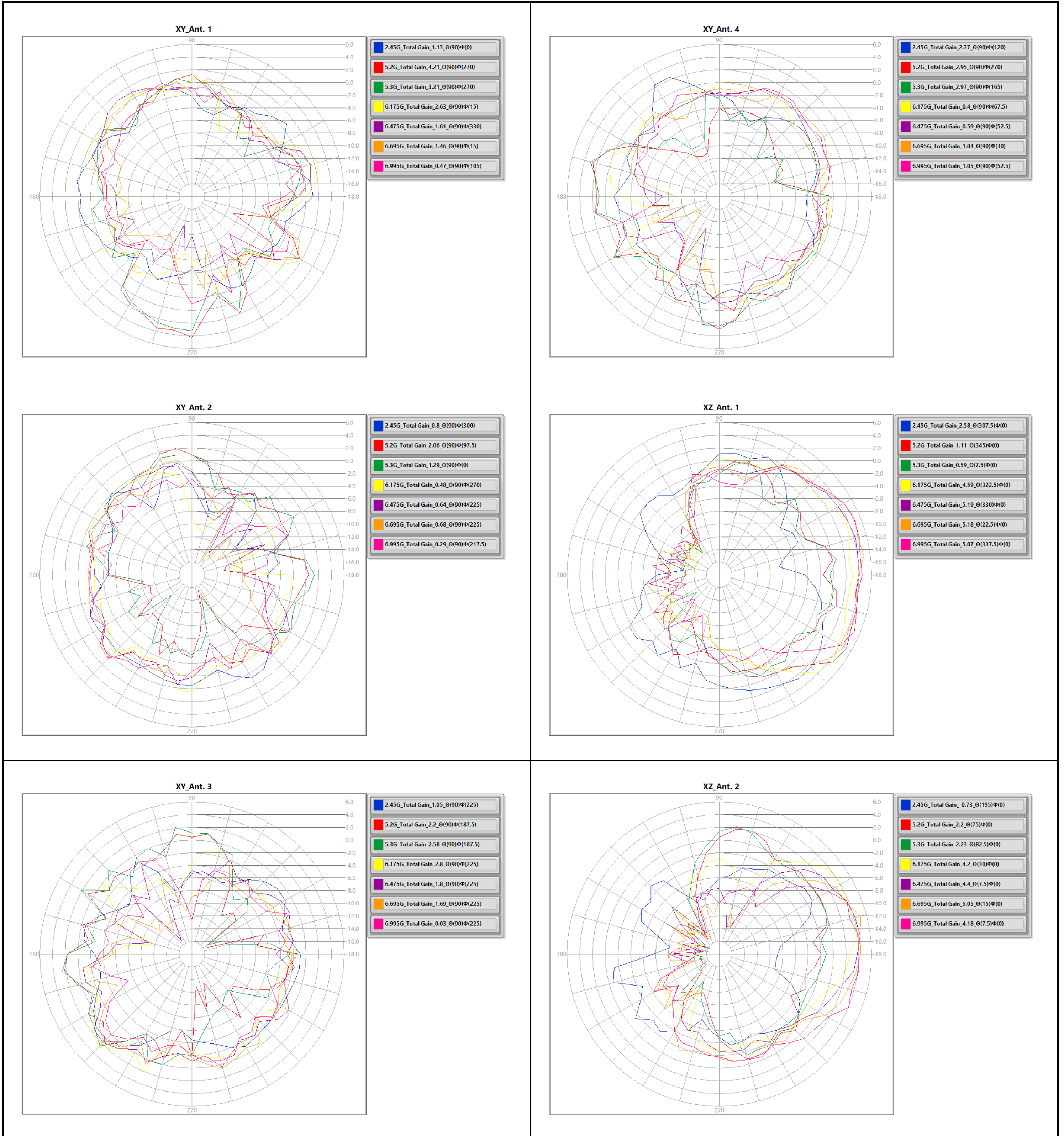
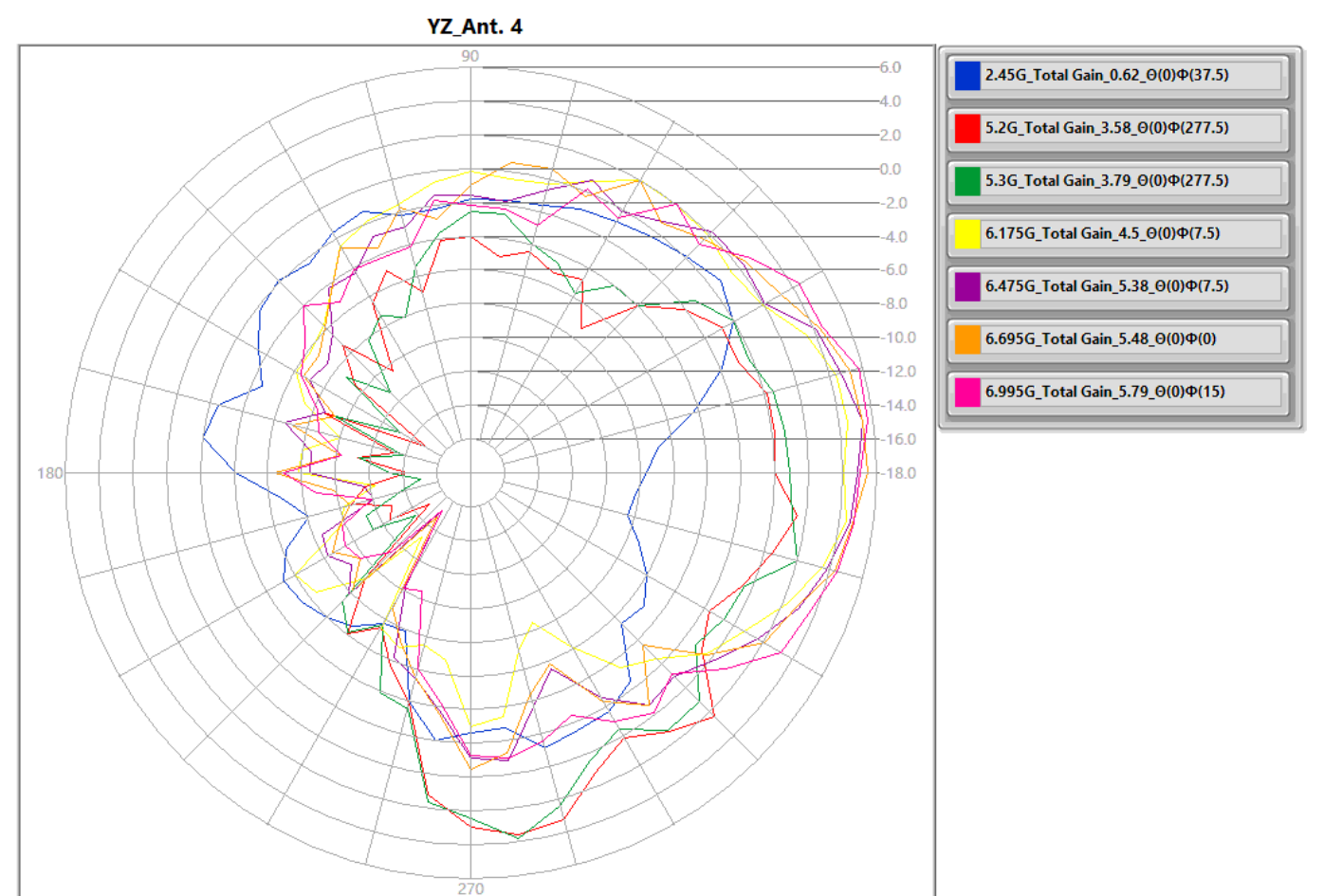
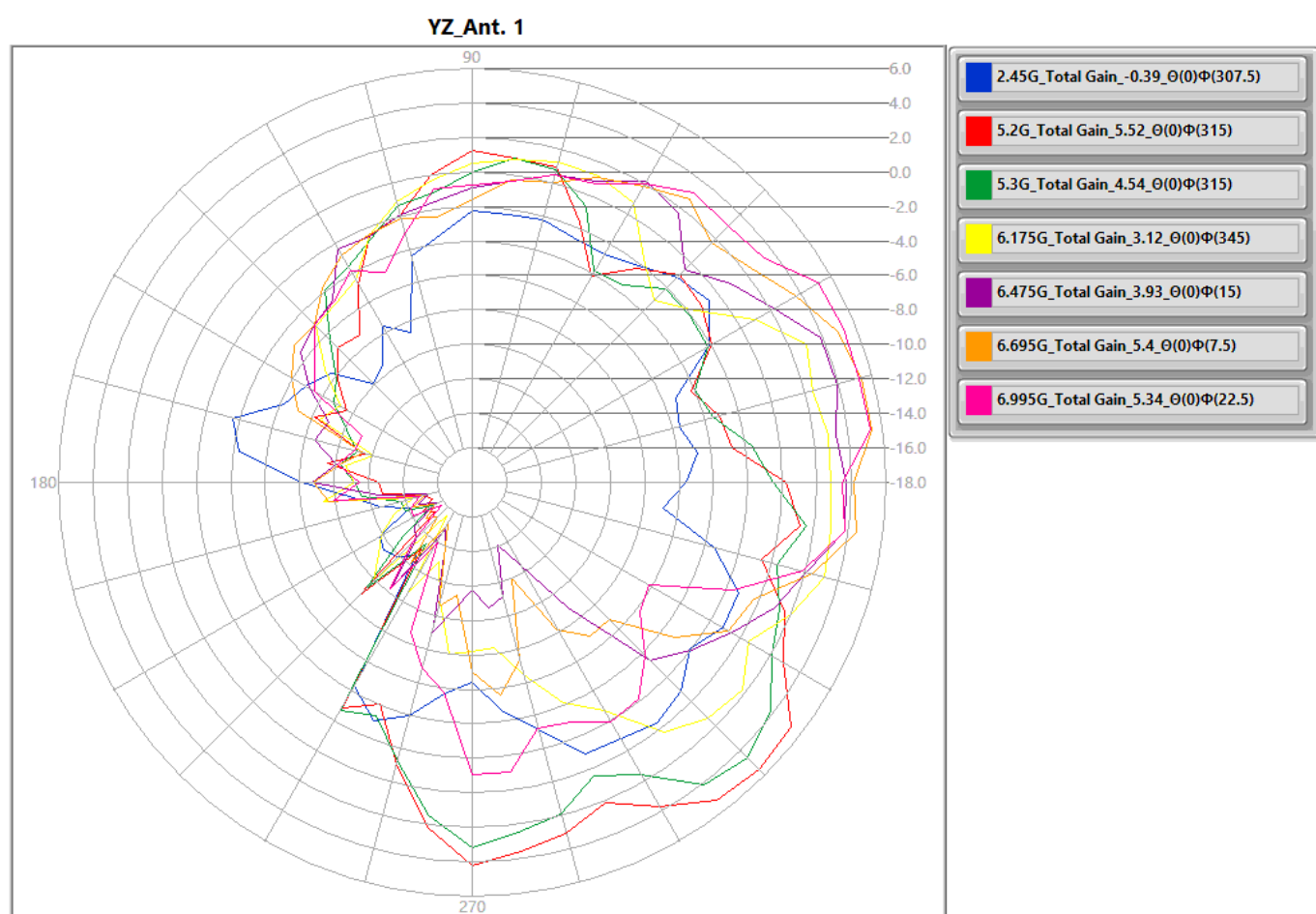
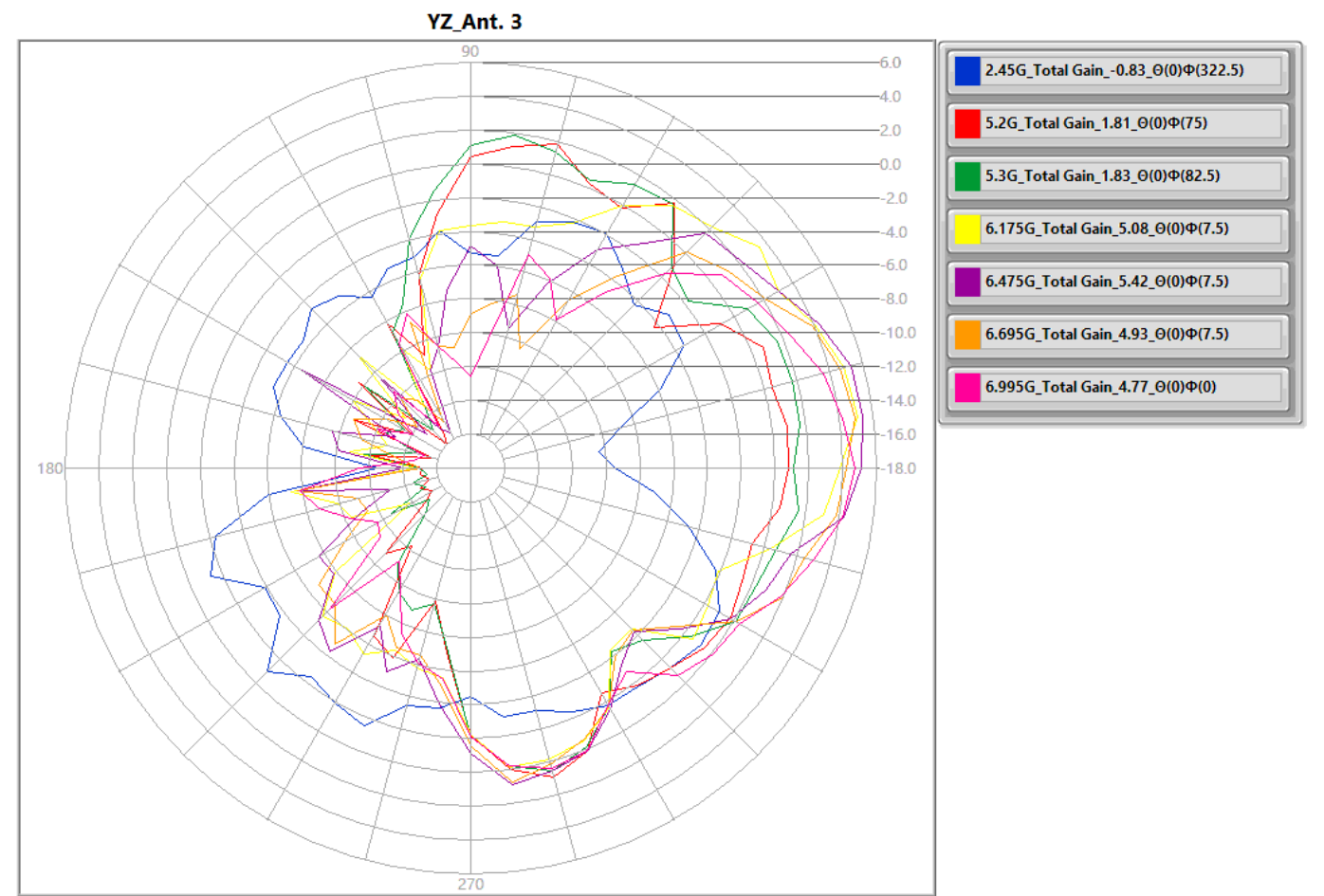
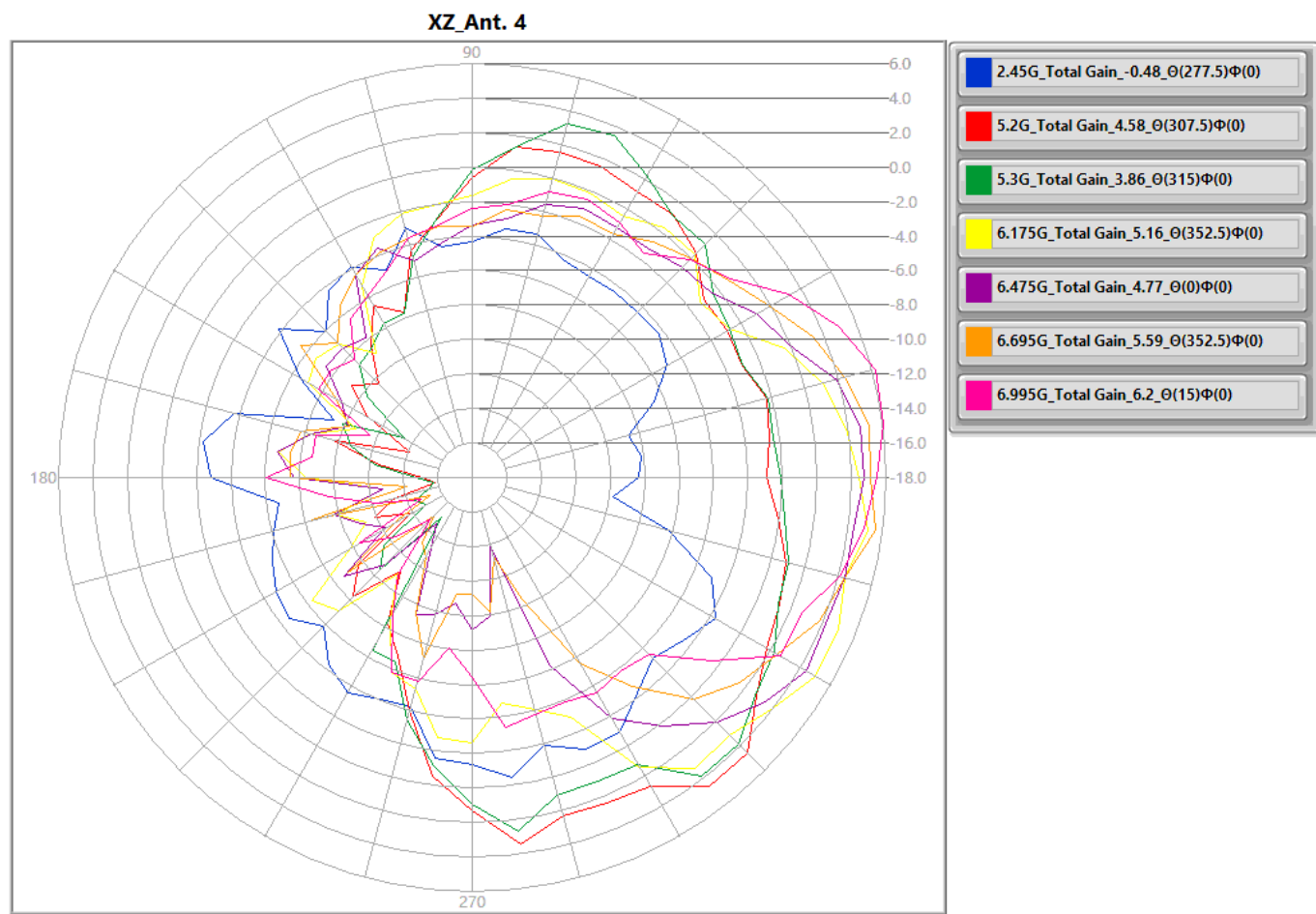
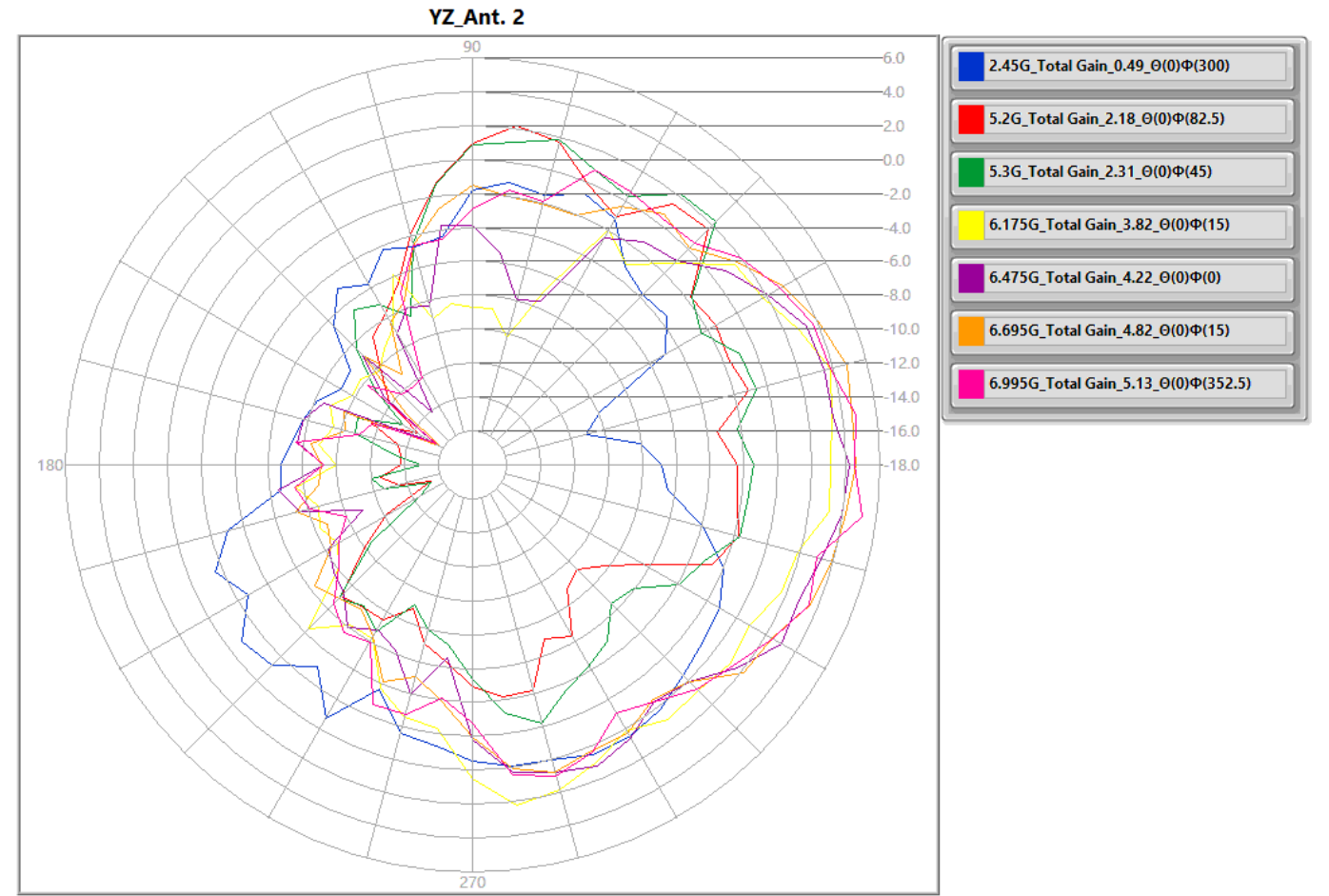
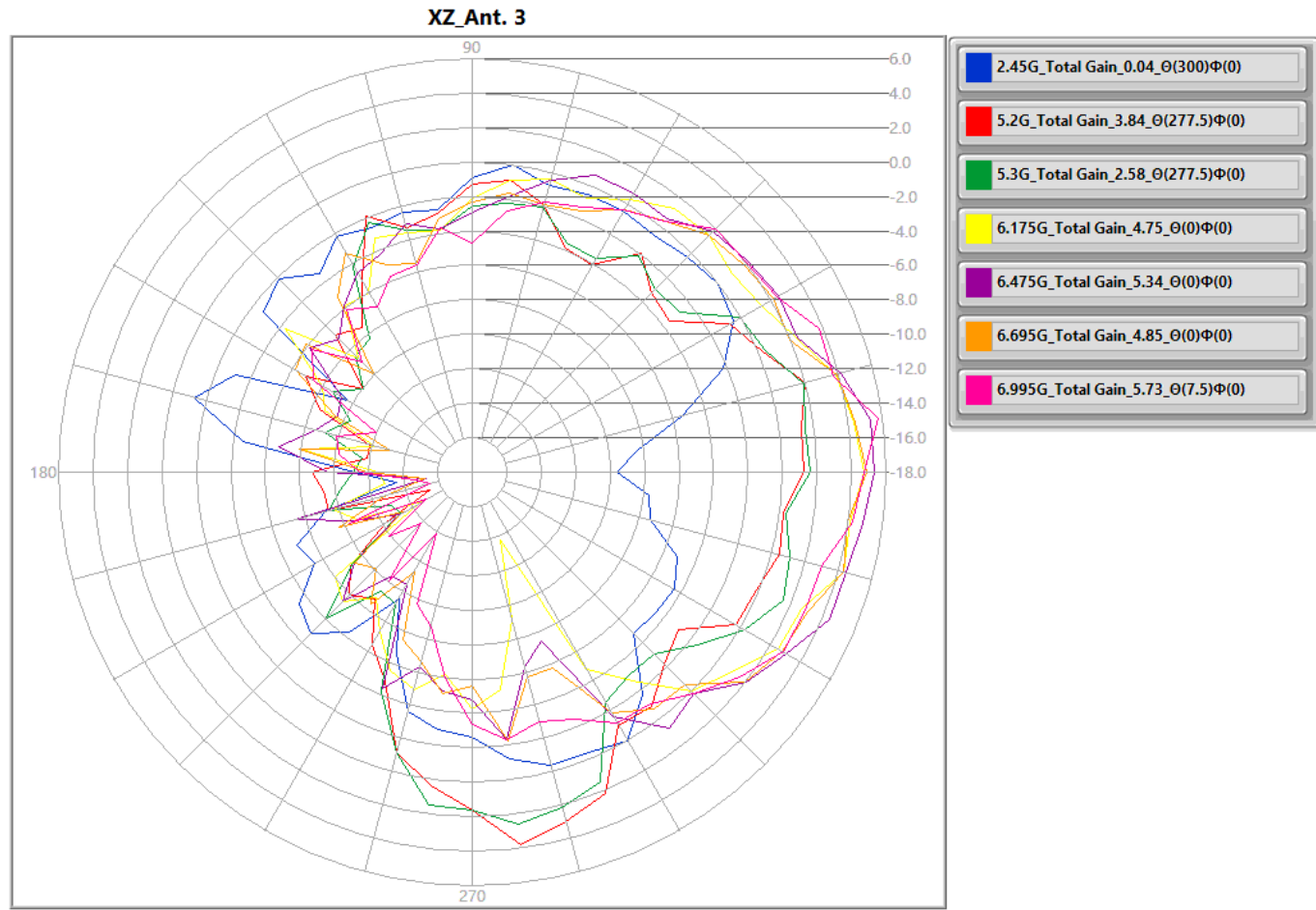


