence Number(0 – 255)
		Range bin size
		Antenna encoder bit number(0x00:11,0x01:12)
		Antenna Angle information
		CRC32c
Sweep data	Range bin size	Message ID (0 x 44)
	+3bytes	Message size(Range bin size + 3)
		Data (Echo strength data)

Format of Receiving Message

3) Message2 & Counters

	Event Counters	
Message ID 0x44		Class
Message size 0x2003	0 0 0 986	

Message ID :Displays the message ID of sweep data (0 x 44).

Message Size :Displays the message size of sweep data.

*Message size = Range bin size+3.

Event Counters :Displays event counters of sweep message receiving process.

Contents of event counters

Location	Outline	Detailed
Upper1	It is interrupted 2 seconds or more during message reception.	If received during the reception of the message is interrupted for two seconds, and discard the message received up to the middle of its sweep. The number of times.
Upper2	Sequence number error	Number of times that the header sequence number is not correctly incremented.
Upper3	Azimuth error(skipping)	Number of times that the angle is open more than once of the orientation information in the header.
Upper4	Invalid data before Header	In a state of waiting for reception of the header, bytes on read-and-discard mode of data that is not recognized as a header.
Upper5	Split receiving of header	In a state of waiting for reception of the header, the header is received over a plurality of reception processing. The number of times.
Lower1	Sweep data ID error	In a state of waiting for the reception of the sweep data, the number of bytes on read-and-discard mode when the message ID is not detected.
Lower2	Mismatching of sweep data range bin number 1	Indicates the number of times the number of data of the range bins number and sweep data of the header do not match.
Lower3	Mismatching of sweep data range bin number 2	Always 0. The counter to be detected above is always 0.
Lower4	Occurrence of exception during sweep data receiving	Always 0. (Referred to debugging)

Lower5	Sweep number	Shows maximum sweep number in receved data at 1
		time receving by appilication. Indication of whether it
		is processed smoothly.

4) Receiving Rate

Read Size		Receive Rate		
8207	Byte	5,723.0	K Byte/Sec	Counter Reset

Read Size: Display the maximum of the data size processed by one reception processing. Receive Rate: Display the maximum of the receiving data size per second.

Counter Reset Button: Clear the maximum value of both Read Size and Receive Rate.

5) Error Status

Error Code	Error File	Error Line	
			Clear

It will display an error of application definition that occurred during the receiving process. Error Code: Display the error number.

Error File: Display the error of occurred location (source file name).

Error Line: Display the places that have occurred error (line number on the source file). Clear Button: Clear the error display.

(2) Video Gain

Video Gain	•	+1.00	Reset	Profits Offset
Video Offset	•	• 0.00	Reset	0.00

Video Gain Scroll Bar: Adjust the radar video gain. (-1.00~+1.00)

Reset

: Reset the Video Gain to default value. (+1.00)

Video Offset Scroll Bar: Adjust the offset voltage of radar video. (-1.00~+1.00)

Reset : Reset the Video Offset to default value. (0.00)

Profit Offset: Gain offset. This value is controlled by other module.



(3) RangeRate

7.5m/pixel(20MHz)
8192 (512 - 8192)

Range Rate: Select the Range Rate (Resolution)

- 0 7.5m/pixel (20MHz)
- 1 15m/pixel (10MHz)
- 2 22.5m/pixel
- 3 30m/pixel (5MHz)
- 4 37.5m/pixel
- 5 45m/pixel
- 6 52.5m/pixel
- 7 60m/pixel (2.5MHz)
- 8 67.5m/pixel
- 9 75m/pixel (2MHz)
- 10 82.5m/pixel
- 11 90m/pixel
- 12 97.5m/pixel 13 - 105m/pixel
- 14 112.5m/pixel
- 15 120m/pixel (1.25MHz)

(4) Input Bin Size

Range Rate	7.5m/pixel(20MHz)
Input Bin Size	8192 (512 - 8192)

Input Bin Size: Specify the input range bin size. (512 - 8192)

*By shortening the capture range bin size(length), you can reduce the CPU load.

(5) 0m Adjustment

Om Adjustment	0	(-2500 m - 2500 m)
Azimuth Adjustment	0x0000	(0x0000 - 0xFFFF) 0.0 deg

0m Adjustment: Adjust the radar echo start range bin. (-2500m - +2500m))

This adjustment is for adjusting the center of the radar image and shift the radar image on the home side in pixels.

