



Author Data Daoud Attayi	Dates of Test February 12-13, 2003	Test Report No RIM-0024-0302-02
Approved	Rev	FCC ID : L6AR6230GE

SAR Compliance Test Report

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Statement of Compliance: Research In Motion Limited, declares under its sole responsibility that the product to which this declaration relates, is in conformity with the appropriate RF exposure standards, recommendations and guidelines. It also declares that the product was tested in accordance with the appropriate measurement standards, guidelines and recommended practices. Any deviations from these standards, guidelines and recommended practices are noted below:

(none)

Device Category: This wireless handheld is a portable device, designed to be used in direct contact with the user's head, hand and to be carried in an approved holster when carried on the user's body.

RF exposure environment: This wireless portable device has been shown to be in compliance for localized specific absorption rate (SAR) for uncontrolled environment/general population exposure limits specified in OET Bulletin 65 Supplement C (Edition 01-01), FCC 96-326 and IEEE Std. C95.1-1999 and had been tested in accordance with the measurement procedures specified in OET Bulletin 65 Supplement C (Edition 01-01) and ANSI/IEEE Std. C95.3-1991.

Approved by:

Paul G. Cardinal, Ph.D.
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Signatures

Date

07 March, 2003

Tested and documented by:

Daoud Attayi
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February 18, 2003

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1.0 OPERATING CONFIGURATIONS AND TEST CONDITIONS

1.1 Picture of Handheld



Figure 1. BlackBerry Wireless Handheld

1.2 Antenna description

Type	Internal fixed antenna
Location	Back top centre section
Configuration	Internal fixed antenna

Table 1. Antenna description

1.3 Handheld description

Handheld Model	R6230GE		
FCC ID	L6AR6230GE		
Serial Number	403TB-065B16		
Prototype or Production Unit	Pre-production		
Mode(s) of Operation	E-GSM 900	DCS 1800	PCS 1900
Maximum conducted RF Output Power	33.00 dBm	30.00 dBm	30.00 dBm
Tolerance in Power Setting	32.7 ± 0.3 dB	29.7 ± 0.3 dB	29.7 ± 0.3 dB
Duty Cycle	1:8	1:8	1:8
Transmitting Frequency Range (s)	880.20-914.80 MHz	1710.20-1784.80 MHz	1850.20-1909.80 MHz

Table 2. Test device description

Note: E-GSM 900 and DCS 1800 bands cannot be used in North America, therefore there is no SAR results presented in this report for FCC submission. A separate report is generated for the above two bands.

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1.4 Body worn accessories

Holster

The holster, with integral belt-clip, is designed to allow the BlackBerry handheld to slide in only one way, and that is with the keyboard side facing the user (facing the belt-clip) while in the holster. This positioning has the benefit of protecting the keypad and the large LCD from damage.

The middle portion of Figure 2 shows the holster with the handheld keyboard side facing the user and with the keyboard side facing away from user. Photo to the right shows that the device with keyboard away from the user does not fit into the holster.



Figure 2. Body-Worn Holster ASY-03998-001

The device-to-phantom spacing when the handheld is in holster is 15 mm as shown in the bottom portion of Figure 2.

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1.5 Headsets

The RIM Blackberry Wireless handheld was tested with and without headset model number HDW-03458-001. The SAR values are shown in Table 15 and 16.

1.6 Procedure used to establish the test signal

The Handheld was put into test mode for the SAR measurements by enabling a call via a Rohde & Schwartz CMU 200 Base Station Simulator test instrument. A SIM card was placed in the Handheld to enable the interaction between the BSS communications test instrument and the Handheld. The CMU 200 communications test instrument then sent out a command for the Handheld to transmit at full power at the specified frequency.

2.0 DESCRIPTION OF THE TEST EQUIPMENT

2.1 SAR measurement system

SAR measurements were performed using a Dosimetric Assessment System (DASY3), an automated SAR measurement system manufactured by Schmid & Partner Engineering AG (SPEAG), of Zurich, Switzerland.

The DASY3 system for performing compliance tests consists of the following items:

- A standard high precision 6-axis robot (Stäubli RX family) with controller and software.
- An arm extension for accommodating the data acquisition electronics (DAE).
- A dosimetric probe, i.e., an isotropic E-field probe optimized and calibrated for usage in tissue simulating liquid. The probe is equipped with an optical surface detector system.
- A DAE module which performs the signal amplification, signal multiplexing, AD-conversion, offset measurements, mechanical surface detection, collision detection, etc. The unit is battery powered with standard or rechargeable batteries. The signal is optically transmitted to the Electro-optical coupler (EOC).
- A unit to operate the optical surface detector which is connected to the EOC.
- The EOC performs the conversion from an optical signal into the digital electric signal of the DAE. The EOC is connected to the PC plug-in card.
- The functions of the PC plug-in card based on a DSP is to perform the time critical tasks such as signal filtering, surveillance of the robot operation fast movement interrupts.
- A computer operating Windows NT.
- DASY3 software version 3.1C.
- Remote control with teach pendant and additional circuitry for robot safety such as warning lamps, etc.
- The SAM Twin Phantom enabling testing left-hand and right-hand usage.
- The device holder for handheld mobile phones.
- Tissue simulating liquid mixed according to the given recipes (see Application Note).
- System validation dipoles allowing for the validation of proper functioning of the system.

