

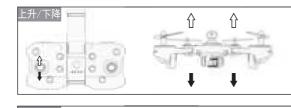


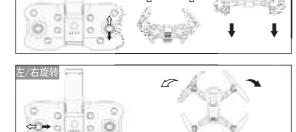
4.遥控器和无人机开关一开互相自动对码,如果飞行器上灯常亮表示

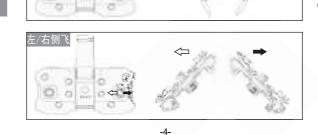
● 起飞流程 1.确保飞行器上的电池已充满电; 2.电池装入飞行器后按顶部的电源按键,蓝灯闪烁代表连接正常,将飞行器放置于水平地面,飞行器提示灯闪烁说明飞行器进入对码状态; 3.电池装入遥控器后将按下电源电键,蓝灯闪烁表示进入对码状态;

5.现在你可以推动动力遥控自由控制飞行器飞行。

● 飞行器方向操作

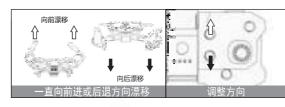






● 微调操作

如果飞行器中空中一直向某个方向漂移或自身在原地左/右旋转,可以通过以 下操作对飞行器进行细微调整,使飞行器达到平稳状态。





● 水平校准



■ 3D翻滚

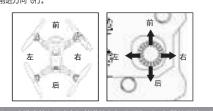
飞行器半空中可以做360度翻滚特殊动作 首先,将飞行器飞到高度为2~3米的空中, 按一下遥控器上右侧的按钮,遥控器会发出 "滴","滴","滴"的响声,这个时候 只要随意推一下将遥控器上的右摇杆,飞行器

就会向所打的方向做360度翻滚动作。



● 无头模式

当进入无头模式后,不管飞行器怎么旋转,遥控器只要推进前进方向,飞行器都是向原先 设定好的前进方向飞行。



● 低压保护

飞行器在空中飞行的时候出现所有指示灯闪烁代表电量低,提示紧急做返航操作。 慢速闪烁: 电池电量低

提示: 当出现低压提示的时候是禁止做360度翻滚操作的

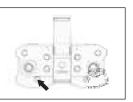
● 一键上升/一键下降

将飞行器放至于水平地面上,按遥控器"一键上升"按键,此时飞行器会自动上升 到1.5米的高度。

一键下降: 当飞行器停留在空中时,按遥控器左下角的一键下降按键,此时飞行器会自动降落到 地面。

● 强制停止

对于定高版本,当动力摇杆向下拉至 最底处时,飞行器并不会立即停止。 如右图中所示,按急停按键保持2秒钟 这是飞行器将会强制停止。

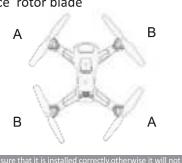


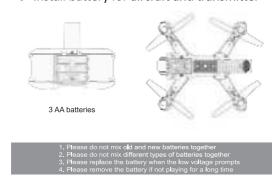






Replace rotor blade





Transmitter

Install battery for aircraft and transmitter

Battery changing

1.Remove thebattery from the aircraft

2.Insert the battery into the USBcharging cable

3. Insert the USB charging cable into the power of the computer USB interface, The red linght indicates than the battery is charging.

 Altitude hold function After using the left joystick(Accelerator) to control the ascending/dsescending flight



Ready to fly you aircraft

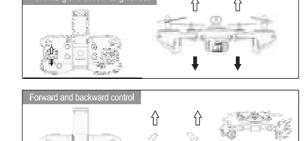
1. Make sure the battery on the aircraft is fully charged; After the battery is installed in the aircraft, press the power button on the top.The blue light flashes to indicate that the connection is normal. Place the aircraft on a level ground. The aircraft prompt light flashes to indicate that the aircraft

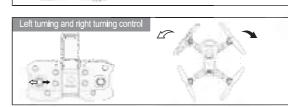
enters the code matching state; 3. After the battery is loaded into the remote control, press the power button, and the blue light flashes to indicate that it enters the code matching state;

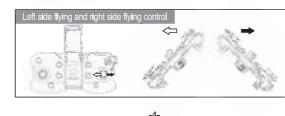
4. The remote control and the UAV will automatically pair codes with each other as soon as the switch is turned on. If the light on the aircraft is always on, the code pairing is completed.

5. Now you can push the power remote control to freely control the aircraft to fly.

Operating direction

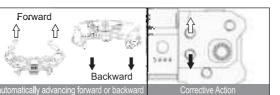


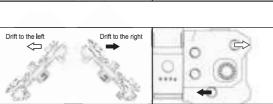




Fine-tuning operation

When the aircraft is hovering in the air, in the event that the aircraft is automatically advancing forward or backward, flying sideward on the





Horizontalcalibration

You can use the horizontal calibration function to calibrate the aircraft when it drifts in a certain direction in the air or when it rotates on the spot. Place the aircraft on a horizontal surface, move the direction control lever on the remote control, and the remote control emits a beep. At the same time, the blue light of the aircraft flashes. Wait for



3D eversion

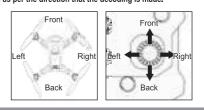
When youare familiar with the basic operation,you can do some awesome& exciting tricks and stunts!First of all,fly the aircraft to a heighe of more than 3 meters, press the 3DEverstion switch on the rear righr side of the transmitter, then push the righr rudder(in any direction)



Headless function

No matter which direction the aircraft may rotate to,the flying direction direction will be as per the direction that the decoding is made.

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Low-voltage protection

 $\ensuremath{\mathsf{AII}}$ lights flashing indicates that the battery is low when the aircraft is flying in the sky. Slow flashing:Battery low power

One key to rise/down

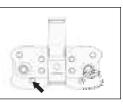
When the aircraft is on the ground, Press the button "One key to ries" on transmitter,At this time the aircraft will aitomatically rise to a height of 1.5

One key to down:

When the aircraft stays in the air, press the descending button in the lower left corner of the remote control, and the aircraft will automatically descend to the ground at this time.

Forced stop

For fixed versions, the aircraft does not stop immediately when the power $% \left\{ 1,2,\ldots ,n\right\}$ remote rod is pulled down to the lowest level. As shown in the figure on the right, press the emergency stop button for 2 seconds, and the aircraft will force it to



FCC Statement

This equipment has been tested and found to comply with the limits for a Class B digital device, pursuant to Part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference in a residential installation. This equipment generates uses and can radiate radio frequency energy and, if not installed and used in accordance with the instructions, may cause harmful interference to radio communications. However, there is no guarantee that interference will not occur in a particular installation. If this equipment does cause harmful interference to radio or television reception, which can be determined by turning the equipment off and on, the user is encouraged to try to correct the interference by one or more of the following measures:

- -- Reorient or relocate the receiving antenna.
- -- Increase the separation between the equipment and receiver.
- -- Connect the equipment into an outlet on a circuit different from that to which the receiver is connected.
- -- Consult the dealer or an experienced radio/TV technician for help.

This device complies with part 15 of the FCC Rules. Operation is subject to the following two conditions:

(1) This device may not cause harmful interference, and (2) this device must accept any interference received, including interference that may cause undesired operation.

Changes or modifications not expressly approved by the party responsible for compliance could void the user's authority to operate the equipment.

portable device statements

The device has been evaluated to meet general RF exposure requirement. The device can be used in portable exposure condition without restriction.