E1(XY plane) –  $\Theta(90)\Phi(0-360)$   
E2(XZ plane) –  $\Theta(0-180)\Phi(0)$  and  $\Theta(0-180)\Phi(180)$   
E3(YZ plane) –  $\Theta(0-180)\Phi(90)$  and  $\Theta(0-180)\Phi(270)$





## Total Gain Data

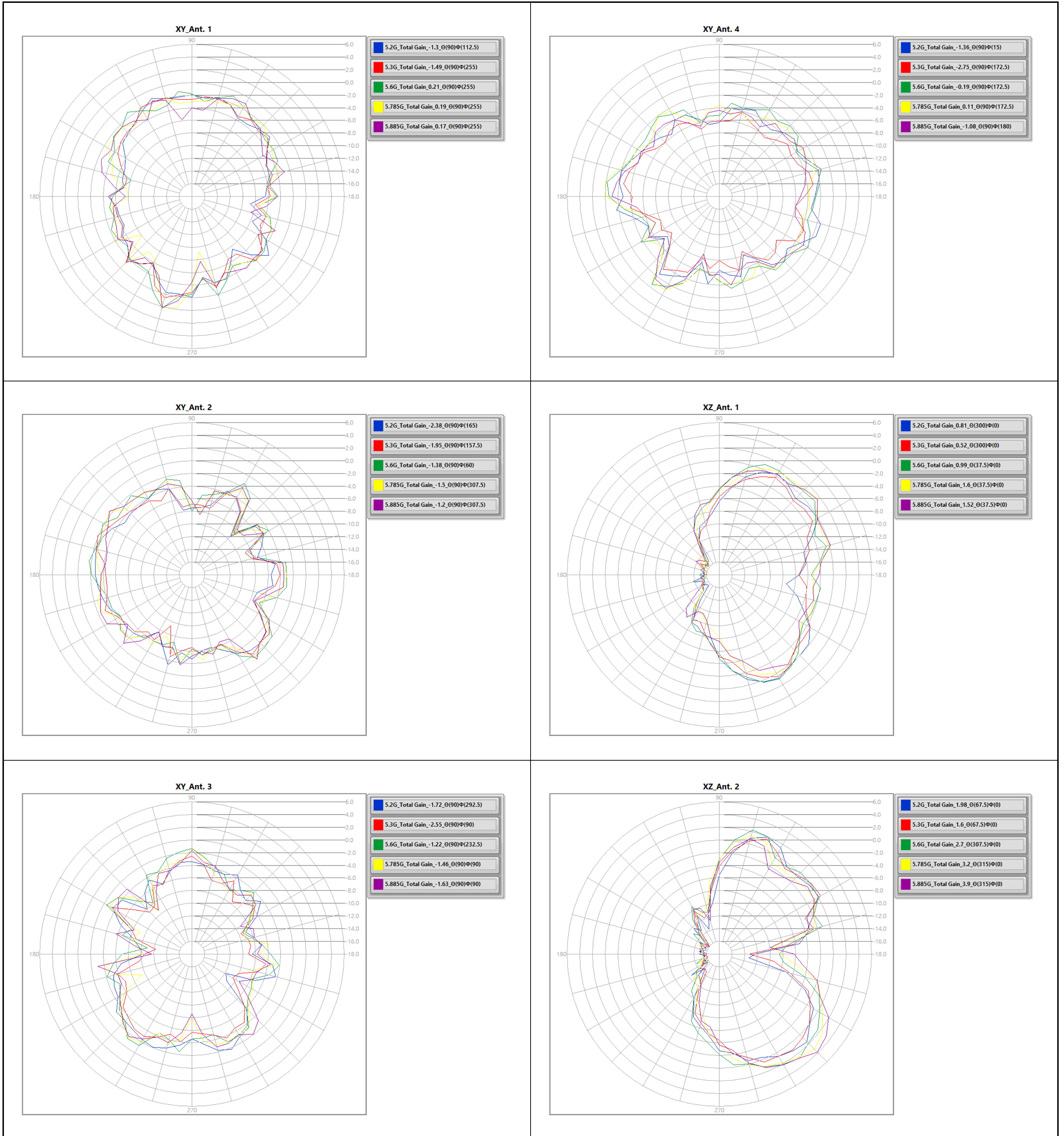


