

## Appendix 5. System Check

Prior to the assessment, the system was verified in the flat region of the phantom, 900 MHz and 1900 MHz dipoles were used. A forward power of 250 mW was applied to the 900 MHz and 1900 MHz dipoles and the system was verified to a tolerance of  $\pm 5\%$  for the 900 MHz and 1900 MHz dipoles.

The applicable verification normalised to 1 Watt.

### System Check 900 Body

Date: 03/01/2014

Validation Dipole and Serial Number: D900V2 SN: 185

Simulant	Frequency (MHz)	Room Temp	Liquid Temp	Parameters	Target Value	Measured Value	Deviation (%)	Limit (%)
Body	900	24.0 °C	22.4 °C	$\epsilon_r$	55.00	52.60	-4.36	5.00
				$\sigma$	1.05	1.05	-0.05	5.00
				1g SAR	10.70	10.60	-0.93	5.00
				10g SAR	6.95	6.96	0.14	5.00

### System Check 900 Body

Date: 06/01/2014

Validation Dipole and Serial Number: D900V2 SN: 185

Simulant	Frequency (MHz)	Room Temp	Liquid Temp	Parameters	Target Value	Measured Value	Deviation (%)	Limit (%)
Body	900	24.0 °C	22.3 °C	$\epsilon_r$	55.00	52.89	-3.84	5.00
				$\sigma$	1.05	1.03	-1.57	5.00
				1g SAR	10.70	10.80	0.93	5.00
				10g SAR	6.95	7.08	1.87	5.00

### System Check 900 Body

Date: 07/01/2014

Validation Dipole and Serial Number: D900V2 SN: 185

Simulant	Frequency (MHz)	Room Temp	Liquid Temp	Parameters	Target Value	Measured Value	Deviation (%)	Limit (%)
Body	900	24.0 °C	22.3 °C	$\epsilon_r$	55.00	52.89	-3.84	5.00
				$\sigma$	1.05	1.03	-1.57	5.00
				1g SAR	10.70	10.64	-0.56	5.00
				10g SAR	6.95	7.00	0.72	5.00

**System Check 1900 Body****Date: 07/01/2014****Validation Dipole and Serial Number: D1900V2: SN: 540**

Simulant	Frequency (MHz)	Room Temp	Liquid Temp	Parameters	Target Value	Measured Value	Deviation (%)	Limit (%)
Body	1900	24.0 °C	22.4 °C	$\epsilon_r$	53.30	53.93	1.18	5.00
				$\sigma$	1.52	1.53	0.69	5.00
				1g SAR	41.30	39.72	-3.83	5.00
				10g SAR	21.90	21.20	-3.20	5.00

**Date: 08/01/2014****Validation Dipole and Serial Number: D1900V2: SN: 540**

Simulant	Frequency (MHz)	Room Temp	Liquid Temp	Parameters	Target Value	Measured Value	Deviation (%)	Limit (%)
Body	1900	24.0 °C	23.0 °C	$\epsilon_r$	53.30	53.76	0.86	5.00
				$\sigma$	1.52	1.54	1.04	5.00
				1g SAR	41.30	39.52	-4.31	5.00
				10g SAR	21.90	21.16	-3.38	5.00

**Date: 09/01/2014****Validation Dipole and Serial Number: D1900V2: SN: 540**

Simulant	Frequency (MHz)	Room Temp	Liquid Temp	Parameters	Target Value	Measured Value	Deviation (%)	Limit (%)
Body	1900	24.0 °C	23.0 °C	$\epsilon_r$	53.30	53.76	0.86	5.00
				$\sigma$	1.52	1.54	1.04	5.00
				1g SAR	41.30	40.80	-1.21	5.00
				10g SAR	21.90	21.88	-0.09	5.00

## Appendix 6. Simulated Tissues

The body mixture consists of water, Polysorbate (Tween 20) and salt. Visual inspection is made to ensure air bubbles are not trapped during the mixing process. The mixture is calibrated to obtain proper dielectric constant (permittivity) and conductivity of the tissue.