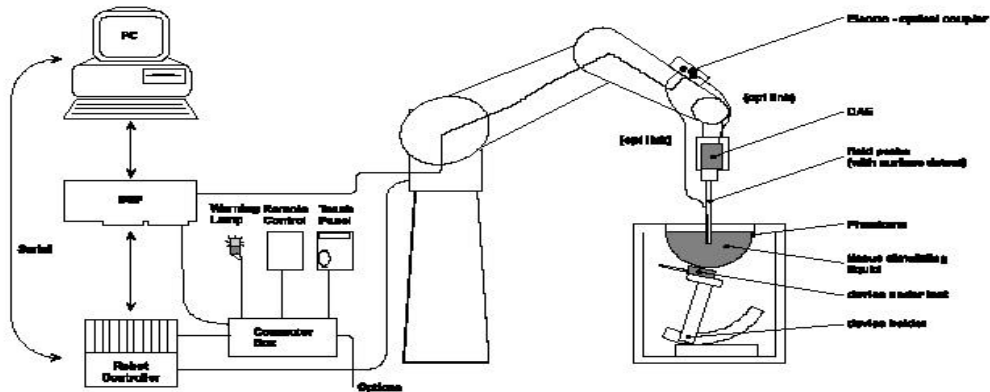


Figure 3: System Description

2.1.1 Equipment List

Manufacturer	Test Equipment	Model Number	Serial Number	Cal. Due Date
SCHMID & Partner Engineering AG	E-field probe	ET3DV6	1644	21/10/2003
SCHMID & Partner Engineering AG	Data Acquisition Electronics (DAE3)	DAE3 V1	473	23/10/2003
SCHMID & Partner Engineering AG	Dipole Validation Kit	D1900V2	545	12/11/2003
Agilent Technologies	Signal generator	HP 8648C	4037U03155	20/03/2003
Agilent Technologies	Power meter	E4419B	GB40202821	20/03/2003
Agilent Technologies	Power sensor	8482A	US37295126	21/03/2003
Amplifier Research	Amplifier	5S1G4M3	300986	CNR
Agilent Technologies	Network analyzer	8753ES	US39174857	21/03/2003
Rohde & Schwarz	Digital communication tester	CMU 200	100250	29/03/2003

Table 3. Equipment list

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2.2 Description of the test setup

Before a SAR test is conducted the Handheld and the DASY equipment are setup as follows:

2.2.1 Handheld and base station simulator setup

- Insert SIM card into the Handheld's SIM card slot and power it up.
- Turn on the CMU 200 test set and set the carrier frequency and power to the appropriate values.
- Connect an antenna to the RF IN/OUT of the communication test set and place it close to the Handheld.

2.2.2 DASY setup

- Turn the computer on and log on to Windows NT.
- Start DASY3 software by clicking on the icon located on the Windows desktop. Once the software loads, click on the Change to Robot toolbar button to open the State and Robot Monitoring Windows.
- Once the DASY State dialog opens you can ignore all errors and click OK to open the Robot Monitoring window.
- Mount the DAE unit and the probe. Turn on the DAE unit.
- Turn the Robot Controller on by turning the main power switch to the horizontal position
- Align the probe and click the align probe in the light beam button to correct the probe offset.
- Open a program and configure it to the proper parameters
- Establish a connection between the Handheld and the communications test instrument. Place the Handheld on the stand and adjust it under the phantom.
- Start SAR measurements.

3.0 ELECTRIC FIELD PROBE CALIBRATION

3.1 Probe Specification

SAR measurements were conducted using the dosimetric probe ET3DV6, designed by Schmid & Partner Engineering AG for the measurement of SAR. The probe is constructed using the thin film technique, with printed resistive lines on ceramic substrates. It has a symmetrical design with triangular core, built-in optical fiber for the surface detection system and built-in shielding against static discharge. The probe is sensitive to E-fields and thus incorporates three small dipoles arranged so that the overall response is close to isotropic. The table below summarizes the technical data for the probe.