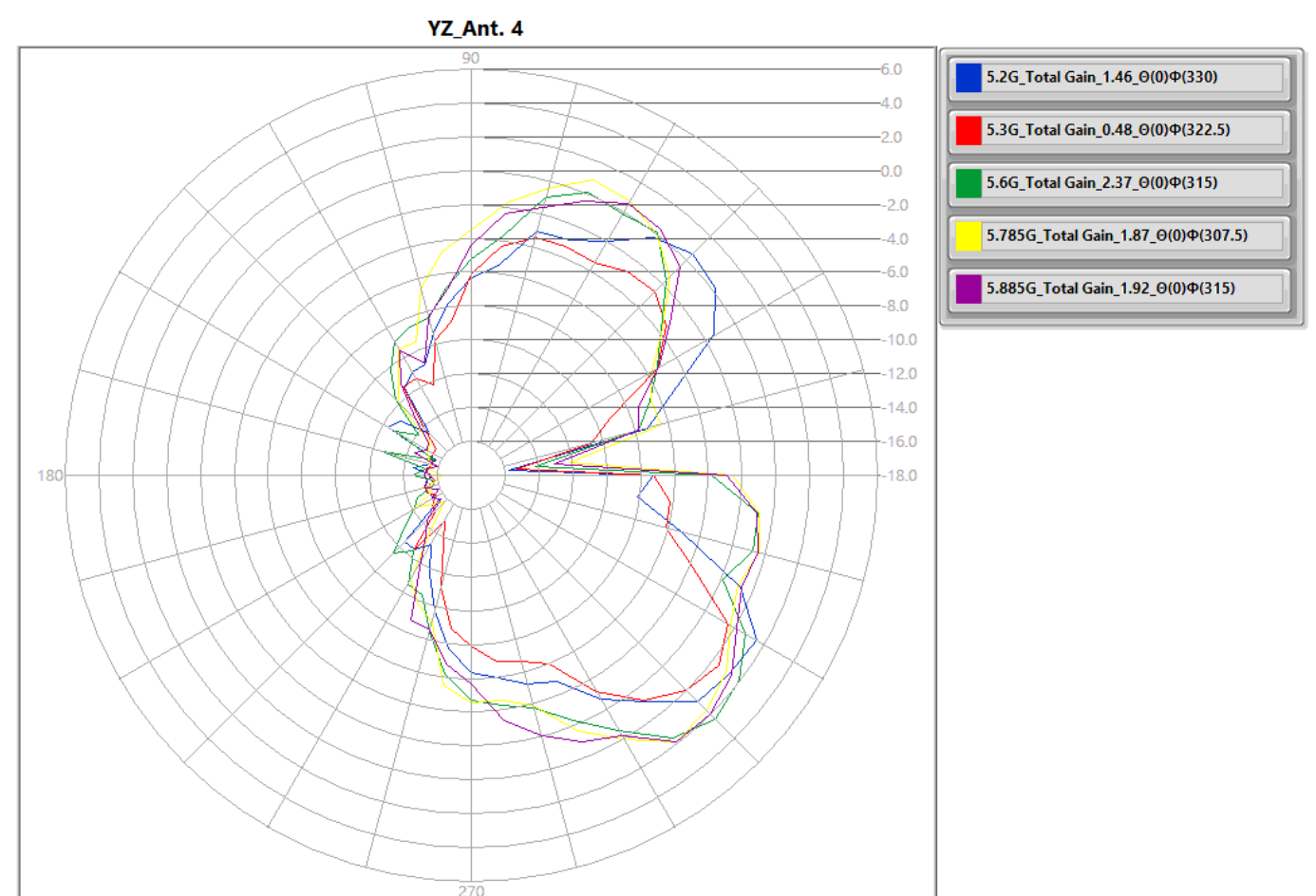
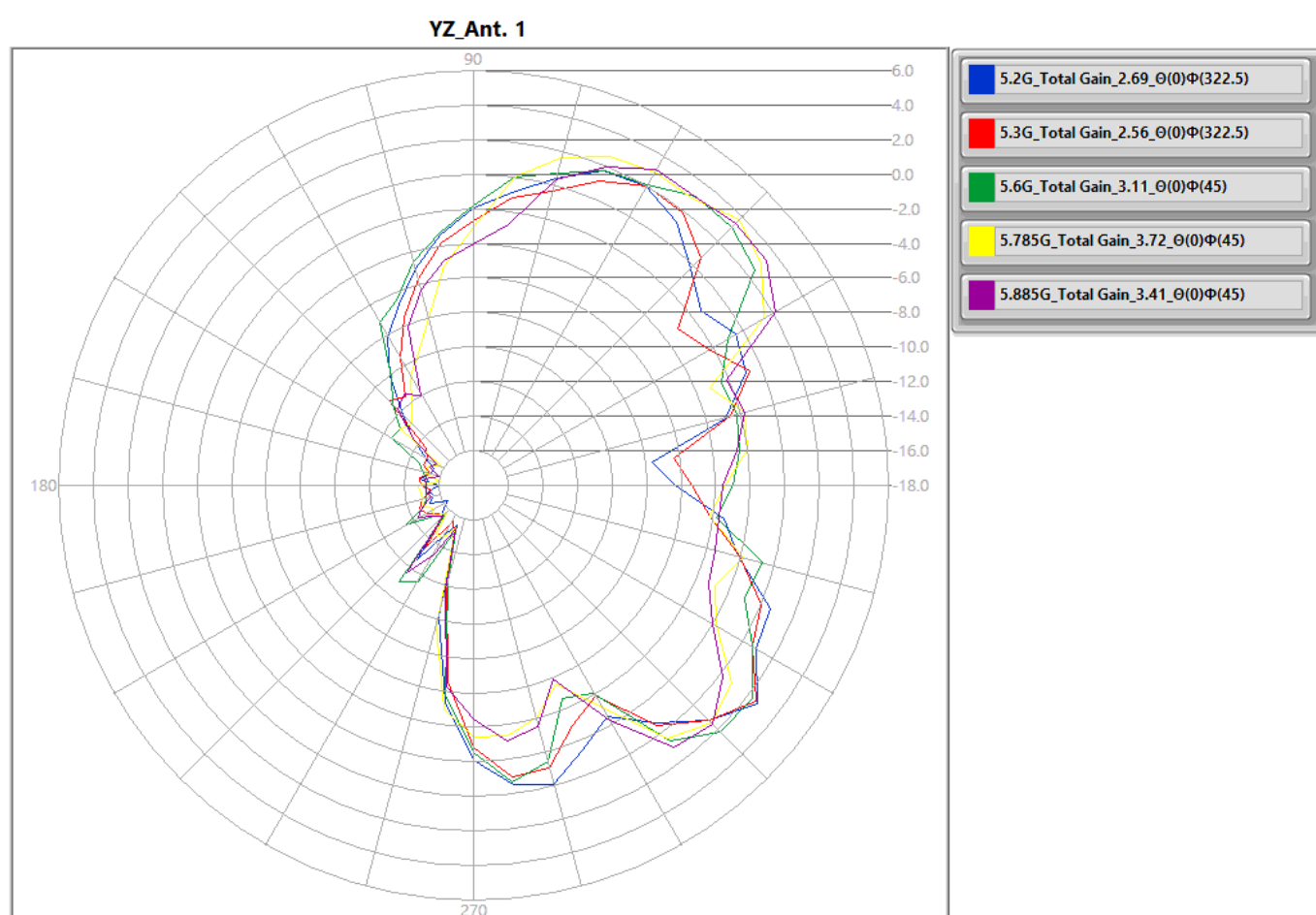
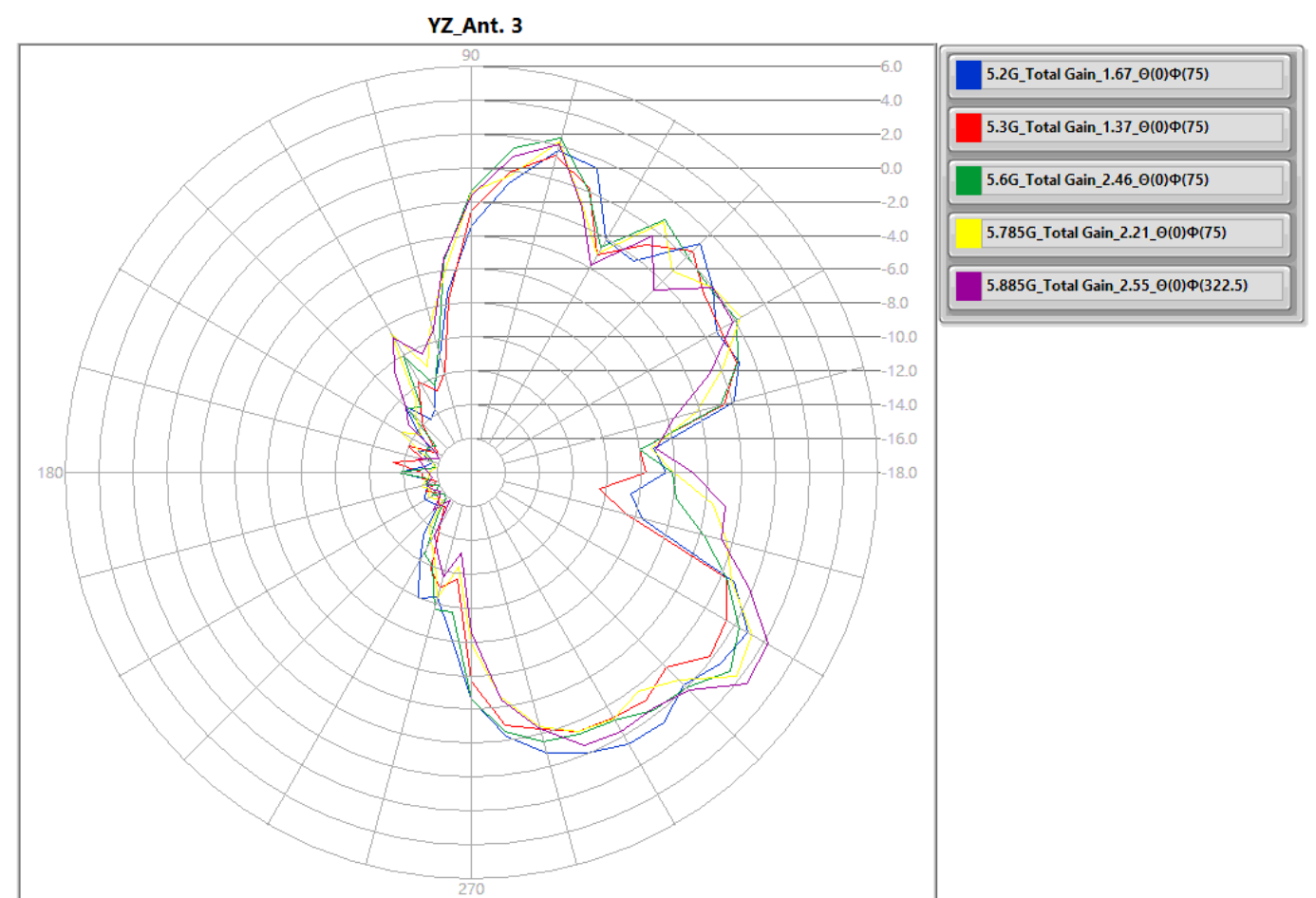
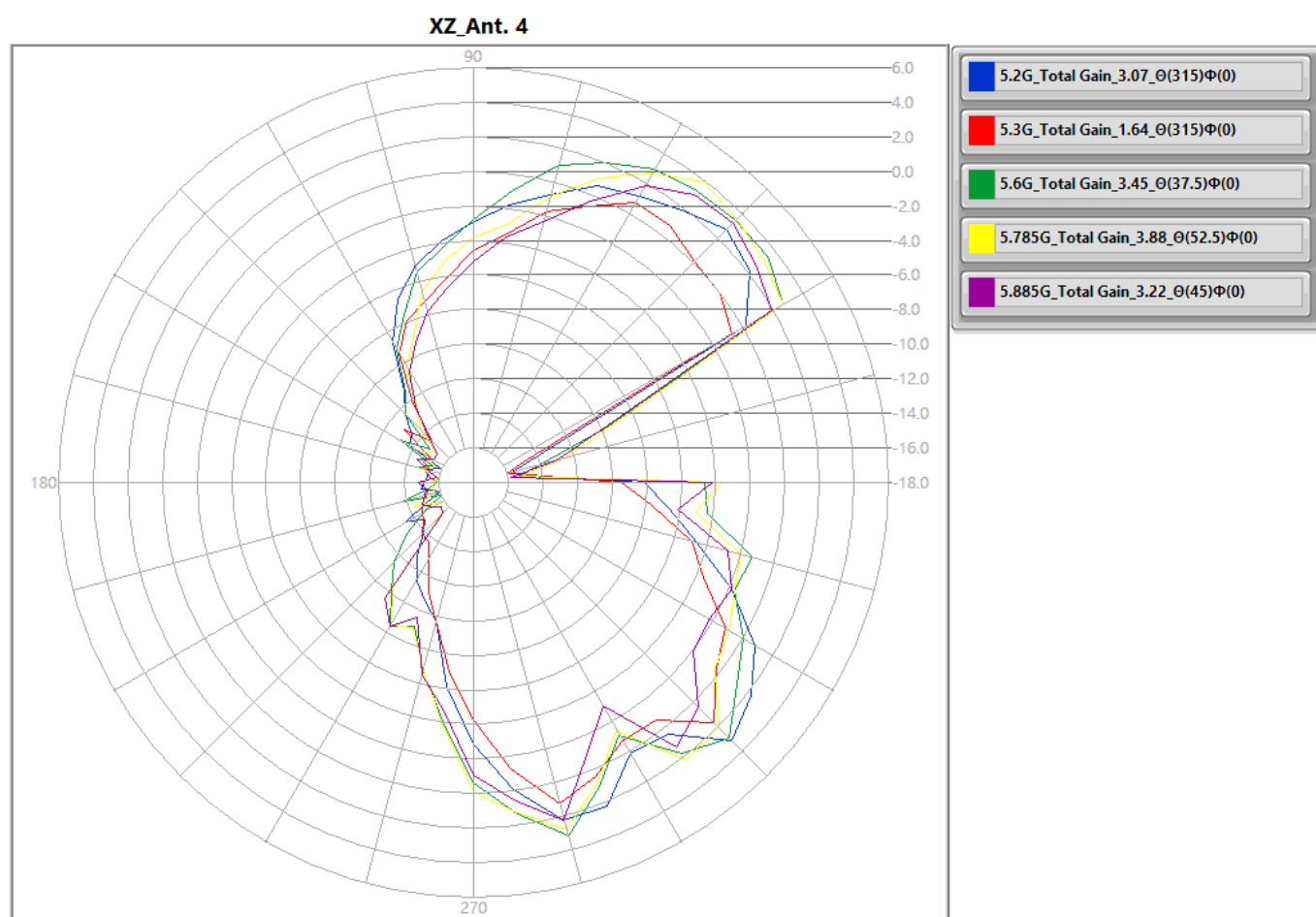
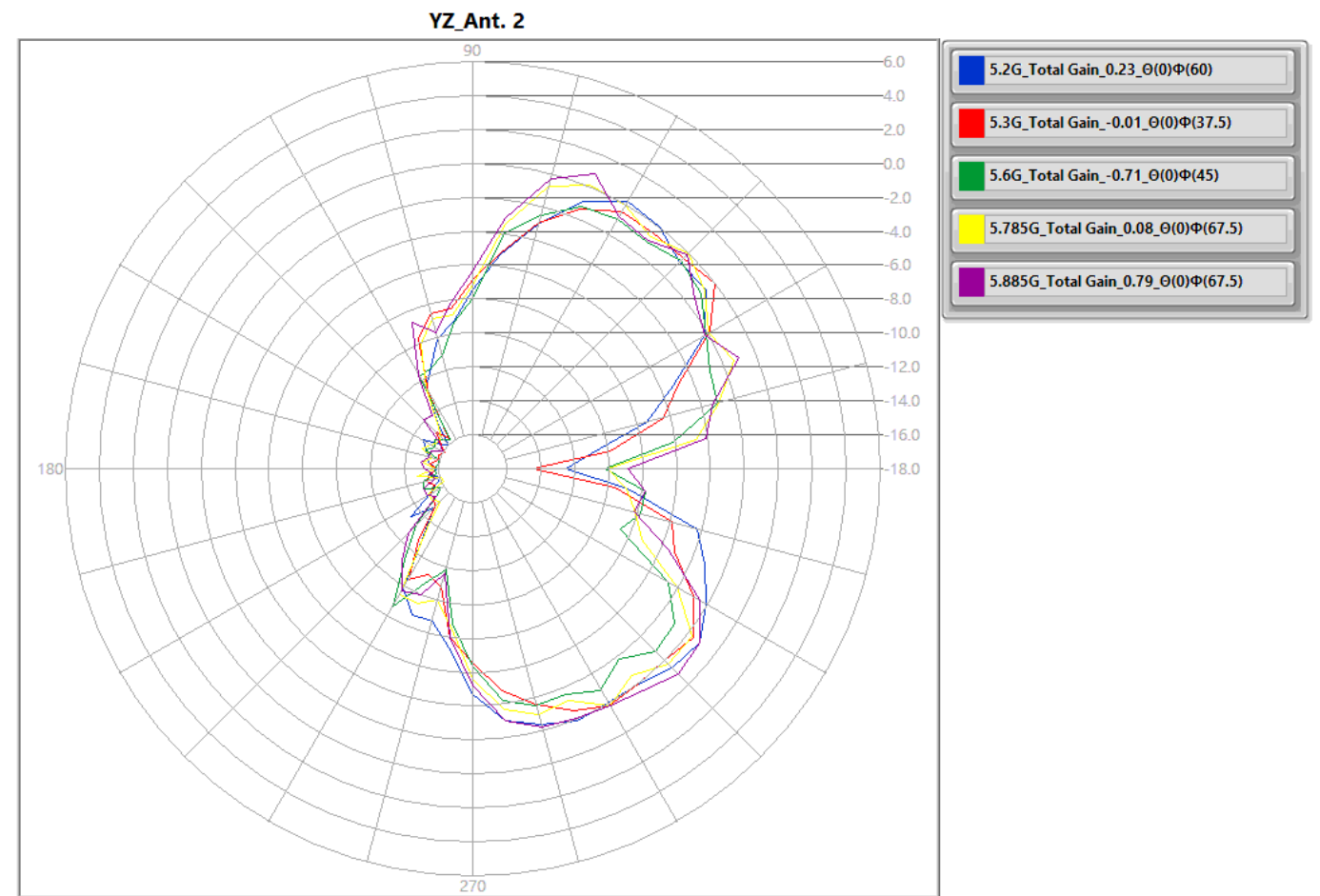
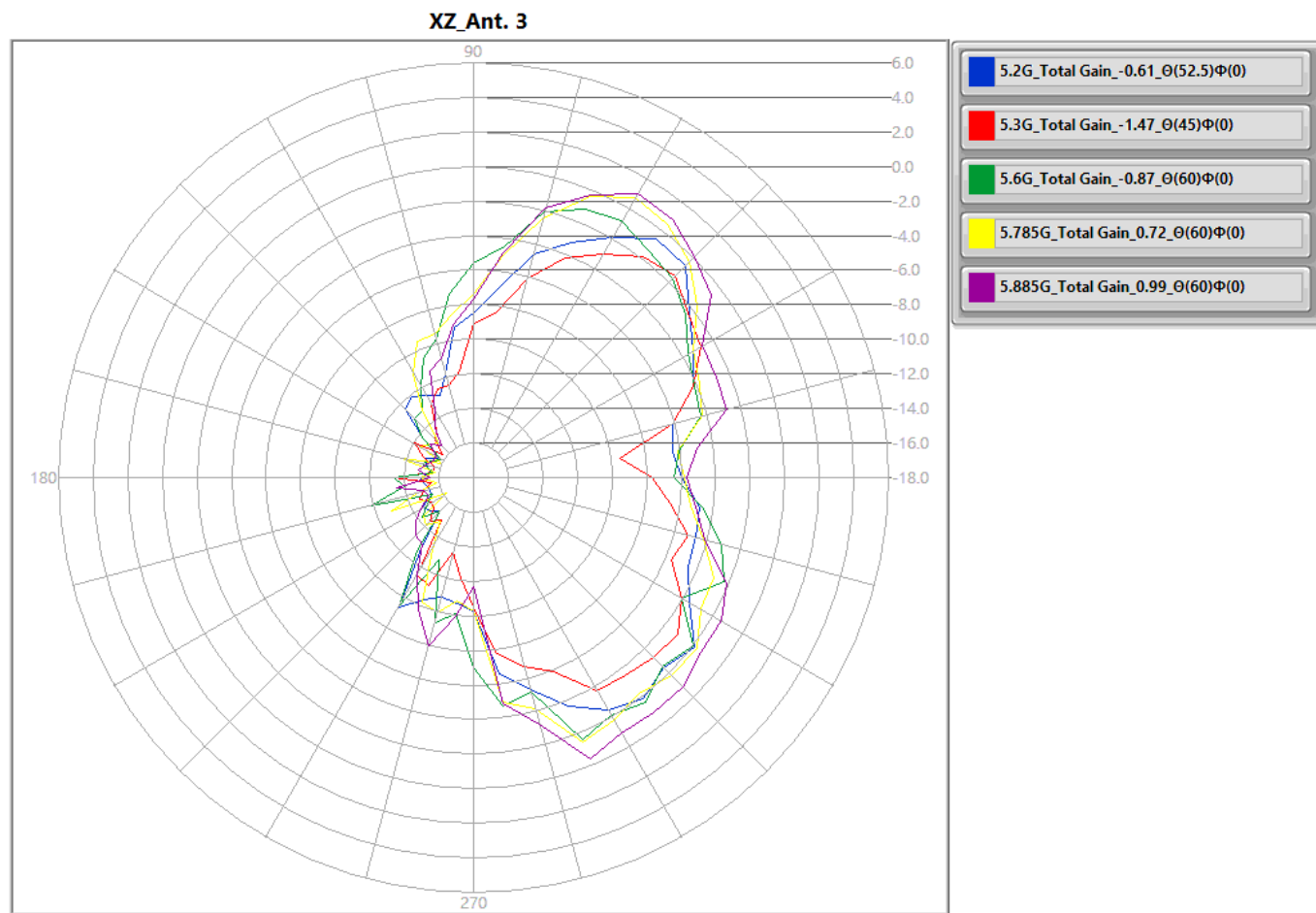






E1(XY plane) –  $\Theta(90)\Phi(0-360)$   
