

ESTECH Co., Ltd.
 Rm. 1015, World Venture Center II,
 TEL: 82-2-867-3201

 426-5, Gasan-dong, Geumcheon-gu,
 FAX: 82-2-867-3204

 Seoul, 153-803, Korea
 FAX: 82-2-867-3204

	SAR Cor	mpliace	Test Report		
APPLICANT NAME & ADD UBISTAR CO.,LTD. 7F, Seongdo Building, 58 Gangnam-Gu, Seoul, 135	7-23, Sinsa-Dong,		DATA & LOCATION OF Dates of testing : Test Site : ESTECH Co	2005 11/09	
Test Device :		TYPE : Fi	Models : U FCC ID : RFL ked WLL Telephon	UX380	.) –Prototype
Test report no :	ESTSAR0511	-002	Number of page :		20
Contact person :	Jin-Sik Mi	n	Responsible test Eng	gineer :	K.H.Kang
Testing has been Carried out in Accordance with :	IEEE P1528-200X Draft 6.4 Recommended Practice for Determining the Peak Spatial-Average Specific Absorption Rate(SAR) in the Human Body Due to Wireless Communications Device : Experimental Techniques				
Applicant Type :		Certificatio	n		
FCC CLASSIFICATIO	N: Licensed N	on-Broadc	ast Transmitter (TNE	3)	
FCC Rule Part(s)	§2.1093; FC	C/OET Bull	etin 65 Supplement	C (July 2	001)
Test results :	The Tested device complies with the requirements in respect of all parameters subject to the test. The test results and statements relate only to the items tested. The test report shall not be reproduced recept in full, without written approval of the laboratory.				

Date and Signatures : 2005/11/18 Report Prepared By : Engineer/ K.H.Kang (Signature) Manager Engineer/ Jay Kim (Signature)

Test report no : ESTSAR0511-002 FCC ID : RFLUX380



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FCC ID	RFLUX380	
Date of test	2005/11/09 ~ 2005/11/18	
Responsible test engineer	Jay Kim	
Measurement performed by	K.H.Kang	
EUT Type	Fixed WLL Telephone (CDMA) -Prototype	
Tx Frequency	824.70 ~ 848.31 MHz (CDMA)	
Rx Frequency	869.70 ~ 893.31 MHz(CDMA)	
Max. RF Output Power	CDMA(24.2 dBm)	

Maximum Results Found During SAR Evaluation

1.1 Head Configuration

Max. SAR Measurement

FREQI	JENCY	Modulation	Conducted	Power(dBm)	Device test	Antenna	SAR (W/kg)
MHz	Ch	Modulation	dBm	Battery	position	position	
-	-	_	-	-	-	-	_

1.2 Body Worn Configuration

Max. SAR Measurement

FREQ	JENCY	Madulation		Power(dBm)	Separation test	Antenna	SAR (W/kg)
MHz	Ch	Modulation	dBm	Battery	position	position	
836.52	384	CDMA	24.2	Standard	2.5cm	-	0.841

1.3 Measurement Uncertainty

Combine Standard Uncertainty	± 10.81 (k=1)	
Extended Standard Uncertainty	\pm 21.62 (k=2, 95% CONFIDENCE LEVEL)	

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The FCC has adopted the guidelines for evaluating the environmental effects of radio frequency radiation in ET Docket 93-62 on Aug. 6, 1996 to protect the public and workers from the potential azards of RF emissions due to FCC-regulated portable device.[1]

The safety limits used for the environmental evaluation measurements are the criteria published by the based on American National Standards Institute (ANSI) For localized specific absorption rate (SAR) in IEEE/ANSI C95.1-1992 Standard for safety Levels with Respect to Human Exposure to Radio Frequency Electronic Fields, 3 kHz to 300 GHz. (c) 1992 by the institute of Electrical and Electronics Engineers, Inc., New York, New York 10017.[2] The measurement procedure described in IEEE/ANSIC95.3-1992 Recommended Practice for the Measurement of Potentially Hazardous Electromagnetic Fields - RF and Microwave[3] is used for guidance in measuring SAR due to the RF radiationexposure from the Equipment Under Test (EUT). These criteria for SAR evaluation are similar to those recommended by the National Council on Radiation Protection and Measurements (NCRP) in Biological Effects and Exposure Criteria for Radio Frequency Electromagnetic Fields," NCRP Report No. 86 (c) NCRP, 1986, Bethesda, MD20814.[6] SAR is ameasure of the rate of energy absorption due to exposure to an RF transmitting source. SAR values have been related to threshold levels for potential biological hazards.

