# BlueRS+C2

Bluetooth Serial Adapter

User manual

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### 1 Introduction

We are very pleased to see that you have bought a Stollmann product and would like to express our appreciation.

This documentation is valid for the following models of the BlueRS+C2 product family

- BlueRS+C2-MF5 (plug on module, antenna internal, 5V DC)
- BlueRS+C2-MF3 (plug on module, antenna internal, 3.3V DC) on request
- BlueRS+C2-MS5 (plug on module, antenna external, 5V DC) on request
- BlueRS+C2-MS3 (plug on module, antenna external, 3.3V DC) on request
- BlueRS+C2-DF (desktop model, antenna internal)
- BlueRS+C2-DS (desktop model, antenna external) on request
- Software versions V1.124.003 or later

### 1.1 Product description

The BlueRS+C2 is an Bluetooth adapter with the following functions.

- The BlueRS+C2 connects devices with a **serial port** to any Bluetooth link. It gives access to other devices situated in the same Bluetooth area (piconet).
- Data can be transmitted with the following rates:
  - limited by the baudrate of the serial link from 1200 up to 230400 baud.
- The connected serial device can drive the BlueRS+C2 by using
  - asynchronous AT commands
  - automatic connection setup

The following profiles are supported:

- One serial profile for transparent data communication through the Bluetooth link.
- A second serial profile for management access from another Bluetooth device using a Bluetooth link.

BlueRS+C2 may be used in two product versions:

- The BlueRS+C2 module may be integrated into different devices and connects them with the Bluetooth interface via a serial TTL/CMOS compatible interface. These modules are referenced as BlueRS+C2-Mxx in this document and represents the product types BlueRS+C2-MF5, BlueRS+C2-MF3, BlueRS+C2-MS5, BlueRS+C2-MS3.
- The BlueRS+C2 **Desktop** device is an external device that connects the terminal equipment with the Bluetooth interface via a serial V.24 / RS-232 interface.

These devices are referenced as **BlueRS+C2-Dx** in this document and represents the product types BlueRS+C2-DF, BlueRS+C2-DS.

Please refer Appendix A1: for information about the differences.

# 1.2 Safety

The BlueRS+C2 is conform to the European safety requirements IEC 60 950. Please use only the delivered power supply or an original replacement from Stollmann.

The homologation for the Bluetooth compatibility tests according the Bluetooth standard V1.1 has been started.

## 1.3 Hints for using the BlueRS+C2 in the United States,

This device complies with Part 15 of the FCC Rules and with RSS-210 of Industry Canada.

Operation is subject to the following two conditions:

- 1. This device may not cause harmful interference
- 2. This device must accept any interference received, including interference that may cause undesired operation.

The radiated output power of **BlueRS+C2** is far below the FCC radio frequency exposure limits. Nevertheless, the **BlueRS+C2** shall be used in such a manner that the potential for human contact during normal operation is minimized.

This equipment has been tested and found to comply with the limits for a Class B digital device, pursuant to Part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference in a residential installation. This equipment generates, uses and can radiate radio frequency energy and, if not installed and used in accordance with the instructions, may cause harmful interference to radio communications. However, there is no guarantee that interference will not occur in a particular installation. If this equipment does cause harmful interference to radio or television reception, which can be determined by turning the equipment off and on, the user is encouraged to try to correct the interference by one or more of the following measures:

- Reorient or relocate the receiving antenna.
- Increase the separation between the equipment and receiver.
- Connect the equipment into an outlet on a circuit different from that to which the receiver is connected.
- Consult the dealer or an experienced radio/TV technician for help.

# Warning:

Changes or modifications made to this equipment not expressly approved by **Stollmann E+V GmbH** may void the FCC authorization to operate this equipment

### 2 Installation

### 2.1 Contents

This packet contains the following items:

- Bluetooth Serial adapter BlueRS+C2
- Mains plug power supply adapter (only BlueRS+C2-Dx)
- DTE interface serial cable (only BlueRS+C2-Dx)
- This user manual

# 2.2 Installation procedure

The following installation procedure is typical for the desktop model BlueRS+C2-Dx. For all plug in modules the installation is dependent on the overall system and has to be referred there.

Desktop model only:

To start using the BlueRS+C2-Dx, please follow these steps:

- Connect the serial port (DTE) of the BlueRS+C2 to the serial port (COM-port) of a PC or other serial terminal equipment by using the supported DTE interface serial cable.
  - Please make sure that the COM-port of the PC is not used for other purposes or by other communication programs.
- Connect the power supply to a standard AC outlet. Please reference to page 5 for selecting the correct plug for interfacing.
- The green LED on the BlueRS+C2-Dx front panel will come on to indicate that the device has been power up. After some seconds the green LED will start blinking to indicate power save mode.
- Optionally: Configure the BlueRS+C2-Dx Bluetooth interface if needed. Configuration is required especially if you want to automatically connect to another Bluetooth device (set up the remote Bluetooth address).

The BlueRS+C2 is now ready for use with Bluetooth links, please refer to the next chapter for the configuration to use the terminal equipment together with the BlueRS+C2.

## 2.3 Displays and control elements BlueRS+C2-MF5 desktop model

For interfacing the module version please refer to the appendix. At the back of the BlueRS+C2 you will find the connectors for the following devices:

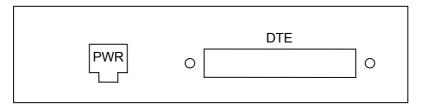


Fig. 2: Back view of the desktop model BlueRS+C2

PWR: external power supply (5V DC)

DTE: V.24 interface for DTE, i.e. a PC

You can control the status of the BlueRS+C2 via two LEDs at the front side.

Fig. 3: Front view of the desktop model BlueRS+C2

Both of the LEDs, **L1** (green) and **L2** (yellow), show the overall status of the BlueRS+C2 in coded form. The following list describes the view for an error free power on sequence of the BlueRS+C2.

|       | Status          |           |                        | L1                  | L2        |                |
|-------|-----------------|-----------|------------------------|---------------------|-----------|----------------|
| 1.    | Power-On-P      | hase, E   | Bootloader, wait       | $oldsymbol{\Theta}$ | Θ         | (about 2 sec)  |
| 2.    | Power-On-P      | hase, I   | nitializing, wait      | $oldsymbol{\Theta}$ | 0         | (about 10 sec) |
| 3.    | Ready, Initia   | lization  | ı ok                   | $\otimes$           | 0         |                |
| 4.    | Ready, Initia   | lization  | ok, power save         | Ø                   | 0         |                |
| 5.    | Connected,      | Bluetoo   | oth link established   | $\otimes$           | $\otimes$ |                |
| LED L | egend:          | $\otimes$ | On,                    | Ο                   | Off       |                |
|       |                 | Θ         | Continuously blinking, | Ø                   | flashir   | ng             |
| A con | nplete list you | can fin   | d in the appendix "LED | displays"           | •         |                |

# 3 Using the BlueRS+C2

Before using the BlueRS+C2 the address of another Bluetooth device has to be selected - if not predefined by factory – that shall be the communication partner in the Bluetooth link.

The compatible devices can be scanned using the configuration command "bdinq". From that list one Bluetooth device has to selected.

If you are using an automatic connecting mode that Bluetooth address has to be entered and stored using the configuration command "brad" (see BlueRS+C2Configurator activation on page 24).

You can select different operation modes for the BlueRS+C2. These operating modes are used to control Bluetooth links and to configure the BlueRS+C2.

### Supported operating modes:

- Automatic connecting deriving from DTR or always connected.
- Automatic accepting of incoming connections.
- Asynchronous mode for devices that need the AT command set.