 E2(XZ plane) –  $\Theta(0-180)\Phi(0)$  and  $\Theta(0-180)\Phi(180)$   
 E3(YZ plane) –  $\Theta(0-180)\Phi(90)$  and  $\Theta(0-180)\Phi(270)$







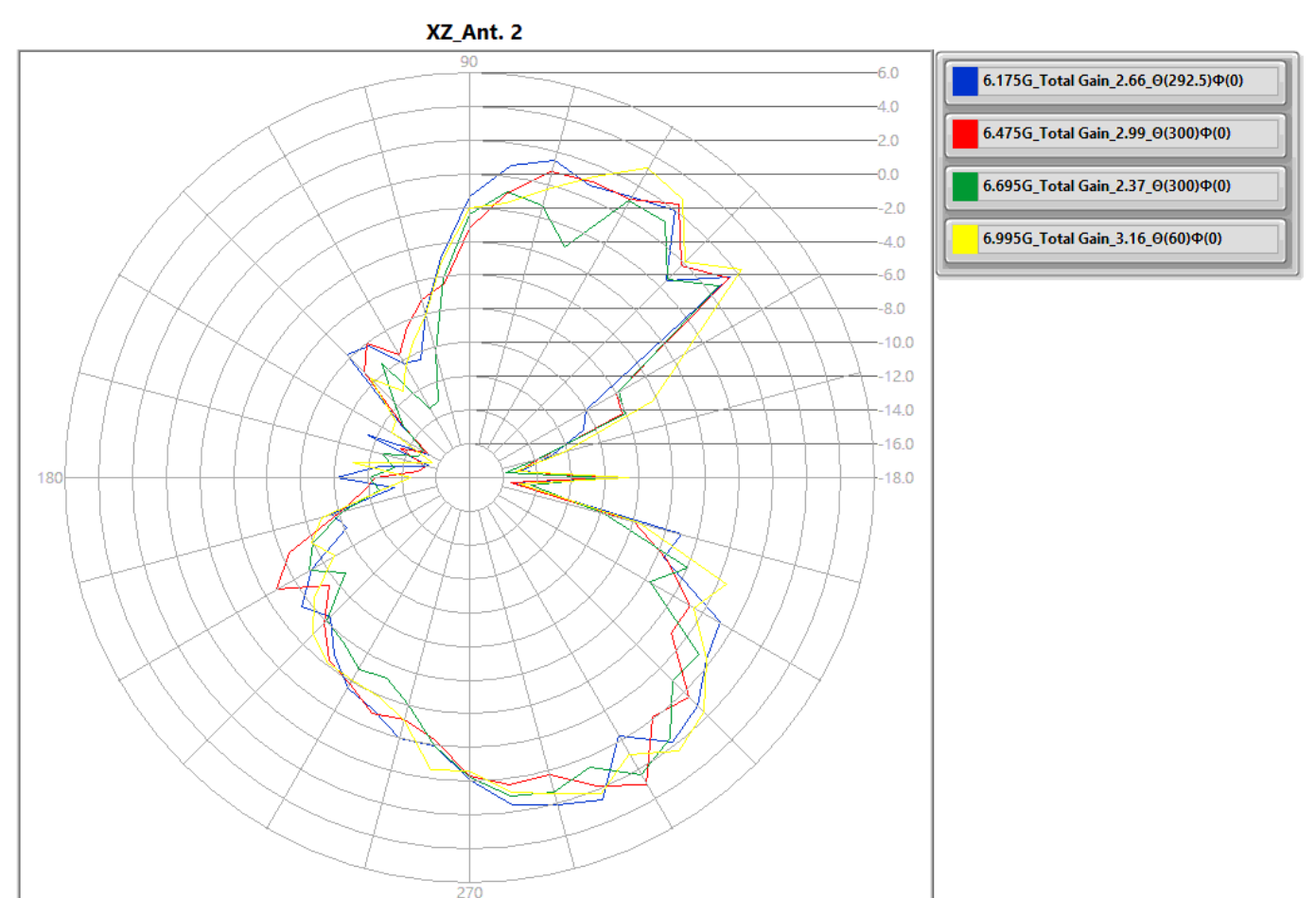
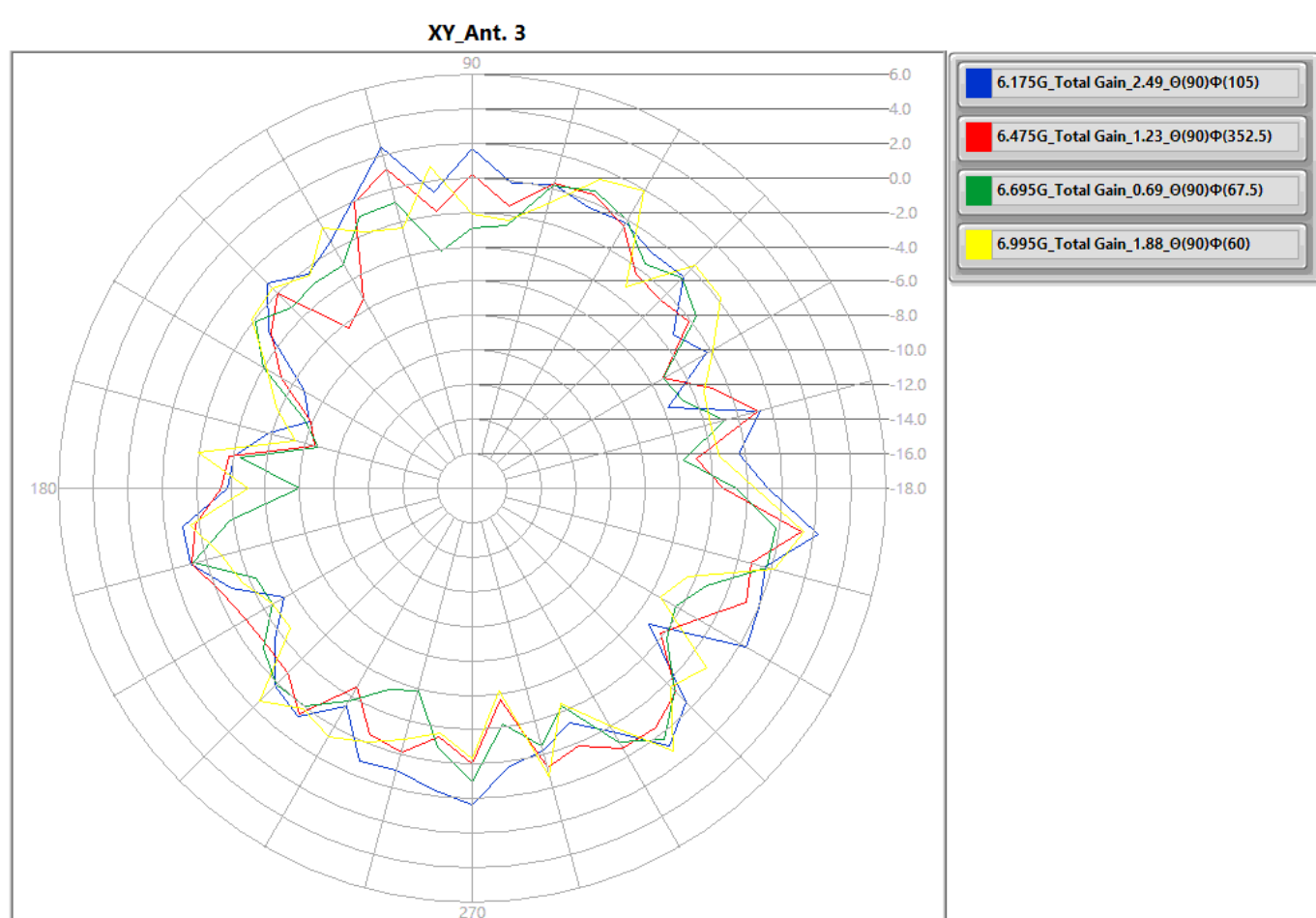
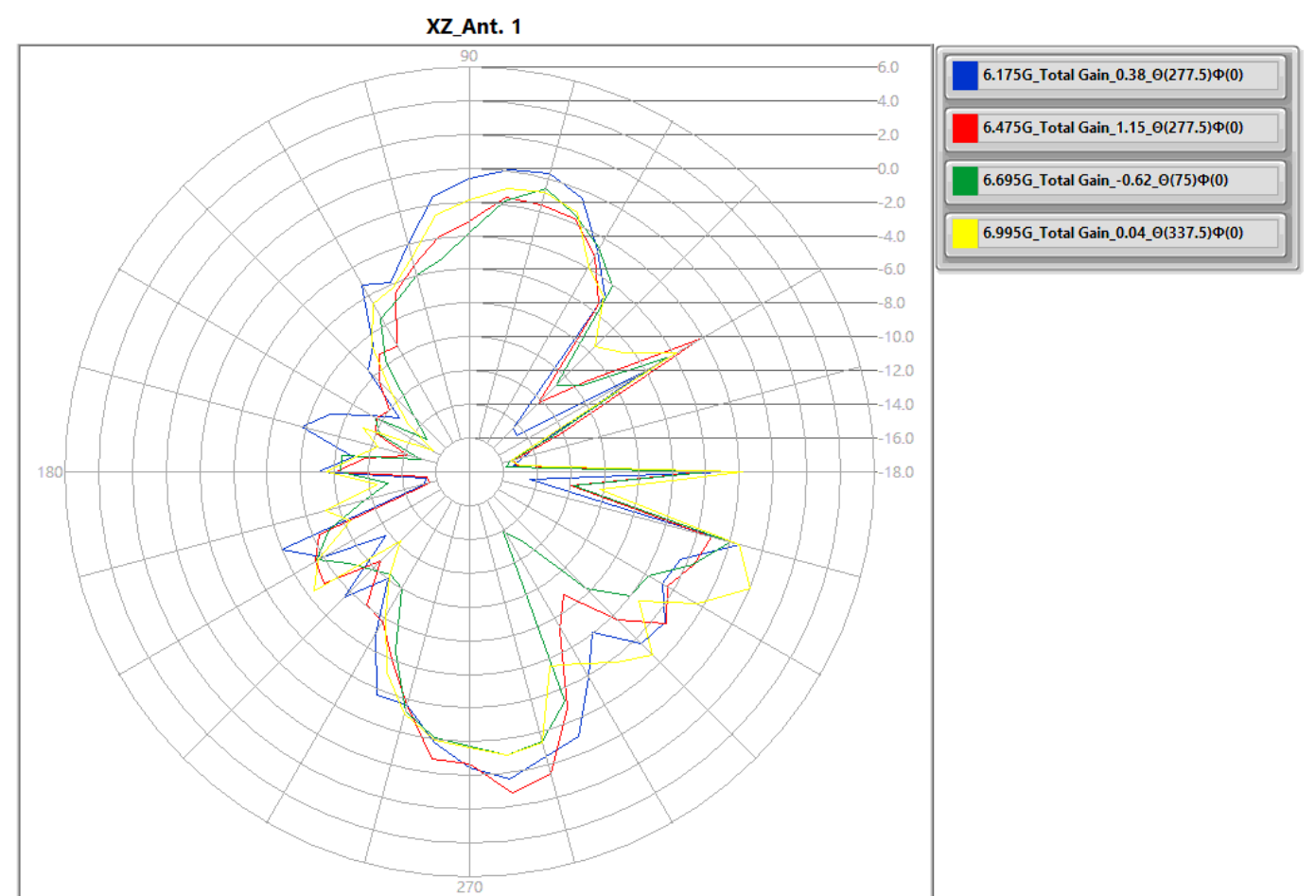