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Property	Data
Frequency range	30 MHz – 3 GHz
Linearity	± 0.1 dB
Directivity (rotation around probe axis)	$= \pm 0.2$ dB
Directivity (rotation normal to probe axis)	± 0.4 dB
Dynamic Range	5 mW/kg – 100 W/kg
Probe positioning repeatability	± 0.2 mm
Spatial resolution	< 0.125 mm ³

Table 4. Probe specification

3.2 Probe calibration and measurement errors

The probe was calibrated on 21/10/2002 with an accuracy better than $\pm 10\%$. The sensitivity parameters (NormX, NormY, NormZ), the diode compression parameter (DCP) and the conversion factor (ConvF) of the probe were tested. The probe calibration parameters are shown on Appendix D.

4.0 SAR MEASUREMENT SYSTEM VERIFICATION

Prior to conducting SAR evaluation, the measurements were validated using the dipole validation kit and a flat phantom. A power level of 1.0 W was applied to the dipole antenna. The verification results are in the table below with a comparison to reference values. Printouts are shown in Appendix A. All the measured parameters are satisfactory.

4.1 System accuracy verification for Head Adjacent use

f (MHz)	Limits / Measured	SAR (W/kg) 1 g/ 10 g	Dielectric Parameters		Liquid Temp (°C)
			ϵ_r	σ [S/m]	
PCS 1900	Measured	44.7 / 22.2	39.1	1.42	23.4
	Recommended Limits	43.2 / 22.0	40.0	1.45	N/A

Table 5. System accuracy (Validation for Head Adjacent use)

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5.0 PHANTOM DESCRIPTION

The SAM Twin Phantom, manufactured by SPEAG, was used during the SAR measurements. The phantom is made of a fiberglass shell integrated with a wooden table.

The SAM Twin Phantom is a fiberglass shell phantom with 2 mm shell thickness. It has three measurement areas:

Left hand

Right hand

Flat phantom

The phantom table dimensions are: 100x50x85 cm (LxWxH). The table is intended for use with free standing robots.

The bottom shelf contains three pair of bolts for locking the device holder in place. The device holder positions are adjusted to the standard measurement positions in the three sections. Only one device holder is necessary if two phantoms are used (e.g., for different solutions).

A white cover is provided to top the phantom during off-periods to prevent water evaporation and changes in the liquid parameters. Free space scans of devices on the cover are possible; however the optical surface detector does not work properly at the cover surface. Place a sheet of white paper on the cover when using optical surface detection.



Figure 4
SAM Twin Phantom

6.0 TISSUE DIELECTRIC PROPERTY

6.1 Composition of tissue simulant

The composition of the brain and muscle simulating liquids for 800-900 MHz and 1800-1900 MHz are shown in the table below.

INGREDIENT	MIXTURE 800–900MHz		MIXTURE 1800–1900MHz	
	Brain %	Muscle %	Brain %	Muscle %
Water	51.07	65.45	54.88	69.91
Sugar	47.31	34.31	0	0
Salt	1.15	0.62	0.21	0.13
HEC	0.23	0	0	0
Bactericide	0.24	0.10	0	0
DGBE	0	0	44.91	29.96

Table 6. Tissue simulant recipe

6.1.1 Equipment

Manufacturer	Test Equipment	Model Number	Serial Number	Cal. Due Date
Pyrex, England	Graduated Cylinder	N/A	N/A	N/A
Pyrex, USA	Beaker	N/A	N/A	N/A
Acculab	Weight Scale	V1-1200	018WB2003	N/A
Hart Scientific	Digital Thermometer	61161-302	21352860	10/09/2003
IKA Works Inc.	Hot Plate	RC Basic	3.107433	N/A

Table 7. Tissue simulant preparation equipment

6.1.2 Preparation procedure

800-900 MHz liquids

- Fill the container with **water**. Begin heating and stirring.
- Add the **Cellulose**, the **preservative substance** and the **salt**. After several hours, the liquid will become more transparent again. The container must be covered to prevent evaporation.
- Add **Sugar**. Stir it well until the sugar is sufficiently dissolved.
- Keep the liquid hot but below the boiling point for at least an hour. The container must be covered to prevent evaporation.
- Remove the container from, and turn the hotplate off and allow the liquid to cool off to room temperature prior to performing dielectric measurements.

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1800-1900 MHz liquid

- Fill the container with **water**. Begin heating and stirring.
- Add the **salt** and **Glycol**. The container must be covered to prevent evaporation.
- Keep the liquid hot but below the boiling point for at least an hour. The container must be covered to prevent evaporation.
- Remove the container from, and turn the hotplate off and allow the liquid to cool off to room temperature prior to performing dielectric measurements.

6.2 Electrical parameters of the tissue simulating liquid

The tissue dielectric parameters shall be measured before a batch can be used for SAR measurements to ensure that the simulated tissue was properly made and will simulate the desired human characteristic. Limits and measured electrical parameters are show in the table below.