(6) Azimuth Adjustment

Om Adjustment	0	(-2500 m - 2500 m)		
Azimuth Adjustment	0x0000	(0x0000 - 0xFFFF)	0.0	deg

Azimuth Adjustment: Adjust the radar azimuth angle. (0x0000 - 0xFFF) This is for radar echo azimuth angle. Resolution is 360/65536(deg.)

2.4.4.3 Failure history

Failure history will be displayed for the troubleshooting.

Date(yy/mm/dd)	Time(hh:mm:ss)	Message	
Date(16/02/02), Time(03 Date(16/02/02), Time(03 Date(16/02/02), Time(03 Date(16/02/02), Time(03 Date(16/02/02), Time(03 Date(16/02/02), Time(03	3:06:19): ********* < Start > ***** 3:06:19): [N_Solid.exe,Version 1 3:37:24): 5:38:15): ******** < Start > ***** 5:38:15): ******** < Start > *****	/**** (SysTime:3515s) I.0,2016/01/14 15:43:42] ***** (SysTime:5379s) ***** (SysTime:12631s) I.0,2016/01/14 15:43:42]	*
•		•	
Update	All Clear Save t	o file	

Update Button: Update the current logging information.

All Clear Button: Clear the all logging information.

Save to file Button: Save the current logging data with file name.

2.4.4.4 Simulation

Enabled	Period 2.0	IP Addr	Port No
Send one sweep	Err Sim 1 Err Sim 2 Err Sim 3	127.0.0.1	50010

This function is to simulate the output of the message of the CDC-1469. It can not use that it has not Open the receiving socket so to send will use the socket for reception.

Enabled: This is switch for simulation on/off.

Period: Specify the radar antenna rotation speed for the simulation.

IP Addr: Specify the output IP address. (127.0.0.1 is special IP which mean own IP address)

Port No: Specify the output port number.

Send one sweep Button: Outputs the message of one sweep data as single.

Outputs the whether Enabled check box is off.

Err Sim 1 Button: Outputs the CRC32C of header with taking small interval.

Err Sim 2 Button: Outputs any of the data before header.

Err Sim 3 Button: Lack the message of 1 sweep length.

*These functions are for communication confirmation and debugging.

(1) Message1

Messag ID	0x48	Sequence no	0x00	Encoder bit size	0x00
Message size	0x0C	Range bin size	0x4000	Antenna angle	0x0000

Specify the header information of simulated sweep message.

Туре	Size	Description
Header	12 bytes	Message ID (0x48) Message size(12) Sequence Number(0 – 255) Range bin size Antenna encoder bit number(0x00:11,0x01:12) Antenna Angle information CBC32c
Sweep Data	Range bin size + 3 bytes	Message ID (0 x 44) Message size(Range bin size + 3) Data (Echo strength data)

(2) Message2 & Counters

Message ID 0x44		Send Counter	Number of bytes	0	Clear
Message size 0x400	3	C Difference	Number of sweeps	0	

Message ID : Specify the message ID of simulated sweep data (0 x 44).

Message Size : Specify the message size od simulated sweep data.

*Message size = Range bin size+3.

Send Counter : Select the both sending data counter and sweep counter.

Receive Counter: Select the both receiving data counter and sweep counter.

Difference :Select the different. (Send Counter) – (Receive Counter)

Number of bytes: Display the data counter.

Number of sweeps: Display the sweep counter.

Clear Button: Clear the above counter.

2.4.4.5 Sweep Tag

```
      Tag Format (Size)

      C None (0)

        • PciRvi (4 bytes)

        • Nams (10 bytes)

      C PCIVdi (16 bytes)

        • PciRvi (16 bytes)

        • Nams (16 bytes)
```

Tag Format (Size):

None(0): No hardware Tag.