You can configure the BlueRS+C2 in the following ways:

- by using BlueRS+C2Configuration commands entered by the locally connected PC.
- by using the AT command set entered by the locally connected PC.
- by using BlueRS+C2Configuration commands entered via the Bluetooth link (remote configuration).

### 3.1 Automatic connection establishment

Automatic connection establishment is available in the following modes:

- An automatic connection will be initiated when control line DTR is on.
- An automatic connection will be initiated when transmit data is received from the DTE device. All data received before the Bluetooth connection is established will be buffered inside the BlueRS+C2 and automatically sent via the Bluetooth link.
- An Automatic connection will be initiated independent of any status line automatically after power up and initialization.
- No connection establishment initiated by this module. Bluetooth connection requests from other Bluetooth devices will be automatically accepted (if compatible).

To enable automatic call you have to set BlueRS+C2Configuration parameter "cmds" to 6, 7, 8 or 13 (see below).

An established connection will be indicated by a status line (default: DCD). See also configuration commands "cdcd" and "cdtr".

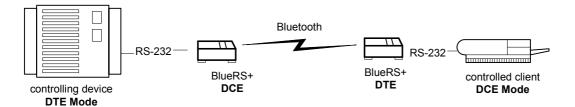
If a connection cannot be established successfully an automatic retry will be started. The duration of trying to establish the connection and the pause for next retry can be configured.

The Bluetooth device to be accessed is taken from the parameter "brad", it has to be set up to the Bluetooth device address of the remote Bluetooth device. Additionally the server channel has to be set up if not fitting to the default (1), see parameter brsch.

| cmds 6        | Automatic connection establishment when DTR is ON.  |
|---------------|---|
| cmds 7        | Automatic connection establishment when transmit data are received by the BlueRS+C2.                                      |
| cmds 8        | Automatic connection establishment independent of any status line.  |
| cmds 12       | No connection establishment initiated by this module.   |
| cato n        | call abort of a not successful call after <i>n</i> seconds.<br><i>n</i> ={3255}, default: <b>15</b> seconds.              |
| capa <i>n</i> | call pause for $n$ seconds before next call attempt. $n = 0$ : no call retry. $n = \{0255\}$ , default: <b>3</b> seconds. |

Hint: The configuration command "idle" can be used, to automatically disconnect after a predefined time without data transmission.

# Example:



Setting of BlueRS+C2 **DCE**:

cmds=8

brad= boad of BlueRS+C2DTE

Setting of BlueRS+C2 **DTE**:

cmds=12

Don't forget to set the baudrate to the correct setting.

### 3.2 AT command set for BlueRS+C2

All parameter can be changed by using an extended AT command set described in this chapter.

Please check if the factory setting will fit with your environment. The factory setting is described (highlighted) in the parameter list below.

If you want another configuration as set in the factory default setting, please do the following steps:

- Connect the PC's com-port to the DTE interface of the BlueRS+C2.
- Connect the power supply to the mains socket.
- Start a terminal emulation on your PC, please verify that the baudrate setting of the terminal emulation fits those of the BlueRS+C2.
- Set up the parameter of the BlueRS+C2 from the terminal emulation and save the parameter using the AT command set.

Example:

To change the access mode to restricted please enter the following commands:

**AT\*\*BRESTR=1**<→ (set restricted mode to ON) **AT&W**<→ (store the new configuration)

• Leave your terminal emulation and start your application program.

With the exception of the command **A**/ (Repeat command) all commands begin with the prefix **AT** and are terminated with <,...>. Corrections in a command line are done with <BACKSPACE>. A command line has a maximum of 80 characters. The command line is automatically cancelled by longer input. Blanks are ignored, capital/small letters are not significant.

The parameter settings of the BlueRS+C2 obtained when using the AT commands can be permanently stored (AT&W) and are not lost by resetting or by leaving the AT command mode.

To enter the AT command mode during an active data connection you must use the following sequence ("Escape sequence"):

at least 1 sec pause <+><+> 1 sec pause

The time gap between all three plus signs may not exceed 1 sec.

The escape sequence is transmitted transparent to the remote device.

By using initialization strings to configure the TA which includes more than one parameter to be configured please follow the examples below:

• Initialization string includes standard AT commands:

AT&F&D2&C1E0&W

By using a special configuration command (at\*\*<cmd>) in the initialization string you have to set a semicolon <;> in case that additional commands will follow.

 Initialization string includes special AT commands: AT&F\*\*BR=8;&D2&C1E0&W

### Supported commands:

### A/

# Repeat last command line

This command repeats the commands of the last entered command line. Note: No prefix **AT** is required.

A/

### Α

# Accept incoming call

Using this command you can accept an incoming call, if automatic call acceptance is not set (Register S0 = 0). An incoming call is always displayed by the message "RING" or the code "2", also if automatic call acceptance is selected.

Must be the last command in an AT command line.

### CONF

### Enter BlueRS+C2Configurator

Enters directly into the BlueRS+C2Configurator, the configuration prompt "#" will be displayed. Leave the BlueRS+C2Configurator with the command "quit" (or "exit" or "go").

**ATCONF** 

### &C

### DCD control

Selects the behavior of the DCD control line from the BlueRS+C2.

AT&C BlueRS+C2 control line DCD is always ON

AT&C1 DCD ON indicates Bluetooth connection is established (default)

AT&C2 DCD line follows DTR
AT&C4 DCD follows remote DCD

#### D

### Initiate Bluetooth link

This command addresses a Bluetooth device directly through it's address or name. If a connection to a Bluetooth device requiring the restricted mode the pin has to be set up using command AT\*\*BPIN.

The link request will time out, if the Bluetooth address is not valid (about 6 seconds).

### ATD <br/> drad>|dx

brad: called Bluetooth remote device address (12 digits)

**dx:** references called Bluetooth remote device service number in bdlist (d1..d9).

This command must be the last command in an AT command line.

Any character input while the RS+ is dialing will cancel the dialing procedure.

### Examples:

ATD 0080371443AB Connect to Bluetooth device 0080371443AB ATD d1 Connect to 1<sup>st</sup> Bluetooth device in *bdlist* (server channel number defined in *brsch*)

#### Note:

The remote Bluetooth device has to be determined before issuing this link request. This can be done in the following ways:

- get it manually by reading from the sticker of the remote Bluetooth device.
- Inquire the address and service by using the commands AT\*\*BDINQ and AT\*\*BDLIST.

Give the BlueRS+C2 about 10 seconds after Reset to initialize before issuing the first command.

### **&D** DTR control

Selects the behavior of the BlueRS+C2, when the DTE control line DTR changes from ON to OFF.

AT&D DTE control line DTR setting is ignored

AT&D2 DTE control line DTR is evaluated: dropping the DTR line by the

DTE will disconnect an existing Bluetooth link.

An incoming call will be accepted only with DTR active.

**AT&D4** DTE control line DTR is partly evaluated:

- dropping the DTR line by the DTE will disconnect an existing

Bluetooth link (default).

- An incoming call will be accepted independent of DTR status.

| _        | 1 1 1      |
|----------|------------|
| -        | Local echo |
| <b>L</b> |            |

Selects the local echo in command mode.

ATE No local echo

ATE1 Local echo on in command phase (default)

### &F

### Load factory defaults

Factory default will be loaded. (for storing in non volatile memory please use the command AT&W).

AT&F setup all parameter concerning data port.

AT&F1 setup all parameter including Bluetooth specifics and passwords.

# H Disconnect

Disconnects existing Bluetooth connection, after issuing the escape sequence (see page 9).