Recommended limits are adopted from IEEE Std 1528-200X, Draft 6.3 – April 8, 2001

“ Recommended Practice for Determining the Peak Spatial-Average Specific Absorption Rate (SAR) in the Human Body Due to Wireless Communications Devices: Environmental Techniques”

and from FCC Tissue Dielectric Properties web page at <http://www.fcc.gov/fcc-bin/dielec.sh>

f (MHz)	Tissue Type	Limits / Measured	Dielectric Parameters		Liquid Temp (°C)
			ϵ_r	σ [S/m]	
PCS 1900	Head	Measured	39.1	1.42	23.4
		Recommended Limits	40.0	1.45	N/A
	Muscle	Measured	51.6	1.42	23.4
		Recommended Limits	54.0	1.45	N/A

Table 8. Electrical parameters of tissue simulating liquid

6.2.1 Equipment

Manufacturer	Test Equipment	Model Number	Serial Number	Cal. Due Date
Agilent Technologies	Network Analyzer	8753ES	US39174857	21/03/2003
Agilent Technologies	Dielectric probe kit	HP 85070C	US9936135	CNR
Dell	PC using GPIB card	GX110	347	N/A
Hart Scientific	Digital Thermometer	61161-302	21352860	10/09/2003

Table 9. Equipment required for electrical parameter measurements

6.2.2 Test Configuration

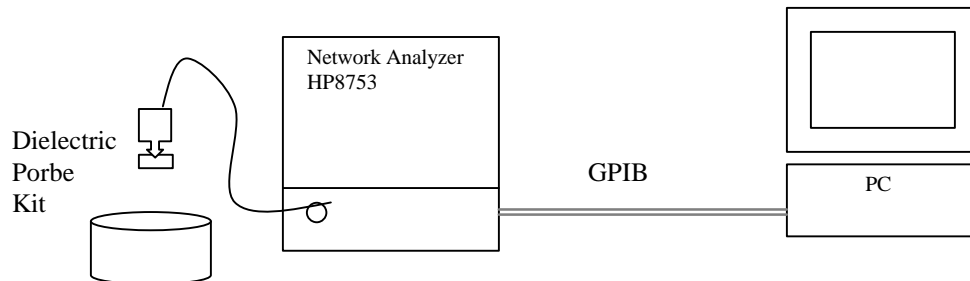


Figure 5: Test configuration

6.2.3 Procedure

1. Turn NWA on and allow at least 30 minutes for warm up.
2. Mount dielectric probe kit so that interconnecting cable to NWA will not be moved during measurements or calibration.
3. Pour de-ionized water and measure water temperature ($\pm 1^\circ$).
4. Set water temperature in HP-Software (Calibration Setup).
5. Perform calibration.
6. Validate calibration with dielectric material of known properties (e.g. polished ceramic slab with $>8\text{mm}$ thickness $\epsilon' = 10.0$, $\epsilon'' = 0.0$). If measured parameters do not fit within tolerance, repeat calibration (± 0.2 for ϵ' : ± 0.1 for ϵ'').
7. Relative permittivity $\epsilon_r = \epsilon'$ and conductivity can be calculated from ϵ''

$$\sigma = \omega \epsilon_0 \epsilon''$$
8. Measure liquid shortly after calibration.
9. Stir the liquid to be measured. Take a sample ($\sim 50\text{ml}$) with a syringe from the center of the liquid container.
10. Pour the liquid into a small glass flask. Hold the syringe at the bottom of the flask to avoid air bubbles.
11. Put the dielectric probe in the glass flask. Check that there are no air bubbles in front of the opening in the dielectric probe kit.
12. Perform measurements.
13. Adjust medium parameters in DASY3 for the frequencies necessary for the measurements ('Setup Config', select medium (e.g. Brain 900 MHz) and press 'Option'-button.
14. Select the current medium for the frequency of the validation (e.g. Setup Medium Brain 900 MHz).

Sample calculation for 1900 MHz head tissue dielectric parameters using data from Table 10.

Relative permittivity $\epsilon_r = \epsilon' = 39.0920$

Conductivity $\sigma = \omega \epsilon_0 \epsilon'' = 2 \times 3.1416 \times 1900 \times 10^6 \times 8.854 \times 10^{-12} \times 13.4647 = 1.4232 \text{ S/m}$