SAR Definition

Specific Absorption Rate (SAR) is defined as the time derivative (rate) of the incremental energy (dU) absorbed by (dissipated in) an incremental mass (dm) contained in a volume element (dV) of a given density (p). it is also defined as the rate of rf energy absorption per unit mass at a point in an absorbing body (see Fig. 3.1.).

$$S A R = \frac{d}{d t} \left(\frac{d U}{d m} \right) = \frac{d}{d t} \left(\frac{d U}{\rho d v} \right)$$

Figure 2.1 SAR Mathematical Equation

SAR is expressed in units of Watts per Kilogram (W/kg).

SAR = $\sigma E^2 / \rho$

Where:

 σ = conductivity of the tissue-simulant material (S/m)

- E = mass density of the tissue-simulant material (kg/m³)
- ρ = Total RMS electric field strength (V/m)



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The FCC rules for evaluating portable devices for RF exposure compliance are contained in 47 CFR §2.1093. For purposes of RF exposure evaluation, a portable device is defined as a transmitting device designed to be used with any part of its radiating structure in direct contact with the user's body or within 20 centimeters of the body of a user or bystanders under normal operating conditions. This category of devices would include hand-held cellular and PCS telephones that incorporate the radiating antenna into the hand-piece and wireless transmitters that are carried next to the body. Portable sevices are evaluated with respect to SAR limits for RF exposure. The applicable SAR limit for portable transmitters used by consumers is 1.6 watts/kg, which is averaged over any one gram of tissue defined as a tissue volume in the shape of a cube. The EUT is a identical prototype, and the all techniques of it are identical with production unit.

2.1 Antenna Description

Туре	Helical		
Location	the right side of the device		
Radiator Material	P-Carbonate		

2.2 Device Description

The second second	FCC ID	FCC ID : RFLUX380	
ne 1	Serial numbers	-	
	Exposure environment	Uncontrolled exposure	
	Device category	Fixed device	
	Mode(s) of Operation	CDMA	
0004	Modulation Mode(s)	CDMA	
The second second	Duty Cycle	1	
and the second s	Transmitting	824.70 ~ 848.31 MHz (CDMA)	
	FreQuency Range(s)	624.70 ~ 646.31 WHZ (CDWA)	
	test signal method	base station simulator internal test code	

2.3 Battery Options

There is only one battery option available for tested device,



4.1 Ambient Conditions

Ambient Temperature (°C)	22
Tissue simulating liquid temperature (°C)	22
Humidity (%)	46

4.2 RF Characteristics of The Test Site

Tests were performed in a fully enclosed RF Shielded environment

4.3 Test Signal, Frequencies, And Output Power

The handset was placed into simulated call mode (800MHz CDMA modes) using manufacturers test codes.

In all operation bands the measurements were performed on lowest, middle and highest channels.

The phone was set to maximum power level during the all tests and at the beginning of the each test the battery was fully charged.

DASY4 system measures power drift during SAR testing by comparing e-field in the same location at the beginning and at the end of measurement. These records were used to monitor stability of power output.



Fig. 4.1 SAR Measurement System



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DESCRIPTION OF THE TEST EQUIPMENT

An SAR measurement system usually consists of a small diameter isotropic electric field probe, a multiple axis probe positioning system, a test device holder, one or more phantom models, the field probe instrumentation, a computer and other electronic equipment for controlling the probe and making the measurements. Other supporting equipment, such as a network analyzer, power meters and RF signal generators, are also required to measure the dielectric parameters of the simulated tissue media and to verify the measurement accuracy of the SAR system.