ATH

### I Display version information

Displays different information about version number and settings:

ATI Returns the "Modem"-type; name of the terminal adapter ("BlueRS+C2")

ATI1 Returns "0"

ATI2 Returns "OK"

ATI3 Returns version string: "V1.xyz"

ATI4 Returns manufacturers name: "Stollmann E+V GmbH"

ATI5 Returns "OK"

ATI6 Returns copyright string: "(c) Copyright Stollmann GmbH"

ATI7 Returns "OK"

ATI8 Returns "ERROR"

ATI9 Returns "OK" (Plug&Play ID-Request not supported)

ATI77 Returns Bootloader version string

ATI99 Returns software creation date

### &K

### Flow control

Selects the flow control behavior of the BlueRS+C2 while in data communication phase.

AT&K No local flow control between the DTE and BlueRS+C2 is used AT&K3 Local flow control is set to hardware handshake RTS/CTS

(default)

AT&K5 Local flow control is set to hardware handshake RTS/CTS

additionally in AT command phase

#### Return to online state 0

If the BlueRS+C2 is in command mode after issuing an escape sequence out of an existing connection, ATO brings the BlueRS+C2 back to data phase. Must be the last command in AT command line.

ATO

# Q Suppress results

With this command result codes or messages can be suppressed.

Returns status - codes after command input (default) ATQ

ATQ1 No result codes are returned

#### &R CTS control

Selects the behavior of the CTS control line from the BlueRS+C2.

BlueRS+C2 control line CTS is following all changes of RTS AT&R

CTS is always ON (default) **AT&R1** AT&R2 AT&R1

BlueRS+C2 control line CTS is following all changes of DTR

BlueRS+C2 control line CTS is following all changes of remote AT&R3

CTS (set for cable replacement)

#### S Display and set internal S register

ATSnn? Show actual values (decimal) of selected register *nn* ATS*nn*=xxx Set selected register *nn* to the decimal value xxx.

See S register definitions on page 21.

#### &S DSR control

Selects the behavior of the DSR control line from the BlueRS+C2.

| AI&S  | BlueRS+C2 control line DSR is always ON (default)             |
|-------|---|
| AT&S1 | DSR ON indicates Bluetooth link is established                |
| AT&S2 | BlueRS+C2 control line DSR is following all changes of DTR    |
| AT&S3 | BlueRS+C2 control line DSR is following all changes of DCD    |
| AT&S4 | BlueRS+C2 control line DSR is following all changes of remote |
|       | DSR (set for cable replacement)                               |
| ΔT&S5 | reserved  |

AT&S5 reservea

| V Result format |  | Result format  |
|-----------------|--|--|
|                 | ATV<br><b>ATV1</b>   | Result is presented as numbers (followed by <¬>) Result is presented as text (default)   |
| &V              |  | Display configuration  |
|                 | AT&V<br>AT&V1  | Displays the actual configuration of AT command setting Displays the actual configuration of extended AT command setting                 |
| W               |  | Extended result codes  |
|                 | <b>ATW</b><br>ATW1   | Result is presented without extended result codes. Result is presented with extended result codes, Result messages include error causes. |
| &W              |  | Store active configuration   |
|                 | The active configuration will be stored in non volatile memory. AT&W |  |
| Z               | Load stored settings   |  |
|                 | _  | juration will be reset to the stored configuration. command in an AT command line.   |
| **DBITS         |  | Number of data bits <i>x</i> asynchronous chars (7, <b>8</b> )   |
|                 | nber of data I<br>AT**DBIT<br>e: only valid                          |  |
| **PF            | PRTY Set parity of asynchronous characters                           |  |

**0**: no parity; 1: even parity; 2: odd parity

**AT\*\*PRTY=0** No parity (default)

AT\*\*PRTY=1 Odd parity
AT\*\*PRTY=2 Even parity
AT\*\*PRTY=3 Space parity
AT\*\*PRTY=4 Mark parity

Notes:To use other data formats than 10 bit (= (N1, 7E1, 7O1) you have to set br to fixed speed.

- only valid for br <> 0.

### 3.2.1 Bluetooth specific AT commands

### **Setting up special Bluetooth parameter:**

### \*\*BACCTAB

Show pairing information

To show the pairing information (setup due to a successful restricted connection) within the BlueRS+C2 you have to issue the command "AT\*\*BACCTAB".

Example: at\*\*bacctab

Response: 1: used: YES BD: 00803714ECA4 name:

OK

#### \*\*BDEL

### Delete pairing information

To delete the pairing information (setup due to a successful restricted connection) within the BlueRS+C2 you have to issue the command "AT\*\*BDEL 1" . The paired Bluetooth device can be read out by the command "AT\*\*BACCTAB".

Example: at\*\*bdel 1

Response: OK

### \*\*BDINQ

### Inquire Bluetooth devices

With this request the automatic scan of all discoverable Bluetooth devices will be initiated.

As a result the creation of the list *bdlist* will be initiated. The list can be read out using the command at\*\*bdlist. If the Inquiry-scan has not been terminated while issuing the command at\*\*bdlist, the BlueRS+C2 will return "inquiry active".

The entries contain the Bluetooth device address, the Bluetooth device names and available services (profiles).

The creation of this list may take up to 20 seconds due to the reaction time of the accessible Bluetooth devices, a maximum of 9 Bluetooth devices can be listed.

When issuing the command "at\*\*bdinq 1" the inquiry scan will only request the Bluetooth addresses, name and service inquiry will not be performed. The maximum waiting time for responses of the Bluetooth devices is limited by a time defined with the command "at\*\*bingtim".

Example: at\*\*bding request Bluetooth devices with name and service.

Response: OK

at\*\*bding 1 request Bluetooth device addresses only

Response: OK

### \*\*BDLIST

### Show inquired Bluetooth devices

With this request the list of found Bluetooth devices will be returned, the entries show the Bluetooth device address and the Bluetooth device name requested by the command *at\*\*bdinq*. For every Bluetooth device in addition the available services (profiles) will be shown.

These entries can be accessed by the selectors *d1* .. *dn* to address the Bluetooth device and the selectors *s1* .. *sn* to address the Bluetooth devices service channel.

Example: at\*\*bdlist

Responses: d1: <bradr1>, <bname1>

s1: <service1>, <server channel>, <bsname1>
s2: <service2>, <server channel>, <bsname2>

d2: <badr2>, <bname2>

s1: <service1>, <server channel>, <bsname3>

OK

or

inquire active; if the search initiated by at\*\*bding

OK; is still active

or

list empty ; no Bluetooth device found

OK

**brad** found Bluetooth remote device address (12 digits)

**bname** found Bluetooth remote device name

**service** coding of service type

**server channel** used channel number for service type

### \*\*BINQTIM

### Timeout for Inquiry Scan

With this command the Inquiry Scan time will be limited to the configured value (default: 8 = 10 seconds). See also command at\*\*bding.

Allowed values: 1 to 48 (1,25 sec to 60 sec).

Example:  $at^*$ binqtim=n set maximum wait time to n \* 1.25 seconds

at\*\*binqtim=2 set maximum wait time to 2.5 seconds

### \*\*BNAME

### BlueRS+C2 own device name

Defines the device name. bname is shown on a remote Bluetooth terminal

device during a Service Discovery sequence It is a string constant according to V.250.

Example: at\*\*bname show own device name

at\*\*bname=<rs+name> set own device name to rs+name

### \*\*BRAD

### Bluetooth Device Remote Address

With this command you can setup the Bluetooth address of the other Bluetooth device, that should be connected using an automatic link setup.

### Example:

AT\*\*BRAD=0080371443AB

### \*\*BRNAME

Displays connected device name

Displays the device name of the connected Bluetooth device.

This value is can not be changed.

Example: at\*\*brname show connected device name

### \*\*BRSCH

### Set remote Bluetooth server channel

Set up server channel of the remote Bluetooth module, to that the Bluetooth link shall be established.