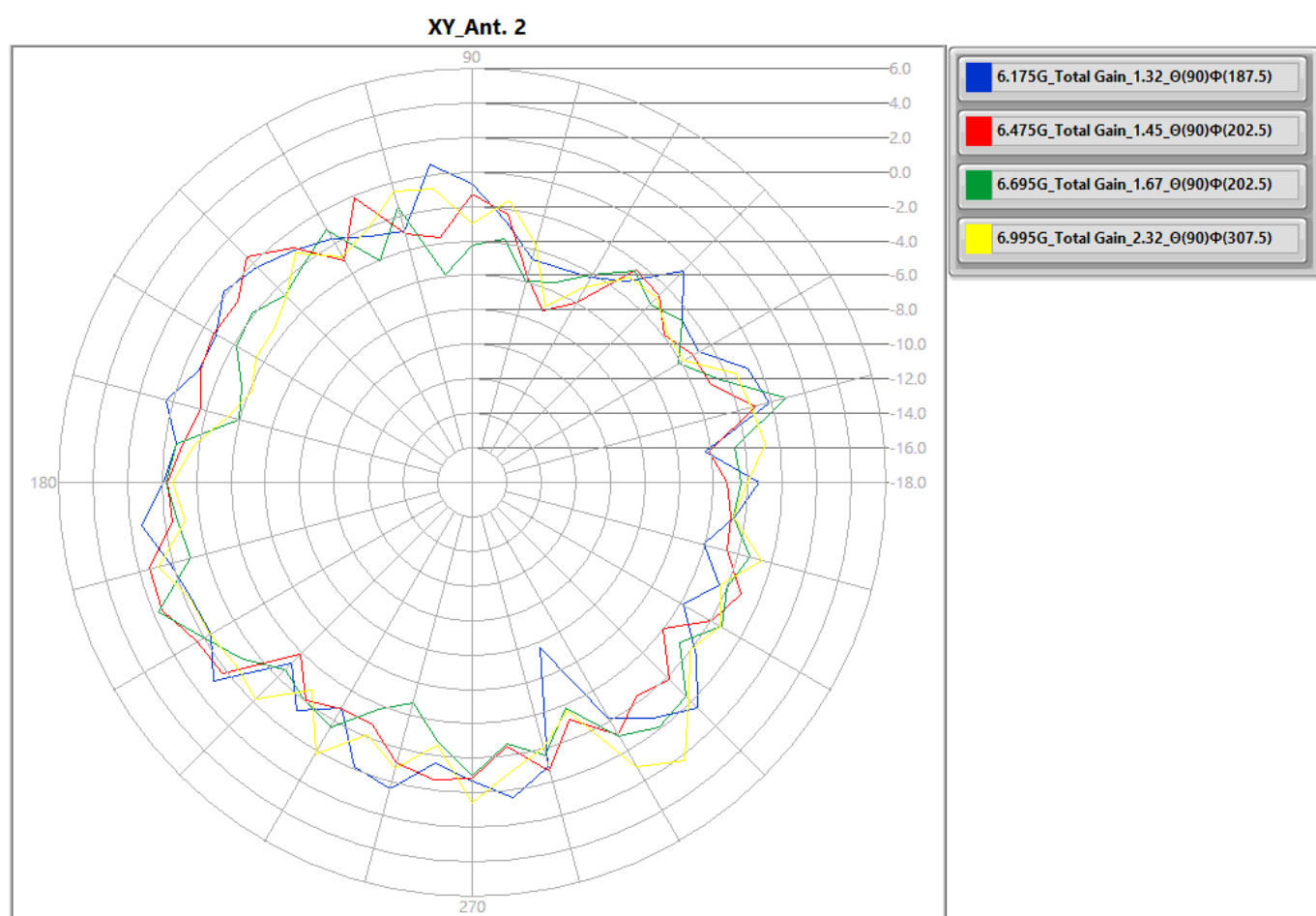
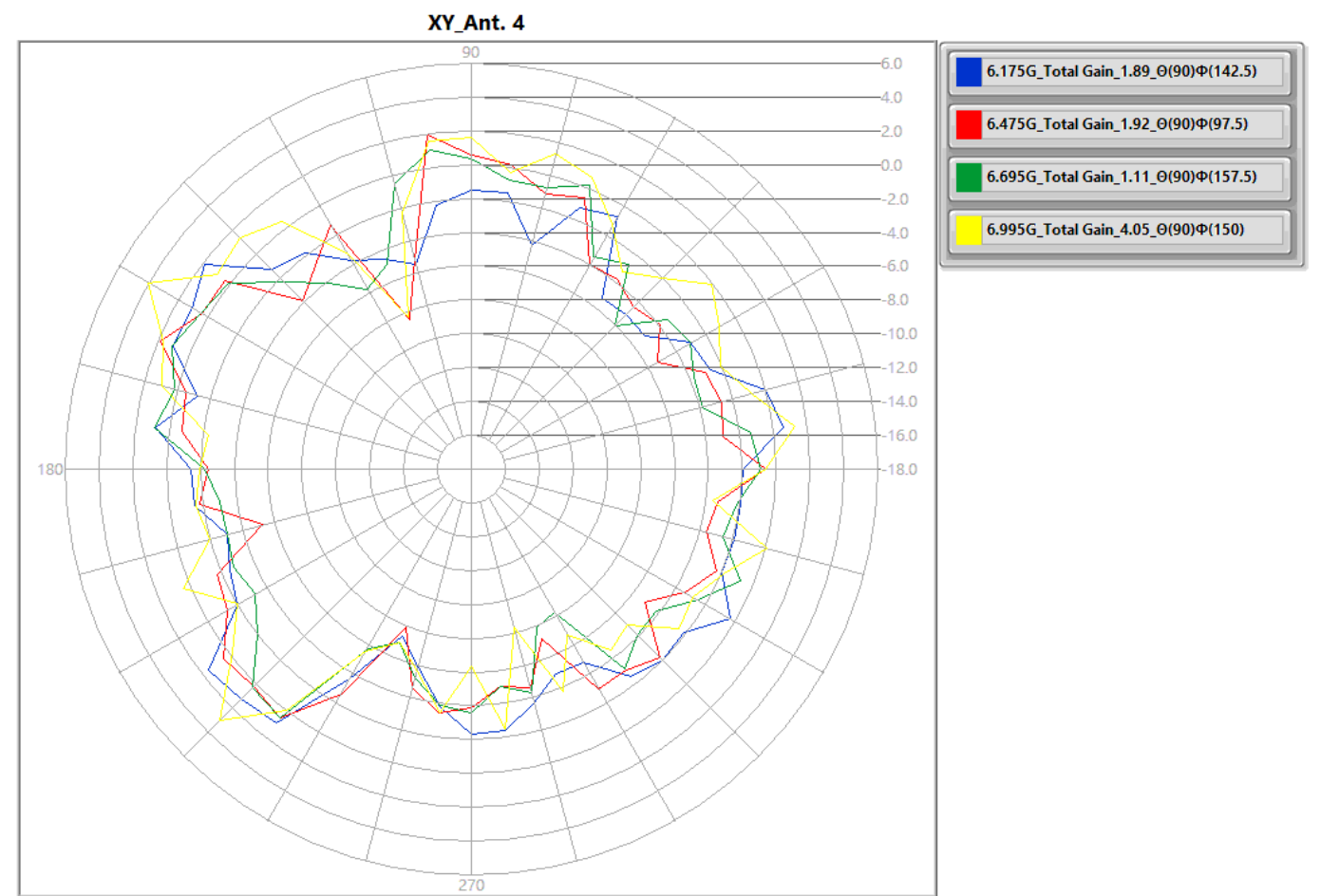
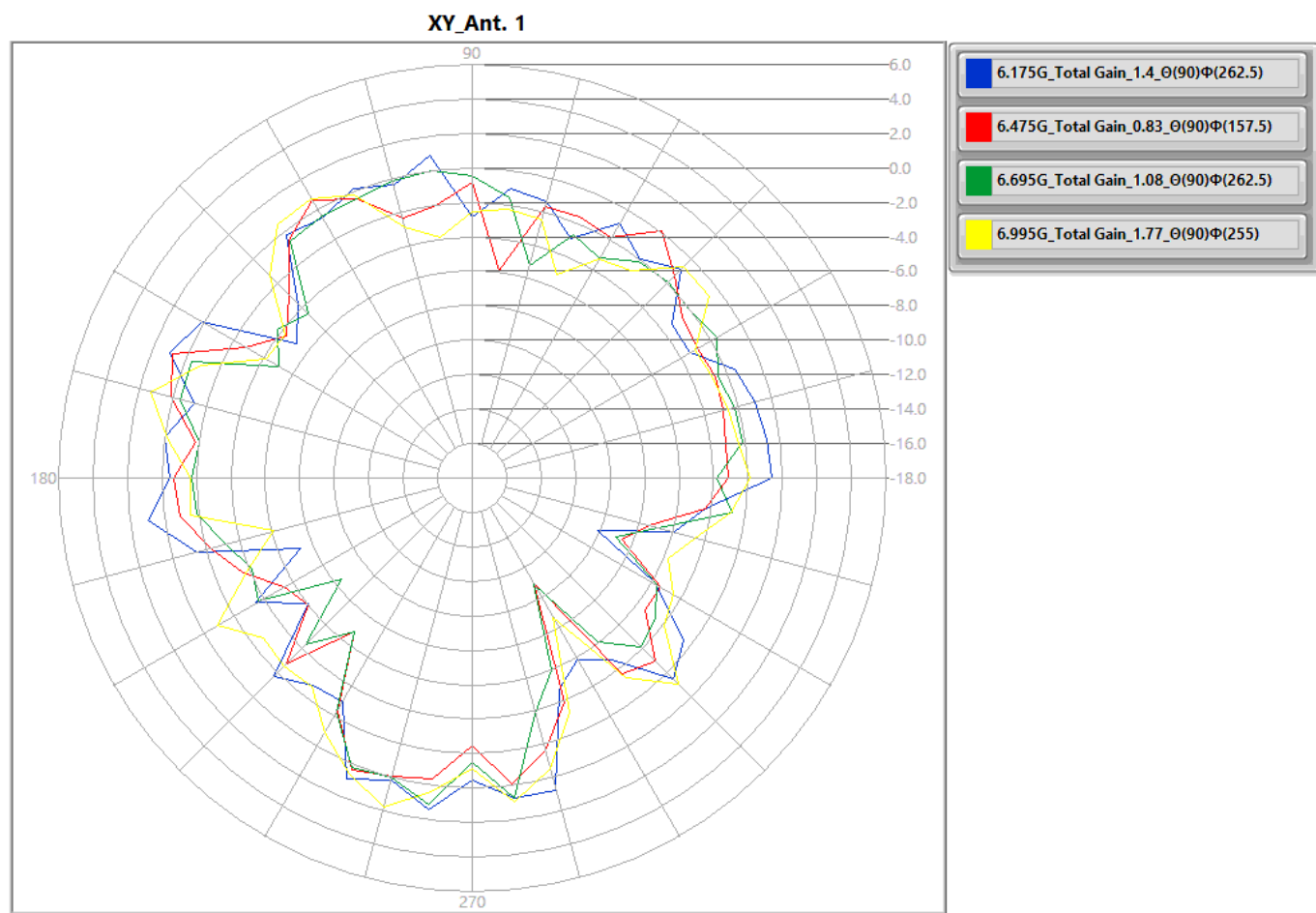
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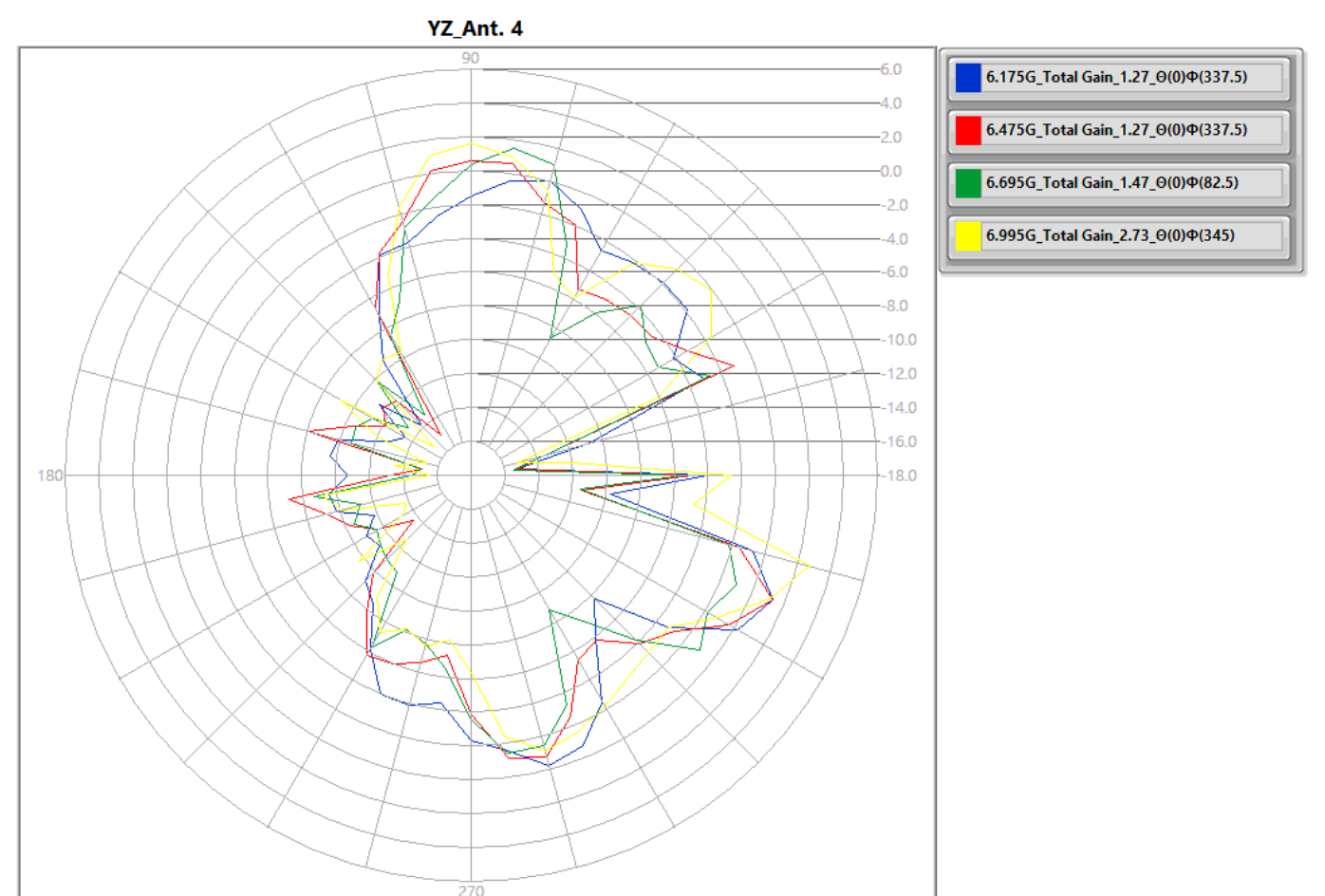
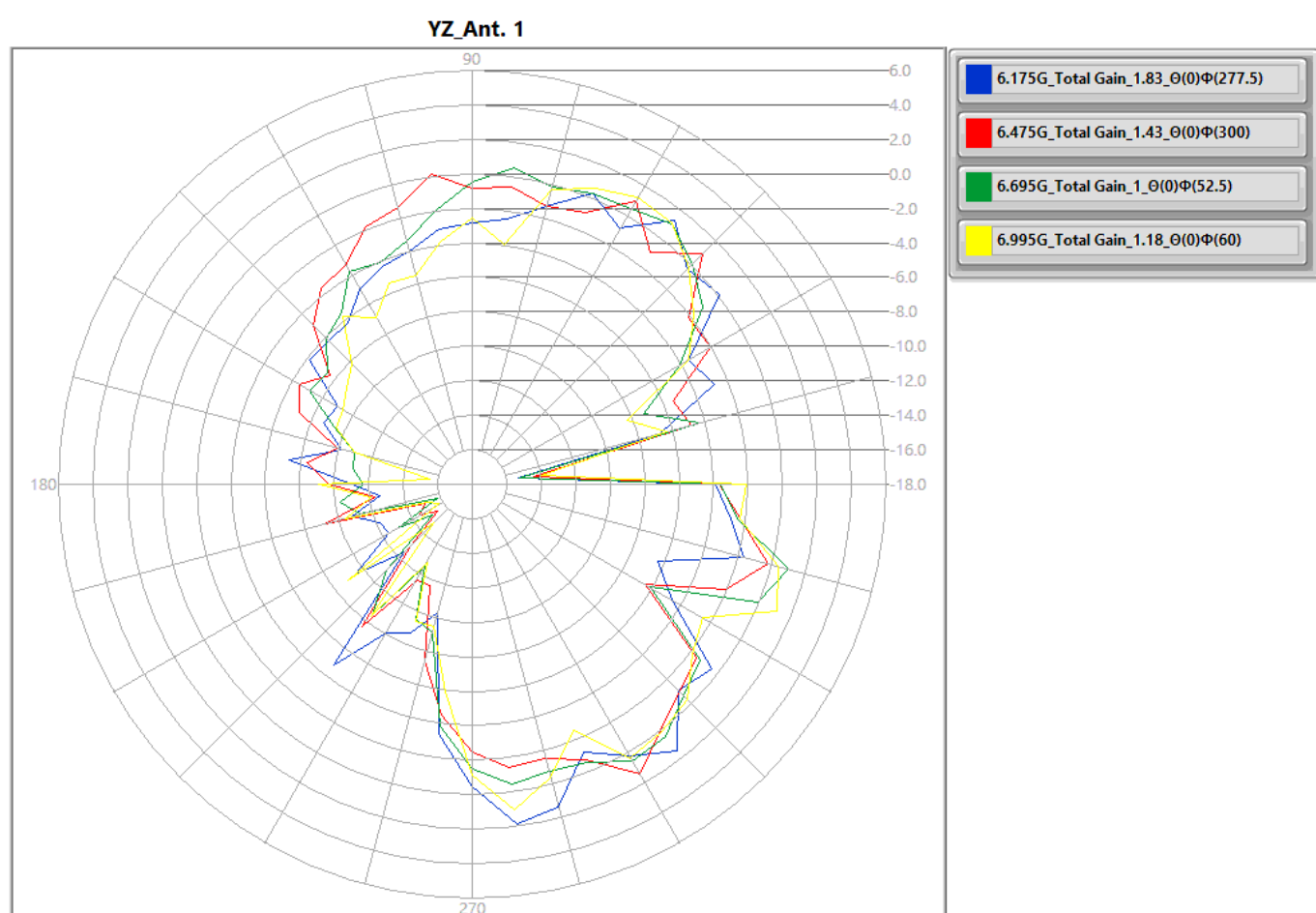
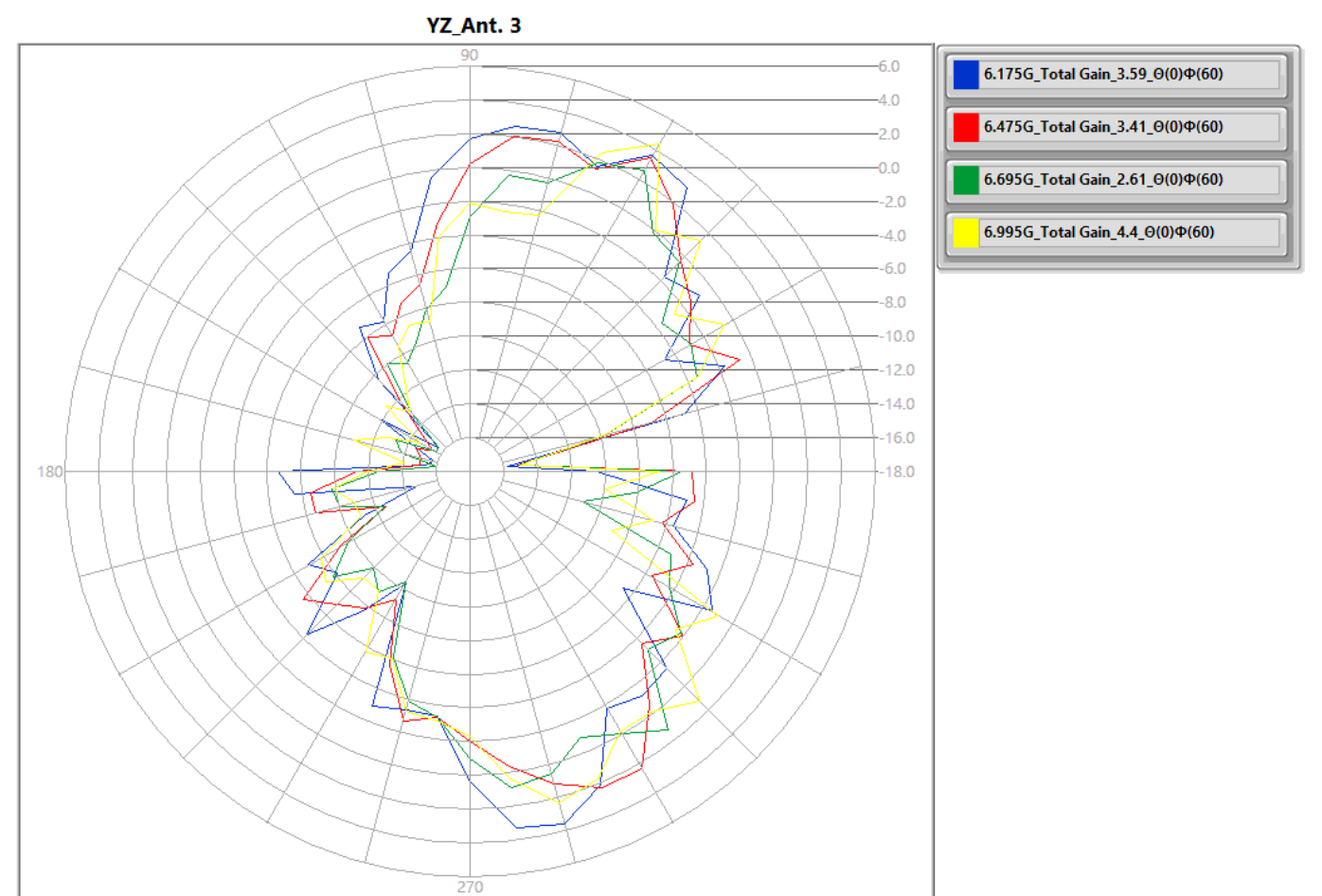