Ingredient (% by weight)	Frequency 850/900 MHz
	Body
De-Ionized Water	71.30
Polysorbate 20	28.00
Salt	0.70

Ingredient (% by weight)	Frequency 1900 MHz
	Body
De-Ionized Water	71.50
Polysorbate 20	28.00
Salt	0.50

## Appendix 7. DASY4 System Details

### A.7.1. DASY4 SAR Measurement System

UL, SAR measurement facility utilises the Dosimetric Assessment System (DASY™) manufactured by Schmid & Partner Engineering AG (SPEAG™) of Zurich, Switzerland. The DASY4 system is comprised of the robot controller, computer, near-field probe, probe alignment sensor, and the SAM phantom containing brain or muscle equivalent material. The robot is a six-axis industrial robot performing precise movements to position the probe to the location (points) of maximum electromagnetic field (EMF). A cell controller system contains the power supply, robot controller; teach pendant (Joystick), and remote control. This is used to drive the robot motors. The Staubli robot is connected to the cell controller to allow software manipulation of the robot. The data acquisition electronics (DAE) performs signal amplification, signal multiplexing, AD-conversion, offset measurements, mechanical surface detection, collision detection etc. The DAE is connected to the Electro-optical coupler (EOC). The EOC performs the conversion from the optical into digital electric signal of the DAE and transfers data to the PC plug-in card. The DAE3 utilises a highly sensitive electrometer-grade preamplifier with auto-zeroing, a channel and gain-switching multiplexer, a fast 16-bit AD-converter and a command decoder and control logic unit. Transmission to the PC-card is accomplished through an optical downlink for data and status information and an optical uplink for commands and clock lines. The mechanical probe-mounting device includes two different sensor systems for frontal and sidewise probe contacts. They are also used for mechanical surface detection and probe collision detection. The robot uses its own controller with a built in VME-bus computer.

**A.7.2. DASY4 SAR System Specifications****Robot System**

<b>Positioner:</b>	Stäubli Unimation Corp. Robot Model: RX90L
<b>Repeatability:</b>	0.025 mm
<b>No. of Axis:</b>	6
<b>Serial Number:</b>	F01/5J86A1/A/01
<b>Reach:</b>	1185 mm
<b>Payload:</b>	3.5 kg
<b>Control Unit:</b>	CS7
<b>Programming Language:</b>	V+

**Data Acquisition Electronic (DAE) System**

<b>Serial Number:</b>	DAE3 SN:417
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**PC Controller**

<b>PC:</b>	Dell Precision 340
<b>Operating System:</b>	Windows 2000
<b>Data Card:</b>	DASY Measurement Server
<b>Serial Number:</b>	1080

**Data Converter**

<b>Features:</b>	Signal Amplifier, multiplexer, A/D converted and control logic.
<b>Software:</b>	DASY Software
<b>Connecting Lines:</b>	Optical downlink for data and status info. Optical uplink for commands and clock.

**PC Interface Card**

<b>Function:</b>	24 bit (64 MHz) DSP for real time processing Link to DAE3 16 bit A/D converter for surface detection system serial link to robot direct emergency stop output for robot.
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DASY4 SAR System Specifications (Continued)	
E-Field Probe	
Model:	ET3DV6
Serial No:	1586
Construction:	Triangular core
Frequency:	10 MHz to 2.55GHz
Linearity:	±0.2 dB (30 MHz to 2.55GHz)
Probe Length (mm):	337
Probe Diameter (mm):	10
Tip Length (mm):	10
Tip Diameter (mm):	6.8
Sensor X Offset (mm):	2.7
Sensor Y Offset (mm):	2.7
Sensor Z Offset (mm):	2.7
Phantom	
Phantom:	SAM Phantom
Shell Material:	Fibreglass
Thickness:	2.0 ±0.1 mm