5.1 Test System Specifications

Test Equipment	Model	Serial Number	Cal. date
DAE	DAE3	551	2004-04-28
E-Field Probe	ET3DV6	1748	2005-01-21
Dinala validation kit	D835V2	475	2005-02-24
Dipole validation kit			
Network analyzer	8753ES	NONE	2005-10-17
Signal generator	E4432B	GB40050840	2005-03-03
RF Power meter	EPM-442A	GB37170412	2005-10-05
Power Sensor	8481A	3318A90368	2005-10-05
RF Power meter	E4418A	GB38272722	2005-03-03
Power Sensor	8481A	3318A96478	2005-03-03
Dielectric Probe	85070D	US01440154	_

5.2 SAR Measurement Setup

Measurement are performed using the DASY4 dosimetric assessment system. The DASY4 is made by Schmid & Partner Engineering AG(SPEAG) in Zurich, Switzerland and consists of high precision robotics system (Staubli), robot controller, Pentium IV computer, near-field probe, probe alignment sensor, and the SAM twin phantom containing the brain equivalent material. The robot is a six-axis industrial robot performing precise movements to position the probe to the location (points) of maximum electromagnetic field(EMF) (see Fig. 5.1) A cell controller system contains the power supply, robot controller, teach pendant(Joystick), and a remote control used to drive the robot motors. The pc consists of the Intel Pentium IV 2.4 GHz computer with Windows2000 system and SAR measurement Software DASY4, A/D interface card, monitor, mouse, and keyboard. The Staubli Robot data acquisition electronic (DAE) circuit that performs the signal amplification, signal multiplexing,

AD-conversion, offset measurements, mechanical surface detection, collision detection, etc.



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5. DESCRIPTION OF THE TEST EQUIPMENT(continued)

Is connected to the Electro-optical coupler (EOC). The EOC performs the conversion from the optical into digital electric signal of the DAE and transfers data to the PC plug-in card.

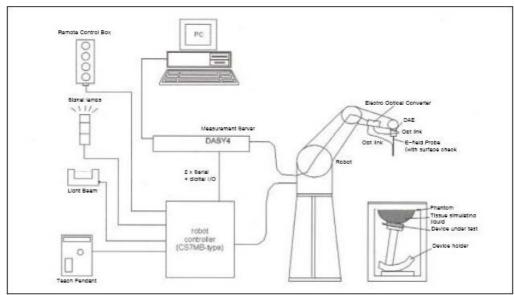


Fig. 5.1 SAR Measurement System Setup

The DAE3 consists of a highly sensitive electrometer–grade preamplifier with auto–zeroing, a channel and gainswitching multiplexer, a fast 16 bit AD–converter and a command decoder and control logic unit. Transmission to the PC–card is accomplished through an optical downlink for data and status information and an optical uplink for commands and clock lines. The mechanical probe mounting device includes two different sensor systems for frontal and sidewise probe contacts. They are also used for mechanical surface detection and probe collision detection. The robot uses its own controller with a built in VME–bus computer. The system is described in detail in [7].

5.3 DASY4 E-Field Probe System

The SAR measurements were conducted with the dosimetric probe ET3DV6, designed in the classical triangular configuration [7] (see Fig.5.2) and optimized for dosimetric evaluation. The probe is constructed using the thick film technique; with printed resistive lines on ceramic substrates. The probe is equipped with an optical multifiber line ending at the front of the probe tip. It is connected to the EOC box in the robot arm and provides an automatic detection transmitter, the other half to a synchronized receiver.



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As the probe approach the surface, the reflection from the surface produces a coupling from the transmitting to the receiving fibers. This reflection increases first during the approach, reaches coupling is zero. The distance of the coupling maximum to the surface is probe angle. The DASY4 software reads the reflection during a software approach and looks for the maximum using a 2nd order fitting (see Table. 5.2). The approach is stopped at reaching the maximum.