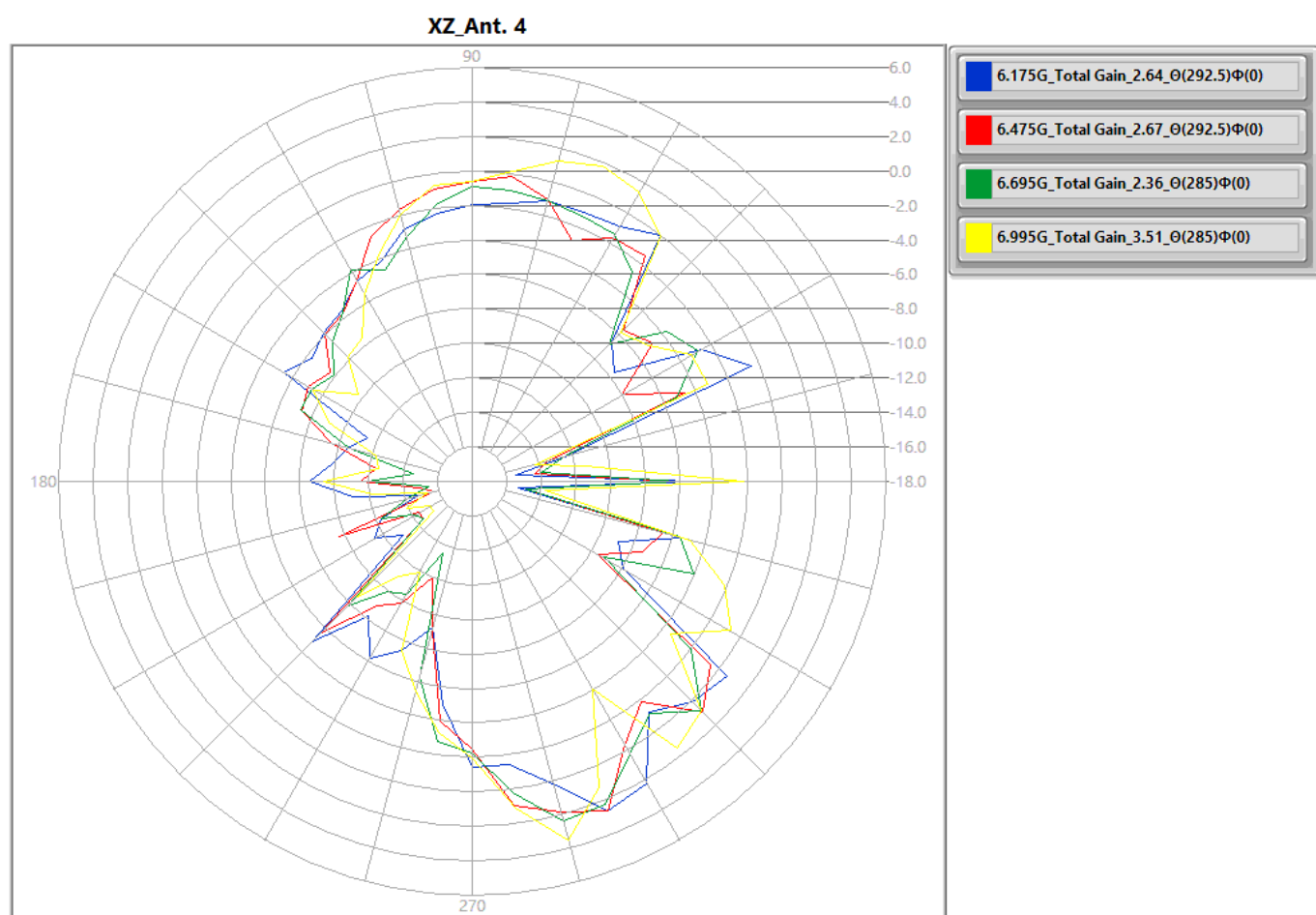
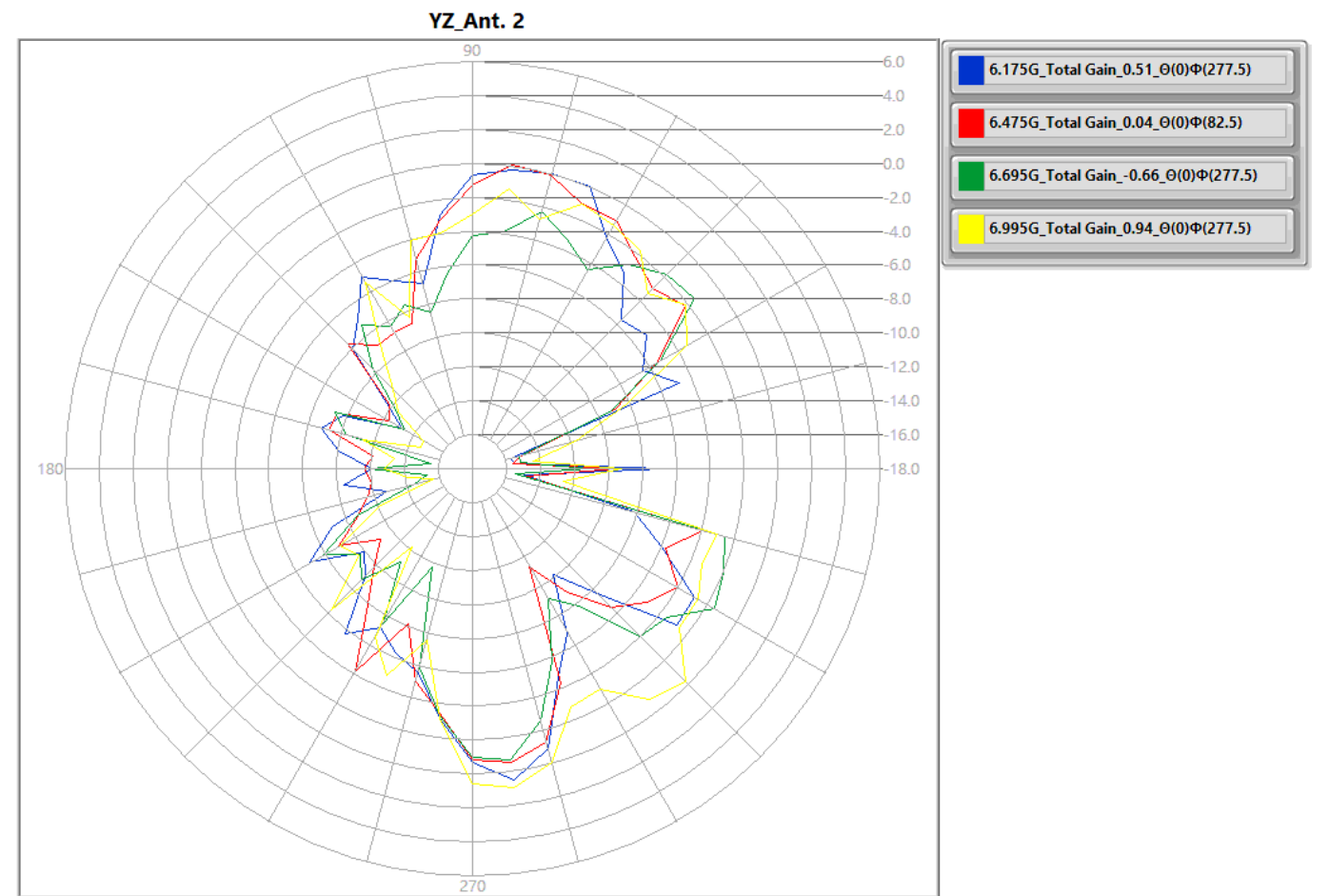
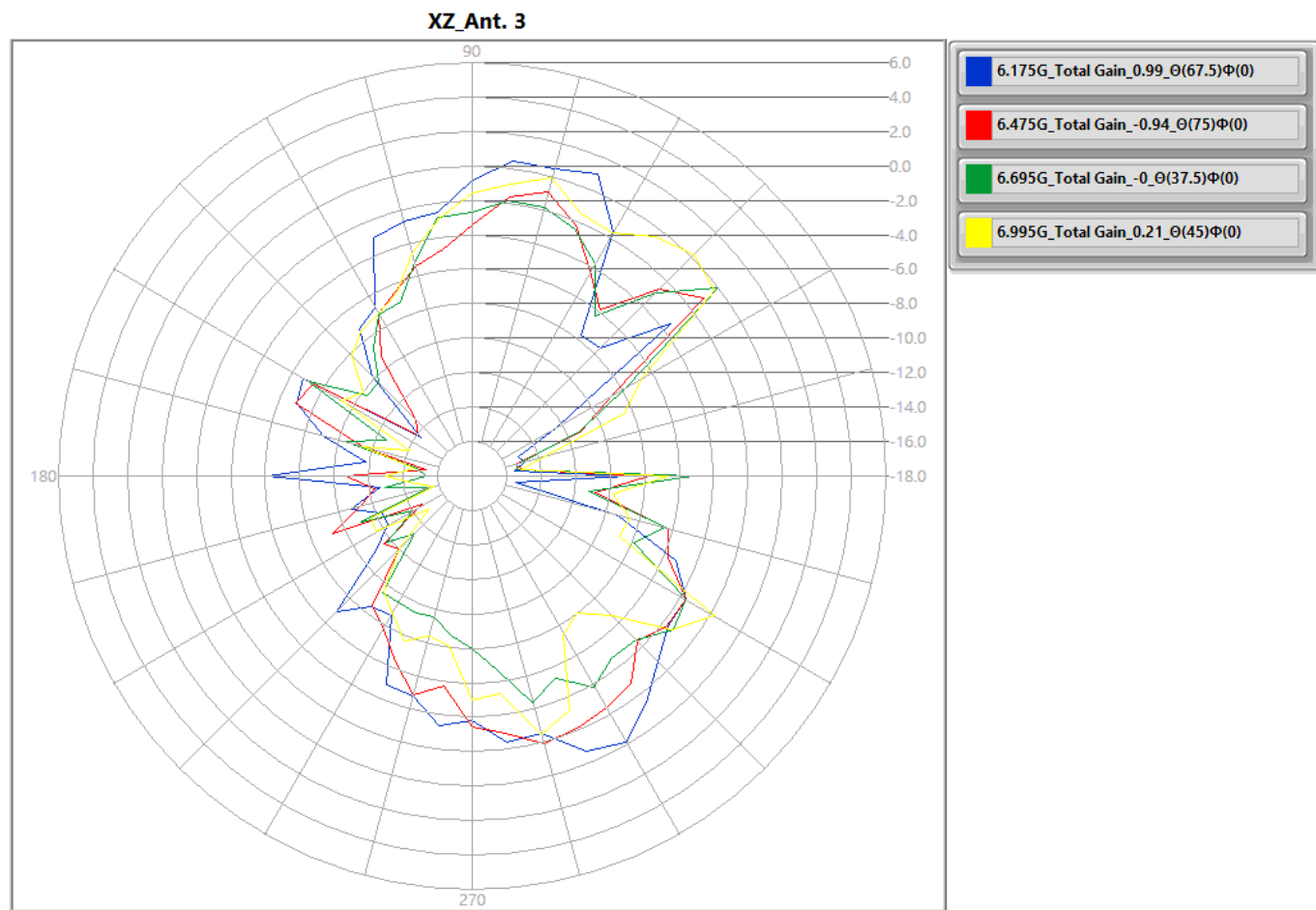






E1(XY plane) –  $\Theta(90)\Phi(0-360)$   
 E2(XZ plane) –  $\Theta(0-180)\Phi(0)$  and  $\Theta(0-180)\Phi(180)$   
