

# **Test Report**

Applicant : Edimax Technology Co., Ltd.

Applicant Address : No.278, Xinhu 1st Rd., Neihu Dist., Taipei City, Taiwan

Product Name : Industrial AC650 Dual-Band USB Adapter

Trade Name : EDIMAX

Model Number : IEW-7811UTC, EW-7811WTC

Applicable Standard : 47 CFR §2.1093

Received Date : Nov. 14, 2022

Test Period : Dec. 08 ~ Dec. 10, 2022

Issued Date : Jan. 17, 2023

Issued by

Approved By	:		

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Test Firm MRA designation number: TW0010

Taiwan Accreditation Foundation accreditation number: 1330





Note:

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# **Revision History**

Rev.	Issue Date	Revisions	Revised By
00	Jan. 07, 2023	Initial Issue	Abby Hsu
01	Jan. 17, 2023	Update Chapter 2 (P.5)	Abby Hsu

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## 1. General Information

## 1.1 Reference Testing Standards

Standard	Description	Version
47 CFR §2.1093	Radiofrequency radiation exposure evaluation: portable devices	-
IEEE 1528	Determining the Peak Spatial-Average Specific Absorption Rate (SAR) in the Human Head from Wireless Communications Devices: Measurement Techniques	2013
IEEE C95.1	IEEE Standard for Safety Levels with Respect to Human Exposure to Electric, Magnetic, and Electromagnetic Fields, 0 Hz to 300 GHz	1992
KDB 248227 D01	SAR guidance for IEEE 802.11 (Wi-Fi) transmitters	v02r02
KDB 447498 D02	SAR Procedures for Dongle	v02r01
KDB 447498 D04	RF exposure procedures and equipment authorization policies for mobile and portable devices	v01
KDB 865664 D01	SAR measurement requirement for 100 MHz to 6 GHz	v01r04
KDB 865664 D02	RF exposure compliance reporting and documentation considerations	v01r02

## 1.2 Testing Location

Site Name: Site Name: Eurofins E&E Wireless Taiwan Co., Ltd.

Site Address: No. 140-1, Changan Street, Bade District, Taoyuan City 334025, Taiwan (R.O.C.)

Site Address: 
No. 2, Wuquan 5th Rd. Wugu Dist., New Taipei City, Taiwan (R.O.C.)

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# 2. Description of Device Under Test (DUT)

Applicant	Edimax Technology Co., Ltd. No.278, Xinhu 1st Rd., Neihu Dist., Taipei City, Taiwan
Product Name	Industrial AC650 Dual-Band USB Adapter
Trade Name	EDIMAX
Model Number	IEW-7811UTC, EW-7811WTC
Models different description	Different model numbers are for market purpose.
SN No.	B2260014334
FCC ID	NDD9578112209
Frequency Range	WLAN 2.4 GHz Band: 2412 - 2472 MHz WLAN 5.2 GHz Band: 5180 - 5240 MHz WLAN 5.8 GHz Band: 5745 - 5825 MHz
Composited Madulations	WLAN 2.4 GHz : 802.11b / g / n HT20 / HT40 / VHT20 / VHT40
Supported Modulations	WLAN 5 GHz: 802.11a / n / ac HT20 / HT40 / VHT20 / VHT40 / VHT80
Device Category	Portable

### Note:

1. The above information of DUT was declared by manufacturer. Please refer to the specifications or user's manual for more detailed description.

Antenna Information			
Model Type Frequency M			Max. Gain (dBi)
ALX22M-222AA1	PIFA antenna	2412 - 2472 MHz	1.8
ALX22M-222AA1	PIFA antenna	5180 - 5240 MHz	2.1
ALX22M-222AA1	PIFA antenna	5745 – 5825 MHz	2.5

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## 3. Summary of Maximum Value

		Highest Reported SAR	
Equipment Class	Mode	Body standalone SAR <sub>1 g</sub> (W/kg)	
DTS	WLAN 2.4 GHz	0.73	
NII	WLAN 5 GHz	1.17	

#### Note:

- 1. The SAR limit for general population / uncontrolled exposure is specified in FCC 47 CFR part 2 (2.1093) and ANSI/IEEE C95.1-1992.
- 2. The test procedures, as described in American National Standards, Institute ANSI/IEEE C95.1 were employed and they specify the maximum exposure limit of tissue for portable devices being used within 20 cm between user and EUT in the uncontrolled environment. A description of the product and operating configuration, detailed summary of the test results, methodology and procedures used in the equipment used are included within this test report.

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### 4. Introduction

### 4.1 SAR Definition

Specific Absorption Rate (SAR) is defined as the time derivative (rate) of the incremental energy (dw) absorbed by (dissipated in) an incremental mass (dm) contained in a volume element (dv) of a given density (ρ). The equation description is as below:

$$SAR = \frac{d}{dt} \left( \frac{dw}{dm} \right) = \frac{d}{dt} \left( \frac{dw}{\rho dv} \right)$$

SAR measurement can be related to the electrical field in the tissue by

$$\mathsf{SAR} = \frac{\sigma |E|^2}{\rho}$$

Where:

 $\sigma$  = conductivity of the tissue (S/m)

 $\rho$  = mass density of the tissue (kg/m<sup>3</sup>)

E = RMS electric field strength (V/m)

SAR is expressed in units of Watts per kilogram (W/kg).

### 4.2 RF Exposure Limits

Table 1 Safety Limits for Controlled / Uncontrolled Environment Exposure

	SAR Exposure Limit		
	General Population / Uncontrolled Exposure <sup>1</sup> (W/kg)	Occupational / Controlled Exposure <sup>2</sup> (W/kg)	
Spatial Peak SAR <sup>3</sup> (head or Body)	1.60	8.00	
Spatial Peak SAR <sup>4</sup> (Whole Body)	0.08	0.40	
Spatial Peak SAR <sup>5</sup> (Hands / Feet / Ankle / Wrist )	4.00	20.00	

### Notes:

- 1. **General Population / Uncontrolled Environments** are defined as locations where there is the exposure of individuals who have no knowledge or control of their exposure.
- 2. **Occupational / Controlled Environments** are defined as locations where there is exposure that may be incurred by persons who are aware of the potential for exposure, (i.e. as a result of employment or occupation).
- 3. The Spatial Peak value of the SAR averaged over any 1 gram of tissue (defined as a tissue volume in the shape of a cube) and over the appropriate averaging time.
- 4. The Spatial Average value of the SAR averaged over the whole body.
- 5. The Spatial Peak value of the SAR averaged over any 10 grams of tissue (defined as a tissue volume in the shape of a cube) and over the appropriate averaging time.

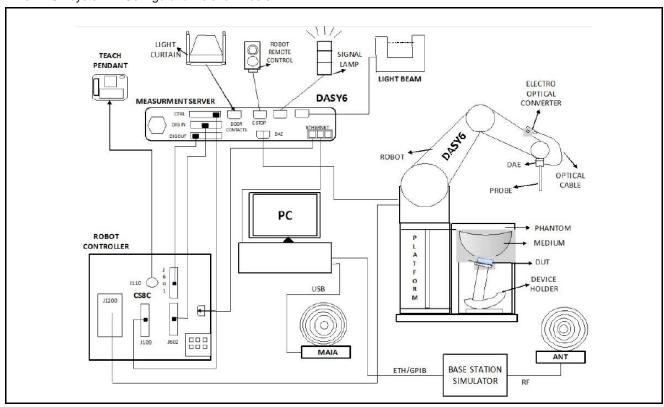
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## 5. System Describtion

### 5.1 SAR Measurement System

The DASY system in Configuration is shown below:



The system for performing compliance tests consists of the following items:

- 1. A standard high precision 6-axis robot (Stäubli TX family) with controller, teach pendant and software. An arm extension for accommodating the data acquisition electronics (DAE).
- 2. An isotropic field probe optimized and calibrated for the targeted measurements.
- 3. A data acquisition electronics (DAE) which performs the signal amplification, signal multiplexing, AD-conversion, offset measurements, mechanical surface detection, collision detection, etc. The unit is battery powered with standard or rechargeable batteries. The signal is optically transmitted to the EOC.
- 4. The Electro-optical converter (EOC) performs the conversion from optical to electrical signals for the digital communication to the DAE. To use optical surface detection, a special version of the EOC is required. The EOC signal is transmitted to the measurement server.
- 5. The function of the measurement server is to perform the time critical tasks such as signal filtering, control of the robot operation and fast movement interrupts.
- 6. The Light Beam used is for probe alignment. This improves the (absolute) accuracy of the probe positioning.
- 7. A computer running Win7/Win8/Win10 professional operating system and DASY software.
- 8. Remote controls with teach pendant and additional circuitry for robot safety such as warning lamps, etc.
- 9. The phantom, the device holder and other accessories according to the targeted measurement.
- 10. Tissue simulating liquid mixed according to the given recipes.
- 11. The validation dipole has been calibrated within and the system performance check has been successful.

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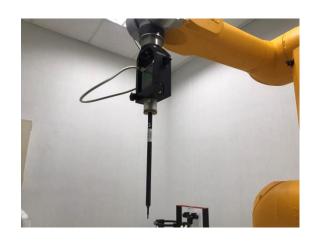


### <DASY E-Field Probe System>

The SAR measurements were conducted with the dosimetric probe (manufactured by SPEAG), designed in the classical triangular configuration and optimized for dosimetric evaluation. The probes is constructed using the thick film technique; with printed resistive lines on ceramic substrates. The probe is equipped with an optical multi-fiber line ending at the front of the probe tip. It is connected to the EOC box on the robot arm and provides an automatic detection of the phantom surface. Half of the fibers are connected to a pulsed infrared transmitter, the other half to a synchronized receiver. As the probe approaches the surface, the reflection from the surface produces a coupling from the transmitting to the receiving fibers. This reflection increases first during the approach, reaches maximum and then decreases. If the probe is flatly touching the surface, the coupling is zero. The distance of the coupling maximum to the surface is independent of the surface reflectivity and largely independent of the surface to probe angle. The DASY software reads the reflection during a software approach and looks for the maximum using a 2nd order fitting. The approach is stopped when reaching the maximum.

Construction	Symmetrical design with triangular core Built-in shielding against static charges PEEK enclosure material (resistant to organic solvents, e.g., DGBE)	
Frequency	4 MHz to 10 GHz Linearity: ± 0.2 dB (30 MHz to 10 GHz)	
Directivity  ±0.1 dB in TSL (rotation around probe axis) ±0.3 dB in TSL (rotation normal to probe axis)		
Dimensions	Overall length: 337 mm (Tip: 20 mm) Tip diameter: 2.5 mm (Body: 12 mm) Typical distance from probe tip to dipole centers: 1 mm	
Calibration	ISO/IEC 17025 calibration service available	





EX3DV4 E-Field Probe Probe setup on robot

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### <Data Acquisition Electronic (DAE) System>

Model	DAE4	
Construction	Signal amplifier, multiplexer, A/D converter and control logic. Serial optical link for communication with DASY embedded system (fully remote controlled). Two step probe touch detector for mechanical surface detection and emergency robot stop.	
Measurement Range	-100 to +300 mV (16 bit resolution and two range settings: 4 mV, 400 mV)	F Ni BBB
Input Offset Voltage	< 5 μV (with auto zero)	
Input Bias Current	< 50 fA	
Dimensions	60 x 60 x 68 mm	

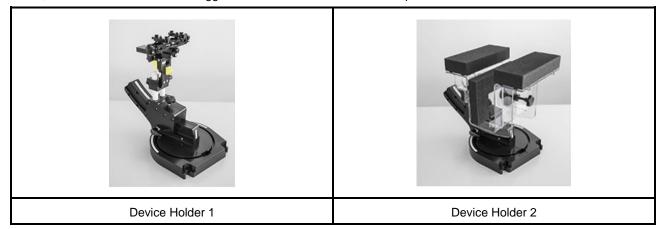
#### <Robot>

T		
Positioner	Stäubli Unimation Corp.	
Robot Model	TX90XL	
Number of Axes	6	
Nominal Load	5 kg	
Reach	1450 mm	-
Repeatability	<u>+</u> 0.035 mm	



### <Device Holder>

The DASY device holder is constructed of low-loss POM material having the following dielectric parameters: relative permittivity  $\varepsilon$ =3 and loss tangent  $\delta$ =0.02. The amount of dielectric material has been reduced in the closest vicinity of the device, since measurements have suggested that the influence of the clamp on the test results could thus be lowered.



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#### <Oval Flat Phantom - ELI>

The shell corresponds to the specifications of the Specific Anthropomorphic Mannequin (Oval Flat) phantom defined in IEEE 1528, IEC 62209-2 and IEC/IEEE 62209-1528. It enables the dosimetric evaluation of wireless portable device usage as well as body mounted usage at the flat phantom region. A cover prevents evaporation of the liquid. Reference markings on the phantom allow the complete setup of all predefined phantom positions and measurement grids by manually teaching three points with the robot.

Shell Thickness	2 ±0.2 mm	17
Filling Volume	Approx. 30 liters	•
Dimensions	190×600×400 mm (H × L × W)	• p3



### <SAM Phantom>

The shell corresponds to the specifications of the Specific Anthropomorphic Mannequin (SAM) phantom defined in IEEE 1528, IEC 62209-1 and IEC/IEEE 62209-1528. It enables the dosimetric evaluation of left and right hand phone usage as well as body-mounted usage at the flat phantom region. A cover prevents evaporation of the liquid. Reference markings on the phantom allow the complete setup of all predefined phantom positions and measurement grids by teaching three points with the robot.

Shell Thickness	2 ±0.2 mm	© \$p1
Filling Volume	Approx. 25 liters	
Dimensions	Length: 1000 mm Width: 500 mm Height: adjustable feet	εα

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## 5.2 Tissue Simulating Liquids (TSL)

### <Tissue Dielectric Parameters in IEEE 1528-2013 and IEC/IEEE 62209-1528>

The following table incorporates the tissue dielectric parameters of head recommended by IEEE 1528-2013 and IEC/IEEE 62209-1528. These head parameters are derived from planar layer models simulating the highest expected SAR for the dielectric properties and tissue thickness variations in human head. Other head and body tissue parameters that have not been specified are derived from the tissue dielectric parameters which computed by the 4-Cole-Cole equation according to the above-mentioned standards.

Table 2 Dielectric properties of the tissue-equivalent liquid material

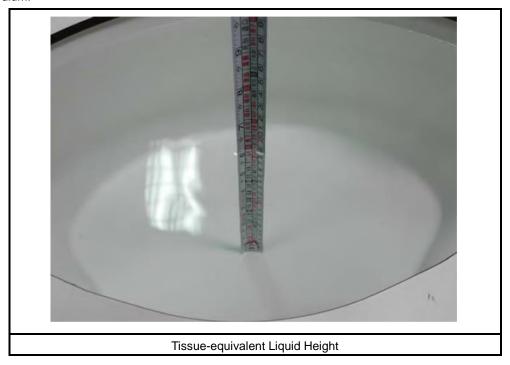
Frequency (MHz)	Relative Permittivity (ε <sub>r</sub> )	Conductivity (σ)
30	55.0	0.75
150	52.3	0.76
300	45.3	0.87
450	43.5	0.87
750	41.9	0.89
835	41.5	0.90
900	41.5	0.97
1450	40.5	1.20
1800	40.0	1.40
1900	40.0	1.40
1950	40.0	1.40
2000	40.0	1.40
2100	39.8	1.49
2450	39.2	1.80
2600	39.0	1.96
3000	38.5	2.40
3500	37.9	2.91
4000	37.4	3.43
4500	36.8	3.94
5000	36.2	4.45
5200	36.0	4.66
5400	35.8	4.86
5600	35.5	5.07
5800	35.3	5.27
6000	35.1	5.48
6500	34.5	6.07
7000	33.9	6.65
7500	33.3	7.24
8000	32.7	7.84
8500	32.1	8.46
9000	31.6	9.08
9500	31.0	9.71
10000	30.4	10.4

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### <Liquid Depth>

The depth of tissue-equivalent liquid in a phantom must be  $\geq$  15.0 cm to ensure that the probe is immersed sufficiently in the tissue medium.