Is	sotropic E-Field F	Probe for Dosimetric Measurements
	Construction	Symmetrical design with triangular core Interleafed sensors Built-in shielding against static charges PEEK enclosure material (resistant to organic solvents, e.g., glycol)
	Calibration	In air from 10 MHz to 3 GHz In brain and muscle simulating tissue at frequencies of 450 MHz, 900 MHz and 1.8 GHz (accuracy \pm 8%) Calibration for other liquids and frequencies upon request
F	requency	10 MHz to > 6 GHz; Linearity: ± 0.2 dB (30 MHz to 3 GHz)
D	Directivity	\pm 0.2 dB in brain tissue (rotation around probe axis) \pm 0.3 dB in brain tissue (rotation normal to probe axis)
D	ynamic Range	5 μ W/g to > 100 mW/g; Linearity: \pm 0.2 dB
Isotropic E-Field Probe	Dimensions	Overall length: 330 mm Tip length: 20 mm Body diameter: 12 mm Tip diameter: 3.9 mm Distance from probe tip to dipole centers: 2.7 mm

Fig. 5.2 Probe Specifications



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5. DESCRIPTION OF THE TEST EQUIPMENT(continued)

5.4 Phantom & Equivalent Tissues SAM Phantom

The SAM Twin Phantom V4.0 is constructed of the fiberglass shell integrated in a wooden table. The shape of the shell is based on data from an anatomical study designed to determine the maximum exposure in at least 90% of all users [11][12]. It enables the dosimetric evaluation of left and right hand phone usage as well as body mounted usage at the flat phantom region. A cover prevents the evaporation of the liquid. Reference markings on the phantom allow the complete setup of all predefined phantom positions and measurement grids by manually teaching three points in the robot.

Head & Muscle simulation Mixture Characterization

The brain and muscle mixtures consist of a viscous gel using hydroxethlcellullose(HEC) gelling agent and saline solution (see Table 5.1). Preservation with a bactericide is added and visual inspection is made to make sure air bubbles are not trapped during the mixing process. The mixture is calibrated to obtain proper dielectric constant (permittivity) and conductivity of the desired tissue. The head tissue dielectric parameters recommended by the IEEE SCC-34/SC-2 have been specified in P1528 are derived from the issue dielectric parameters computed from the 4-Cole-Cole equations The mixture characterizations used for the brain and muscle tissue simulation liquids are according to the data by C. Gabriel and G. Hartagrove [13]. (see Fig. 5.3)

Frequency	Не	ad	Bc	ody
(MHz)	εr	σ (S/m)	εr	σ (S/m)
150	52.3	0.76	61.9	0.8
300	45.3	0.87	58.2	0.92
450	43.5	0.87	56.7	0.94
835	41.5	0.9	55.2	0.97
900	41.5	0.97	55	1.05
915	41.5	0.98	55	1.06
1450	40.5	1.2	54	1.3
1610	40.3	1.29	53.8	1.4
1800-2000	40	1.4	53.3	1.52
2450	39.2	1.8	52.7	1.95
3000	38.5	2.4	52	2.73
5800	35.3	5.27	48.2	6

Fig.5.3 Head and body tissue parameters by the IEEE SCC-34/SC-2 in P1528



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5. DESCRIPTION OF THE TEST EQUIPMENT(continued)

8	35MHz		1900MHz				
	Head	Body		Head	Body		
Sugar	47.31%	34.31%	DGBE(diethyene Glycol butyl Ether)	44.91%	29.96%		
Deionized water	51.07%	.07% 65.45% Deionized water 54.88		54.88%	69.91%		
Salt	1.15%	0.62%	Salt	0.21%	0.13%		
HEC (hydroxyethyl cellulose)	0.24%						
Preventol	0.24%	0.10%					
З	41.0±5%	55.2±5%	З	40.0±5%	53.3±5%		
σ	σ 0.89±10% 0.97±10%		σ	1.45±10%	1.52±10%		

Fig. 5.4 Composition of the Tissue Equivalent Matter

Device Holder for Transmitters

In combination with the SAM Twin Phantom V4.0, the Mounting Device enables the rotation of the accurately, and repeatably be positioned according to the FCC specifications. The device holder can be locked at different phantom locations (left head, right head, flat phantom).