The own server channel number is fixed to 1, only used for accepting Bluetooth links.

Remote management between BlueRS+C2 is achieved using the server channel 30.

default: 1

Example: at\*\*brsch=1

### \*\*BSNAME

### BlueRS+C2 service name

Defines the service name of the BlueRS+C2. bsname is shown on a remote Bluetooth terminal device during a Service Discovery sequence.

Example: at\*\*bsname

at\*\*bsname=<rs+srvname> set own device name to rs+srvname

default: "BlueRS+C2 serial port"

Note:

To activate a new name for discoveries you have to make a power off/on cycle.

### \*\*BRESTR

#### Set restricted mode

Control the restricted mode for exchanging the Pin (Passkey). When set to 1 the setting of parameter bpin will be used to verify a pin with the requesting Bluetooth device.

The pins of two bluetooth devices have to set to the same value, if one of these devices allows only restricted connections. If a restricted connection has been established one time between two Bluetooth devices these devices know each other and are called as "paired" (see command "AT\*\*BACCTAB" for information about the paired Bluetooth device).

After a pairing has taken place Bluetooth links can be established between these paired devices independent of the setting of the restricted mode!

To delete the pairing information within the BlueRS+C2 you have to issue the command "AT\*\*BDEL 1".

### \*\*BPIN

### Bluetooth device Pin (Passkey)

Set the Pin for establishing a connection in the restricted mode by the command "AT\*\*BPIN=<old\_pin>,<newpin>".

This Pin is always checked if

- the BlueRS+C2 is set to restricted mode
- the BlueRS+C2 is not set to restricted mode and the other Bluetooth device is set to restricted mode.

The Pin has a fixed length of 4 digits, factory default: **0000**.

To reset the Pin to factory default please use the command AT&F1 (all parameter will be set to factory default.

Example: at\*\*bpin=0000,1234set Pin to 1234 (old Pin was 0000)

Note: After a pairing has taken place (Pin sucessful exchanged) Bluetooth links can be established between these paired devices independent of the setting of the restricted mode and the Pin!

#### \*\*BOAD

### Bluetooth Device Own Address

With this command you can read out the own Bluetooth device address. This value is can not be changed.

Example:

AT\*\*BOAD

### \*\*<cmd>

### Execute configuration command

Executes one configuration command, for definition of commands see page 27. AT\*\*<*cmd*>

More than one configuration command have to be separated by a ";". AT\*\*cmd1;\*\*cmd2

### 3.2.2 AT command S register set

| S0        | 0: No automatic call acceptance, acceptance of an incoming call is controlled by the data terminal (command ATA after RING)  1: Immediate call acceptance by the terminal adapter (default)  2n: Call acceptance through the terminal adapter after n "RING" messages. |  |
|-----------|--|--|
| S2        | Escape Character (default = 43h)   |  |
| S3        | Carriage Return Character (default = 13)   |  |
| <b>S4</b> | Line Feed Character (default = 10)   |  |
| <b>S5</b> | Backspace Character (default = 08)   |  |
| <b>S7</b> | Wait time for Carrier (sec) (default = 30 sec)   |  |
| S9        | Enable PNP functionality for Windows95 (default=1, enabled)  |  |
| S91       | 0: default   |  |
|           | 1: all unknown AT commands will be answered with OK.   |  |
|           | 2: Windows 2000 compatibility: some AT commands will be answered with OK, unknown AT commands will be answered with OK.  |  |

### 3.2.3 AT result codes

### Result codes (numerical and verbose):

| Code | Text                  | Meaning  |
|------|-----------------------|--|
| 0    | OK                    | Command completed  |
| 1    | CONNECT < radr>       | Connection established   |
| 2    | RING <radr></radr>    | Indicates an incoming call (Link request received)                                   |
| 3    | NO CARRIER<br>berr>   | No synchronization (berr = BT error cause)   |
| 4    | ERROR                 | Illegal command or error that can not be indicated otherwise                         |
| 6    | NO DIALTONE<br>berr > | No access to Bluetooth? network (berr = BT error)                                    |
| 7    | BUSY < berr >         | Number engaged (berr = BT error cause)   |
| 8    | NO ANSWER < berr >    | No connection; addressed Bluetooth device can not be reached (berr = BT error cause) |

### **Error cause display:**

< berr > = BT release (error) cause, hexadecimal

Example: NO CARRIER <0104>

In AT command mode, error cause display (does not belong to the AT command standard) can be turned on by issuing the command ATW1 (default). The shown error causes use the coding defined by the Bluetooth definition (see page 36).

## 3.3 Cable replacement

A pair of BlueRS+C2 devices can be used to operate as a RS232 cable replacement. Typically one BlueRS+C2 has to operate as a DCE interface ("BlueRS+C2DCE", DSU9 female) and the other one as a DTE interface ("BlueRS+C2DTE", DSUB9 male). These devices have to be ordered with the correct interfaces.

When ordering a pair of BlueRS+C2 both devices will have the correct setting to operate without changing any parameter. The default behavior is as follows:

- The Bluetooth link is established directly and automatically after powering on from the BlueRS+C2 operating in DCE mode
- the restricted mode is disabled
- data transfer is transparent set to baudrate 115200 bit/s
- all status lines are transparently transferred to the other device (local flowcontrol is disabled).
- LED2 shows the Bluetooth connection status (ON = link established)

In detail the following settings differ from the factory default setting:

### BlueRS+C2DCE:

| cmds 8    | Automatic connection establishment independent of any status line.                     |
|-----------|--|
| cdtr 0    | DTR line is not controlling the Bluetooth link   |
| cdsr 4    | DSR Output line of <b>BlueRS+C2</b> DCE follows DSR input line of <b>BlueRS+C2</b> DTE |
| ccts 3    | CTS Output line of BlueRS+C2DCE follows CTS input line of                              |
|           | BlueRS+C2DTE   |
| cdcd 4DCD | Output line of <b>BlueRS+C2</b> DCE follows DCD input line of <b>BlueRS+C2</b> DTE     |
| cri 1     | RI Output line of <b>BlueRS+C2</b> DCE follows RI input line of                        |
|           | BlueRS+C2DTE   |
| flc 0     | no hardware flowcontrol  |

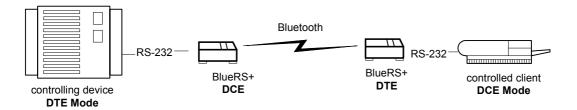
#### BlueRS+C2DTE:

| CO. OZD I L. |   |
|--------------|---|
| cmds 12      | Only acceptance of incoming Bluetooth link requests.          |
| cdtr 0       | DSR line is not controlling the Bluetooth link (DTR is mapped |
|              | internally to DSR)  |
| cdsr 4       | DTR Output line of BlueRS+C2DTE follows DTR input line of     |
|              | BlueRS+C2DCE (DTR is mapped internally to DSR)                |
| ccts 3       | RTS Output line of BlueRS+C2DTE follows RTS input line of     |
|              | BlueRS+C2DCE (RTS is mapped internally to CTS)                |
| flc 0        | no hardware flowcontrol                                       |
|              |   |

Note: to readout the mode of operation of the **BlueRS+C2** please use the command "devmode".

Don't forget to set the baudrate to the correct setting.