### <Test Site Environment>

Item	Requirement	Actual
Temperature (°C)	18 - 25	21 - 23

### <Liquid Check>

- 1. The dielectric parameters of the liquids were verified prior to the SAR evaluation using a DAKS 3.5 Probe Kit.
- 2. The SAR testing with IEC tissue parameters as an alternative option to Head and body parameters. The head TSL were applied to body SAR tests with restrictions below:

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Tissue Temp (°C)	Head / Body	Frequency	Cond. σ	Perm. εr	target Cond. σ	target Perm. εr	σ (Delta)(%)	εr (Delta)(%)	Limit (%)	Date
22.4	Head	5180 MHz	4.63	36.61	4.64	36.02	-0.17	1.63	±5	Dec. 08, 2022
22.4	Head	5190 MHz	4.64	36.59	4.65	36.01	-0.21	1.61	±5	Dec. 08, 2022
22.4	Head	5200 MHz	4.65	36.57	4.66	36.00	-0.25	1.59	±5	Dec. 08, 2022
22.4	Head	5220 MHz	4.67	36.53	4.68	35.98	-0.31	1.53	±5	Dec. 08, 2022
22.4	Head	5230 MHz	4.68	36.51	4.69	35.97	-0.31	1.49	±5	Dec. 08, 2022
22.4	Head	5240 MHz	4.69	36.48	4.70	35.96	-0.25	1.44	±5	Dec. 08, 2022
22.4	Head	5250 MHz	4.70	36.46	4.71	35.95	-0.20	1.41	±5	Dec. 08, 2022
22.4	Head	5260 MHz	4.71	36.44	4.72	35.94	-0.15	1.39	±5	Dec. 08, 2022
22.4	Head	5270 MHz	4.73	36.42	4.73	35.93	-0.11	1.38	±5	Dec. 08, 2022
22.4	Head	5280 MHz	4.74	36.41	4.74	35.92	-0.11	1.37	±5	Dec. 08, 2022
22.4	Head	5290 MHz	4.74	36.40	4.75	35.91	-0.14	1.36	±5	Dec. 08, 2022
22.4	Head	5300 MHz	4.75	36.38	4.76	35.90	-0.19	1.33	±5	Dec. 08, 2022
22.4	Head	5310 MHz	4.76	36.36	4.77	35.89	-0.24	1.30	±5	Dec. 08, 2022
22.4	Head	5320 MHz	4.77	36.33	4.78	35.88	-0.27	1.26	±5	Dec. 08, 2022
22.4	Head	5745 MHz	5.20	35.51	5.22	35.36	-0.34	0.42	±5	Dec. 08, 2022
22.4	Head	5755 MHz	5.21	35.48	5.23	35.35	-0.37	0.38	±5	Dec. 08, 2022
22.4	Head	5775 MHz	5.23	35.44	5.25	35.33	-0.34	0.32	±5	Dec. 08, 2022
22.4	Head	5785 MHz	5.24	35.43	5.26	35.32	-0.31	0.31	±5	Dec. 08, 2022
22.4	Head	5795 MHz	5.25	35.41	5.27	35.31	-0.29	0.30	±5	Dec. 08, 2022
22.4	Head	5825 MHz	5.28	35.38	5.30	35.28	-0.36	0.28	±5	Dec. 08, 2022
22.6	Head	2412 MHz	1.78	39.58	1.77	39.27	0.78	0.80	±5	Dec. 10, 2022
22.6	Head	2422 MHz	1.79	39.54	1.78	39.25	0.90	0.73	±5	Dec. 10, 2022
22.6	Head	2437 MHz	1.81	39.50	1.79	39.22	1.08	0.70	±5	Dec. 10, 2022
22.6	Head	2452 MHz	1.82	39.45	1.80	39.20	1.20	0.63	±5	Dec. 10, 2022
22.6	Head	2462 MHz	1.84	39.42	1.81	39.18	1.22	0.61	±5	Dec. 10, 2022
22.6	Head	2467 MHz	1.84	39.41	1.82	39.18	1.26	0.58	±5	Dec. 10, 2022
22.6	Head	2472 MHz	1.85	39.39	1.82	39.17	1.31	0.56	±5	Dec. 10, 2022

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# 6. System Verification

## 6.1 SAR System Verification

## <Symmetric Dipoles for SAR System Verification>

Construction	Symmetrical dipole with $\lambda/4$ balun enables measurement of feed point impedance with NWA matched for use near flat phantoms filled with head simulating solutions Includes distance holder and tripod adaptor Calibration Calibrated SAR value for specified position and input power at the flat phantom in head simulating solutions.									
Return Loss	> 20 dB at specified verification position.	OdB at specified verification position.								
Options	Dipoles for other frequencies or solutions and other calibration conditions are available upon request.									
Spacer Signal Generator	Tuning element  3D Probe positioner  Flat Phantom  Dir.Coupler  Cable X a Att1  PM1  Att2									

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## **6.1.1 SAR Verification Summary**

Prior to the assessment, the validation data compared to the original value provided by SPEAG should be within its specifications of ±10%. The measured SAR will be normalized to 1 W input power. The result indicates the system check can meet the variation criterion and plots can be referred to Appendix B of this report.

Mixture Type	Frequency (MHz)	Power	Probe Model / Serial No.	Dipole Model / Serial No.	SAR <sub>1 g</sub> (W/kg)	1 W Normalize SAR <sub>1 g</sub> (W/kg)	1 W Target SAR1 g (W/kg)	SAR <sub>10 g</sub> (W/kg)	1 W Normalize SAR <sub>10 g</sub> (W/kg)	1 W Target SAR <sub>10 g</sub> (W/kg)	Deviation 1 g (%)	Deviation 10 g (%)	Date
Head	2450	17 dBm	EX3DV4 – SN3977	D2450V2 – SN712	2.65	52.87	52.80	1.25	24.94	24.40	0.1%	2.2%	Dec. 10, 2022
Head	5250	17 dBm	EX3DV4 – SN7647	D5250V2 – SN1021	3.85	76.82	78.10	1.11	22.15	22.10	-1.6%	0.2%	Dec. 08, 2022
Head	5750	17 dBm	EX3DV4 – SN7647	D5750V2 – SN1021	3.75	74.82	77.30	1.06	21.15	21.50	-3.2%	-1.6%	Dec. 08, 2022