Note : A simulating human hand is not used due to the complex anatomical and geometrical structure of the hand that may produce infinite number of configurations [12]. To produce the worst-case condition (the hand absorbs antenna output power), the hand is omitted during the tests.



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6.1 Definition of Reference Point EAR Reference point

The point "M" is the reference point for the center of the mouth, "ERP" is the ear reference point. The ERP are 15mm posterior to the entrance to the ear canal(EEC) along the B–M line (Back–Mouth), as shown is figure 6.1. The plane passing through the two ear canals and M is defined as the Reference Plane. The line N–F (Neck–Front) is perpendicular to the reference plane and passing through the ERP is called the Reference Pivoting Line (see Figure 6.1) B–M is perpendicular to the N–F line. Both N–F and B–M lines are marked on the external phantom shell to facilitate handset positioning [5].

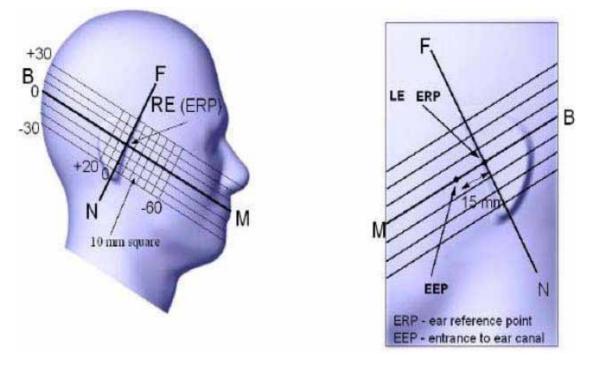


Figure 6.1 Close-up side view of ERP

Handset Reference Points

Two imaginary lines on the handset were established: the vertical centerline and the horizontal line. The test device was placed in a normal operating position with the "test device reference point" located along the "vertical centerline" on the front of the device aligned to the "ear reference point" (see Fig. 6.2). The "test device reference point" was than located at the same level as the center of the ear reference point. The test device was positioned so that the "vertical centerline" was bisecting the front surface of the handset at it's top and bottom edges, positioning the "ear reference point" on the outer surface of the both the left and right head phantoms on the ear reference point.

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6. DESCRIPTION OF THE TEST PROCEDURE(continued)

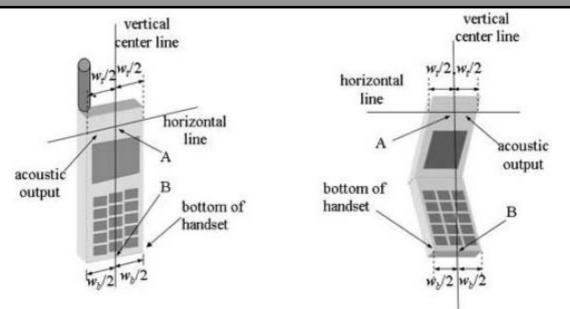


Figure 6.2 Handset Vertical Center & Horizontal Line Reference Points

- 6.2 Test Configuration Positions Positioning for Cheek/Touch
- 1) Ready the handset for talk operation, if necessary. For example, for handsets with a cover piece, open the cover. (If the phone can also be used with the cover closed ,both configurations must be tested.)
- 2) Define two imaginary lines on the handset: the vertical centerline and the horizontal line. The vertical centerline passes through two points on the front side of the handset: the midpoint of the width wt of the handset at the level of the acoustic output (point A on Figures 6.2), and the midpoint of the width wb of the bottom of the handset (point B). The horizontal line is perpendicular to the vertical centerline and passes through the center of the acoustic output (see Figure 6.2). The two lines intersect at point A. Note that for many handsets, point A coincides with the center of the acoustic output. However, the acoustic output may be located elsewhere on the horizontal line. Also note that the vertical centerline is not ecessarily parallel to the front face of the handset (see Figure 6.2), especially for clamshell handsets, handsets with lip pieces, and other irregularly-shaped handsets.
- 3) Position the handset close to the surface of the phantom touch that point A is on the (virtual) extension of the line passing through points RE and LE on the phantom (see Figure 6.3), such that the plane defined by the vertical center line and the horizontal line of the phone is approximately parallel to the sagittal plane of the phantom.