Title

SubTitle

February 12, 2003 09:53 AM

Title

SubTitle

February 13, 2003 09:23 AM

Frequency	e'	e''	Frequency	e'	e''
1.700000000 GHz	39.8623	12.9978	1.700000000 GHz	52.2716	12.8157
1.710000000 GHz	39.8093	13.0264	1.710000000 GHz	52.2266	12.8313
1.720000000 GHz	39.7695	13.0536	1.720000000 GHz	52.1922	12.8887
1.730000000 GHz	39.7504	13.0719	1.730000000 GHz	52.1734	12.9227
1.740000000 GHz	39.7211	13.1022	1.740000000 GHz	52.1486	12.9687
1.750000000 GHz	39.6673	13.1253	1.750000000 GHz	52.1281	12.9826
1.760000000 GHz	39.6489	13.1644	1.760000000 GHz	52.1058	13.0265
1.770000000 GHz	39.6021	13.1896	1.770000000 GHz	52.0693	13.0465
1.780000000 GHz	39.5797	13.2125	1.780000000 GHz	52.0449	13.0957
1.790000000 GHz	39.5349	13.2519	1.790000000 GHz	52.0046	13.1192
1.800000000 GHz	39.4925	13.2626	1.800000000 GHz	51.9713	13.1655
1.810000000 GHz	39.4328	13.2929	1.810000000 GHz	51.9117	13.1951
1.820000000 GHz	39.3835	13.3081	1.820000000 GHz	51.8594	13.2225
1.830000000 GHz	39.3167	13.3222	1.830000000 GHz	51.7911	13.2783
1.840000000 GHz	39.2888	13.3488	1.840000000 GHz	51.7736	13.3331
1.850000000 GHz	39.2391	13.3769	1.850000000 GHz	51.7113	13.3420
1.860000000 GHz	39.1968	13.4005	1.860000000 GHz	51.6800	13.3844
1.870000000 GHz	39.1772	13.4250	1.870000000 GHz	51.6510	13.4109
1.880000000 GHz	39.1638	13.4338	1.880000000 GHz	51.6312	13.4258
1.890000000 GHz	39.1108	13.4347	1.890000000 GHz	51.5974	13.4429
1.900000000 GHz	39.0920	13.4647	1.900000000 GHz	51.5711	13.4781
1.910000000 GHz	39.0614	13.4696	1.910000000 GHz	51.5256	13.5096

Table 10. 1900 MHz head and muscle tissue dielectric parameters

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7.0 SAR SAFETY LIMITS

Standards/Guideline	Localized SAR Limit (W/kg) General public (uncontrolled)	Localized SAR Limits (W/kg) Workers (controlled)
ICNIRP (1998) Standard	2.0 (10g)	10.0 (10g)
IEEE C95.1 (1999) Standard	1.6 (1g)	8.0 (1g)

Table 11. SAR safety limits for Controlled / Uncontrolled environment

Human Exposure	Localized SAR Limits (W/kg) 10g, ICNIRP (1998) Standard	Localized SAR Limits (W/kg) 1g, IEEE C95.1 (1999) Standard
Spatial Average (averaged over the whole body)	0.08	0.08
Spatial Peak (averaged over any X g of tissue)	2.00	1.60
Spatial Peak (hands/wrists/feet/ankles averaged over 10 g)	4.00	4.00 (10g)

Table 12. SAR safety limits

Uncontrolled Environments are defined as locations where there is exposure of individuals who have no knowledge or control of their exposure.

Controlled Environments are defined as locations where there is exposure that may be incurred by persons who are aware of the potential for exposure, (i.e. as a result of employment or occupation).

8.0 DEVICE POSITIONING

8.1 Device holder for SAM Twin Phantom

The Handheld was positioned for all test configurations using the DASY3 holder. The device holder facilitates the rotation of the mounted transmitter in spherical coordinates whereby the rotation point is the ear opening. The devices can be easily, accurately and with repeatability positioned according to FCC and CENELEC specifications. The device holder can be locked at different phantom locations (left head, right head, flat phantom).

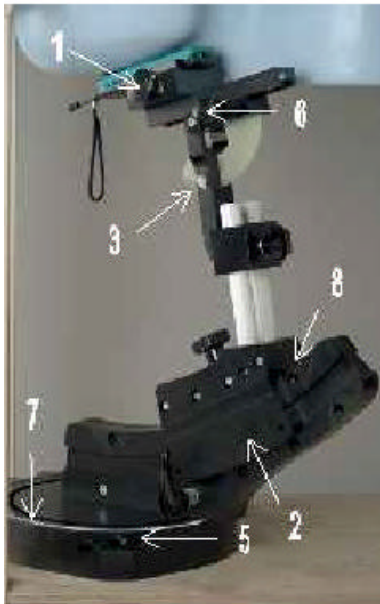


Figure 6
Device Holder

1. Put the phone in the clamp mechanism (1) and hold it straight while tightening. (Curved phones or phones with asymmetrical ear pieces should be positioned so that the ear piece is in the symmetry plane of the clamp).

2. Adjust the sliding carriage (2) to 90°. Then adjust the phone holder angle (3) until the reference line of the phone is horizontal (parallel to the flat phantom bottom). The phone reference line is defined as the front tangential line between the ear piece and the center of the device bottom (or the center of the flip hinge). For devices with parallel front and back sides, the phone holder angle (3) is 0°.

3. Place the device holder at the desired phantom section and move it securely against the positioning pins (4). The screw in front of the turning plate can be applied for correct positioning (5). (Do not tighten it too strongly).