Range bin	Description	Remarks
4080~4095	Padding data 16bytes	0 Fixed
3~4079	Radar picture data 3 - 4079	Valid
2	Radar picture data 2	Valid
1	Radar picture data 1	Valid
0	Radar picture data 0	Valid

PciVdo(16): Pci – Vdi format

Range bin	Description	Remarks	
16~4095	Radar picture data 0 - 4079	Valid	
15	Command register H	0 Fixed	
14	Command register L	0 Fixed	
13	End distance H	Valid	
12	End distance L	Valid	
11	Start distance H	0 Fixed	
10	Start distance L	0 Fixed	
9	Times of day H	0 Fixed	
8	Times of day L	0 Fixed	
7	Dummy	uncertainty	
6	PPS counter value H	0 Fixed	
5	PPS counter value M	0 Fixed	
4	PPS canter value L	0 Fixed	
3	External Tag H	0 Fixed	
2	External Tag L 0 Fixed		
1	Radar antenna azimuth H [65536 / 360] Valid		
0	Radar antenna azimuth L [65536 / 360] Valid		

PciRvi(4) : Pci – Rvi format

Range bin	Description	Remarks
4084~4095	Padding data 12 bytes	0 Fixed
4~4083	Radar picture data 0 - 4079	Valid
3	External Tag H	0 Fixed
2	External Tag L	0 Fixed
1	Radar antenna azimuth H [65536 / 360]	Valid
0	Radar antenna azimuth L [65536 / 360]	Valid

Range bin	Description	Remarks
16~4095	Radar picture data 0 - 4079	Valid
4~15	Padding data 12bytes	0 Fixed
3	External Tag H	0 Fixed
2	External Tag L	0 Fixed
1	Radar antenna azimuth H [65536 / 360]	Valid
0	Radar antenna azimuth L [65536 / 360]	Valid

PciRvi(16): Pci - Rvi format + 12 bytes padding

Nams(10): Nams format

Range bin	Description	Remarks
4090~4095	Padding data 6bytes (=0)	0 Fixed
10~4089	Radar picture data 0 - 4079	Valid
9	End distance H	Valid
8	End distance L	Valid
7	Start distance H	0 Fixed
6	Start distance L	0 Fixed
5	Radar antenna azimuth H [65536 / 360]	Valid
4	Radar antenna azimuth L [65536 / 360]	Valid
3	PPS times of day H	0 Fixed
2	PPS times of day MH	0 Fixed
1	PPS times of day ML	0 Fixed
0	PPS times of day L	0 Fixed

Nams(16): Nams format + 6bytes padding

Range bin	Description	Remarks
16~4095	Radar picture data 0 - 4079	Valid
10~15	Padding data 6bytes	0 Fixed
9	End distance H	Valid
8	End distance L	Valid
7	Start distance H	0 Fixed
6	Start distance L	0 Fixed
5	Radar antenna azimuth H [65536 / 360]	Valid
4	Radar antenna azimuth L [65536 / 360]	Valid
3	PPS times of day H	0 Fixed
2	PPS times of day MH	0 Fixed
1	PPS times of day ML	0 Fixed
0	PPS times of day L	0 Fixed

2.5.5 Admin Menu

This menu is a summary of the settings to be performed when the system is introduced. This is not used in normal. To display this menu, complete the following steps.

- i. Click the File of main menu with pushing the Ctrl key.
- ii. Select the Admin Menu of Menu.
- iii. Push the OK button after input the password. (Initial password: "Admin")



2.5.5.1 Radar Image

(1) A Scope

It is an item holder for the A Scope display.

1) Double Buffered

🔽 Double Buffered

Double Buffered: In case a radar picture is updated, it carries out through a buffer. Flicker when moving the image will be reduced by this function.

(2) B Scope

It is an item holder for the B Scope display.

1) Double Buffered

🔽 Double Buffered

Double Buffered: In case a radar picture is updated, it carries out through a buffer. Flicker when moving the image will be reduced by this function.

(3) Ppi Scope

It is an item holder for the Ppi Scope display.

1) Double Buffered

Double Buffered

Double Buffered: In case a radar picture is updated, it carries out through a buffer. Flicker when moving the image will be reduced by this function.

2.5.5.2 On Error Reboot

	1
It reboots, when an error occurs.	Forced reboot

If reboots, when an error occurs: Reboots the PC at error occurrence. Forced reboot: Reboots immediately. (Test use)

2.5.5.3 Admin Password

Admin Password 🛛	Admin
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Admin Password: Set the password to enter to display the Administrator menu.