 E3(YZ plane) –  $\Theta(0-180)\Phi(90)$  and  $\Theta(0-180)\Phi(270)$





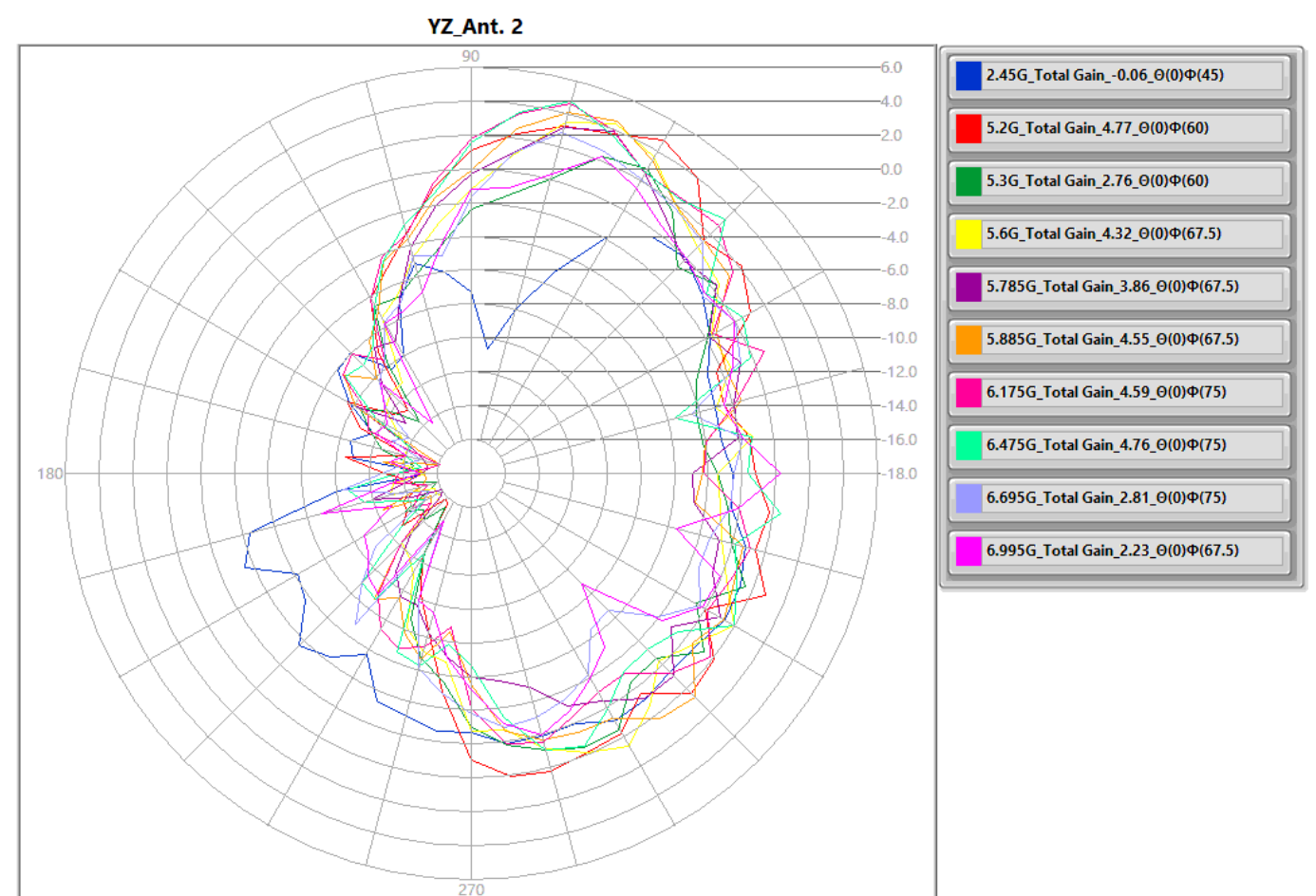
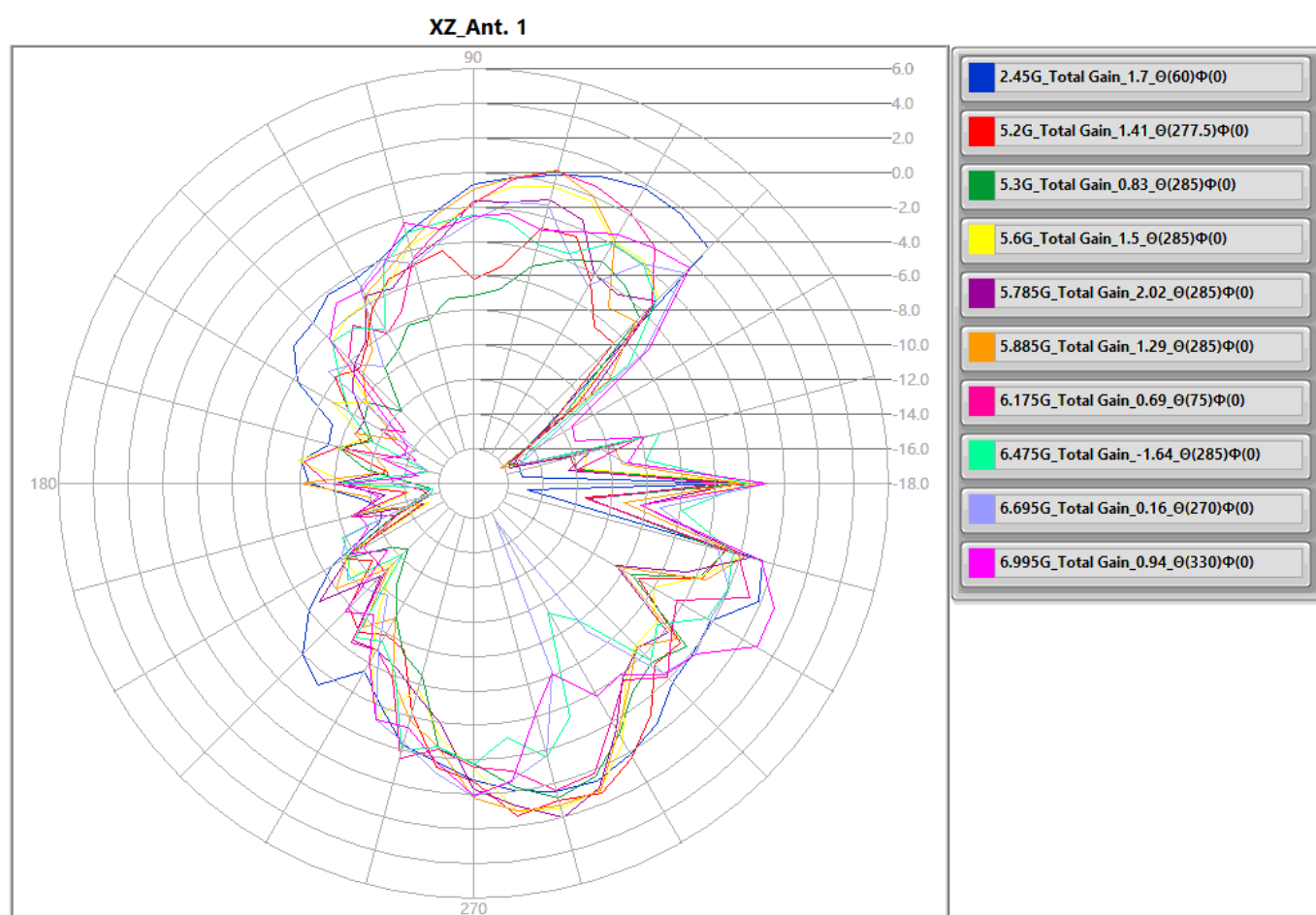
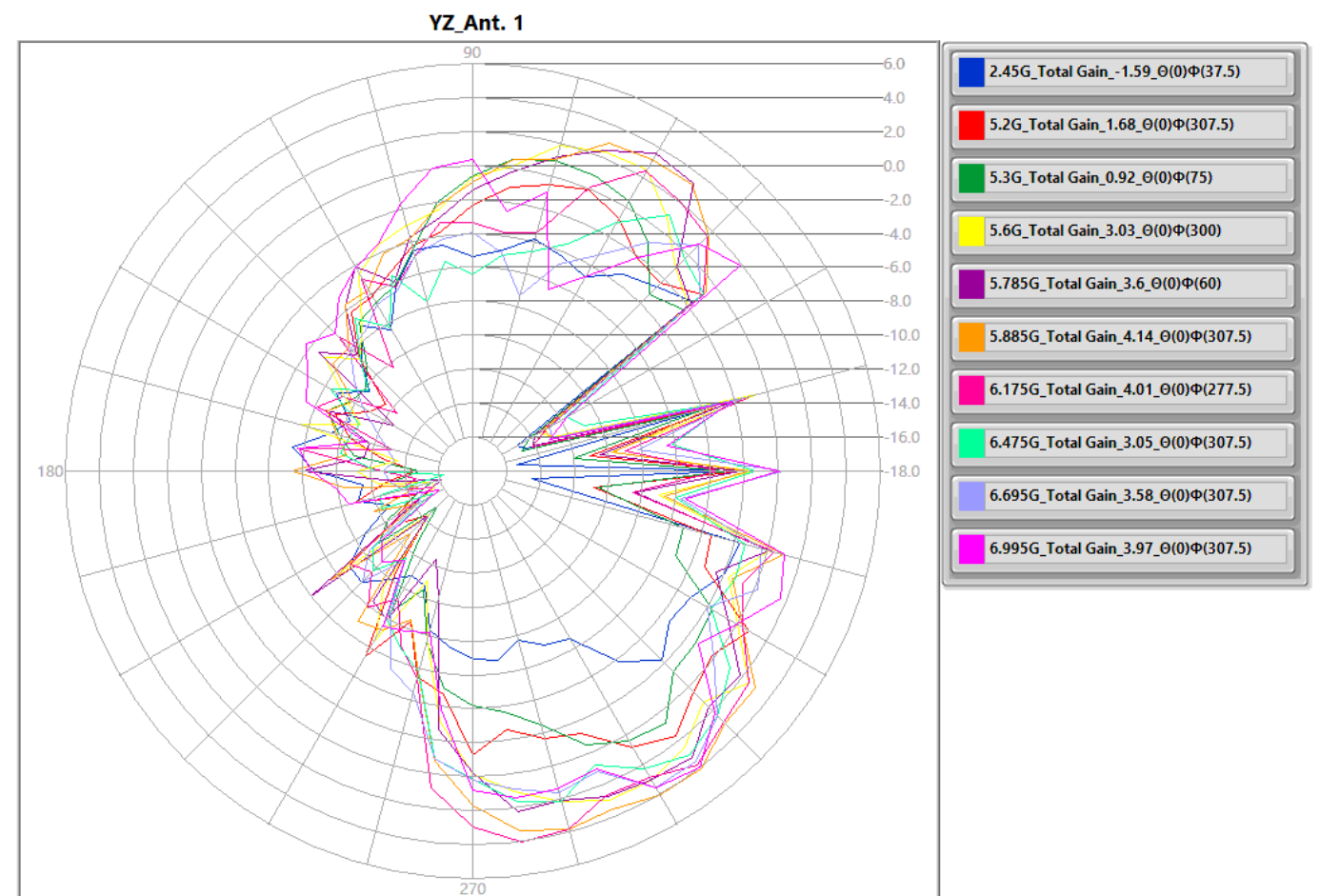
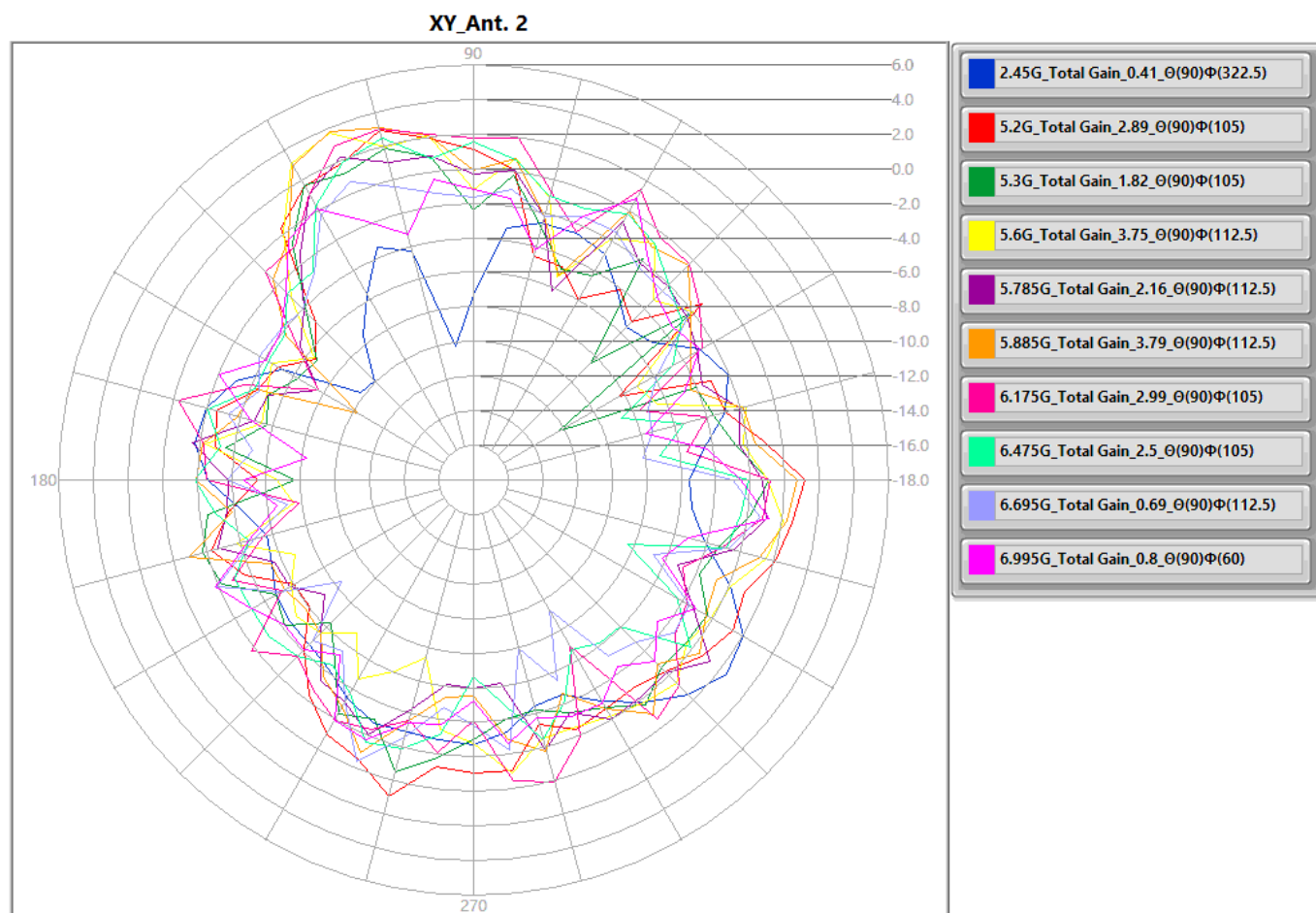
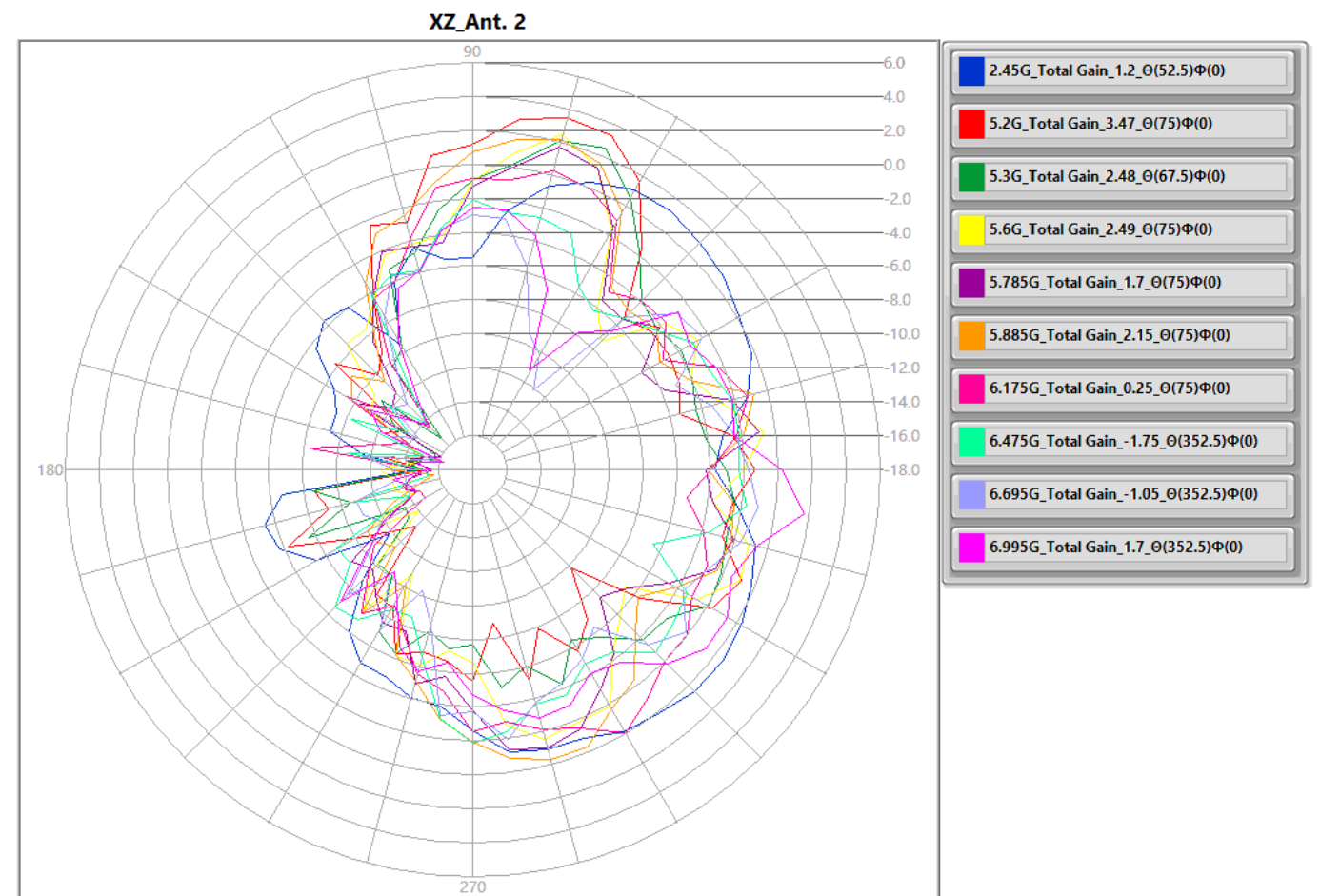