# Example:



# 3.4 Table of coding of Bluetooth services

List of Bluetooth services (profiles):

| Code | Text                | Meaning                                   |
|------|---------------------|---|
| 1101 | SerialPort          | Serial port, serial data link without any |
|      |                     | restriction                               |
| 1102 | LANAccessUsingPPP   | Lan Access with PPP protocol              |
| 1103 | DialupNetworking    | Dial Up Networking to establish switched  |
|      |                     | connections to the ISDN or PSTN           |
| 1104 | IrMCSync            |   |
| 1105 | OBEXObjectPush      | OBEX Object Push                          |
| 1106 | OBEXFileTransfer    | OBEX Filetransfer                         |
| 1107 | IrMCSyncCommand     |   |
| 1108 | Headset             | Headset access via Bluetooth              |
| 1109 | Cordless Telephony  |   |
| 1100 | Intercom            |   |
| 1111 | Fax                 | Fax                                       |
| 1112 | HeadsetAudioGateway | Headset Gateway for audio signals         |
| 1113 | WAP                 |   |
| 1114 | WAP_CLIENT          |   |

# 4 BlueRS+C2 Configurator command set

The settings of the BlueRS+C2 for the serial interface and the Bluetooth interface are called configuration. The BlueRS+C2 is delivered with a set of pre-set values. In the following section it will be shown how, by using the configuration commands, you can examine the configuration of the BlueRS+C2 and if necessary change it. The values can be stored in non volatile memory; this means they'll remain unchanged even if the power supply is disconnected.

You can configure the BlueRS+C2 in the following ways:

- by using BlueRS+C2Configurator commands entered by a locally connected PC.
- by using the AT command set entered by a locally connected PC.
- Seite: by using BlueRS+C2Configurator commands entered via the Bluetooth link (remote configuration).

The BlueRS+C2Configurator can be entered in the following ways:

- by entering a special escape sequence (default: "!!!") after initialization independent whether a Bluetooth link is established or not.
- by using a special command from the asynchronous dialup command interface (AT: "ATCONF").
- Seite: 24 remote via a Bluetooth connection from another Bluetooth device.
- or escape sequence in power up phase if enabled (rsttim>10, rstmsg=1).

# 4.1 Configuring the BlueRS+C2 after power on

- Connect the PC's com-port to the DTE interface of the BlueRS+C2.
- Start a terminal emulation program (i.e. Hyper-Terminal) with the following settings: 9600 Baud, 8 databits, No Parity (8N1)
- Connect the BlueRS+C2 to the mains by the mains plug adaptor
- Wait until LED 2 starts blinking (after about 5 sec, see config cmd "rsttim") and the message to enter the config-sequence is displayed:

"+++ Press <CR>,<CR>,<ESC>,<ESC> to enter BlueRS+C2Configurator

- Type in quickly within 2 seconds after the message appears: <RET> <RET> <ESC> <ESC>, to call up the **BlueRS+C2**Configurator.
- The **BlueRS+C2**Configurator acknowledges by giving a welcome string and a "#" as the prompt character. Now you can work with the **BlueRS+C2**Configurator by using the configuration commands (see page 27).
- Setup the parameter for the BlueRS+C2 from your terminal program and store them.

Example:

To **set** the baudrate to 9600 baud please enter the following commands:

**br=4**<¬> (set baudrate to 9600 baud) **save**<¬> (store the new configuration)

quit<, (leave the BlueRS+C2Configurator and activate the new

value settings)

Hint: The active set of parameters can be displayed on screen by the **BlueRS+C2**Configurator with the command **"show**<...>".

Leave the terminal program and start your application.

Now you can use the **BlueRS+C2** with the new set of parameters by running the needed PC program.

## 4.2 Configuring the BlueRS+C2 with AT commands

To execute one BlueRS+C2Configuration command *cmd* out of the AT command mode you have to issue the command: "at\*\**cmd*".

To call up the BlueRS+C2Configurator please use the command "atconf".

You can leave the BlueRS+C2Configurator by the command "quit" (or "exit" or "go").

# 4.3 Remote Configuration using the TA+Configurator commands

The BlueRS+C2 to be configured is referred here as "remote BlueRS+C2".

The BlueRS+C2 to configure is referred as "local BlueRS+C2".

Please make sure that the *remote* BlueRS+C2 to be configured at the other end is powered up.

- Connect the PC's com-port to the DTE interface of the local BlueRS+C2.
- Connect the power supply to the mains socket.
- Start a terminal emulation program (i.e. Windows-Terminal)
- Configure the *local* BlueRS+C2 with the special service channel 30 (brsch=30).
- Set up a Bluetooth-Link to the *remote* BlueRS+C2 to be configured by using the command: ATD<*brad*><¬!>.
  - The called BlueRS+C2Configurator acknowledges by requesting the remote password. Please enter the correct password (default: no password, just return). Now you can work with the BlueRS+C2Configurator by using the BlueRS+C2Configurator commands (see page 24).
- Configure the parameter for the remote BlueRS+C2 from your terminal program and store them (if wanted). (see page 27).

Hint: The active set of parameters can be displayed on screen by the

BlueRS+C2Configurator with the command "show<¬>". If necessary the *remote* BlueRS+C2 can be reset using the command "reset<¬>".

- Hang up the Bluetooth connection by leaving the BlueRS+C2Configurator using the command quit.
- Leave your terminal program. After the next reset the changes will be active.
- Restore the server channel to the desired value, default to 1 (brsch=1).

Now the configured *remote* BlueRS+C2 with the new set of parameters can be used by running the needed PC program.

### 4.4 List of BlueRS+C2Configurator commands

The BlueRS+C2Configurator commands typed in must have the correct syntax and be complete, including all blanks. Capital/small letter use is not important. The entry is not case sensitive.

The bolded values are factory defaults. The usage is:

[?]<command>[=parameter]

Example to **set** the baudrate to 9600 baud:

br=4

Example to **show** the selected baudrate:

br

Example to **show all** selectable baudrates:

?bi

To get an overview about the commands of your BlueRS+C2 some major commands here as a preview:

show
 showall
 quit
 help
 defa 1
 show the usually used parameter
 show all changeable parameter
 leave BlueRS+C2Configurator
 show all available commands
 setup factory default parameter set

**save** store parameter non volatile

### at.sx

### AT command parameter set

AT command set only:

Handle AT specific settings.

Show and change AT S registers by entering the new value.

at.s0 show setting of S0-Register

at.s0=1 set Register S0 to 1

boad

Bluetooth Device Own Address

With this command you can read out the own Bluetooth device address. (read only)

Example:

boad

bpin

Bluetooth device Pin (Passkey)

4. BlueRS+C2 Configurator command set

Set the Pin for setting up a connection in restricted mode.

#### br

### baudrate asynchronous

Selection of the asynchronous baudrate for the DTE interface

- 1: 1200 bit/s
- 2: 2400 bit/s
- 3: 4800 bit/s
- 4: 9600 bit/s
- 5: 19200 bit/s
- 6: 38400 bit/s
- 7: 57600 bit/s
- 8: 115200 bit/s (default)
- 9: 230400 bit/s
- 20: 300 bit/s
- 21: 600 bit/s

### brad

### Bluetooth Device Remote Address

With this command you can setup the Bluetooth address of the other Bluetooth device, that should be connected using an automatic link setup.

### Example:

brad=0080371443AB

#### brestr

Set restricted mode

Enable and disable the restricted mode with exchanging the Pin (Passkey).

### cato

### call timeout to abort

Time to abort a call if not successful connected after n seconds.  $n = \{3..255\}$ , default: **15** seconds.

#### capa

### call pause

Automatic call: set a call pause for n seconds before next call attempt. n = 0: no call retry, default: **3** seconds.

### ccts

### CTS control

CTS control

- 0: CTS follows RTS
- 1 : CTS always ON (default)
- 2: CTS follows DTR
- 3: CTS follows remote CTS line status

#### cdcd

### DCD control

DCD control

- 0: DCD always ON
- 1 : DCD indicates a Bluetooth connection (default)
- 2: follows DTR
- 4: follows remote DCD

### cdsr

#### DSR control

### DSR control

- **0**: DSR always ON (default)
- 1 : DSR indicates a Bluetooth connection
- 2 : DSR follows DTR line status
- 3: DSR follows DCD line status
- 4 : DSR follows remote DSR line status

### cdtr

### DTR control

Usage of DTR to control a Bluetooth connection

0: No control:

Incoming calls will be accepted independent of DTR status;

DTR drop does not disconnect an active connection.