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# 7. Test Equipment List

## 7.1 SAR Test Equipment List

		SAR02-BD to	est site				
				Calibra	tion	Calibration	Cal.
Manufacturer	Name of Equipment	Type/Model	Serial Number	Cal. Date	Cal.Period	Authority	Method
SPEAG	2450 MHz System Validation Kit	D2450V2	712	Jun. 30, 2022	1 year	CTTL	С
SPEAG	5 GHz System Validation Kit	D5GHzV2	1021	Jun. 30, 2022	1 year	CTTL	С
SPEAG	Dosimetric E-Field Probe	EX3DV4	3977	Jul. 26, 2022	1 year	SPEAG	С
SPEAG	Dosimetric E-Field Probe	EX3DV4	7647	Apr. 27, 2022	1 year	SPEAG	С
SPEAG	Data Acquisition Electronics	DAE4	779	Jul. 19, 2022	1 year	SPEAG	С
SPEAG	Data Acquisition Electronics	DAE4	1253	Dec. 30, 2021	1 year	SPEAG	С
SPEAG	Measurement Server	SE UPS 031 AA	1025	NCF	?	N/A	N/A
SPEAG	Measurement Server	SE UMS 011 BB	1241	NCF	₹	N/A	N/A
SPEAG	Device Holder	N/A	N/A	NCR		N/A	N/A
SPEAG	Phantom	ELI V5.0	1133	NCR		N/A	N/A
SPEAG	Phantom	ELI V4.0	1036	NCF	₹	N/A	N/A
SPEAG	Robot	Staubli TX90XL	F07/564ZA1/A/01	NCR		N/A	N/A
SPEAG	Robot	Staubli TX90XL	F11/5G9EA1/A/01	NCR		N/A	N/A
00540	0.44	DASY52	N1/0	NCR		N1/A	N1/A
SPEAG	Software	V52.10.4.1535	N/A			N/A	N/A
CDEAC	Cathurana	SEMCAD X	NI/A	NO	,	NI/A	NI/A
SPEAG	Software	V14.6.14(7501)	N/A	NCF	<	N/A	N/A
SPEAG	Network Analyzer	DAKS_VNA R140	0010318	May. 23, 2022	1 year	SPEAG	С
SPEAG	Dielectric Probe Kit	DAKS-3.5	1101	May. 23, 2022	1 year	SPEAG	С
HILA	Digital Thermometer	TM-906A	1500033	Nov. 03, 2022	1 year	ETC	С
Agilent	Power Sensor	8481H	3318A20779	May. 26, 2022	1 year	ETC	С
Agilent	Power Meter	EDM Series E4418B	GB40206143	May. 26, 2022	1 year	ETC	С
Agilent	Signal Generator	E8257D	MY44320425	Feb. 15, 2022	1 year	ITRI	С
Keysight	Spectrum Analyzer	N9010B	MY59071418	Mar. 16, 2022	1 year	ETC	С
Mini-Circuits	Dual Directional Coupler	ZCDC20-5R263-S+	E69806	NCF	2	N/A	N/A
Mini-Circuits	Power Amplifier	EMC014225P	980292	NCF	₹	N/A	N/A
Mini-Circuits	Power Amplifier	EMC2830P	980293	NCF	2	N/A	N/A
EMCI	Power Amplifier	EMC0618-P	980833	NCR		N/A	N/A
EMCI	Power Amplifier	EMC2830-P	980880	NCF	₹	N/A	N/A
Attenuator	INMET	18AH-03	S180301	NCF	₹	N/A	N/A
Attenuator	INMET	18AH-10	S181001	NCF	₹	N/A	N/A
Attenuator	INMET	18AH-20	S182001	NCF	?	N/A	N/A

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Testing Engineer: Boyu Chen

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### 8. Measurement Procedure

### 8.1 SAR Measurement Procedure

The measurement procedures are as follows:

- 1. The DUT is installed engineering testing software that provides continuous transmitting signal.
- 2. Measure output power through RF cable and power meter
- 3. Set scan area, grid size and other setting on the DASY software
- 4. Find out the largest SAR result on these testing positions of each band
- 5. Measure SAR results for other channels in worst SAR testing position if the SAR of highest power channel is larger than 0.8 W/kg

According to the test standard, the recommended procedure for assessing the peak spatial-average SAR value consists of the following steps:

- 1. Power reference measurement
- 2. Area scan
- 3. Zoom scan
- 4. Power drift measurement

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#### 8.1.1 Area & Zoom Scan Procedures

First Area Scan is used to locate the approximate location(s) of the local peak SAR value(s). The measurement grid within an Area Scan is defined by the grid extent, grid step size and grid offset. Next, in order to determine the EM field distribution in a three-dimensional spatial extension, Zoom Scan is required. The Zoom Scan measures points and step size follow as below. The Zoom Scan is performed around the highest E-field value to determine the averaged SAR-distribution.

The measure settings are referred to KDB 865664 D01v01r04:

Maximum distance from closest measurement point (geometric center of probe sensors) to phantom surface  Maximum probe angle from probe axis to phantom surface normal at the measurement location  Maximum area scan spatial resolution: Δx <sub>Area</sub> , Δy <sub>Area</sub> Maximum zoom scan spatial resolution: Δx <sub>Area</sub> , Δy <sub>Area</sub> Maximum zoom scan spatial resolution: Δx <sub>Area</sub> , Δy <sub>Area</sub> Maximum zoom scan spatial resolution: Δx <sub>Area</sub> , Δy <sub>Area</sub> Maximum zoom scan spatial resolution: Δx <sub>Area</sub> , Δy <sub>Area</sub> Maximum zoom scan spatial resolution: Δx <sub>Area</sub> , Δy <sub>Area</sub> Maximum zoom scan spatial resolution: Δx <sub>Area</sub> , Δy <sub>Area</sub> Maximum zoom scan spatial resolution: Δx <sub>Area</sub> , Δy <sub>Area</sub> Maximum zoom scan spatial resolution: Δx <sub>Area</sub> , Δy <sub>Area</sub> Maximum zoom scan spatial resolution: Δx <sub>Area</sub> , Δy <sub>Area</sub> Maximum zoom scan spatial resolution: Δx <sub>Area</sub> , Δy <sub>Area</sub> Maximum zoom scan spatial resolution: Δx <sub>Area</sub> , Δy <sub>Area</sub> Maximum zoom scan spatial resolution: Δx <sub>Area</sub> , Δy <sub>Area</sub> Maximum zoom scan spatial resolution: Δx <sub>Area</sub> , Δy <sub>Area</sub> Maximum zoom scan spatial resolution: Δx <sub>Area</sub> , Δy <sub>Area</sub> Maximum zoom scan spatial resolution: Δx <sub>Area</sub> , Δy <sub>Area</sub>	The measure settings are referred	וט אטם סנ	00004 DUTVUTTU4 .		Ī		
center of probe sensors) to phantom surface       5 mm ± 1 mm       mm         Maximum probe angle from probe axis to phantom surface normal at the measurement location $30^{\circ} \pm 1^{\circ}$ $20^{\circ} \pm 1^{\circ}$ $20^{\circ} \pm 1^{\circ}$ ≤ 2 GHz: ≤ 15 mm $3 - 4$ GHz: ≤ 12 mm $4 - 6$ GHz: ≤ 12 mm       When the x or y dimension of the test device, in the measurement plane orientation, is smaller than the above, the measurement resolution must be ≤ the corresponding x or y dimension of the test device with at least one measurement point on the test device.         Maximum zoom scan spatial resolution: $\Delta x_{Area}$ , $\Delta y_{Area}$ $\Delta x_{Area}$ , $\Delta x_{Area}$				≤ 3 GHz	> 3 GHz		
Center of probe sensors) to phantom surface       mm         Maximum probe angle from probe axis to phantom surface normal at the measurement location       30° ± 1°       20° ± 1°         A GHz: ≤ 12 mm       3 - 4 GHz: ≤ 12 mm       4 - 6 GHz: ≤ 10 mm         When the x or y dimension of the test device, in the measurement plane orientation, is smaller than the above, the measurement resolution must be ≤ the corresponding x or y dimension of the test device with at least one measurement point on the test device.         Maximum zoom scan spatial resolution: ΔxArea, ΔyArea       ≤ 2 GHz: ≤ 8 mm 2 - 3 GHz: ≤ 5 mm*       3 - 4 GHz: ≤ 5 mm*         A - 6 GHz: ≤ 4 mm       2 - 3 GHz: ≤ 5 mm*       3 - 4 GHz: ≤ 4 mm         4 - 5 GHz: ≤ 2 mm       3 - 4 GHz: ≤ 2 mm         Maximum zoom scan spatial resolution, normal to phantom surface grid       Δ Zzoom(1): between 1st two points closest to phantom surface       ≤ 4 mm       3 - 4 GHz: ≤ 3 mm         4 - 5 GHz: ≤ 2 mm       Δ Zzoom(n-1): between subsequent points       ≤ 1.5·Δzzoom(n-1) mm         Minimum zoom scan volume       x, y, z       ≥ 30 mm       3 - 4 GHz: ≥ 28 mm         Minimum zoom scan volume       x, y, z       ≥ 30 mm       3 - 4 GHz: ≥ 25 mm	Maximum distance from closest	measureme	ent point (geometric	5 mm + 1 mm	$\frac{1}{2} \cdot \delta \cdot \ln(2) \text{ mm } \pm 0.5$		
Maximum zoom scan spatial resolution: $\Delta x_{Area}$ , $\Delta y_{Area}$ Maximum zoom scan spatial resolution: $\Delta x_{Area}$ , $\Delta y_{Area}$ Maximum zoom scan spatial resolution: $\Delta x_{Area}$ , $\Delta y_{Area}$ Maximum zoom scan spatial resolution: $\Delta x_{Area}$ , $\Delta y_{Area}$ Maximum zoom scan spatial resolution: $\Delta x_{Area}$ , $\Delta y_{Area}$ Maximum zoom scan spatial resolution: $\Delta x_{Area}$ , $\Delta y_{Area}$ Maximum zoom scan spatial resolution: $\Delta x_{Area}$ , $\Delta y_{Area}$ $ \begin{array}{c}                                     $	center of probe sensors) to phan	tom surfac	е	3 111111 ± 1 1111111	mm		
Maximum area scan spatial resolution: $\Delta x_{Area}$ , $\Delta y_{Area}$		e axis to pl	nantom surface normal	30° ± 1°	20° ± 1°		
Maximum area scan spatial resolution: $\Delta x_{Area}$ , $\Delta y_{Area}$ When the x or y dimension of the test device, in the measurement plane orientation, is smaller than the above, the measurement resolution must be $\leq$ the corresponding x or y dimension of the test device with at least one measurement point on the test device.  Maximum zoom scan spatial resolution: $\Delta x_{Area}$ , $\Delta y_{Area}$ $ \begin{array}{c} \leq 2 \text{ GHz} \leq 8 \text{ mm} \\ 2-3 \text{ GHz} \leq 5 \text{ mm}^* \\ \end{cases} $ $ \begin{array}{c} 3-4 \text{ GHz} \leq 4 \text{ mm} \\ 4-6 \text{ GHz} \leq 4 \text{ mm} \\ \end{cases} $ Maximum zoom scan spatial resolution: $\Delta x_{Area}$ , $\Delta y_{Area}$ $ \begin{array}{c} \Delta z_{Zoom}(n) \\ \text{between 1st two} \\ \text{points closest to} \\ \text{phantom surface} \end{array} $ $ \begin{array}{c} \Delta z_{Zoom}(n>1) \\ \text{between subsequent} \\ \text{points} \end{array} $ $ \begin{array}{c} 3-4 \text{ GHz} \leq 3 \text{ mm} \\ 4-5 \text{ GHz} \leq 2.5 \text{ mm} \\ 5-6 \text{ GHz} \leq 2.5 \text{ mm} \end{array} $ $ \begin{array}{c} 3-4 \text{ GHz} \leq 3 \text{ mm} \\ 4-5 \text{ GHz} \leq 2.5 \text{ mm} \end{array} $ $ \begin{array}{c} 4-5 \text{ GHz} \leq 2.5 \text{ mm} \end{array} $ $ \begin{array}{c} 5-6 \text{ GHz} \leq 2.5 \text{ mm} \end{array} $ $ \begin{array}{c} 3-4 \text{ GHz} \leq 3 \text{ mm} \end{array} $ $ \begin{array}{c} 4-5 \text{ GHz} \leq 2.5 \text{ mm} \end{array} $ $ \begin{array}{c} 5-6 \text{ GHz} \leq 2.5 \text{ mm} \end{array} $ $ \begin{array}{c} 3-4 \text{ GHz} \leq 2.5 \text{ mm} \end{array} $ $ \begin{array}{c} 3-4 \text{ GHz} \leq 2.5 \text{ mm} \end{array} $ $ \begin{array}{c} 3-4 \text{ GHz} \leq 2.5 \text{ mm} \end{array} $ $ \begin{array}{c} 3-4 \text{ GHz} \leq 2.5 \text{ mm} \end{array} $				≤ 2 GHz: ≤ 15 mm	3 – 4 GHz: ≤ 12 mm		
Maximum area scan spatial resolution: $\Delta x_{Area}$ , $\Delta y_{Area}$ the measurement plane orientation, is smaller than the above, the measurement resolution must be ≤ the corresponding x or y dimension of the test device with at least one measurement point on the test device.Maximum zoom scan spatial resolution: $\Delta x_{Area}$ , $\Delta y_{Area}$ $\leq 2  \text{GHz}$ : ≤ 8 mm $2 - 3  \text{GHz}$ : ≤ 5 mm* $3 - 4  \text{GHz}$ : ≤ 5 mm* $3 - 4  \text{GHz}$ : ≤ 4 mm*Maximum zoom scan spatial resolution, normal to phantom surface grid $\Delta z_{Zoom}(n)$ $\leq 5  \text{mm}$ $3 - 4  \text{GHz}$ : ≤ 3 mm $5 - 6  \text{GHz}$ : ≤ 2 mmMaximum zoom scan spatial resolution, normal to phantom surface grid $\Delta z_{Zoom}(n)$ : between 1st two points closest to phantom surface $3 - 4  \text{GHz}$ : ≤ 2.5 mm $4 - 5  \text{GHz}$ : ≤ 2.5 mm $4 - 5  \text{GHz}$ : ≤ 2.5 mm $\Delta z_{Zoom}(n>1)$ : between subsequent points $\leq 1.5 \cdot \Delta z_{Zoom}(n-1)  \text{mm}$ Minimum zoom scan volume $x, y, z$ $\geq 30  \text{mm}$ $3 - 4  \text{GHz}$ : ≥ 28 mm $\Delta z_{Zoom}(n>1)$ : between subsequent points $\Delta z_{Zoom}(n-1)  \text{mm}$				2 – 3 GHz: ≤ 12 mm	4 – 6 GHz: ≤ 10 mm		
Maximum area scan spatial resolution: $\Delta x_{Area}$ , $\Delta y_{Area}$ the above, the measurement resolution must be $\leq$ the corresponding x or y dimension of the test device with at least one measurement point on the test device.  Maximum zoom scan spatial resolution: $\Delta x_{Area}$ , $\Delta y_{Area}$				When the x or y dimension of	of the test device, in		
the above, the measurement resolution must be $\leq$ the corresponding x or y dimension of the test device with at least one measurement point on the test device.  Maximum zoom scan spatial resolution: $\Delta x_{Area}$ , $\Delta y_{Area}$ $ \begin{array}{c}                                     $		A		the measurement plane orie	ntation, is smaller than		
	Maximum area scan spatial reso	IUtion: ΔX <sub>Ar</sub>	ea, <b>Δy</b> Area	the above, the measurement	t resolution must be ≤		
				the corresponding x or y dim	ension of the test		
Maximum zoom scan spatial resolution: $\Delta x_{Area}$ , $\Delta y_{Area}$ ≤ 2 GHz: ≤ 8 mm 2 − 3 GHz: ≤ 5 mm*3 − 4 GHz: ≤ 5 mm* 4 − 6 GHz: ≤ 4 mm*Maximum zoom scan spatial resolution, normal to phantom surface				device with at least one mea	surement point on the		
Maximum zoom scan spatial resolution: $\Delta x_{Area}$ , $\Delta y_{Area}$ $2-3$ GHz: $\leq 5$ mm* $4-6$ GHz: $\leq 4$ mm* $4-6$ GHz: $\leq 4$ mm $4-5$ GHz: $\leq 3$ mm $5-6$ GHz: $\leq 2$ mm Maximum zoom scan spatial resolution, normal to phantom surface $\frac{\Delta z_{Zoom}(1):}{Detween 1st two}$ $\frac{3-4}{5-6}$ GHz: $\frac{2}{5-6}$ mm				test device.			
			≤ 2 GHz: ≤ 8 mm	3 – 4 GHz: ≤ 5 mm*			
Maximum zoom scan spatial resolution, normal to phantom surface	Maximum zoom scan spatial res	olution: Δx	Area, <b>Δy</b> Area	2 – 3 GHz: ≤ 5 mm*	4 – 6 GHz: ≤ 4 mm*		
Maximum zoom scan spatial resolution, normal to phantom surface		uniform g	grid: Δz <sub>zoom</sub> (n)	≤ 5 mm	4 – 5 GHz: ≤ 3 mm		
resolution, normal to phantom surface					5 - 6 GHZ: 5 2 MM		
grid $\Delta z_{Zoom}$ (n>1): between subsequent points $≤ 1.5 \cdot \Delta z_{Zoom}$ (n-1) mm points $3-4$ GHz: ≥ 28 mm Minimum zoom scan volume $x, y, z$ ≥ 30 mm $4-5$ GHz: ≥ 25 mm	resolution, normal to phantom	Graded	between 1st two points closest to	≤ 4 mm	4 – 5 GHz: ≤ 2.5 mm		
between subsequent points $ \leq 1.5 \cdot \Delta z_{Zoom} (n-1) \text{ mm} $ Minimum zoom scan volume $ x, y, z                                $		grid	'		<u> </u>		
Minimum zoom scan volume $x, y, z \ge 30 \text{ mm}$ $4-5 \text{ GHz} \ge 25 \text{ mm}$			between subsequent	≤ 1.5·∆z <sub>zoom</sub> (r	1-1) mm		
,,,,					3 – 4 GHz: ≥ 28 mm		
5 – 6 GHz: ≥ 22 mm	Minimum zoom scan volume		x, y, z	≥ 30 mm	4 – 5 GHz: ≥ 25 mm		
					5 – 6 GHz: ≥ 22 mm		