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6. DESCRIPTION OF THE TEST PROCEDURE(continued)

- 4) Translate the handset towards the phantom along the line passing through RE and LE until the handset touches the ear.
- 5) While maintaining the handset in this plane, rotate it around the LE-RE line until the vertical centerline is in the plane normal to MB-NF including the line MB (called the reference plane).
- 6) Rotate the phone around the vertical centerline until the phone (horizontal line) is symmetrical with respect to the line NF.
- 7) While maintaining the vertical centerline in the reference plane, keeping point A on the line passing through RE and LE, and maintaining the phone contact with the ear, rotate the handset about the line NF until any point on the handset is in contact with a phantom point

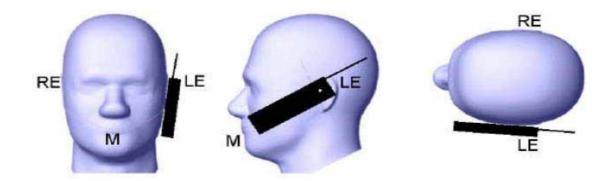


Figure 6.3 "Cheek" or "Touch" Position.

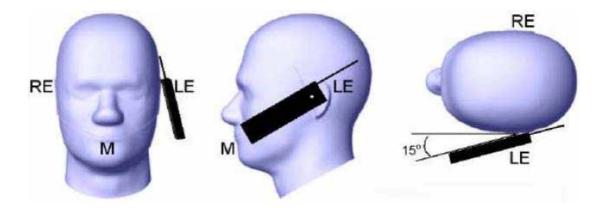


Figure 6.4 "Tilted" Position.



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6. DESCRIPTION OF THE TEST PROCEDURE(continued)

Positioning for Ear / 15° Tilted

- 1) Repeat steps 1 to 7 of 6.2(Positioning for Cheek/Touch) to place the device in the "cheek position."
- 2) While maintaining the orientation of the phone retract the phone parallel to the reference plane far enough to enable a rotation of the phone by 15 degree.
- 3) Rotate the phone around the horizontal line by 15 degree.
- 4) While maintaining the orientation of the phone, move the phone parallel to the reference plane until any part of the phone touches the head. (In this position, point A will be located on the line RE-LE). The tilted position is obtained when the contact is on the pinna. If the contact is at any location other than the pinna, the angle of the phone shall be reduced. The tilted position is obtained if any part of the phone is in contact of the ear as well as a second part of the phone is contact with the head.

Body Holder / Belt Clip Configurations

Body-worn operation configurations are tested with the belt-clips and holsters attached to the device and positioned against a flat phantom in a normal use configuration. A device with a headset output is tested with a headset connected to the device. Body dielectric parameters are used.

Accessories for Body-worn operation configurations are divided into two categories: those that do not contain metallic components and those that do contain metallic components. When multiple accessories that do not contain metallic components are supplied with the device, the device is tested with only the accessory that dictates the closest spacing to the body. Then multiple accessories that contain metallic components are supplied with the device, the device is tested with each accessory that contains a unique metallic component. If multiple accessories share an identical metallic component (i.e. the same metallic belt-clip used with different holsters with no other metallic components) only the accessory that dictates the closest spacing to the body is tested.

Body-worn accessories may not always be supplied of available as options for some devices intended to be authorized for body-worn use. In this case, a test configuration where a separation distance between the back of the device and the flat phantom is used. All test position spacings are documented. Transmitters that are designed to operate in front of a person's face, as in push-to-talk configurations, are tested for SAR compliance is tested with the accessory(ies), including headsets and microphones, attached to the device and positioned against a flat phantom in a normal use configuration. In all case SAR measurements are performed to investigate the worst case positioning. Worst-case positioning is then documented and used to perform Body SAR testing.

In order for users to be aware of the body-worn operation requirements for meeting RF exposure compliance, operation instructing instructions and cautions statements are included in the user's manual.