2.5.5.4 Process

Process Priority	1 - High	•	CPU Select	🗖 СРИ О	🗖 CPU 2
Thread Priority	3 - Normal	•		🗖 CPU 1	🗖 CPU 3

Process Priority: Select the application process priority.

0 – Real time 1 – High 2 – Above Normal 3 – Normal 4 – Below Normal 5 – Idle High priority ↑ ↓ Low priority

Thread Priority: Select the priority of the application's main thread.

0 - Time Critical High priority 1 - Highest ↑ 2 - Above Normal 3 - Normal 4 - Below Normal 5 - Lowest ↓ 6 - Idle Low priority

CPU Select: (Not using)

2.5.5.5 Common Memory

It is an interface for providing other applications with a radar picture.

Common Memory	Main output	D:/画像配信XE2/Exe/(no name)::VDIeBuff
	Group core	D:/画像配信XE2/Exe/(no name)::CoreBuff

Main output: Output for shared memory name to the image processing module. Group core: Shared memory name for the final output.

2.5.5.6. Debug

For debugging (No discloser)

2.6 Startup parameter

The format of the command line parameters



The following control is possible by the command line parameter.

Command Line Parameter	Description
/ini=(Initialization file name)	Specify the initialization file.
	The default is to N_Solid.ini of module directory.
/log=(Failure log file name)	Specify the failure log file name.
	The default is to N_Solid.log of module directory.
/name=(Instance distinguished name)	Specify the unique identification name to create
	multiple instances in the PC.
/mem=(Shared memory name)	Specify the name of the destination shared
	memory of the captured radar image.

3. Specification

Transmitting frequency	: Non-chirp pulse	9,410MHz(P0N)
	Chirp pulse	9,440 ± 15MHz(Q0N)
	Non-Chirp/Chirp pu	ulse(P0N/Q0N) ^{*1}
Frequency Accuracy	: +/- 300ppm	
Transmitting power(Peak)	: 240W +1dB, -3dB	(120W~300W) ^{*2}
Transmitter Type	: Solid State Power	Amplifier(SSPA)
Transmission pulse width	: Refer to Transmiss	sion Table(1)
Pulse repetition frequency(PRF)	: Refer to Transmiss	sion Table(1)

Transmission Table(1)

	Pulse width			
No.	Non-chirp	Chirp	Non-chirp pulse /Chirp	PRF
	pulse	pulse	pulse	
0	0.07us	2.8us	0.07us/2.8us	2280Hz
1	0.15us	4.6us	0.15us/4.6us	2280Hz
2	0.3us	9.1us	0.3us/9.1us	2280Hz
3	0.15us	18.3us	0.15/18.3us	1280Hz
4	0.15us	28.0us	0.15us/28.0us	640Hz
5	0.3us	9.1us	0.3us/9.1us	1864Hz
6	0.6us	9.1us	0.6us/9.1us	1280Hz
7	0.07us	2.8us	0.07us/2.8us	4100Hz

Minimum Detection Signal(MDS) : -93dBm or less

A/D Sampling rate	: 16bit/84MHz
Pulse compression	: Provided
Video Processing function	: Interference rejection, CFAR and
	Coherent integration
Output signal	: Radar video and Trigger
Radar control/monitoring	: TCP/IP communication
Power supply	: DC48V ± 10%
Power consumption	: Less than 130W
Dimensions	: 554mm(W) x 330mm(D) x 580mm(H)
	(Including Mounting Plate)
Operation temperature range	: -15 ~ +50ºC, Non-condensing
Relative humidity	: 93% @+40ºC
Storage temperature range	: -25 ~ +60ºC
*1: Transmits both P0	N and Q0N at simultaneously

*2: Transmitting power is fixed.

2)	Radar	Control/Monitoring	PC display
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<u>Hardware</u>	
PC Model	: HP Z230 or equivalent/ 32 or 64bit Model
CPU	: Xeon 2.8GHz or more
Memory	: 4Gbyets or more

Hard Disk	: 500GB or more
NIC#1	: Gigabit (1000Mbps)
	Jumbo Frame more than 9014bytes
NIC#2	: Ethernet (1000Mbps/100Mbps/10Mbps)
OS	: Windows 7 Professional (32 or 64bit)
<u>Software</u>	
Feature	: Radar Control
	Radar Condition Monitoring
	Radar Echo Display
	NTP Time adjustment
	VNC Server