Note:  $\delta$  is the penetration depth of a plane-wave at normal incidence to the tissue medium; see IEEE Std 1528-2013 for details.

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<sup>\*</sup> When zoom scan is required and the reported SAR from the area scan based 1-g SAR estimation procedures of KDB Publication 447498 is  $\leq$  1.4 W/kg,  $\leq$  8 mm,  $\leq$  7 mm and  $\leq$  5 mm zoom scan resolution may be applied, respectively, for 2 GHz to 3 GHz, 3 GHz to 4 GHz and 4 GHz to 6 GHz.



#### 8.1.2 Volume Scan Procedures

The volume scan is used for assess overlapping SAR distributions for antennas transmitting in different frequency bands. It is equivalent to an oversized zoom scan used in standalone measurements. The measurement volume will be used to enclose all the simultaneous transmitting antennas. For antennas transmitting simultaneously in different frequency bands, the volume scan is measured separately in each frequency band. In order to sum correctly to compute the 1 g aggregate SAR, the DUT remain in the same test position for all measurements and all volume scan use the same spatial resolution and grid spacing. When all volume scan were completed, the software, SEMCAD postprocessor can combine and subsequently superpose these measurement data to calculating the multiband SAR.

### 8.1.3 Power Drift Monitoring

All SAR testing is under the DUT install full charged battery and transmit maximum output power. In DASY measurement software, the power reference measurement and power drift measurement procedures are used for monitoring the power drift of DUT during SAR test. Both these procedures measure the field at a specified reference position before and after the SAR testing. The software will calculate the field difference in dB. If the power drifts more than 5 %, the SAR will be retested.

### 8.1.4 Spatial Peak SAR Evaluation

The procedure for spatial peak SAR evaluation has been implemented according to the test standard. It can be conducted for 1 g and 10 g, as well as for user-specific masses. The DASY software includes all numerical procedures necessary to evaluate the spatial peak SAR value.

The base for the evaluation is a "cube" measurement. The measured volume must include the 1 g and 10 g cubes with the highest averaged SAR values. For that purpose, the center of the measured volume is aligned to the interpolated peak SAR value of a previously performed area scan.

The entire evaluation of the spatial peak values is performed within the post-processing engine (SEMCAD). The system always gives the maximum values for the 1 g and 10 g cubes. The algorithm to find the cube with highest averaged SAR is divided into the following stages:

- 1. Extraction of the measured data (grid and values) from the Zoom Scan
- 2. Calculation of the SAR value at every measurement point based on all stored data (A/D values and measurement parameters)
- 3. Generation of a high-resolution mesh within the measured volume
- 4. Interpolation of all measured values form the measurement grid to the high-resolution grid
- 5. Extrapolation of the entire 3-D field distribution to the phantom surface over the distance from sensor to surface
- 6. Calculation of the averaged SAR within masses of 1 g and 10 g

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# 9. Measurement Uncertainty

## 9.1 SAR Measurement Uncertainty

	Mea	surement U	Incertainty (0	).3-6 GHz	)			
Uncertainty Component	Tol.	Prob. Dist.	Div.	Ci - 1g	Ci - 10g	ui - 1g (%)	ui - 10g (%)	vi
Measurement System								
Probe calibration	12.0	N	2	1	1	6.0	6.0	œ
Probe Calibration Drift	1.7	R	1.732	1	1	1.0	1.0	8
Other Probe+Electronic	0.7	N	1	1	1	0.7	0.7	× ×
Probe Linearity	4.7	R	1.732	1	1	2.7	2.7	∞
Broadband Signal	3.0	R	1.732	1	1	1.7	1.7	∞
Probe Isotropy	7.6	R	1.732	1	1	4.4	4.4	∞
RF Ambient	1.8	N	1	1	1	1.8	1.8	×
Probe Positioning	0.006 mm	N	1	0.14	0.14	0.1	0.1	œ
Data Processing	1.2	N	1	1	1	1.2	1.2	œ
Phantom and Device Errors								
Conductivity (meas.)DAK	2.5	N	1	0.78	0.71	2.0	1.8	œ
Conductivity (temp.)	3.3	R	1.732	0.78	0.71	1.5	1.4	œ
Phantom Shell Permittivity	14	R	1.732	0	0	0.0	0.0	œ
Distance DUT - TSL	2	N	1	2	2	4.0	4.0	œ
Device Positioning	1	N	1	1	1	1.0	1.0	× ×
Device Holder	3.6	N	1	1	1	3.6	3.6	×
DUT Modulation	2.4	R	1.732	1	1	1.4	1.4	∞
Time-average SAR	1.7	R	1.732	1	1	1.0	1.0	∞
DUT Drift	2.5	N	1	1	1	2.5	2.5	∞
Correction to the SAR Results								
Deviation to Target	1.9	N	1	1	0.84	1.9	1.6	œ
SAR scaling	0.0	R	1.732	1	1	0.0	0.0	∞
Combined Standard Uncertainty	у				RSS	11.0	10.9	
Expanded Uncertainty (95% cor	nfidence ir	iterval)			k =2	21.9	21.7	