4. Shift the phone clamp (6) so that the ear piece is exactly below the ear marking of the phantom. The phone is now correctly positioned in the holder for all standard phantom measurements, even after changing the phantom or phantom section.

5. Adjust the device position angles to the desired measurement position.
6. After fixing the device angles, move the phone fixture up until the phone touches the ear marking.
(The point of contact depends on the design of the device and the positioning angle).

8.2 Description of the test positioning

8.2.1 Test Positions of Device Relative to Head

The handset was tested in two test positions against the head phantom, the “cheek” position and the “tilted” position, on both left and right sides of the phantom.

The handset was tested in the above positions according to IEEE 1528-Draft 6.1 “Recommended Practice for Determining the Spatial-Peak Specific Absorption Rate (SAR) in the Human Body Due to Wireless Communications Devices: Experimental Techniques”.

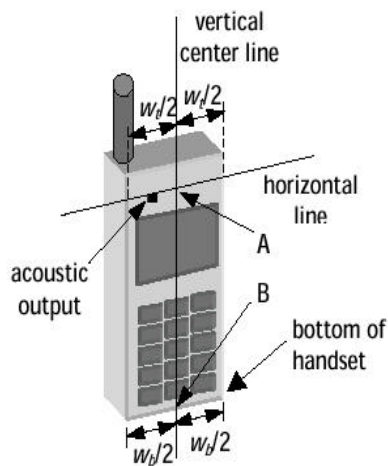


Figure 7a – Handset vertical and horizontal reference lines – fixed case

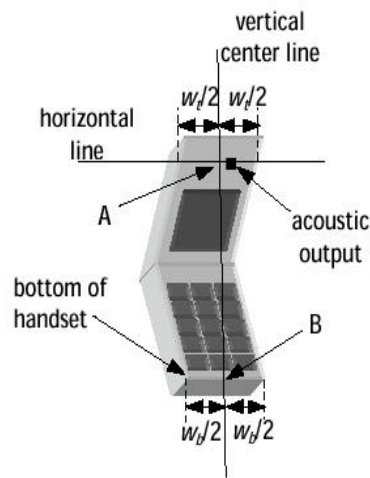


Figure 7b – Handset vertical and horizontal reference lines – “clam-shell”

8.2.1.1 Definition of the “cheek” position

- 1) Ready the handset for talk operation, if necessary. For example, for handsets with a cover piece, open the cover.
- 2) Define two imaginary lines on the handset: the vertical centerline and the horizontal line. The vertical centerline passes through two points on the front side of the handset: the midpoint of the width w_t of the handset at the level of the acoustic output (point A on Figures 7a and 7b), and the midpoint of the width w_b of the bottom of the handset (point B). The horizontal line is perpendicular to the vertical centerline and passes through the center of the acoustic output (see Figure 7a). The two lines intersect at point A. Note that for many handsets, point A coincides with the center of the acoustic output. However, the acoustic output may be located elsewhere on the horizontal line. Also note that the vertical centerline is not necessarily parallel to the front face of the handset (see Figure 7b), especially for clamshell handsets, handsets with flip pieces, and other irregularly shaped handsets.
- 3) Position the handset close to the surface of the phantom such that point A is on the (virtual) extension of the line passing through points RE and LE on the phantom (see Figure 7), such that the plane defined by the vertical center line and the horizontal center line is in a plane approximately parallel to the sagittal plane of the phantom.
- 4) Translate the handset towards the phantom along the line passing through RE and LE until the handset touches the ear.
- 5) While maintaining the handset in this plane, rotate it around the LE-RE line until the vertical centerline is the plane normal to MB (“mouth-back”) - NF (“neck-front”) including the line MB (reference plane).
- 6) Rotate the phone around the vertical centerline until the phone (horizontal line) is symmetrical with respect to the line NF.
- 7) While maintaining the vertical centerline in the reference plane, keeping point A on the line passing through RE and LE, and maintaining the phone contact with the ear, rotate the handset about the line NF until any point on the handset is in contact with a phantom point below the ear (cheek).