2: DTR off disconnects

Incoming calls will be accepted only when DTR is ON;

DTR drop disconnects an active connection.

4: DTR ignore and DTR drop disconnects (default)

Incoming calls will be accepted independent of DTR status;

DTR drop disconnects an active connection.

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# cmds command set (note 1)

Command set for connection control

- **0**: AT command set (default)
- 6: Automatic connection establishment when DTR is ON.
- 7: Automatic connection establishment when transmit data are available.
- 8: Automatic connection establishment independent of any status line.
- 12: No connection establishment initiated by this module.

Note: For details see the appropriate chapters.

### cpua, cpua2, cpl3 Output pin behavior (BlueRS+C2 module only)

(under development)

Definition of the behavior of the output pins UA UA2 and L3 of BlueRS+C2.

The behavior can be configured by using one of the following setting to the value of the list below.

The output level can be inverted by adding 128 to the desired value (defines the output pin to low active).

- 0: always OFF. Default UA, UA2, L3
- 1: always ON
- 29: Bluetooth link established, same as DCD on V.24.

### cri RI control

RI control

**0** : RI is set with an incoming Bluetooth link request (default)

1 : RI follows remote RI line status

# defa default settings

Sets up factory default parameter setting.

defa 0: setup all parameter concerning data port

defa 1: setup all parameter to factory defaults including Bluetooth

parameter.

### devmode device mode strapping

Shows the mode of operation of the BlueRS+C2: DTE or DCE mode.

When selecting DTE mode two additional inputs are evaluated and mapped to the behavior of DCD (Pin 18) and RI (Pin 11).

0: DTE mode 1: DCE mode

Note: If you are working in DCE mode using the plug-on module, please make sure, that PIN20 of connector P1 is connected to GND.

### dbits

### asynchronous databits

Number of data bits asynchronous chars (default: 8) 7,8

Note: To use other data formats than 10 bit (8N1, 7E1, 7O1) you have to set br to fixed speed.

#### flc

### flowcontrol

Flowcontrol to DTE

- 0 : No flowcontrol
- 3: Hardware flowcontrol RTS/CTS (default)
- 5 : Hardware flowcontrol RTS/CTS additionally in AT command phase

### flash

### load new firmware

This commands loads new firmware into the BlueRS+C2. The actual firmware will be overwritten.

The firmware will be stored into the used part of the flash memory. While uploading the following checks will be performed:

- File transfer protocol is XMODEM1K
- An overall firmware checksum is used.
- The firmware type written in the module header of the firmware must be compatible to the hardware- and allowed firmware type (stored inside the Bootloader).

This command is available only via the local serial port.

#### idle

#### Idle data timeout

Timer to disconnect the Bluetooth link after inactivity on the serial line (sec).

- 0: inactive (default)
- 1..n: delay time to disconnect in seconds (1..255).

#### load

### Load stored parameter setting

All parameters stored in non volatile ram will be loaded.

### opt

### option register for AT register

option register representing the setting of some AT commands:

bit 0: 1 = echo on, equals ATE1 bit 1: 1 = quiet, equals ATQ1

bit 2: 1 = numeric response, equals ATV0

### prty

### asynchronous parity

Parity of asynchronous character (default: no parity)

**0**: No parity; 1: Odd parity; 2: Even parity, 3: space parity, 4: mark parity

Note: To use other data formats than 10 bit (8N1, 7E1, 7O1) you have to set br to fixed speed.

### quit, exit, go

### activate parameter changes

Activates the actual parameter settings and leave the BlueRS+C2Configurator (without storing the parameter in non volatile memory ).

### reset

### reset BlueRS+C2

Resets the whole functionality of the BlueRS+C2 by a forced hardware reset (like Power off / on).

Refer also to parameter rsttim.

#### rsttim

### startup timer

Startup delay timer after reset. Within this period the configuration can be entered after reset.

1 .. 255 : reset phase in 100 milliseconds, default: **40** (4 seconds)

#### save

### store parameter changes

Stores the actual set of parameters in non volatile memory

#### sbits

### number of stopbits

Number of stopbits of asynchronous character

1 : One stopbit (default); 2 : two stopbit

Note: To use other data formats than 10 bit (8N1, 7E1, 7O1) you have to set br to fixed speed.

#### show

### show parameters

Displays the actual set of parameters

### showall

### show all parameters

Displays the all accessible parameters

#### trcnnn

#### commands for internal trace

The usage of the commands for internal trace are described in chapter 5.3.

### ver

### show version string

Displays detailed information about the software version and BlueRS+C2 type.

### verb

## show version string of Bootloader

Displays detailed information about the software version of the Bootloader.

#### <cmd>?

### more information for one command

Displays the allowed values for one selected command <cmd>

#### ??

## help

Displays help texts for all commands

Notes:

## 4.5 Software update

The BlueRS+C2 uses a Flash-EPROM for software updates to store the operational software. This software can be updated from a local connected PC via the COM port or via an remote configuration connection. Please fulfill the following steps to update the BlueRS+C2:

- Get a new software release for the BlueRS+C2 from your supplier or <a href="http://www.stollmann.de/">http://www.stollmann.de/</a> or <a href="ftp://ftp.stollmann.de/">ftp://ftp.stollmann.de/</a> and copy it to your PC.
- Start a terminal emulation on your PC with the capability to run an X-MODEM-1K file transfer (i.e. HyperTerminal).
- Local update: enter the BlueRS+C2Configurator.
- Enter the BlueRS+C2Configuration command "flash".
- Wait for end of erasing the Flash-EPROM and the prompt to start your X-MODEM transfer.
- Start the 1k-X-MODEM file transfer (send file or upload) by selecting the Transfer / Send File menu point in your terminal emulation and select the new software.
- After completion you will get the information whether the software update ended successfully or erroneous.
- The loaded new firmware will be activated automatically.
- Due to new functionality the last stored configuration setting may be lost, please check before using.

For more details refer to the description of the commands flash in the chapter "List of BlueRS+C2Configurator commands" on page 27.

### Note:

Due to an error it may be that no firmware is active within the BlueRS+C2. This will be indicated by continuous flashing of the LEDs L1, L2 (Bootloader active). To store a new firmware correctly you have to enter the command at\*\*flash and load a firmware using the XMODEM protocol as described above. This Bootloader supports only AT\*\*cmd with fixed baudrate of 115.200 Baud.

# 5 Diagnostic and error messages

For the diagnostic of erroneous situations the following functionality is supported. Please check first the behavior of LED displays, if an Bluetooth link can not be established. Refer to list of LED displays on page 42.

# 5.1 Error messages from AT command set

When the extended result messages are selected using the command ATW1 Bluetooth error codes are displayed in addition to the standard AT result messages. Bluetooth error codes are always coded as <xxxx>. The meaning can be taken from the following tables Bluetooth error codes (see page 36).