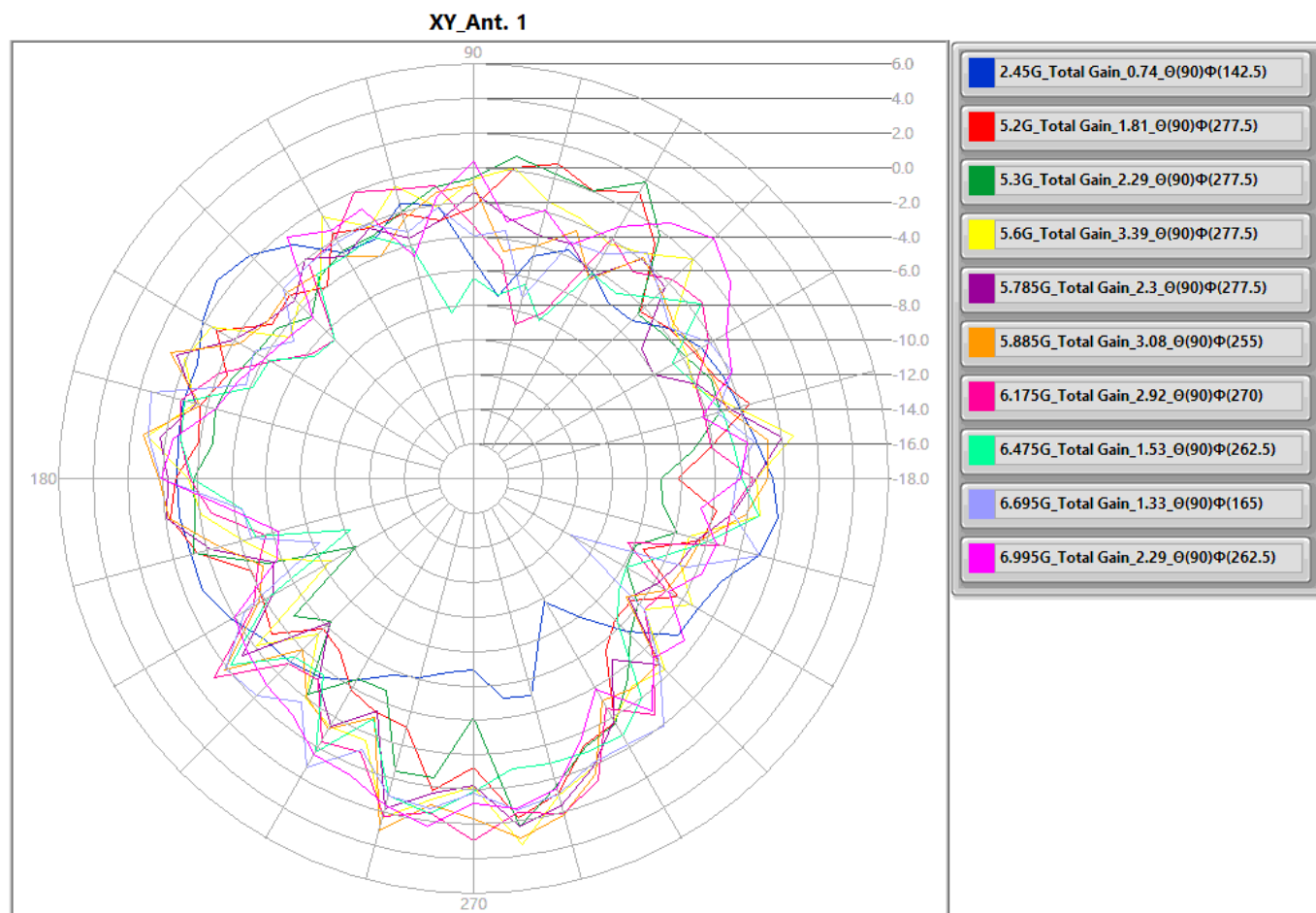










E1(XY plane) –  $\Theta(90)\Phi(0-360)$ E2(XZ plane) –  $\Theta(0-180)\Phi(0)$  and  $\Theta(0-180)\Phi(180)$ E3(YZ plane) –  $\Theta(0-180)\Phi(90)$  and  $\Theta(0-180)\Phi(270)$ 



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