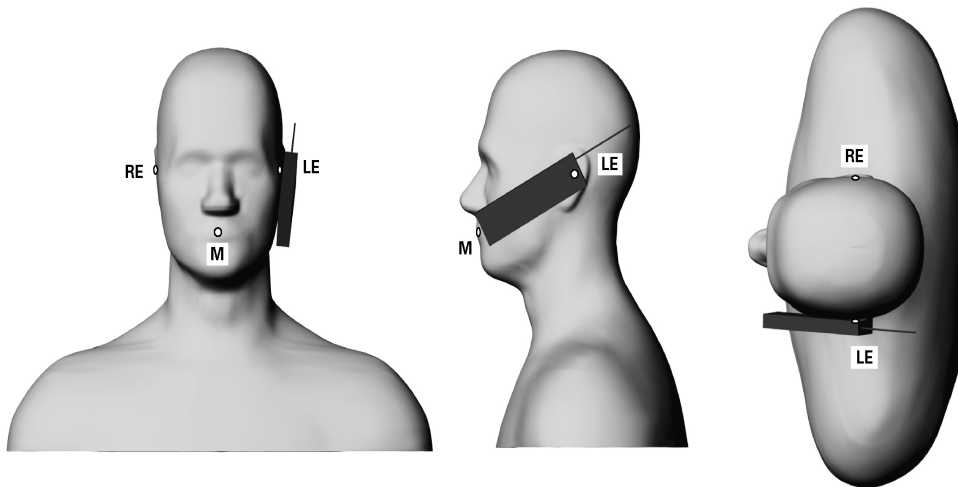


Figure 8 – Phone position 1, “cheek” or “touch” position. The reference points for the right ear (RE), left ear (LE) and mouth (M), which define the reference plane for phone positioning, are indicated. The shoulders are shown for illustration purposes only.

8.2.1.2 Definition of the “Tilted” Position

- 1) Repeat steps 1 to 7 of 5.4.1 (in this report 8.2.1.1) to replace the device in the “cheek position.”
- 2) While maintaining the device in the reference plane (described above) and pivoting against the ear, move the device outward away from the mouth by an angle of 15 degrees, or until the antenna touches the phantom.

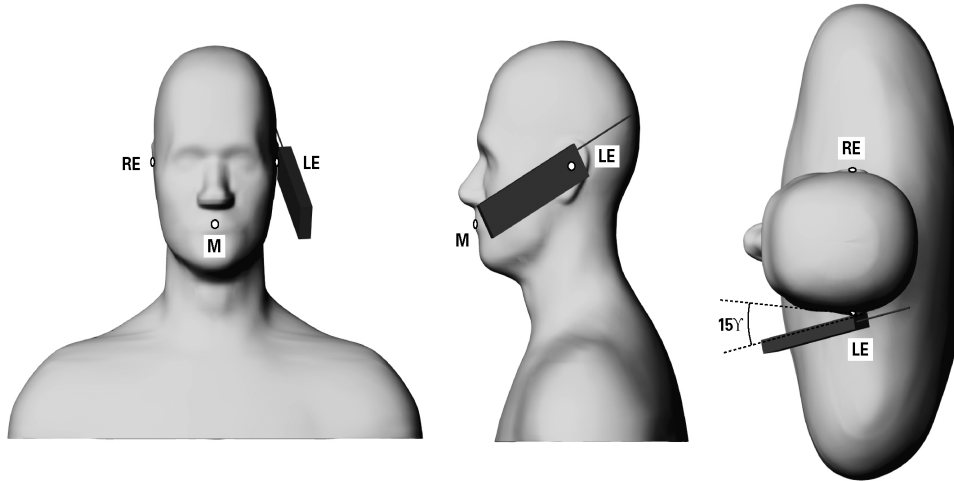


Figure 9 – Phone position 2, “tilted position.” The reference points for the right ear (RE), left ear (LE) and mouth (M), which define the reference plane for phone positioning, are indicated. The shoulders are shown for illustration purposes only.

8.2.2 Body Holster Configuration

A body worn holster, as shown on Figure 2, was tested with the Wireless Handheld for FCC RF exposure compliance. The EUT was positioned in the holster case and the belt clip was placed against the flat section of the phantom. A headset was then connected to the handheld to simulate hands-free operation in a body worn holster configuration.

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9.0 High Level Evaluation

9.1 Maximum search

The maximum search is automatically performed after each coarse scan measurement. It is based on splines in two or three dimensions. The procedure can find the maximum for most SAR distributions even with relatively large grid spacing. After the coarse scan measurement, the probe is automatically moved to a position at the interpolated maximum. The following scan can directly use this position for reference, e.g., for a finer resolution grid or the cube evaluations.

9.2 Extrapolation

The extrapolation can be used in z-axis scans with automatic surface detection. The SAR values can be extrapolated to the inner phantom surface. The extrapolation distance is the sum of the probe sensor offset, the surface detection distance and the grid offset. The extrapolation is based on fourth order polynomial functions. The extrapolation is only available for SAR values.

9.3 Boundary correction

The correction of the probe boundary effect in the vicinity of the phantom surface is done in the standard (worst case) evaluation; the boundary effect is reduced by different weights for the lowest measured points in the extrapolation routine. The result is a slight overestimation of the extrapolated SAR values (2% to 8%) depending on the SAR distribution and gradient. The advanced evaluation makes a full compensation of the boundary effect before doing the extrapolation. This is only possible for probes with specifications on the boundary effect.

9.4 Peak search for 1g and 10g cube averaged SAR

The 1g and 10g peak evaluations are only available for the predefined cube 5x5x7 scan. The routines are verified and optimized for the grid dimensions used in these cube measurements.