## 5.2 Bluetooth error codes

Note: error codes marked with (i) are internal errors.

| Error cause | Meaning   | Translation  |
|-------------|---|--------------|
| hexadecimal | ŭ   | to AT result |
|             |   | codes        |
| 0x0000      | no error, no explanation  | 3            |
| 0x0001      | driver and application version mismatch                           | 3            |
| 0x0002      | application id provided is not correct                            | 3            |
| 0x0003      | unknown message code in message                                   | 3            |
| 0x0004      | not enough resources to complete request (out of                  | 3            |
|             | descriptor etc)   |              |
| 0x0005      | at least one parameter of the message is wrong                    | 3            |
| 0x0006      | no adapter plugged in   | 3            |
| 0x0007      | too much outstanding messages in downstream                       | 6            |
|             | direction   |              |
| 0x0008      | driver is busy, repeat request later                              | 6            |
| 0x0009      | error in message transport system (driver not correct installed?) | 3            |
| 0x0101      | (i) HCI_ERR_UNKNOWN_COMMAND                                       | 3            |
| 0x0102      | (i) HCI_ERR_NOCONNECTION  | 3            |
| 0x0103      | bluetooth adapter crashed   | 3            |
| 0x0104/260  | remote bluetooth device not found (wrong address?,                | 8            |
|             | out of range?)  |              |
| 0x0105      | authentication error(wrong pin code supplied?)                    | 3            |
| 0x0106      | (i) HCI_ERR_KEY_MISSING   | 3            |
| 0x0107      | (i) HCI_ERR_MEMORY_FULL   | 3            |
| 0x0108/264  | lost connection to remote bluetooth device (out of                | 3            |

|        | range)   |   |
|--------|--|---|
| 0x0109 | max no of connections exceeded                     | 6 |
| 0x010a | max no of voice connections exceeded               | 6 |
| 0x010b | (i) HCI_ERR_ACL_CONN_ALREADY_EXISTS                | 3 |
| 0x010c | (i) HCI_ERR_COMMAND_DISALLOWED                     | 3 |
| 0x010d | connection attempt by remote side rejected         | 3 |
| 0x010e | connection attempt by remote side rejected         | 3 |
| 0x010f | connection attempt by remote side rejected         | 3 |
| 0x0110 | connection attempt by remote side timed out        | 8 |
| 0x0111 | (i) HCI_ERR_UNSUPPORTED_PARAM_VALUE                | 3 |
| 0x0112 | (i) HCI_ERR_INVALID_HCI_PARAMETER_VALUE            | 3 |
| 0x0113 | connection terminated by remote side               | 3 |
| 0x0114 | connection terminated by remote side               | 3 |
| 0x0115 | connection terminated by remote side               | 3 |
| 0x0116 | connection terminated by local side                | 3 |
| 0x0117 | (i) HCI_ERR_REPEATED_ATTEMPTS                      | 3 |
| 0x0118 | authentication rejected by remote side             | 3 |
| 0x0119 | incompatible remote bluetooth adapter              | 3 |
| 0x011a | unspecified error                                  | 3 |
| 0x011b | (i) HCI_ERR_UNSUPPORTED_LMP_PARAMETER_VAL          | 3 |
| 0x011c | master slave role switch not allowed               | 3 |
| 0x011d | connect lost to remote Bluetooth adapter (link     | 3 |
|        | manager)   |   |
| 0x011e | (i) (HCI_ERR_LMP_ERROR_TRANSACTION_COLLISION       | 3 |
| 0x011f | (i) HCI_ERR_LMP_PDU_NOT_ALLOWED                    | 3 |
| 0x0120 | attempt to enable encryption failed                | 3 |
| 0x0121 | information: unit key used                         | 3 |
| 0x0122 | (i) quality of service not supported.              | 3 |
| 0x0123 | (i) HCI_ERR_INSTANT_PASSED                         | 3 |
| 0x0124 | (i) unit key not supported                         | 3 |
| 0x0164 | (i) HCI_ERR_ILLEGAL_HANDLE                         | 3 |
| 0x0165 | initialization of adapter failed (timeout)         | 6 |
| 0x0166 | initialization of adapter failed (synchronization) | 6 |
| 0x0201 | (i) connection went to state pending               | 3 |
| 0x0202 | protocol not supported by remote side              | 3 |
| 0x0203 | connection refused due to security conditions      | 3 |
| 0x0204 | out of resources                                   | 3 |
| 0x02ee | remote side timed out                              | 3 |
| 0x0301 | version of remote SDP entity not compatible        | 3 |
| 0x0302 | invalid service record handle                      | 3 |
| 0x0303 | invalid request syntax                             | 3 |
| 0x0304 | invalid size of pdu                                | 3 |
| 0x0305 | continuation state is invalid                      | 3 |

| 0x0306 | not enough resources to complete operation          | 3 |
|--------|---|---|
| 0x0364 | client received unhandled SDP opcode                | 3 |
| 0x0365 | No answer from server(timeout)                      | 3 |
| 0x0366 | specified service not found                         | 3 |
| 0x0367 | Syntax Error in Response from server                | 3 |
| 0x0464 | Connection setup was rejected by remote side (DM),  | 3 |
|        | i.e. the Pin exchange has failed in restricted mode |   |
| 0x0465 | Connection timed out (no response)                  | 8 |
| 0x0466 | Non Supported Command received (incompatible        | 3 |
|        | remote side)  |   |
| 0x0467 | Illegal parameter                                   | 3 |

Note: error codes marked with (i) are internal errors.

# 5.3 Diagnostic using the internal Trace

For more sophisticated debugging an internal trace functionality is implemented. This logging mechanism allows to write activities of the Bluetooth interfaces and the serial interface into a wrap around buffer. The type of entries can be selected by a trace mask.

| trcmsk             | set ti   | race mask   |  |  |
|--------------------|--|---|--|--|
| trcmsk <i>par</i>  | buffer. Default: Blu DTE-Data ir The parame to be entere | the mask to select the type of data to be written into the trace r.  ult: Bluetooth HCl and Blueface messages, DTE interface lines, Data in connection-setup and clearing-phase.  parameter par has to be setup in the following way, all bytes have entered (default 00 00 00 00 00 00 00 04):  par := bl1 bl2 bl3 dl1 dl2 dl3 sl1 app bt1 |  |  |
|                    | bl1<br>bl2<br>bl3<br>dl1<br>dl2<br>dl3<br>sl1            | reserved (00) reserved (00) reserved (00) reserved (00) reserved (00) reserved (00) Serial line 1; i.e. first V.24 port; default: <b>00</b> bit0: control lines after change bit2: data bytes while connection control (call phase)   |  |  |
|                    | app<br>bt1   | reserved (00) Bluetooth; default: <b>04</b> bit0: hci interface, commands and events bit1: hci interface, acl data bit2: Blueface interface: signaling bit3: Blueface interface: traffic while DCD off bit4: Blueface interface: traffic  |  |  |
| examples:<br>trcms | sk 000000000   |   |  |  |
| trcon              | start  | trace write   |  |  |

trcon

set trace to active regarding to trace mask

| trcoff  | stop trace write   |
|---------|--|
| trcoff  | set trace to OFF independent of trace mask   |
| trcclr  | clear trace buffer   |
| trcclr  | clear actual trace buffer contents   |
| trcread | read trace buffer  |
| trcread | Output of the complete trace buffer in hexadecimal chars (ASCII, max. line length 72 chars). |

Every entry of the trace buffer is output using the following format: *Entry number – Timestamp – Type – Length – Databytes* 

Entry number Sequence number of entry

Timestamp in units of 10 ms
TypeAndSource Source of traceentry:

bit0-7: type from trace mask bit8-14: source of trace entry:

bit15: 0xxx: incoming event (from Bluetooth link)

8xxx: outgoing event (to Bluetooth link)

"FFFF": Reset for firmware

Length Length of following data bytes

Databytes Data bytes; continued lines are indicated by an ">".