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6. DESCRIPTION OF THE TEST PROCEDURE(continued)

6.3 Scan Procedures

First coarse scans are used for quick determination of the field distribution. Nest cube scan, 7x7x7 points; spacing between each point 5x5x5 mm, is performed around the highest E-field value to determine the averaged SAR-distribution over 1g.

6.4 SAR Averaging Methods

The maximum SAR value is averaged over its volume using interpolation and extrapolation. The interpolation of the points is done with a 3d-Spline. The 3d-Spline is composed of three one-dimensional splines with the "Not a Knot" ?condition [W.Gander, Computerma-thematik, p. 141-150](x, y and z ?directions) [Numerical Recipes in C, Second Edition, p 123].

The extrapolation is based on least square algorithm [W.Gander, Computermathematik, p. 168–180]. Through the points in the first 30 mm in all z-axis, polynomials of order four are calculated . This polynomial is then used to evaluate the points between the surface and the probe tip. The points calculated from the surface, have a distance of 1mm from one another.



According to CENELEC [17], typical worst-case uncertainty of field measurements is 5 dB.

For well-defined modulation characteristics the uncertainty can be reduced to 3 dB.

	I			I Curr DC		
ERROR Description	Uncertainty Probability		Divisor	ci 1	Standard unc.	vi or
	value ±%	Distribution		1g	(1g)	Veff
MEASUREMENT SYSTEM						
Probe Calibration	± 11.7 %	normal	1	1	± 4.8 %	∞
Axial Isotropy	± 4.7	rectangular	√3	(1-cp) ^{1/2}	± 1.9%	∞
Hemispherical Isotropy	± 9.6	rectangular	√ 3	(cp) ^{1/2}	± 3.9%	∞
Boundary Effects	± 1.0	rectangular	√3	1	± 0.6%	∞
Linearity	± 4.7	rectangular	√3	1	± 2.7%	∞
System Detection Limits	± 1.0	rectangular	√ 3	1	± 0.6%	∞
Readout Electronics	± 1.0	normal	1	1	± 1.0%	∞
Response time	± 0.8	rectangular	√ 3	1	± 0.5%	∞
Integration time	± 2.6	rectangular	√ 3	1	± 1.5%	∞
RF Amnient Conditions	± 3.0	rectangular	√3	1	± 1.7%	∞
Probe Positioner Mechanical Tolerance	± 0.4	rectangular	√ 3	1	± 0.2%	∞
Probe Positioning with respect to Phantom Shell	± 2.9	rectangular	√ 3	1	± 1.7%	∞
Extrapolation, Interpolation and Integration Algorithms for Max. SAR Evaluation	± 1.0	rectangular	√3	1	± 0.6%	∞
Test Sample Related						•
Test Sample Positioning	± 2.9	normal	1	1	± 2.97%	145
Device Holder Uncertainty	± 3.6	normal	0.84	1	± 3.69%	5
Output Power Validation - SAR drift measurement	± 5.0	rectangular	√ 3	1	± 2.9%	∞
Phantom and Tissue						
Parameters Phantom Uncertainty (shape and thickness tolerances)	± 4.0	rectangular	√ 3	1	± 2.3%	∞
Liquid conductivity Target - tolerance	± 5.0	rectangular	√ 3	0.64	± 1.8%	∞
Liquid Conductivity - measurement uncertainty	± 2.5	normal	1	0.64	± 1.6%	∞
Liquid permittivity Target - tolerance	± 5.0	rectangular	√ 3	0.6	± 1.7%	∞
Liquid Permittivity - measurement uncertainty	± 2.5	normal	1	0.6	± 1.5%	∞
Combined S	Combined Standard Uncertainty					
Coverag		K = 2				
Expanded S	Standard Uncert	ainty			± 22.64 %	

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Tissue Verification

Table 8.1 Simulated Tissue Verification [5]