The measure volume of 32x32x35mm mm contains about 35g of tissue. The first procedure is an extrapolation (incl. Boundary correction) to get the points between the lowest measured plane and the surface. The next step uses 3D interpolation to get all points within the measured volume in a 1mm grid (35000 points). In the last step, a 1g cube is placed numerically into the volume and its averaged SAR is calculated. This cube is then moved around until the highest averaged SAR is found. This last procedure is repeated for a 10 g cube. If the highest SAR is found at the edge of the measured volume, the system will issue a warning: higher SAR values might be found outside of the measured volume. In that case the cube measurement can be repeated, using the new interpolated maximum as the center.

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10.0 MEASUREMENT UNCERTAINTIES

Uncertainty Component	Tolerance (\pm %)	Probability Distribution	Sensitivity coefficient (1-g)	Sensitivity coefficient (10-g)	1-g Standard Uncertainty (\pm %)	10-g Standard Uncertainty (\pm %)
Measurement System						
Probe Calibration ($k=1$)	3.3	Normal	1	1	3.3	3.3
Axial Isotropy	4.7	Rectangle	0.7	0.7	1.9	1.9
Hemispherical Isotropy	9.6	Rectangle	0.7	0.7	3.9	3.9
Boundary Effect	11.0	Rectangle	1	1	6.4	6.4
Linearity	4.7	Rectangle	1	1	2.7	2.7
System Detection Limits	1.0	Rectangle	1	1	0.6	0.6
Readout Electronics	1.0	Normal	1	1	1.0	1.0
Response Time	0.8	Rectangle	1	1	0.5	0.5
Integration Time	1.8	Rectangle	1	1	1.1	1.1
RF Ambient Conditions	3.0	Rectangle	1	1	1.7	1.7
Probe Positioner Mechanical Tolerance	0.4	Rectangle	1	1	0.2	0.2
Probe Positioning with respect to Phantom Shell	2.9	Rectangle	1	1	1.7	1.7
Extrapolation, interpolation and Integration Algorithms for Max. SAR Evaluation	3.9	Rectangle	1	1	2.3	2.3
Test sample Related						
Test Sample Positioning		Normal	1	1	6.7	6.7
Device Holder Uncertainty		Normal	1	1	5.9	5.9
Output Power Variation - SAR drift measurement	5	Rectangle	1	1	2.9	2.9
Phantom and Tissue Parameters						
Phantom Uncertainty (shape and thickness tolerances)	4.0	Rectangle	1	1	2.3	2.3
Liquid Conductivity - deviation from target values	5.0	Rectangle	0.7	0.5	2.0	1.4
Liquid Conductivity - measurement uncertainty	10.0	Rectangle	0.7	0.5	4.0	2.9
Liquid Permittivity - deviation from target values	5.0	Rectangle	0.6	0.5	1.7	1.4
Liquid Permittivity - measurement uncertainty	5.0	Rectangle	0.6	0.5	1.7	1.4
Combined Standard Uncertainty		RSS			14.5	14.1
Expanded Uncertainty (95% CONFIDENCE LEVEL)					29.0	28.2

Table 13. Measurement uncertainty

11.0 TEST RESULTS

11.1 SAR Measurement results at highest power measured against the head

Mode	f (MHz)	Conducted Output Power (dBm)	SAR, averaged over 1 g (W/Kg)			SAR, averaged over 1 g (W/Kg)		
			Left-hand			Right-hand		
			Liquid Temp (°C)	Cheek	Tilted	Liquid Temp (°C)	Cheek	Tilted
PCS 1900	1850.20	29.80	22.8	0.15	0.19	23.0	0.20	0.21
	1880.00	29.90	22.7	0.12	0.20	22.8	0.16	0.19
	1908.80	29.80	22.6	0.16	0.26	22.7	0.15	0.21

Table 14. SAR results for head configuration

11.2 SAR Measurement results at highest power measured against the body using Holster

Mode	f (MHz)	Conducted Output Power (dBm)	Liquid Temp (°C)	SAR, averaged over 1 g (W/kg)	SAR, averaged over 1 g with headset (W/kg)
PCS 1900	1850.20	29.80	23.2	0.06	-
	1880.00	29.90	23.0	0.05	-
	1908.80	29.80	22.8	0.07	0.07

Table 15. SAR results with holster for body configuration

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11.3 SAR Measurement results at highest power measured for the hand

Mode	Device Configuration touching flat phantom	f (MHz)	Conducted Output Power (dBm)	Liquid Temp (°C)	SAR, averaged over 10 g (W/kg)	SAR, averaged over 10 g with headset (W/kg)
PCS 1900	back	1850.20	29.90	22.7	2.66	2.80
	back	1880.00	29.90	22.5	2.61	-
	back	1908.80	29.80	22.4	1.99	-

Table 16. SAR results for hand configuration

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