Coding of trace data bytes dependent of *TypeAndSource*:

0901/8901: Serial line control line change:

bit0 : 1 = DSR is ON bit1 : 1 = DCD is ON bit2 : 1 = CTS is ON bit3 : 1 = RING is ON bit4 : 1 = RTS is ON bit5 : 1 = DTR is ON

# 6 Appendix

#### A1: Technical data BlueRS+C2

BlueRS+C2 desktop model serial interface:

functional: V.24 electrical: V.28

mechanical: 9 pin DSUB connector (female)

BlueRS+C2 module serial interface:

functional: V.24 electrical: TTL

mechanical: double pin rows P1

Transmission speeds:

DTE: 1200 – 230400 bit/s (asynchronous)

Character representation: 8Bit no Parity, 1 stop bit

7Bit even/odd Parity, 1 stop bit

Character synchronization: asynchronous

Operating mode: half duplex or full duplex Flowcontrol Hardware (RTS/CTS)

Bluetooth link: RF part: +4 dBm Radio,

20 m (Bluetooth Power Class 2) Bluetooth Spec: 1.0 B (1.12.1999)

Flowcontrol credit based

Class 1 module: RF part: +20 dBm Radio,

100 m (Bluetooth Power Class 1)

Bluetooth antenna: internal or external via coax SMC connector

Physical dimensions:

BlueRS+C2-Dx: desktop casing: 71 x 22 x 123 mm (WxHxD) BlueRS+C2-Mx: plug on module: 56 x 56 x 12s mm

(WxHxD)

Power supply:

BlueRS+C2-Dx: external power supply 5V DC.

idle: ca. 75 mA, active: ca. 115 mA.

BlueRS+C2-Mx5: 5V DC, +-5%, via double pin row P2

idle: ca. 30 mA. active: ca. 70 mA.

# A2: LED displays BlueRS+C2 desktop models

# Active states:

| L1        | L2                         | Status   |                                      |  |  |
|-----------|----------------------------|--|--------------------------------------|--|--|
| Θ         | $oldsymbol{\Theta}$ (2sec) | Power-On-Phase ; Bootloader, Init active, wait               |                                      |  |  |
| $\otimes$ | 0                          | Ready, idle ; Initializing ok, no Bluetooth link established |                                      |  |  |
| Ø         | 0                          | Ready, power down; Init ok, no Bluetooth link established    |                                      |  |  |
| $\otimes$ | Ø                          | Connecting   | ; Bluetooth link will be established |  |  |
| $\otimes$ | $\otimes$                  | Connected  | ; Bluetooth link established         |  |  |
|           |                            |  |                                      |  |  |

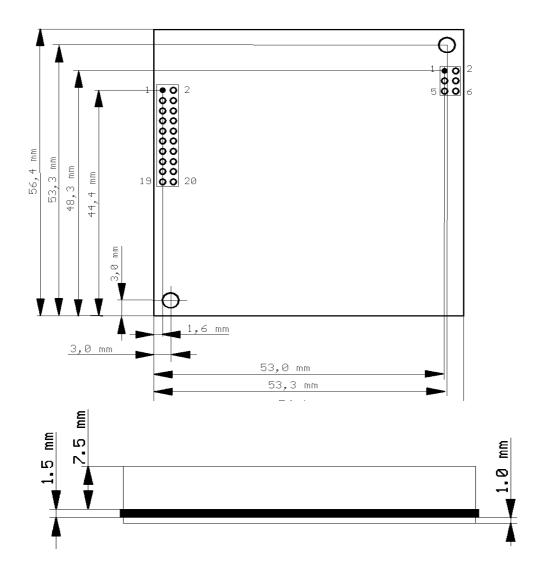
# Error states:

| Error state | <u> </u> |   |  |  |
|-------------|----------|---|--|--|
| L1          | L2       | Status  |  |  |
| Ο           | 0        | BlueRS+C2 not ok  | Hardware error, BlueRS+C2 repair necessary |  |
| 0           | Θ (nx1s) | BlueRS+C2 not ok  | Hardware error, BlueRS+C2 repair necessary |  |
| Θ           | Θ        | L1, L2 flashing: Bootloader active, no operational firmware programmed. Use command at**flash to download firmware with 115200 Bd ,N81 (see page 35). |  |  |

## LED Legend:

| $\otimes$           | On                       |                     |   |
|---------------------|--------------------------|---------------------|---|
| Ø                   | OCC                      | short on, long off  | Cycle 1 to 2 sec                        |
| $\oplus$            | fl                       | long on, short off  | Cycle 1 sec                             |
| $oldsymbol{\Theta}$ | ( <b>n</b> x <b>m</b> s) | continuous blinking | : <b>n</b> times every <b>m</b> seconds |
| 0                   | Off                      |                     |   |

## A3: Mechanical dimensions of the BlueRS+C2 module



## A4: BlueRS+C2 Serial Interface Connector P1

| P1-Pin | Signal    | Direction<br>from<br>BlueRS+C2 | BlueRS+C2 usage        | External interfacing |
|--------|-----------|--------------------------------|------------------------|----------------------|
| 1      | GND       | I                              | 0V-Power               | 0V Power supply      |
| 2      | VCC       | I                              | +5V-Power              | +5V Power supply     |
| 3      | GND       |                                | GND                    | GND                  |
| 4      | TXD~      | I                              |                        |                      |
| 5      | GND       |                                | GND                    | GND                  |
| 6      | RXD~      | 0                              |                        |                      |
| 7      | ID2       | 0                              | GND                    | NC or READ           |
| 8      | RTS~      |                                |                        |                      |
| 9      | ID1       | 0                              | GND                    | NC or READ           |
| 10     | CTS~      | 0                              |                        |                      |
| 11     | RESET     | I                              | RESET active low (OC)  | NC                   |
| 12     | DTR~      | I                              |                        |                      |
| 13     | L3~ (UA0) | 0                              | (internal 10k Pull up) | NC or status info    |
| 14     | DCD~      | 0                              |                        |                      |
| 15     | RI~       | 0                              |                        |                      |
| 16     | DSR~      | 0                              |                        |                      |
| 17     | UA~       | 0                              | User Output 1          | NC or status info    |
| 18     | UE~       | I                              | User Input 1           | 10k Pull up          |
| 19     | UA2       | 0                              | User Output 2          | NC or status info    |
| 20     | UE2       | I                              | User Input 2           | GND                  |

Outputs:

UA: default: similar to L1 of BlueRS+C2-Dx

L3: Bluetooth link established

UA2: reserved

Inputs:

UE: reserved

UE2: select DCE/DTE mode. GND=DCE mode.

Inputs and output lines with '~' are low active (i.e. ON has the TTL level 0VDC)

## A5: BlueRS+C2 Interface Connector P2

## If mounted:

| P2-Pin | Signal | Direction |
|--------|--------|-----------|
| 1      | NC     | -         |
| 2      | NC     | -         |
| 3      | NC     | -         |
| 4      | NC     | -         |
| 5      | NC     | -         |
| 6      | NC     | -         |

# A6: Pinout of the V.24/V.28 interface BlueRS+C2 desktop models (DSUB 9)

| Pin | V.24/V.28      |              |     | I/O | TEXT                |
|-----|----------------|--------------|-----|-----|---------------------|
|     | ITU            | DIN          | EIA |     |                     |
| 1   | 109            | M5           | DCD | 0   | Data carrier detect |
| 2   | 104            | D2           | R D | 0   | Receive data        |
| 3   | 103            | D1           | TD  | ı   | Transmit data       |
| 4   | 108/1<br>108/2 | S1.1<br>S1.2 | DTR | I   | Data terminal ready |
| 5   | 102            | E2           | GND |     | Signal ground       |
| 6   | 107            | M1           | DSR | 0   | Data set ready      |
| 7   | 105            | S2           | RTS | I   | Request to send     |
| 8   | 106            | M2           | CTS | 0   | Clear to send       |
| 9   | 125            | М3           | RI  | 0   | Ring indicator      |