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	Mea	asuremen	t Uncertai	nty (3-6 GH	z)			
Uncertainty Component	Tol.	Prob. Dist.	Div.	Ci - 1g	Ci - 10g	ui - 1g (%)	ui - 10g (%)	vi
Measurement System								
Probe Calibration	13.1	N	2	1	1	6.55	6.55	∞
Probe Calibration Drift	1.7	R	1.732	1	1	1.0	1.0	8
Other Probe+Electronic	1.2	N	1	1	1	1.2	1.2	8
Probe Linearity	4.7	R	1.732	1	1	2.7	2.7	8
Broadband Signal	2.6	R	1.732	1	1	1.5	1.5	8
Probe Isotropy	7.6	R	1.732	1	1	4.4	4.4	8
RF Ambient	1.8	N	1	1	1	1.8	1.8	8
Probe Positioning	0.005 mm	N	1	0.29	0.29	0.15	0.15	8
Data Processing	2.3	N	1	1	1	2.3	2.3	8
Phantom and Device Errors								
Conductivity (meas.)DAK	2.5	N	1	0.78	0.71	2.0	1.8	œ
Conductivity (temp.)	3.4	R	1.732	0.78	0.71	1.5	1.4	8
Phantom Shell Permittivity	14	R	1.732	0.25	0.25	2.0	2.0	∞
Distance DUT - TSL	2	N	1	2	2	4.0	4.0	∞
Device Positioning	1	N	1	1	1	1.0	1.0	∞
Device Holder	3.6	N	1	1	1	3.6	3.6	∞
DUT Modulation	2.4	R	1.732	1	1	1.4	1.4	8
Time-average SAR	1.7	R	1.732	1	1	1.0	1.0	8
DUT Drift	2.5	N	1	1	1	2.5	2.5	8
Correction to the SAR Results	T							
Deviation to Target	1.9	N	1	1	0.84	1.9	1.6	∞
SAR scaling	0.0	R	1.732	1	1	0.0	0.0	œ
Combined Standard Uncertainty	/				RSS	11.6	11.6	
Expanded Uncertainty (95% cor	nfidence ir	nterval)			k =2	23.2	23.0	

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	Mea	surement U	ncertainty	(6-10 GHz	)			
Uncertainty Component	Tol.	Prob. Dist.	Div.	Ci - 1g	Ci - 10g	ui - 1g (%)	ui - 10g (%)	vi
Measurement System								
Probe calibration	18.6	N	2	1	1	9.3	9.3	8
Probe Calibration Drift	1.7	R	1.732	1	1	1.0	1.0	8
Other Probe+Electronic	2.4	N	1	1	1	2.4	2.4	8
Probe Linearity	4.7	R	1.732	1	1	2.7	2.7	× ×
Broadband Signal	2.8	R	1.732	1	1	1.6	1.6	œ
Probe Isotropy	7.6	R	1.732	1	1	4.4	4.4	8
RF Ambient Condition	1.8	N	1	1	1	1.8	1.8	œ
Probe Positioning	0.005mm	N	1	0.50	0.50	0.25	0.25	œ
Data Processing	3.5	N	1	1	1	3.5	3.5	8
Phantom and Device Errors								
Conductivity (meas.)DAK	2.5	N	1	0.78	0.71	2.0	1.8	8
Conductivity (temp.)	2.4	R	1.732	0.78	0.71	1.1	1.0	œ
Phantom Shell Permittivity	14.0	R	1.732	0.5	0.5	4.0	4.0	8
Distance DUT - TSL	2	N	1	2	2	4.0	4.0	œ
Device Positioning	1	N	1	1	1	1.0	1.0	œ
Device Holder	3.6	N	1	1	1	3.6	3.6	œ
DUT Modulation	2.4	R	1.732	1	1	1.4	1.4	œ
Time-average SAR	1.7	R	1.732	1	1	1.0	1.0	× ×
DUT Drift	2.5	N	1	1	1	2.5	2.5	œ
Correction to the SAR Resul	ts							
Deviation to Target	1.9	N	1	1	0.84	1.9	1.6	œ
SAR scaling	0.0	R	1.732	1	1	0.0	0.0	∞
Combined Standard Uncerta	inty				RSS	14.2	14.1	
Expanded Uncertainty (95%	confidence in	iterval)			k =2	28.4	28.3	

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### 10. Measurement Evaluation

## 10.1 Positioning of the DUT in Relation to the Phantom

According to KDB 447498 D02:

Test all USB orientations with a device-to-phantom separation distance of 5 mm or less, according to KDB Publication 447498 D01 requirements. These test orientations are intended for the exposure conditions found in typical laptop/notebook/netbook or tablet computers with either horizontal or vertical USB connector configurations at various locations in the keyboard section of the computer. Current generation portable host computers should be used to establish the required SAR measurement separation distance. The same test separation distance must be used to test all frequency bands and modes in each USB orientation. The typical Horizontal-Up USB connection, found in the majority of host computers, must be tested using an appropriate host computer. A host computer with either Vertical-Front or Vertical-Back USB connection should be used to test one of the vertical USB orientations. If a suitable host computer is not available for testing the Horizontal-Down or the remaining Vertical USB orientation, a high quality USB cable, 12 inches or less, may be used for testing these other orientations. It must be documented that the USB cable does not influence the radiating characteristics and output power of the transmitter.

USB dongles have a rather small footprint; therefore, the SAR scan resolutions should be smaller than those typically used for testing devices with larger form factors, to maintain acceptable uncertainty for the interpolation and extrapolation algorithms used in the 1-g SAR analysis. In addition, when USB cables are used to connect a dongle to the host for SAR testing, the dongle should be supported in several cm of foamed polystyrene (e.g., Styrofoam) to minimize any field perturbation effects due to test device holder used to position the dongle for SAR testing. Dongles with certain spacers, contours or tapering added to the housing should generally be tested according to the 6 mm test separation requirement required for simple dongles, which is based on overall host platform, device and user operating configurations and exposure conditions of a peripheral device as compared to individual use conditions.

USB dongle transmitters must show compliance at a test separation distance of 5 mm. When the SAR is  $\geq$  1.2 W/kg, applications for equipment certification require a KDB inquiry for equipment approval.2 Preliminary data submitted through KDB inquiries showing compliance at test distances greater than 5 mm are usually inapplicable and insufficient for the FCC to determine if potential exposure concerns may be eliminated to enable the device to satisfy compliance. The information must clearly demonstrate that the likelihood of non-compliance is remote. When the SAR is  $\geq$  1.2 W/kg, especially for SAR > 1.5 W/kg, certain caution statements, labels and other means to ensure compliance may be required.

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### 10.2 SAR Testing with RF Transmitter

### 10.2.1 SAR Testing with WLAN

A Wi-Fi device must be configured to transmit continuously at the required data rate, channel bandwidth and signal modulation, using the highest transmission duty factor supported by the test mode tools for SAR measurement. The test frequencies established using test mode must correspond to the actualchannel frequencies.

For WLAN SAR testing, the DUT has installed WLAN engineering testing software which can provide continuous transmitting RF signal. And the RF signal utilized in SAR measurement has almost 100 % duty cycle and crest factor is 1.

### <KDB 248227 D01 General requirements>

SAR test reduction for 802.11 Wi-Fi transmission mode configurations are considered separately for DSSS and OFDM. An initial test position is determined to reduce the number of tests required for certain exposure configurations with multiple test positions. An initial test configuration is determined for each frequency band and aggregated band according to maximum output power, channel bandwidth, wireless mode configurations and other operating parameters to streamline the measurement requirements. For 2.4 GHz DSSS, either the initial test position or DSSS procedure is applied to reduce the number of SAR tests; these are mutually exclusive. For OFDM, an initial test position is only applicable to next to the ear, UMPC mini-tablet and hotspot mode configurations, which is tested using the initial test configuration to facilitate test reduction. For other exposure conditions with a fixed test position, SAR test reduction is determined using only the initial test configuration.