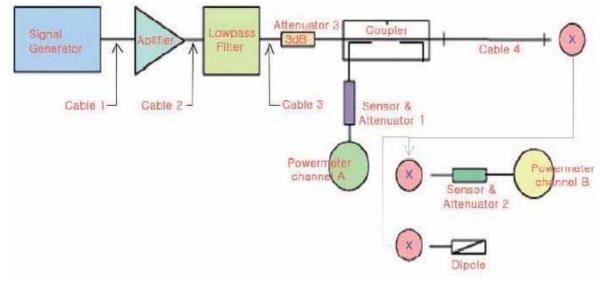
MEASURED TISSUE PARAMETERS										
Liquid Tem	peratu	re (°C)	22		Liquid De	epth(mm)	1	50		
Date	2005-11-17		2005-11-17				/ /			
Tissue	835M	835MHz Brain 835MHz Muscle								
	Target	Measured	Target	Measured						
Dielectric Constant: ε	41.5	40.6	55.2	54.2						
Conductivity: σ	0.9	0.89	0.97	0.96						
Deviation (%) $\begin{array}{c} \epsilon : -2.17\% \\ \sigma : -1.11\% \end{array}$		ε:-1.81% σ:-1.03%								

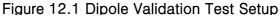
Test System Validation

- Prior to assessment, the system is verified to the $\pm 10\%$ of the specifications at 835MHz (Graphic Plots Attached)
- The results are nominalized to 1W input power.

Table 8.2 System Validation [5]

SYSTEM DIPOLE VALIDATION TARGET & MEASURED									
Tissue	System Validation Kit:	Forward Power (W)	Targeted SAR1g (mW/g)	Measured SAR1g (mW/g)	Deviation (%)	Test Date			
835MHz Brain	D835V2(S/N :475)	1.0	9.5	9.36	1.47%	2005-11-17			







ESTECH Co., Ltd. Rm.1015, World Venture Center II, TEL: 82-2-867-3201 426-5, Gasan-dong, Geumcheon-gu, FAX: 82-2-867-3204 Seoul, 153-803, Korea

continued

Ambient TEMPERATURE (C) : 22 Relative HUMIDITY (%): 46 Mixture Type : 835MHz Body Dielectric Constant : 54.2 Conductivity: 0.96

Measurement Results

ANSI / IEEE C95.1 1992 - SAFETY LIMIT Spatial Peak Uncontrolled Exposure/General Population

Brain 1.6 W/kg (mW/g) averaged over 1 gram

MEASURE	MEASUREMENT RESULTS (CDMA Body SAR With Adapter)										
Frequ	Frequency		Conducted Power(dBm)		botton	Device Test	Antenna	SAR			
MHz	Ch.	Moudulation	Begin	End	battery	position	Position	(W/kg)			
824.70	1013	CDMA	24.20	24.18	Standard	2.5Cm	-	0.708			
836.52	384	CDMA	24.20	24.11	Standard	2.5Cm		0.679			
848.31	777	CDMA	24.20	24.12	Standard	2.5Cm	_	0.598			

MEASUREMENT RESULTS (CDMA Body SAR Without Adapter)										
Frequency		Manadalatian	Conducted Power(dBm)			Device Test	Antenna	SAR		
MHz	Ch.	Moudulation	Begin	End	battery	position	Position	(W/kg)		
824.70	1013	CDMA	24.20	24.14	Standard	2.5Cm	_	0.722		
836.52	384	CDMA	24.20	24.23	Standard	2.5Cm	_	0.841		
848.31	777	CDMA	24.20	24.16	Standard	2.5Cm	_	0.640		

NOTES:

1. The test data reported are the worst-case SAR value with the antenna-head position set in a typical configuration.

2. All modes of operation were investigated and the worst-case are reported.

3. Battery Type : Standard

Radiated measurements indicate that the Extended-life battery produces lower ERP and EIRP, therefore the Standard-life battery is used in SAR testing.

4. Power Measured : Conducted

5. SAR Measurement System : <u>SPEAG</u>

6. SAR Configuration : Body (For this test the EUT is Since this EUT does not supply any body worn accessory to the end user a distance of 2.5Cm from the EUT back surface to the liquid interface is configured for the generic test.

Engineer K.H.Kang



TEL: 82-2-867-3201 FAX: 82-2-867-3204

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