The multiple test positions require SAR measurements in head, hotspot mode or UMPC mini-tablet configurations may be reduced according to the highest reported SAR determined using the initial test position(s) by applying the DSSS or OFDM SAR measurement procedures in the required wireless mode test configuration(s). The initial test position(s) is measured using the highest measured maximum output power channel in the required wireless mode test configuration(s). When the reported SAR for the initial test position is:

- ≤ 0.4 W/kg, further SAR measurement is not required for the other test positions in that exposure configuration and wireless mode combination within the frequency band or aggregated band. DSSS and OFDM configurations are considered separately according to the required SAR procedures.
- > 0.4 W/kg, SAR is repeated using the same wireless mode test configuration tested in the initial test position to
  measure the subsequent next closet/smallest test separation distance and maximum coupling test position, on the
  highest maximum output power channel, until the reported SAR is ≤ 0.8 W/kg or all required test positions are tested.
   ※ For subsequent test positions with equivalent test separation distance or when exposure is dominated by coupling
  conditions, the position for maximum coupling condition should be tested.
  - X When it is unclear, all equivalent conditions must be tested.
- For all positions/configurations tested using the initial test position and subsequent test positions, when the reported SAR is > 0.8 W/kg, measure the SAR for these positions/configurations on the subsequent next highest measured output power channel(s) until the reported SAR is ≤ 1.2 W/kg or all required test channels are considered.
   ※ The additional power measurements required for this step should be limited to those necessary for identifying subsequent highest output power channels to apply the test reduction.
- When the specified maximum output power is the same for both UNII 1 and UNII 2A, begin SAR measurements in
  UNII 2A with the channel with the highest measured output power. If the reported SAR for UNII 2A is ≤ 1.2 W/kg,
  SAR is not required for UNII 1; otherwise treat the remaining bands separately and test them independently for SAR.
- When the specified maximum output power is different between UNII 1 and UNII 2A, begin SAR with the band that has the higher specified maximum output. If the highest reported SAR for the band with the highest specified power is ≤ 1.2 W/kg, testing for the band with the lower specified output power is not required; otherwise test the remaining bands independently for SAR.

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To determine the initial test position, Area Scans were performed to determine the position with the Maximum Value of SAR (measured). The position that produced the highest Maximum Value of SAR is considered as the worst case position; thus used as the initial test position.

- After an initial test configuration is determined, if multiple test channels have the same measured maximum output power, the channel chosen for SAR measurement is determined according to the following:
  - (1) The channel closest to mid-band frequency is selected for SAR measurement.
  - (2) For channels with equal separation from mid-band frequency; for example, high and low channels or two mid-band channels, the higher frequency (number) channel is selected for SAR measurement. These channel selection procedures apply to both the initial test configuration and subsequent test configuration(s) selection.

### 10.3 Conducted Power Measurements

Refer to Appendix A.

### 10.4 Antenna location

Refer to Appendix E.

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## 10.5 Test Results

### 10.5.1 SAR Test Result

Index.	Band	Modulation	Channel	Frequency (MHz)	Test Position	Spacing (mm)	SAR <sub>1 g</sub> (W/kg)	Meas. Conducted Power (dBm)	Tune-up (dBm)	Duty Cycle (%)	Reported SAR <sub>1g</sub> (W/kg)
	WLAN 2.4 GHz	802.11b	6	2437	Horizontal-Up	5	0.576	17.99	18	98.29	0.59
1	WLAN 2.4 GHz	802.11b	1	2412	Horizontal-Up	5	0.593	17.18	18	98.29	0.73
	WLAN 2.4 GHz	802.11b	11	2462	Horizontal-Up	5	0.509	17.93	18	98.29	0.53
	WLAN 2.4 GHz	802.11b	6	2437	Horizontal-Down	5	0.421	17.99	18	98.29	0.43
	WLAN 2.4 GHz	802.11b	6	2437	Vertical-Front	5	0.277	17.99	18	98.29	0.28
	WLAN 2.4 GHz	802.11b	6	2437	Vertical-Back	5	0.394	17.99	18	98.29	0.40
	WLAN 2.4 GHz	802.11b	6	2437	Tip	5	0.058	17.99	18	98.29	0.06
2	WLAN 5 GHz	802.11ac VHT80	42	5210	Horizontal-Up	5	0.793	14.17	15	86.67	1.11
	WLAN 5 GHz	802.11n HT40	38	5190	Horizontal-Up	5	0.762	14.58	15	87.91	0.96
	WLAN 5 GHz	802.11ac VHT80	42	5210	Horizontal-Down	5	0.303	14.17	15	86.67	0.42
	WLAN 5 GHz	802.11ac VHT80	42	5210	Vertical-Front	5	0.308	14.17	15	86.67	0.43
	WLAN 5 GHz	802.11ac VHT80	42	5210	Vertical-Back	5	0.296	14.17	15	86.67	0.41
	WLAN 5 GHz	802.11ac VHT80	42	5210	Tip	5	0.517	14.17	15	86.67	0.72
3	WLAN 5 GHz	802.11ac VHT80	155	5775	Horizontal-Up	5	0.846	15.21	16	86.67	1.17
	WLAN 5 GHz	802.11n HT40	159	5795	Horizontal-Up	5	0.786	15.66	16	87.91	0.97
	WLAN 5 GHz	802.11ac VHT80	155	5775	Horizontal-Down	5	0.233	15.21	16	86.67	0.32
	WLAN 5 GHz	802.11ac VHT80	155	5775	Vertical-Front	5	0.319	15.21	16	86.67	0.44
	WLAN 5 GHz	802.11ac VHT80	155	5775	Vertical-Back	5	0.205	15.21	16	86.67	0.28
	WLAN 5 GHz	802.11ac VHT80	155	5775	Tip	5	0.424	15.21	16	86.67	0.59

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## 10.6 Measurement Variability

According to KDB 865664 D01v01r04, SAR measurement variability must be assessed for each frequency band, which is determined by the SAR probe calibration point and tissue-equivalent medium used for the device measurements. When both head and body tissue-equivalent media are required for SAR measurements in a frequency band, the variability measurement procedures should be applied to the tissue medium with the highest measured SAR, using the highest measured SAR configuration for that tissue-equivalent medium.

The following procedures are applied to determine if repeated measurements are required:

- 1. The original highest measured Reported SAR 1-g is  $\geq$  0.80 W/kg, repeated that measurement once.
- 2. Perform a second repeated measurement the ratio of the largest to the smallest SAR for the original and first repeated measurements is <1.2 W/kg, or when the original or repeated measurement is ≥ 1.45 W/kg (~10% from the 1-g SAR limit).

Band	Modulation	Channel	Frequency (MHz)	Test Position	Spacing (mm)	Note	Original SAR <sub>1 g</sub> (W/kg)	First SAR <sub>1 g</sub> (W/kg)	First Ratio SAR <sub>1 g</sub>
WLAN 5 GHz	802.11ac VHT80	155	5775	Horizontal-Up	5	Index. #3_once	0.846	0.838	0.95%

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## 10.7 Requirements on the Uncertainty Evaluation

Decision Rule							
■ Uncertainty is not included.							
☐ Uncertainty is included.							
The highest measured 1-g SAR is less than 1.5 W/kg and the highest measured 10-g SAR is less than 3.75 W/kg.							
Therefore, per KDB Publication 865664 D01, the extended measurement uncertainty analysis described in IEEE 1528-							
2013 and IEC/IEEE 62209-1528 is not required.							
11. Conclusion							
The SAR test values found for the device are below the maximum limit of 1.6 W/kg.							

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